

1 **Morphological Functions with Parallel Sets for the Pore Space of X-ray CT Images of Soil**
 2 **Columns**

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5 *Abstract*—During the last few decades, new imaging tech-
 6 niques like X-ray computed tomography have made available rich
 7 and detailed information of the spatial arrangement of soil con-
 8 stituents, usually referred to as soil structure. Mathematical
 9 morphology provides a plethora of mathematical techniques to
 10 analyze and parameterize the geometry of soil structure. They
 11 provide a guide to design the process from image analysis to the
 12 generation of synthetic models of soil structure in order to inves-
 13 tigate key features of flow and transport phenomena in soil. In this
 14 work, we explore the ability of morphological functions built over
 15 Minkowski functionals with parallel sets of the pore space to
 16 characterize and quantify pore space geometry of columns of intact
 17 soil. These morphological functions seem to discriminate the
 18 effects on soil pore space geometry of contrasting management
 19 practices in a Mediterranean vineyard, and they provide the first
 20 step toward identifying the statistical significance of the observed
 21 differences.

(BOSSUYT *et al.*, 2002; VON LÜTZOW *et al.*, 2006). 34
 Performance of many of these functions strongly 35
 depends on pore space geometry. For example, it has 36
 been shown that gradients of a number of soil char- 37
 acteristics exist inside soil. Among them are gradients 38
 in oxygen concentrations of the soil air (SEXSTONE 39
et al., 1985), gradients in concentrations of a variety 40
 of elements, including Ca, Mg, K, Na, Mn, K, Al, and 41
 Fe (SANTOS *et al.*, 1997; JASINSKA *et al.*, 2006), and in 42
 organic matter compositions (ELLERBROCK and GERKE, 43
 2004; URBANEK *et al.*, 2007). These differences in turn 44
 influence soil structure that is of particular impor- 45
 tance for processes such as soil carbon sequestration 46
 (SIX *et al.*, 2000; DENEFF *et al.*, 2001; CHENU and 47
 PLANTE, 2006). 48

23 *1. Introduction*

24 One of the most pervasive features of natural soils
 25 is its structure as expressed by the size, shape, and
 26 arrangement of the soil particles and voids, including
 27 both the primary particles to form compound parti-
 28 cles (i.e. soil aggregates) and the compound particles
 29 themselves (BREWER, 1964). Soil structure plays a
 30 major role in soil functioning, including its contri-
 31 bution to accumulation and protection of soil organic
 32 matter, to optimization of soil water and air regimes,
 33 and to storage and availability of plant nutrients

In this work, we propose a quantitative descrip- 49
 tion of geometrical characteristics of soil pore space 50
 as volume, surface, shape, and connectivity within 51
 the unified framework that provides mathematical 52
 morphology (SERRA, 1982). Mathematical morphol- 53
 ogy includes a plethora of mathematical techniques to 54
 analyze and parameterize the geometry of different 55
 features of soil structure. These techniques belong to 56
 well-established mathematical fields such as integral 57
 geometry (SANTALÓ, 1976), stochastic geometry 58
 (MATHERON, 1975), or digital topology and geometry 59
 (KLETTE and ROSENFELD 2004). They make available a 60
 sound mathematical background that guides the pro- 61
 cess from image acquisition and analysis to the 62
 generation of synthetic models of soil structure (ARNS 63
et al., 2004) to investigate key features of flow and 64
 transport phenomena in soil (LEHMANN, 2005; MECKE 65
 and ARNS, 2005). 66

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X-ray computed tomography (CT) provides a 67
 direct and non-destructive procedure to use three- 68
 dimensional information to quantify geometrical 69
 features of soil pore space (Peyton *et al.* 1994; Perret 70



71 *et al.*, 1999; Pierret *et al.*, 2002; Mees *et al.*, 2003;
 72 LEHMANN *et al.* 2006; SAN JOSÉ MARTÍNEZ *et al.*, 2010;
 73 ZHOU *et al.*, 2013). During the last few decades,
 74 mathematical morphology has been successfully used
 75 to analyze different characteristics of the rich three-
 76 dimensional geometrical information gained through
 77 X-ray CT (MECKE and Stoyan, 2000; Banhart, 2008).
 78 Among the tools of mathematical morphology, Min-
 79 kowski functionals (ARNS *et al.*, 2002; LEHMANN
 80 *et al.*, 2006), which belong to the mathematical the-
 81 ory of integral geometry (SANTALÓ, 1976), are
 82 particularly worthy of consideration since they pro-
 83 vide computationally efficient means to measure four
 84 fundamental geometrical properties of three-dimen-
 85 sional geometrical objects such as soil pore space.
 86 These properties are the volume, the boundary sur-
 87 face, the integral mean curvature, and the
 88 connectivity of the object of interest. Hadwiger's
 89 theorem (SANTALÓ, 1976) states that any functional
 90 that assigns a number to any three-dimensional object
 91 and meets some self-evident and natural geometrical
 92 restrictions is a linear combination of these Min-
 93 kowski functionals. Then, these functionals are
 94 powerful tools to describe quantitatively 3D geome-
 95 try. MECKE (1998) and ROTH *et al.* (2005) made use of
 96 Minkowski functions based on threshold variation of
 97 Minkowski functionals to characterize two-dimen-
 98 sional porous structures. San José Martínez *et al.*
 99 (2013) used the same methodology with the pore
 100 space of columns of intact soil. Also, two-dimen-
 101 sional porous structures were investigated by MECKE
 102 (2002) and VOGEL *et al.* (2005) with Minkowski
 103 functions based on dilations and erosions. ARNS *et al.*
 104 (2002, 2004) considered the evolution of Minkowski
 105 functionals with dilations and erosions to characterize
 106 3D images of Fontainebleau sandstone. Renard and
 107 Allard (San José Martínez 2013) used the Euler
 108 number as a function of erosion/dilation to explore
 109 the role of connectivity for the characterization of
 110 heterogeneous aquifers with 2D models.

111 In this work, we introduced two morphological
 112 transformations, namely erosion and dilations, and
 113 morphological functions built over Minkowski
 114 functionals. These morphological functions take
 115 account of the evolution of Minkowski functionals
 116 as dilations and erosions are performed on the object
 117 of interest, the pore space of soil columns imaged

with X-ray CT. In this way, different geometrical 118
 objects are provided that can be seen as parallel sets 119
 of the pore space. Then, the Minkowski functionals 120
 of the new objects are computed and represented as 121
 a function of the radius of the ball of the structuring 122
 element of the corresponding dilation/erosion. We 123
 observed that morphological functions of dilation/ 124
 erosion seem to discriminate between two pore 125
 structures in a Mediterranean vineyard subjected to 126
 contrasting management practices: conventional 127
 tillage and permanent cover crop of resident 128
 vegetation. 129

2. Morphology of Pore Space Volume 130

Morphological analysis mimics other scientific 131
 procedures, and in some instances it can be seen as a 132
 two-step process. To illustrate this point, let us con- 133
 sider, for instance, the procedure to determine 134
 particle size distributions by sieving. This technique 135
 first generates a series of subsets of primary mineral 136
 particles, the oversize sets corresponding to each 137
 sieve size; then, these oversize sets are weighted. In 138
 morphological analysis, first, geometrical transfor- 139
 mations are applied to the object of interest in an 140
 image, and then measurements are carried out. When 141
 the granulometry of an image of grains of different 142
 sizes shall be determined, successive morphological 143
 operations are performed on the image. These oper- 144
 ations consist on the elimination of grains smaller 145
 than a certain size with a suitable morphological 146
 transformation (Fig. 1). Each one of these operations 147
 is followed by the measurement of the area for 2D 148
 images or the volume for 3D images, of the grains left 149
 (SERRA, 1982). Figure 1 illustrates this procedure in a 150
 CT image of a packing of sand particles. Now we are 151
 going to describe the basic morphological operations, 152
 i.e. dilations and erosions. Finally, the notions of 153
 Minkowski functionals and morphological functions 154
 will be presented. 155

3. Morphological Operations 156

Grains or pore space in a 3D CT image of soil will 157
 be idealized as sets of points in three-dimensional 158

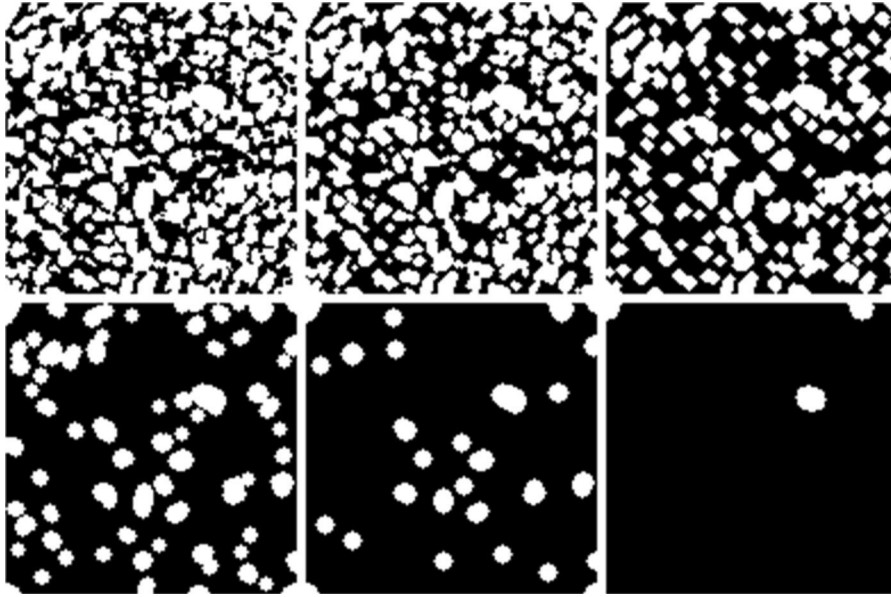


Figure 1

Granulometric analysis of a section of a CT image of 15.4 mm side of a packing of sand particles by successive morphological operations

159 space. These types of geometrical objects will be the
 160 mathematical objects of interest. In this work we will
 161 focus on soil pore space as the geometrical object of
 162 interest. Mathematically, an object is a closed and
 163 bounded set. A ball is a closed set if it contains the
 164 points of the spherical surface that defines its
 165 boundary. And it is a bounded set because it is con-
 166 tained in a sphere of finite radius. Dilation of an
 167 object expands it. This new object can be thought of
 168 as being the union of all balls with a given radius r
 169 centered at points of the original object. If the ori-
 170 ginal object is a ball of radius r_0 , the dilated object
 171 by balls of radius r will be a new ball of radius $r_0 + r$.

172 We consider a generic object K and a ball B of
 173 radius 1 whose center is located at the origin of
 174 coordinates. Both K and B are objects, closed and
 175 bounded sets, but K is the object of interest or simply
 176 an object that we scrutinize with the object B that is
 177 called the structuring element. A ball of radius r
 178 centered at the origin, rB , is obtained by multiplying
 179 the coordinates of the points of B by r . In a ball of
 180 radius 1, centered at point x , B_x , is obtained adding x
 181 to every point of B . Scalar multiplication by a posi-
 182 tive number r produces an expansion with scaling
 183 factor r when $r > 1$, and a contraction with scaling
 184 factor r when $r < 1$. Addition with a vector x

185 produces a translation in the direction of the vector x
 186 at a distance equal to the “length” of this vector, its
 187 modulus. Then, we have the following mathematical
 188 expressions that define the sets rB and B_x (OSHER and
 189 MÜCKLICH 2000):

$$rB = \{ry : y \in B\} \quad \text{and} \quad B_x = \{y + x : y \in B\} \quad (1)$$

190 That is to say, rB is the set of points ry when y
 191 belongs to B , and B_x is the set of points $y + x$ when y
 192 belongs to B . In these expressions, ry stands for the
 193 scalar multiplication of the scalar r and the vector y ,
 194 and $y + x$ represents the sum of two vectors, y and x .
 195 Thus, the dilation (Fig. 2) of the object K by balls of
 196 radius r , that is the union of all balls rB_x of radius r
 197 centered at points x of K , will be another object K_r
 198 defined as
 199

$$K_r = \bigcup_{x \in K} rB_x. \quad (2)$$

200 The set K_r is also called the parallel body of K at a
 201 distance r or r -parallel body to K . This is the set of all
 202 points within a distance smaller than r from the
 203 object K . In this work, the structuring element will be
 204 a ball centered at the origin. Then, the dilation of an
 205 object by a ball of radius r is equivalent to the r -
 206

Author Proof

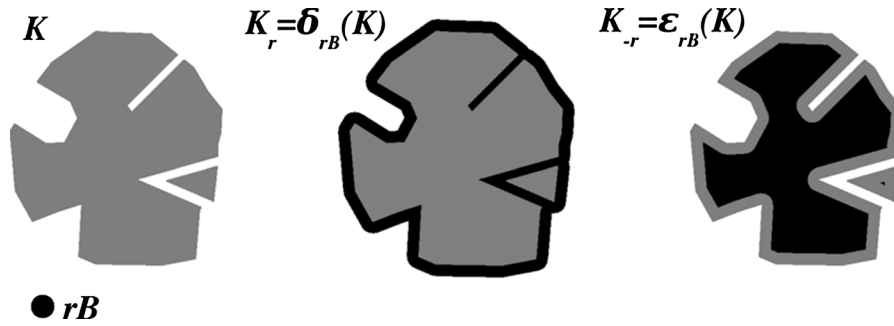


Figure 2

Effect of dilation $K_r = \delta_{rB}(K)$ (grey plus black) and erosion $K_{-r} = \epsilon_{rB}(K)$ (black) of object K by the structuring element rB

parallel body to K . Roughly speaking, it is like a “skin” of thickness r is added to K .

We will analyze binary (black and white) images of soil. They contain two complementary phases: the phase of voids (pores) and the phase of soil matrix (mineral particles). As we said previously, in this study, the pore space is the object of interest and it will be white, while the mineral matrix will form the background and it will be black, as is customary in image analysis. Then, the erosion of one phase is equivalent to the dilation of the complementary phase. Erosion of the pore space is dilation of the soil matrix, and erosion of the soil matrix is dilation of pore space. For an object K , the erosion by a ball of radius r is defined as (ARNS *et al.*, 2002).

$$K_{-r} = \{x : rB_x \subset K\} \tag{3}$$

Consequently, the erosion of an object K by a ball rB corresponds to the set of all positions of their centers within K where the structuring element rB fits completely into K (Fig. 2). Roughly speaking, it is like a “layer” of thickness r is removed from K . Therefore, we may generalize the notion of r -parallel body so that K_r will be a dilation for $r > 0$, and erosion for $r < 0$ and the original object K for $r = 0$ (ARNS *et al.*, 2002).

4. Measurements: Minkowski Functionals

What is the area of a two-dimensional object or the volume of a three-dimensional one when the object is dilated? Let us consider a simple object like a square or a cube with edges of size a and a disk or a

ball of radius r as a structuring element. In the plane, the area of the dilated object K_r of a square K by a disk rB can easily be computed as (Fig. 3).

$$\begin{aligned} A(K_r) &= A(\delta_{rB}(K)) = a^2 + 4ar + \pi r^2 \\ &= A(K) + L(K)r + A(B)r^2. \end{aligned} \tag{4}$$

In this expression, A stands for the area and L stands for the length of the perimeter of the square K . Here, B is the disk centered at the origin with radius 1. In the space, we get

$$\begin{aligned} V(K_r) &= V(\delta_{rB}(K)) = a^3 + 6a^2r + 3\pi ar^2 + \frac{4}{3}\pi r^3 \\ &= V(K) + S(K)r + M(K)r^2 + V(B)r^3 \end{aligned} \tag{5}$$

Here, V stands for the volume, S for the area of the boundary, and M for the mean breadth multiplied by 2π (it can be shown that the mean breadth of a

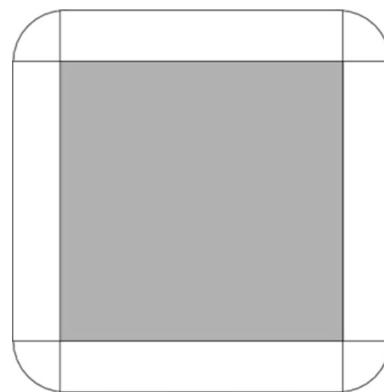


Figure 3

Dilation of a square with a disk as structuring element

cube of edge a is $3a/2$ (SANTALÓ, 1976). Here, B is the ball centered at the origin with radius 1.

Now, let us consider a general convex object in d -dimensional linear space; then one has the Steiner formula (OSHER and MÜCKLICH, 2000).

$$V(K_r) = \sum_{i=0}^d \binom{d}{i} W_i^{(d)}(K). \quad (6)$$

In this expression, $W_i^{(d)}(K)$ are the Minkowski functionals. There are $d + 1$ Minkowski functionals in dimension d .

Minkowski functionals are a complete set of geometrical features as established by Hadwiger's theorem (SANTALÓ, 1976). In simple terms, this theorem states that any functional that assigns a number to any object of interest and fulfills some very natural geometrical restrictions is a linear combination of the Minkowski functionals with numbers as scalars of this linear combination.

There are three Minkowski functionals in the plane and four in space. In the plane (the two-dimensional linear space), one has

$$\begin{aligned} W_0^{(2)}(K) &= A(K), \quad W_1^{(2)}(K) = L(K) \quad \text{and} \\ W_2^{(2)}(K) &= A(B)\chi(K). \end{aligned} \quad (7)$$

In this expression, A stands for the area, L stands for the length of the perimeter of K , and $\chi(K)$ for its Euler-Poincaré characteristic. Here, B is the disk centered at the origin with radius 1. In space (the three-dimensional, linear space), one has

$$\begin{aligned} W_0^{(3)}(K) &= V(K), \quad W_1^{(3)}(K) = (1/3)S(K), \\ W_2^{(3)}(K) &= (1/3)M(K) \quad \text{and} \\ W_3^{(3)}(K) &= V(B)\chi(K). \end{aligned} \quad (8)$$

Here, B is the ball centered at the origin with radius one, V stands for the volume, S for the area of the boundary, and M for the mean breadth multiplied by 2π (it can be shown that the mean breadth of a cube of edge a is $3a/2$ (SANTALÓ, 1976). As before, $\chi(K)$ is the Euler-Poincaré characteristic of the spatial object K . See Appendix 2 for more details on interpretation of these functionals.

Another important feature of Minkowski functionals is that they are easy to compute (MICHIELSEN 2001). For computational purposes, points of

geometrical objects are considered a voxel of a digital image (i.e. the elements of regular lattice). Taking into account the C -additivity property (see Appendix 1) and the fact that digital images are sets of cubes (or voxels), their computation reduces to the computation of the Minkowski functionals on cubes and their intersections (vertices, edges, and faces) (LIKOS *et al.*, 1995).

5. Morphological Functions

Mathematical morphology offers a powerful description of objects in terms of functions. This technique is similar to the process that provides particle size distributions by morphological analysis of soil images (SERRA, 1982; SOILLE, 2002; VOGEL, 2002).

Consider a 3D binary image of soil where the void phase K is the object of interest. Let K_r be, as before, the dilation of K by balls of radius r when $r > 0$ and the erosion of K by balls of radius r when $r < 0$. Then, consider any Minkowski functional, say M , and the function

$$f(r) = M(K_r) \quad (9)$$

This family of functions built over the Minkowski functionals provides a way to investigate the morphology of the pore space K as it is dilated and eroded with balls of increasing radius r . VOGEL *et al.* (2005) used this approach on 2D images to describe crack dynamics in clay soil. ROTH *et al.* (2005) make use of opening (i.e. erosion followed by dilation) to build Minkowski functions to quantifying permafrost patterns with aerial photographs. These functions add new information to that provided by Minkowski functionals as they yield the pore size distribution of the porous structure. ARNS *et al.* (2004) characterized disordered systems and matched model reconstructions to 3D images of Fontainebleau sandstone with Minkowski functions based on dilations and erosions. VOGEL *et al.* (2010) took advantage of Minkowski functions based on openings to quantify soil structure of arable soil and of repacked sand using 3D images from X-ray tomography of samples of different sizes recorded at different resolutions.



MECKE (1996) considered a different type of Minkowski function. In this case, the original 2D image is a grayscale image before segmentation. A series of binary images were obtained when the threshold varied from the minimum value of the grayscale to its maximum. Minkowski functionals were evaluated on each binarized image of the series, and four Minkowski functions were defined when the Minkowski functionals evolved as a function of threshold. ROTH *et al.* (2005) also made use of this type of functions to quantify permafrost patterns obtained from aerial 2D photographs.

In this work, we will investigate, in a three-dimensional setting, how Minkowski functions based on parallel sets of binary 3D X-ray CT images of soil columns can be used to characterize soil pore structure of cultivated soil.

6. Materials and Methods

6.1. Soil Columns: Sample Collection

The columns were collected at the experimental farm “Finca La Grajera”, a property of La Rioja region government, northern Spain, Latitude, 42°26′34 18″N; longitude 2°30′53 07″W, in December 2010. The field slope was about 10.2 % with west-east orientation. The soil was classified as fine-loamy, mixed, thermic Typic Haploxerepts according to the USDA soil classification (Soil Survey Staff, 2006), and contained 230 g kg⁻¹ clay, 433 g kg⁻¹ silt, 337 g kg⁻¹ sand, 9.3 g kg⁻¹ organic matter, and 149 g kg⁻¹ carbonates, with pH 8.62 and electrical conductivity 0.17 dS m⁻¹ at the Ap horizon (0–20 cm). Climate in the area is semiarid according to the UNESCO aridity index (UNESCO, 1979), with heavy winter rains and summer drought conditions. For the period 2005–2009, the average annual precipitation was 470 mm, average annual temperature was 13 °C, and average annual potential evapotranspiration (FAO-Penman) was 1,132 mm.

In this study, we considered four columns collected between rows of the vineyard that was established in 1996 with *Vitis vinifera* L. “Tempranillo”, grafted onto 110-R rootstock. Two types of soil cover management in between rows were undertaken:

(T) conventional tillage management between rows, which consisted of a soil tillage of 15-cm depth by cultivator once every 4–6 weeks, as required for weed control during the grapevine growth cycle; (C) permanent cover crop of resident vegetation, which was dominated by annual grass and forbs common to La Rioja vineyards (see PEREGRINA *et al.*, 2010, for more details). Columns were extracted vertically by percussion drilling between rows, within PVC cylinders of 7.5 cm interior diameter and 30 cm height from the upmost part of soil profile. As a consequence, only the upper half of the column was affected by tillage that was undertaken 3 months before the collection of samples.

6.2. Image Acquisition, Filtering, and Segmentation

Soil columns were scanned at Fraunhofer ITWM facilities (Germany) with a PerkinElmer amorphous silicon (a-Si) detector with 2,048 × 2,048 pixels and a Feinfocus FXE 225.51 microfocus beam source tube. It was operated at 190 kV (53 μA) acceleration voltage and 20 W target power. The tube had a tungsten target installed. In addition, a collimator to reduce stray radiation and a 200-μm steel filter in front of the target was used. Only the upper half of the column was scanned to image the tilled part of the columns from tilled soil, and the region between 6.5 and 15 cm was selected to have a resolution of 50 μm. In this way, soil macro-pore structure important for intense renewal of air and serving to transport and distribute water in soil (BREWER, 1964) was imaged.

Raw data from tomography correspond to a stack of 1,706 two-dimensional, 16-bit grayscale images with a pixel size of 50 μm. These horizontal sections are disks of 7.5 cm diameter, 50 μm apart from one another. Thus, the 3D image is made up of voxels of 50 μm. Light values of the grayscale designate voxels corresponding to low densities of the soil column, whereas high values indicate voxels of high density parts of the column. The original 2D projections were filtered by a 3 × 3 median filter before reconstruction in order to reduce random noise from the detector. It is a nonlinear smoothing method used to reduce isolated noise without blurring sharp edges (WANG and LAI, 2009).



417 The segmentation process provides a way to
 418 separate the object of interest from the background, in
 419 this case, the pore space from the soil matrix. This
 420 process produces binary images when a threshold is
 421 selected, and every voxel with a grayscale value
 422 lower than the selected threshold is considered part of
 423 the pore space and set to 1 (white), while every voxel
 424 with a grayscale value higher than the selected
 425 threshold is considered part of the soil matrix and set
 426 to 0 (black). ImageJ version 1.47v, a public domain
 427 program developed at the National Institutes of
 428 Health, was used for image processing. We selected
 429 a global method as we focused primarily on the
 430 analysis of geometrical features evolutions. The
 431 modes method of thresholding was chosen to gener-
 432 ate binary images (SONKA *et al.*, 1998) for its
 433 performance (LASSANOV *et al.*, 2009). In this proce-
 434 dure, the histogram is iteratively smoothed until there
 435 are only two local maxima. Then, the threshold is
 436 chosen at the midpoint between these local maxima.
 437 Figure 4 illustrates image binarization, and Fig. 5
 438 shows the view of 3D reconstruction of pore space in
 439 a binary image. The plot of histograms with loga-
 440 rithmic scale on the vertical axis is displayed (Fig. 4)
 441 to show the two maxima. Notice the different pore
 442 structures that display a typical sample from soil
 443 under cover crop of resident vegetation and from soil
 444 under conventional tillage (Fig. 5). The homogeneity
 445 of the pore space produced by tillage is obvious (T
 446 samples) as compared to the much more heteroge-
 447 neous result of the cover resident vegetation crop (C
 448 samples).

449 6.3. Computing Minkowski Functions for Parallel 450 Sets

451 We will consider binary images segmented with the
 452 modes method procedure. In these images, the pore
 453 space will be the object of interest while the soil matrix
 454 will be the background. Now, to study pore structure,
 455 we will investigate the evolution of Minkowski func-
 456 tionals as successive erosions, and dilations with balls
 457 of increasing radius are performed on the binary images
 458 (ARNS *et al.*, 2002; VOGEL *et al.* 2005).

459 We follow the procedure developed by MECKE
 460 (1996) and the code published by MICHIELSEN (2001)
 461 to compute Minkowski functionals. For the sake of

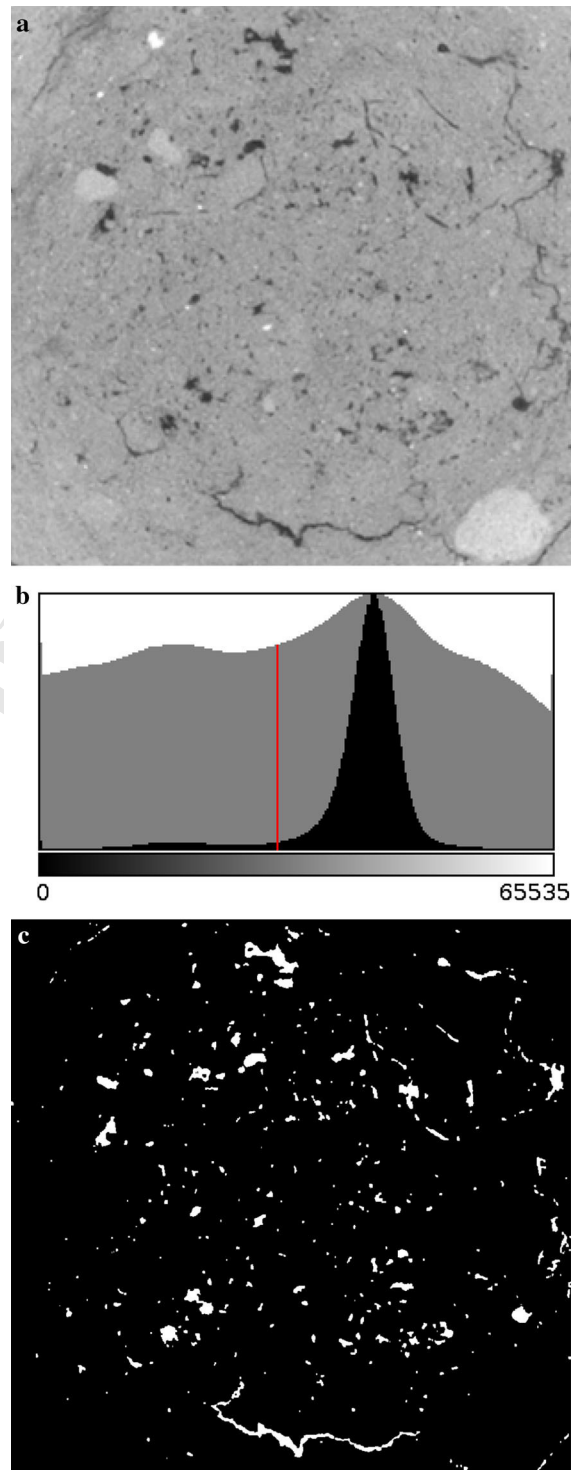


Figure 4

Segmentation process on a horizontal section of 960×960 pixels of column C1: **a** gray-scale image, **b** histogram with (black) and without (grey) logarithmic scales, and the resulting threshold marked with a vertical red line, and **c** segmented image (white voids, black solid)

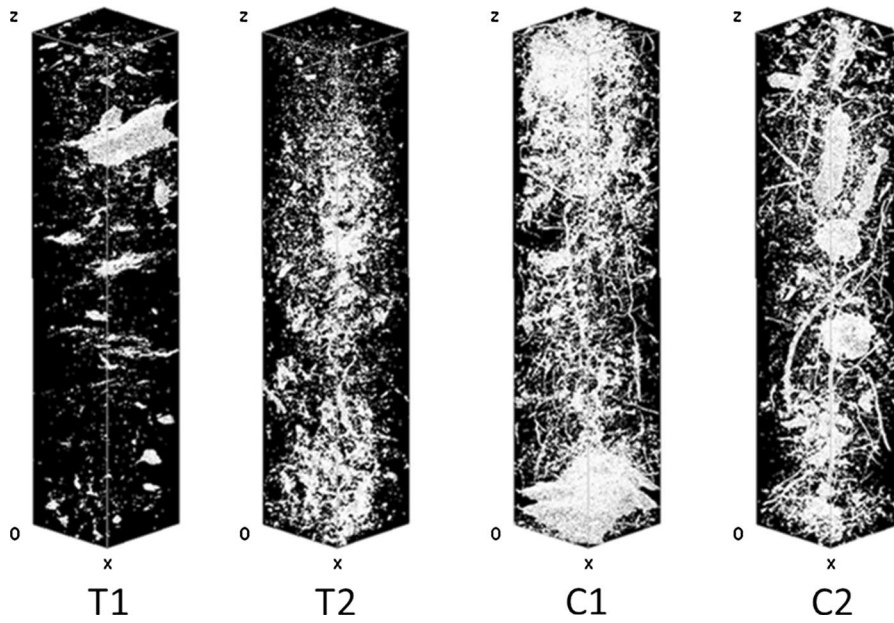


Figure 5

3D reconstructions of the pore geometry (*white*) in each soil column in a box that is 8.5 cm high (*z* axis) and 1.7 cm long (*x* axis) and wide (*y* axis)

462 clarity, let us illustrate this procedure in 2D images
 463 made up of pixels that geometrically are squares. The
 464 object of interest, K , is a finite union of squares
 465 (compact and convex object). Each square is consid-
 466 ered to be decomposed into the four points of its four
 467 vertices, the four open segments of its four edges, and
 468 the rest of the square, i.e. its interior. Then, the square
 469 of each pixel is the union of nine disjoint sets: four
 470 points, four open segments, and the interior of the
 471 square. As a consequence, we only need to know the
 472 Minkowski functional of these three types of sets (a
 473 point, an open segment, and an open square), and
 474 then use C-additivity extended to the union of an
 475 arbitrary amount of sets. If n_s is the number of
 476 squares of the object, n_e the number of edges, and n_v
 477 the number of vertices of the pixels of the object of
 478 interest are counted once, it is easy to verify that
 479 (MICHIELSEN 2001).

$$A(K) = n_s, \quad L(K) = -4n_s + 2n_e \quad \text{and} \quad (10)$$

$$\chi(K) = n_s - n_e + n_v.$$

480 For three-dimensional objects, a similar argument
 482 shows that (MICHIELSEN 2001).

$$V(K) = n_c, \quad S(K) = -6n_c + 2n_f,$$

$$\pi^{-1}M(K) = 3n_c - 2n_f + n_e \quad \text{and} \quad (11)$$

$$\chi(K) = -n_c + n_f - n_e + n_v$$

In this expression, n_c is the number of cubes and
 n_f is the number of faces of the voxels of the object
 K , counted once.

The Euler-Poincaré characteristic—Euler number,
 for short—describes the connectivity of an object. In
 order to reconcile this global topological point of
 view with the local counterpart that displays the
 computation of this number in terms of numbers of
 cubes, faces, edges, and vertices, it is necessary to
 define when voxels are connected, or equivalently,
 when are they neighbors. In the plane, a common
 choice is to consider that two black pixels are
 connected when they have an edge or a vertex in
 common. In the three-dimensional space, it is
 customary to consider two black voxels connected
 when they have a face, an edge, or a vertex in
 common. This implies that any voxel is connected to
 26 voxels or it has 26 neighbors (MICHIELSEN and DE
 RAEDT, 2001).

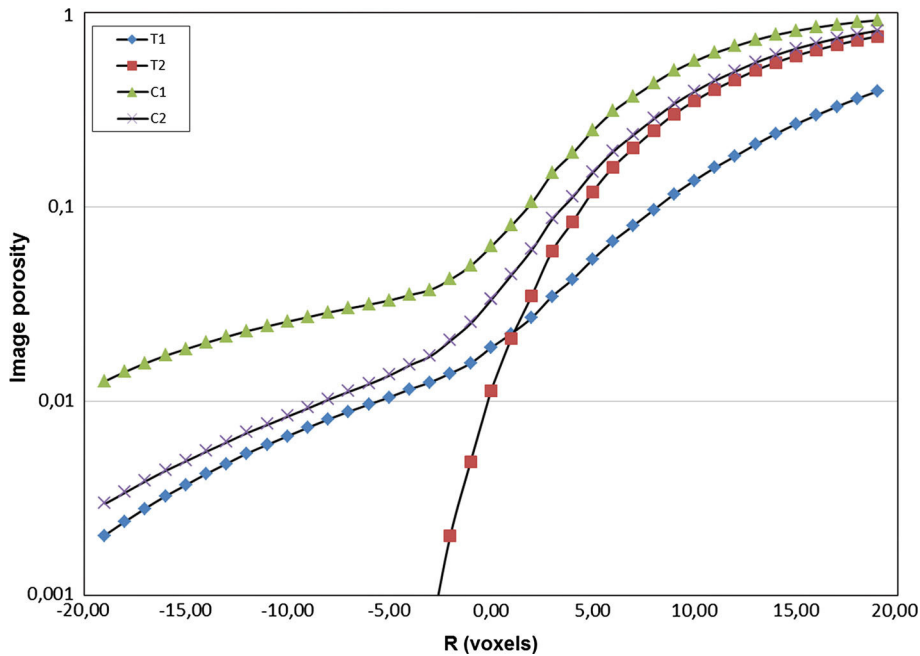


Figure 6
Image porosity as a function of diameter of erosion/dilatation

503

7. Results and Discussion

504 To evaluate Minkowski functionals, each column
 505 was divided into five consecutive cubes that shared a
 506 face, from top to bottom. The cubes had 340 voxels
 507 per edge and they were centered on the axes of the
 508 column in order to avoid voxels belonging to the
 509 container or voxels representing soil near the sam-
 510 pling tube that might have been damaged during
 511 sampling. The pore space in each cube was eroded/
 512 dilated to yield parallel sets. Diameters of balls took
 513 19 different values for erosions and 19 for dilation,
 514 as well; it was incremented from 0 in steps of the voxel
 515 size (i.e. 50 μm). As Minkowski functionals are
 516 additive, their values for each column were obtained
 517 by simply adding the corresponding values of the
 518 cubes of the column. We considered densities of
 519 Minkowski functionals. Thus, we had volume frac-
 520 tion or image porosity, specific boundary surface area,
 521 specific integral of mean curvature, and specific
 522 Euler number of the pore space.

523 Figures 6, 7, 8, 9 display the evolution of these
 524 geometrical densities as functions of erosion/dilatation
 525 diameter (R). As stated above, dilations of pore space
 526 produce an increase of its volume. Let us remark that

this effect is more pronounced when there are tunnels
 of soil materials through voids because dilations
 reduce them, even if it also depends on the com-
 plexity of the pore-solid interface as measured by
 surface area and integral of mean curvature. Roughly
 speaking, dilations turn some voxels of the soil
 matrix into voxels of its pore space. Hence, this
 morphological operation expands the void part of the
 sample. Erosion produces the inverse process. Dif-
 ferences between soil samples under natural resident
 vegetation cover (C) and samples under conventional
 tillage (T) are noticeable even if samples T2 and C2
 have a similar evolution for dilations. Nevertheless,
 the evolution of image porosity (Fig. 6) and specific
 boundary surface (Fig. 7) with erosions diverges.
 This suggests that geometrical features of sample T2
 are smaller than three voxels as they vanish with
 erosions of diameter smaller than that size. The
 opposite behavior is observed on sample C1. The
 erosion with the larger ball still left an important
 amount of porosity in this sample. Overall, samples
 with natural resident vegetation cover (C) store a
 greater amount of volume fraction and specific sur-
 face at any diameter of the balls used to erode/dilate
 as compared to samples from tilled soil (T). This is



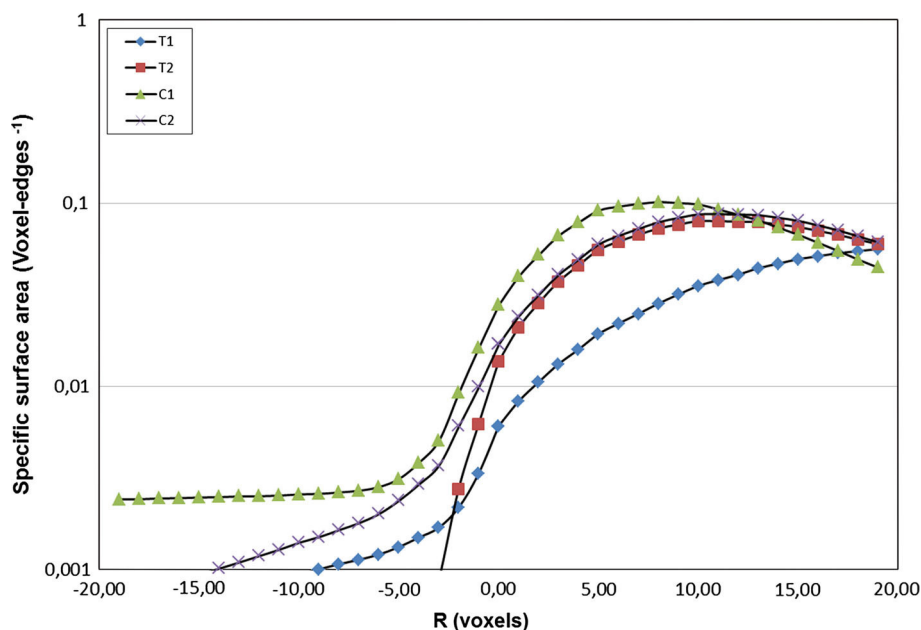


Figure 7
Specific surface area (voxel-edges⁻¹) as a function of diameter of erosion/dilatation

552 consistent with results reported by PEREGRINA *et al.*
553 (2010).

554 Figures 8 and 9 depict the evolution of the specific
555 integral of mean curvature—mean curvature, for
556 short—and connectivity. Let us remember that the
557 connectivity is evaluated as the number of connected
558 components of the object of interest minus its tunnels
559 plus its cavities (see Appendix 2). Tunnels are
560 redundant loops or handles, as torus-like holes
561 through the object of interest. As we are dealing with
562 images of a natural soil, we may assume that there are
563 no soil materials completely surrounded by voids and,
564 as a consequence, the Euler number corresponds to the
565 number of connected components of the pores space
566 minus the number of tunnels of solid materials
567 through the pore space. The morphological functions
568 of the specific mean curvature (Fig. 8) and connect-
569 ivity (Fig. 9) seem to indicate that conventional
570 tillage and resident vegetation cover produces two
571 different pore structures; this difference is especially
572 apparent when comparing samples C1 and T1. Sample
573 C1 yields more specific mean curvature than sample
574 T1 when dilated with balls smaller than nine voxels.
575 In this range of diameters, mostly small voids con-
576 necting soil matrix should populate sample C1 as

577 compared to sample T1, as is apparent from Fig. 5. 577
578 High Euler numbers of sample C1 at small diameters 578
579 seem to suggest this behavior. But large diameters 579
580 decrease specific mean curvature and Euler number of 580
581 sample C1, producing negative values. Nevertheless, 581
582 in the case of T1, these geometrical measurements 582
583 have lower growth. In the case of connectivity, it is 583
584 negative for the largest diameter of dilations. This 584
585 suggests that the pore structure of sample C1 contains 585
586 a great amount of small features as the number of 586
587 small voids (i.e. connected components) exceeds the 587
588 number of tunnels of solid materials through them; 588
589 therefore, high values of the specific mean curvature 589
590 from these small features of the C1 pore space might 590
591 be explained by the regularity of the surface that 591
592 enclosed them, and they are also compatible with their 592
593 small size. Moreover, C1 seems to display a rich 593
594 structure as compared to sample T1. Between diam- 594
595 eters 8 and 9, the graphs of both samples intersect at 595
596 a positive specific mean curvature, but sample C1 has 596
597 negative Euler characteristic. Therefore, it suggests 597
598 that geometrical features similar in size should dom- 598
599 inate sample T1, while the dilations of sample C1 599
600 show a more complex structure highly connected with 600
601 tunnels through it, as it seems to indicate negative 601

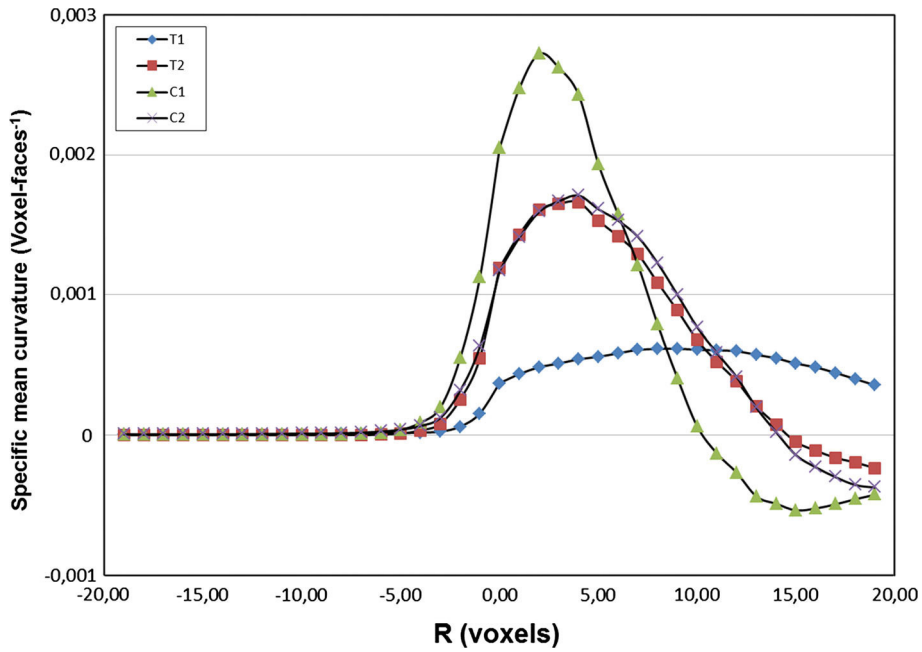


Figure 8
Specific curvature (voxel-faces⁻¹) as a function of diameter of erosion/dilatation

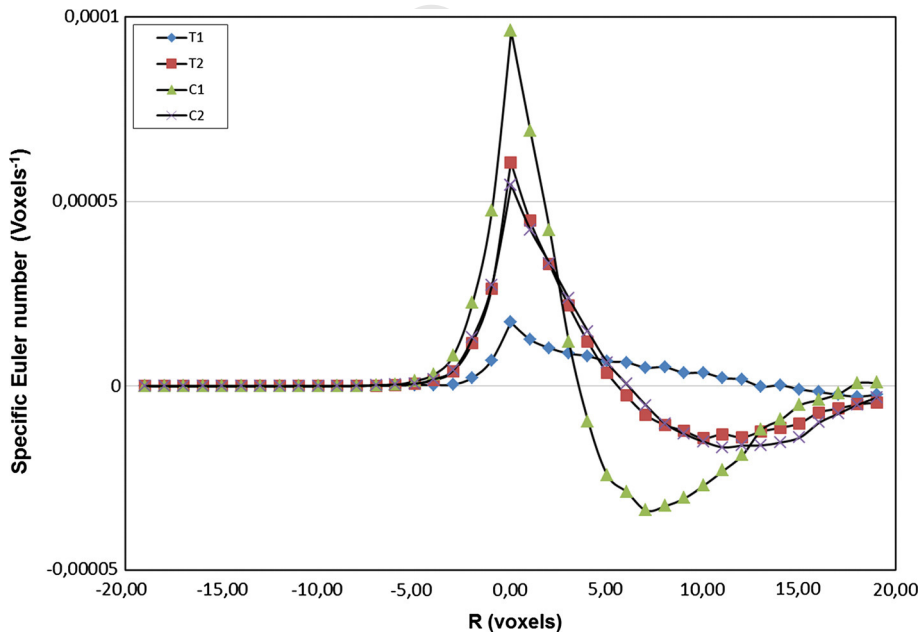


Figure 9
Specific Euler number (voxel⁻¹) as a function of diameter of erosion/dilatation

602 Euler numbers. The low variation of specific mean
603 curvature and Euler numbers of sample T1 is com-
604 patible with a pore structure made up with irregular

geometrical features of similar sizes that collapse as
diameter of dilation increases and do not generate a
complex and highly connected structure.

605
606
607

608 These results open the door to new investigations
 609 to identify statistically significant differences in soil
 610 structure due to contrasting management practices. It
 611 was the necessary first step towards further research
 612 that should include a richer sample. Then, the trends
 613 that suggest this study would be the hypothesis of
 614 those new investigations. Therefore, this might pro-
 615 vide the basis for new projects that are likely to be
 616 lengthy and costly, as there is the need for a greater
 617 amount of 3D tomograms of large soil columns.

618 It has been reported that different land use and
 619 management practices significantly affect directions
 620 and magnitudes of the soil processes by contributing
 621 different quantities and qualities of biomass inputs,
 622 generating different levels of soil disturbance, influ-
 623 encing soil temperature and moisture regimes. These
 624 differences generate notable changes in soil physical
 625 and hydraulic properties, including changes in soil
 626 organic matter content, soil porosity, hydraulic con-
 627 ductivity, and water retention (WANG *et al.*, 2012;
 628 Zhou *et al.*, 2013). Our results suggest that the evo-
 629 lution of morphological features with dilation/erosion
 630 is a suitable indicator of soil structure for cultivated
 631 soil, and it seems to describe the influence of two
 632 different soil management practices (i.e. conventional
 633 tillage and natural cover crop) on soil structure in a
 634 Spanish Mediterranean vineyard. It is worth noting
 635 here how these results reflect the different pore
 636 structures as depicted by Fig. 5. The homogeneity of
 637 the pore space produced by tillage is obvious as
 638 compared to the heterogeneity of samples under
 639 resident vegetation cover. Similar geometrical fea-
 640 tures seem to dominate samples T2 and C2, but big
 641 structures discriminate between them and explain the
 642 behavior of the morphological functions of image
 643 porosity and specific boundary surface when sample
 644 T2 is eroded. These results are consistent with pre-
 645 vious studies on the impact of land use on soil
 646 structure (KRAVCHENKO *et al.*, 2011; WANG *et al.*,
 647 2012) when they remarked on the homogeneity of the
 648 pore structure of conventional tillage as compared
 649 with no-till.

650 Soil structure is regarded as one of the main
 651 providers of physical protection of soil organic matter
 652 and carbon sequestration by soils (SIX *et al.*, 1998).
 653 One of the mechanisms of such protection is a
 654 reduced access of organic material inside soil voids to

decomposing microorganisms. The differences that
 we are observing in the porosity patterns between C
 and T samples hint at their potentially different
 effectiveness for protecting carbon. Clearly, T sam-
 ples with their network of bigger voids will be
 offering greater microbial access, thus poorer pro-
 tection than the C samples that have more porosity
 connected with smaller features. Observations of
 ANANYEVA *et al.* (2013) support this hypothesis.

8. Conclusions

In this work, we have introduced the essential
 tools of mathematical morphology in order to quan-
 tify the geometrical morphology of soil structure. We
 made use of 3D images from X-ray CT of soil col-
 umns collected at the experimental farm “Finca La
 Grajera”, property of the La Rioja region govern-
 ment, northern Spain. In this study, we considered
 four columns collected between rows of the vineyard
 that was established in 1996 with *Vitis vinifera* L.
 “Tempranillo”. Two types of soil management in
 between rows were undertaken: (T) conventional
 tillage management between rows, which consists of
 a soil tillage of 15-cm depth by cultivator once every
 4–6 weeks, as required for weed control during the
 grapevine growth cycle; (C) permanent cover crop of
 resident vegetation, which was dominated by annual
 grass and forbs common to La Rioja.

We have presented the building blocks of math-
 ematical morphology, the morphological operations
 of dilation, erosion. We have dealt with the Min-
 kowski functionals (i.e. volume, boundary surface,
 curvature, and connectivity) and the Minkowski
 functions that take account of the evolution of the
 Minkowski functionals as morphological operations
 are performed on the 3D object of interest with balls
 of increasing diameter.

Our results suggest that the evolution of mor-
 phological features with dilation/erosion is a suitable
 indicator of soil structure for cultivated soil and it
 seems to describe the influence of two different soil
 management practices (i.e. conventional tillage and
 natural cover crop) on soil structure in a Spanish
 Mediterranean vineyard. It is worth noting here how
 these results reflect the different pore structures as

699 depicted by Fig. 5. The homogeneity of the pore
700 space produced by tillage is obvious as compared to
701 the heterogeneity of samples under resident vegeta-
702 tion crop. Similar geometrical features seem to
703 dominate samples T2 and C2, but big structures dis-
704 criminate between them and explain the behavior of
705 specific image porosity and boundary surface when
706 sample T2 is eroded.

707 These geometrical descriptors that seem to dis-
708 criminate between these two types of samples could
709 be used as inputs for morphological models of natural
710 soil structures. But further investigations are needed
711 to establish quantitatively the statistical significance
712 of the observed impact of contrasting management
713 practices on soil structure.

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723 work.

724 Appendix 1

725 Let us be more precise and specify the objects of
726 interest and the geometrical conditions of Hadwiger's
727 theorem. A class of objects to which this theorem
728 applies is the class of sets that can be viewed as the
729 union of a finite number of convex objects. An object
730 K is convex when it contains any point of the seg-
731 ment that joins two of its points. The class of objects
732 made up of finite unions of convex sets is worth
733 considering as any three-dimensional binary image
734 can be considered an element of this class. Binary
735 images are sets of voxels which may be thought of as
736 being cubes, and then any geometrical structure of
737 interest in a binary image is a finite union of convex
738 objects, which are the voxels.

739 There are three geometrical conditions that a
740 functional to which Hadwiger's theorem applies must
741 fulfill. The first one is motion invariance: the number
742 assigned by a functional must be independent of the
743 position of the object in space when the object is
744 translated or rotated. The second one is C -additivity:

$$\mathcal{F}(K_1 \cup K_2) = \mathcal{F}(K_1) + \mathcal{F}(K_2) - \mathcal{F}(K_1 \cap K_2) \quad (12)$$

745 That is to say, the number assigned by a func-
746 tional \mathcal{F} to the union of two objects K_1 and K_2 equals
747 the value of the functionals over those two objects
748 minus parts counted twice. And the third condition is
749 continuity. Consider a sequence of objects $\{K_n\}$ that
750 approaches the object K as n tends to infinity. An
751 example of this is the sequence of r -parallel bodies of
752 an object K ; it is clear that the sequence of r -parallel
753 bodies $\{K_n\}$ with $r = 1/n$, approaches K as n goes to
754 infinity or, equivalently, as r goes to zero. Then, the
755 continuity condition is fulfilled if $\mathcal{F}(K_n)$ tends to
756 $\mathcal{F}(K)$ as n goes to infinity. Under these conditions
757 there are $d + 1$ numbers c_i such that
758

$$\mathcal{F}(K) = \sum_{i=0}^d c_i W_i^{(d)}(K) \quad (13)$$

760 where $W_i^{(d)}(K)$ are the Minkowski functionals that
761 assign to any object a number and K belongs to the d -
762 dimensional linear space.

763 Appendix 2

764 When the boundary surface of a three-dimensional
765 object is smooth, the third functional, the surface integral
766 of the mean curvature, $M(K)$, may be interpreted as the
767 mean breadth of the object (OSHER and MÜCKLICH,
768 2000). This functional might also be an indicator of the
769 surface boundary shape. Points on the boundary sur-
770 face of an object with positive curvatures settle on
771 convex parts (protrusions) while points with negative
772 curvatures belong to concave parts (hollows). Hence,
773 the mean curvature of convex points will be positive
774 while it will be negative for concave points. Taking
775 into account that the surface integral of the mean cur-
776 vature over a certain boundary region of K may be
777 interpreted as the average of the mean curvature over
778 this surface region, the third functional, $M(K)$, should

779 be positive for convex parts of the boundary surface
780 while it should be negative for concave parts.

781 When the object of interest K corresponds to the
782 pore space P , the Euler-Poincaré characteristic $\chi(P)$
783 is an index of the topology of the pore phase and it
784 quantifies pore connectivity (VOGEL and KRETZSCH-
785 MAR, 1996). In the plane, Euler-Poincaré can be
786 computed subtracting the number of holes of the
787 object, $H(K)$, from the number of connected com-
788 ponents, $CC(K)$ (MECKE, 1998):

$$\chi(K) = CC(K) - H(K) \quad (14)$$

790 In this context, a connected component of an object
791 is any part of it whose points are connected to one
792 another by curves of points contained in the object.
793 Then, a disk has Euler-Poincaré characteristic equal to 1
794 because it has one connected component and no holes. A
795 punctured disk has Euler-Poincaré number equal to 0, a
796 disk punctured twice, -1 , and so on. If the object is just
797 the union of n separated grains on an image, the Euler-
798 Poincaré characteristic equals n . This object has n
799 connected components. Similar definitions and rela-
800 tions hold in space though distinction between two
801 kinds of holes must be made. In space, the Euler-
802 Poincaré characteristic can be computed as the sum of
803 the number of connected components, $CC(K)$, and the
804 number of cavities of the object, $C(K)$, subtracted by
805 the number of tunnels, $T(K)$ (MECKE, 1998):

$$\chi(K) = CC(K) - T(K) + C(K) \quad (15)$$

806 Cavities are holes completely surrounded by the
807 object, while tunnels are handles or redundant loops as
808 torus-like holes through the object connected with the
809 exterior or background. If the object is just a separate
810 union of n grains of an image, the Euler-Poincaré
811 characteristic equals n . Then, a solid ball has Euler-
812 Poincaré characteristic equal to 1, a ball with a cavity
813 in it, 2, a ball with two cavities, 3, and so on. But, if
814 the ball has a tunnel that goes through it, the Euler-
815 Poincaré characteristic is 0, two tunnels gives a
816 Euler-Poincaré characteristic equal to -1 , and so on.

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