

## MTNS 2016 - extended abstract

## On periodically time-varying convolutional codes

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## I. EXTENDED ABSTRACT

Convolutional codes [4] are an important type of error correcting codes that can be represented as a time-invariant discrete linear system over a finite field [8]. They are used to achieve reliable data transfer, for instance, in mobile communications, digital video and satellite communications [9]. In particular, periodically time-varying convolutional codes have attracted the attention of several researchers [2], [3]. One of the advantages of this type of codes is that they can have better distance properties than the best time-invariant convolutional code of the same rate and total encoder memory [7].

In this work we consider convolutional codes  $\mathcal{C}$  with  $P$ -periodic encoders, i.e.:

$$\mathcal{C} := \{w : w(Pl + t) = (G^t(D)u)(Pl + t); \\ t = 0, \dots, P - 1; l = 0, 1, \dots\}, \quad (1)$$

where each  $G^t(D)$  is a  $n \times k$  polynomial matrix over a finite field  $\mathbb{F}$ , i.e.,  $G^t(D) \in \mathbb{F}^{n \times k}[D]$ ,  $D$  represents the shift  $Du(l) = u(l - 1)$ , and  $u$  is an information sequence in  $\mathbb{F}^k$ .

Inspired by the ideas developed in [6] and [1] for the case of behaviors, considering the linear map

$$L_p : (\mathbb{R}^n)^{\mathbb{Z}} \rightarrow (\mathbb{R}^{Pn})^{\mathbb{Z}}$$

defined by

$$(L_p w)(l) := \begin{bmatrix} w(Pl) \\ w(Pl + 1) \\ \vdots \\ w(Pl + P - 1) \end{bmatrix}, \quad P \in \mathbb{N}$$

we associate with  $\mathcal{C}$  a time-invariant convolutional code  $\mathcal{C}^L$ , the “lifted” version of  $\mathcal{C}$ , defined as

$$\mathcal{C}^L := \left\{ \tilde{w} \in (\mathbb{R}^{Pn})^{\mathbb{Z}} \mid \tilde{w} = L_p w, w \in \mathcal{C} \right\}.$$

Note that, since

$$(G^t(D)u)(Pl + t) = ((D^{-t}G^t(D))u)(Pl),$$

Equation (1) can also be written as

$$(\Omega_{P,n}(D)w)(Pl) = (G(D)u)(Pl), l = 0, 1, \dots,$$

with

$$\Omega_{P,n}(D) = \begin{bmatrix} I_n \\ D^{-1}I_n \\ \vdots \\ D^{-P+1}I_n \end{bmatrix}$$

and

$$G(D) = \begin{bmatrix} G^0(D) \\ D^{-1}G^1(D) \\ \vdots \\ D^{-P+1}G^{P-1}(D) \end{bmatrix} \in \mathbb{R}^{Pn \times k}.$$

Moreover, by decomposing the matrix  $G$  as

$$G(D) = G^L(D^P) \Omega_{P,n}(D)$$

with

$$G^L(D) = [G^{L_0}(D) \quad G^{L_1}(D) \quad \dots \quad G^{L_{P-1}}(D)],$$

the lifted code can be represented as

$$\mathcal{C}^L := \left\{ \tilde{w} : \tilde{w}(l) = (G^L(D)\tilde{u})(l), l = 0, 1, \dots \right\},$$

where  $\tilde{w} = L_p w$  and  $\tilde{u} = L_p u$ .

In the sequel, we consider convolutional codes  $\mathcal{C}$  with 2-periodic encoders, i.e., such  $P = 2$  and

$$G^t(D) = G_0^t + G_1^t D + \dots + G_N^t D^N \in \mathbb{F}^{n \times k}[D], \quad t = 0, 1.$$

Moreover we assume that the matrices  $G_0^0, G_0^1, G_N^0$  and  $G_N^1$  are full column rank. This implies that the matrices  $G^t(D)$  are column reduced (see [5] for a definition),  $t = 0, 1$ . Assuming also that  $G^t(D)$  are right-prime,  $t = 0, 1$ , we have that  $G^t(D)$  are minimal encoders,  $t = 0, 1$  [4]. Minimal encoders are particularly important since their McMillan degrees correspond to the code degree, which is a measure of its complexity.

The parameters of the encoders  $G^t$ ,  $t = 0, 1$ , are  $(n, k, \delta)$ , where  $\delta = kN$  is the degree of the code  $\mathcal{C}^t$  generated by  $G^t(D)$ .

The generalized Singleton bound for each code  $\mathcal{C}^t$  is

$$\begin{aligned} & (n - k) \left( \left\lfloor \frac{\delta}{k} \right\rfloor + 1 \right) + \delta + 1 \\ &= (n - k) \left( \left\lfloor \frac{kN}{k} \right\rfloor + 1 \right) + kN + 1 \\ &= nN + n - k + 1. \end{aligned} \quad (2)$$

By definition,

$$\begin{aligned} G^0(D) &= G_0^0 + G_1^0 D + \dots + G_N^0 D^N + 0D^{N+1} \\ DG^1(D) &= 0 + G_0^1 D + G_1^1 D^2 + \dots + \\ & \quad G_{N-1}^1 D^N + G_N^1 D^{N+1} \end{aligned}$$

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which can be decomposed as

$$\begin{aligned} \begin{bmatrix} G^0(D) \\ DG^1(D) \end{bmatrix} &= \left( \begin{bmatrix} G_0^0 \\ 0 \end{bmatrix} + \begin{bmatrix} G_2^0 \\ G_1^1 \end{bmatrix} D^2 + \dots \right) \\ &+ \left( \begin{bmatrix} G_1^0 \\ G_0^1 \end{bmatrix} + \begin{bmatrix} G_3^0 \\ G_2^1 \end{bmatrix} D^2 + \dots \right) D \end{aligned}$$

The matrix  $G^L$  can be written as

$$\begin{aligned} G^L(D) &= \begin{bmatrix} G_0^0 & G_1^0 \\ 0 & G_0^1 \end{bmatrix} + \begin{bmatrix} G_2^0 & G_3^0 \\ G_1^1 & G_2^1 \end{bmatrix} D \\ &+ \dots + \begin{bmatrix} G_N^0 & 0 \\ G_{N-1}^1 & G_N^1 \end{bmatrix} D^{\lceil \frac{N}{2} \rceil} \end{aligned} \quad (3)$$

We will prove the following result.

*Theorem 1:*  $G^L(D)$  is a minimal time-invariant encoder.

*Proof:* Since, by hypothesis,  $G_0^0, G_1^0, G_N^0$  and  $G_N^1$  are full column rank, we have that  $G^L(D)$  is column reduced.

We prove now that  $G^L(D)$  is right-prime. By hypothesis,  $\begin{bmatrix} G^0(D) \\ DG^1(D) \end{bmatrix}$  is right-prime and

$$\begin{bmatrix} G^0(D) \\ DG^1(D) \end{bmatrix} = G^L(D^2) \begin{bmatrix} I_n \\ DI_n \end{bmatrix} \quad (4)$$

If  $G^L(D^2) = \begin{bmatrix} G^{L_0}(D^2) & G^{L_1}(D^2) \end{bmatrix}$  is not right-prime, then  $G^{L_0}(D^2)$  and  $G^{L_1}(D^2)$  have a squared non unimodular common factor,  $F(D) \in \mathbb{F}^{k \times k}[D]$ , i.e.,

$$G^{L_0}(D^2) = \tilde{G}^{L_0}(D)F(D) \quad \text{and} \quad G^{L_1}(D^2) = \tilde{G}^{L_1}(D)F(D)$$

Then, by equation (4),

$$\begin{aligned} \begin{bmatrix} G^0(D) \\ DG^1(D) \end{bmatrix} &= \begin{bmatrix} \tilde{G}^{L_0}(D)F(D) & \tilde{G}^{L_1}(D)F(D) \end{bmatrix} \begin{bmatrix} I_n \\ DI_n \end{bmatrix} \\ &= \tilde{G}^{L_0}(D)F(D) + \tilde{G}^{L_1}(D)F(D)D \\ &= \tilde{G}^{L_0}(D)F(D) + \tilde{G}^{L_1}(D)DF(D) \\ &= (\tilde{G}^{L_0}(D) + \tilde{G}^{L_1}(D)D)F(D) \end{aligned}$$

which is a contradiction because  $\begin{bmatrix} G^0(D) \\ DG^1(D) \end{bmatrix}$  is right-prime.

Hence  $G^L(D^2)$  is right-prime and therefore also  $G^L(D)$  is right-prime. ■

The parameters of the encoder  $G^L(D)$  are  $(2n, 2k, kN)$  since it can be shown, by equation (3), that if  $N$  is even the degree is  $\delta = 2k \lceil \frac{N}{2} \rceil = 2k \frac{N}{2} = kN$  and if  $N$  is odd the degree is  $\delta = k \lceil \frac{N}{2} \rceil + k \lfloor \frac{N}{2} \rfloor = kN$ . Then the generalized Singleton bound is

$$\begin{aligned} &(2n - 2k) \left( \lfloor \frac{kN}{2k} \rfloor + 1 \right) + kN + 1 \\ &= \begin{cases} nN + 2n - 2k + 1, & \text{if } N \text{ even} \\ nN + n - k + 1, & \text{if } N \text{ odd} \end{cases} \end{aligned}$$

which, is equal to the bound of each periodic encoder (2) when  $N$  is odd, but has an increase of  $n-k$  when  $N$  is even.

This result is similar to the one derived in [2] using a different reasoning.

Obtaining a larger bound for the odd case is encouraging from the point of view of achieving a larger distance for the periodic case. However, the question whether the obtained bound can be reached is still the subject of current investigation.

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