- 1 Testing social learning of anti-predator responses in juvenile jackdaws: the importance of
- 2 accounting for levels of agitation
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9 Abstract

Social learning is often assumed to help young animals respond appropriately to potential 10 11 threats in the environment. We brought wild, juvenile jackdaws briefly into captivity to test whether short exposures to conspecific vocalisations are sufficient to promote anti-predator 12 learning. Individuals were presented with one of two models – a stuffed fox representing a 13 14 genuine threat, or a toy elephant simulating a novel predator. Following an initial baseline presentation, juveniles were trained by pairing models with either adult mobbing calls, 15 indicating danger, or contact calls suggesting no danger. In a final test phase with no 16 17 playbacks, birds appeared to have habituated to the elephant, regardless of training, but responses to the fox remained high throughout, suggesting juveniles already recognised it as 18 19 a predator before the experiment began. Training with mobbing calls did seem to generate elevated escape responses, but this was likely to be a carry-over effect of the playback in the 20 previous trial. Overall, we found little evidence for social learning. Instead, individuals' 21 22 responses were mainly driven by their level of agitation immediately preceding each 23 presentation. These results highlight the importance of accounting for agitation in studies of 24 anti-predator learning, and whenever animals are held in captivity for short periods.

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26 Keywords: predator recognition, mobbing, corvids, captivity, habituation, personality

27 Introduction

28 The ability to recognise and respond appropriately towards predators is a critical component of fitness. Many young animals appear to recognise predators as being dangerous on their 29 first encounter (1–3), be this through genetically determined responses (4) or through 30 information acquired during development (5,6). For many species, however, learning during 31 32 early life plays a major role in the development of predator recognition (7,8). Learned predator recognition is likely to be particularly advantageous in highly variable or 33 heterogeneous environments, where predator assemblages and predation risk can vary 34 spatially and/or temporally. Animals may learn about predators and potential sources of 35 danger through personal experience of being chased, by observing predators attacking 36 conspecifics (9,10) or through the anti-predator signals and cues of conspecifics alone 37 38 (reviewed in 11). In aquatic environments learning about danger via social cues often involves the learned association of chemosensory information, such as the pairing of the chemical 39 distress signals of an attacked conspecific with the scent of the predator (12,13). In contrast, 40 41 in terrestrial systems information about predators is commonly conveyed by visual and acoustic means (11). Vocalisations made in response to predators can act as a warning of 42 43 danger, eliciting flight responses, but many species also produce distinctive 'mobbing' alarm calls when a predator is spotted (14). These calls can encode information about the nature of 44 the threat (15), triggering responses in both hetero- and conspecifics (16,17) that may either 45 46 flee or may join the instigator in mobbing the target in an attempt to drive it away from the area (18). 47

A large body of experimental evidence shows that mobbing vocalisations can also help naïve
individuals to learn socially about danger. In a pioneering experiment, Curio et al. (19)

instigated a mobbing response in observer blackbirds (Turdus merula) towards a stimulus that 50 they had previously treated as being harmless (a model friarbird, Philemon corniculatus, or a 51 plastic bottle), by allowing the observer to witness a demonstrator mobbing the model. The 52 demonstrator was in fact mobbing a model owl that was hidden to the observer, but this 53 54 learned association between the demonstrator's mobbing response and the (harmless) stimulus resulted in the transmission of mobbing responses along a chain of six individuals by 55 56 using the observer as the demonstrator in each subsequent trial. While the great majority of 57 research has been conducted in controlled laboratory settings, such cultural transmission of predator recognition has since been documented in the wild. For instance, American crows 58 59 (Corvus brachyrhynchos) with no experience of being trapped or observing trapping socially 60 learned to mob researchers who returned to the area wearing the same mask that had been worn when individuals from the previous generation of crows had been captured (20). 61

In recent decades a number of experiments have successfully trained naïve individuals about 62 predators or brood parasites through pairing model predator or brood parasite presentations 63 64 with a training stimulus. This stimulus was either a live conspecific demonstrator engaging in 65 mobbing (19,21,22), mobbing calls paired with mounts of conspecifics (23), or mobbing calls 66 alone (18,21,24), but in all cases the training phase lasted between 2 and 5 minutes. While such prolonged learning opportunities may reflect cases in which mobbing continues until the 67 target moves away or the mobbing group loses interest (25–27), in many instances exposure 68 69 to conspecifics' anti-predator responses are fleeting. For example, many predators are highly 70 mobile, actively hunt their prey using the element of surprise and leave the area rapidly after 71 an unsuccessful hunt (e.g. 28,29), providing prey species with only brief but vital opportunities 72 for learning from conspecifics' responses. We tested whether a short, eight second exposure

to conspecific mobbing calls might be sufficient to train individuals to respond fearfully to anovel predator.

We conducted our study on wild jackdaws (Corvus monedula), highly social members of the 75 corvid family. Jackdaws breed colonially, and short bursts of scolding calls are commonly 76 77 heard in colonies in response to passing predators (G. McIvor, Pers. Obs. 2014). Jackdaw 78 nestlings fledge from cavities from 30 days after hatching (30), and are dependent on their 79 parents for up to 6 weeks thereafter (31,32). In response to predators, adult jackdaws 80 produce distinctive anti-predator mobbing calls known as scold calls. Scold calls can be 81 emitted singly to act as a warning of danger (e.g. if a predator is passing by), or repeated to 82 recruit others to mob. These calls are likely to play a key role in helping young jackdaws learn about danger. Indeed, Lorenz (7) suggested, based on his observations of hand-reared 83 84 jackdaws, that predator recognition is socially learned in this species, though this remains to be tested. 85

To control individuals' exposure to experimental stimuli and allow comparisons of their 86 87 responses before and after exposure to social information, we brought juveniles temporarily 88 into captivity for testing. This represents a compromise between testing in laboratory 89 conditions, where the proximity of test stimuli and absence of distractions may artificially 90 enhance social learning (33), and field experiments on unconstrained individuals where it can be extremely difficult to ensure that subjects attend to the relevant stimuli over repeated 91 controlled presentations. Free-living juveniles were captured for the experiment 2 to 6 weeks 92 93 after fledging using walk-in traps. Captured birds were transferred to a nearby aviary, and 94 after an acclimatisation period given a series of presentations of one of two models – a stuffed fox to represent a genuine threat, or a toy elephant that simulated a novel predator. The first 95

96 presentation that each bird received was made with no accompanying playback, to gain a measure of their baseline response to the model stimulus. In conjunction with the second 97 time the model was presented, the birds also received an 8 second playback of the calls of 98 99 colony members – either scold calls that suggested danger, or contact calls that suggested no 100 danger. Such brief calling events are common in jackdaw colonies. To test whether the 101 scold/contact call playback in the training phase influenced the subsequent response of 102 individuals towards the model, we presented the model a final time with no accompanying 103 playback. We predicted that birds shown the elephant with scold calls would show a greater 104 escape response to the model than those shown the elephant with contact calls, and would 105 also direct scold calls at the model. In contrast, we expected the jackdaws to already recognise foxes as a threat and thus show an equally high escape response to the fox model regardless 106 of which playback they had received. Finally, we predicted that the response of birds in the 107 108 elephant-scold group would match the escape response level of those birds shown the fox 109 model.

110 Methods

111 Subjects and Housing

The experiment was carried out over 14 days in July 2015. Forty-eight juvenile jackdaws were captured using a passive walk-in trap baited with bread and oats. Half of the birds used in the experiment had been ringed as chicks at our study site and had a known fledge date. On average these birds fledged from the nest 31 days before capture (range = 19 to 43 days). As breeding is highly synchronous across our jackdaw population (>90% of all nests fledge within a 14 day period; unpublished data), the 24 birds whose fledging date was unknown were likely to have been at large in the environment for a similar length of time and have had a similar
likelihood of having encountered predators as the birds with known fledging dates.

120 Once captured, individuals were removed from the walk-in trap and transferred to a separate, temporary aviary in a field 100m away. Although we cannot rule out the possibility that 121 122 jackdaws flying past may have observed experimental presentations to other individuals 123 before they themselves received them, this is very unlikely given that models were only 124 displayed for a few seconds during presentations before being returned to a concealed 125 position. The aviary consisted of a wooden frame (2x3x1.8m) covered by game-bird netting, which allowed the bird to see in all directions. A diagram of the experimental arena is 126 provided in the supplementary materials. Half of the roof was covered in wooden boards to 127 provide shade, and two screens were provided at the back of the aviary behind which the bird 128 129 could hide. Branches were provided as perches in each corner, and a central beam ran across the middle of the arena that could also be used as a perch, as could the ledges than ran around 130 the outside of the arena. All birds were provided with a dish containing food (rolled oats) and 131 water. Birds were typically kept in the aviary for 25 to 35 minutes, after which they were 132 released. 133

134

135 Experimental Procedure

Following transfer from the walk-in trap to the experimental aviary, each jackdaw was given 137 10 to 15 minutes to calm down and acclimatise to its surroundings before the experiment 138 commenced. This start time was consistent with the exception of 2 of the 48 trials, where the 139 birds receiving longer periods because of farm machinery moving nearby (mean duration of

140 acclimatisation period (SE) = 12.75 (0.51) mins; range: 10-32 mins). The 10 to 15 minute period was considered to be an acceptable compromise between the need for time to 141 acclimatise to the aviary and the ethical requirement of minimising the total length of time 142 that juvenile birds were separated from their parents, upon whom they were still partially 143 dependent. Birds were shown one of two models, in a series of three separate presentations: 144 145 (1) Baseline, (2) Training and (3) Test. Twenty-four birds were shown a toy elephant to 146 simulate a novel predator. This stimulus was deliberately chosen so as to avoid any potential 147 resemblance to any animal the jackdaws may have encountered previously. To provide an ecologically relevant comparison, the other 24 birds were shown a taxidermy model of a red 148 fox (Vulpes vulpes), a predator that is common around our study site and is frequently 149 mobbed by jackdaws when encountered. The elephant model was of roughly equivalent 150 height and length as the fox model. Birds were assigned to their model group at random, and 151 152 received three presentations of the same model. The model was located in a hide 10m from 153 the front of the aviary, and was mounted onto a skateboard to allow it to be smoothly moved 154 in and out from the concealed position. Stones were piled in front where the models emerged 155 so that the birds would only see the model, and not the skateboard. The skateboard's movement was controlled by an experimenter inside an adjacent hide by way of a connecting 156 157 broom-handle (see figure S1 in supplementary materials).

Presentation 1 was intended to measure the *Baseline* response of the bird to the model, and involved the model being rolled from the concealed position and sitting stationary in the open for 8 to 10 seconds before returning to cover, with no accompanying playback. Five minutes after Presentation 1, the birds were shown the same model again in Presentation 2, the *Training* phase, where the model was accompanied by a playback. The playback contained

either contact calls that would suggest there was no danger posed by the model, or scold calls that would suggest that the model was dangerous. Both the model and playback type to which the birds were assigned were allocated at random, but with a limit of 12 individuals to each combination of model and playback type. The specific playback track that the bird received during the *Training* presentation was also allocated at random, from a choice of six playback tracks for both the Scold and Contact call groups.

All calls used for playbacks were collected using Olympus LS-100 digital recorders (Olympus 169 170 Corporation, Tokyo, Japan), used in conjunction with two types of microphone. Contact calls were obtained by recording calls between pairs at nest boxes using AKG-C417PP lapel mics 171 (AKG Acoustics, Vienna, Austria). Scold calls were collected using Sennheiser ME66 shotgun 172 173 microphones (Sennheiser Electronic GMBH & Co. KG, Wedemark, Germany) with a Reinhardt 174 windshield when nests were being visited by researchers. There is no evidence that the scold calls of jackdaws are predator specific, and previous experiments at our study sites show that 175 playbacks of scold calls recorded in response to humans elicit collective anti-predator 176 177 responses as if a predator were present (34). In our recordings, the identity of all callers was 178 known, and only calls from adult individuals nesting in the colony where the experiment was 179 carried out were used. Callers were not related to test subjects, and the parentage all marked juveniles was checked prior to the trials to ensure they had not been allocated a playback 180 track that contained the calls of a parent. Each playback contained the calls of four birds, and 181 182 each bird contributed 3 calls each. Playback tracks were prepared using the open source audio 183 editing software Audacity (www.audacityteam.org), with normalised amplitude across all 184 tracks. The playbacks were made through three separate FoxPro Fury (FOXPRO Inc., 185 Lewistown, PA, USA) speakers, to simulate a natural bout of calling by a group of jackdaws.

186 Speakers were set to volume level 18, simulating the amplitude of a calling bout 10 m away (c.72dB) as measured using a Voltcraft SL-100 sound level meter. The three speakers were set 187 to the same operating channel to allow them to be controlled by a single handset. They were 188 arrayed in an arc around the hide from which the model was presented, and each speaker 189 190 contained a different track loaded in each position on their memory. This meant that all three speakers would play a different track of four calls simultaneously over an 8 second period. 191 192 This produced a playback of 12 calls in total, containing calls from 3 individual birds, with each 193 individual contributing 4 calls each (see Supplementary Materials S1). The playback slot was assigned at random for each bird. Each of the three tracks that occupied a memory slot had 194 195 been prepared simultaneously in Audacity, and this ensured that they each achieved an identical effect. Playbacks were arranged so that the time between calls on the three 196 synchronised tracks decreased as the playback continued, simulating the build-up of calls 197 198 that occurs naturally during social chatter(contact call group) or recruitment to a mobbing 199 event (scold call group).

Five minutes after the end of Presentation 2 the birds received the third and final *Test* presentation. The procedure was identical to Presentation 1, and served to test whether the responses of the birds changed as a result of the playbacks they heard in Presentation 2. Five minutes after the end of Presentation 3, the birds were removed from the aviary and released. The birds were filmed for the full time spent in the aviary using a Panasonic HC-X920 camera (Panasonic Corporation, Osaka, Japan).

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207 Video and Data Analysis

Videos were coded using Noldus Observer XT12 (Noldus Information Technology Inc., 208 209 Wageningen, Netherlands). Coding of videos was done blind to both the model and playback type to which the bird had been assigned, by a single observer (GM). The number of flights 210 made by the bird in the 60 s prior to the model presentation, and 60 s following the 211 presentation were recorded, as was the distance travelled during these flights. There was a 212 213 high level of collinearity between the number of flights and distance travelled (r=0.964), so 214 the number of flights made was used as a response variable as this was less subjective. We 215 also recorded any vocalisations made by the birds. We analysed the data using R version 3.1.2 (R Core Team), and the packages Ime4, pastecs, ggplot2 for graphs, and Imtest for Breusch-216 217 Pagan tests.

218 We analysed the influence of the presentation number (1,2 or 3), model (fox or elephant), 219 and playback type (scold or contact calls) on the number of flights that the birds made in the 60 seconds after each presentation, which we interpreted as an indicator of individuals' 220 stress/escape responses towards the model. We used general linear mixed models (Ime4 221 222 package), with focal bird identity and playback track fitted as random effects. The number of 223 flights made by the birds in the 60 seconds before each presentation was included as an 224 additional explanatory term in each model, to account for any captivity-induced agitation and/or carry-over effects from previous presentations. Over-dispersion in the raw data made 225 Poisson error structure unsuitable, so we square root transformed the response variable 226 227 (number of flights in 60 seconds post-presentation) which allowed the model to be fitted with a Gaussian error structure. Model plots were examined for evidence of violation of 228 229 assumptions, and refitted as GLMs to allow a Breusch-Pagan test to check for 230 heteroscedasticity in the data. We fitted 19 models in total, containing all potential

231 combinations of the three main explanatory variables (model, playback type, and 232 presentation number) and the possible interaction terms, as well as the number of flights in 233 the 60 seconds prior to the presentation as a main effect only.

To further examine the factors influencing responses in the test phase, we conducted an additional analysis, using only the data from the 60 seconds before and after Presentation 3. In this analysis we used linear regression models, to test the influence of the playback, model, and the number of flights made in the 60 seconds prior to Presentation 3 on the number of flights made by the birds in the 60 seconds after. The number of flights before and after the presentation was square-root transformed, as in the previous analyses.

We used an information theoretic (IT) approach to model selection, using Akaike's Information Criterion corrected for small sample sizes (AICc) to rank the models, following the approach advocated by Richards et. al (35). Models that had a Δ AICc \leq 6 of the model with the lowest AICc value (Table 1) formed the 'top set'. We then applied the 'nesting rule' (36) to the top set, whereby models that were more complex versions of nested models with a lower AICc value were removed from the top set so as not to retain unnecessarily complex models.

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248 Results

249 Effects of training on responses

Individuals showed substantial variation in their responses to the three model (i.e.
fox/elephant) presentations (Supplementary materials; Fig S3). In mixed model analysis, four
models formed the top set (Table 1), and from these models numbers 6 and 9 were retained

253 (Table 2) following application of the nesting rule (36). In both models, the number of flights 254 made in the 60 seconds prior to each presentation being made was a strong positive predictor of how many flights were made in the 60 seconds following the presentation (Table 2). Both 255 256 candidate models also included an interaction between presentation number and model type. Birds shown the Elephant model displayed a substantial decrease in response to 257 258 Presentation 3 compared to Presentation 1, while those shown the Fox did not (\overline{x} (SE) 259 Number of Flights made in the 60 s after presentation: Fox Presentation 1 = 9.66 (1.59), Fox 260 Presentation 3 = 9.46 (1.41); Elephant Presentation 1 = 9.75 (1.41), Elephant Presentation 3 = 261 5.75 (1.28); Figure 1, Table 2).

262 Between Presentation 1 and Presentation 2 there was no change in the response of the birds to the presentation, regardless of the model shown or playback heard in Presentation 2, with 263 264 the birds showing a similar level of alarm in each (Table 2, Figure 1). Birds that were played scolds in Presentation 2 generally flew more in response to presentations across all 265 presentation periods and regardless of the model shown (\overline{x} (SE) Number of Flights made in 266 267 the 60 s after presentation: Contact call group birds = 7.42 (0.76); Scold call group birds = 268 10.56 (0.89)). However, while playback type was a term in the model with the lowest AICc 269 (Model 6, Table 1), it did not appear to have a robust effect on the number of flights made in 270 the 60 s after the presentation (estimate (SE) = 0.369 (0.226), t = 1.63, p = 0.11; Model 6, Table 2) and did not appear in the second best model (Model 9; Table 1). 271

272 Only two birds made scold calls during the experiment, and neither case occurred during the 273 60 seconds after a model presentation. Both cases occurred between Presentations 2 and 3, 274 with one bird (Fox-Scold group) directing the vocalisation at a passing buzzard (*Buteo buteo*),

while the other (Fox-Contact group) appeared to direct the vocalisation in the direction of thehide where the fox was concealed.

277

278 Potential carry-over effects of playbacks

279 In the analysis that considered only the responses to the final, Test presentation, there were 280 three models in the top set, but after the nesting rule was applied only one was retained (p3.model4; Table 3, Supplementary Materials S2). As in the previous analysis, birds were 281 282 likely to fly more in response to presentations of the fox than the elephant (Estimate (SE) = 283 0.916 (0.245), t = 3.74, p < 0.001, Figure 1) and the number of flights made in the 60 seconds 284 pre-presentation predicted the number of flights after the presentation (Estimate (SE) = 0.777 (0.077), t = 10.06, p < 0.001; Figure 2). The number of flights in the 60 seconds prior to 285 the presentation (pre60) was by far the best predictor of post-presentation responses, with 286 all models containing this term having an adjusted-R² ranging from 0.63 to 0.72 (Table 3). 287 288 However, if we did not account for agitation, and left pre60 out of the analysis, then playback type changed from being a non-significant predictor of the birds' behaviour following 289 Presentation 3 to having $\alpha \leq 0.05$ (p3.model6 and p3.model9). On average, birds that had been 290 291 played scolds in Presentation 2 flew more than those that had heard contact calls (\overline{x} (SE) 292 Number of Flights made in the 60 s after presentation: Scold call group = 9.5 (1.4), Contact 293 call group = 5.7 (1.3); Est (SE) = 0.886 (0.421), t = 2.10, p = 0.04).

294 Discussion

Predation is typically the main cause of mortality for fledgling birds (37–39), so there is great
 pressure on young individuals to quickly learn how to identify and respond to potential

297 predators. While experiments have demonstrated that birds can learn about novel predators 298 through exposure to social information over several minutes (19,23), it remains unclear 299 whether the very brief exposures to social information that often accompany natural 300 predator attacks are sufficient to promote learning. Moreover, experimental tests of anti-301 predator social learning outside of controlled laboratory setting remain rare.

302 Here we found that, contrary to expectations, brief exposures to social information in the 303 form of conspecific vocalisations did not appear to produce a consistent change in young 304 jackdaws' responses to potential predators. If social learning had a strong effect, we would 305 expect naïve birds to show low baseline responses to models which increased following scold 306 call training and declined or remained constant following control call training. Instead, birds 307 often showed high levels of agitation from the start of the experiment, with an overall decline 308 in the number of flights made in response to the Elephant from presentation 1 to presentation 3, while responses to the Fox remained elevated throughout, regardless of training. This 309 suggests that the jackdaws may have habituated to the novel Elephant stimulus through 310 311 repeated presentations, and that most if not all individuals already recognised the Fox as a 312 threat from the start of the experiment. Although visual inspection of Figure 1 suggests that 313 the responses of birds given scold call training may have remained elevated while those with contact call training declined, our analyses showed no clear statistical evidence for an 314 interaction between presentation number and playback type. We did find some weak support 315 316 for a main effect of playback type, with scold-trained birds tending to fly more than those that 317 heard contact calls (playback type features in the top model, but does not have a significant 318 effect at α = 0.05). However, this effect was consistent across both model groups, suggesting 319 that it could be the result of birds still being in an elevated state of agitation as a result of

recently having heard scold calls, rather than specific learned responses towards the models. Indeed, the number of flights made in the minute before presentations was by far the strongest predictor of the subsequent responses to the presentations (Figure 2), indicating that captivity- and/or carry-over induced agitation rather than social learning was the primary driver of behaviour.

325 This conclusion is further supported by analyses honing in on responses to the final, test 326 phase. Here, as in the main analysis, we found stronger responses to the Fox than to the 327 Elephant but, as before, the strongest predictor was the number of flights in the minute 328 preceding the presentation. Playback type did not appear to have a robust effect on responses, as it did not feature in the top model, and its inclusion produced only a 1% 329 330 improvement in the variance explained (adjusted R^2 of model 2 = 0.72; model 4 = 0.71). To the extent that there was some small increase in the responses of birds that heard scold calls 331 compared to those that heard contact calls, this was consistent across both model types and 332 is most likely to represent a carry-over effect from calls heard in training. It is important to 333 334 note that, had we not accounted for levels of agitation prior to presentations, we could have 335 reached very different conclusions, as playback type did appear to have a statistically 336 significant effect (p < 0.05) when pre-presentation flights were not included in the analysis.

Although our experiment failed to generate the predicted effects, it nevertheless has a number of important fundamental and practical implications. First, our results show that taking levels of agitation induced by captivity and/or carry-over effects into account is critical for studies attempting to train animals to respond to novel stimuli. Given the growing emphasis on harnessing social learning to promote adaptive behaviours in conservation contexts (40,41), accounting for agitation will be vital in the design and interpretation of such

research. This may be particularly important for species such as corvids that exhibit high levels 343 of neophobia (42,43) and for in situ conservation and wildlife management schemes, where 344 animals are not used to captive conditions. More generally, a failure to consider captivity-345 induced agitation could lead to false conclusions in any behavioural assay where animals are 346 347 brought into captivity. For instance, some studies have interpreted movement around an enclosed space as indicative of exploratory tendencies, when it may in fact reflect agitation 348 349 induced by spatial neophobia (reviewed in 44) and/or elevated stress levels due to capture 350 and handling (45). The high flight responses observed in response to the first baseline presentation, regardless of the model shown, suggests that at this is likely to be the case here. 351 352 While levels of agitation could, in principle, be reduced in experiments such as ours by allowing subjects more time to acclimatise to captive conditions, this must always be traded 353 off against the ethical imperative to keep presentations as short as possible, particularly if 354 355 they involve young animals that are still dependent on parents.

356 Second, our experiment showed that responses differed substantially between individuals 357 (evident in figure S3). While such differences might be influenced by previous experience with 358 predators (46,47), it is also possible that individual differences in agitation (possibly linked to 359 variation in stress reactivity or coping styles; 48) could affect the potential for individuals to learn about novel predators, both in experimental and natural contexts. While a hormonally-360 mediated stress response is known to be necessary to promote aversion learning (49,50), 361 362 there is some evidence that acute levels of stress can inhibit learning (51). Moreover, highly 363 anxious individuals may be faster to flee upon hearing conspecific alarm calls, thus reducing 364 their potential for learning to associate the calls with the presence of a novel predator. Given 365 evidence that personality differences influence social information use in other contexts

(e.g.52,53), understanding how personality affects the development of anti-predator
 responses is a clear priority for future research.

Finally, our results raise questions about the stimuli needed to promote social learning of anti-368 369 predator responses. Whereas some studies on captive animals show that playbacks of 370 mobbing or alarm calls are sufficient to promote learned fear responses towards novel stimuli 371 (18,24), this did not appear to be the case in our experiment. Indeed, as the great majority of 372 research on socially learned anti-predator responses has taken place under controlled 373 laboratory conditions, it remains unclear whether vocalisations alone are sufficient to 374 promote learning in the wild. Corvids, for example, show a range of distinctive behaviours in 375 response to predators, including gaze fixing, aggressive postures, and diving flights directed 376 at the threat (54–56). It is quite possible that the posture and directedness of the behaviour 377 of conspecifics is as important as, or complimentary to, the vocalisations themselves in 378 serving to reinforce learning and increase signal saliency. Such multimodal signals have been found to increase the speed at which predators learn to discriminate aposematic prey (57), 379 380 and also enhance the responses of observers to anti-predator alarm signals compared to 381 when such signals are presented singly (58).

Understanding how wild animals learn about new threats is an important priority for both fundamental and applied research. Tightly controlled laboratory experiments show that antipredator responses can, in principle, be socially learned, but work on wild animals remains rare. We must now embrace the complexities of the real world, including individual variation and multi-modal signal structure, to better understand how such learning operates in practice.

388 Ethics

Birds were captured by trained bird ringers operating under licences issued by the British Trust for Ornithology (permit C5752), and held briefly in captivity under UK Home Office project licence PPL 80/2371. The experiment was carried out following methodological approval from the Biosciences Ethics Panel of the University of Exeter, and adhered to the standards outlined in the in the ASAB/ABS (2012) Guidelines for the Treatment of Animals in Behavioural Research and Teaching (59).

395 Data accessibility

396 The data and R code are available from the Dryad Digital Repository at 397 https://doi.org/10.5061/dryad.9r8v0

398 Author contributions

Conceptualization GEM, AT; Data collection GEM, VEL; Video coding; GEM; Data analysis;
GEM, Writing, GEM, VEL, AT. All authors gave their final approval for publication.

401 **Competing interests**

402 The authors declare no competing interests.

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Table 1: Model selection table for the variables influencing the (square-root transformed) 568 569 number of flights made by the jackdaws in the 60 seconds after each presentation. The grey 570 area highlights the models that form the top set prior implementation of a model nesting rule 571 (Richards, 2007) that filtered out those that should not be retained. When factors are included in the model this is denoted by the symbol •, and numbers refer to the coefficients of numeric 572 variables when these were included in the model, while * denotes interaction terms between 573 variables. sqrt.pre60 refers to the number of flights made in the 60 seconds prior to the 574 presentation (square-root transformed), while model denotes the model shown 575 576 (Elephant/Fox), pres.num the presentation number (1,2, or 3), and pb.group whether the bird heard scold calls or contact calls during presentation 2. Potential 'top' models are highlighted 577 578 in bold, and these are reported in full in Table 2.

579

									model*						
						model*	model*	pb.group*	pb.group*						
Model ID	Intercept	sqrt.pre60	model	pb.group	pres.num	pb.group	pres.num	pres.num	pres.num	df	logLik	AICc	ΔAICc	retained	weight
sqrt.sel6	1.815	0.521	٠	•	•		•			11	-213.8	451.5	0.0	Yes	0.53
sqrt.sel9	1.991	0.527	•		•		•			10	-215.1	451.8	0.3	Yes	0.47
sqrt.sel3	1.753	0.527	•	•	•	•	•			12	-213.6	453.7	2.1	No	
sqrt.sel5	1.943	0.508	•	•	•		•	•		13	-213.3	455.4	3.9	No	
sqrt.sel2	1.882	0.514	•	•	•	•	•	•		14	-213.2	457.6	6.1		
sqrt.sel15	1.679	0.526		•	•					8	-220.8	458.7	7.1		
sqrt.sel18	1.852	0.532			•					7	-222.1	459.0	7.5		
sqrt.sel12	1.637	0.522	•	•	•					9	-220.7	460.7	9.2		
sqrt.sel14	1.812	0.528	•		•					8	-222.0	461.1	9.6		
sqrt.sel1	1.869	0.504	٠	•	•	•	•	•	•	16	-212.6	461.5	10.0		
sqrt.sel11	1.807	0.514		•	•			•		10	-220.4	462.4	10.9		
sqrt.sel7	1.573	0.529	•	•	•	•				10	-220.6	462.8	11.3		
sqrt.sel8	1.764	0.509	٠	•	•			•		11	-220.3	464.6	13.1		
sqrt.sel17	1.472	0.525		•						6	-226.1	464.9	13.4		
sqrt.sel19	1.644	0.532								5	-227.4	465.3	13.8		
sqrt.sel4	1.701	0.516	•	•	•	•		•		12	-220.2	466.8	15.2		
sqrt.sel13	1.431	0.521	•	•						7	-226.1	466.9	15.4		
sqrt.sel16	1.605	0.528	•							6	-227.4	467.3	15.8		
sqrt.sel10	1.366	0.528	•	•		•				8	-225.9	468.9	17.4		

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Table 2: Values from the GLMM models highlighted in Table 1 as the being the candidate 'best' models for predicting which factors influenced the (square-root transformed) number of flights made by the birds around the experimental arena in the sixty seconds after the model presentation. Bird identity and playback heard were included as random effects in each model, with the variance (SD) of bird identity being 0.303 (0.55) in Model 6 and 0.331 (0.58) in Model 9. Variance attributable to the playback track was zero in all models.

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Variable	Estimate	SE	t-Value	P-Value						
Intercept	1.815	0.264	6.87	<0.001						
sqrt.Flights in 60s prior to Pres	0.521	0.064	8.16	<0.001						
Model: Elephant	0	0								
Fox	-0.257	0.318	-0.81	0.42						
Playback Group: Contact	0	0								
Scold	0.369	0.226	1.63	0.11						
Presentation Number: Pres 1	0	0								
Pres 2	0.067	0.275	0.25	0.81						
Pres 3	-1.221	0.275	-4.43	<0.001						
Presentation Number*Model	0									
Pres 2:Fox	-0.154	0.389	-0.40	0.693						
Pres 3:Fox	1.216	0.389	3.13	0.002						

Model sqrt.sel6 Summary

Variable	Estimate	SE	t-Value	P-Value
Intercept	1.991	0.247	8.07	<0.001
sqrt.Flights in 60s prior to Pres	0.527	0.064	8.22	<0.001
Model: Elephant	0	0		
Fox	-0.26	0.322	-0.81	0.42
Presentation Number: Pres 1	0	0		
Pres 2	0.068	0.275	0.25	0.81
Pres 3	-1.223	0.276	-4.43	<0.001
Presentation Number*Model				
Pres 2:Fox	-0.156	0.389	-0.40	0.69
Pres 3:Fox	1.217	0.389	3.13	0.002

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Table 3: Model selection table for the variables influencing the (square-root transformed) 592 593 number of flights made by the jackdaws in the 60 seconds after Presentation 3 only. The grey area highlights the models that form the top set prior implementation of a model nesting rule 594 595 [36] that filtered out those that should not be retained. When factors are included in the model this is denoted by the symbol •, and numbers refer to the coefficients of numeric 596 variables when these were included in the model, while * denotes interaction terms between 597 variables. sqrt.pre60 refers to the (square-root transformed) number of flights made in the 598 60 seconds prior to the model presentation, while model denotes the model shown 599 (Elephant/Fox), and pb.group whether the bird heard scold calls or contact calls during 600 presentation 2. The top model is highlighted in bold. As there was only one top model 601 following application of the nesting rule, model weights are provided for all of the models 602 listed. 603

604

					* *						
					model*						
model.ID	Intercept	sqrt.pre60	model	pb.group	pb.group	df	logLik	AIĆc	ΔAIĆc	weight	Retained
p3.model4	0.305	0.777	•			4	-58.7	126.2	0.0	0.50	Yes
p3.model2	0.201	0.754	•	•		5	-57.9	127.3	1.1	0.30	No
p3.model1	0.036	0.760	•	•	•	6	-57.0	128.1	1.9	0.20	No
p3.model7	0.733	0.792				3	-65.1	136.8	10.6	0.00	
p3.model3	0.636	0.770		•		4	-64.6	138.2	12.0	0.00	
p3.model6	1.302		•	•		4	-84.7	178.3	52.1	0.00	
p3.model8	1.745		•			3	-87.0	180.5	54.2	0.00	
n3 model5	1 210		٠	•	•	5	-84 6	180 G	54.4	0.00	

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Figure 1: Plots of the raw data for the number of flights made by the birds in the sixty seconds following the presentation of a) the model elephant, or b) the model fox. Light colours in each represent birds from the Contact call group, while the darker plots display data from birds played Scold calls in Presentation 2. There were no accompanying playbacks in Presentations 1 and 3.



Figure 2: Scatterplot of the number of flights made in the 60 seconds prior to the Presentation
3, against the number of flights made in the 60 seconds after the presentation, highlighting
the consistency of this relationship between groups, regardless of the model shown or the
playback previously heard.

