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# On the solvability of a boundary value problem for *p*-Laplacian differential equations

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**Abstract.** Using barrier strip conditions, we study the existence of  $C^2[0,1]$ -solutions of the boundary value problem  $(\phi_p(x'))' = f(t, x, x'), x(0) = A, x'(1) = B$ , where  $\phi_p(s) = s|s|^{p-2}, p > 2$ . The question of the existence of positive monotone solutions is also affected.

**Keywords:** boundary value problem, second order differential equation, *p*-Laplacian, existence, sign conditions.

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## 1 Introduction

This paper is devoted to the solvability of the boundary value problem (BVP)

$$(\phi_p(x'))' = f(t, x, x'), \quad t \in [0, 1],$$
(1.1)

$$x(0) = A, \quad x'(1) = B.$$
 (1.2)

Here  $\phi_p(s) = s|s|^{p-2}$ , p > 2, the scalar function f(t, x, y) is defined for  $(t, x, y) \in [0, 1] \times D_x \times D_y$ , where the sets  $D_x, D_y \subseteq \mathbf{R}$  may be bounded, and  $B \ge 1$ . Besides, f is continuous on a suitable subset of its domain.

The solvability of various singular and nonsingular BVPs with *p*-Laplacian has been studied, for example, in [1-5,7-12,14]. Conditions used in these works or do not allow the main nonlinearity to change sign, [2,11], or impose a growth restriction on it, [3,9,11], or require the existence of upper and lower solutions, [1,3,5,8,9,12]; other type conditions have been used in [7], where the main nonlinearity may changes its sign. As a rule, the obtained results guarantee the existence of positive solutions.

Another type of conditions have been used in [10] for studying the solvability of (1.1), (1.2) in the case  $p \in (1, 2)$ . The existence of at least one positive and monotone  $C^2[0, 1]$ -solution is established therein under the following barrier condition:

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**H.** There are constants  $L_i$ ,  $F_i$ , i = 1, 2, and a sufficiently small  $\sigma > 0$  such that

$$F_{1} \geq F_{2} + \sigma, \quad F_{1} - \sigma > 0, \quad L_{2} - \sigma \geq L_{1},$$

$$[A - \sigma, L + \sigma] \subseteq D_{x}, \quad [F_{2}, L_{2}] \subseteq D_{y}, \quad \text{where } L = L_{1} + |A|,$$

$$f(t, x, y) \geq 0 \quad \text{for } (t, x, y) \in [0, 1] \times D_{x} \times [L_{1}, L_{2}], \quad (1.3)$$

$$f(t, x, y) \leq 0 \quad \text{for } (t, x, y) \in [0, 1] \times D_{x} \times [L_{1}, L_{2}], \quad (1.4)$$

$$f(l, x, y) \le 0$$
 for  $(l, x, y) \in [0, 1] \times D_A \times [r_2, r_1],$  (1.4)

where the constants *m* and *M* are, respectively, the minimum and the maximum of f(t, x, p) on  $[0, 1] \times [A - \sigma, L + \sigma] \times [F_1 - \sigma, L_1 + \sigma]$  and  $D_A = (-\infty, L] \cap D_x$ .

Let us recall, the strips  $[0,1] \times [L_1, L_2]$  and  $[0,1] \times [F_2, F_1]$  are called "barrier" because they limit the values of the first derivatives of all  $C^2[0,1]$ -solution of (1.1), (1.2) between themselves. Recently, it was shown in [13] that conditions of form (1.3) and (1.4) guarantee  $C^1[0,1]$ -solutions to the  $\phi$ -Laplacian equation

$$(\phi(x'))' = f(t, x, x'), \qquad t \in (0, 1),$$

with boundary conditions (1.2), where  $\phi : \mathbf{R} \to \mathbf{R}$  is an increasing homeomorphism and  $f : [0,1] \times \mathbf{R}^2 \to \mathbf{R}$  is continuous.

It turned out that the cases 1 and <math>p > 2 require different technical approaches for the use of **H** for studying the solvability of (1.1), (1.2). So, in the present paper we show that **H** with the additional requirement

$$B - M \ge F_1 \tag{1.5}$$

guarantees the existence of at least one monotone, and positive in the case  $A \ge 0$ ,  $C^2[0,1]$ -solution to (1.1), (1.2) with p > 2. In fact, our main result is the following.

**Theorem 1.1.** Let **H** and (1.5) hold, and f(t, x, y) be continuous on the set  $[0, 1] \times [A - \sigma, L + \sigma] \times [F_1 - \sigma, L_1 + \sigma]$ . Then BVP (1.1), (1.2) has at least one strictly increasing solution in  $C^2[0, 1]$  for each  $p \in (2, \infty)$ .

The paper is organized as follows. In Section 2 we present preliminaries needed to formulate the Topological Transversality Theorem, which is our basic tool, and prove auxiliary results. In Section 3 we give the proof of Theorem 1.1, formulate a corollary and give an example.

#### 2 Fixed point theorem, auxiliary results

Let *K* be a convex subset of a Banach space *E* and  $U \subset K$  be open in *K*. Let  $\mathbf{L}_{\partial U}(\overline{U}, K)$  be the set of compact maps from  $\overline{U}$  to *K* which are fixed point free on  $\partial U$ ; here, as usual,  $\overline{U}$  and  $\partial U$  are the closure of *U* and boundary of *U* in *K*.

A map *F* in  $\mathbf{L}_{\partial U}(\overline{U}, K)$  is essential if every map *G* in  $\mathbf{L}_{\partial U}(\overline{U}, K)$  such that  $G/\partial U = F/\partial U$  has a fixed point in *U*. It is clear, in particular, every essential map has a fixed point in *U*.

The following fixed point theorem due to A. Granas et al. [6].

Theorem 2.1 (Topological transversality theorem). Suppose:

- (*i*)  $F, G : \overline{U} \to K$  are compact maps;
- (*ii*)  $G \in \mathbf{L}_{\partial U}(\overline{U}, K)$  is essential;
- (iii)  $H(x,\lambda), \lambda \in [0,1]$ , is a compact homotopy joining G and F, i.e. H(x,0) = G(x) and H(x,1) = F(x);
- (iv)  $H(x, \lambda), \lambda \in [0, 1]$ , is fixed point free on  $\partial U$ .

*Then*  $H(x, \lambda), \lambda \in [0, 1]$ , *has at least one fixed point in* U *and in particular there is a*  $x_0 \in U$  *such that*  $x_0 = F(x_0)$ .

The following results is important for our consideration. It can be found also in [6].

**Theorem 2.2.** Let  $l \in U$  be fixed and  $F \in \mathbf{L}_{\partial U}(\overline{U}, K)$  be the constant map F(x) = l for  $x \in \overline{U}$ . Then *F* is essential.

Further, we need the following fact.

**Proposition 2.3.** Let the constants B and M be such that  $B \ge 1$  and B > M > 0. Then

$$(B-M)^r \leq B^r - M$$
 for  $r \in [1,\infty)$ .

*Proof.* The inequality is evident for r = 1. For  $M \in (0, B)$  consider the function  $g(r) = (B - M)^r - B^r + M$ ,  $r \in (1, \infty)$ . First, let  $B - M \in (0, 1)$ . Then  $\ln(B - M) < 0$  and so

$$g'(r) = (B - M)^r \ln(B - M) - B^r \ln B < 0$$
 for  $r \in \mathbf{R}$ .

Next, assume B - M = 1. Now we get

$$g'(r) = -(1+M)^r \ln(1+M) < 0$$
 for  $r \in \mathbf{R}$ .

Finally, let  $B - M \in (1, \infty)$ . In this case from B > B - M > 0 we have  $B^r \ge (B - M)^r$  for  $r \in [0, \infty)$  and so

$$g'(r) \leq B^r \ln(B-M) - B^r \ln B = B^r \ln \frac{B-M}{B} < 0 \quad \text{for } r \in [0,\infty).$$

In summary, we have proved that g'(r) < 0 for each  $r \in [0, \infty)$ . Then, the result follows from the fact that g(1) = 0.

Let us emphasize explicitly that we conduct the rest consideration of this section for an arbitrary fixed p > 2.

For  $\lambda \in [0, 1]$  consider the family of BVPs

$$\begin{cases} (\phi_p(x'))' = \lambda f(t, x, x'), & t \in [0, 1], \\ x(0) = A, & x'(1) = B, & B \ge 1, \end{cases}$$
(2.1)

where  $f : [0,1] \times D_x \times D_y \to \mathbf{R}$ ,  $D_x, D_y \subseteq \mathbf{R}$ . Since

$$\phi_p(s) = s|s|^{p-2} = \begin{cases} s^{p-1}, & s \ge 0, \\ -(-s)^{p-1}, & s < 0, \end{cases}$$

we have

$$\phi'_{p}(s) = \begin{cases} (p-1)s^{p-2}, & s \ge 0\\ (p-1)(-s)^{p-2}, & s < 0 \end{cases} = (p-1)|s|^{p-2}$$

and  $(\phi_p(x'(t)))' = (p-1)|x'(t)|^{p-2}x''(t)$ , if x''(t) exists. So, we can write (2.1) as

$$\begin{cases} (p-1)|x'(t)|^{p-2}x''(t) = \lambda f(t, x, x'), \ t \in [0, 1], \\ x(0) = A, \ x'(1) = B. \end{cases}$$
(2.1')

For convenience set

$$m_p = \frac{m}{(p-1)(F_1 - \sigma)^{p-2}}$$
 and  $M_p = \frac{M}{(p-1)(F_1 - \sigma)^{p-2}}$ 

where  $F_1$ ,  $\sigma$ , m and M are as in **H**.

The next result gives a priori bounds for the  $C^{2}[0, 1]$ -solutions of family (2.1') (as well as of (2.1)).

**Lemma 2.4.** Let **H** hold and  $x \in C^2[0,1]$  be a solution to family (2.1'). Then

$$A \le x(t) \le L$$
,  $F_1 \le x'(t) \le L_1$  and  $m_p \le x''(t) \le M_p$  for  $t \in [0, 1]$ .

*Proof.* The proof of the bounds for x and x' is the same as the corresponding part of the proof of [10, Lemma 3.1], but we will state it for completeness. So, assume on the contrary that

$$x'(t) \le L_1 \quad \text{for } t \in [0,1]$$
 (2.2)

is not true. Then,  $x'(1) = B \le L_1$  together with  $x' \in C[0,1]$  implies that

$$S_+ = \{t \in [0,1] : L_1 < x'(t) \le L_2\}$$

is not empty. Moreover, there exists an interval  $[\alpha, \beta] \subset S_+$  with the property

$$x'(\alpha) > x'(\beta). \tag{2.3}$$

Then, by the fundamental theorem of calculus applied to x', (2.3) implies that there is a  $\gamma \in (\alpha, \beta)$  such that

$$x''(\gamma) < 0.$$

We have  $(\gamma, x(\gamma), x'(\gamma)) \in S_+ \times D_x \times (L_1, L_2]$ , which yields

$$f(\gamma, x(\gamma), x'(\gamma)) \ge 0,$$

by (1.3). Then,

$$0 > (p-1)|x'(\gamma)|^{p-2}x''(\gamma) = \lambda f(\gamma, x(\gamma), x'(\gamma)) \ge 0 \quad \text{for } \lambda \in [0, 1],$$

a contradiction. Thus, (2.2) is true.

By the mean value theorem, for each  $t \in (0, 1]$  there exists  $\xi \in (0, t)$  such that  $x(t) - x(0) = x'(\xi)t$ , which yields

$$x(t) \le L$$
 for  $t \in [0, 1]$ .

Arguing as above and using (1.4), we establish  $x'(t) \ge F_1$  for all  $t \in [0,1]$  and, as a consequence,  $x(t) \ge A$  on [0,1].

To reach the bounds for x''(t) from

$$x'(t) > F_1 - \sigma > 0, \qquad t \in [0,1],$$

we obtain firstly

$$0 < \frac{1}{(p-1)(x'(t))^{p-2}} \le \frac{1}{(p-1)(F_1 - \sigma)^{p-2}}.$$

Next, multiplying both sides of this inequality by  $\lambda M \ge 0$  and  $\lambda m \le 0$ , for  $t \in [0, 1]$  obtain respectively

$$\frac{\lambda M}{(p-1)(x'(t))^{p-2}} \le \frac{\lambda M}{(p-1)(F_1 - \sigma)^{p-2}} \le \frac{M}{(p-1)(F_1 - \sigma)^{p-2}} = M_p,$$

and

$$\frac{\lambda m}{(p-1)(x'(t))^{p-2}} \ge \frac{\lambda m}{(p-1)(F_1 - \sigma)^{p-2}} \ge \frac{m}{(p-1)(F_1 - \sigma)^{p-2}} = m_p;$$

from  $f(t, x, L_1) \ge 0$  for  $(t, x) \in [0, 1] \times [A - \sigma, L + \sigma]$  and  $f(t, x, F_1) \le 0$  for  $(t, x) \in [0, 1] \times [A - \sigma, L + \sigma]$ , it follows that  $M \ge 0$  and  $m \le 0$ .

On the other hand,

$$m \le f(t, x(t), x'(t)) \le M$$
 for  $t \in [0, 1]$ ,

since  $(x(t), x'(t)) \in [A, L] \times [F_1, L_1]$  for each  $t \in [0, 1]$ . Multiplying the last inequality by  $\lambda(p-1)^{-1}(x'(t))^{2-p} \ge 0, \lambda, t \in [0, 1]$ , we arrive to

$$m_p \le \frac{\lambda m}{(p-1)(x'(t))^{p-2}} \le \frac{\lambda f(t, x(t), x'(t))}{(p-1)(x'(t))^{p-2}} \le \frac{\lambda M}{(p-1)|x'(t)|^{p-2}} \le M_p$$

for all  $\lambda, t \in [0, 1]$ , from where, keeping in mind that x'(t) > 0 on [0, 1], we get

$$m_p \leq \frac{\lambda f(t, x(t), x'(t))}{(p-1)|x'(t)|^{p-2}} \leq M_p \quad \text{for all } \lambda, t \in [0, 1],$$

which yields the required bounds for x''(t).

Now, introduce sets

$$C^{1}_{+}[0,1] = \{ x \in C^{1}[0,1] : x(t) > 0 \text{ on } [0,1], \ x(1) = \phi_{p}(B) \}$$

and, in case that H holds,

$$V = \{ x \in C^{1}[0,1] : A - \sigma \le x \le L + \sigma, F_{1} - \sigma \le x' \le L_{1} + \sigma \}.$$

Introduce also the map  $\Lambda_{\lambda} : V \to C^1_+[0,1]$  defined by

$$\Lambda_{\lambda} x = \lambda \int_{1}^{t} f(s, x(s), x'(s)) ds + \phi_{p}(B) \quad \text{for } \lambda \in [0, 1].$$

Lemma 2.5. Let H hold and

$$f(t, x, y) \in C\Big([0, 1] \times [A - \sigma, L + \sigma] \times [F_1 - \sigma, L_1 + \sigma]\Big).$$

$$(2.4)$$

*Then*  $\Lambda_{\lambda}$ *,*  $\lambda \in [0, 1]$ *, is well defined and continuous.* 

*Proof.* Clearly, because of (2.4),  $(\Lambda_{\lambda} x)'(t) = \lambda f(t, x(t), x'(t)), x \in V$ , is continuous on [0, 1] for each  $\lambda \in [0, 1]$ . Next, observe that for each  $x \in V$  we have

$$\lambda f(t, x(t), x'(t)) \le \lambda M \le M$$
 for  $\lambda, t \in [0, 1]$ .

Integrating this inequality from 1 to  $t, t \in [0, 1)$ , we get

$$\lambda \int_{1}^{t} f(s, x(s), x'(s)) ds \ge M(t-1), \qquad t \in [0, 1],$$

from where it follows

$$\lambda \int_1^t f(s, x(s), x'(s)) ds \ge -M, \qquad t \in [0, 1],$$

and

$$-M + \phi_p(B) \le (\Lambda_\lambda x)(t), \qquad t \in [0,1].$$

By (1.5) and Proposition 2.3, we have

$$0 < (F_1 - \sigma)^{p-1} < (B - M)^{p-1} \le -M + B^{p-1} = -M + \phi_p(B)$$

and then,

$$0 < (F_1 - \sigma)^{p-1} < (\Lambda_\lambda x)(t), \qquad t \in [0, 1].$$

Obviously,  $(\Lambda_{\lambda} x)(1) = \phi_p(B)$ . Finally, (2.4) implies that the map  $\Lambda_{\lambda}$ ,  $\lambda \in [0, 1]$ , is continuous on *V*.

Further, introduce the sets

$$C^{2}_{BC}[0,1] = \{ x \in C^{2}[0,1] : x(0) = A, \ x'(1) = B \},\$$
  
$$K = \{ x \in C^{2}_{BC}[0,1] : x'(t) > 0 \text{ on } [0,1] \}$$

and the map  $\Phi_p : K \to C^1_+[0,1]$  defined by  $\Phi_p x = \phi_p(x')$ .

**Lemma 2.6.** The map  $\Phi_p$  is well defined and continuous.

*Proof.* For each  $x \in K$  we have x'(t) > 0,  $t \in [0, 1]$ . Then,

$$(\Phi_p x)(t) = x'(t)|x'(t)|^{p-2} = x'(t)^{p-1} > 0 \text{ on } [0,1]$$
 (2.5)

and, obviously,  $(\Phi_p x)'(t) = (p-1)(x'(t))^{p-2}x''(t)$  is continuous on [0,1]. Also,  $(\Phi_p x)(1) = x'(1)|x'(1)|^{p-2} = \phi_p(B)$ . So,  $\Phi_p x \in C^1_+[0,1]$ . The continuity of  $\Phi_p$  follows from  $x' \in C[0,1]$  and (2.5).

It is well known that the inverse function of  $\phi_p(s)$  is  $\phi_q(s) = s|s|^{q-2}$ ,  $q^{-1} + p^{-1} = 1$ , p > 1. Using it, we introduce the map  $\Phi_q : C^1_+[0,1] \to K$ , defined by

$$(\Phi_q y)(t) = \int_0^t \phi_q(y(s))ds + A, \qquad t \in [0,1].$$

But, for  $y \in C^{1}_{+}[0, 1]$  we have y(t) > 0 on [0, 1] and so

$$(\Phi_q y)(t) = \int_0^t (y(s))^{\frac{1}{p-1}} ds + A, \qquad t \in [0,1].$$

**Lemma 2.7.** The map  $\Phi_q : C^1_+[0,1] \to K$  is well defined, the inverse map of  $\Phi_p$  and continuous.

*Proof.* For each fixed  $y \in C^1_+[0,1]$  we get a unique  $x(t) = (\Phi_q y)(t) = \int_0^t (y(s))^{\frac{1}{p-1}} ds + A$ . In fact, to establish the veracity of the first two assertions, we have to show that  $x \in K$  or, what is the same, to show that x is a unique  $C^2[0,1]$ -solution to the BVP

$$x'|x'|^{p-2} = y, \quad t \in [0,1], \qquad x(0) = A, \quad x'(1) = B$$
 (2.6)

with x'(t) > 0 on [0, 1].

The last follows immediately from  $x'(t) = (y(t))^{\frac{1}{p-1}}$  on [0,1]. Then,  $x'|x'|^{p-2} = (x'(t))^{p-1} = y(t)$  for  $t \in [0,1]$ . Besides,  $x'(1) = (y(1))^{\frac{1}{p-1}} = (\phi_p(B))^{\frac{1}{p-1}} = B$  and x(0) = A. Now, the continuity of y'(t) and y(t) > 0 on [0,1] imply that

$$x''(t) = \frac{1}{p-1} (y(t))^{\frac{2-p}{p-1}} y'(t)$$

exists and is continuous on [0, 1]. Thus, x(t) is a solution to (2.6) and is in  $C^{2}[0, 1]$ .

To complete the proof we just have to observe that the continuity of  $\Phi_q$  follows from the continuity of  $y^{1/(p-1)}(t)$  on [0,1].

#### **3 Proof of main result**

*Proof of Theorem 1.1.* We will prove the assertion for an arbitrary fixed p > 2. Introduce the set

$$U = \{x \in K : A - \sigma < x < L + \sigma, F_1 - \sigma < x' < L_1 + \sigma, m_p - \sigma < x''(t) < M_p + \sigma\}$$

and consider the homotopy

$$H_{\lambda}: \overline{U} \times [0,1] \to K$$

defined by  $H_{\lambda}(x) := \Phi_q \Lambda_{\lambda} j$ , where  $j : \overline{U} \to C^1[0, 1]$  is the embedding jx = x. To show that all assumptions of Theorem 2.1 are fulfilled observe firstly that U is an open subset of K, and K is a convex subset of the Banach space  $C^2[0, 1]$ . For the fixed points of  $H_{\lambda}$ ,  $\lambda \in [0, 1]$ , we have

$$\Phi_q \Lambda_\lambda j(x) = x$$

and

$$\Phi_p x = \Lambda_\lambda j(x),$$

which is the operator form of the family

$$\begin{cases} \phi_p(x') = \lambda \int_1^t f(s, x(s), x'(s)) ds + \phi_p(B), \ t \in (0, 1), \\ x(0) = A, \ x'(1) = B. \end{cases}$$
(3.1)

Thus, the fixed points of  $H_{\lambda}$  coincide with the  $C^2[0, 1]$ -solutions of (3.1). But, it is obvious that each  $C^2[0, 1]$ -solution of (3.1) is a  $C^2[0, 1]$ -solution of (2.1). So, all conclusions of Lemma 2.4 are valid in particular and for the  $C^2[0, 1]$ -solutions of (3.1) which allow us to conclude that the  $C^2[0, 1]$ -solutions of (3.1) do not belong to  $\partial U$  and so the homotopy is fixed point free on  $\partial U$ . On the other hand, it is well known that j is completely continuous, that is, it maps each bounded set to a compact one. Thus,  $j(\overline{U})$  is a compact set. Besides, it is clear that  $j(\overline{U}) \subset V$ . Then, according to Lemma 2.5,  $\Lambda_{\lambda}(j(\overline{U})) \subseteq C^1_+[0, 1]$  is compact. Finally, the set  $\Phi_q(\Lambda_\lambda(j(\overline{U})) \subset K$  is compact, by Lemma 2.7. So, the homotopy is compact. Now, since for  $x \in \overline{U}$  we have  $\Lambda_0 j(x) = \phi_p(B) = B^{p-1}$ , the map  $H_0$  maps each  $x \in \overline{U}$  to the unique solution  $l = Bt + A \in K$  to the BVP

$$x' = B, \quad t \in (0,1),$$
  
 $x(0) = A, \quad x'(1) = B,$ 

i.e., it is a constant map and so is essential, by Theorem 2.2. So, we can apply Theorem 2.1. It infers that the map  $H_1(x)$  has a fixed point in U. It is easy to see that it is a  $C^2[0,1]$ -solution of the BVPs of families (3.1) and (2.1) obtained for  $\lambda = 1$  and, what is the same, of (1.1), (1.2).

An elementary consequence of the just proved theorem is the following.

**Corollary 3.1.** Let  $A \ge 0$ , **H** and (1.5) hold, and f(t, x, y) be continuous for  $(t, x, y) \in [0, 1] \times [A - \sigma, L + \sigma] \times [F_1 - \sigma, L_1 + \sigma]$ . Then for each p > 2 BVP (1.1), (1.2) has at least one strictly increasing solution in  $C^2[0, 1]$  with positive values on (0, 1].

We illustrate this result by the following example.

Example 3.2. Consider the BVP

$$(\phi_p(x'))' = rac{(2x'-1)(x'-10)}{\sqrt{x+1}+100}, \quad t \in (0,1),$$
  
 $x(0) = 2, \quad x'(1) = 5,$ 

where p > 2 is fixed.

It is easy to check that **H** holds for  $F_2 = 1$ ,  $F_1 = 2.1$ ,  $L_1 = 11.9$ ,  $L_2 = 13$  and  $\sigma = 0.1$ ; moreover, we can take L = 14, m = -0.5 and M = 0.5. The function  $f(t, x, y) = \frac{(2y-1)(y-10)}{\sqrt{x+1+100}}$ is continuous for  $(t, x, y) \in [0, 1] \times [2, 14] \times [2.1, 11.9]$ . Thus, we can apply Corollary 3.1 to conclude that this BVP has a positive strictly increasing solution in  $C^2[0, 1]$ .

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