



Asymptotic behaviour for a thermoelastic problem of a microbeam with thermoelasticity of type III

Roberto Díaz  and Octavio Vera

Universidad del Bío-Bío, Collao 1202, casilla 5-C, Concepción, Chile

Received 25 April 2017, appeared 3 November 2017

Communicated by Vilmos Komornik

Abstract. In this paper we study the asymptotic behavior of a equation modeling a microbeam moving transversally, coupled with an equation describing a heat pulse on it. Such pulse is given by a type III of the Green–Naghdi model, providing a more realistic model of heat flow from a physics point of view. We use semigroups theory to prove existence and uniqueness of solutions of our model, and multiplicative techniques to prove exponentially stable of its associated semigroup.

Keywords: C_0 -semigroup, functional analysis, transverse vibration, coupled system, exponential stability.

2010 Mathematics Subject Classification: 35B40, 35B35, 49K20.

1 Introduction


We begin by recalling Green and Naghdi [6,7] seminal work from about two decades ago, where they introduced new thermoelastic theories by a novel approach based on entropy equality instead of usual entropy inequality. They derived three theories under different assumptions, they are currently known as thermoelasticity type I, Type II and Type III respectively. These theories constitute a refined sequence of models addressing progressively certain anomalies such as infinite speed heat propagation induced by heat conduction classical theory under Type I model and so on.

On other hand, Abouelregal and Zenkour [1] propose a model given by the first equation from the system given below, based on Euler–Bernoulli beam’s model. We will assume that such beam is moving along the x axis with constant velocity κ , and it is subject to a heat pulse governed by the so-called Green and Naghdi Theory (type III), resulting in a system given by:

$$u_{tt} + (p(x) u_{xx})_{xx} + 2q(x) u_t + 2\delta u_{xt} - \kappa^2 u_{xx} + \eta \theta_{txx} = 0, \quad (1.1)$$

$$\theta_{tt} + \theta_t - \kappa \theta_{xx} - \eta u_{xxt} - \xi \theta_{xxt} = 0, \quad (1.2)$$

where $u = u(x, t)$ is a real valued function, representing the transverse displacement on the axis x which is fixed at both ends, $\theta = \theta(x, t)$ is the difference of temperature between the

 Corresponding author. Email: roberto.diaz1301@alumnos.ubiobio.cl, roberto.diaz@ulagos.cl

actual state and a reference temperature, and η is the coupling constant. We will assume throughout this paper $q(x)$ and $p(x)$ are positive definite functions, where $q(x) \in L^\infty(0, L)$, $p(x) \in H^2(0, L)$ and there are constants $\alpha_1, \alpha_2, \beta_1$ and β_2 such that

$$0 < \alpha_1 \leq p(x) \leq \alpha_2, \quad \forall x \in [0, L], \quad (1.3)$$

$$0 < \beta_1 \leq q(x) \leq \beta_2, \quad \forall x \in [0, L] \quad (1.4)$$

under the following boundary conditions

$$u(0, t) = u(L, t) = 0, \quad u_x(0, t) = u_x(L, t) = 0, \quad \theta(0, t) = \theta(L, t) = 0, \quad (1.5)$$

with initial values

$$u(x, 0) = u_0(x), \quad u_t(x, 0) = u_1(x), \quad \theta(x, 0) = \theta_0(x), \quad x \in [0, L]. \quad (1.6)$$

We will establish stabilization results of the system (1.1)–(1.6) showing the energy is exponentially stable. Similar results are well known for stabilization for various flexible structures showing the energy decay exponentially, for instance see [3, 8] and references therein.

For (1.1)–(1.6) we have the following estimate of the energy.

Lemma 1.1. *For every solution of the system (1.1)–(1.6) the total energy $\mathcal{E} : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is given at time t by*

$$\mathcal{E}(t) = \frac{1}{2} \int_0^L (u_t^2 + p(x) u_{xx}^2 + \kappa^2 u_x^2 + \theta_t^2 + \kappa \theta_x^2) dx \quad (1.7)$$

and satisfies

$$\frac{d}{dt} \mathcal{E}(t) = -2 \int_0^L q(x) u_t^2 dx - \int_0^L \theta_t^2 dx - \xi \int_0^L \theta_{xt}^2 dx. \quad (1.8)$$

Proof. We multiply (1.1) by u_t and integrating with respect to x over $[0, L]$, we obtain

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int_0^L u_t^2 dx + \int_0^L p(x) u_{xx} u_{xxt} dx + 2 \int_0^L q(x) u_t^2 dx \\ & + \delta \int_0^L \frac{1}{2} \frac{d}{dx} (u_t^2) dx + \kappa^2 \int_0^L u_x u_{xt} dx + \eta \int_0^L \theta_{txx} u_t dx = 0. \end{aligned}$$

then

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int_0^L u_t^2 dx + \frac{1}{2} \frac{d}{dt} \int_0^L p(x) u_{xx}^2 dx + 2 \int_0^L q(x) u_t^2 dx \\ & + \delta \int_0^L \frac{1}{2} \frac{d}{dx} (u_t^2) dx + \frac{1}{2} \kappa^2 \frac{d}{dt} \int_0^L u_x^2 dx + \eta \int_0^L \theta_{txx} u_t dx = 0. \end{aligned}$$

Using the boundary condition (1.5), we have

$$\frac{1}{2} \frac{d}{dt} \int_0^L (u_t^2 + p(x) u_{xx}^2 + \kappa^2 u_x^2) dx + 2 \int_0^L q(x) u_t^2 dx + \eta \int_0^L \theta_{txx} u_t dx = 0. \quad (1.9)$$

On the other hand, multiplying (1.2) by θ_t and integrating with respect to x over $[0, L]$, using the boundary conditions (1.5) and performing straightforward calculations, we have

$$\frac{1}{2} \frac{d}{dt} \int_0^L (\theta_t^2 + \kappa \theta_x^2) dx - \eta \int_0^L \theta_{txx} u_t dx + \xi \int_0^L \theta_{xt}^2 dx + \int_0^L \theta_t^2 dx = 0. \quad (1.10)$$

adding (1.9) and (1.10), the proof of lemma is complete. \square

The goal in this paper is to prove the following theorem.

Theorem 1.2. *Let u, θ be solutions of the system (1.1)–(1.6). Then there exist positive constants K and γ such that*

$$\mathcal{E}(t) \leq K \mathcal{E}(0) e^{-\gamma t}, \quad \forall t \geq 0.$$

This paper is organized as follows: Section 2: we will develop the necessary tools to prove our main result; and Section 3 and 4: we show well-posedness and the exponential stability of the system (1.1)–(1.6), and final section with conclusions and remarks.

2 Setting of the semigroup

Before proving our main result, we will obtain the phase space and the domain of the operator associated to the system (1.1)–(1.6).

We will use the following standard $L^2(0, L)$ space, the scalar product and norm are denoted by

$$\langle u, v \rangle_{L^2(0, L)} = \int_0^L u \bar{v} \, dx, \quad \|u\|_{L^2(0, L)}^2 = \int_0^L u^2 \, dx.$$

To prove the theorem 1.2, we need the following two inequalities.

I. The Poincaré inequality

$$\|u\|_{L^2(0, L)}^2 \leq C_P \|u_x\|_{L^2(0, L)}^2, \quad \forall u \in H_0^1(0, L).$$

where C_P is the Poincaré constant.

II. Young-type inequality

$$\int_0^L \phi \psi \, dx \leq \int_0^L |\phi \psi| \, dx \leq \frac{1}{2} \left(\varepsilon \int_0^L \phi^2 \, dx + \frac{1}{\varepsilon} \int_0^L \psi^2 \, dx \right), \quad \forall \varepsilon > 0, \quad \forall \phi, \psi \in L^2(0, L).$$

Taking $u_t = v$ and $\phi = \theta_t$ the initial value problem (1.1)–(1.6) can be reduced to the following abstract initial value problem for a first-order evolution equation

$$\frac{d}{dt} U(t) = \mathcal{A} U(t), \quad U(0) = U_0, \quad \forall t > 0, \quad (2.1)$$

where $U(t) = (u, v, \theta, \phi)^T$ and $U_0(t) = (u_0, v_0, \theta_0, \phi_0)^T$, where the linear operator $\mathcal{A} : \mathcal{D}(\mathcal{A}) \subset \mathcal{H} \rightarrow \mathcal{H}$ is given by

$$\mathcal{A} \begin{pmatrix} u \\ v \\ \theta \\ \phi \end{pmatrix} = \begin{pmatrix} v \\ - (p(x) u_{xx})_{xx} - 2q(x) v - 2\delta v_x + \kappa^2 u_{xx} - \eta \phi_{xx} \\ \phi \\ -\phi + \kappa \theta_{xx} + \eta v_{xx} + \zeta \phi_{xx} \end{pmatrix}. \quad (2.2)$$

We introduce the phase space $\mathcal{H} = H_0^2(0, L) \times L^2(0, L) \times H_0^1(0, L) \times L^2(0, L)$ endowed with the inner product given by

$$\begin{aligned} \langle (u, v, \theta, \phi), (u_1, v_1, \theta_1, \phi_1) \rangle_{\mathcal{H}} &= \int_0^L v \bar{v}_1 \, dx + \int_0^L p(x) u_{xx} \bar{u}_{1xx} \, dx + \kappa^2 \int_0^L u_x \bar{u}_{1x} \, dx \\ &+ \kappa \int_0^L \theta_x \bar{\theta}_{1x} \, dx + \int_0^L \phi \bar{\phi}_1 \, dx, \end{aligned}$$

where $U = (u, v, \theta, \phi)$, $\tilde{U} = (u_1, v_1, \theta_1, \phi_1)$ and the norm

$$\begin{aligned} & \|(u, v, \theta, \phi)\|_{\mathcal{H}}^2 \\ &= \int_0^L u_t^2 dx + \int_0^L p(x) u_{xx}^2 dx + \kappa^2 \int_0^L u_x^2 dx + \kappa \int_0^L \theta_x^2 dx + \int_0^L \phi^2 dx \\ &= \|v\|_{L^2(0,L)}^2 + \left\| \sqrt{p(x)} u_{xx} \right\|_{L^2(0,L)}^2 + \kappa^2 \|u_x\|_{L^2(0,L)}^2 + \kappa \|\theta_x\|_{L^2(0,L)}^2 + \|\phi\|_{L^2(0,L)}^2. \end{aligned}$$

Instead of dealing with (1.1)–(1.6) we will consider (2.1) in the Hilbert space \mathcal{H} , with domain $\mathcal{D}(\mathcal{A})$ of the operator \mathcal{A} given by

$$\mathcal{D}(\mathcal{A}) = \left\{ (u, v, \theta, \phi) \in \mathcal{H} : v \in H_0^2(0, L), \theta \in H_0^1(0, L), -p(x) u_{xx} + \kappa^2 u - \eta \phi \in H^2(0, L) \right\}.$$

Firstly, we show that the operator \mathcal{A} generates a C_0 -semigroup of contractions on the space \mathcal{H} .

3 Well posedness

Proposition 3.1. *The operator \mathcal{A} generates a C_0 -semigroup $\mathcal{S}_{\mathcal{A}}(t)$ of contractions on the space \mathcal{H} .*

Proof. We will show that \mathcal{A} is a dissipative operator and 0 belongs to the resolvent set of \mathcal{A} , denoted by $\varrho(\mathcal{A})$. Then our conclusion will follow using the well know Lumer–Phillips theorem [10].

$$\begin{aligned} \langle \mathcal{A}U, U \rangle_{\mathcal{H}} &= \int_0^L [(-p(x) u_{xx})_{xx} \bar{v} - 2q(x) v \bar{v} - 2\delta v_x \bar{v} + \kappa^2 u_{xx} \bar{v} - \eta \phi_{xx} \bar{v} \\ &\quad + \kappa^2 v_x \bar{u}_x + p(x) v_{xx} \bar{u}_{xx} + \kappa \theta_{xx} \bar{\phi} - \phi \bar{\phi} + \eta v_{xx} \bar{\phi} + \xi \phi_{xx} \bar{\phi} + \kappa \phi_x \bar{\theta}_x] dx \\ &= \int_0^L [-p(x) u_{xx} \bar{v}_{xx} + p(x) v_{xx} \bar{u}_{xx} - 2\delta v_x \bar{v} - \kappa^2 u_x \bar{v}_x + \kappa^2 v_x \bar{u}_x \\ &\quad - \kappa \theta_x \bar{\phi}_x + \kappa \phi_x \bar{\theta}_x - \phi \bar{\phi} - \eta \phi \bar{v}_{xx} + \eta v_{xx} \bar{\phi} - 2q(x) v^2 - \xi \phi_x^2] dx \\ &= 2i \operatorname{Im} \int_0^L p(x) v_{xx} \bar{u}_{xx} dx - 2\delta \int_0^L v_x \bar{v} dx + 2i\kappa^2 \operatorname{Im} \int_0^L v_x \bar{u}_x dx \\ &\quad + 2i\kappa \operatorname{Im} \int_0^L \theta_x \bar{\phi}_x dx + 2i\eta \operatorname{Im} \int_0^L v_{xx} \bar{\phi} dx - 2 \int_0^L q(x) v^2 dx \\ &\quad - \xi \int_0^L \phi_x^2 dx - \int_0^L \phi^2 dx. \end{aligned} \tag{3.1}$$

Taking real parts in (3.1), we obtain

$$\operatorname{Re} \langle \mathcal{A}U, U \rangle_{\mathcal{H}} = -2 \int_0^L q(x) v^2 dx - \int_0^L \phi_x^2 dx - 2\delta \operatorname{Re} \int_0^L v_x \bar{v} dx - \int_0^L \phi^2 dx. \tag{3.2}$$

On the other hand

$$\frac{d}{dx} (|v|^2) = \frac{1}{2} \operatorname{Re}(v_x \bar{v}).$$

Then

$$2 \operatorname{Re} \int_0^L v_x \bar{v} dx = \frac{1}{2} \int_0^L \frac{d}{dx} (|v|^2) dx = 0.$$

Replacing into (3.2), we obtain

$$\operatorname{Re} \langle \mathcal{A}U, U \rangle_{\mathcal{H}} = -2 \int_0^L q(x) v^2 dx - \int_0^L \phi_x^2 dx - \int_0^L \phi^2 dx. \quad (3.3)$$

Hence \mathcal{A} is a dissipative operator.

On the other hand, we have that $0 \in \rho(\mathcal{A})$. In fact, given $F = (f_1, f_2, f_3, f_4) \in \mathcal{H}$, we must show that there exists a unique $U = (u, v, \theta, \phi)$ in $\mathcal{D}(\mathcal{A})$ such that $\mathcal{A}U = F$. Indeed,

$$v = f_1 \in H_0^2(0, L), \quad (3.4)$$

$$-(p(x) u_{xx})_{xx} - 2q(x) v - 2\delta v_x + \kappa^2 u_{xx} - \eta \phi_{xx} = f_2 \in L^2(0, L), \quad (3.5)$$

$$\phi = f_3 \in H_0^1(0, L), \quad (3.6)$$

$$-\phi + \kappa \theta_{xx} + \eta v_{xx} + \zeta \phi_{xx} = \psi f_4 \in L^2(0, L). \quad (3.7)$$

Replacing (3.4) into (3.5) we have

$$[-p(x) u_{xx} + \kappa^2 u - \eta \phi]_{xx} - 2q(x) f_1 - 2\delta f_{1x} = f_2 \in L^2(0, L), \quad (3.8)$$

then

$$[-p(x) u_{xx} + \kappa^2 u - \eta \phi]_{xx} = f_2 + 2q(x) f_1 + 2\delta f_{1x} \in L^2(0, L).$$

Hence

$$[-p(x) u_{xx} + \kappa^2 u - \eta \phi]_{xx} \in L^2(0, L). \quad (3.9)$$

It is well known there is a unique

$$-p(x) u_{xx} + \kappa^2 u - \eta \phi \in H^2(0, L)$$

satisfying (3.9) and

$$\|[-p(x) u_{xx} + \kappa^2 u - \eta \phi]_{xx}\|_{L^2(0, L)} \leq \|f_2 + 2q(x) f_1 + 2\delta f_{1x}\| \leq C \|F\|$$

for a positive constant C .

Moreover, substituting (3.4) and (3.6) into (3.7) we have

$$\kappa \theta_{xx} = f_4 + f_3 - \eta f_{1xx} - \zeta f_{3xx} \in H^{-1}(0, L),$$

then $\theta \in H_0^1(0, L)$.

It is easy to show that $\|U\|_{\mathcal{H}} \leq C \|F\|_{\mathcal{H}}$ for a positive constant C . Therefore we conclude that $0 \in \rho(\mathcal{A})$. \square

From Proposition 3.1 we can state the following result [10].

Theorem 3.2. *Assume that $U_0 \in \mathcal{D}(\mathcal{A})$, then there exists a unique solution $U(t) = (u, v, \theta, \phi)$ of (1.1)–(1.5) with boundary conditions (1.6) satisfying*

$$(u, v, \theta, \phi) \in C([0, \infty) : \mathcal{D}(\mathcal{A})) \cap C^1([0, \infty) : \mathcal{H}),$$

or equivalently, the abstract Cauchy problem (2.1) satisfies

$$\begin{aligned} u &\in C([0, \infty) : H_0^2(0, L)) \cap C^1([0, \infty[: L^2(0, L)), \\ \theta &\in C([0, \infty[: H_0^1(0, L)) \cap C^1([0, \infty[: L^2(0, L)). \end{aligned}$$

However, if $U_0 \in \mathcal{D}(\mathcal{A})$, then

$$\begin{aligned} u &\in C^2([0, \infty[: H_0^2(\Omega)) \cap C^2([0, \infty[: L^2(0, L)), \\ \theta &\in C^1([0, \infty[: H_0^1(0, L)), \\ -p(x)u_{xx} + \kappa^2 u - \eta\phi &\in C([0, \infty[: H^2(0, L)). \end{aligned}$$

4 Asymptotic behaviour

In this section, we will show that the energy decays uniformly with time. This is given by means of an exponential energy decay estimate, i.e. the solution of the system (1.1)–(1.6) converges uniformly to zero as the time t tends to infinity. The idea is to use the multipliers techniques, presented by the following lemmas.

Lemma 4.1. *For every solution u , θ of the system (1.1)–(1.6), the time derivative of the functional $\mathcal{F}_1(t)$, defined by*

$$\mathcal{F}_1(t) := 2 \int_0^L u u_t dx + 2 \int_0^L q(x) u^2 dx, \quad (4.1)$$

satisfies

$$\frac{d}{dt} \mathcal{F}_1(t) = -2 \int_0^L p(x) u_{xx}^2 dx + 4\delta \int_0^L u_x u_t dx - 2\kappa^2 \int_0^L u_x^2 dx - 2\eta \int_0^L \theta_t u_{xx} dx + 2 \int_0^L u_t^2 dx.$$

Moreover the functional $\mathcal{F}_1(t)$ given by (4.1) satisfies the inequality

$$-\mu_0 \mathcal{E}(t) \leq \mathcal{F}_1(t) \leq (\mu_0 + \mu_1) \mathcal{E}(t), \quad \forall t \geq 0, \quad (4.2)$$

where

$$\mu_0 = \max \left\{ 1, \frac{C_P}{\kappa^2} \right\}, \quad \mu_1 = \frac{2\beta_2 C_P}{\kappa^2}.$$

Proof. Differentiating (4.1) in t -variable, using (1.1) and integrating by parts we have

$$\begin{aligned} \frac{d}{dt} \mathcal{F}_1(t) &= 2 \int_0^L u u_{tt} dx + 2 \int_0^L u_t^2 dx + 2 \frac{d}{dt} \int_0^L q(x) u^2 dx \\ &= 2 \int_0^L u [-(p(x)u_{xx})_{xx} - 2q(x)v - 2\delta v_x + \kappa^2 u_{xx} - \eta\theta_{txx}] dx \\ &\quad + 2 \int_0^L u_t^2 dx + 2 \frac{d}{dt} \int_0^L q(x) u^2 dx \\ &= -2 \int_0^L p(x) u_{xx}^2 dx - 2 \frac{d}{dt} \int_0^L q(x) u^2 dx + 4\delta \int_0^L u_x u_t dx - 2\kappa^2 \int_0^L u_x^2 dx \\ &\quad - 2\eta \int_0^L \theta_t u_{xx} dx + 2 \int_0^L u_t^2 dx + 2 \frac{d}{dt} \int_0^L p(x) u^2 dx \\ &= -2 \int_0^L p(x) u_{xx}^2 dx + 4\delta \int_0^L u_x u_t dx - 2\kappa^2 \int_0^L u_x^2 dx - 2\eta \int_0^L \theta_t u_{xx} dx + 2 \int_0^L u_t^2 dx. \end{aligned}$$

On the other hand, using the Young and Poincaré inequalities in (4.1), we have

$$\begin{aligned} \left| 2 \int_0^L u u_t dx \right| &\leq C_P \int_0^L u_x^2 dx + \int_0^L u_t^2 dx \\ &\leq \frac{C_P}{\kappa^2} \int_0^L \kappa^2 u_x^2 dx + \int_0^L u_t^2 dx \\ &\leq \max \left\{ \frac{C_P}{\kappa^2}, 1 \right\} \left(\int_0^L \kappa^2 u_x^2 dx + \int_0^L u_t^2 dx \right) \\ &= \mu_0 \mathcal{E}(t). \end{aligned}$$

For the second part of the functional (4.1), we have

$$2 \int_0^L q(x) u^2 dx \leq 2 \beta_2 C_P \int_0^L u_x^2 dx \leq \frac{2 \beta_2 C_P}{\kappa^2} \int_0^L \kappa^2 u_x^2 dx \leq \mu_1 \mathcal{E}(t).$$

Then

$$- \mu_0 \mathcal{E}(t) \leq \mathcal{F}_1(t) \leq (\mu_0 + \mu_1) \mathcal{E}(t), \quad \forall t \geq 0.$$

Hence the lemma follows. \square

Lemma 4.2. For every solution u, θ of the system (1.1)–(1.6), the time derivative of the functional $\mathcal{F}_2(t)$ defined by

$$\mathcal{F}_2(t) := 2 \int_0^L u \theta_t dx + \int_0^L \theta_x^2 dx + \eta \int_0^L u_x^2 dx, \quad (4.3)$$

satisfies

$$\frac{d}{dt} \mathcal{F}_2(t) = - 2 \int_0^L u \theta_t dx - 2 \kappa \int_0^L u_x \theta_x dx + 2 \xi \int_0^L u_{xx} \theta_t dx + 2 \int_0^L u_t \theta_t dx + 2 \int_0^L \theta_x \theta_{xt} dx.$$

Moreover,

$$|\mathcal{F}_2(t)| \leq \mu_3 \mathcal{E}(t),$$

where

$$\mu_3 = \max \left\{ 1, C_P, \frac{1}{\kappa}, \frac{\eta}{\kappa^2} \right\}.$$

Proof. Differentiating (4.3) in t -variable, using (1.2) and integrating by parts we have

$$\begin{aligned} \frac{d}{dt} \mathcal{F}_2(t) &= 2 \int_0^L u \theta_{tt} dx + 2 \int_0^L u_t \theta_t dx + 2 \int_0^L \theta_x \theta_{xt} dx + 2 \eta \int_0^L u_x u_{xt} dx \\ &= 2 \int_0^L u [-\phi + \kappa \theta_{xx} + \eta v_{xx} + \xi \phi_{xx}] dx + 2 \int_0^L u_t \theta_t dx \\ &\quad + 2 \int_0^L \theta_x \theta_{xt} dx + 2 \eta \int_0^L u_x u_{xt} dx \\ &= - 2 \int_0^L u \theta_t dx - 2 \kappa \int_0^L u_x \theta_x dx - 2 \eta \int_0^L u_x v_x dx + 2 \xi \int_0^L \theta_t u_{xx} dx \\ &\quad + 2 \int_0^L u_t \theta_t dx + 2 \int_0^L \theta_x \theta_{xt} dx + 2 \eta \int_0^L u_x v_x dx \\ &= - 2 \int_0^L u \theta_t dx - 2 \kappa \int_0^L u_x \theta_x dx + 2 \xi \int_0^L u_{xx} \theta_t dx \\ &\quad + 2 \int_0^L u_t \theta_t dx + 2 \int_0^L \theta_x \theta_{xt} dx. \end{aligned}$$

On the other hand using the Poincaré and Young inequality into (4.3), we obtain

$$\begin{aligned} |\mathcal{F}_2(t)| &\leq C_P \int_0^L u_x^2 dx + \int_0^L \theta_t^2 dx + \frac{1}{\kappa} \int_0^L \kappa \theta_x^2 dx + \frac{\eta}{\kappa^2} \int_0^L \kappa^2 u_x^2 dx \\ &\leq \mu_3 \mathcal{E}(t). \end{aligned}$$

Hence the lemma is follows. \square

Lemma 4.3. *The time derivative of the functional $\mathcal{G}(t)$ defined by*

$$\mathcal{G}(t) := \mathcal{F}_1(t) + \mathcal{F}_2(t)$$

satisfies

$$\frac{d}{dt} \mathcal{G}(t) = -2 \mathcal{E}(t) + \mathcal{R},$$

where

$$\begin{aligned} \mathcal{R} &= - \int_0^L p(x) u_{xx}^2 dx + 4\delta \int_0^L u_x u_t dx - \kappa^2 \int_0^L u_x^2 dx - 2\eta \int_0^L \theta_t u_{xx} dx \\ &\quad + 3 \int_0^L u_t^2 dx + \int_0^L \theta_t^2 dx + \kappa \int_0^L \theta_x^2 dx - 2 \int_0^L u \theta_t dx - 2\kappa \int_0^L u_x \theta_x dx \\ &\quad + 2\zeta \int_0^L u_{xx} \theta_t dx + 2 \int_0^L u_t \theta_t dx + 2 \int_0^L \theta_x \theta_{xt} dx. \end{aligned} \quad (4.4)$$

Moreover the remainder \mathcal{R} satisfies the following inequality

$$\begin{aligned} \mathcal{R} &\leq \left[-1 + \frac{\eta \varepsilon_2}{\alpha_1} + \frac{\zeta \varepsilon_5}{\alpha_1} \right] \int_0^L p(x) u_{xx}^2 dx + \left[\frac{2\delta}{\varepsilon_1} + 3 + \varepsilon_6 \right] \int_0^L u_t^2 dx \\ &\quad + \left[2\delta \varepsilon_1 - \kappa^2 + C_P \varepsilon_3 + \frac{\kappa}{\varepsilon_4} \right] \int_0^L u_x^2 dx + \left[\frac{\eta}{\varepsilon_2} + 1 + \frac{1}{\varepsilon_3} + \frac{\zeta}{\varepsilon_5} + \frac{1}{\varepsilon_6} \right] \int_0^L \theta_t^2 dx \\ &\quad + [C_\kappa + \kappa \varepsilon_4 + \varepsilon_7] \int_0^L \theta_x^2 dx + \frac{1}{\varepsilon_7} \int_0^L \theta_{xt}^2 dx \end{aligned} \quad (4.5)$$

for all $\varepsilon_i > 0$, $i = 1, \dots, 7$, and where $C_\kappa \in \mathbb{R}^+$, $C_\kappa > \kappa$.

Proof. Differentiating $\mathcal{G}(t)$ in t -variable and adding terms we have

$$\begin{aligned} \frac{d}{dt} \mathcal{G}(t) &= \frac{d}{dt} \mathcal{F}_1(t) + \frac{d}{dt} \mathcal{F}_2(t) \\ &= -2 \int_0^L p(x) u_{xx}^2 dx + 4\delta \int_0^L u_x u_t dx - 2\kappa^2 \int_0^L u_x^2 dx - 2\eta \int_0^L \theta_t u_{xx} dx \\ &\quad + 2 \int_0^L u_t^2 dx - 2 \int_0^L u \theta_t dx - 2\kappa \int_0^L u_x \theta_x dx + 2\zeta \int_0^L u_{xx} \theta_t dx \\ &\quad + 2 \int_0^L u_t \theta_t dx + 2 \int_0^L \theta_x \theta_{xt} dx + 3 \int_0^L u_t^2 dx - 3 \int_0^L u_t^2 dx \\ &\quad + \int_0^L \theta_t^2 dx - \int_0^L \theta_t^2 dx + \kappa \int_0^L \theta_x^2 dx - \kappa \int_0^L \theta_x^2 dx \\ &= -2 \mathcal{E}(t) + \mathcal{R}. \end{aligned} \quad (4.6)$$

On the other hand from (1.3), we have

$$\int_0^L u_{xx}^2 dx = \int_0^L \frac{1}{p(x)} p(x) u_{xx}^2 dx \leq \frac{1}{\alpha_1} \int_0^L p(x) u_{xx}^2 dx. \quad (4.7)$$

Using (4.7) and the inequalities of Young and Poincaré in (4.4), we obtain

$$\begin{aligned}
\mathcal{R} \leq & - \int_0^L p(x) u_{xx}^2 dx + 2\delta \varepsilon_1 \int_0^L u_x^2 dx + \frac{2\delta}{\varepsilon_1} \int_0^L u_t^2 dx - \kappa^2 \int_0^L u_x^2 dx \\
& + \frac{\eta \varepsilon_2}{\alpha_1} \int_0^L p(x) u_{xx}^2 dx + \frac{\eta}{\varepsilon_2} \int_0^L \theta_t^2 dx + 3 \int_0^L u_t^2 dx + \int_0^L \theta_t^2 dx + C_\kappa \int_0^L \theta_x^2 dx \\
& + C_P \varepsilon_3 \int_0^L u_x^2 dx + \frac{1}{\varepsilon_3} \int_0^L \theta_t^2 dx + \frac{\kappa}{\varepsilon_4} \int_0^L u_x^2 dx + \kappa \varepsilon_4 \int_0^L \theta_x^2 dx \\
& + \frac{\xi \varepsilon_5}{\alpha_1} \int_0^L p(x) u_{xx}^2 dx + \frac{\xi}{\varepsilon_5} \int_0^L \theta_t^2 dx + \varepsilon_6 \int_0^L u_t^2 dx + \frac{1}{\varepsilon_6} \int_0^L \theta_t^2 dx \\
& + \varepsilon_7 \int_0^L \theta_x^2 dx + \frac{1}{\varepsilon_7} \int_0^L \theta_{xt}^2 dx.
\end{aligned} \tag{4.8}$$

Adding terms into (4.8) we have

$$\begin{aligned}
\mathcal{R} \leq & \left[-1 + \frac{\eta \varepsilon_2}{\alpha_1} + \frac{\xi \varepsilon_5}{\alpha_1} \right] \int_0^L p(x) u_{xx}^2 dx + \left[\frac{2\delta}{\varepsilon_1} + 3 + \varepsilon_6 \right] \int_0^L u_t^2 dx \\
& + \left[2\delta \varepsilon_1 - \kappa^2 + C_P \varepsilon_3 + \frac{\kappa}{\varepsilon_4} \right] \int_0^L u_x^2 dx + \left[\frac{\eta}{\varepsilon_2} + 1 + \frac{1}{\varepsilon_3} + \frac{\xi}{\varepsilon_5} + \frac{1}{\varepsilon_6} \right] \int_0^L \theta_t^2 dx \\
& + [C\kappa + \kappa \varepsilon_4 + \varepsilon_7] \int_0^L \theta_x^2 dx + \frac{1}{\varepsilon_7} \int_0^L \theta_{xt}^2 dx.
\end{aligned}$$

Therefore the lemma is proved. \square

Since Lemmas 4.1 and 4.2 yields for $\mathcal{G}(t)$ the following estimate

$$- \mu_4 \mathcal{E}(t) \leq \mathcal{G}(t) \leq (\mu_1 + \mu_4) \mathcal{E}(t), \quad \forall t \geq 0, \tag{4.9}$$

where

$$\mu_4 := \mu_0 + \mu_3.$$

Now, we proceed following closely Gorain [5] and Komornik [8] approaches by introducing an energy $\mathcal{V}(t)$ a Lyapunov functional defined by $\mathcal{V}(t) := \mathcal{E}(t) + \delta_1 \mathcal{G}(t)$ where $\delta_1 > 0$ is a small enough to be chosen later. The Lemmas 4.1 and 4.2 yields the following $\mathcal{V}(t)$ estimates:

$$(1 - 2\delta_1 \mu_4) \mathcal{E}(t) \leq \mathcal{V}(t) \leq [1 + (\mu_1 + \mu_4) \delta_1] \mathcal{E}(t), \quad \forall t \geq 0, \tag{4.10}$$

where we choose $\delta_1 < \frac{1}{2\mu_4}$ so that $\mathcal{V}(t) \geq 0$ for $t \geq 0$.

We state our main result as follows.

Theorem 4.4. *Let u, θ be solutions of the system (1.1)–(1.6). Then there exist positive constants γ and K such that*

$$\mathcal{E}(t) \leq K \mathcal{E}(0) e^{-\gamma t}, \quad \forall t \geq 0.$$

Proof. From Lemma 1.1 we have

$$\mathcal{E}(t) = \frac{1}{2} \int_0^L (u_t^2 + p(x) u_{xx}^2 + \kappa^2 u_x^2 + \theta_t^2 + \kappa \theta_x^2) dx, \tag{4.11}$$

and

$$\frac{d}{dt} \mathcal{E}(t) = -2 \int_0^L q(x) u_t^2 dx - \int_0^L \theta_t^2 dx - \xi \int_0^L \theta_{xt}^2 dx. \tag{4.12}$$

Let us now define an energy like Lyapunov functional

$$\mathcal{V}(t) := \mathcal{E}(t) + \delta_1 \mathcal{G}(t)$$

taking time derivative, using (4.12) and (4.6) we obtain

$$\begin{aligned} \frac{d}{dt} \mathcal{V}(t) &= \frac{d}{dt} \mathcal{E}(t) + \delta_1 \frac{d}{dt} \mathcal{G}(t) = -2 \int_0^L q(x) u_t^2 dx - \int_0^L \theta_t^2 dx \\ &\quad - \zeta \int_0^L \theta_{xt}^2 dx - 2\delta_1 \mathcal{E}(t) + \delta_1 \mathcal{R}. \end{aligned} \quad (4.13)$$

Then using (4.11) and (4.5) into (4.13), we have

$$\begin{aligned} \frac{d}{dt} \mathcal{V}(t) &\leq -2 \int_0^L q(x) u_t^2 dx - \int_0^L \theta_t^2 dx - \zeta \int_0^L \theta_{xt}^2 dx \\ &\quad - \delta_1 \int_0^L u_t^2 dx - \delta_1 \int_0^L p(x) u_{xx}^2 dx - \kappa^2 \delta_1 \int_0^L u_x^2 dx - \delta_1 \int_0^L \theta_t^2 dx \\ &\quad - \kappa \delta_1 \int_0^L \theta_x^2 dx + \delta_1 \left[-1 + \frac{\eta \varepsilon_2}{\alpha_1} + \frac{\zeta \varepsilon_5}{\alpha_1} \right] \int_0^L p(x) u_{xx}^2 dx \\ &\quad + \delta_1 \left[\frac{2\delta}{\varepsilon_1} + 3 + \varepsilon_6 \right] \int_0^L u_t^2 dx + \delta_1 \left[2\delta \varepsilon_1 - \kappa^2 + C_P \varepsilon_3 + \frac{\kappa}{\varepsilon_4} \right] \int_0^L u_x^2 dx \\ &\quad + \delta_1 \left[\frac{\eta}{\varepsilon_2} + 1 + \frac{1}{\varepsilon_3} + \frac{\zeta}{\varepsilon_5} + \frac{1}{\varepsilon_6} \right] \int_0^L \theta_t^2 dx \\ &\quad + \delta_1 [C_\kappa + \kappa \varepsilon_4 + \varepsilon_7] \int_0^L \theta_x^2 dx + \frac{\delta_1}{\varepsilon_7} \int_0^L \theta_{xt}^2 dx. \end{aligned}$$

How $q(x)$ satisfies $0 < \beta_1 \leq q(x) \leq \beta_2, \forall x \in [0, L]$, we have

$$\begin{aligned} \frac{d}{dt} \mathcal{V}(t) &\leq -2\beta_1 \int_0^L u_t^2 dx - \int_0^L \theta_t^2 dx - \zeta \int_0^L \theta_{xt}^2 dx \\ &\quad - \delta_1 \int_0^L u_t^2 dx - \delta_1 \int_0^L p(x) u_{xx}^2 dx - \kappa^2 \delta_1 \int_0^L u_x^2 dx - \delta_1 \int_0^L \theta_t^2 dx \\ &\quad - \kappa \delta_1 \int_0^L \theta_x^2 dx + \delta_1 \left[-1 + \frac{\eta \varepsilon_2}{\alpha_1} + \frac{\zeta \varepsilon_5}{\alpha_1} \right] \int_0^L p(x) u_{xx}^2 dx \\ &\quad + \delta_1 \left[\frac{2\delta}{\varepsilon_1} + 3 + \varepsilon_6 \right] \int_0^L u_t^2 dx + \delta_1 \left[2\delta \varepsilon_1 - \kappa^2 + C_P \varepsilon_3 + \frac{\kappa}{\varepsilon_4} \right] \int_0^L u_x^2 dx \\ &\quad + \delta_1 \left[\frac{\eta}{\varepsilon_2} + 1 + \frac{1}{\varepsilon_3} + \frac{\zeta}{\varepsilon_5} + \frac{1}{\varepsilon_6} \right] \int_0^L \theta_t^2 dx \\ &\quad + \delta_1 [C_\kappa + \kappa \varepsilon_4 + \varepsilon_7] \int_0^L \theta_x^2 dx + \frac{\delta_1}{\varepsilon_7} \int_0^L \theta_{xt}^2 dx. \end{aligned} \quad (4.14)$$

Adding terms into (4.14), we obtain

$$\begin{aligned}
\frac{d}{dt} \mathcal{V}(t) \leq & - \left[2\beta_1 - \delta_1 \left(\frac{2\delta}{\varepsilon_1} + 2 + \varepsilon_6 \right) \right] \int_0^L u_t^2 dx \\
& - \left[2\delta_1 - \frac{\eta \varepsilon_2 \delta_1}{\alpha_1} - \frac{\zeta \varepsilon_5 \delta_1}{\alpha_1} \right] \int_0^L p(x) u_{xx}^2 dx \\
& - \left[2\kappa^2 \delta_1 - 2\delta \varepsilon_1 \delta_1 - C_P \varepsilon_3 \delta_1 - \frac{\kappa \delta_1}{\varepsilon_4} \right] \int_0^L u_x^2 dx \\
& - \left[1 - \delta_1 \left(\frac{\eta}{\varepsilon_2} + \frac{1}{\varepsilon_3} + \frac{\zeta}{\varepsilon_5} + \frac{1}{\varepsilon_6} \right) \right] \int_0^L \theta_t^2 dx \\
& - [\kappa \delta_1 - C_\kappa \delta_1 - \kappa \varepsilon_4 \delta_1 - \varepsilon_7 \delta_1] \int_0^L \theta_x^2 dx \\
& - \left[\zeta - \frac{\delta_1}{\varepsilon_7} \right] \int_0^L \theta_{xt}^2 dx.
\end{aligned}$$

We define the following positive constants

$$\begin{aligned}
C_1 &= 2\beta_1 - \delta_1 \left(\frac{2\delta}{\varepsilon_1} + 2 + \varepsilon_6 \right), \\
C_2 &= 2\delta_1 - \frac{\eta \varepsilon_2 \delta_1}{\alpha_1} - \frac{\zeta \varepsilon_5 \delta_1}{\alpha_1}, \\
C_3 &= 2\kappa^2 \delta_1 - 2\delta \varepsilon_1 \delta_1 - C_P \varepsilon_3 \delta_1 - \frac{\kappa \delta_1}{\varepsilon_4}, \\
C_4 &= 1 - \delta_1 \left(\frac{\eta}{\varepsilon_2} + \frac{1}{\varepsilon_3} + \frac{\zeta}{\varepsilon_5} + \frac{1}{\varepsilon_6} \right), \\
C_5 &= \kappa \delta_1 - C_\kappa \delta_1 - \kappa \varepsilon_4 \delta_1 - \varepsilon_7 \delta_1, \\
C_6 &= \zeta - \frac{\delta_1}{\varepsilon_7},
\end{aligned}$$

where $\varepsilon_i > 0$, $\forall i = 1, \dots, 7$. Hence

$$C_1, C_4, C_6$$

are strictly positive if and only if

$$\delta_1 < \min \left\{ \frac{2\beta_1}{2 + \varepsilon_6 + \frac{2\delta}{\varepsilon_1}}, \frac{1}{\frac{\eta}{\varepsilon_2} + \frac{1}{\varepsilon_3} + \frac{\zeta}{\varepsilon_5} + \frac{1}{\varepsilon_6}}, \zeta \varepsilon_7 \right\}.$$

We will provide extra conditions on ε_i so that C_2, C_3, C_5 are positive constants. We will have

$$C_2 = 2\delta_1 - \frac{\eta \varepsilon_2 \delta_1}{\alpha_1} - \frac{\zeta \varepsilon_5 \delta_1}{\alpha_1} > 0$$

if and only if

$$0 < \varepsilon_2 < \frac{2\alpha_1 - \zeta \varepsilon_1}{\eta}.$$

In an analogous way for \mathcal{C}_3

$$\mathcal{C}_3 = 2\kappa^2 \delta_1 - 2\delta \varepsilon_1 \delta_1 - C_P \varepsilon_3 \delta_1 - \frac{\kappa \delta_1}{\varepsilon_4} > 0$$

if and only if

$$0 < \varepsilon_1 < \frac{2\kappa^2 - C_P \varepsilon_3 - \frac{\kappa \delta_1}{\varepsilon_4}}{2\delta},$$

and also for \mathcal{C}_5 , we have

$$\mathcal{C}_5 = \kappa \delta_1 - C_\kappa \delta_1 - \kappa \varepsilon_4 \delta_1 - \varepsilon_7 \delta_1 > 0$$

if and only if

$$0 < \varepsilon_7 < \kappa - C_\kappa - \kappa \varepsilon_4.$$

Since the above calculations, we obtain

$$\begin{aligned} \frac{d}{dt} \mathcal{V}(t) \leq & -C_1 \int_0^L u_t^2 dx - C_2 \int_0^L p(x) u_{xx}^2 dx - C_3 \int_0^L u_x^2 dx - C_4 \int_0^L \theta_t^2 dx \\ & - C_5 \int_0^L \theta_x^2 dx - C_6 \int_0^L \theta_{xt}^2 dx. \end{aligned}$$

then

$$\begin{aligned} \frac{d}{dt} \mathcal{V}(t) \leq & -C_1 \int_0^L u_t^2 dx - C_2 \int_0^L p(x) u_{xx}^2 dx - C_3 \int_0^L u_x^2 dx - C_4 \int_0^L \theta_t^2 dx \\ & - C_5 \int_0^L \theta_x^2 dx. \end{aligned} \tag{4.15}$$

Since $\delta_1 > 0$ is small enough, we assume that

$$0 < \delta_1 < \delta_2 := \min \left\{ \frac{2\beta_1}{2 + \varepsilon_6 + \frac{2\delta}{\varepsilon_1}}, \frac{1}{\frac{\eta}{\varepsilon_2} + \frac{1}{\varepsilon_3} + \frac{\xi}{\varepsilon_5} + \frac{1}{\varepsilon_6}}, \xi \varepsilon_7, \frac{1}{2\mu_4} \right\}.$$

From (4.15) we get the differential inequality

$$\frac{d}{dt} \mathcal{V}(t) \leq -\delta_1 \mathcal{E}(t). \tag{4.16}$$

Using (4.10), we have

$$\frac{d}{dt} \mathcal{V}(t) \leq \frac{-\delta_1 \mathcal{V}(t)}{1 + (\mu_1 + \mu_4) \delta_1}, \tag{4.17}$$

then

$$\frac{d}{dt} \mathcal{V}(t) \leq -\gamma \mathcal{V}(t), \tag{4.18}$$

where

$$\gamma := \frac{\delta_1}{1 + (\mu_1 + \mu_4) \delta_1}.$$

Multiplying (4.18) by $e^{\lambda t}$ and integrating over $[0, t]$ for any $t \geq 0$, we get

$$\mathcal{V}(t) \leq e^{-\gamma t} \mathcal{V}(0). \tag{4.19}$$

Applying (4.10) to (4.19), we obtain

$$\mathcal{E}(t) \leq \frac{1 + (\mu_1 + \mu_4) \delta_1}{(1 - 2\mu_4 \delta_1)} \mathcal{E}(0) e^{-\gamma t}.$$

Hence Theorem 4.4 is proved. \square

References

- [1] A. E. ABOUELREGAL, A. M. ZENKOUR, Thermoelastic problem of an axially moving microbeam subjected to a external transverse excitation, *J. Theor. Appl. Mech.* **53**(2015), 167–178. <https://doi.org/10.15632/jtam-pl.53.1.167>
- [2] K. AMMARI, M. TUESNAK, Stabilization of Bernoulli–Euler beams by means of a pointwise feedback force, *SIAM J. Control Optim.* **39**(2000), 1160–1181. MR1814271; <https://doi.org/10.1137/S0363012998349315>
- [3] C. AN, J. SU, Dynamic response of axially moving Timoshenko beams: Integral transform solution, *Appl. Math. Mech. – Engl. Ed.* **35**(2014) 1421–1436. <https://doi.org/10.1007/s10483-014-1879-7>
- [4] B. D. COLEMAN, M. E. GURTIN, Equipresence and constitutive equations for rigid heat conductors, *Z. Angew. Math. Phys.* **18**(1967), 199–208. MR0214334; <https://doi.org/10.1007/BF01596912>
- [5] G. C. GORAIN, Exponential energy decay estimate for the solution of internally damped wave equation in a bounded domain, *J. Math. Anal. Appl.* **216**(2000), 510–520. MR1489594; <https://doi.org/10.1006/jmaa.1997.5678>
- [6] A. E. GREEN, P. M. NAGHDI, A re-examination of the basic postulates of thermomechanics, *Proc. Royal Society London Ser. A* **432**(1991), 171–194. MR1116956; <https://doi.org/10.1098/rspa.1991.0012>
- [7] A. E. GREEN, P. M. NAGHDI, On undamped heat waves in an elastic solid, *J. Thermal Stresses* **15**(1992), 253–264. MR1175235; <https://doi.org/10.1080/01495739208946136>
- [8] V. KOMORNIK, *Exact controllability and stabilization. The multiplier method*, John Wiley and Sons Ltd., 1994. MR1359765
- [9] P. K. NANDI, G. C. GORAIN, S. KAR, Stabilization of transverse vibrations of an inhomogeneous beam, *Qscience Connect.* **1991**, No. 21, 1–7. <https://doi.org/10.5339/connect.2013.21>
- [10] A. PAZY, *Semigroups of linear operators and applications to partial differential equations*, Applied Mathematical Sciences, Vol. 44, Springer-Verlag, New York, 1983. MR710486; <https://doi.org/10.1007/978-1-4612-5561-1>