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**The Development of an Executable  
Graphical Notation for Describing  
Direct Manipulation Interfaces**

A dissertation presented  
in partial fulfillment of the requirements  
for the degree of  
Doctor of Philosophy in Computer Science  
at Massey University

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# Abstract

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The research reported in this thesis involves the development of an executable semi-formal graphical notation, Lean Cuisine+, for describing the underlying behaviour of event-based direct manipulation interfaces, and the application of the notation both in 'reverse engineering', and during the early design phase of the interface development life cycle.

A motivation for the research stems from the need for tools and techniques to support high level interface design. The research supports and brings together a number of views concerning the requirements of notations at this level. These are that a notation should be semi-formal, graphical, executable, and object-oriented, and that to be most effective it should be targeted at a specific category of interaction. The Lean Cuisine+ notation meets all these criteria, the underlying meneme model matching closely with the selection-based nature of direct manipulation interfaces.

Lean Cuisine+ is a multi-layered notation, and is a development of Lean Cuisine (Apperley & Spence, 1989). The base layer is a tree diagram which captures part of the behaviour of an interface in terms of constraints and dependencies between selectable dialogue primitives. Further constraints and dependencies associated with the dynamics of the interface are captured through overlays to the basic tree diagram. An orthogonal task layer captures any temporal relationships between primitive task actions, and provides a link with higher level functionality. Lean Cuisine+ is able to combine both static and dynamic modelling in a coherent manner, thus avoiding the necessity of employing separate and possibly disjoint models at the early design stage. A software support environment for the notation is also specified and partially prototyped.

The research demonstrates the advantages of a notation which can be executed to provide limited but valid early simulation of the dynamic behaviour of the interface under design. A mapping from Lean Cuisine+ to a dialogue implementation language, DAL (Anderson, 1993), is also developed in support of the view that a multi-notational approach to interface development is required, and that it must be possible to move easily from initial specification to prototyping and implementation.

The Lean Cuisine+ descriptions of aspects of the Apple Macintosh interface included in the thesis show the notation to be capable of handling a range of direct manipulation interaction styles and a variety of interface objects. A five stage methodology for the construction of Lean Cuisine+ specifications for new interfaces is also developed, and applied in two case studies.

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# Brief Contents

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<b>PART 1</b>	<b>SURVEY AND FRAMEWORK</b>	
Chapter 1	Introduction .....	3
Chapter 2	Direct Manipulation Interfaces .....	15
Chapter 3	A Review of Dialogue Models and Notations .....	33
Chapter 4	Extending Lean Cuisine .....	63
<b>PART 2</b>	<b>DEVELOPMENT</b>	
Chapter 5	The Basic Lean Cuisine+ Notation .....	81
Chapter 6	Extending the Lean Cuisine+ Object Range .....	103
Chapter 7	Lean Cuisine+ in High Level Interface Design .....	125
Chapter 8	Software Support for Lean Cuisine+ .....	157
<b>PART 3</b>	<b>REVIEW</b>	
Chapter 9	Conclusions and Further Work .....	185
<b>REFERENCES AND GLOSSARY</b>		
References .....		195
Glossary .....		205
<b>APPENDICES</b>		
Appendix A	The Lean Cuisine Notation .....	227
Appendix B	A Macintosh Task Analysis .....	231
Appendix C	The Lean Cuisine+ Notation .....	237
Appendix D	A Support Environment Prototype .....	245

# Detailed Contents

---

<b>Chapter 1 Introduction</b>	<b>3</b>
1.1 Motivation for the research	3
Direct manipulation interfaces	4
The interface development life cycle (IDLC)	5
Existing interface development tools	6
The need for 'high level' tools	8
Formal vs informal specifications	10
Focus on a graphical representation	11
1.2 Objectives of the research	12
1.3 Approach adopted	13
1.4 Structure of the thesis	14
<b>Chapter 2 Direct Manipulation Interfaces</b>	<b>15</b>
2.1 The nature of direct manipulation	15
The object-action model	18
2.2 The desktop metaphor	20
Menus	21
Windows	21
2.3 The Macintosh interface	22
The desktop	23
Basic interaction techniques	25
Modality	26
The hierarchical file system	27
Other Macintosh applications	28
2.4 Modelling direct manipulation interfaces	29
Three views of the interface	30
2.5 Software architectures for direct manipulation interfaces	31
2.6 Review	32
<b>Chapter 3 A Review of Dialogue Models and Notations</b>	<b>33</b>
3.1 Specifying system behaviour	33
3.2 Dialogue notations	35
3.2.1 Sequence-based notations	37
State transition diagrams (STDs)	37

---

Event-decomposition graphs (EDGs) .....	41
Petri nets .....	43
Other sequence-based notations .....	46
3.2.2 State-based notations .....	47
Statecharts .....	47
3.2.3 Object-based notations .....	51
Lean Cuisine .....	51
Other object-based notations .....	55
3.3 Comparison and review .....	57
A direct manipulation dialogue model .....	59
A way forward .....	61
<b>Chapter 4 Extending Lean Cuisine</b> .....	<b>63</b>
4.1 Analysis of Macintosh interaction tasks .....	63
Finder processes .....	66
MacPaint processes .....	68
A task taxonomy .....	70
4.2 Extending the scope of Lean Cuisine .....	72
4.3 A framework for Lean Cuisine+ .....	74
<b>Chapter 5 The Basic Lean Cuisine+ Notation</b> .....	<b>81</b>
5.1 Introduction .....	81
5.2 The base layer .....	83
Object state variables .....	86
5.3 Further constraint layers .....	86
The selection trigger layer .....	86
The option precondition layer .....	90
The existence dependency layer .....	91
5.4 An extended icon object hierarchy .....	92
System directives .....	96
5.5 The addition of menus .....	99
5.6 Review .....	100
<b>Chapter 6 Extending the Lean Cuisine+ Object Range</b> .....	<b>103</b>
6.1 External selection triggers .....	103
6.2 The Microsoft Word dialogue .....	103
Object state variables .....	107
Selection trigger layer .....	108
Option precondition layer .....	111

Existence dependency layer .....	111
6.3 The MacDraw dialogue .....	114
Object state variables .....	116
Selection trigger layer .....	119
Option precondition layer .....	119
6.4 The completed Finder-application linkage .....	121
6.5 The dialogue interlink diagram (DID) .....	121
6.6 Review .....	123
<b>Chapter 7 Lean Cuisine+ in High Level Interface Design</b>	<b>125</b>
7.1 The role of Lean Cuisine+ in interface design .....	125
7.2 Task analysis .....	126
7.3 The Lean Cuisine+ task layer .....	127
7.4 A methodology for constructing Lean Cuisine+ specifications .....	128
7.5 Case study I: the Finder document folder system .....	130
7.6 Case study II: an electronic mail browser .....	142
7.7 Review .....	154
<b>Chapter 8 Software Support for Lean Cuisine+</b>	<b>157</b>
8.1 Requirements of a support environment .....	157
8.2 A support environment prototype .....	158
Execution of the specification .....	164
8.3 Prototyping the interface under design.....	170
Mapping to a dialogue specification language .....	171
The modified event response system (MERS) notation .....	172
Dialogue activation language (DAL) .....	173
<b>Chapter 9 Conclusions and Further Work</b>	<b>185</b>
9.1 Review of the Lean Cuisine+ notation .....	185
Visual aspects of the notation .....	186
Applicability of the notation .....	187
Executability of the notation .....	187
Mappability of the notation for prototyping and implementation .....	188
9.2 The wider contribution of the thesis .....	188
Support for the early design phase of the IDLC .....	188
Definition of a direct manipulation behavioural model .....	189
Analysis of Macintosh interaction tasks .....	189
9.3 General conclusions .....	190
9.4 Further work .....	191



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<b>References</b>	<b>195</b>
<b>Glossary</b>	<b>205</b>
<b>Appendix A The Lean Cuisine Notation</b>	<b>227</b>
A1 Menu definitions .....	227
A2 Menu subgroup structures .....	227
A3 Lean Cuisine definitions .....	227
A4 Menu and meneme modifiers .....	228
A5 Special characters .....	228
<b>Appendix B A Macintosh Task Analysis</b>	<b>231</b>
B1 Macintosh Finder .....	232
B2 MacPaint application .....	235
<b>Appendix C The Lean Cuisine+ Notation</b>	<b>237</b>
C1 Basic features and definitions .....	237
C2 Additional constraints .....	242
C3 The task layer .....	243
C4 Execution of a Lean Cuisine+ specification .....	244
<b>Appendix D A Support Environment Prototype</b>	<b>245</b>
D1 Basic browsing mode .....	246
D2 Selection trigger mode .....	248
D3 Option precondition mode .....	250
D4 Existence dependency mode .....	252
D5 Object state variable (OSV) mode .....	253
D6 Task mode .....	255
D7 Execution mode .....	256

# Figures and Tables

---

## Figures

Figure 2.1: Macintosh document window (active state) .....	24
Figure 2.2: Example Macintosh desktop .....	25
Figure 2.3: Example dialogue box (Microsoft Word) .....	27
Figure 2.4: Example Macintosh document folder icon/window hierarchy .....	28
Figure 3.1: STD for MacWrite <i>Style</i> menu (Apperley & Spence, 1989) .....	39
Figure 3.2: STD for Finder document folder system .....	40
Figure 3.3: EDG for Finder document folder system .....	42
Figure 3.4: Petri net for Finder document folder system .....	45
Figure 3.5: Statechart for Finder document folder system .....	49
Figure 3.6: Lean Cuisine in action .....	52
Figure 3.7: Lean Cuisine diagram for Finder document folder system .....	53
Figure 4.1: <i>Get Value</i> subtask .....	65
Figure 4.2: Taxonomy of interaction tasks .....	71
Figure 4.3: Lean Cuisine+ framework .....	76
Figure 5.1: Finder: Lean Cuisine+ base layer tree diagram .....	83
Figure 5.2: <i>PrintDirectory</i> modal subdialogue tree .....	85
Figure 5.3: Finder: Selection trigger layer over greyed base layer diagram .....	88
Figure 5.4: Finder: Option precondition layer over greyed base layer diagram .....	90
Figure 5.5: Finder: Existence dependency layer over greyed base layer diagram .....	92
Figure 5.6: Extended Finder icon object hierarchy .....	93
Figure 5.7: Base layer tree diagram for extended Finder document folder system .....	95
Figure 5.8: <i>OpenDisk</i> subdialogue involving a system directive .....	96
Figure 5.9: Finder diskette-related selection triggers .....	97
Figure 5.10: Finder diskette-related option preconditions .....	98
Figure 5.11: Finder menus showing option preconditions .....	100
Figure 5.12: Lean Cuisine+ structural dialogue components .....	101
Figure 6.1: Finder icon object hierarchy showing external triggers .....	104
Figure 6.2: Microsoft Word: base layer tree diagram .....	106
Figure 6.3: Microsoft Word: Internal selection triggers .....	109
Figure 6.4: Microsoft Word: External selection triggers .....	110
Figure 6.5: Microsoft Word: Option preconditions .....	112

---

Figure 6.6: Microsoft Word: Existence dependencies .....	113
Figure 6.7: MacDraw: base layer tree diagram for level 2 .....	115
Figure 6.8: MacDraw: selection triggers for level 2 .....	118
Figure 6.9: MacDraw: option preconditions for level 2 .....	120
Figure 6.10: The DID for part of the Macintosh interface .....	121
Figure 6.11: Finder icon object hierarchy showing all application links .....	122
Figure 6.12: Dialogue levels in Lean Cuisine+ .....	123
Figure 7.1: Task action sequence for <i>Open (Folder)</i> over greyed base layer diagram ..	127
Figure 7.2: Methodology for constructing a Lean Cuisine+ Specification .....	129
Figure 7.3: STAGE 1: Finder task decomposition .....	132
Figure 7.4: STAGE 2: Initial Finder subdialogue trees .....	135
Figure 7.5: STAGE 3: Initial Finder object hierarchy .....	136
Figure 7.6: STAGE 3: Refined Finder object hierarchy .....	136
Figure 7.7: STAGE 3: Refined Finder subdialogue trees .....	136
Figure 7.8: STAGE 3: Composite Finder dialogue tree .....	137
Figure 7.9: STAGE 4: Finder selection triggers showing Table 7.1 references .....	138
Figure 7.10: STAGE 4: Finder option preconditions showing Table 7.1 references ..	139
Figure 7.11: STAGE 4: Finder existence dependency .....	140
Figure 7.12: STAGE 4: Finder task action sequence for <i>Empty Trash</i> .....	141
Figure 7.13: STAGE 5: Finder menus .....	141
Figure 7.14: STAGE 1: Mail browser task decomposition .....	143
Figure 7.15a: STAGE 2: Initial mail browser subdialogue trees .....	145
Figure 7.15b: STAGE 2: Initial mail browser subdialogue trees - contd .....	146
Figure 7.16: STAGE 3: Initial Mail browser object hierarchy .....	147
Figure 7.17: STAGE 3: Refined Mail browser object hierarchy .....	147
Figure 7.18: STAGE 3: Composite mail browser dialogue tree .....	148
Figure 7.19: STAGE 4: Mail browser selection triggers showing Table 7.3 refs .....	151
Figure 7.20: STAGE 4: Further mail browser constraints .....	152
Figure 7.21: STAGE 4: Mail browser <i>Open box</i> task action sequence .....	153
Figure 7.22: STAGE 5: Mail browser menus showing option preconditions .....	154
Figure 8.1: Support environment window format .....	159
Figure 8.2: Basic browsing mode showing base layer dialogue tree .....	160
Figure 8.3: Selection trigger overlay for <i>NewFolder</i> .....	161
Figure 8.4: OSV mode showing state variables for <i>FolderIcon</i> .....	162
Figure 8.5: Task overlay for task <i>Open Folder</i> .....	163
Figure 8.6: Finder simulation: example icon/window system .....	164
Figure 8.7: Finder simulation Stage #1: start-up state .....	167
Figure 8.8: Finder simulation Stage #7: folders B, C and F open .....	168
Figure 8.9: Finder simulation Stage #14: Trash folder open .....	169

Figure 8.10: Finder simulation Stage #7 under tandem execution ..... 171  
 Figure 8.11a: Mapping Lean Cuisine+ to DAL ..... 176  
 Figure 8.11b: Mapping Lean Cuisine+ to DAL - continued ..... 177  
 Figure 8.11c: Mapping Lean Cuisine+ to DAL - continued ..... 178  
 Figure 8.11d: Mapping Lean Cuisine+ to DAL - continued ..... 179  
 Figure 8.11e: Mapping Lean Cuisine+ to DAL - continued ..... 180

**Tables**

Table 2.1: Macintosh mouse techniques ..... 26  
 Table 3.1: Classification of surveyed graphical dialogue notations ..... 36  
 Table 3.2: Finder states: STDs vs. statecharts ..... 50  
 Table 3.3: Required scope of a direct manipulation dialogue model ..... 59  
 Table 4.1: Primitive virtual devices (Wallace, 1976) ..... 64  
 Table 4.2: Interaction tasks (Foley *et al*, 1984) ..... 65  
 Table 4.3: Macintosh mouse techniques ..... 66  
 Table 4.4: Taxonomy of interaction tasks ..... 71  
 Table 4.5: Required scope of a direct manipulation dialogue model ..... 73  
 Table 4.6: Aspects of the dialogue model requiring Lean Cuisine extensions ..... 74  
 Table 5.1: Initial set of Finder OSVs ..... 87  
 Table 5.2: Application icon related OSVs ..... 94  
 Table 5.3: Finder menu option preconditions ..... 100  
 Table 6.1: OSVs for Microsoft Word ..... 107  
 Table 6.2: OSVs for level 2 of MacDraw ..... 117  
 Table 7.1: STAGE 1: Finder tasks ..... 133  
 Table 7.2a: Initial set of Finder OSVs ..... 138  
 Table 7.2b: Initial set of Finder OSVs - contd ..... 139  
 Table 7.3: STAGE 1: Mail browser tasks ..... 144  
 Table 7.4a: OSVs for mail browser ..... 149  
 Table 7.4b: OSVs for mail browser - contd ..... 150  
 Table 8.1: Finder simulation: initial OSV values ..... 165  
 Table 8.2: Icon set and window stack at each stage of the simulation ..... 166  
 Table 8.3: Feature analysis of Lean Cuisine+ and DAL ..... 175

# Part 1

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## Survey and Framework

Chapter 1	Introduction .....	3
Chapter 2	Direct Manipulation Interfaces .....	15
Chapter 3	A Review of Dialogue Models and Notations .....	33
Chapter 4	Extending Lean Cuisine .....	63

# Chapter 1

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## Introduction

*“The problem addressed here is not how to construct good interfaces; it is how to provide an environment in which good interfaces can be constructed.”*

Hartson & Hix, 1989

### 1.1 Motivation for the research

As human-computer interfaces have become easier to use they have become harder to create. Graphical interface software is large, complex, and difficult to debug and modify. The design of graphical interfaces has been likened to the design of buildings - partly an art, partly a science (Foley & Van Dam, 1984). An application's interface can account for a significant fraction of the code. Surveys of artificial intelligence applications, for example, report that 40 or 50 percent of the code and run-time memory are devoted to interface aspects (Bobrow, Mittal & Stefik, 1986). Smith (1986) points out that user interface software is not only critical to system performance but can also represent a sizeable investment. The production of good interactive software is therefore both difficult and expensive.

Rhyne & Watson (1987) consider that interface requirements are rarely as well defined and stable as requirements for computational algorithms. Farooq & Dominick (1988, p.481) are also of the view that the creation of a user interface requires special skills, tools and methodologies, “because it is an intrinsically different activity from the coding of computational algorithms”. In the context of menu systems, Edmondson & Spence (1992, p.1) observe that “a designer has available, on the one hand, an embarrassingly large repertoire of interaction and presentation techniques, but on the other, a distressingly small toolkit of guidelines, notations, methodologies, frameworks and languages to provide the means for intelligent thought”.

Hartson & Hix (1989, p.8) define dialogue “as the observable two-way exchange of symbols and actions between human and computer”. In this thesis the term dialogue is used to refer to the *structure* of the human-computer interaction expressed in terms of constraints relating to dialogue primitives, and described through the employment of a formal or semi-formal dialogue model. Structural models of the human-computer interface serve as frameworks for understanding the elements of interfaces and for

guiding the dialogue developer in their construction (Hartson, 1989). Rhyne & Watson (1987) take the view that some symbolic specification of interface behaviour appears inescapable for the near future, but that the task is difficult, and can only be made easier through the development of better specification paradigms. A problem identified with some existing dialogue notations is that they describe only the 'surface behaviour' of the interface. New notations must go beyond this and must be capable of associating the functionality of the interface with objects, actions and states. Two concepts associated with dialogue design underpin the research reported. The first is the notion of 'dialogue independence' - the separation of the design of dialogue from the design of computational software. Most current approaches to interface development are based to some extent on dialogue independence. The second is the isolation of the *design* of interactive dialogues from the detail of their implementation.

Interface representation is currently achieved through a variety of notational schemes, including both textual and graphical representation languages. Control structures govern how sequencing among dialogue and computational components is designed and executed, the two basic kinds being 'sequential' and 'asynchronous' (Hartson, 1989). In sequential dialogue only one task is presented to the user at any one time, whereas in asynchronous dialogue more than one task or thread may be available. Asynchronous dialogue is also described as multi-threaded. In this thesis it is assumed to be multi-threaded dialogue *in which there is generally an absence of sequence within the separate threads or subdialogues*. Asynchronous dialogue is also referred to as 'event-based' dialogue (Hartson & Hix, 1989, p.11), "because end-user actions (e.g., clicking the mouse button on an icon) are viewed as input events". It should be noted that asynchronous does not imply concurrent. Concurrent dialogue is multi-threaded dialogue in which more than one thread can be executed simultaneously.

### **Direct manipulation interfaces**

So-called 'direct manipulation' interfaces are asynchronous, with the objects of interest being displayed so that actions are directly in the problem domain. They are most easily understood by example, perhaps the best known being the Apple Macintosh interface (Apple, 1989a) which is used as the basis for the case studies in this thesis. This interface is based on the 'desktop' metaphor in which icons represent documents and folders and in which the mouse is the electronic extension of the hand. This is an example of the more general 'model world' metaphor defined by Hudson & King (1986). Many real direct manipulation interfaces include elements from several styles in a single interface, e.g. menus, dialogue boxes and windows; incorporate objects of a dynamic nature, e.g. windows and icons; and involve concurrency, conditions, and object inter-relationships. The nature of direct manipulation interfaces is examined in detail in Chapter 2 of this thesis.

The specification of direct manipulation interfaces presents particular problems not encountered in other software systems. Myers (1989, p.15) states that “direct manipulation interfaces popular on many modern systems are among the most difficult to implement....because they often provide elaborate graphics, many ways to give the same command, many asynchronous input devices, a mode-free interface (the user can give any command at virtually any time), and rapid semantic feedback”. Rhyne & Watson (1987) highlight the difficulties of testing for potential ambiguities in the design of asynchronous dialogues, and identify a need for tools to assist the designer in building and debugging such dialogues. Hartson & Hix (1989, p.18) see research on structural modelling of asynchronous dialogue as still embryonic, because “such dialogue is less structured than sequential dialogue”. Techniques are required for recording behavioural, structural and detailed representation of both visible and non-visible aspects of direct manipulation interfaces. Ideally the techniques should be independent of tools through which they may be implemented, and be complete in their ability to represent interfaces.

The ‘object-oriented’ paradigm, in which hierarchies of objects are manipulated and where immediate semantic feedback is required, seems to suit the implementation of direct manipulation interfaces (Barth, 1986; Sibert, Hurley & Bleser, 1986; Rhyne, Ehrich, Bennett, Hewett, Sibert & Bleser, 1987; Hartson, 1989; Foley, Kim, Kovacevic & Murray, 1989; Bass & Coutaz, 1991; Markopoulos, Pycock, Wilson & Johnson, 1992). In describing the development of the Xerox Star interface, Smith, Irby, Kimball, Verplank & Harslem (1982) argue that such interfaces are by their very nature object-oriented. Hartson takes the view that object orientation is effective for representing asynchronous dialogue, and for representing the behaviour of specific interface features (e.g. windows), because of its event-based nature. However, he also considers that a disadvantage of object orientation is its tendency to obscure temporal relationships in the high level sequencing behaviour in the application interface.

Event-based mechanisms are currently the primary underlying techniques upon which asynchronous dialogue is constructed. Reliable guidelines for the *design* of direct manipulation interfaces do not yet exist. There is a need for tools that can assist with their design and development.

### **The interface development life cycle (IDLC)**

The interface development process, or life cycle, can be viewed as consisting of a number of stages. Shneiderman (1987) defines an eight stage life cycle, consisting of: collection of information; definition of requirements and semantics; design of syntax and support facilities; specification of physical devices; development of software; implementation and testing; evaluation; and revision. The need to view interface development as an integral part of the software engineering process is being recognised, and this life cycle bears broad resemblance to the more generally prescribed software life



cycle (e.g. Sommerville, 1985). Although this is a step-by-step description, the process is equally iterative. A distinction must be drawn between design representations and design methodologies. The former define the space of objects that can be designed within them and impose structure on them (Moran, 1981). A representation may be incorporated into a methodology, and it is important to show where such representations fit into the scheme of things.

A variety of models at various levels of abstraction have been employed in the early stages of the IDLC. These include user models, task models, and dialogue models. From an implementation viewpoint, Green (1986) broadly classifies the latter into state transition networks, formal grammars, and event-based techniques. User and task models are applicable to the first two stages of the life cycle, that is, to information collection and requirements definition. They form important inputs to the early phase of Shneiderman's third (design) stage, where dialogue models come into play, and where prototyping of the interface may be employed. Prototyping is also sometimes called dialogue simulation, and prototypes may involve executable specifications. Hartson & Hix (1989) view prototyping as an effective way to begin evaluation and testing earlier in the life cycle than was formerly the case. Dialogue models and notations, which are the focus of this thesis, are reviewed in Chapter 3.

### **Existing interface development tools**

Many attempts have been made to develop tools to make the task of designing and implementing interfaces easier. These include user interface toolkits, and so-called 'user interface management systems' (UIMs). Toolkits are libraries of pre-defined interaction techniques offering support for the implementation of limited interaction styles, but providing only minimal support for interface design. UIMs reach further back into the IDLC by providing for the specification of sequencing and dialogue control. In UIMs, the concept of dialogue independence is explicitly recognised and supported. Both UIMs and toolkits are intended to speed up the development of interfaces. Hill (1987) defines the key goals of a UIM as reducing the high cost of implementing user interfaces, and helping improve the quality of user interfaces by facilitating prototyping and experimentation. Hix & Hartson (1986) consider however that many UIMs emphasise the execution-time aspects of interface management at the expense of interface design. Koiuvnen & Mantyla (1988, p.44) state that "the concept of UIM is still also a vague one, and many mutually inconsistent approaches exist". They go on to produce a taxonomy of toolkits and UIMs. Myers (1989) also provides a useful survey of both toolkits and UIMs.

All UIMs are restricted in the forms of user interfaces they can generate. A further limitation of many UIMs is that they require the designer to specify interfaces in a textual, formal, programming-style language (Myers, 1987b). This has proved useful

and appropriate for textual command languages but difficult and clumsy for direct manipulation interfaces. A number of UIMSs allow the designer to use more graphical styles. Examples include Menulay (Buxton, Lamb, Sherman & Smith, 1983), Trillium (Henderson, 1986), and GRINS (Olsen, Dempsey & Rogge, 1985). These are still limited for the most part to using graphical techniques for specifying static aspects of the interface, i.e. to control the *placement* of interaction objects.

A number of problems have been identified with current UIMSs and interface toolkits:

- ♦ they are generally aimed at the programmer rather than the designer (Olsen, 1987a, 1987b; Myers, 1987a, 1989; Rhyne *et al*, 1987; Cockton, 1987, 1990b);
- ♦ they have borrowed models from other areas of computer science (Cockton, 1987);
- ♦ they are difficult to use (Rhyne *et al*, 1987);
- ♦ they support only part of the IDLC (Myers, 1989);
- ♦ they cannot support the development of direct manipulation interfaces (Myers, 1987a, 1989);
- ♦ they are unavailable commercially or not portable (Myers, 1989);
- ♦ they do not support evaluation (Myers, 1989).

Cockton (1990a, 1990b) considers models and architectures to be central to the development of tool-based design environments for interactive systems, which he calls 'interactive system design environments' (ISDEs). Cockton believes that current software practice is still dominated by a 'programming language' approach, where the designer's representation of the formalism is the implementation language. Olsen (1987b, p.73) goes further, stating that "A UIMS can be viewed as a tool for increasing programmer productivity". Myers (1987a) even argues for a UIMS classification based on the level of programming skills needed to use them, which he sees as closely tied to their ease of use. Olsen (1987c) considers that difficulties in expressing interfaces in 'borrowed models' have led to UIMSs not being used, in spite of large potential productivity gains. Rhyne *et al* (1987) see the difficulties in using current UIMSs as arising partly from the difficulty of the problem, partly from the considerable programming skills required by users of today's tools, and partly because tool interfaces are themselves badly designed.

Most automated tools support the developer in the *coding* phase of software production, not the design phase, and they generally lack tools to facilitate construction of human-computer interfaces (Hartson, 1989). Markopoulos *et al* (1992) take the view that recent generations of UIMSs have provided the designer with increasingly sophisticated design tools supporting rapid prototyping. They go on to argue that prototyping is largely a trial and error software engineering activity to support implementation,

providing no explicit theory beyond the particular implementation, and lacking principles for design and design decisions. Models and tools must be developed that provide support for the design process, to enable a designer to evaluate the consistency and completeness of the definition. Rhyne *et al* (1987, p.83) argue that “consistency is more likely to result when designers have a clear and spare mental model of the interface”.

It must be recognised that direct manipulation interfaces are intrinsically complex, and may include multiple states, simultaneous interaction events, complex constraints, communication with the application, and elaborate feedback. Hudson (1987) argues that syntax (for direct manipulation interfaces) should be in terms of individual objects, should be as simple as possible, and should involve physical actions such as pointing or dragging instead of more linguistic concepts. This implies that previous approaches based on state transition networks or grammars which control the overall interface are not good candidates for direct manipulation interfaces. Jacob (1986, p.287) supports this, stating that “it is unnatural, though possible, to describe the user interface of a direct manipulation system as a conventional dialogue by means of a syntax diagram or other such notation”. Cockton (1987) considers that the real issue is find a language that captures the *user's* view of a direct manipulation interface as perspicuously as possible, and with as few ad hoc features and extensions to the specification technique as possible. He also considers (Cockton, 1990b) that models are of limited use when we do not really understand the properties which component abstractions should satisfy. The identification of these properties for direct manipulation interfaces is central to this research.

### **The need for ‘high level’ tools**

It is not enough for the designer or user to ‘patch together’ an interface using a toolkit. In supporting this view, Rhyne *et al* (1987, p.85) argue that “The complexity of the design problem at this level precludes the simple assembly of interaction technique modules”. There is a need for ‘high level’ tools, models, and techniques for the designer, providing for both interface creation and interface analysis. Foley (1987) defines high level user interface representation as embodying information about the interface in terms of objects, actions, relations, attributes, and pre- and post-conditions associated with the actions. Alexander (1987) considers it important that interface designers are able to experiment with different ideas at the early stages of the interface development process.

With one or two exceptions (e.g. the UofA UIMS (Singh & Green, 1991)), there are few tools to support high level design of user interfaces. To some extent this is a consequence of the variety of individual methodologies in use, but Rhyne *et al* (1987) consider the greater cause to be the fact that few researchers have attempted to build such tools. Both Cockton (1990b) and Guindon (1990) also support this view. Guindon

observes that high level design has seldom been empirically studied, and that it is poorly supported by software tools and environments available today. Farooq & Dominick (1988, p.491) argue that higher level directly executable specification techniques are needed to avoid burying the interface designer in low level details, "especially during the experimentation associated with prototyping such interfaces". Olsen (1987a) identifies a goal for future research as being the development of designer oriented tools - in particular, tools that automate the design process, that involve high level representations of the user interface, and that allow designers to produce different styles of user interfaces. The high level design of interfaces is arguably the weakest link in the chain, and is an under-researched area.

Parallels can be drawn with two other areas of systems design:

- ♦ *The development of data models for database design*  
In the 1960s and early 1970s databases were designed using various implementation models, (hierarchical, network, or relational). Not until the mid 1970s was attention devoted to the development of independent conceptual data models, e.g. the E-R model (Chen, 1976), for use in the early stages of data base design.
- ♦ *The production of systems requirements specifications*  
Tse & Pong (1991) argue that a requirements specification should be independent of the design and implementation of the target system, and that the supporting language should be behaviour-oriented and non-procedural. It should provide a means of improving the conceptual clarity of the problems, should allow us to model logical and physical characteristics separately, and should be expressible in a precise notation with a unique interpretation. They also present a case for a hierarchical framework to permit downwards movement from higher levels of abstraction to more detailed descriptions.

Olsen (1987b) takes the view that the use of high level specifications should simplify the production of user interfaces. However, referring to existing models created for specifying interactive tasks, he states (Olsen, 1987c) that there are very few guidelines or principles to direct high level design of interfaces. He sees most current UIMS developments as being driven not by the task model but rather by syntactic and device oriented models. Smith (1986) argues the importance of distinguishing the underlying logic or architectural form of user interface functions from the detailed presentation of those functions to the user. Anderson & Apperley (1991, p.2) state that "initially what is needed is some form of abstraction that permits the basic dialogue structure of the interface to be defined, and then the details....to be added as required". In the context of menu systems, Apperley & Spence (1989) identify the need for a design methodology for the dialogue designer which should in itself provide a good interface to

the designer, and which should reflect the *structure* of the dialogue rather than the underlying program.

In order to characterise at a high level the interaction between a user and a system an explicit representation of the *behaviour* of the system itself is needed (Kieras & Polson, 1983). Edmondson (1991, p.8) notes that this is *underlying* behaviour "as distinct from the *superficial* behaviour we observe when looking at the mechanics of the interface". A representation of the behaviour of an interactive system should be independent of the implementation, and should reflect structural properties such as hierarchy, possible modes, and consistent patterns of interaction, in addition to being easy to define and understand. This representation will involve both semantic and syntactic aspects of the interface. Olsen (1987b, p.75) takes the view that the semantics of an application are expressed in "the behaviour of the objects and actions of the user interface and in the relationship between these objects and actions". Chakravarty & Kleyn (1990) observe that the interference of events internal to a task with the events in a higher level task making use of it, or with tasks that are interleaved in a multi-threaded execution, is a major problem associated with developing a specification of high level system behaviour.

### **Formal vs informal specifications**

There is a tension between the merits of a fully formal specification, defined in a language which is mathematically precise and in which strict syntax and semantics are used, and the need in the early stages of design for a less formal and more intuitive approach as an aid to understanding the system being designed. Carey & Graham (1987) consider that any (design) method must be formal enough to provide benefits throughout the development cycle, and natural enough for designers to use it productively. Green (1986) argues that on the one hand design notations can be very informal, since their main purpose is to record the thoughts of the designer, but that on the other hand the notations used in the implementation of user interfaces must be formal, since they will be used to produce the implementation of the interface. Cockton (1987) sees the need for users to be able to comprehend and understand future dialogue models as more important than identifying a mathematically optimum model. Moran (1981) supports this view, arguing that a model can be too abstract, and thus difficult, for most people to grasp. Harbert, Lively & Sheppard (1990) consider the range of things that must be specified in a user interface to be too broad for any one form of specification.

Guindon (1990) considers that the early stages of design are best characterised as 'opportunistic'. He defines opportunistic design (p.336) as "design in which interim decisions can lead to subsequent decisions at various levels of abstraction in the solution decomposition". The results of this study have implications for methods and environments that support the early stages of design: representation languages should

support a smooth progression from requirements expressed informally to design decisions expressed formally or semi-formally, in code.

Docker (1989) in the context of the development of a structured analysis programming environment, quotes from Gehani & McGettrick (1986, p.vii): “Formal specifications do not render informal specifications obsolete or irrelevant; although they (formal specifications) can be checked to some degree for completeness, redundancy, and ambiguity, and can be used in program verification, they are often hard to read and understand. Consequently, informal specifications are still necessary as an aid to the understanding of the system being designed; informal and formal specifications complement each other”. Docker also suggests the possibility of a spectrum of descriptions going from informal at one end to strictly formal at the other, and introduces the term ‘semi-formal’ to describe, for example, the class of techniques called ‘structured systems analysis’. He sees these techniques as having been developed (p.8) “in an attempt to improve both the approach to analysis, and to place the emphasis more on the *graphical* presentation of information as a better method of communications”.

### **Focus on a graphical representation**

It has been argued (Tse & Pong, 1991) that graphical languages are better at the higher levels of abstraction, and textual languages are better for providing detailed description. In the context of specifying systems requirements, Tse & Pong argue that graphical representation of complex material is much more comprehensible than its textual counterpart, because it is two-dimensional rather than one-dimensional, and therefore provides an additional degree of freedom in presentation; because it can show naturally both hierarchy and concurrency; because it can be read selectively rather than linearly; because it reduces the number of concepts to be held in short-term memory; and because the reader can move naturally from higher to lower levels of detail. Harel, Lachover, Naamad, Pnueli, Politi, Sherman & Shuti-Trauring (1988) consider that languages for describing reactive systems ought to make it possible to move easily from the initial stages of requirements and specification to prototyping and design. They go on to suggest that specifications, including behavioural aspects, should be based to a large extent on ‘visual formalisms’ depending on a small number of carefully chosen diagrammatic paradigms. (Harel, 1988, p.528) supports the use of visual formalisms for representing computer-related systems “because they are to be generated, comprehended, and communicated by humans”.

This suggests an approach to interface design in which a semi-formal high level graphical specification is augmented by non-graphical detail, and subsequently mapped into a more formal dialogue specification language for implementation; that is, an approach based upon multiple specifications. At the highest level of design what is needed is a visual vocabulary suitable for ‘sketching’ the interface, a representation able

to capture both user and system interaction with the visual display. In the words of Jacob (1985, p.52): “a visual representation chosen for this purpose needs to describe the external (user-visible) behaviour of the user interface of a system precisely, leaving no doubt as to the behaviour of the system for each possible input. It should separate function from implementation, describing the behaviour of a user interface completely and precisely without unduly constraining the way it will be implemented”.

Chakravarty & Kleyn (1990) consider that compactness and readability are crucial to the usefulness of visual formalisms (which they term ‘visualisms’) applied to the description of the behaviour of reactive software systems. The control aspects of such systems comprise the generation and processing of external and internal events, the actions performed as a result of the events, the directions of control flow, and the concurrency of events, all of which contribute to the difficulty of specifying and understanding system behaviour. In any visual formalism there is a trade-off between the visual complexity of the graphical notation and the effort required to use it. As the visual complexity increases, the effort required to use the notation effectively also increases.

It is interesting to note that the most successful and widely adopted graphical representations in other fields of systems design have been simple notations with a few easily understood constructs, for example, the E-R notation (Chen, 1976) in high level data base design, and the data flow notation of structured systems analysis (Gane & Sarson, 1979). The event model, a candidate for describing direct manipulation interfaces, has to date lacked a graphical representation. Issues associated with graphical notations are explored further in Chapter 3 of this thesis.

## **1.2 Objectives of the research**

The principal objective of this research is to develop a semi-formal graphical notation and associated methodology for use during the high level design phase of interface development. The notation should be targeted specifically at direct manipulation interfaces and should be extensively evaluated in the context of an existing interface. Implicit in this objective are the following secondary objectives:

- ♦ That visually, the notation should:
  - have a small number of simple concepts;
  - be suitably expressive, and in particular reflect the object oriented nature of direct manipulation interfaces;
  - be compact, and maintain locality between dialogue elements.
- ♦ That the notation should be suited both to the analysis of existing interfaces, and to the high level synthesis of component dialogues for new interfaces.

- ♦ That the notation should be executable, and thereby support a limited form of early prototyping of interfaces.
- ♦ That the notation should be mappable into a formal dialogue specification language, and thereby support interface prototyping and implementation.

### 1.3 Approach adopted

The approach to achieving the objectives set out in Section 1.2 can be summarised as follows:

- ♦ The nature of direct manipulation interaction is established, and the desktop metaphor is examined with reference to the Apple Macintosh. Three views pertinent to the development of direct manipulation interfaces are identified (Chapter 2).
- ♦ Existing dialogue notations are reviewed in the context of direct manipulation interfaces, with a focus on graphical representations for specifying underlying interface behaviour to support high level design. Some preliminary results of this research have been published (Phillips, 1991). Based on this analysis, the required scope of a direct manipulation dialogue model is established (Chapter 3).
- ♦ A task analysis of part of the Macintosh interface is undertaken in order to establish the fundamental nature of direct manipulation interaction. The results of this analysis have been published (Phillips & Apperley, 1991). A framework for developing and extending Lean Cuisine (Apperley & Spence, 1989), a tree-structured graphical notation for describing the behaviour of menu systems, is defined (Chapter 4).
- ♦ Lean Cuisine is developed incrementally into an object-based multi-layered notation, Lean Cuisine+, providing for specification of the full range of constraints and dependencies which exist between selectable dialogue primitives in a direct manipulation interface. This development is achieved through the description of the behaviour of part of the Macintosh interface (Chapters 5 and 6). Aspects of this research have been published (Phillips, 1992).
- ♦ The role of Lean Cuisine+ in interface design is considered, and an orthogonal task layer is added to the notation. A five stage design methodology, commencing with a task decomposition is developed and applied to an example interface (Chapter 7).
- ♦ A specification for a software environment to support the construction, browsing, and execution of Lean Cuisine+ specifications is developed. The extensions to support execution complete the Lean Cuisine+ notation. The software environment is partially prototyped using HyperCard. Mapping to a more formal dialogue specification language to support interface prototyping and implementation is considered (Chapter 8).



- ◆ The Lean Cuisine+ notation is reviewed and the contribution of the research examined critically (Chapter 9).

## **1.4 Structure of the thesis**

The thesis is arranged in three parts. Part 1 includes this introductory chapter, Chapters 2 and 3, which present the major part of the literature survey, and Chapter 4, which establishes a framework for the notation developed in Part 2.

In Part 2, the basic Lean Cuisine+ notation is developed in Chapters 5 and 6, and extended in Chapters 7 and 8. Chapter 7 also presents a methodology for the construction of Lean Cuisine+ specifications, and Chapter 8 defines a software environment to support the notation.

Part 3 contains a single review chapter, Chapter 9, in which the contribution of the research is examined and further work identified.