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**NORSAR**

Exploring the Earth

# The SELENA–RIS<sub>e</sub> Open Risk Package

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*INTERNATIONAL CONFERENCE ON OPEN RISK ANALYSIS  
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# Terminology SELENA – *RIS<sub>e</sub>*

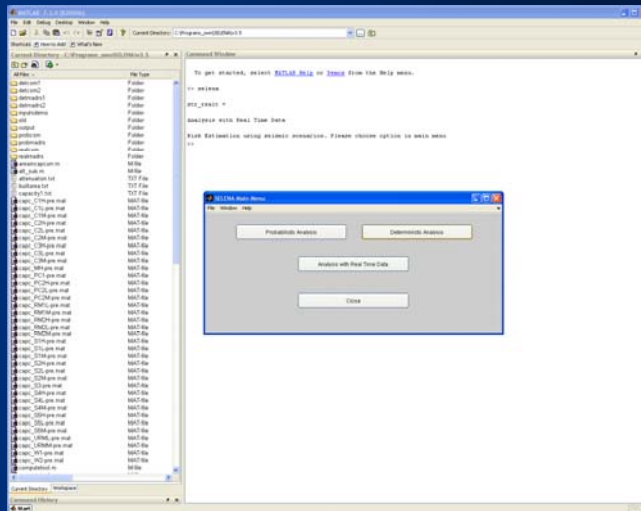


SELENA:

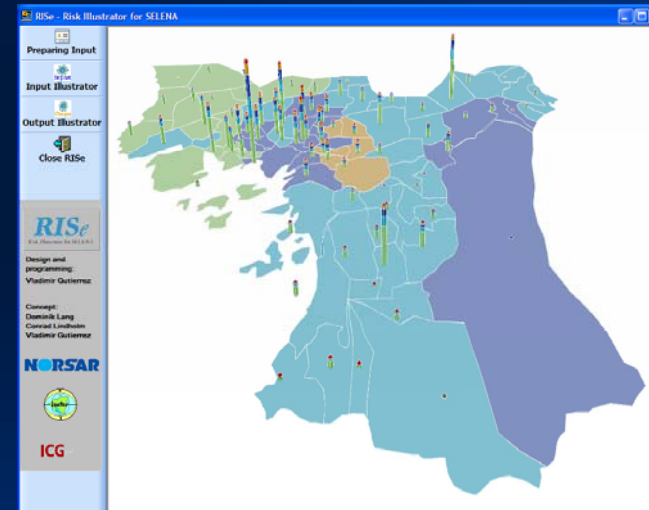
*"Seismic Loss Estimation  
using a Logic Tree Approach"*

*RIS<sub>e</sub>:*

*"Risk Illustrator for SELENA"*



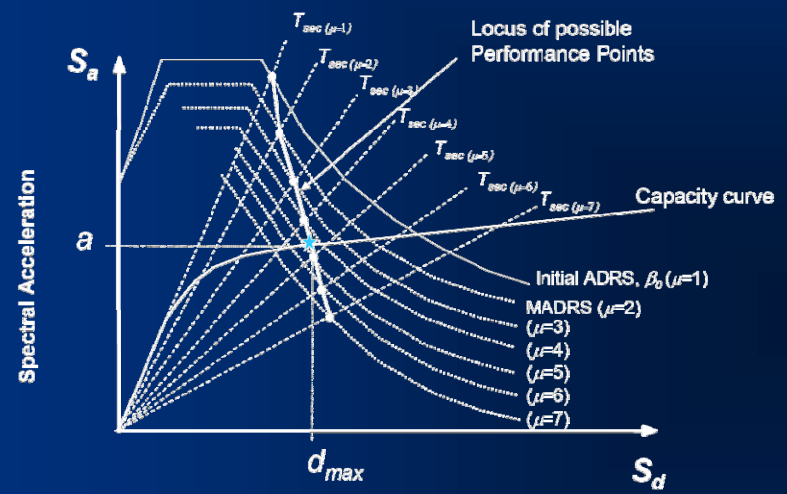
Damage and loss computation software



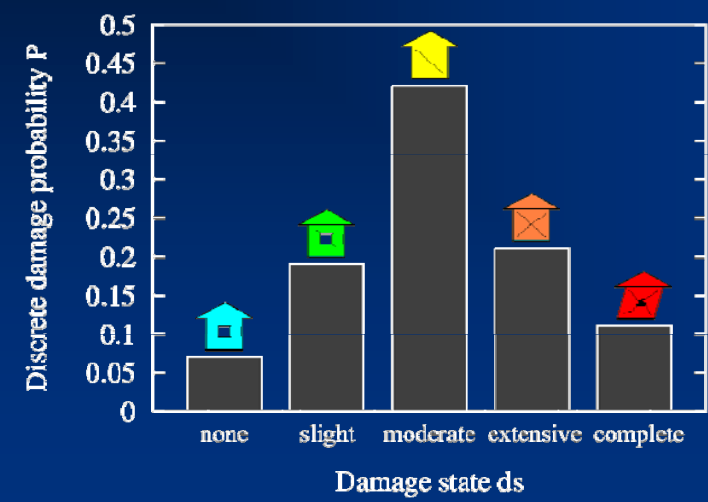
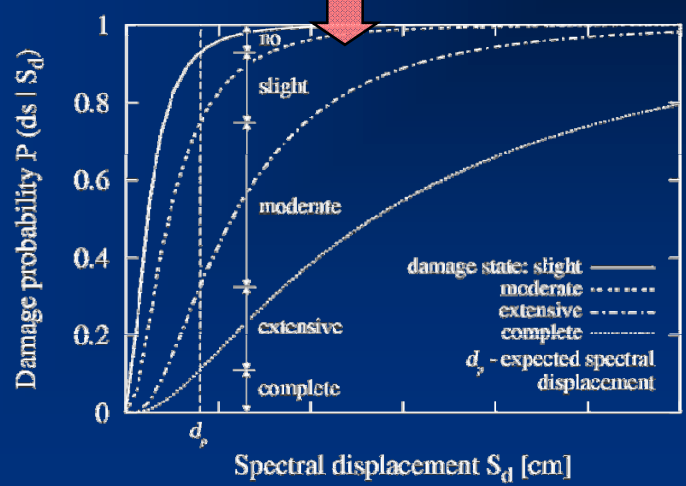
Google Earth interface  
(KML file converter)

# SELENA – Basic features (1)

- ⇒ analytical (*engineering*) approach using capacity spectrum method (CSM)
  - iterative procedure A of ATC-40 (1996)
  - procedure C of MADRS (FEMA-440, 2005)



⇒ classification of physical damage following '*HAZUS damage states*' (FEMA, 2003)





# SELENA – Basic features (2)

⇒ ground motion values (PGA,  $S_d$ ) can be provided on three different ways:

- (1) deterministic scenario
- (2) grided data (e.g. given by probabilistic shake maps)
- (3) randomly distributed data (e.g. coming from recording stations)

⇒ seismic demand in the  $S_a-S_d$  domain is represented by a code design spectrum

- currently incorporated: IBC-2006  
Eurocode 8 – Type 1 & 2 (CEN, 2002)  
Indian code IS 1893 (Part 1): 2002 (BIS, 2002)

→ respective soil classification schemes considered:

Soil type	Shear wave velocity $v_{s,30}$	IBC-2006 (NEHRP)	Eurocode 8	IS 1893 (Part 1): 2002
hard rock	$> 1500 \text{ m/s}$	A	A	I
rock	$760 - 1500 \text{ m/s}$	B		
stiff soil	$360 - 760 \text{ m/s}$	C		
soft soil	$180 - 360 \text{ m/s}$	D	C	II
very soft soil	$< 180 \text{ m/s}$	E	D	III

# SELENA – Basic features (2)

⇒ ground motion values (PGA,  $S_d$ ) can be provided on three different ways:

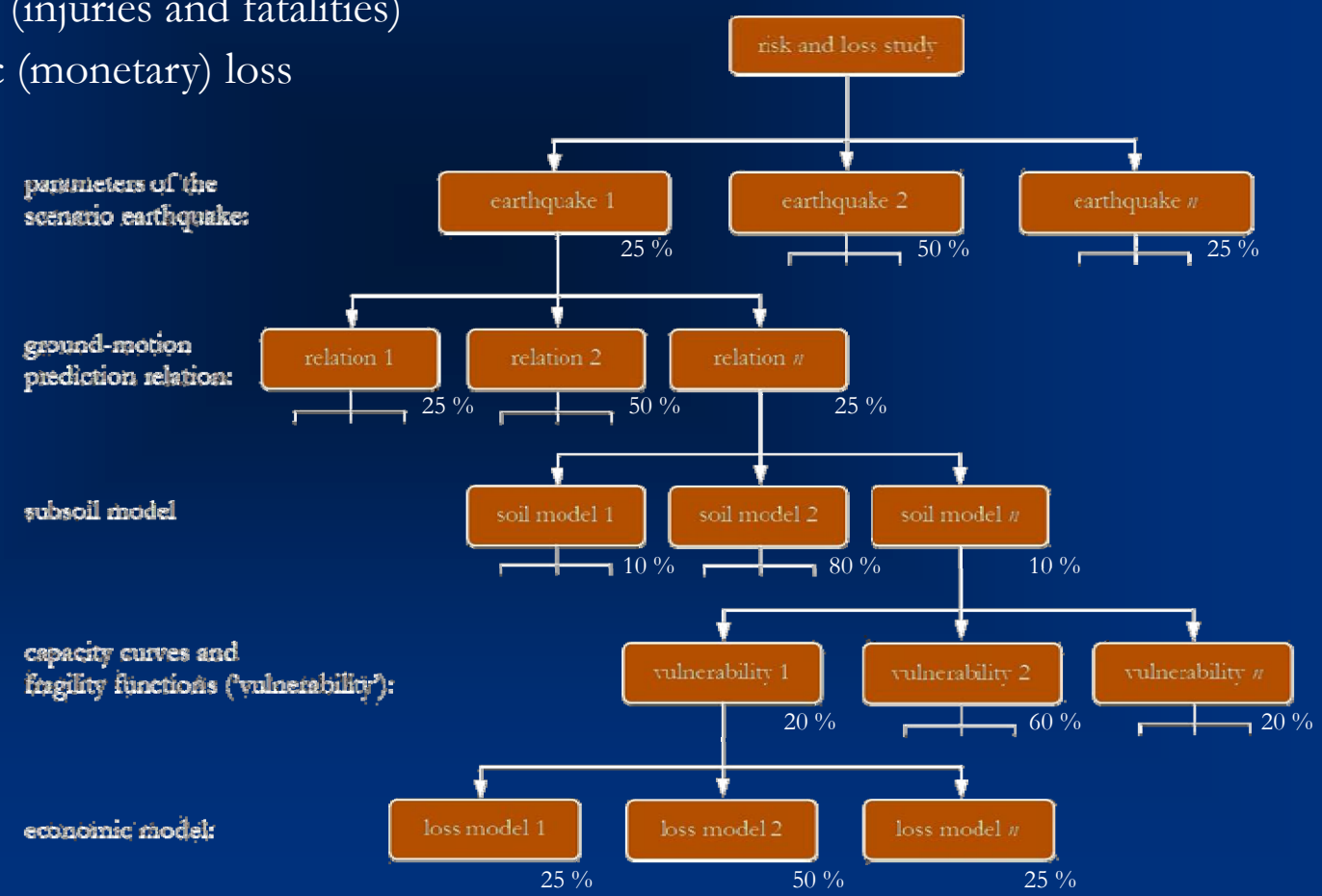
- (1) deterministic scenario
- (2) grided data (e.g. given by probabilistic shake maps)
- (3) randomly distributed data (e.g. coming from recording stations)

*program sequence of a deterministic analysis:*



# SELENA – Basic features (3)

- ⇒ weighted logic tree computation scheme → weighted results will provide expected mean values and confidence levels (percentiles)
  - ground motion with and w/o soil amplification factors
  - damage probabilities and damage extent (no. of buildings or building floor area)
  - casualties (injuries and fatalities)
  - economic (monetary) loss



# Connection SELENA – *RIS<sub>e</sub>*

- ⇒ currently *RIS<sub>e</sub>* is solely customized to the SELENA file structure
- ⇒ *RIS<sub>e</sub>* serves as an intermediary between SELENA and Google Earth

**INVENTORY DATABASE**

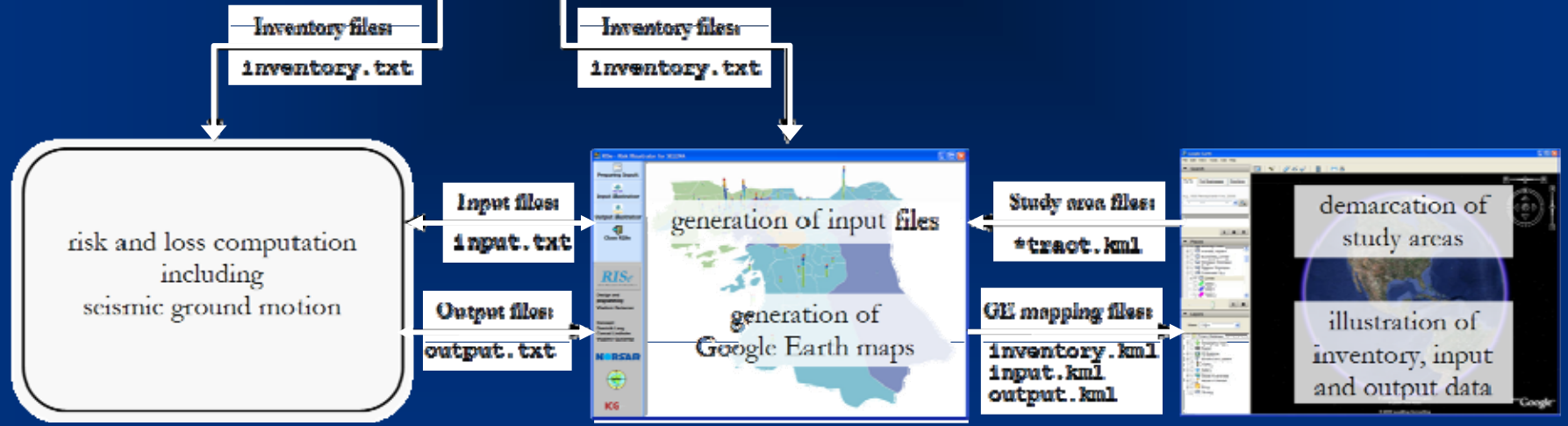
ocup1mbt1.txt

numbuild.txt

builtarea.txt

% geomnt	mbt1	mbt2	mbt3	mbt4	mbt5
90001	129	56	1200	139	80
90002	100	189	1101	200	110
90003	—	—	—	—	—
90004	—	—	—	—	—

⇒ both input and output files are required/given in plain ASCII text format



# RIS<sub>e</sub> – Illustrating input and inventory



⇒ all geo-referenced input files can be converted into GE maps

⇒ different illustration types are incorporated (color-shaded, bar chart plots, etc.)

Input file (.txt)	Mapping file (.kml)	Description
earthquake.txt	earthquake.kml	1 placemark for each defined earthquake epicenter (only deterministic analysis)
INVENTORY INFORMATION:		
numbuild.txt	numbuild.kml	1 color-shaded map for each model building type
builtarea.txt	builtarea.kml	1 color-shaded map for each model building type
population.txt	population.kml	1 absolute bar chart map
ocupmbt/ <i>l</i> .txt	ocupmbt/ <i>l</i> .kml	1 color-shaded map for each occupancy type and model building type <i>l</i>
occupancy.txt	occupancy.txt	1 normalized bar chart map illustrating the distribution of building floor area to the main occupancy types RES, COM, IND, REL, GOV and EDU irrespective of model building type
SOIL INFORMATION:		
soilcenter/ <i>k</i> .txt	soilcenter/ <i>k</i> .kml	1 color-shaded map for each soil model <i>k</i>
GROUND MOTION INFORMATION:		
shakecenter/ <i>i</i> .txt	shakecenter/ <i>i</i> .kml	3 color-shaded maps for each shakemap <i>i</i> separate for PGA, $S_a(0.3 s)$ & $S_a(1.0 s)$



# RIS<sub>e</sub> – Illustrating input and inventory



⇒ all geo-referenced input files can be converted into GE maps

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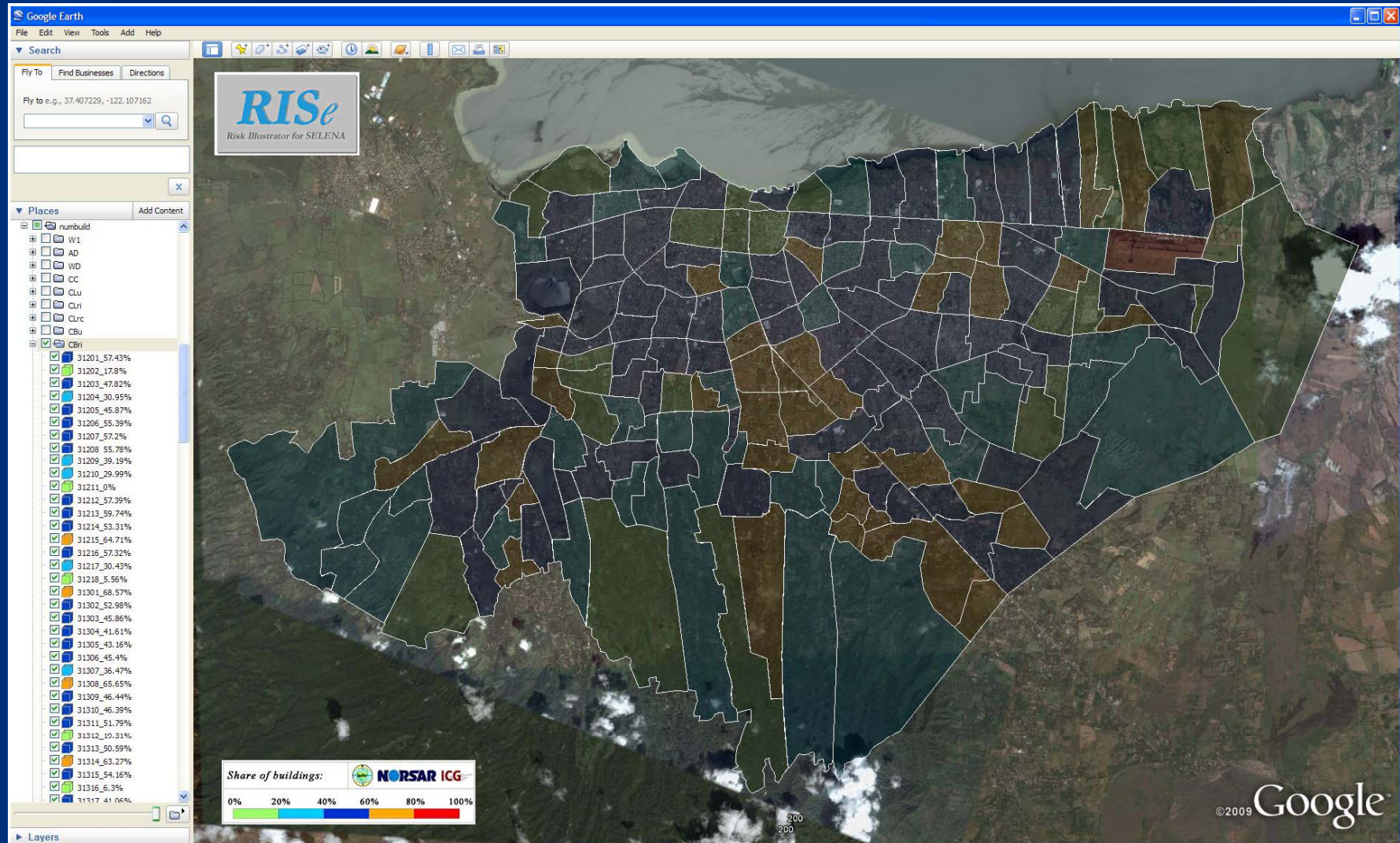
Input file (.txt)	Mapping file (.kml)	Description
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INVENTORY INFORMATION:		
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builtarea.txt	builtarea.kml	1 color-shaded map for each model building type
population.txt	population.kml	1 absolute bar chart map
ocupmbt/ <i>l</i> .txt	ocupmbt/ <i>l</i> .kml	1 color-shaded map for each occupancy type and model building type <i>l</i>
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GROUND MOTION INFORMATION:		
shakecenter/ <i>i</i> .txt	shakecenter/ <i>i</i> .kml	3 color-shaded maps for each shakemap <i>i</i> separate for PGA, $S_a(0.3 s)$ & $S_a(1.0 s)$

# RISe – Illustrating input and inventory



⇒ number of buildings disaggregated by MBT

(→ [numbuild.kml](#))



# RIS<sub>e</sub> – Illustrating input and inventory



- ⇒ all geo-referenced input files can be converted into GE maps
- ⇒ different illustration types are incorporated (color-shaded, bar chart plots, etc.)

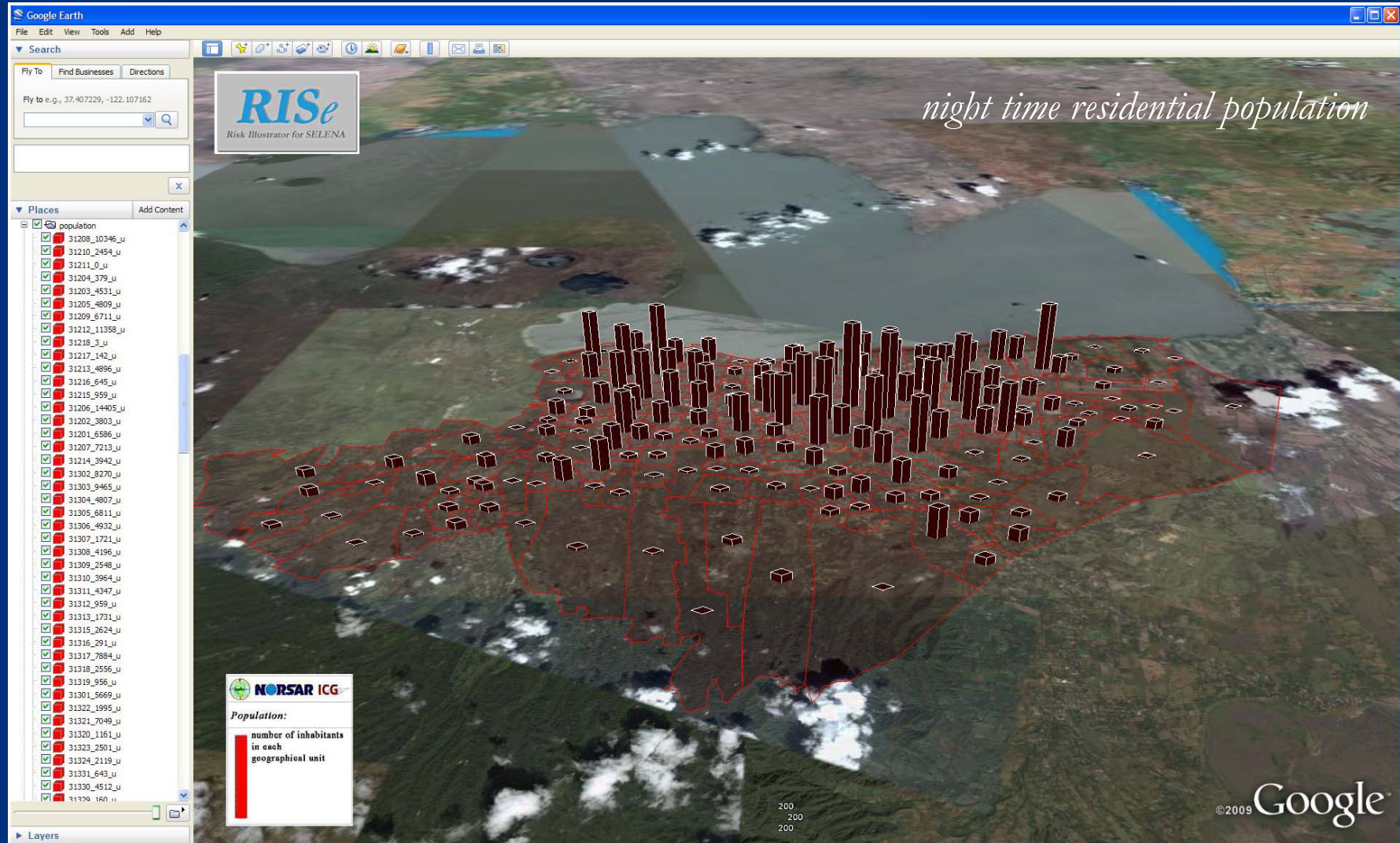
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builtarea.txt	builtarea.kml	1 color-shaded map for each model building type
population.txt	<b>population.kml</b>	<b>1 absolute bar chart map</b>
ocupmbt/ <i>l</i> .txt	ocupmbt/ <i>l</i> .kml	1 color-shaded map for each occupancy type and model building type <i>l</i>
occupancy.txt	occupancy.txt	1 normalized bar chart map illustrating the distribution of building floor area to the main occupancy types RES, COM, IND, REL, GOV and EDU irrespective of model building type
SOIL INFORMATION:		
soilcenter $k$ .txt	soilcenter $k$ .kml	1 color-shaded map for each soil model $k$
GROUND MOTION INFORMATION:		
shakecenter $i$ .txt	shakecenter $i$ .kml	3 color-shaded maps for each shakemap $i$ separate for PGA, $S_a(0.3 s)$ & $S_a(1.0 s)$

# RIS<sub>e</sub> – Illustrating input and inventory



⇒ number of population in each geounit

(→ population.kml)



# RIS<sub>e</sub> – Illustrating input and inventory



⇒ all geo-referenced input files can be converted into GE maps

⇒ different illustration types are incorporated (color-shaded, bar chart plots, etc.)

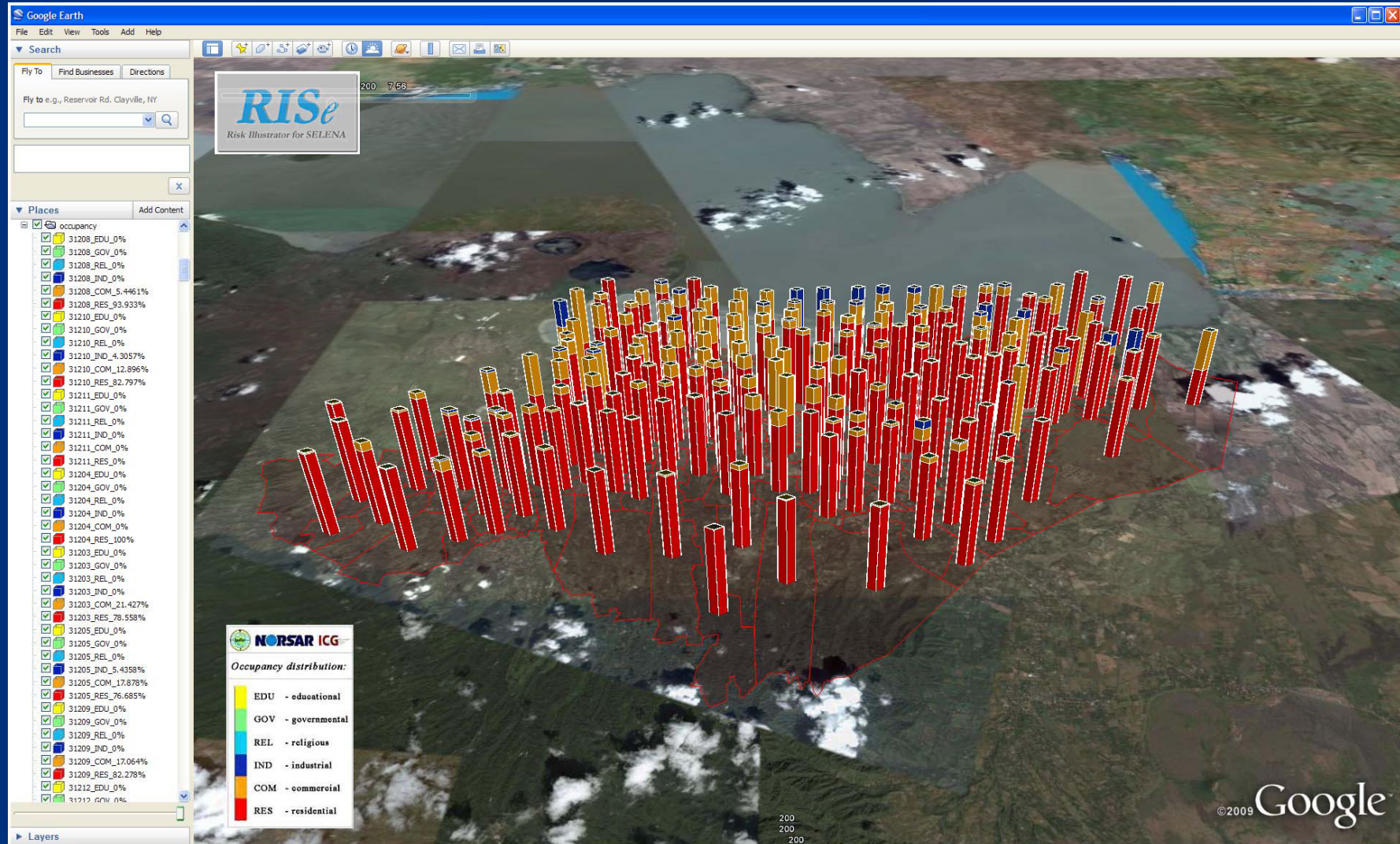
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earthquake.txt	earthquake.kml	1 placemark for each defined earthquake epicenter (only deterministic analysis)
INVENTORY INFORMATION:		
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ocupmbt/ <i>l</i> .txt	ocupmbt/ <i>l</i> .kml	1 color-shaded map for each occupancy type and model building type <i>l</i>
<b>occupancy.txt</b>	<b>occupancy.txt</b>	<b>1 normalized bar chart map illustrating the distribution of building floor area to the main occupancy types RES, COM, IND, REL, GOV and EDU irrespective of model building type</b>
SOIL INFORMATION:		
soilcenter $k$ .txt	soilcenter $k$ .kml	1 color-shaded map for each soil model $k$
GROUND MOTION INFORMATION:		
shakecenter $i$ .txt	shakecenter $i$ .kml	3 color-shaded maps for each shakemap $i$ separate for PGA, $S_a(0.3 s)$ & $S_a(1.0 s)$

# RIS<sub>e</sub> – Illustrating input and inventory



⇒ percental distribution of occupancy types in the geounits

(→ [occupancy.kml](#))



# RIS<sub>e</sub> – Illustrating output



Output file	Mapping file	Description
GROUND MOTION INFORMATION:		
gmotionsceni.txt	gmotionsceni.kml	6 color-shaded maps (separate for PGA, $S_a(0.3 s)$ & $S_a(1.0 s)$ on rock and soil conditions) for each logic tree branch $i$
DAMAGE INFORMATION:		
dout <i>i</i> .txt	dout <i>i</i> .kml	normalized bar chart maps separate for each model building type for each logic tree branch $i$
medianct.txt	medianct.kml	absolute bar chart maps separate for each model building type
16prctile.txt	16prctile.kml	absolute bar chart maps separate for each model building type
84prctile.txt	84prctile.kml	absolute bar chart maps separate for each model building type
LOSS INFORMATION:		
lossmedian.txt	loss.kml	absolute bar chart map (median $\pm 1\sigma$ )
loss16prctile.txt		
loss84prctile.txt		
hlbyinjurmean.txt	hlbyinjurs.kml	absolute bar chart maps (median $\pm 1\sigma$ ) for each injury severity level (1–4) and each daytime scenario (2 am, 10 am, 5 pm)
hlbyinjur16.txt		
hlbyinjur84.txt		
hlbyinjurmean.txt	totalinjurs.kml	absolute bar chart maps (median $\pm 1\sigma$ ) for cumulated casualty numbers separated for each daytime scenario (2 am, 10 am, 5 pm)
hlbyinjur16.txt		
hlbyinjur84.txt		

# RIS<sub>e</sub> – Illustrating output



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GROUND MOTION INFORMATION:		
gmotionsceni.txt	gmotionscen <i>i</i> .kml	6 color-shaded maps (separate for PGA, $S_a(0.3 s)$ & $S_a(1.0 s)$ on rock and soil conditions) for each logic tree branch <i>i</i>
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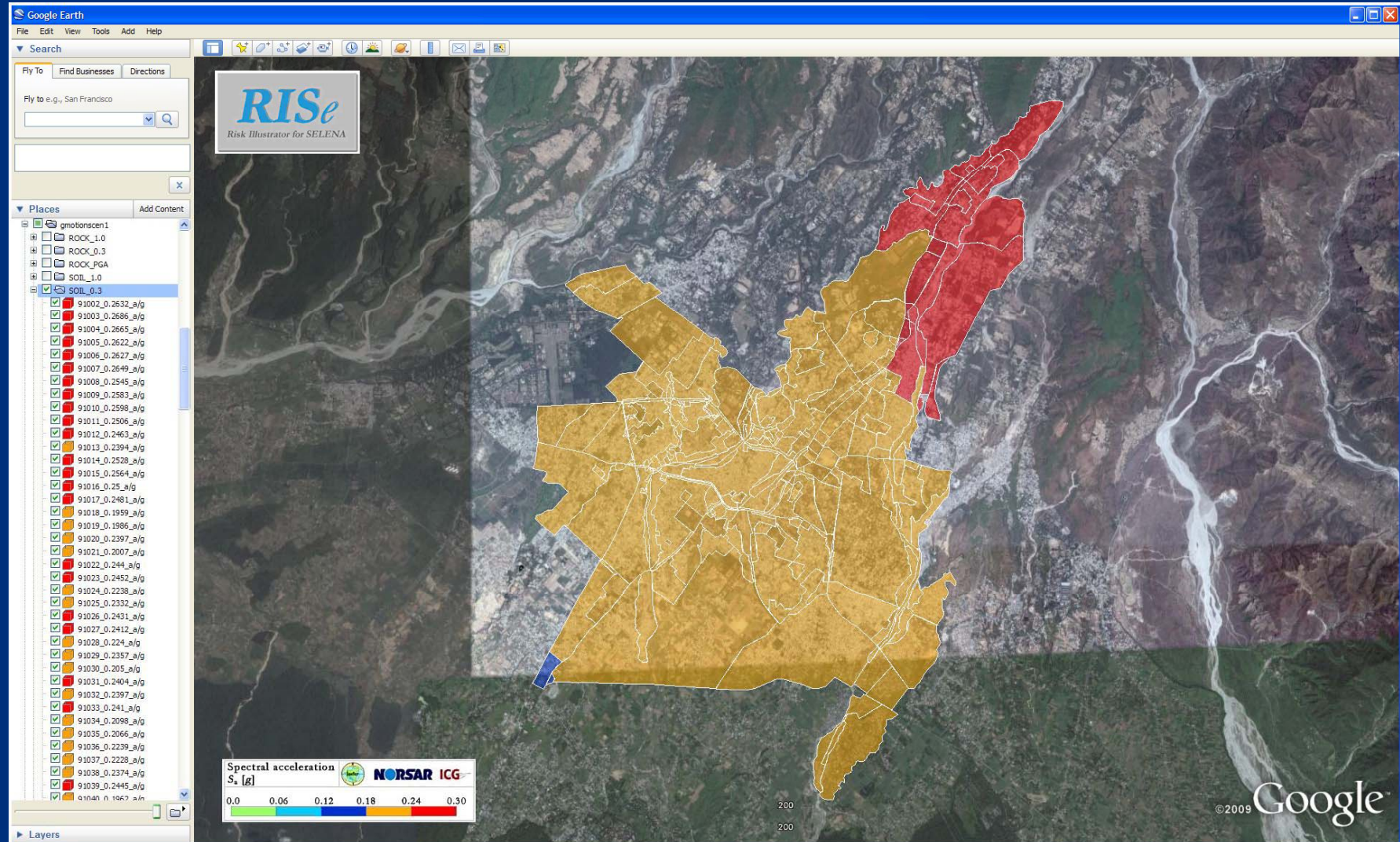


# RIS<sub>e</sub> – Illustrating output



⇒ spectral ground motion maps (deterministic scenario)

(→ [gmotionsceni.kml](#))



# RIS<sub>e</sub> – Illustrating output



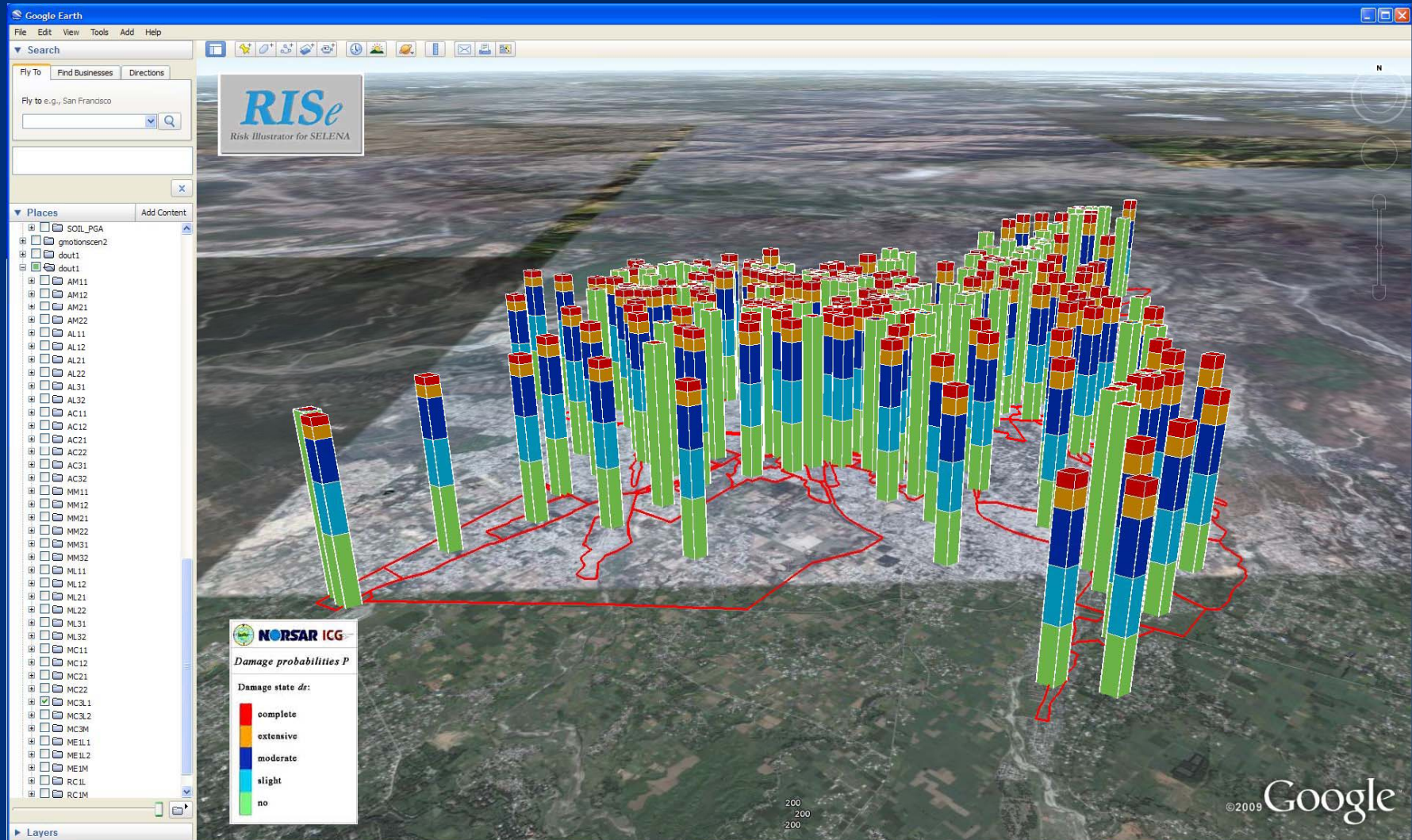
Output file	Mapping file	Description
GROUND MOTION INFORMATION:		
gmotionsceni.txt	gmotionsceni.kml	6 color-shaded maps (separate for PGA, $S_a(0.3 s)$ & $S_a(1.0 s)$ on rock and soil conditions) for each logic tree branch $i$
DAMAGE INFORMATION:		
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hlbyinjur16.txt		
hlbyinjur84.txt		

# RIS<sub>e</sub> – Illustrating output



⇒ damage probabilities separate for each building typology

(→ [doutz.kml](#))



# RIS<sub>e</sub> – Illustrating output

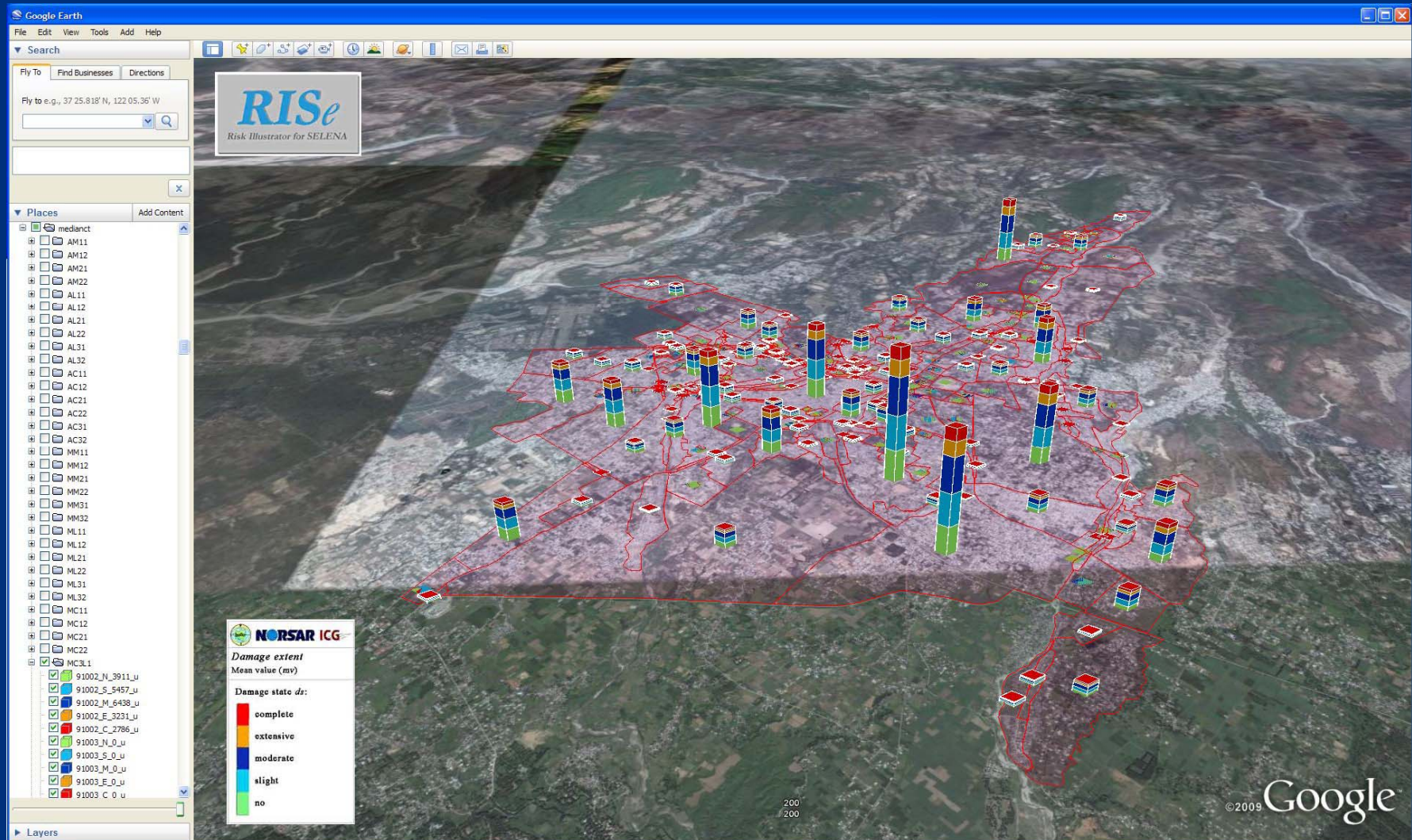


Output file	Mapping file	Description
GROUND MOTION INFORMATION:		
gmotionsceni.txt	gmotionsceni.kml	6 color-shaded maps (separate for PGA, $S_a(0.3 s)$ & $S_a(1.0 s)$ on rock and soil conditions) for each logic tree branch $i$
DAMAGE INFORMATION:		
douti.txt	douti.kml	normalized bar chart maps separate for each model building type for each logic tree branch $i$
<b>medianct.txt</b>	<b>medianct.kml</b>	<b>absolute bar chart maps separate for each model building type</b>
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hlbyinjur16.txt		
hlbyinjur84.txt		

# RIS<sub>e</sub> – Illustrating output



⇒ absolute damage extent separate for each building typology (→ [medianct.kml](#))



# RIS<sub>e</sub> – Illustrating output

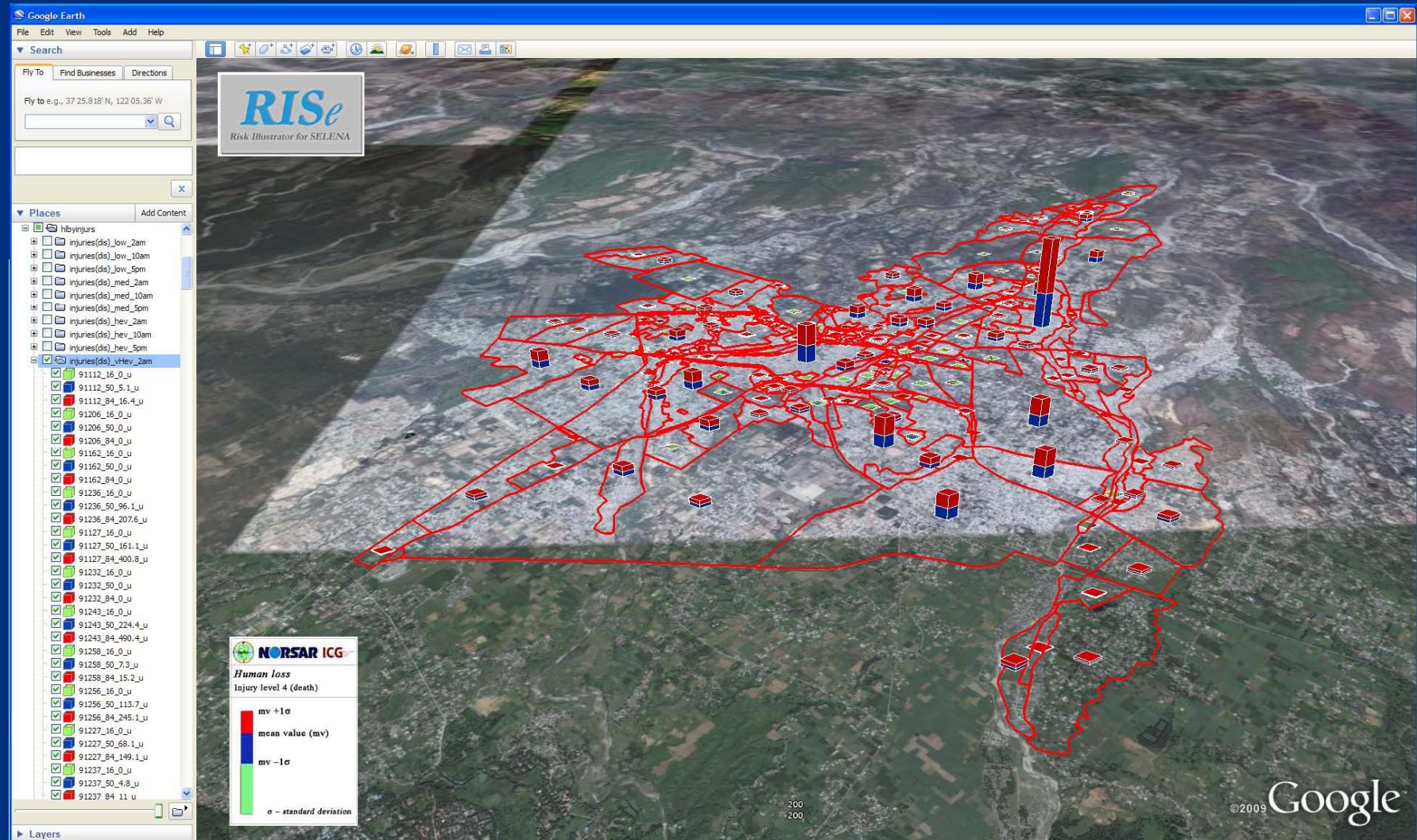


Output file	Mapping file	Description
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hlbyinjur16.txt		
hlbyinjur84.txt		

# RIS<sub>e</sub> – Illustrating output



⇒ casualties ( $mv \pm \sigma$ ) for 4 severity levels and 3 daytime scenarios (→ [hlbyinjurs.kml](http://hlbyinjurs.kml))



# "Openness" of SELENA



⇒ **Free:** distributed free of charge through the NORSAR/ICG website

⇒ **Open source:** open source code, different formats now available

(1) MATLAB code

(2) "C" code which can be compiled into

a) stand-alone binary independent of MATLAB & toolboxes

b) binary (mex/oct) functions which can be used from within the MATLAB/Octave environment

## Advantages:

- approximately 50 times faster than MATLAB code

- code can be run in the free (open source) MATLAB clone GNU Octave

⇒ **Open documentation:** open user manual in MS Word .doc and LATEX, all figure files in gnuplot .gpl format





# "Openness" of RISE

- ⇒ **Freeware:** distributed free of charge through the NORSAR/ICG website
- ⇒ **Open source:** open source code, coded in C#

## Advantages:

- coding can be done in the *Integrated Development Environment* (IDE) provided free of charge by Microsoft (MS Visual Studio C# Express Edition 2008)
- running the RISE software only requires an installation of
  - a) the free Microsoft .NET framework (at least version 2.0)
  - b) Google Earth's free version

⇒

- ⇒ **Open documentation:** open user manual currently only in MS Word .doc