

Experimental comparison of FBARs and SMRs responsivities to mass loadings

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Abstract —The utilisation of thin film technology to develop film bulk acoustic resonators (FBARs) and solidly mounted resonators (SMRs), offers great potential to outperform the sensitivity and minimum detection limit of gravimetric sensors. Up to now, the choice between FBARs and SMRs depends primarily on the users' ability to design and fabricate Bragg reflectors and/or membranes, because neither of these two types of resonators has been demonstrated to be superior to the other. In the work reported here, it is shown that identically designed FBARs and SMRs resonating at the same frequency exhibit different responsivities, R_m , to mass loadings, being the FBARs more responsive than the SMRs. For the specific device design and resonant frequency (~2 GHz) of the resonators presented, FBARs' mass responsivity is ~20% greater than that of SMRs, and although this value should not be taken as universal for all possible device designs, it clearly indicates that FBAR devices should be favoured over SMRs in gravimetric sensing applications.

I. INTRODUCTION

Bulk acoustic wave (BAW) resonators, such as the quartz crystal microbalance (QCM), are nowadays routinely used in gravimetric sensing applications [1-3]. Historically, the emergence of the quartz crystal as a microbalance can be traced back to Sauerbrey [4], who realised that a resonating quartz crystal could be used for the microgravimetric measurement of sputtered thin films. The addition of a mass on the resonator surface lowers the frequency of resonance, f_r , due to the increase of the thickness of the resonance cavity and to a variation of the energy confinement due to acoustic impedance mismatch. Hence a variation of the mass bound on the resonators' surface, for example due the adsorption of biological samples, can be detected by tracking changes in f_r , being the total mass bound on the resonator proportional to the change in f_r . The mass responsivity of the sensor, R_m , is defined as the change

in frequency response (Δf_r) per unit mass change (Δm), as follows:

$$R_m = \frac{\Delta f_r}{\Delta m} \quad (1)$$

If the mass bound on the BAW resonator is small (lower than ~2% of the total mass of the resonator), there is an approximately quadratic relationship between the fundamental resonant frequency and the mass loading responsivity [4-6], meaning higher frequency devices will generate exponentially more absolute frequency shift for a given mass load, allowing ever decreasing mass loads to be effectively monitored. QCMs have a mass detection limit of a few nanograms, which is limited by their low operation frequency (5–20 MHz) due to the quartz substrate thickness [7,8]. In this respect, the utilisation of thin film technology to develop film bulk acoustic resonators (FBARs) and solidly mounted resonators (SMRs), extremely high frequency QCMs with an operating frequency in the GHz range, offers great potential to outperform the sensitivity and minimum detection limit of existing QCM-based gravimetric sensors.

The fundamental difference between FBARs and SMRs is the way by which the acoustic energy is trapped within the piezoelectric thin film [9,10]. If the piezoelectric film is deposited directly on a substrate, the acoustic wave is mostly transmitted into it due to the similar acoustic impedance between both materials. For the FBAR configuration, the air/piezoelectric interface on both facets of the resonator ensures energy trapping of the acoustic wave regardless of the resonance frequency. In the SMRs, Bragg reflectors consisting of alternating layers of high/low acoustic impedance materials underneath the resonator, effectively trap the acoustic wave. In the last few years, there has been much discussion about which one of these two resonators is the superior one: FBARs are generally regarded as easier to fabricate, and acoustic wave

trapping occurs at all frequencies thereby allowing maximum design flexibility [9,11]. Furthermore the cavity which is etched on the substrate to release the membrane can be utilised to develop a micro fluidic channel system under the resonator, hence enabling integrated lab-on-a-chip biosensors to be developed [12-14]. However the membrane is fragile and prone to break in harsh environments. SMRs are significantly more robust than FBARs; however Bragg reflectors must be pre-designed to reflect the desired frequencies, and must be precisely fabricated or else will degrade the effective coupling coefficient as well as creating additional loss mechanisms thus decreasing their quality factor, Q [15,16].

Since there is not an obvious better technology, up to now the choice between FBARs and SMRs depends primarily on the application and the environment that the resonator will be utilised in, but mostly on the users' ability to design and fabricate Bragg reflectors and/or membranes. In the work reported here, it will be shown that FBARs possess greater responsivity to mass loadings than SMRs and hence this type of BAW resonator is preferred for gravimetric sensing applications.

II. EXPERIMENTAL

Both the FBAR and SMR devices presented here consist of a reactively sputtered thin film of ZnO ($\sim 1.2 \mu\text{m}$) sandwiched between metallic electrodes.

The FBARs fabrication process commenced with patterning and sputtering a thin layer ($\sim 100 \text{ nm}$) of Al_2O_3 on the bottom of a double-side polished (100)-oriented Si substrate. This layer acts as a hard mask on a forthcoming deep reactive ion etching (DRIE) process and defines the dimensions of the membrane. A second Al_2O_3 layer (100 nm), that doubles as a support for the ZnO membrane and an etch barrier for the forthcoming DRIE process, was reactively sputtered on the top of the substrate. The SMRs fabrication process commenced with growing seven alternating low and high acoustic impedance layers of porous SiO_2 (669 nm) and Mo (786 nm) on a Si (100) substrate, to form an acoustic mirror centred at $\sim 2 \text{ GHz}$ and with $\sim 1 \text{ GHz}$ bandwidth. For both the FBARs and SMRs, the bottom electrodes ($4/50 \text{ nm Cr/Au}$) were patterned through a standard photolithography process and thermally evaporated on the top Al_2O_3 layer (for the FBARs) or the top SiO_2 layer (for the SMRs). The ZnO piezoelectric films were then reactively sputtered from a 4-in diameter metallic Zn target in a high target utilization sputtering (HiTUS) system [17]. The ZnO films were sputtered with a 10:7 Ar: O_2 admixture at a total pressure of $\sim 3 \times 10^{-3} \text{ mbar}$, and at room temperature. These conditions provided deposition rates of $\sim 50 \text{ nm}\cdot\text{min}^{-1}$. Further information on the sputtering conditions and characterisation of the resulting ZnO films is reported elsewhere [18-20].

X-ray diffractometry (XRD) using $\text{CuK}\alpha$ radiation was used to assess the crystal quality of the sputtered ZnO films. The θ - 2θ scan of the films over a broad angle range ($2\theta = 30^\circ$ - 80°) confirmed the preferential

orientation of the films along the (0001) direction (c -axis). θ - 2θ scans are shown in Fig. 1(a) where only the peaks corresponding to the (0002) and (0004) ZnO planes, together with those of the (004) Si planes and (110) Mo planes (for the films grown on the reflector only) are observed. The identification of the peaks is based on their tabulated values [21].

Fig. 1(b) presents the rocking curves of the most intense reflection from ZnO, i.e., the (0002) peak at $\theta = 17.1^\circ$. The peaks have a full width at half maximum (FWHM) of 5.7° and 9.1° for the films deposited on Al_2O_3 and Bragg reflector respectively, indicating the smaller angular dispersion of the crystallites around the c -axis of the films utilised to fabricate the FBARs. Nevertheless both FWHM values ensure sufficient piezoelectricity for good resonators' performance.

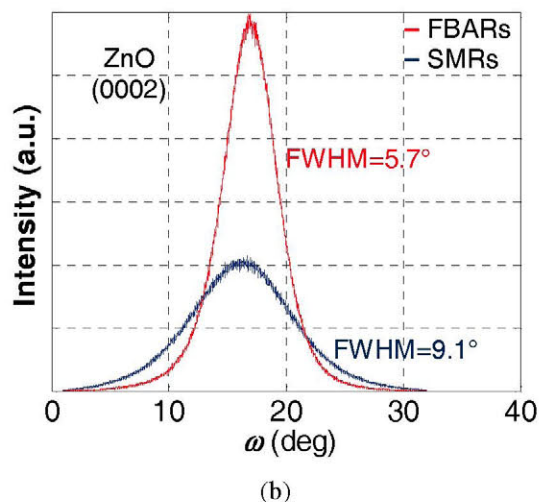
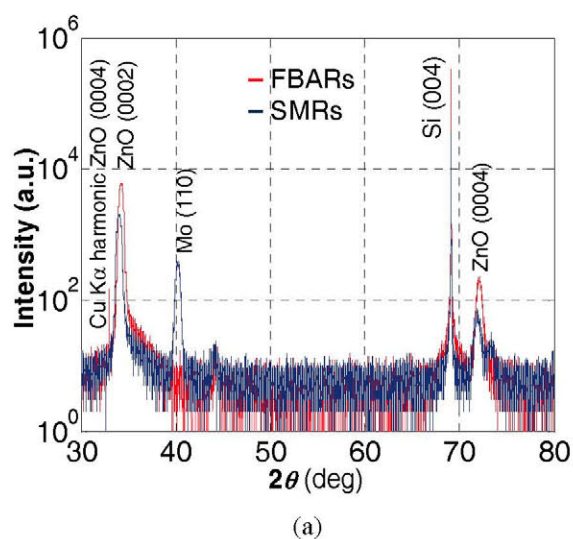


FIG. 1. (a) X-ray diffractograms in a θ - 2θ configuration of the ZnO films deposited on Al_2O_3 for FBAR fabrication (red line) and on Bragg reflector for SMR fabrication (blue line). (b) Rocking curves of the ZnO (0002) peaks.

After ZnO deposition, the top electrode was patterned with a lift-off photolithography process with

identical materials and thicknesses to the bottom electrode. Via etch holes were then formed through the ZnO for electrical connection to the bottom electrode by wet etching the ZnO in a 2% glacial acetic and phosphoric acids solution at room temperature. Finally the Si from the back of the wafer was removed on the FBAR devices with a DRIE process to release the ZnO/Al₂O₃ membrane, and the Al₂O₃ layer under the ZnO was removed by wet etching in potassium hydroxide at room temperature. Fig. 2 shows a top view of the devices fabricated. The resonant area is where the top and bottom electrodes overlap.

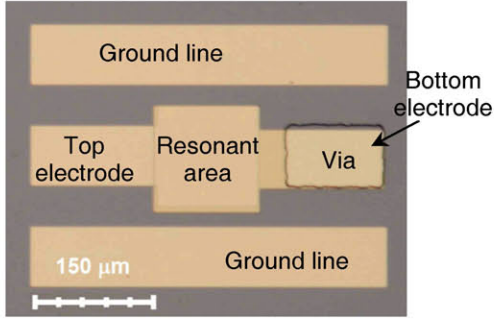


FIG. 2. Top view of the devices fabricated.

III. RESULTS AND DISCUSSION

A. Resonators' design and electrical characterisation

The transmission characteristics of the devices were measured with a coplanar probe station (on a GSG configuration) connected to a network analyser. Both types of devices were found to resonate at ~1.94 GHz, which lies well within the optimum range of the reflector's performance.

The quality factors (Q) at the parallel resonant frequency were extracted from the S-parameter spectrum using the IEEE standard definition [22]:

$$Q = \frac{1}{2} f_{a-r} \frac{\partial \varphi}{\partial f} \quad (2)$$

where φ represents the admittance phase and f_{a-r} represents the anti-resonance frequency. Q was found to be ~1380 and ~840 for the FBARs and SMRs respectively. The lower value of Q exhibited by the SMRs is explained in part by the slightly worse ZnO crystallographic orientation (as indicated by the wider XRD rocking curve).

B. Comparison of the mass sensitivities of FBARs and SMRs

When an additional mass is added onto a resonator's surface, a negative frequency shift will be observed on its frequency response. This has been verified experimentally by sputtering thin aluminium layers of different thicknesses on top of the resonators. In order to calculate precisely the frequency shifts due to different mass loadings, an automated measurement routine was written with LabVIEW® to continuously

monitor and record the resonance spectrum of the resonators. Firstly the resonant frequency of unloaded devices was verified to be stable (to ± 2 kHz) by tracking their response over a period of ~15 min. Then layers of Al of different thicknesses were evaporated on top of identical devices and the exact mass load being added was calculated from the additional layer thickness, lateral dimensions of the resonant area and the aluminium's mass density. The resonators were then re-measured and their resonant frequency was again tracked over several minutes to verify stability. Δf_r was calculated by comparison of f_r s of loaded and unloaded resonators.

The environmental temperature, which is known to affect the frequency response of the devices [23-25], was controlled by placing the resonators, wire bonded to 50Ω transmission line PCBs, into a solid brass environmental isolation assembly with a high thermal mass. This assembly was placed onto the metallic output pads of a HAAKE K20 water bath, which pumped a thermal fluid at fixed rate and controllable temperature. This was able to control the temperature of the resonators within less than $\pm 0.5^\circ\text{C}$ of the set temperature as measured by an automated thermocouple (National Instruments TC 01) with a resolution of 0.1°C and a response time of less than 1 second. All measurements were carried out at a constant temperature of 22°C .

The f_r of the two types of resonators decreases linearly due to mass loads within the range studied. The Δf_r observed for different loads is shown in Fig. 3 together with finite element analysis (FEA) predictions, where it was assumed that the additional mass added was evenly distributed on the resonators' surface.

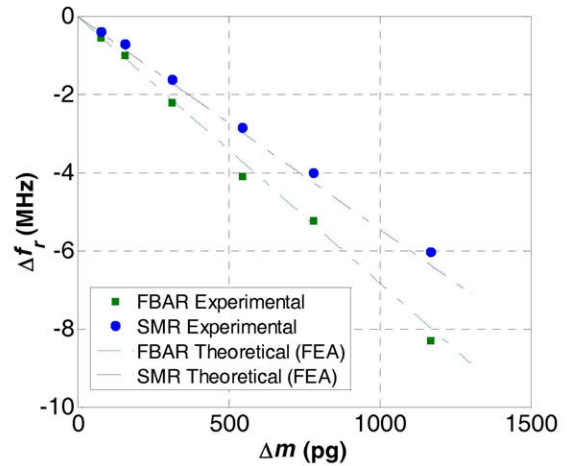


FIG. 3. Experimentally observed variation of the frequency of resonance, Δf_r , at room temperature (22°C) when different mass loads are deposited on the FBARs and SMRs surface. The dashed lines represent theoretical (FEA) calculations.

It can be seen that the FBARs exhibit a greater responsivity, $R_m \approx 6.9 \text{ kHz}\cdot\text{pg}^{-1}$, than the SMRs, $R_m \approx 5.1 \text{ kHz}\cdot\text{pg}^{-1}$. It is worthwhile noting that the precise values of responsivity depend in part on the

resonators' size and design, and therefore these specific values can not be taken as an universal FBAR nor SMR response to mass loadings. However this result is very significant in that identically designed FBARs and SMRs resonating at the same frequency exhibit different frequency shifts for identical mass loads being the FBARs more responsive than the SMRs.

IV. CONCLUSIONS

Evaluation of the mass responsivity of FBARs and SMRs has been carried out. Identical sets of FBARs and SMRs were fabricated with their fundamental resonant mode at ~ 2 GHz. In order to calculate the responsivity of both types of devices, thin aluminium layers of different thicknesses were evaporated on top of the FBARs and SMRs. The exact mass load being added, Δm , was precisely calculated from the additional layer thickness, lateral dimensions of the resonant area and the aluminium's mass density. The f_r of the two types of resonators decreases linearly due to mass loads within the range studied, but it was found that FBARs exhibit a greater responsivity, $R_m \approx 6.9 \text{ kHz} \cdot \text{pg}^{-1}$, than the SMRs, $R_m \approx 5.1 \text{ kHz} \cdot \text{pg}^{-1}$. However these specific values of responsivity depend on the resonators' design and frequency of resonance, and therefore should not be taken as universal FBAR nor SMR responses to mass loadings.

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