

Distribution Regression with Minimax-Optimal Guarantee

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Joint work with

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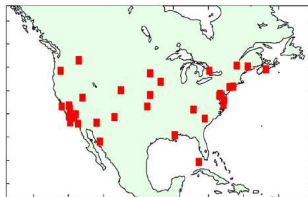
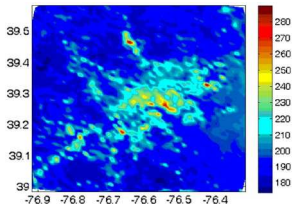
MASCOT-NUM, Toulouse
March 25, 2016

Example: sustainability

- **Goal:** aerosol prediction = air pollution \rightarrow climate.



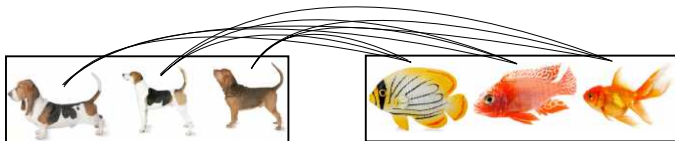
- Prediction using labelled bags:
 - bag := multi-spectral satellite measurements over an area,
 - label := local aerosol value.



Example: existing methods

Multi-instance learning:

- [Haussler, 1999, Gärtner et al., 2002] (set kernel):



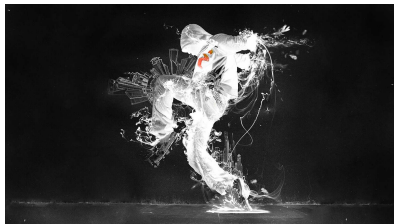
- **sensible** methods in regression: few,
 - 1 restrictive technical conditions,
 - 2 super-high resolution satellite image: would be needed.

Contributions:

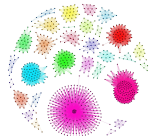
- 1 Practical: state-of-the-art accuracy (aerosol).
- 2 Theoretical:
 - General bags: graphs, time series, texts, ...
 - Consistency of set kernel in regression (17-year-old open problem).
 - How many samples/bag?

Contributions:

- ① Practical: state-of-the-art accuracy (aerosol).
- ② Theoretical:
 - General bags: graphs, time series, texts, ...
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 - How many samples/bag?
 - AISTATS-2015 (oral – 6.11%) → JMLR in revision.



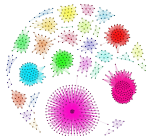
Objects in the bags



- Examples:

- time-series modelling: user = set of **time-series**,
- computer vision: image = collection of patch **vectors**,
- NLP: corpus = bag of **documents**,
- network analysis: group of people = bag of friendship **graphs**, ...

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- Wider context (statistics): point estimation tasks.

Regression on labelled bags

- Given:

- labelled bags: $\hat{\mathbf{z}} = \{(\hat{P}_i, y_i)\}_{i=1}^{\ell}$, \hat{P}_i : bag from P_i , $N := |\hat{P}_i|$.
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$$f_{\hat{\mathbf{z}}}^{\lambda} = \arg \min_{f \in \mathcal{H}} \frac{1}{\ell} \sum_{i=1}^{\ell} \left[\underbrace{f(\mu_{\hat{P}_i})}_{\text{feature of } \hat{P}_i} - y_i \right]^2 + \lambda \|f\|_{\mathcal{H}}^2.$$

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- Prediction:

$$\hat{y}(\hat{P}) = \mathbf{g}^T (\mathbf{G} + \ell \lambda \mathbf{I})^{-1} \mathbf{y},$$
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Challenges

- 1 Inner product of distributions: $K(\mu_{\hat{P}_i}, \mu_{\hat{P}_j}) = ?$
- 2 How many samples/bag?

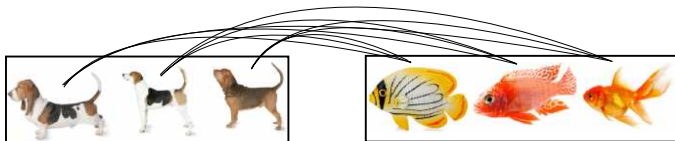
Regression on labelled bags: similarity

Let us define an inner product on distributions $[\tilde{K}(P, Q)]$:

① Set kernel: $A = \{a_i\}_{i=1}^N$, $B = \{b_j\}_{j=1}^N$.

$$\tilde{K}(A, B) = \frac{1}{N^2} \sum_{i,j=1}^N k(a_i, b_j) = \left\langle \underbrace{\frac{1}{N} \sum_{i=1}^N \varphi(a_i)}_{\text{feature of bag } A}, \frac{1}{N} \sum_{j=1}^N \varphi(b_j) \right\rangle.$$

Remember:



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- 2 Taking 'limit' [Berlinet and Thomas-Agnan, 2004, Altun and Smola, 2006, Smola et al., 2007]: $a \sim P$, $b \sim Q$

$$\tilde{K}(P, Q) = \mathbb{E}_{a,b} k(a, b) = \left\langle \underbrace{\mathbb{E}_a \varphi(a)}_{\text{feature of distribution } P =: \mu_P}, \mathbb{E}_b \varphi(b) \right\rangle.$$

Example (Gaussian kernel): $k(\mathbf{a}, \mathbf{b}) = e^{-\|\mathbf{a}-\mathbf{b}\|_2^2 / (2\sigma^2)}$.

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- $k : \mathcal{D} \times \mathcal{D} \rightarrow \mathbb{R}$ sym. is pd. if $\mathbf{G} = [k(x_i, x_j)]_{i,j=1}^n \succeq 0$.

Other valid similarities

Recall: $K(P, Q) = \langle \mu_P, \mu_Q \rangle$.

K_G	K_e	K_C
$e^{-\frac{\ \mu_P - \mu_Q\ ^2}{2\theta^2}}$	$e^{-\frac{\ \mu_P - \mu_Q\ }{2\theta^2}}$	$\left(1 + \ \mu_P - \mu_Q\ ^2 / \theta^2\right)^{-1}$

K_t	K_i
$\left(1 + \ \mu_P - \mu_Q\ ^\theta\right)^{-1}$	$\left(\ \mu_P - \mu_Q\ ^2 + \theta^2\right)^{-\frac{1}{2}}$

Functions of $\|\mu_P - \mu_Q\| \Rightarrow$ computation: similar to set kernel.

Quality of estimator, baseline:

$$\mathcal{R}(f) = \mathbb{E}_{(\mu_P, y) \sim \rho} [f(\mu_P) - y]^2,$$

$f_\rho = \text{best regressor.}$

How many samples/bag to get the accuracy of f_ρ ? Possible?

Assume (for a moment): $f_\rho \in \mathcal{H}(K)$.

Our result: how many samples/bag

- Known [Caponnetto and De Vito, 2007]: best/achieved rate

$$\mathcal{R}(f_z^\lambda) - \mathcal{R}(f_\rho) = \mathcal{O}\left(\ell^{-\frac{bc}{bc+1}}\right),$$

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Our result

- If $2 \leq a$, then f_z^λ attains the **best achievable rate**.
- In fact, $a = \frac{b(c+1)}{bc+1} < 2$ is enough.
- Consequence: **regression with set kernel is consistent**.

Why can we get consistency/rates? – intuition

- Convergence of the mean embedding:

$$\|\mu_P - \mu_{\hat{P}}\|_H = \mathcal{O}\left(\frac{1}{\sqrt{N}}\right).$$

- Hölder property of K ($0 < L$, $0 < h \leq 1$):

$$\|K(\cdot, \mu_P) - K(\cdot, \mu_{\hat{P}})\|_{\mathcal{H}} \leq L \|\mu_P - \mu_{\hat{P}}\|_H^h.$$

- $f_{\hat{z}}^\lambda$ depends 'nicely' on $\mu_{\hat{P}}$. [39 pages]

- 1 Misspecified setting ($f_\rho \in L^2 \setminus \mathcal{H}$):
 - Consistency: convergence to $\inf_{f \in \mathcal{H}} \|f - f_\rho\|_{L^2}$.
 - Smoothness on f_ρ : computational & statistical tradeoff.

② Vector-valued output:

- Y : separable Hilbert space $\Rightarrow K(\mu_P, \mu_Q) \in \mathcal{L}(Y)$.
- Prediction on a test bag \hat{P} :

$$\hat{y}(\hat{P}) = \mathbf{g}^T (\mathbf{G} + \ell \lambda \mathbf{I})^{-1} \mathbf{y},$$
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Specifically: $Y = \mathbb{R} \Rightarrow \mathcal{L}(Y) = \mathbb{R}$; $Y = \mathbb{R}^d \Rightarrow \mathcal{L}(Y) = \mathbb{R}^{d \times d}$.

Aerosol prediction result ($100 \times RMSE$)

We perform on par with the state-of-the-art, hand-engineered method.

- Zhuang Wang, Liang Lan, Slobodan Vucetic. IEEE Transactions on Geoscience and Remote Sensing, 2012: 7.5 – 8.5 ($\pm 0.1 - 0.6$):
 - hand-crafted features.
- Our prediction accuracy: 7.81 (± 1.64).
 - no expert knowledge.
- Code in ITE: #2 on mloss,

<https://bitbucket.org/szzoli/ite/>






- Problem: distribution regression.
- Contribution:
 - computational & statistical tradeoff analysis,
 - specifically, the set kernel is consistent: 17-year-old open question,
 - minimax optimal rate is achievable: sub-quadratic bag size.
- Details (JMLR in revision):

<http://arxiv.org/abs/1411.2066>

Thank you for the attention!



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