Dynamics of nearly inviscid Faraday waves in almost circular containers

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Abstract

Parametrically driven surface gravity-capillary waves in an elliptically distorted circular cylinder are studied. In the nearly inviscid regime, the waves couple to a streaming flow driven in oscillatory viscous boundary layers. In a cylindrical container, the streaming flow couples to the spatial phase of the waves, but in a distorted cylinder, it couples to their amplitudes as well. This coupling may destabilize pure standing oscillations, and lead to complex time-dependent dynamics at onset. Among the new dynamical behavior that results are relaxation oscillations involving abrupt transitions between standing and quasiperiodic oscillations, and exhibiting 'canards'.

Keywords: Faraday oscillations; Forced symmetry breaking; Global bifurcations; Relaxation oscillations; Canards

1. Introduction

Surface gravity-capillary waves exhibit a wide variety of pattern-forming phenomena, depending both on the mode of excitation and on the size of the domain relative to the wavelength selected by the driving frequency. In large domains recent work has focused on two-frequency forcing [1], in which the two frequency components select distinct wavenumbers. These experiments, generally carried out in quite viscous liquids, have revealed various superlattice patterns, as well as nonperiodic states resembling quasipatterns [12,27,28,1]. In these experiments, the frequencies used are in (low order) resonance, so that the forcing acceleration remains periodic in time, with the

frequency ratio, their relative phase, and their relative contribution to the forcing providing parameters to be tuned in the experiment. Existing theory has been successful in explaining a number of the experimental observations [42,37,39], but for reasons explained below such theory is generally restricted to highly viscous liquids. This is because in nearly inviscid liquids the behavior is complicated by the presence of a mean flow, also known as a *streaming flow*, driven by time-averaged Reynolds stresses in oscillatory viscous boundary layers near rigid walls and the free surface [40,31,43]. These mean flows in turn interact with the waves that produce them, leading to a description of the Faraday system in terms of amplitude equations coupled to a Navier–Stokes-like equation for the mean flow with boundary conditions obtained by matching to the oscillatory boundary layers [43]. These equations represent a new class of pattern-forming dynamical systems.

The new terms in the amplitude equations are formally of cubic order, indicating that the effects of the mean flow cannot be neglected, even in the limit of vanishing viscosity. The resulting equations have thus far been studied only in the simplest cases: with single frequency forcing, periodic boundary conditions and one horizontal dimension. When the spatial period is comparable to the wavelength selected by the parametric forcing the coupled amplitude-mean flow equations simplify: all solutions are attracted to standing waves of constant amplitude, and the streaming flow only advects the spatial phase of these waves; this phase in turn appears in the boundary conditions for the streaming flow, giving rise to a pair of simpler coupled phase-mean flow equations. Analysis of these equations reveals that the coupling to the streaming flow is significant, and can lead to a number of new instabilities, which are absent if the streaming flow is neglected [33]. These include parity-breaking instabilities that lead to pattern drift, and oscillatory instabilities that produce oscillations in the spatial phase of the pattern. In larger domains amplitude inhomogeneities can develop and these also couple to the mean flow [30].

In the present paper we examine this type of dynamical system in three dimensions. The structure of the resulting equations in various small aspect ratio domains has recently been determined [22]. Of the domains considered a circular domain is of particular interest. If the domain is precisely circular the amplitude of the standing waves produced by the parametric driving decouples from the mean flow, and the streaming flow couples to the spatial phase of the pattern only, as in ref. [33]. However, as pointed out in [22], the situation changes dramatically when the shape of the container is perturbed. In the case of a slightly elliptical container two types of standing waves, oriented along the major and minor axes of the ellipse, come in in close succession as the amplitude of the parametric excitation increases, and these may interact already at small amplitude, producing mixed modes which are much more efficient at driving a streaming flow. In this case, the streaming flow couples to the two amplitudes, as well as to the spatial phase of the resulting pattern. This interaction with the streaming flow is responsible for a new class of dynamical behavior that now involves the amplitudes as well. In particular, we demonstrate in this paper that it can lead to relaxation oscillations of a particularly interesting type: oscillations that switch from single frequency standing waves to two-frequency waves and back. Under appropriate conditions these relaxation oscillations can exhibit the so-called 'canard' phenomenon in which the system follows nominally unstable solutions in the slow phase. Various global bifurcations are located as well, of which perhaps the most interesting is responsible for the appearance of chaotic dynamics right at threshold of the primary instability.

Our calculations are based on the assumption that the *effective* Reynolds number of the streaming flow, suitably defined, remains small. This assumption permits us to project the Navier–Stokes-like equation for the streaming flow onto the dominant spatial eigenfunction, replacing it by a single ordinary differential equation for the evolution of the amplitude of this eigenfunction. The coupling of this viscous mode to the amplitude of the competing standing waves is retained as a free parameter; the remaining nonlinear coefficient values are taken (mostly) from a paper by Miles [34] for an inviscid fluid in a circular cylinder of aspect ratio $R \approx 0.66$ with a free contact line.

The paper is organized as follows. In Section 2, we summarize the derivation of the coupled amplitude-streaming flow equations for this system, and the conditions for their validity. In Section 3, we discuss the basic properties of these equations, and identify four regions in parameter space where these equations are valid but new types of dynamical behavior may be expected. In Section 4, we explore numerically the behavior of the coupled amplitude-streaming flow equations in these regions and offer, in each case, a dynamical systems explanation of the observed

dynamics. The paper concludes with a discussion of the implication of our results, both for dynamical systems theory and for future experiments on the Faraday system.

2. Coupled amplitude-streaming flow equations

We consider nonaxisymmetric Faraday waves in a slightly elliptical container. The ellipticity breaks the O(2) symmetry of the container and picks out standing oscillations with nodes along either the major or the minor axis of the ellipse. A convenient way of understanding this selection is to formulate the problem first in a circular container, treating the ellipticity as a small perturbation, comparable to the small damping from the viscous boundary layers (and the flow in the bulk) and the small forcing amplitude required to overcome it. In the unforced case, the free oscillations of the fluid in such a container are most easily described in terms of clockwise and counterclockwise rotating waves, and we therefore use the amplitudes A_{\pm} of these waves to describe the dynamics of the system. In a circular container, the parametric forcing couples these waves, resulting in a reflection-symmetric standing oscillation with arbitrary orientation. Because of this symmetry only the phase of the standing wave couples to the streaming flow. However, as soon as the shape of the container is perturbed from circular both the phase and the amplitudes couple to the streaming flow. This coupling takes place via the difference in frequency between the oscillations along the two principal axes [22] and has a dramatic impact on the dynamics.

Since we are treating departures from circular symmetry as a perturbation we can use cylindrical coordinates (r, θ, z) , and consider a circular cyclinder of height *h* and radius *Rh*. In these coordinates, the coupled amplitude-streaming flow equations derived by Higuera et al. [22], suitably scaled, take the form

$$A'_{\pm}(\tau) = -(1 + i\Gamma)A_{\pm} + iAA_{\mp} + i(\alpha_1 |A_{\pm}|^2 + \alpha_2 |A_{\mp}|^2)A_{\pm} + i\mu \bar{A}_{\mp} \mp i\Omega \int_{-1}^0 \int_0^{2\pi} \int_0^R g(r, z) u \cdot e_{\theta} r \, dr \, d\theta \, dz A_{\pm},$$
(1)

$$\frac{\partial \boldsymbol{u}}{\partial \tau} - [\boldsymbol{u} + \boldsymbol{G}(A_+, A_-)] \times (\boldsymbol{\nabla} \times \boldsymbol{u}) = -\boldsymbol{\nabla} \boldsymbol{p} + R e^{-1} \Delta \boldsymbol{u},$$
⁽²⁾

with $\nabla \cdot \boldsymbol{u} = 0$. In these equations, \boldsymbol{u} denotes the streaming flow, Ω is a known constant, and the quantities Γ , μ and A are proportional to the detuning, forcing amplitude and ellipticity of the container, respectively. The detuning takes into account the mismatch between half the forcing frequency and the natural frequency of inviscid oscillations, and includes the frequency shift due to viscosity, while A is proportional to the frequency difference $\Omega_1 - \Omega_2$ between inviscid oscillations along the two principal axes of the container. The time has been scaled by the viscous damping time $\delta \equiv \gamma_1 C_g^{1/2} + \gamma_2 C_g$, where $C_g \equiv \nu (gh^3 + Th/\rho)^{-1/2} \ll 1$, and γ_1 and γ_2 are known constants that depend on the excited mode. This scaling is responsible for the appearance of the Reynolds number

$$Re = \frac{\gamma_1 C_g^{1/2} + \gamma_2 C_g}{C_g}$$
(3)

in the Navier–Stokes-like Eq. (2) for the streaming flow. This Reynolds number is formally of order one [32,43], but can in fact be both large and small. For example, if the container is not deep the damping of the waves is dominated by the Stokes boundary layers and $Re \sim \gamma_1/\sqrt{C_g}$, while in a deep container both terms (i.e., $\gamma_1 C_g^{1/2} + \gamma_2 C_g$) contribute to the damping. Calculations show that for the first few modes $\gamma_2/\gamma_1 \sim 10^2$ [32] so that systems with $C_g \leq 10^{-4}$, such as water or silicon oils in centimeter-deep containers, have Reynolds numbers $Re = O(1/\sqrt{C_g})$. In these systems, therefore, the streaming is only weakly damped and hence is easily driven by time-averaged Reynolds stresses.

Eq. (2) also contains a Stokes drift term G given by

$$G = (|\Lambda_{-}|^{2} - |\Lambda_{+}|^{2})g(r,\theta)e_{\theta},$$
(4)

and is to be solved subject to the boundary conditions

$$u = [\varphi_1 A_+ \overline{A}_- e^{2im\theta} + c.c. + \varphi_2 (|A_+|^2 + |A_-|^2)] n_0 \times e_\theta + [i\varphi_3 A_+ \overline{A}_- e^{2im\theta} + c.c. + \varphi_4 (|A_-|^2 - |A_+|^2)] e_\theta$$
(5)

on either r = R or z = -1, and

$$\boldsymbol{u} \cdot \boldsymbol{e}_{z} = \frac{\partial \boldsymbol{u}}{\partial z} \cdot \boldsymbol{e}_{r} = 0, \quad \frac{\partial \boldsymbol{u}}{\partial z} \cdot \boldsymbol{e}_{\theta} = \varphi_{5}(|A_{-}|^{2} - |A_{+}|^{2}) \tag{6}$$

on z = 0. Here n_0 denotes the outward unit normal, and the scalar functions $\varphi_1, \ldots, \varphi_5$ and g are all real, independent of θ and computable in terms of the components of the excited inviscid linear mode of the system [22]. For a pinned contact line the coefficients γ_1 and γ_2 in (3) and the corresponding inviscid eigenfunctions have been calculated in [32], while Miles [34] has calculated the coefficients α_1 and α_2 of the nonlinear terms for a particular case with a free contact line (see Fig. 1). In the following we generally use Miles' results for h = 14.1 cm and Rh = 9.24 cm, viz. $\alpha_1 = 0.4$, $\alpha_2 = -2.58$ (Cases I–III). These values correspond to an experiment of Funakoshi and Inoue [14], although in this case the waves were excited directly by lateral vibration, rather than parametrically. The results in Case IV are obtained for $\alpha_1 = 0.48$, $\alpha_2 = -0.58$.

It is important to observe that in these equations all coefficients are formally of order one. In particular, the forcing of the streaming flow remains finite even in the limit of vanishing viscosity, as originally noted by Schlichting [40] and Longuet-Higgins [31]. The boundary conditions (5,6) show that its magnitude is in general of order $(|A_+|^2, |A_-|^2)$, and hence of order $\mu - \mu_0$, where μ_0 is the threshold for the onset of the Faraday instability. Note also that a nonvanishing streaming flow is associated even with standing waves ($|A_+| = |A_-|$), although for such waves $u \cdot e_{\theta}$ changes sign under reflection $\theta \to -\theta$ and the last term in Eq. (1) vanishes. Thus for standing waves the streaming flow decouples from the amplitudes, although it may be involved in triggering instabilities of such waves.

2.1. The circular container

As already mentioned, when A = 0 the streaming flow decouples from the equations for the amplitudes. To see this we consider waves with azimuthal wavenumber *m*, and write

$$A_{+} = B_{+} \mathrm{e}^{-\mathrm{i}m\theta_{0}(\tau)},\tag{7}$$

to obtain

$$B'_{\pm}(\tau) = -(1 + i\Gamma)B_{\pm} + i(\alpha_1|B_{\pm}|^2 + \alpha_2|B_{\mp}|^2)B_{\pm} + i\mu\overline{B}_{\mp}$$
(8)

and

$$\theta_0'(\tau) = (\Omega/m) \int_{-1}^0 \int_0^{2\pi} \int_0^R g(r, z) \boldsymbol{u} \cdot \boldsymbol{e}_\theta r \, \mathrm{d}r \, \mathrm{d}\theta \, \mathrm{d}z.$$
(9)

These equations provide the simplest description of nearly inviscid Faraday waves in O(2)-symmetric systems and all their solutions converge to reflection-symmetric steady states of the form

$$B_{\pm} = R_0 \mathrm{e}^{\mathrm{i}m\theta_0^0},\tag{10}$$

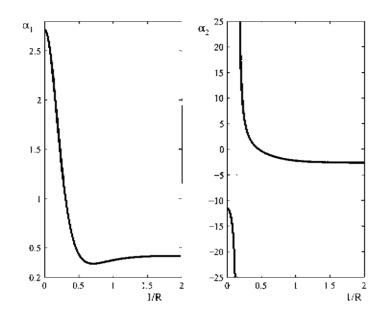


Fig. 1. The coefficients α_1 , α_2 for a m = 1 inviscid mode with a free contact line as a function of the aspect ratio R. Here $\alpha_1 = -A - B$, $\alpha_2 = -A + B$, where A and B are computed by Miles [34].

i.e., to standing waves, and only the spatial phase θ_0 couples to the streaming flow, as described by Eq. (9) and

$$\frac{\partial \boldsymbol{u}}{\partial \tau} - \boldsymbol{u} \times (\boldsymbol{\nabla} \times \boldsymbol{u}) = -\boldsymbol{\nabla} \boldsymbol{p} + R e^{-1} \Delta \boldsymbol{u}, \qquad \boldsymbol{\nabla} \cdot \boldsymbol{u} = \boldsymbol{0}, \tag{11}$$

subject to

$$\boldsymbol{u} = 2R_0^2[\varphi_1 \cos[2m(\theta - \theta_0)] + \varphi_2]\boldsymbol{n}_0 \times \boldsymbol{e}_\theta - 2R_0^2\varphi_3 \sin[2m(\theta - \theta_0)]\boldsymbol{e}_\theta$$
(12)

on either r = R or z = -1, and

$$\boldsymbol{u} \cdot \boldsymbol{e}_{z} = \frac{\partial \boldsymbol{u}}{\partial z} \cdot \boldsymbol{e}_{r} = \frac{\partial \boldsymbol{u}}{\partial z} \cdot \boldsymbol{e}_{\theta} = 0 \tag{13}$$

on z = 0. The (constant) arbitrary phase θ_0^0 appearing in (10) has been eliminated by an appropriate rotation. Eqs. (9), (11)–(13) possess, for all R_0^2 , reflection-symmetric steady states of the form $u = u^s(r, \theta - \theta_0, z), \theta_0 = \text{constant}$, with $u^s(r, \theta, z) \cdot e_{\theta} = -u^s(r, -\theta, z) \cdot e_{\theta}$; note that there is a whole family of such states, obtained by an arbitrary rotation. For small R_0^2 the existence and (orbital) asymptotic stability of these states can be ascertained analytically. It turns out that these states can lose stability at finite R_0 either through a parity-breaking bifurcation giving rise to uniformly drifting spatially uniform standing waves (such as those observed in Faraday experiments in annular containers [10]), or via a symmetry-breaking Hopf bifurcation that produces so-called direction-reversing waves [29]. In the latter case, the standing waves drift alternately clockwise and counterclockwise but their mean location remains fixed. Solutions of this type have been found in a two-dimensional Cartesian geometry with periodic boundary conditions, and represent the instability that sets in at smallest amplitude [33]. Neither instability is present if the coupling to the streaming flow is ignored.

2.2. Nearly circular cylinder

As soon as $A \neq 0$ the symmetry of the problem is reduced to the group D_2 generated by

$$\Lambda_{\pm} \to -\Lambda_{\pm}, \quad \theta \to \theta + \pi, \quad \text{and} \quad \Lambda_{+} \leftrightarrow \Lambda_{-}, \quad \theta \to -\theta, \quad u \cdot e_{\theta} \to -u \cdot e_{\theta},$$
 (14)

and the streaming flow couples to the amplitudes as well. The description of this coupling becomes simpler when the effective Reynolds number of the streaming flow is small (i.e., $\mu - \mu_0$ is small) for then the non-potential term $-\mathbf{u} \times (\nabla \times \mathbf{u})$ in Eq. (2) is negligible. In fact this approximation remains qualitatively useful even for larger Reynolds numbers. The absence of nonlinear terms allows us to isolate the part of the streaming flow velocity that contributes to the nonlocal term in Eq. (1), by decomposing the streaming flow variables as

$$(\boldsymbol{u}, p) = (v(r, z, \tau)\boldsymbol{e}_{\theta}, 0) + (\hat{\boldsymbol{u}}, p), \quad \text{where } \int_{0}^{2\pi} \hat{\boldsymbol{u}} \cdot \boldsymbol{e}_{\theta} \, \mathrm{d}\theta \equiv 0.$$
(15)

Thus,

$$A'_{\pm}(\tau) = -(1 + i\Gamma)A_{\pm} + iAA_{\mp} + i(\alpha_1 | A \pm |^2 + \alpha_2 | A_{\mp} |^2)A_{\pm} + i\mu \overline{A}_{\mp} \mp 2\pi i\Omega \int_{-1}^0 \int_0^R g(r, z)v(r, z, \tau) r \, dr \, dz A_{\pm},$$
(16)

$$v_{\tau} = Re^{-1}(v_{rr} + r^{-1}v_r - r^{-2}v + v_{zz}) \quad \text{if} \quad 0 < r < R, \quad -1 < z < 0, \tag{17}$$

$$v = 0 \quad \text{as } r \to 0, \tag{18}$$

$$v = \varphi_4(|A_-|^2 - |A_+|^2)$$
 on either $r = R$ or $z = -1$, (19)

$$v_z = \varphi_5(|A_-|^2 - |A_+|^2) \quad \text{on}\, z = 0, \tag{20}$$

and the axisymmetric part of the streaming flow vanishes for standing waves $(|\Lambda_+| = |\Lambda_-|)$.

Although the above model can be integrated numerically by relatively inexpensive methods we simplify it further by expanding the axisymmetric component of the streaming flow velocity, v, in terms of purely azimuthal hydrodynamic modes. These satisfy the eigenvalue equation

$$\lambda V = V_{rr} + r^{-1}V_r - r^{-2}V + V_{zz} \quad \text{if} \quad 0 < r < R, \quad -1 < z < 0, \tag{21}$$

$$V = 0 \text{ as } r \to 0, \quad V = \varphi_4 \text{ on either } r = R \text{ or } z = -1, \quad V_z = \varphi_5 \text{ on } z = 0.$$
(22)

The eigenvalues λ are all real and negative. If only the first such mode is retained, we obtain

$$A'_{\pm}(\tau) = -(1 + i\Gamma)A_{\pm} + iAA_{\mp} + i(\alpha_1|A_{\pm}|^2 + \alpha_2|A_{\mp}|^2)A_{\pm} + i\mu A_{\mp} \mp i\gamma v_1 A_{\pm},$$
(23)

$$v_1'(\tau) = \varepsilon(-v_1 + |\Lambda_-|^2 - |\Lambda_+|^2),\tag{24}$$

where $\varepsilon = -\lambda_1 R e^{-1} > 0$, and $\lambda_1 < 0$ is the first purely azimuthal hydrodynamic eigenvalue. In the following we define new variables

$$X = i(A_{+} - A_{-})/2, \quad Y = (A_{+} + A_{-})/2, \quad v = -v_1/2,$$
(25)

and rewrite Eqs. (23)-(24) in the more useful form

$$X' = -(1 + i(\Gamma + A))X + i((\alpha_1 + \alpha_2)|X|^2 + 2\alpha_1|Y|^2)X - i(\alpha_1 - \alpha_2)\overline{X}Y^2 + i\mu\overline{X} - 2\gamma vY,$$
(26)

$$Y' = -(1 + i(\Gamma - A))Y + i((\alpha_1 + \alpha_2)|Y|^2 + 2\alpha_1|X|^2)Y - i(\alpha_1 - \alpha_2)\overline{Y}X^2 + i\mu\overline{Y} + 2\gamma vX,$$
(27)

$$v' = \varepsilon(-v + \mathbf{i}(XY - XY)). \tag{28}$$

This form of the equations makes it clear not only that the (axisymmetric part of the) streaming flow vanishes if either X = 0 or Y = 0, i.e., for pure standing waves, but also that both modes must be present in order to drive such a flow, i.e., all instabilities of standing waves within Eqs. (26)–(28) will be due to *mode interaction*, at least when $A \neq 0$.

Eqs. (26)–(28) constitute the basic system studied in the remainder of this paper, and we investigate its properties for small values of ε . If ε is too large the mean flow becomes slaved to the amplitudes, and Eqs. (26)–(28) become instead

$$X' = -(1 + i(\Gamma + A))X + i((\alpha_1 + \alpha_2)|X|^2 + 2(\alpha_1 + \gamma)|Y|^2)X - i(\alpha_1 - \alpha_2 + 2\gamma)\overline{X}Y^2 + i\mu\overline{X},$$
(29)

$$Y' = -(1 + i(\Gamma - \Lambda))Y + i((\alpha_1 + \alpha_2)|Y|^2 + 2(\alpha_1 + \gamma)|X|^2)Y - i(\alpha_1 - \alpha_2 + 2\gamma)\overline{Y}X^2 + i\mu\overline{Y},$$
(30)

i.e., amplitude equations for the Faraday system of the usual kind, but with coefficients modified by the presence of the mean flow according to $\alpha_1 \rightarrow \alpha_1 + \gamma$, $\alpha_2 \rightarrow \alpha_2 - \gamma$. The resulting equations form a special case of the system studied by Dangelmayr and Knobloch [9]. When ε is sufficiently small the streaming flow v participates actively in the dynamics and permits behavior that would not otherwise occur. This occurs when the mean flow is sufficiently weakly damped, i.e., when $|\lambda_1|$ is sufficiently small or *Re* sufficiently large.

3. Analytical results

Eqs. (26)–(28) are equivariant with respect to the group D_2 generated by the two reflections

$$R_1: (X, Y, v) \to (-X, Y, -v), \qquad R_2: (X, Y, v) \to (X, -Y, -v).$$
(31)

These symmetries will prove to be of crucial importance in the analysis that follows.

We begin by examining the steady states and their stability properties. The steady states are of two types, hereafter *pure modes* associated with vanishing streaming flow, and *mixed modes* which are accompanied by a nonzero streaming flow. These are distinguished by their symmetries.

3.1. Pure modes (P_{\pm})

The two possible pure modes are given by $P_+ \equiv (0, Y, 0) = (0, R_+e^{i\phi_+}, 0)$ and $P_- \equiv (X, 0, 0) = (R_-e^{i\phi_-}, 0, 0)$, with P_+ invariant under R_1 and P_- under R_2 . The amplitudes of these modes satisfy

$$P_{\pm}: 1 + (I' \mp A - (\alpha_1 + \alpha_2)R_{\pm}^2)^2 = \mu^2.$$
(32)

The P_{\pm} are both pure parity standing waves, one with a nodal line along the major axis of the container and the other along the minor axis. When A = 0 and the container is perfectly circular the pure modes are part of a whole circle of standing oscillations.

The P_+ and P_- solutions bifurcate from the trivial state at

$$\mu_{0+} = (1 + (\Gamma - A)^2)^{1/2}$$
 and $\mu_{0-} = (1 + (\Gamma + A)^2)^{1/2}$, (33)

respectively. The bifurcation to P_{\pm} is supercritical if $(\Gamma \mp A)(\alpha_1 + \alpha_2) < 0$.

Linearization about the pure modes identifies the stability properties of these states. These fall into one of two classes: the eigenvector may respect the symmetry of the solution, or it may break it. A steady state bifurcation of the former type corresponds to saddle-node bifurcations (SN), while a steady state bifurcation of the latter type is a pitchfork that produces a pair of *mixed modes*, i.e., steady states that do not have any symmetry. In the following we

refer to this bifurcation as a symmetry-breaking bifurcation (SB). A simple calculation shows that these bifurcations occur at

$$SN: R_{\pm}^2 = \frac{\Gamma \mp \Lambda}{\alpha_1 + \alpha_2},\tag{34}$$

SB:
$$R_{\pm}^2 = \frac{\Gamma}{2(\alpha_1 + \gamma)}$$
, if $\Gamma A \neq 0$, (35)

respectively. We emphasize that SB produces *steady* solutions of the form (X, Y, v), $XYv \neq 0$, in contrast to the parity-breaking bifurcation that occurs when A = 0 and produces a *drifting* pure mode.

The pure modes P_{\pm} may also experience Hopf bifurcation. Only one type, a symmetry-breaking Hopf bifurcation, is possible and takes place at

$$R_{\pm}^{2} = \frac{4I'\Lambda \pm 2\varepsilon \pm \varepsilon^{2}}{4\Lambda(2\alpha_{1} - \varepsilon\gamma)},\tag{36}$$

provided that $\gamma A \neq 0$. This requirement follows immediately from the expression for the oscillation frequency ω_{\pm} .

$$\omega_{\pm}^2 = -\varepsilon^2 \mp 4\gamma A \varepsilon R_{\pm}^2 > 0. \tag{37}$$

Thus, at most one pure mode can lose stability at a symmetry-breaking Hopf bifurcation, P_+ if $\gamma A < 0$, and P_- if $\gamma A > 0$. Note that this instability involves the excitation of the streaming flow ($\gamma \neq 0$) and requires a finite ellipticity of the container. The oscillations that result resemble trapped direction-reversing waves, oscillating about the major or minor axes, but exhibit no drift. Such states correspond to two-frequency Faraday oscillations.

3.2. Mixed modes (M)

The mixed modes $M \equiv (X, Y, v) = (R_-e^{i\phi_-}, R_+e^{i\phi_+}, v)$ satisfy

$$E \equiv R_{+}^{2} + R_{-}^{2} = \frac{\Gamma}{2(\alpha_{1} + \gamma)},$$
(38)

$$(E(\alpha_1 + \alpha_2) - \Gamma)^2 + (1 + \Lambda^2 + \Lambda(\alpha_2 - \alpha_1 - 2\gamma)L)^2 = (1 + \Lambda^2)\mu^2,$$
(39)

$$\tan(\phi_{+} - \phi_{-}) = \Lambda, \qquad \cos^{2}(\phi_{+} + \phi_{-}) = \frac{(E(\alpha_{1} + \alpha_{2}) - \Gamma)^{2}}{\mu^{2}(1 + \Lambda^{2}),}$$
(40)

where $L \equiv R_+^2 - R_-^2$. Since these modes have no symmetry, the linearization about them does not block-diagonalize, and the stability analysis must in general be done numerically. However, it is possible to show that the mixed modes lose stability at a saddle-node bifurcation when

$$\mu^{2}(1+\Lambda^{2})(\alpha_{1}+\gamma)^{2}-\Gamma^{2}(\alpha_{1}-\alpha_{2}+2\gamma)^{2}=0,$$
(41)

a result that also follows from Eqs. (38,39). These modes can also undergo a Hopf bifurcation. In contrast to the pure modes such a bifurcation is possible even when $\gamma = 0$, but then occurs only if P_+ and P_- bifurcate in *opposite* directions. However, if $\gamma \neq 0$, a Hopf bifurcation may occur along the mixed mode branch even when it connects two supercritical pure modes.

The stability results for the P_{\pm} and M solutions described above are illustrated in Fig. 2 for four representative sets of parameter values. In Fig. 2a, both pure mode branches bifurcate supercritically, with the P_{-} branch bifurcating before the P_{+} branch. The P_{-} states are therefore stable at small amplitude and remain so until a symmetry-breaking bifurcation at SB, where stability is transferred to the mixed modes M. These in turn lose stability at a Hopf bifurcation prior to the end of the M branch on the P_{+} branch. The P_{+} solutions above SB have two unstable eigenvalues and acquire stability only at larger amplitude, at another Hopf bifurcation. A stability gap, where time-dependent solutions may be expected, is therefore present between the two Hopf bifurcations H.

Fig. 2b shows a case in which a symmetry-breaking Hopf bifurcation occurs below the symmetry-breaking steady state bifurcation on the P_{-} branch. Since the latter is subcritical the resulting mixed modes have initially three unstable eigenvalues but acquire stability after a saddle-node bifurcation, followed by a Hopf bifurcation. Once stable they remain so until their termination point on the P_{+} branch, where they transfer stability to the P_{+} branch. Once again time-dependent behavior is expected in the region between the two Hopf bifurcations H.

In Fig. 2c, both pure mode branches bifurcate subcritically. The P_{-} branch bifurcates first and acquires stability at a saddle-node bifurcation before losing it again at larger amplitude at a symmetry-breaking steady state bifurcation SB. The P_{+} branch is never stable, and neither are the mixed modes connecting the pure mode branches. Here time-dependent states set in beyond the symmetry-breaking bifurcation on the P_{-} branch.

Finally, in Fig. 2d the parameters Γ and A are small, and the pure modes P_{\pm} come in in close succession and bifurcate almost vertically (see Eq. (32)). The figure shows that this time it is the P_{\pm} branch that comes in first, and that it bifurcates slightly subcritically with all three of the possible secondary instabilities present. Since the Hopf bifurcation occurs below the saddle-node bifurcation the P_{\pm} state has two unstable eigenvalues above the saddle-node, one of which passes through zero at SB. It follows that the mixed mode states created at SB have initially two unstable eigenvalues, i.e., that the bifurcation is *subcritical*. In contrast, the P_{\pm} state bifurcation from P_{\pm} to the mixed modes is *supercritical*, and hence that the mixed modes are stable near P_{\pm} . It follows that there must be a Hopf bifurcation along the mixed mode branch, at $\mu = \mu_H^M$ say, and indeed our calculations confirm that this is so. The presence of this bifurcation is important in what follows since it implies that Eqs. (26)–(28) have *no stable* nontrivial fixed points for $\mu < \mu_H^M$. Consequently, the *first* state observed once μ exceeds the threshold value μ_0 must be a *time-dependent* state. We return to this point below.

The dynamical behavior in the regions identified by the linear stability theory is the subject of the following section.

4. Numerical results

In this section we study the dynamics of Eqs. (26)–(28) in the intervals of μ identified in the preceding section. We consider only the four cases shown in Fig. 2, hereafter referred to as Cases I through IV.

4.1. Case I: Periodic oscillations

Case I is the simplest and exhibits periodic oscillations only, albeit of two distinct types. In the region of interest identified in Section 3 we find stable R_1 -symmetric periodic orbits, labeled R_{1s} in Fig. 3a. These disappear with increasing μ at a Hopf bifurcation on the P_+ branch, and annihilate with unstable R_1 -symmetric solutions (labeled R_{1u}) at a saddle-node bifurcation SN as μ decreases (see Fig. 3a). The latter are created in a gluing bifurcation at $\mu = \mu_g \approx 1.926$ involving an unstable P_+ state and a pair of unstable asymmetric periodic orbits (labeled A_u) produced in a (subcritical) Hopf bifurcation on the branch of mixed modes M. Thus, the asymmetric periodic orbits are unstable throughout their range of existence, $\mu_g < \mu < \mu_H \approx 1.932$. The gluing bifurcation is shown in two different projections in Fig. 3b. The eigenvalues of the fixed point P_+ at $\mu = \mu_g$ are 0.16, -0.004, $-1.1 \pm 1.9i$ and -2.16; the eigenvectors of the first two of these are (Re(X), Im(X), Re(Y), Im(Y), v) = (0.8093, 0.5869, 0, 0, 0.0237) and (0.6392, 0.4902, 0, 0, 0.592). Thus, both eigenvectors are odd with respect to R_1 , and the homoclinic bifurcation at $\mu = \mu_g$ is of type a in the terminology of Glendinning [15], with no stable periodic orbits or complex dynamics near μ_g . The saddle-node bifurcation on the R_1 -symmetric branch is nonlocal and consistent with this classification.

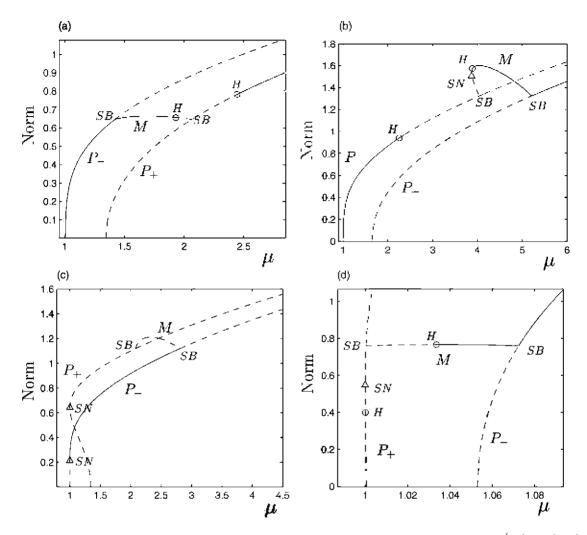


Fig. 2. Bifurcation diagrams for the pure modes P_{-} and mixed modes M showing the Euclidean norm $||(X, Y, v)|| \equiv \sqrt{|X|^2 + |Y|^2 + v^2}$ as a function of μ . Solid (broken) lines indicate stable (unstable) steady states. Saddle-node (Δ), symmetry-breaking and Hopf (\odot) bifurcations are labeled by SN, SB and H, respectively. The parameters are: (a) $\Gamma = 0.5$, $\Lambda = -0.4$, $\alpha_1 = 0.4$, $\alpha_2 = -2.58$, $\gamma = 0.2$, $\varepsilon = 0.01$; (b) $\Gamma = 0.7$, $\Lambda = -0.6$, $\alpha_1 = 0.4$, $\alpha_2 = -2.58$, $\gamma = -0.2$, $\varepsilon = 0.01$; (c) $\Gamma = -0.5$, $\Lambda = 0.4$, $\alpha_1 = 0.4$, $\alpha_2 = -2.58$, $\gamma = -0.6$, $\varepsilon = 0.01$; (d) $\Gamma = 0.15$, $\Lambda = 0.18$, $\alpha_1 = 0.48$, $\alpha_2 = -0.58$, $\gamma = -0.35$, $\varepsilon = 0.001$.

4.2. Case II: Relaxation oscillations and canards

Case II is very interesting from a theoretical point of view, even though no chaotic dynamics appear to be present. As shown in Fig. 4a, the periodic orbits in the system undergo two distinct types of transition as μ increases. In the first, near $\mu = 2.7$, a pair of R_2 -symmetric periodic orbits, created in a Hopf bifurcation on the P_- branch, forms a pair of heteroclinic connections between P_+ and $-P_+$. Fig. 5a shows one of the R_2 -symmetric periodic orbits, in two different projections, just before this transition, while Fig. 5b shows one of the two periodic orbits that result from it. Each of these orbits has R_1R_2 -symmetry. Such symmetry-switching bifurcations are typical of D_2 -symmetric systems [38,21] and occur as a result of the formation and breakup of a pair of heteroclinic connections. Since the eigenvalues of P_+ at the bifurcation are 0.2770, -0.0182, -2.2687 and -1 ± 3.3415 i

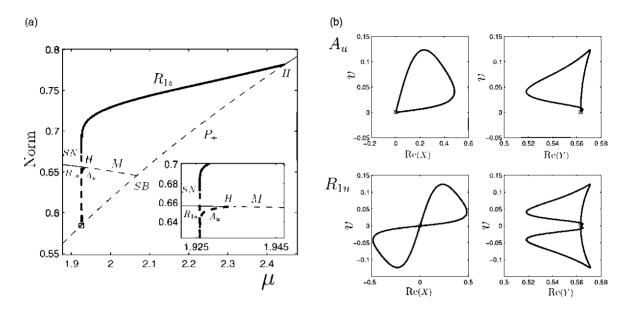


Fig. 3. Case I, corresponding to Fig. 2a. (a) Branches of steady states and periodic orbits in terms of the Euclidean norm ||(X, Y, v)|| and the L_2 norm $||(X, Y, v)||_{L_2}$, respectively, as a function of μ . Thick solid (dashed) lines indicate stable (unstable) periodic orbits generated in Hopf bifurcations (H) on P_+ and M. Thin solid (dashed) lines indicate stable (unstable) steady states. (b) Two projections of the unstable periodic orbits close to the gluing bifurcation at $\mu = \mu_R$; an unstable asymmetric periodic orbit A_u and an unstable R_1 -symmetric periodic orbit R_{1u} . The symbol \Box indicates the location on P_+ of the global bifurcation.

with (Re(X), Im(X), Re(Y), Im(Y), v) = (-0.7808, -0.6243, 0, 0, 0.0242) and (0.5416, 0.4885, 0, 0, 0.6842) as the first two eigenvectors the heteroclinic cycle $P_+ \leftrightarrow -P_+$ is asymptotically planar, with no stable periodic orbits or complex dynamics nearby. Consequently the two stable orbits must go through saddle-node bifurcations before the switching bifurcation can take place, cf. [15].

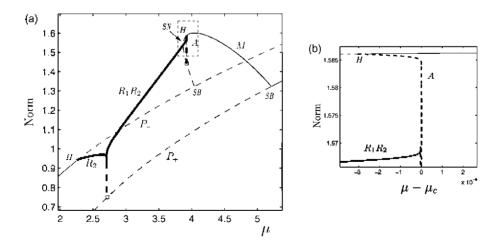


Fig. 4. Case II. (a) Branches of steady states and periodic orbits, in terms of the Euclidean norm ||(X, Y, v)|| and the L_2 norm $||(X, Y, v)||_{L_2}$, respectively, as a function of μ . Global bifurcations are indicated by open squares, while thick solid (dashed) lines correspond to stable (unstable) periodic orbits, and thin solid (dashed) lines correspond to stable (unstable) steady states. (b) Enlargement of the framed region in (a) centered at $\mu_c = 3.9210403$, indicating the location of the $R_1 R_2$ -symmetric and asymmetric (A) orbits. Remaining parameters are as in Fig. 2b.

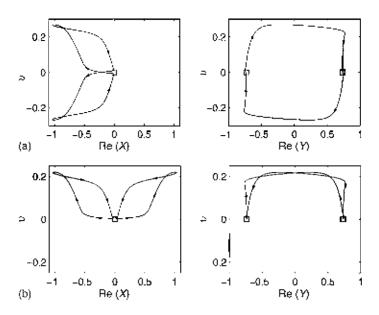


Fig. 5. Case II. A symmetry-switching transition involving the pure modes $\pm P_+$, in terms of projections onto the (Re(X), v) and (Re(Y), v) variables. (a) A periodic R_2 -symmetric orbit at $\mu = 2.704115$. (b) A periodic R_1R_2 -symmetric orbit at $\mu = 2.704122$. The symbol \Box indicates the location of the unstable fixed points $\pm P_+$. The parameters correspond to those of Fig. 2b.

The second transition, near $\mu \approx 3.9210403$, is of much greater interest. Here each of the stable $R_1 R_2$ -symmetric periodic orbits created in the first transition (Fig. 4a) appears to 'break up' in what looks like a saddle-node bifurcation into a pair of unstable periodic orbits with no symmetry, which in turn disappear in a subcritical Hopf bifurcation on the branch of mixed modes at $\mu_H = 3.92073453$ (Fig. 4b). Fig. 6 shows these two orbits near this transition, and illustrates the abrupt change in the oscillation amplitude that results from it. Numerically, we find that the period of

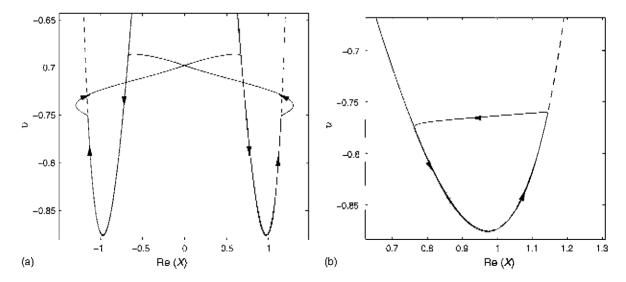


Fig. 6. Case II. Periodic orbits close to the codimension-two global bifurcation at $\varepsilon = 0$, $\mu = \mu_0$, superposed on the nullcline Σ . (a) A stable $R_1 R_2$ -symmetric periodic orbit at $\mu = 3.921039743$, $\varepsilon = 0.01$. (b) An unstable asymmetric periodic orbit at $\mu = 3.921040287$, $\varepsilon = 0.01$. The remaining parameters are as in Fig. 2b.

both types of oscillation appears to diverge at a common value of μ near $\mu = 3.9210403$, hereafter $\mu_{\rm o}$. However, the nature of this divergence is highly unusual, and does not conform with the logarithmic divergence associated with an approach to a global bifurcation, even though Fig. 4a suggests that the transition between the small and large amplitude oscillations is somehow related to the proximity to an unstable mixed mode. It is clear, moreover, that the transition cannot be a gluing bifurcation of the type encountered in Case I, since any gluing bifurcation between a pair of asymmetric orbits and an $R_1 R_2$ -symmetric periodic orbit at an asymmetric mixed mode is necessarily of codimension two, and hence nongeneric in one parameter families of vector fields.

With $\varepsilon = 0.01$ it is exceedingly difficult to unravel the details of this unusual transition by numerical computation alone. We have therefore adopted a dual approach, by examining first the limit $\varepsilon \to 0$, and then performing detailed computations for somewhat larger values of ε to confirm the predictions of the $\varepsilon \to 0$ analysis. We begin by writing Eqs. (26)–(28) in the form

$$\mathbf{X}' = \mathbf{F}_1(\mathbf{X}, \mathbf{Y}, v; \mu), \quad \mathbf{Y}' = \mathbf{F}_2(\mathbf{X}, \mathbf{Y}, v; \mu), \quad v' = \varepsilon G(\mathbf{X}, \mathbf{Y}, v), \tag{42}$$

where X = (Re(X), Im(X)), Y = (Re(Y), Im(Y)) and suppose that $0 < \varepsilon \ll 1$. In this regime, Eqs. (42) exhibit *relaxation oscillations*, and we can understand the properties of these oscillations by examining first the case $\varepsilon = 0$. In this case, v becomes a parameter, and Eqs. (42) become

$$X' = F_1(X, Y; v, \mu), \quad Y' = F_2(X, Y; v, \mu).$$
(43)

This pair of equations can have both steady state solutions and periodic solutions. Of particular significance is the one-dimensional nullcline $\Sigma : F_1(X, Y, v; \mu) = F_2(X, Y, v; \mu) = 0$ that contains the steady states when $\varepsilon > 0$ and consists of them when $\varepsilon = 0$. These may be stable or unstable. When $0 < \varepsilon \ll 1$ the solutions of Eqs. (42) can be thought of as drifting slowly along the attracting part of Σ . Typically this slow drift ends near folds on Σ where the solution is forced away from Σ and the slow drift is replaced by a fast transition that takes the system to another branch of Σ . This is the essence of all relaxation oscillations. However, in certain circumstances the periodic oscillations may follow the *unstable* part of Σ after the fold. This is the hallmark of the so-called *canard* phenomenon, and related behavior has been seen, for example, in model equations describing chemical systems [8,35]. Like the present system these systems also exhibit abrupt transitions from small amplitude oscillations to large amplitude relaxation-type oscillations, a behavior that has been called a *canard explosion* [8,18,35].

To understand this behavior in the present context we show in Fig. 7a, a projection of Σ on the (Re(X), v)plane when $\mu \approx \mu_H$. This projection shows four branches, S^{\pm} (solid lines) and U^{\pm} (dashed lines), corresponding respectively to stable and unstable steady states of Eqs. (43); the points q_{\pm} denote saddle-node bifurcations where these steady states change their stability. Note that the branches S^+ and U^+ as well as the point q^+ are related through $R_1 R_2$ -symmetry to S^- , U^- and q^- . Away from the fold points q^{\pm} the manifolds S^{\pm} and U^{\pm} are normally hyperbolic. As a consequence when $0 < \varepsilon \ll 1$ they perturb to normally hyperbolic invariant manifolds M_S^{\pm} and M_U^{\pm} lying within $O(\varepsilon)$ of S^{\pm} and U^{\pm} [13]. The former is attracting, while the latter is of saddle-type, properties that are inherited from those of S^{\pm} and U^{\pm} . Together these manifolds define the *slow manifold* of the system (42). To find the *flow* on this manifold due to the slow evolution of v we solve (43) for X, Y as functions of v and compute G(X(v), Y(v), v). The fixed points of this reduced flow with $v \neq 0$ approximate the mixed modes M^{\pm} of (42) for $0 < \varepsilon \ll 1$ and lie within Σ . Fig. 7b shows these fixed points superposed on Σ when $\varepsilon = 0.01$. There are two pairs of such points, labeled M_1^{\pm} and M_2^{\pm} , of which $M_1^{\pm} \approx q^{\pm}$ undergo a subcritical Hopf bifurcation at $\mu_H = 3.92073453$. Numerically we find that the resulting unstable asymmetric oscillations grow in amplitude as μ increases but remain unstable all the way to $\mu = \mu_c$, where the transition to the stable large amplitude $R_1 R_2$ -symmetric oscillations takes place.

Fig. 8(a–d) describes geometrically what happens in a typical canard explosion. The figure is drawn for $0 < \varepsilon \ll 1$ but does not distinguish between the slow unstable manifolds M_U^{\pm} and the stable manifolds W^s of the fixed points M_2^{\pm} . This permits us to extend M_U^{\pm} past the folds q^{\pm} . Fig. 8a shows the relative position of these manifolds prior to the explosion. The fixed point $M_1^{\pm} \in M_S^{\pm}$ is attracting, while $M_2^{\pm} \in M_U^{\pm}$ is a saddle. If μ is now increased M_1^{\pm} moves

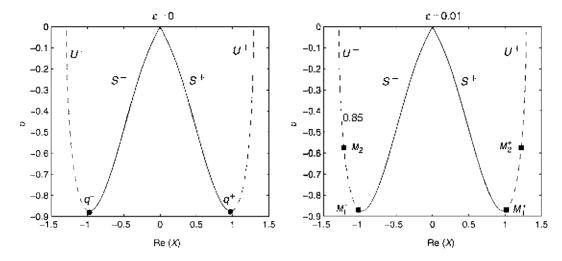


Fig. 7. Case II. Projection of the nullcline Σ on (Re(X), v)-plane for $\mu = 3.9213453 \approx \mu_H$ and the indicated values of ε . The remaining parameters are as in Fig. 2b. Solid (dashed) line corresponds to stable (unstable) steady states of Eqs. (42) for $\varepsilon = 0$.

past q^+ and falls in M_U^+ , resulting in a Hopf bifurcation. Fig. 8b shows the relative orientation of M_S^+ , the resulting small amplitude periodic solution γ_s and $W^s(M_2^+)$ when this bifurcation is supercritical. As μ increases further M_S^+ and $W^s(M_2^+)$ approach one another, and at a critical value $\mu = \mu_c$ they may coalesce (see Fig. 8c). As this happens the small amplitude oscillation grows and at $\mu = \mu_c$ it collides with M_2^+ , forming a homoclinic connection. Beyond this critical parameter value the homoclinic connection breaks, forming a large amplitude periodic orbit γ_ℓ lying outside of $W^s(M_2^+)$ (Fig. 8d). Here the formation of a canard therefore corresponds to the appearance of a homoclinic connection and hence is associated with a *global bifurcation* [35].

In our case, however, the Hopf bifurcation is subcritical, M_1^+ is stable, and the details of the transition differ [2,3]. Fig. 8e and f shows the analogues of Fig. 8b and d for this case. Prior to the canard the small amplitude periodic solution γ_s is unstable (Fig. 8e) and coexists with a *stable* large amplitude periodic orbit γ_ℓ lying outside of $W^s(M_2^+)$. As μ approaches μ_c these orbits both approach M_2^+ along $W^s(M_2^+)$ and at $\mu = \mu_c$ (Fig. 8c) γ_s appears to coincide with a part of γ_ℓ . Once $\mu > \mu_c$ the slow manifold M_s^+ lies on the inside of $W^s(M_2^+)$ and no oscillations are present (Fig. 8f). Thus, the small amplitude unstable oscillation annihilates the large amplitude stable oscillation, a transition that must take place via the formation of a connection to M_2^+ since the two oscillations have different symmetry properties. Thus, the canard at $\mu = \mu_c$ looks like a saddle-node bifurcation of periodic orbits (cf. [8]) but is in fact also associated with a global bifurcation.

When ε is finite but sufficiently small ($\varepsilon = 0.01$ is sufficiently small in this sense) the behavior of the system (26)–(28) is indistinguishable from the qualitative predictions based on the above picture. Fig. 6 shows an unstable asymmetric small amplitude oscillation at $\mu = 3.921040287$ and a stable R_1R_2 -symmetric relaxation oscillation at $\mu = 3.921039743$, each projected on the (Re(X), υ) variables and superposed on the nullcline Σ , for $\varepsilon = 0.01$. In each case, the arrows indicate the direction of motion for comparison with Fig. 8e and f. The figure confirms that the slow manifold for $\varepsilon = 0.01$ does indeed follow the locus of fixed points computed with $\varepsilon = 0$ (Fig. 7a), and that as μ increases a pair of unstable small amplitude asymmetric periodic orbits is born in a (subcritical) Hopf bifurcation of $M_1^{\pm} \approx q^{\pm}$. As μ increases further the amplitude of each of these grows, initially slowly but then more rapidly, prior to the canard transition at $\mu = \mu_c$. At μ_c the unstable periodic orbit γ_s^+ follows M_U^+ , the unstable part of the slow manifold between M_1^+ and the saddle-type fixed point M_2^+ (Fig. 6b), forming a saddle-loop connection. Fig. 9 shows that during this process the period of both the asymmetric and the $R_1 R_2$ -symmetric oscillations diverges, confirming

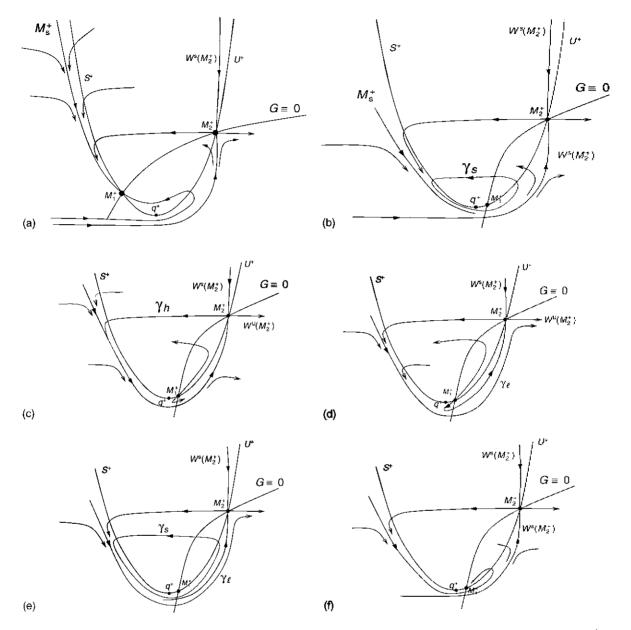


Fig. 8. Case II. Projection of the nullclines Σ and V on the (Re(X), v)-plane, showing the relative orientation of the slow manifold M_s^+ and the stable and unstable manifolds $W^{s,n}$ of the fixed point M_2^+ . (a) M_1^- is stable. (b) M_1^+ undergoes a supercritical Hopf bifurcation at $\mu = \mu_H$ producing a stable small amplitude asymmetric orbit γ_s . (c) The canard manifold $W^s(M_2^+)$ at $\mu = \mu_c$, connecting M_s^+ with M_U^+ , showing the homoclinic connection γ_h . (d) The formation of a stable large amplitude relaxation oscillation γ_c when $\mu > \mu_c$. (e) M_1^+ undergoes a subcritical Hopf bifurcation at $\mu = \mu_H$ producing an unstable small amplitude asymmetric orbit γ_s within a stable large amplitude relaxation oscillation γ_{ℓ_c} . (f) The formation of a canard at $\mu = \mu_c$ is responsible for the absence of both periodic orbits when $\mu > \mu_c$.

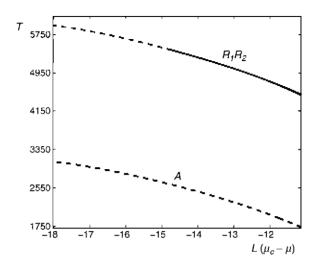


Fig. 9. Case II. The period T of asymmetric and R_1R_2 -symmetric oscillations near the canard at $\mu = \mu_c \approx 3.9210403$. The symbol L indicates the natural logarithm. Solid (broken) lines indicate stable (unstable) oscillations. Both periods diverge as $\mu \to \mu_c -$, indicating proximity to a global bifurcation.

the presence of a global bifurcation involving M_2^+ , and that for both oscillations this occurs from the *same* side. However, despite much effort (see Fig. 9) we have been unable to confirm the expected result that the oscillation period T of both the small and large amplitude oscillations should diverge logarithmically, as $T \sim -\lambda_u^{-1} \ln |\mu - \mu_c|$, where λ_u is the unstable eigenvalue of M_2^+ .

These and other conflicts with expectation are all reconciled when one recognizes that the location of the detachment of the trajectory from the unstable slow manifold is exponentially sensitive to the value of ε and that the range of μ around μ_c during which canards are present is proportional to exp $-c/\varepsilon$, where *c* is a positive constant [11,18]. This fact suggests in turn that there is an exponentially small neighborhood of μ_c in which the finite value of ε restores the expected behavior, such as the logarithmic divergence. In fact, we find that the finite value of ε 'unfolds' the saddle-node/global bifurcation present at $\varepsilon = 0$ (cf. [16]), with the result that the global bifurcation splits into *two* successive codimension-one global bifurcations, one involving the small amplitude asymmetric oscillations and the other the large amplitude $R_1 R_2$ -symmetric oscillations, with the saddle-node bifurcation now occurring on one or other of these oscillation branches. The behavior near each of these global bifurcations is determined by the eigenvalue ratio $\delta = |\lambda_s/\lambda_u|$, where $\lambda_s \approx -0.00051$ is the least stable eigenvalue of M_2^+ and $\lambda_u \approx 0.4889$ is its unstable eigenvalue, both computed at $\mu = \mu_c$ for $\varepsilon = 0.01$. Thus, $\delta \ll 1$. Under these conditions classical theory [45] shows that neither type of periodic orbit will be stable near $\mu = \mu_c$. It follows therefore that once $0 < \varepsilon \ll 1$ the saddle-node bifurcation must move away from $\mu = \mu_c$, and that it is the *stable* $R_1 R_2$ -symmetric orbit that must undergo a saddle-node bifurcation prior to the formation of the canard at $\mu = \mu_c$. If this is so $\mu_c \gtrsim 3.921040287$, and the two periodic orbits approach their individual global bifurcations from opposite sides after all.

In order to confirm these conclusions we have recomputed our results with $\varepsilon = 0.2$. With this larger value of ε the qualitative picture remains unchanged (Fig. 10a) but the nature of the transition becomes much clearer. Fig. 10b shows that the asymmetric oscillations continue to be subcritical and unstable, and that these approach monotonically a global bifurcation at $\mu_a = 3.881857$ involving the mixed modes M_2^{\pm} as μ increases. Moreover, this bifurcation is now distinct from the corresponding global bifurcation on the branch of R_1R_2 -symmetric relaxation oscillations which takes place at a larger value of μ , $\mu_s = 3.882094$. In addition, one can now follow the oscillation period close to each global bifurcation, and finds that in both cases it diverges logarithmically, as expected from global bifurcations. Note also that the R_1R_2 -symmetric oscillations remain *stable* almost until the end of the branch, but that right before the end they go through a saddle-node bifurcation at which they lose stability. Thus, on both

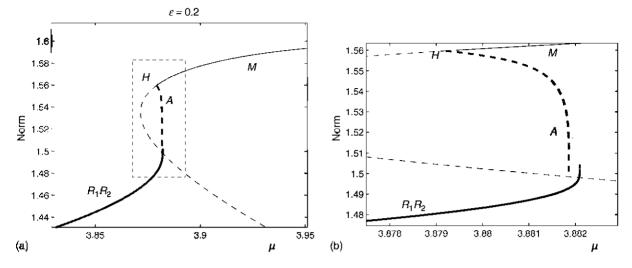


Fig. 10. (a) Bifurcation diagram for the same parameters as Case II but with $\varepsilon = 0.2$ for comparison with Fig. 4a. (b) Detail of the bifurcation diagram in (a) for comparison with Fig. 4b, showing the 'unfolding' of the canard transition at finite ε .

branches the oscillations are unstable near their respective global bifurcations, as expected from the fact that here too $\delta \ll 1$. We conclude that the strange behavior of the canard transition is a consequence of the exponentially small region in which the two global bifurcations and the accompanying saddle-node bifurcation occur. As a result the logarithmic divergence of the period is postponed to very high periods, the two families of periodic orbits undergo global bifurcations almost simultaneously, and the relaxation oscillations involved appear to approach the global bifurcation from the *wrong* direction and with the *wrong* stability assignment. It is reasonable to expect that for any finite value of ε these 'paradoxes' are resolved in this exponentially small region around $\mu = \mu_e$ in the same way as found here for $\varepsilon = 0.2$.

Finally, the theoretical prediction [18] that canards will form once $\mu - \mu_H = O(\varepsilon)$ is also broadly consistent with the numerical results. We believe, therefore, that except for the effects of symmetry the transition observed in Fig. 6 is essentially the result of a classical canard associated with a *subcritical* Hopf bifurcation.

4.3. Case III: Symmetric and asymmetric bursting

This case displays very interesting dynamics over a large (semi-infinite) range of the forcing amplitude μ where no stable steady states exist. As shown in Fig. 11, when the pure mode P_{-} loses stability in a symmetry-breaking bifurcation at $\mu = \mu_{SB} \approx 2.8$, small perturbations drive the system to a stable branch of $R_1 R_2$ -symmetric periodic orbits. If this periodic branch is continued backwards (i.e., for $\mu < \mu_{SB}$) one finds that it ultimately terminates in a heteroclinic bifurcation involving the nonsymmetric fixed points M^{\pm} . The eigenvalues of M^{\pm} at this bifurcation are 0.001940, -0.42229, $-0.998 \pm 4.819i$ and -1.58926 and hence no chaotic dynamics result. An entirely different scenario unfolds when this periodic branch is continued for $\mu > \mu_{SB}$. First, the $R_1 R_2$ -symmetric branch undergoes a pitchfork bifurcation that generates stable asymmetric periodic orbits (see Fig. 11, inset). With further increase in μ these asymmetric orbits undergo a period doubling bifurcation PD and, as shown in the bifurcation diagram of Fig. 12, chaotic dynamics are found not long after. The chaotic behavior is marked by a *crisis* in which two asymmetric chaotic attractors collide at $\mu \approx 4.903$ and merge, forming a symmetric chaotic attractor (a symmetry-increasing bifurcation). The interval over which chaos is observed is relatively short (4.902 $\leq \mu \leq 4.92$), however, and the system is soon attracted to a new branch of $R_1 R_2$ -symmetric periodic orbits created in a saddle-node bifurcation. When, in turn, this $R_1 R_2$ -symmetric branch loses stability, we observe a new branch of stable asymmetric periodic

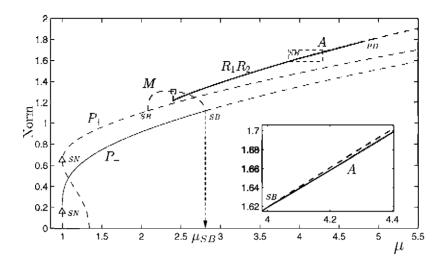


Fig. 11. Case III, corresponding to Fig. 2c. Bifurcation diagram for steady states and periodic orbits, in terms of the Euclidean norm ||(X, Y, v)||and the L_2 norm $||(X, Y, v)||_{L_2}$, respectively, as a function of μ . Thick solid (dashed) lines correspond to stable (unstable) periodic orbits; thin solid (dashed) lines correspond to stable (unstable) steady states. The arrow indicates the location of a subcritical bifurcation on P_- to unstable M. This bifurcation produces a hysteretic transition to stable R_1R_2 -symmetric oscillations that exist between the heteroclinic bifurcation indicated by the symbol \Box and a symmetry-breaking bifurcation labeled SB (inset).

orbits created in a nearby saddle-node bifurcation. This sort of alternating transition between R_1R_2 -symmetric and asymmetric oscillations is repeated again and again. Note also that the chaotic windows associated with these transitions become narrower and narrower as μ increases. In Fig. 13, we show stable attractors associated with three consecutive periodic windows in Fig. 12. These limit cycles are evidently *relaxation oscillations*, but this time involving slow drifts along branches of both equilibria *and* of periodic orbits, with fast jumps between them. Because of their resemblance to bursting in excitable membranes or spiking in neurons we refer to these oscillations as *bursting* or *spiking* as well. In our case, however, the bursting oscillations may be symmetric or asymmetric, with the symmetry alternately present and broken in successive periodic windows. In the following we suggest an explanation for this remarkable behavior adapted from ref. [41].

As in Case II the behavior described above can be understood, at least in part, by considering the nullcline $\Sigma : F_1(X, Y, v; \mu) = F_2(X, Y, v; \mu) = 0$. As indicated in Fig. 14, the projection of Σ onto the (v, Re(X)) plane consists of pairs of branches of stable (S^{\pm}) and unstable (U^{\pm}) states, related by symmetry. However, in Case III Eqs. (42) with $\varepsilon = 0$ also contain a one parameter family of attracting *limit cycles*. These periodic solutions are created, as v increases, in a heteroclinic bifurcation involving the two fixed points U^+ and U^- , and are R_1R_2 -symmetric. Between this heteroclinic bifurcation and the fold points q^{\pm} the stable R_1R_2 -symmetric limit cycles coexist with the stable fixed points S^{\pm} (see Fig. 14). When ε is finite but small these states couple to the slow evolution of the variable v, and the manifolds of steady states and periodic orbits become part of the *slow manifold* of the system (42), cf. [41]. In the following we speak of the solutions as drifting along this manifold (the slow phase); this drift proceeds until the system is forced away from the slow manifold, heralding the onset of the fast phase of the oscillation that takes it back to the slow manifold. The plots in Figs. 13 can be interpreted in this light, with episodes of almost constant Re(X) corresponding to drift along the manifold of steady states S^{\pm} and the return trajectory consisting of a drift along the branch of periodic orbits.

To understand the nature of the oscillations that result we begin by considering the drift along M_S^+ , the part of the slow manifold near the stable steady states S^+ . The drift is in the direction of increasing v and so takes the system towards q^+ (see Fig. 14). Near this point this slow drift ends and the system jumps abruptly to the branch of symmetric periodic states, labeled p. In Fig. 14, this transition is indicated by a vertical short-dashed line, and

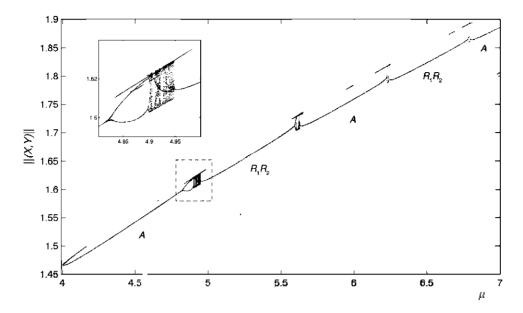


Fig. 12. Case III: bifurcation diagram showing an alternating sequence of R_1R_2 -symmetric (R_1R_2) and asymmetric (A) periodic orbits. The figure is constructed by recording successive maxima of $||(X, Y)|| \equiv \sqrt{||X||^2 + ||Y||^2}$ at each value of μ . The inset shows an enlargement of the first chaotic region. The parameters are as in Fig. 2c.

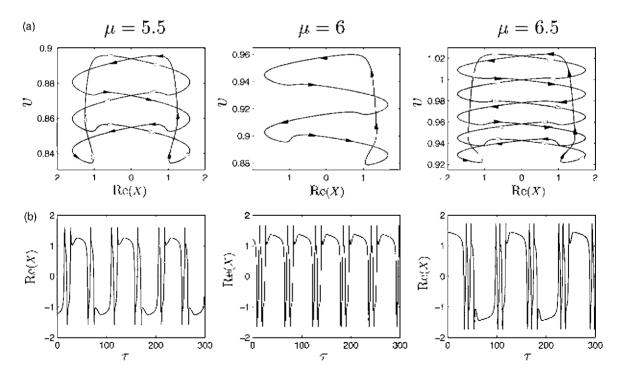


Fig. 13. Case III. (a) Projection onto the ($\operatorname{Re}(X), v$) plane of stable symmetric and asymmetric periodic orbits in successive periodic windows in Fig. 12. (b) The corresponding time series $\operatorname{Re}(X(\tau))$.

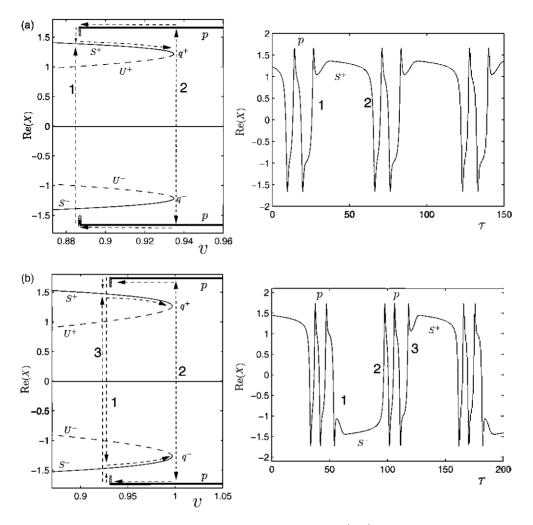


Fig. 14. Case III. The slow manifold for the system (42) lies within $O(\varepsilon)$ of the manifolds S^+ , U^+ of steady states, and the manifold p of periodic orbits, of Eqs. (42) with $\varepsilon = 0$. The slow drifts in v that occur when $0 < \varepsilon \ll 1$ are indicated by broken 'horizontal' arrows; the fast phase results in 'vertical' jumps. These are indicated by vertical arrows, and labeled by integers to indicate the corresponding transition in the associated time series Re($X(\tau)$). (a) Asymmetric relaxation oscillations of Eqs. (42) when $\mu = 6.0$ and $\varepsilon = 0.01$. (b) $R_1 R_2$ -symmetric relaxation oscillations of Eqs. (42) when $\mu = 6.5$ and $\varepsilon = 0.01$.

labeled with the number 2. The system then drifts towards the left along the corresponding slow manifold M_p until it reaches the vicinity of the $\varepsilon = 0$ heteroclinic connection, where the oscillations disappear and so does the associated slow manifold M_p ($0 < \varepsilon \ll 1$). With the disappearance of M_p the system is forced to either jump toward S^+ or toward S^- . Which of these two outcomes takes place is determined by the phase of the trajectory near U^+ or U^- . These states are saddles with one unstable direction and three stable directions; for example, the eigenvalues of U^{\pm} at $\mu = 6.5$ are 0.6547, -0.9999 ± 14.236 and -2.65405. Thus, the least stable eigenvalue is in fact complex, and this is so in the other periodic windows as well. The time series show clearly that when the drift along M_p ends the system approaches either U^+ or U^- along its stable manifold; what happens thereafter depends on which part of its unstable manifold is followed. If the unstable manifold of U^+ (say) takes the system to S^+ (as in Fig. 14a) the fast phase (labeled 1) terminates on S^+ and the system thereafter drifts towards the right along M_S^+ . The resulting

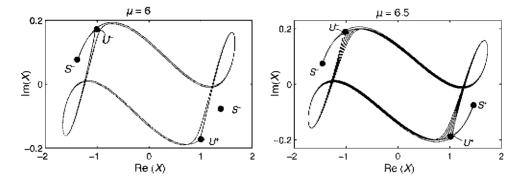


Fig. 15. Case III. Projections of (a) an asymmetric solution at $\mu = 6.0$ and (b) an $R_1 R_2$ -symmetric solution at $\mu = 6.5$ on the (Re(X), Im(X)) plane, both calculated with $\varepsilon = 0.01$, showing the role played by the stable manifold of U^+ in determining the part of the slow stable manifold followed by the solution. The actual trajectory *spirals* around this manifold.

oscillation is an asymmetric relaxation oscillation. In contrast, if the unstable manifold of U^+ takes the system to S^- (cf. Fig. 15) the fast phase terminates on S^- and the system thereafter drifts towards the right along M_S^- . In Fig. 14b, this transition is labeled 1; the accompanying panel shows the corresponding signature in the time series. When the slow phase terminates the system jumps back to the large amplitude periodic state (transition 2) and drifts along it to the left, but this time when it falls off M_p in a transition labeled 3 it goes to U_- and by symmetry follows *its* unstable manifold towards S^+ . The resulting trajectory is R_1R_2 -symmetric. Fig. 15 shows the oscillations of Fig. 13 in a projection that highlights the role of the stable manifold of these unstable steady states as a separatrix between the two slow phases of the relaxation oscillation.

We now turn to the sequence of *transitions* revealed in Fig. 12. The bifurcation diagrams in Fig. 16 shows what happens in all transitions from an asymmetric oscillation to a symmetric one, and from a symmetric one to an asymmetric one, as μ increases, while Fig. 17 shows the *period* of the corresponding solutions, also as a function of μ (boxed regions). Each transition is accompanied by a stability gap within which chaotic dynamics (symmetric and asymmetric) are found, and each new periodic solution emerges out of such a region in a saddle-node bifurcation. Fig. 17 also shows that in each transition the period of the stable oscillation jumps by an approximately constant amount, and subsequently decreases along both the stable and the unstable branches away from the saddle-node bifurcation.

Fig. 18 focuses on a branch of asymmetric relaxation oscillations that first appears in a saddle-node bifurcation near $\mu = 7.0$, and shows that as one follows the stable branch from the saddle-node towards larger μ one encounters an interval of μ in which the period drops precipitously (Fig. 18a, inset). Just after this point the stable (asymmetric) relaxation oscillation loses stability via period-doubling (not shown). Fig. 18b shows the time series at the point marked 3 ($\mu = 7.3118$) just before this loss of stability, and suggests that this loss of stability is a consequence of the fact that the trajectory is beginning to follow the unstable manifold before peeling off towards S^{\pm} . By point 5 ($\mu = 7.5533$) the trajectory follows the unstable manifold U^- all the way to the saddle-node at q^- . For yet larger μ the oscillation remains unstable but the trajectory departs from U^- in the *opposite* direction (see point 6, $\mu = 10.0$). These results indicate that with increasing μ the trajectory comes closer and closer to the hyperbolic steady states U^{\pm} resulting in longer and longer drift along the unstable manifold M_U . This fact also suggests an increasing role for the leading eigenvalues of U^{\pm} . In the present case the least stable eigenvalue λ_s is complex, but the unstable cigenvalue $\lambda_u < |\text{Re}(\lambda_s)|$. Thus no chaotic dynamics are expected. Note that in contrast to Case II in the present case the drift along U^{\pm} is not triggered by a *bifurcation* in the fast system, and so is not the result of a canard.

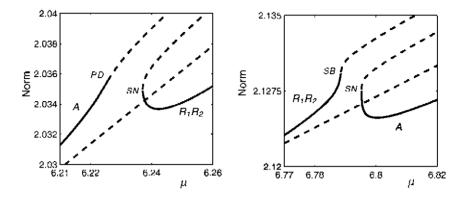


Fig. 16. Case III. Detail of the bifurcation diagrams near the transition from asymmetric to symmetric relaxation oscillations near (a) $\mu = 6.23$, and (b) $\mu = 6.79$. Solid (broken) lines indicate stable (unstable) solutions. The labels SN, SB and PD denote saddle-node, symmetry-breaking and period-doubling bifurcations, respectively. The original (and unstable) oscillations correspond to the straight dashed line and undergo no bifurcations in this regime.

Stable bursting behavior of the type shown in Figs. 13, 14 and 18 becomes increasingly dramatic as μ is increased, revealing ever more clearly the two slow phases and the rapid transition between them. In Fig. 19a, we show a stable oscillation for $\varepsilon = 0.01$ and $\mu = 9.0$ projected onto the $(||(X, Y)|| \equiv \sqrt{||X||^2 + ||Y||^2}, v)$ plane, cf. Fig. 14, and superposed on the slow manifold computed with $\varepsilon = 0$. We see that during one part of the slow

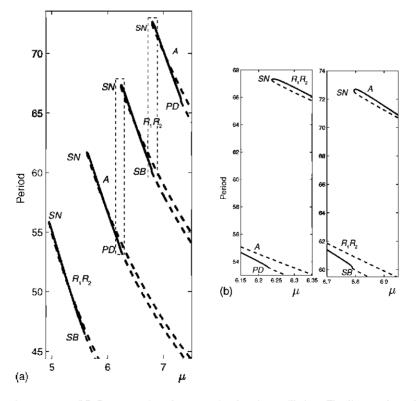


Fig. 17. Case III. Alternating sequence of R_1R_2 -symmetric and asymmetric relaxation oscillations. The diagram shows the period (half-period) of asymmetric (symmetric) periodic relaxation oscillations as a function of μ . Solid (dashed) line corresponds to stable (unstable) states. The labels SN, SB and PD denote saddle-node, symmetry-breaking and period-doubling bifurcations, respectively.

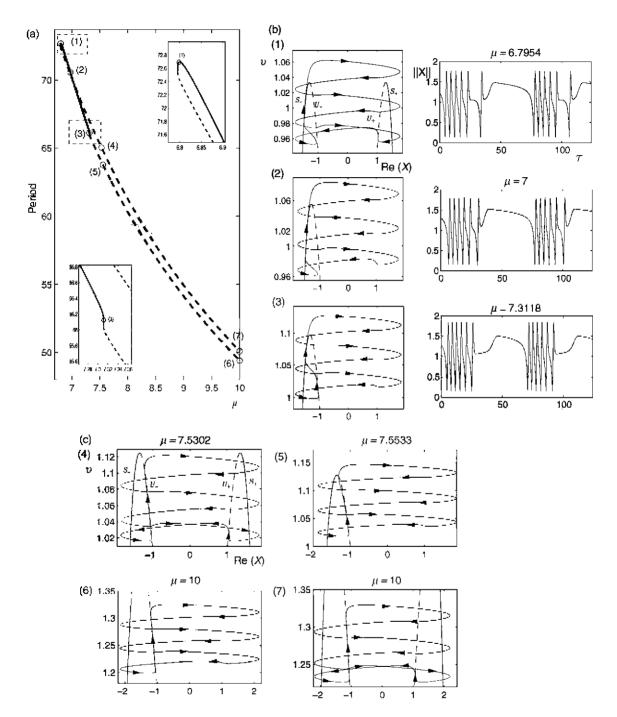


Fig. 18. Case III. (a) Period of asymmetric relaxation oscillations as a function of μ . Solid (dashed) lines correspond to stable (unstable) states. (b) Stable relaxation oscillations corresponding to the open circles (1–3) in figure (a) projected on the (Re(X), v) plane together with the corresponding time series $||X(\tau)||$. (c) Unstable relaxation oscillations corresponding to the remaining open circles (4–7) in figure (a) in the same projection.

phase (labeled 1) the system drifts towards smaller v along the slow manifold M_p of stable periodic solutions p. Near the heteroclinic connection in the fast system the oscillations end and the system undergoes a rapid transition to the stable manifold M_S indicated by a vertical arrow. Thereafter it enters a new slow phase, labeled 2, and drifts in the direction of increasing v, towards the fold point q, where the slow phase ends and the system makes a rapid transition back to M_p . This transition is also indicated by a vertical arrow. The small cusp-like feature at the onset of phase 2 results from a brief visit of the trajectory near the unstable slow manifold M_{U} , before being ejected towards the stable slow manifold M_S . As μ increases and the next symmetry-switching transition is approached the solutions spend more and more time near M_U , and hence involve longer and longer episodes of drift along M_{U} . Fig. 19b and c show two examples of this behavior, differing only slightly in the value of μ . In the first of these the system drops to the unstable steady state at the end of the slow phase 1, and then drifts along M_U towards larger v before a sudden jump to M_S . The slow drift continues along M_S towards the fold on Σ where the system jumps to the oscillatory state p, and the slow phase 1 recommences. In contrast, the solution in Fig. 19c jumps from M_U to M_p (instead of M_S) and so begins to drift towards smaller v but the next time, instead of following M_U , it jumps to M_S and begins to follow the standard relaxation oscillation scenario. The remarkable sensitivity to the value of μ is evidently a consequence of the amplification of small differences in the approach of the trajectory towards M_U by the unstable eigenvalue of U, and heralds the transition from asymmetric oscillations to symmetric ones: in effect, with each half-turn around U^{\pm} the trajectory changes the direction in which it leaves U^{\pm} , and hence its symmetry. In addition its period jumps by a finite amount, a phenomenon we have already noted. When the number of turns increases monotonically with μ there will be an infinite sequence of symmetry-changing transitions, and hence a sequence of periodic windows with alternating symmetric and asymmetric relaxation oscillations. Thus each saddle-node bifurcation creates a pair of periodic orbits with an extra half-turn. Moreover, since it takes a finite interval in μ to change the frequency sufficiently to add a halfturn these symmetry-changing transitions cannot accumulate, in contrast to the cascades of symmetry-switching gluing bifurcations that occur in other D_2 -symmetric systems [21]. As documented above this is the case for the parameters of Case III; for other choices such as Case II with $0.35 \le \gamma < 0.4$ (not shown) the number of transitions is finite.

4.4. Case IV: Delayed loss of stability and chaos

Case IV is quite complex because of the proximity to the saddle-node bifurcation on the P_+ branch of two other bifurcations, the symmetry-breaking Hopf and steady state bifurcations H and SB, respectively. The former interaction, i.e., saddle-node/Hopf, is responsible for the properties of the oscillations created at the Hopf bifurcation. This codimension-two bifurcation is much studied [19,46] and its unfolding corresponding to Fig. 2d confirms not only the presence of a branch of oscillatory solutions that bifurcates towards larger μ but also shows that this branch must be initially unstable before acquiring stability in a tertiary torus bifurcation. This theoretical prediction is confirmed in Fig. 20a where the torus bifurcation is labeled TR ($\mu \approx 1.00136$). The figure shows, however, that the interval in which the periodic oscillations (thick line) are stable is quite narrow, and that these oscillations lose stability at larger μ at a second torus bifurcation ($\mu = 1.0083$). We presume that this loss of stability is a consequence of the proximity of these parameter values to the second codimension-two interaction: the saddle-node/pitchfork bifurcation. Indeed, Fig. 20a shows that the periodic oscillations eventually become stable again (at a third torus bifurcation) before transferring stability, via a Hopf bifurcation, to the mixed modes M created at SB. This Hopf bifurcation is in turn found in the appropriate unfolding of the saddle-node/pitchfork interaction.

It is important to emphasize that the oscillations created in the Hopf bifurcations on the P_+ and M branches have distinct symmetry properties. The former are R_1 -symmetric and disappear in a gluing bifurcation at $\mu = \mu_g \approx 1.03$ involving the larger amplitude P_+ state. The latter produces a pair of asymmetric oscillations, which glue together as μ approaches μ_g from above (see Fig. 20a). There are therefore two possible sources of complex behavior in this parameter regime, the first associated with the global bifurcation at $\mu = \mu_g$, and the second associated with

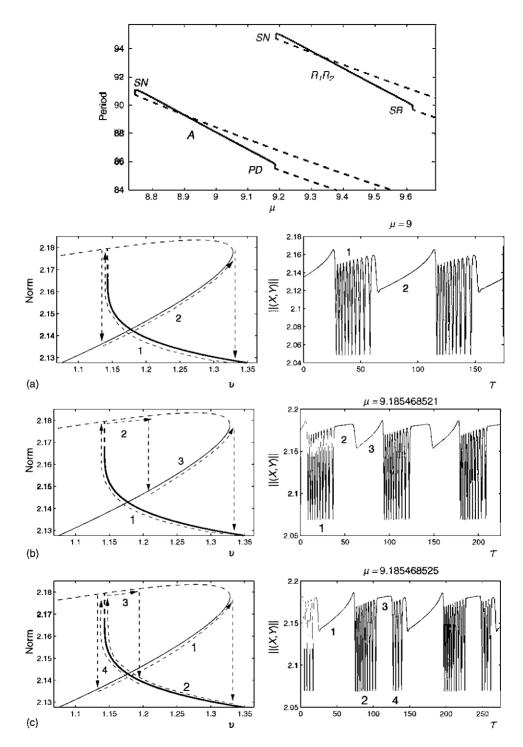


Fig. 19. Case III. Stable asymmetric relaxation oscillations for (a) $\mu = 9$, (b) $\mu = 9.185468521$ and (c) $\mu = 9.185468525$. The top panel shows the location of these solutions in a period vs. μ plot (Fig. 17). The slow drifts, present when $0 < \varepsilon \ll 1$, are labeled with numbers to indicate the corresponding phase in the accompanying time series ||(X, Y)||, computed from Eqs. (42) with $\varepsilon = 0.01$. The arrows indicate the direction of drift as well as the fast transitions.

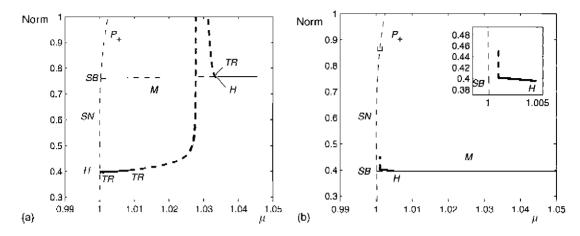


Fig. 20. Case IV, corresponding to Fig. 2d for (a) $\gamma = -0.35$ (mean flow included) and (b) $\gamma = 0$ (mean flow absent). This solid (dashed) lines correspond to stable (unstable) steady states. Thick solid (dashed) lines correspond to branches of stable (unstable) periodic orbits generated in Hopf bifurcations on P_{\perp} and M, indicated by the letter H. Saddle-node, symmetry-breaking pitchfork and torus bifurcations are indicated by SN, SB and TR, respectively. In (b) the symbol \square indicates the homoelinic global bifurcation where the branch of periodics orbits, created at H, terminates. Note the rapid growth in the oscillation amplitude (inset) as this point is approached, cf. [35].

the termination of the torus branches. The former is not directly responsible for the observed chaotic dynamics (see below) since the eigenvalues of P_+ at μ_g are real, and the leading unstable eigenvalue is smaller than the (magnitude of the) leading stable one. Analysis of the saddle-node/Hopf interaction shows that the associated torus branch terminates in general in a global bifurcation as well. As shown by Guckenheimer [17] and in more detail by Kirk [24,25] this bifurcation is generically associated with thin wedges of chaotic behavior. We expect this type of behavior at the end of the first torus branch, and similar behavior may be associated with the torus branches created when the various periodic oscillations identified below lose stability as well. Fig. 20b shows that when the coupling to the mean flow is omitted the behavior of the system simplifies dramatically. However, despite the differences in behavior summarized in Fig. 20a and b there is clear correspondence between the two figures. This correspondence is a consequence of both the small value of ε which is responsible for replacing the steady states M in Fig. 20b by slowly drifting states that form the slow phase of the oscillations. This correspondence is explored in greater depth below.

In Fig. 21a, we show a two-frequency attractor obtained at $\mu = 1.0005$, that is, immediately after the trivial state becomes unstable ($\mu_0 = 1.00045$), with the mean flow included (Fig. 20a). Fig. 22a shows the corresponding time series. This attractor appears to describe oscillations about the small amplitude R_1 -symmetric oscillation created at the Hopf bifurcation on the P_+ branch. The absence of exact R_1 symmetry suggests that this attractor is related to the symmetry-breaking torus bifurcation at $\mu \approx 1.00136$. This bifurcation appears to be supercritical, producing stable two-frequency oscillations in $\mu \leq 1.00136$. These are initially almost R_1 -symmetric but grow increasingly asymmetric as μ decreases. The R_1 -symmetric oscillations undergo a second torus bifurcation at $\mu \approx 1.0083$ but this time the bifurcation is subcritical, i.e., the resulting two-frequency oscillations are present in $\mu < 1.0083$ but are now unstable. However, Fig. 23 shows that this observation only scratches the surface of the complexity that is present in this parameter regime. In addition to the R_1 -symmetric oscillations just mentioned (Fig. 20 and lowest curve in Fig. 23) there is a large number of *additional* branches of R_1 -symmetric oscillations, four of which are included in the figure. These are labeled (a–d) and are stable near minimum period (solid lines) and unstable elsewhere (dashed lines). Fig. 24 shows the projections of these stable oscillations in four cases, one from each branch. It is clear that the oscillations corresponding to the different branches differ in the number of revolutions

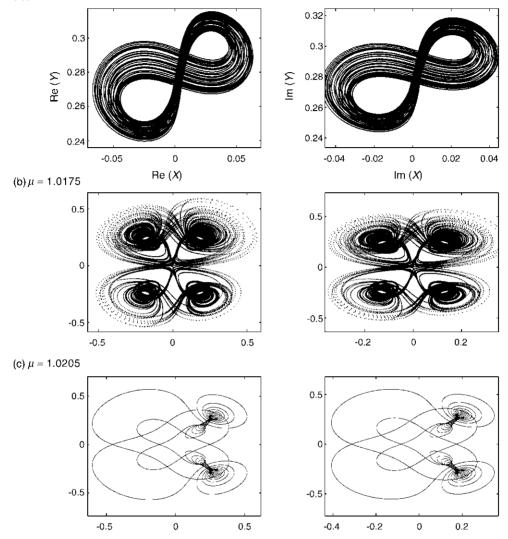


Fig. 21. Case IV. Stable attractors of Eqs. (26)–(28) for the parameters in Fig. 2d. (a) A torus at $\mu = 1.0005$. (b) A chaotic attractor at $\mu = 1.0175$. (c) A R_2 -symmetric periodic orbit at $\mu = 1.0205$.

about the two mixed modes M^{\pm} , and that multiple stable oscillations are present simultaneously. However, in all cases the oscillation period is of order $1/\varepsilon$ as expected of relaxation oscillations. The torus bifurcations at which these oscillations acquire stability with increasing μ may be responsible for the presence of chaotic oscillations in this regime, such as that shown in Figs. 21b and 22b, but the details of this process are beyond the scope of the present paper.

The behavior reported in Fig. 24 is also a consequence of the two distinct slow time scales present in the problem, i.e., of the small value of the parameter ε . The set Σ of equilibria of Eqs. (42) with $\varepsilon = 0$, given by $F_1(X, Y; v, \mu) = F_2(X, Y; v, \mu) = 0$, consists of symmetry-related stable (S^{\pm}) and unstable (U^{\pm}) steady states. Of these the S^{\pm} are created in pitchfork bifurcations from the trivial state as |v| decreases. The S^{\pm} states lose

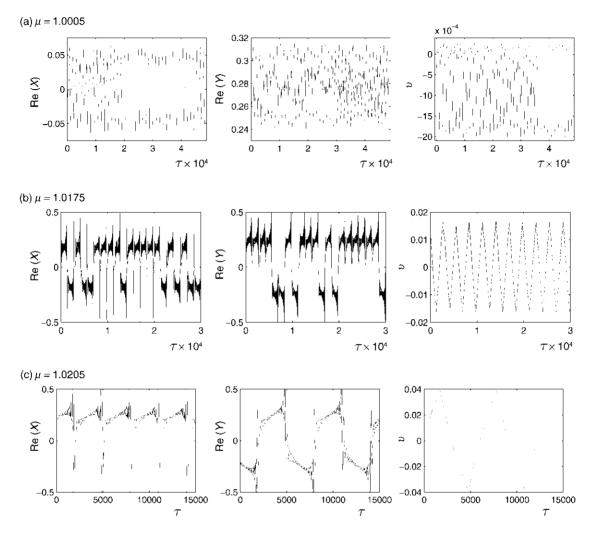


Fig. 22. Case IV. Time series corresponding to the attractors in Fig. 21.

stability via subcritical Hopf bifurcations at h^{\pm} and turn into U^{\pm} (see Fig. 25). The branches of periodic oscillations p created in these Hopf bifurcations are always unstable and terminate in a homoclinic connection to an R_1 -symmetric fixed point U_0 . When $\mu = 1.01185 \ U_0 = (0, 0, 1.025, 0.87303)$ and its eigenvalues are real: 0.458, -0.054, -1.945 and -2.458. The eigenvectors of the two leading eigenvalues are $V_u = (0.8454, 0.5341, 0, 0)$ and $V_s = (0.7458, 0.4389, 0, 0)$. The global bifurcation at U_0 is therefore a standard 'figure eight' gluing bifurcation with no associated chaos; its presence does not appear to be relevant for the dynamics shown in Fig. 24. Rather, the observed behavior appears to be a consequence of the fact that all four eigenvalues of S^{\pm} are *complex*. When $0 < \varepsilon \ll 1$ the solutions of Eqs. (42) drift slowly along the attracting slow manifolds M_S^{\pm} associated with S^{\pm} ; this drift is in the direction of increasing v for M_S^{-} and decreasing v for M_S^{+} . As in Case III, when ε is sufficiently small the fast motion undergoes a delayed loss of stability (cf. [2]), although this time no global bifurcation is involved. This behavior can be seen clearly in Fig. 26, computed for $\varepsilon = 0.0001$: the trajectory moves slowly along M_S^{-} , passes through a Hopf bifurcation (in the fast system) at h^{-} , and continues along the unstable manifold M_U^{-} for a

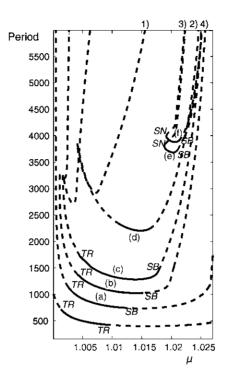


Fig. 23. Case IV. The period of several branches of periodic oscillations as a function of μ when $\varepsilon = 0.001$. The branches (a d) are R_1 -symmetric, while (e and f) are R_2 -symmetric. Solid (dashed) lines indicate stable (unstable) solutions. Saddle-node, symmetry-breaking pitchfork and torus bifurcations are indicated by SN, SB and TR, respectively.

time of order $1/\varepsilon$. The trajectory then spirals away from M_U^- and towards M_S^+ . Once it is sufficiently close to M_S^+ the same process repeats, but this time with v decreasing. As shown in Fig. 27 the drift along the slow manifolds M_S^{\pm} and M_U^{\pm} is faster at larger values of ε . With less time to approach M_S^{\pm} the oscillations appear less and less "damped" and the orbits begin to resemble those in Fig. 24.

The above point of view also permits us to understand the origin of the prominent cusp-like feature that develops on the higher branches of oscillatory states as μ decreases (Fig. 23). This structure is not due to an incipient global bifurcation. Instead what appears to be happening is the following. As μ decreases the real part λ of the unstable eigenvalue at the detachment point also decreases, implying a longer oscillation period. At the same time the Hopf frequency ω at h^- also decreases. For the transition from U^- to S^+ one must make at least half a turn around U^- before detachment, otherwise the trajectory ends up on the large amplitude U^- state (see Fig. 25). This change in the type of oscillation becomes inevitable once ω/π falls below λ . Numerically we find that this condition is quite accurately satisfied at the tip of the cusp, while before the cusp is reached (i.e., for larger values of μ) $\lambda \lesssim \omega/\pi$. After the cusp the unstable two-dimensional manifold of U^- starts to veer away from the stable manifold of S^+ and begins to approach the three-dimensional stable manifold of the large amplitude $U^$ state. As this happens the period drops slightly but the oscillation amplitude starts to increase. Fig. 28 shows the oscillations on either side of the (secondary) minimum in the period along branch (d) in Fig. 23. Thereafter the period increases rapidly as the trajectory spends more and more time drifting along the slow manifold associated with the large amplitude unstable state U^- instead of the stable small amplitude state S^+ , thereby acquiring an altogether different appearance. On the left each branch eventually terminates in a homoclinic connection to the pure mode P_+ contained in the slow manifold of U^- (see Fig. 29, panel 1), while on the right it terminates

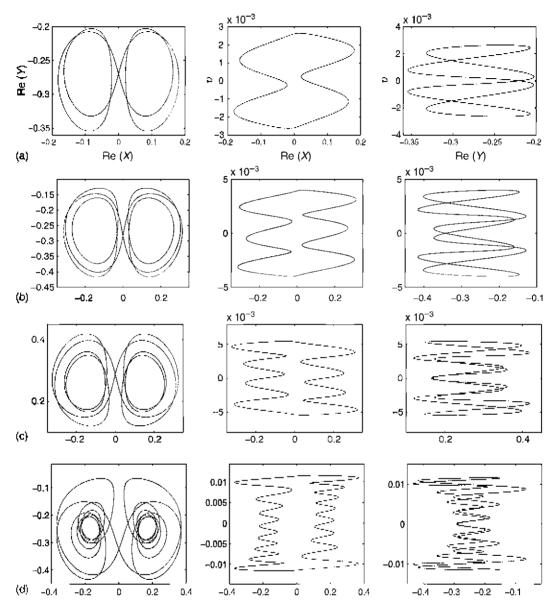


Fig. 24. Case IV. Examples of stable R_1 -symmetric oscillations on the branches (a–d) in Fig. 23 at $\mu = 1.01185$.

in a homoclinic connection to the origin (see Fig. 29, panel 2). Except for the complications arising from the presence of reflection symmetry much of the above phenomenology resembles that studied recently by Krauskopf and Wieczorek [26] and attributed to a nearby saddle-node/Hopf bifurcation with no stable fixed points [47], cf. Fig. 20a.

Fig. 23 also shows two branches of R_2 -symmetric oscillations labeled (c and f). These are also stable near minimum period; a stable R_2 -symmetric oscillation on branch (e) is illustrated in Figs. 21c and 22c. This type of solution can be described in an analogous manner to the R_1 -symmetric orbits on branches (a–d) discussed above.

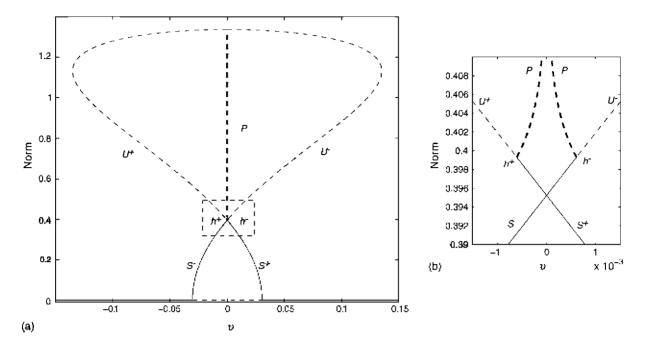


Fig. 25. Case IV. (a) Bifurcation diagram for Eqs. (42) showing the norm ||(X, Y)|| as a function of v when $\mu = 1.01185$ and $\varepsilon = 0$. Thick dashed lines indicate branches of periodic orbits generated in Hopf bifurcations at h^{\pm} . Thin solid (dashed) lines indicate stable (unstable) steady states. The remaining parameters are as in Fig. 21. (b) Detail of the bifurcation diagram in (a).

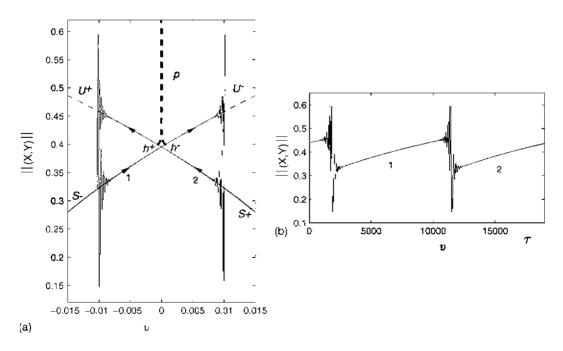


Fig. 26. Case IV. (a) Stable relaxation oscillation computed from Eqs. (42) when $\mu = 1.01185$, $\varepsilon = 0.0001$, projected onto the (v, ||(X, Y)||) plane. (b) The corresponding time series $||X(\tau), Y(\tau)||$. The remaining parameters are as in Fig. 21.

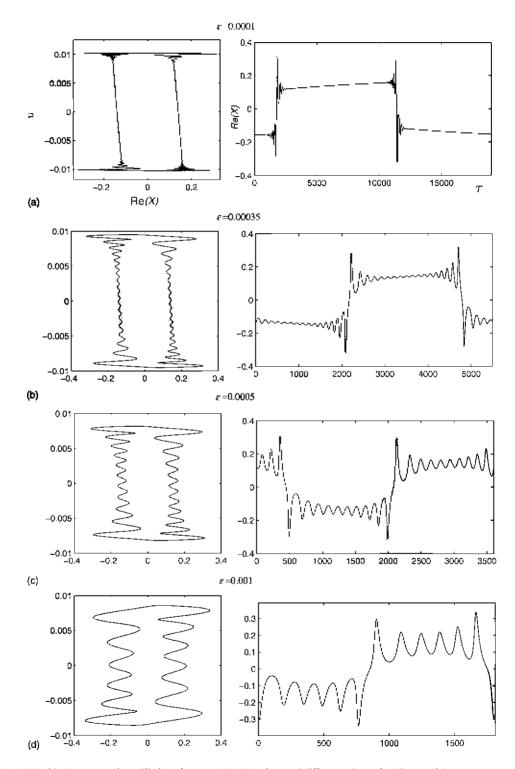


Fig. 27. Case IV. Stable R_1 -symmetric oscillations for $\mu = 1.01185$ and several different values of ε . The remaining parameters are as in Fig. 21. In each case the time series (right column) show a single period only. Note that (d) corresponds to a branch omitted from Fig. 23.

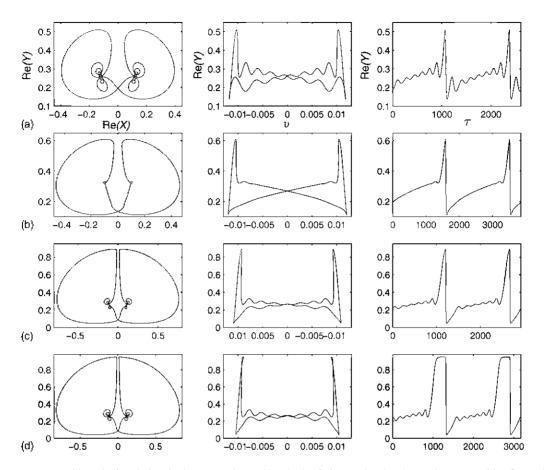


Fig. 28. Case IV. Unstable periodic solutions in the cusp region on branch (d) of Fig. 23, showing the continuous transition from relaxation oscillations involving the states S^+ to oscillations involving the large amplitude states U^- . (a) $\mu = 1.008389$, near minimum period, (b) $\mu = 1.004072$, near the tip of the cusp, (c) $\mu = 1.00733$, near the secondary minimum, (d) $\mu = 1.00844$, to the right of the secondary minimum.

The divergence of the oscillation period with both increasing and decreasing μ indicates that *all* of these branches appear and disappear through global bifurcations (see Fig. 23). To identify these we show in Figs. 29 and 30 high period unstable oscillations on the (d) and (f) branches, one near the initial appearance of each branch and one near its end. In contrast to the (d) branch the (f) branch originates and terminates in global bifurcations involving the origin and the steady states $\pm P_{\pm}$. However, despite the appearance of Figs. 29 and 30, no heteroclinic connection to a periodic orbit actually occurs. In fact the observed behavior appears to be organized by codimension-two points corresponding to connections between the steady states P_{\pm} and the origin. The figures suggest, and computations confirm, that all the eigenvalues of the fixed points involved are real. However, a more detailed understanding of this remarkable behavior along the lines of refs. [23,21], or indeed in terms of the theory of slow-fast systems, is beyond the scope of this paper.

It is clear that in Case IV the system (26)–(28) exhibits multiple coexisting stable states, some periodic (see Fig. 23), others quasiperiodic or chaotic (see Fig. 21). The latter are readily located between the symmetry-breaking bifurcation on branch (c) and the saddle-node bifurcation on branch (c), and exist on either side of $\mu = 1.017$. Since we do not follow unstable tori we cannot identify the transitions that might lead from the various two-frequency states to the observed stable chaotic oscillations. It is likely, however, that each of the periodic oscillations depicted

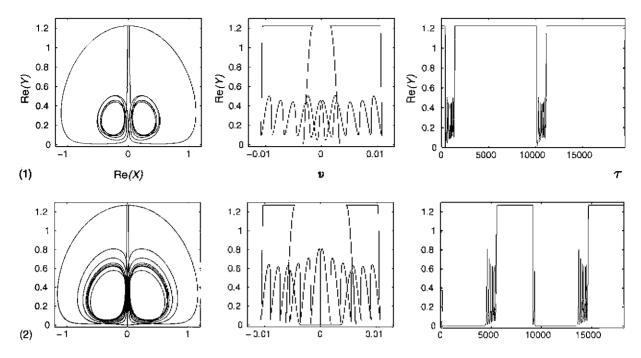


Fig. 29. Case IV. Examples of large period unstable R_1 -symmetric oscillations on branch (d) at the locations indicated in Fig. 23. (1) $\mu = 1.0230$, (2) $\mu = 1.0258$.

in Fig. 24 bifurcates into chaos, and hence that the example in Fig. 21b is but one from a number of coexisting intervals of chaos, cf. [26].

5. Discussion and conclusions

In this paper we have examined the dynamics of parametrically driven Faraday waves in slightly elliptical containers on the assumption that (i) the viscosity of the liquid is small (as measured by the dimensionless quantity $C_g \ll 1$) and (ii) the effective Reynolds number Re of the streaming flow driven in oscillatory boundary layers (defined in Eq. (3)) is also small. Under these conditions we were able to replace the Navier–Stokes-like equation for the mean flow by a single ordinary differential equation, and focused on the interesting case $0 < e \ll 1$. The mean flow is then only weakly damped, and the resulting equations take the form of a *singularly* perturbed system. Although the condition for this to be the case, $\lambda_1 Re^{-1} \ll 1$, provides a competing constraint on the Reynolds number, the two requirements are not in contradiction. This is because the small hydrodynamic eigenvalue λ_1 depends on the aspect ratio R of the cylinder and will be small when R is large. The approach we have taken focuses on the role played by the coupling to the streaming flow, but does not attempt to make quantitative predictions for the Faraday system under experimental conditions. Specific applications require the computation of the coupling coefficients α_1 , α_2 for appropriate meniscus boundary conditions. These remain to be done. For this reason we have chosen to treat Eqs. (26)–(28) as a model system that captures the dominant effects of the coupling to the streaming flow, with γ as a free parameter, for fixed detuning Γ and ellipticity A. We have

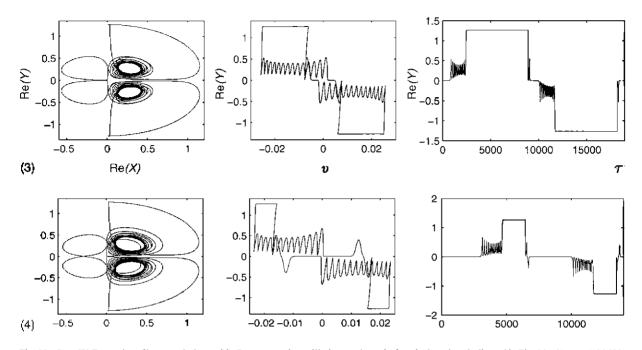


Fig. 30. Case IV. Examples of large period unstable R_2 -symmetric oscillations on branch (f) at the locations indicated in Fig. 23. (3) $\mu = 1.02632$, (4) $\mu = 1.02680$.

seen that the broken circular symmetry of the system ($A \neq 0$) destroys the one-parameter family of standing waves present in a circular container, selecting two standing waves from this family, with slightly different frequencies and thresholds. As in other problems of this type [36] this results in the competition between two almost degenerate modes, and such interaction often leads to complex dynamics.

We have focused on four distinct cases, three of which were computed for the coefficients α_1 , α_2 obtained by Miles for a free contact line [34]. In each of these linear stability theory indicated the absence of any stable steady states, i.e., the presence of regions in parameter space in which the pure and mixed modes are all unstable. In the first case we found very simple dynamics, organised by a gluing bifurcation of a standard kind, but no chaos. Cases II and III are of greater interest. When ε is small both these cases exhibit relaxation oscillations with multiple time scales. In Case II these oscillations involved fast transitions between slowly varying steady states called mixed modes, corresponding to periodic standing waves. In the original Faraday system this type of oscillation corresponds to a quasiperiodic mode of oscillation of the system with two quite distinct frequencies. In Case III we located relaxation oscillations of a more complex kind. Here the slow manifold of the amplitude equations is composed of both equilibria and (symmetric) periodic oscillations, and the resulting time series (Fig. 19a) appear indistinguishable from the type of (so-called parabolic) bursting behavior exhibited by neurons [44], even though it involves visits to saddle-foci. In the Faraday system, the periodic oscillations correspond to mixed mode oscillations in which the contribution of the two orthogonal standing waves oscillates periodically in time (as does their relative phase), and the relaxation oscillations found are oscillations between this complex state and a pure mode standing wave. However, in both cases the basic picture is simple: the system drifts along the slow manifold until it passes a bifurcation, typically a saddle-node bifurcation, where it is forced away from the slow manifold. The resulting fast phase then takes it to another part of the slow manifold and the process repeats. In our system we have seen that oscillations of this type occur when the streaming flow is weakly damped. As a result the streaming flow behaves as a slowly varying parameter, and the system drifts along the slow manifold computed by 'freezing' the mean flow.

In our system we encountered two twists on this well-known picture. The first centered on the presence of the two reflection symmetries in Eqs. (26)-(28) which permit the presence of periodic oscillations with different types of symmetry: these can in turn undergo symmetry-breaking or symmetry-switching bifurcations. The second centered on the presence of canard explosions characterized by an abrupt change in the amplitude (and in our case symmetry as well) of a periodic orbit. Fig. 6a and b shows an example of each of these orbits in Case II, computed at almost the same value of the parameter μ . The figure shows clearly the dramatic change in the oscillation amplitude as μ passes through the canard at $\mu = \mu_e$. We were able to demonstrate that the canard in Case II is linked to a subcritical Hopf bifurcation, and established a link between canards and global bifurcations. In particular we argued that there must exist an exponentially small neighborhood of the canard parameter value μ_{\circ} in which the canard is 'unfolded' by any finite value of the small parameter ε , thereby restoring the behavior expected of a global bifurcation. It is this exponential sensitivity to the exact value of μ that is responsible for the explosive nature of the canard phenomenon [11.2]. In case III we found a whole variety of bursting solutions, characterized by slow drifts along branches of both stable and unstable equilibria and of periodic states, separated by fast transitions between them. Here we located an apparently infinite sequence of hysteretic transitions between asymmetric and $R_1 R_2$ -symmetric oscillations occurring in ever narrower intervals in μ as μ increases. Much of this behavior could be understood by studying the trajectory near the point of closest approach to the unstable saddles U^{\pm} , and the global behavior of their stable and unstable manifolds, which is in turn inherited from the heteroclinic connection that destroys the oscillations in the fast system. In particular, we saw that the change of symmetry between successive periodic windows is due to an extra half-turn of the trajectory around the unstable steady states as μ increases. This point of view allowed us to understand why the intervening chaotic intervals become narrower with increasing μ but the 'symmetry-switching' transitions do not accumulate at a finite value of μ , in contrast to the cascades of symmetry-switching gluing bifurcations that occur in other D_2 -symmetric systems [21].

In Case IV we saw that the primary pure mode branch bifurcates subcritically before turning around towards larger μ . By moving the Hopf bifurcation to direction-reversing waves below this saddle-node bifurcation we made sure that the branch of pure modes P_+ remains unstable above the saddle-node bifurcation. In this case the directionreversing waves created in the Hopf bifurcation must also be initially unstable, and only acquire stability at larger μ at a torus bifurcation. When this bifurcation is supercritical the resulting torus branch bifurcates towards *smaller* values of μ and is at least initially stable. The branch terminates in a global bifurcation involving the pure modes and this bifurcation is typically associated with chaos [17.24,25]. Thus, in this instance the primary bifurcation gives rise to either chaotic or quasiperiodic oscillations even though it is a steady state bifurcation. The same mechanism has been seen in other systems, and is responsible for the presence of chaos at onset of natural doubly diffusive convection [7] and for the presence of a three-frequency state called a *repeated transient* at onset of binary fluid convection [6]. However, a more detailed look at this case revealed a plethora of additional branches of periodic orbits, which start and end in global bifurcations, and acquire stability through torus bifurcations. These periodic orbits have a highly unusual appearance which we have traced to the separation between the time scales for the evolution of the waves and of the mean flow, specifically the requirement $0 < \varepsilon \ll (\Gamma - A)^2 \sim 10^{-3}$. In particular, we found that the unusual appearance of the oscillations is the consequence of delayed loss of stability that occurs as a result of a slow passage through a Hopf bifurcation in a system with symmetry. Theory (cf. [2]) shows that the delay lasts for a time of order $1/\varepsilon$; during this time the solution drifts along the unstable manifold of equilibria, much as in a canard, although the resulting behavior is not canard-like and in particular has quite different dependence on the parameters μ and ε . Note that since the Hopf bifurcations are subcritical the unstable periodic orbits created at the bifurcation are not involved in this behavior, cf. [20].

The present system differs in an important aspect from the most familiar systems exhibiting canards in having a pair of reflection symmetries. These symmetries have an important effect on the transitions, and in particular one can have canards on branches of symmetric oscillations as well as nonsymmetric ones. Related behavior is present when two identical oscillators are symmetrically coupled. The resulting system can undergo relaxation oscillations with both oscillators oscillating in phase (a symmetric oscillation) or exactly out of phase (an asymmetric oscillation).

Examples include coupled neurons [18] and coupled continuously stirred tank reactors [4,5], but the transition between these two oscillation types has not hitherto been systematically investigated. This is an interesting topic for future investigation.

The results of this paper demonstrate that the inclusion of the streaming flow in the amplitude equations describing Faraday waves in a nearly circular domain has dramatic consequences for the range of available dynamical behavior. In particular, its presence is responsible for relaxation oscillations, an unusual phenomenon in fluid dynamics, and one that could be confirmed in experiments. Of the four cases considered, Case IV is closest to the conditions required for the validity of Eqs. (26)–(28) since both Γ and A are small, and the magnitude of the streaming flow remains small as well. Yet despite this its effects remain dramatic (cf. Fig. 20). In forthcoming work, we shall examine these transitions in greater detail, and shall explore the analogues of this behavior in the partial differential Eqs. (1)–(6) as well.

Acknowledgements

This work was supported in part by EPSRC grant GR/R52879/01 and by an EPSRC visitor grant at Leeds University (MH). Partial support from the NASA Microgravity Sciences Program under grants NAG3-2152 and NNC04GA47G is also gratefully acknowledged. We thank J. Guckenheimer, M. Krupa, J. Moehlis, J. Porter and M. Wechselberger for several helpful discussions.

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