



PhD thesis

Activity choice modeling for pedestrian facilities

Antonin Danalet

Outline

Motivation: Understanding pedestrian demand

Detecting activity-episode sequences

A path choice approach to activity modeling

Location choice with panel effect

Conclusion and future work

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Conclusion and future work

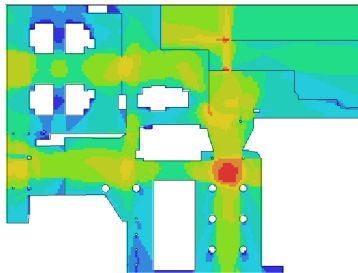
New interest in pedestrian modeling

- Urban growth and its pressure on pedestrian facilities
- Availability of new tracking data



In airports...

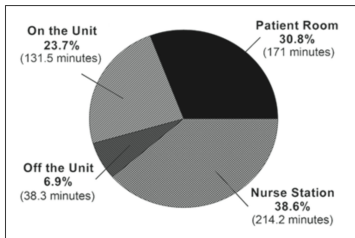
- +38 % air passengers (2008-2013)
- Surveying [LUS14], space syntax [KBM14]



[KMM15]

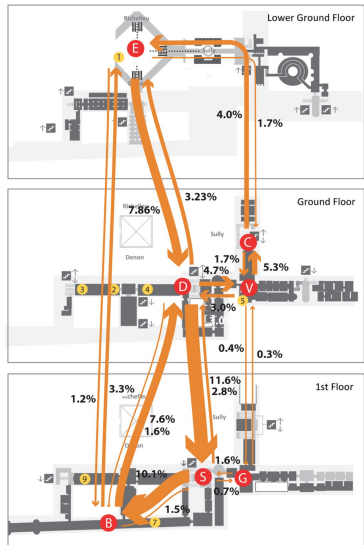
In hospitals...

- US: Hospital-building and -renovation boom [HCSL08]
- Time use of nurses using RFID [HCSL08]



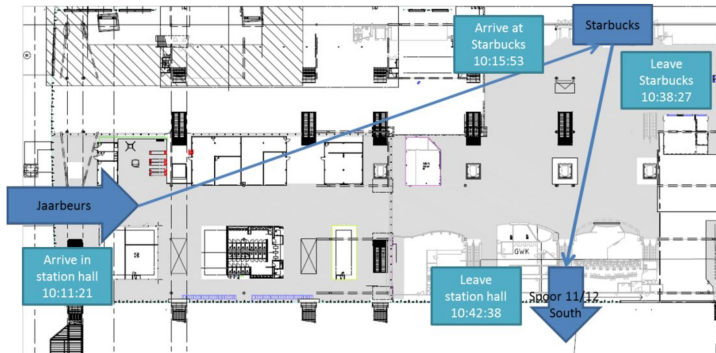
In museums...

- Louvre: +35 % visitors (2004-2014)
- Understanding congestion using Bluetooth [YSR⁺14]



In train stations...

- Utrecht Central Station: +14% visitors by 2020
- Activity location choice using WiFi and Bluetooth [Ton14]



Challenges of pedestrian facilities

- Knowing the number of visitors
 - Determining the source of congestion
 - Localizing points of interest
 - Modifying/building new facilities
 - Defining timetables
-

Data from communication antennas

+

- Large sample size
- Low cost
- Low privacy risk
- No recall bias
- No need to distribute devices
- Tracking non-travelers
- Full coverage of the facility

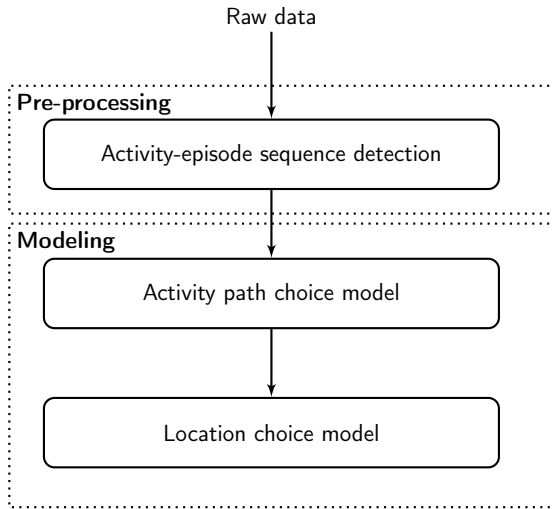
-

- No socioeconomics
 - Not representative
 - Privacy risk
 - Low frequency
 - Low precision
 - No stops
 - No activity purpose
-

Goal: Understanding pedestrian demand

- **Where, when and for how long** do pedestrians perform activities in pedestrian facilities?
- Based on **communication network traces** from **existing antennas**

Activity path approach



Activity-episode sequence detection

- Explicit modeling of the imprecision in the measure
- Usage of prior knowledge of the infrastructure
- Avoidance of the pingpong effect



Activity-path choice model

- No tours, no priorities
 - Managing large choice sets
 - Unique utility for activity type, time-of-day and duration choices
-

Location choice model

- Including panel data
- Correcting for serial correlation



More details

- Introduction: Chapter 1 in [Dan15b]
- Literature review: Chapter 2 in [Dan15b]



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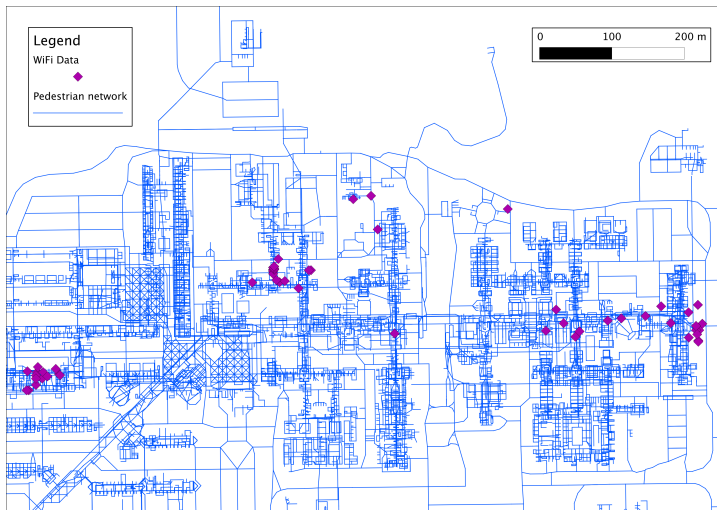
Conclusion and future work

Data requirement

- Required
 - Localization data with full coverage of the facility
 - Semantically-enriched routing graph for pedestrians
- Not required but often available information
 - Potential attractivity measure



Data requirement: Localization



Data requirement: Map (POI + network)



Potential attractivity measure

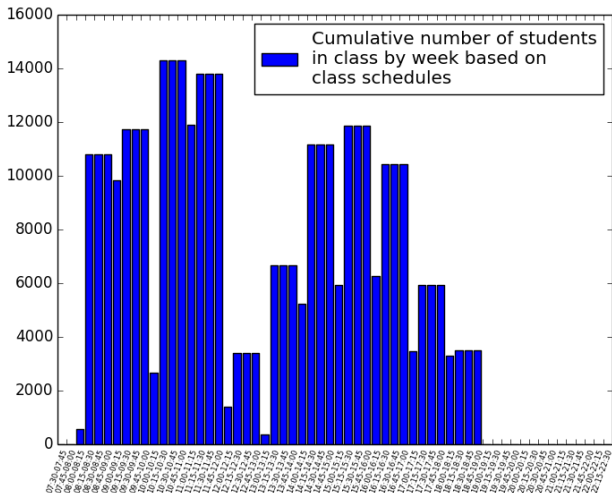
For individual n , point of interest x , start and end times t^- and t^+ :

$$S_{x,n}(t^-, t^+) = \int_{t=t^-}^{t^+} \delta_{x,n}(t) \cdot att_n(x, t) dt$$

with

- Time constraints $\delta_{x,n}$
(e.g., train or class schedules, opening hours)
 - Destination attractivity $att_n(x, t)$
(e.g., classroom, platform, scene aggregate occupancy)
-

Data requirement: Potential attractivity



Methodology

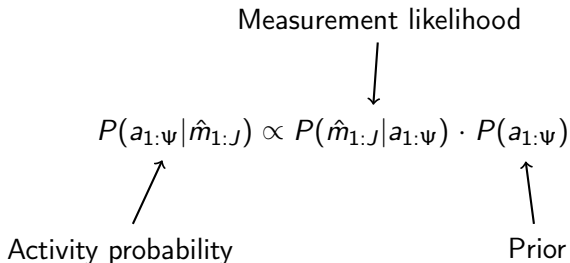
Input

- Localization measurement
- Semantically-enriched routing graph
- Potential attractivity measure

Output

- Set of candidate activity-episode sequences associated with the likelihood to be the true one
-

Probabilistic measurement model: a Bayesian approach



with

- measurement $\hat{m} = (\hat{x}, \hat{t})$, $(\hat{m}_1, \hat{m}_2, \dots, \hat{m}_j, \dots, \hat{m}_J) = \hat{m}_{1:J}$
 - activity episode $a = (x, t^-, t^+)$, $(a_1, a_2, \dots, a_\psi, \dots, a_\Psi) = a_{1:\Psi}$
-

Measurement likelihood

$$\begin{aligned} P(\hat{m}_{1:J} | a_{1:\Psi}) &= \prod_{\psi=1}^{\Psi} P(\hat{m}_{1:J}^{\psi} | a_{\psi}) && \Leftrightarrow \text{Independence between activities} \\ &= \prod_{\psi=1}^{\Psi} \prod_{j=1}^J P(\hat{m}_j^{\psi} | a_{\psi}) && \Leftrightarrow \text{Independence between measurements} \\ &= \prod_{\psi=1}^{\Psi} \prod_{j=1}^J P(\hat{x}_j^{\psi} | x_{\psi}) && \Leftrightarrow \text{No time measurement error} \end{aligned}$$

Prior: Potential attractivity measure

$$\begin{aligned} P(a_{1:\Psi}) &= \prod_{\psi=1}^{\Psi} P(a_{\psi}) \\ &= \prod_{\psi=1}^{\Psi} P(x_{\psi}, t_{\psi}^{-}, t_{\psi}^{+}) \\ &= \prod_{\psi=1}^{\Psi} \frac{S_{x_{\psi}, n}(t_{\psi}^{-}, t_{\psi}^{+})}{\sum_{x \in POI} S_{x, n}(t_{\psi}^{-}, t_{\psi}^{+})} \end{aligned}$$

Probabilistic measurement model: a Bayesian approach

Measurement likelihood

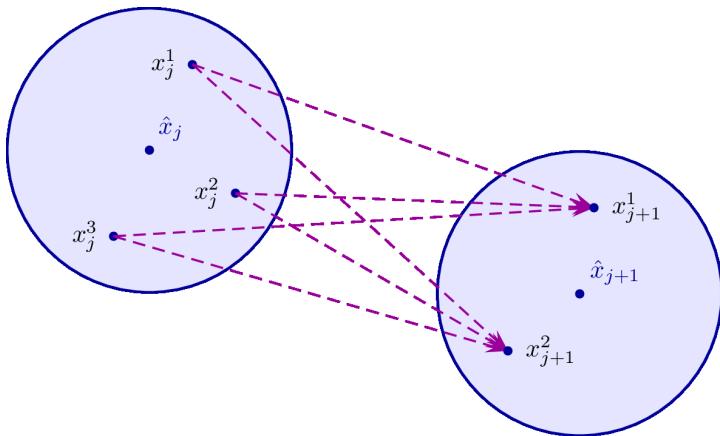
$$P(\mathbf{a}_{1:\psi} | \hat{\mathbf{m}}_{1:J}) \propto P(\hat{\mathbf{m}}_{1:J} | \mathbf{a}_{1:\psi}) \cdot P(\mathbf{a}_{1:\psi})$$

Activity probability

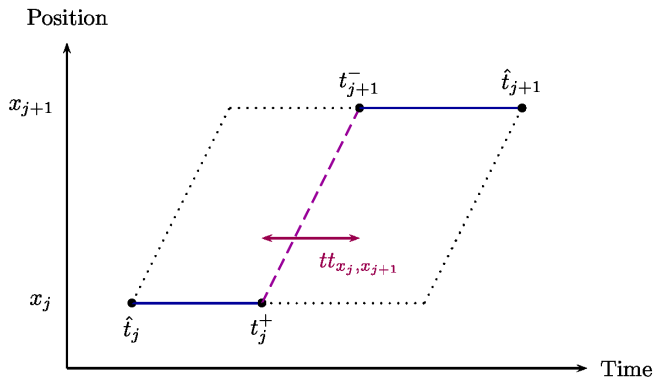
Prior

The diagram illustrates the Bayesian measurement model equation. At the top, the text 'Measurement likelihood' has a downward-pointing arrow leading to the term $P(\hat{\mathbf{m}}_{1:J} | \mathbf{a}_{1:\psi})$ in the equation. Below the equation, 'Activity probability' has an upward-pointing arrow leading to the term $P(\mathbf{a}_{1:\psi})$, and 'Prior' has an upward-pointing arrow leading to the same term. The terms $\mathbf{a}_{1:\psi}$ and $P(\mathbf{a}_{1:\psi})$ are highlighted in red in the original image.

Generation of activity-episode sequences

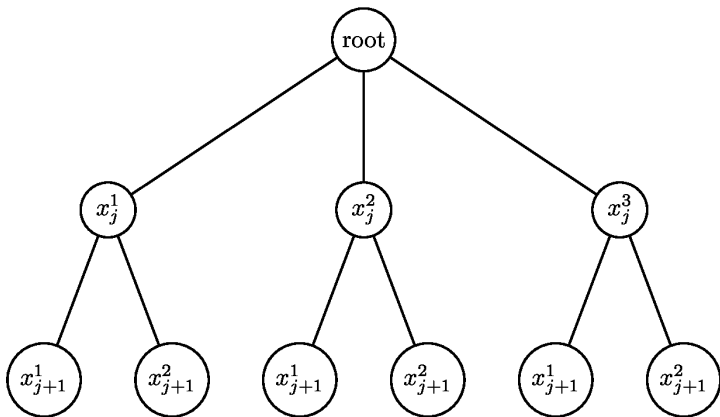


Generation of activity-episode sequences



with $tt_{x_j, x_{j+1}}$ the travel time from x_j to x_{j+1}

Generation of activity-episode sequences



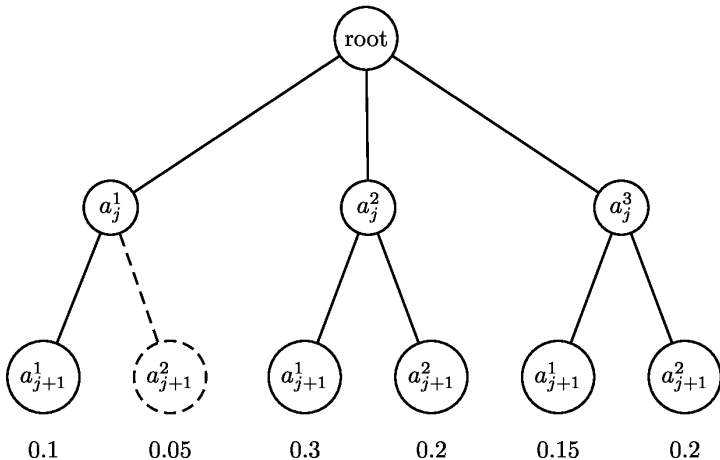
Intermediary measurements

Eliminate intermediary measurements if

$$E(t^+) - E(t^-) < T_{\min}$$

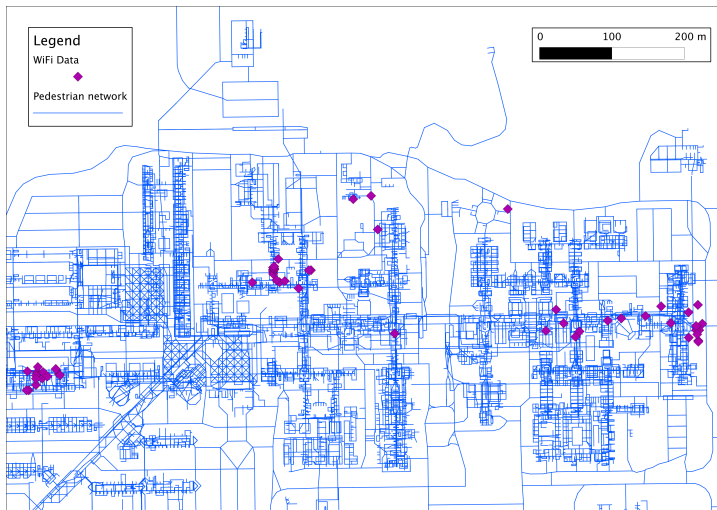
since we generate an activity episode at each measurement.

Sequence elimination

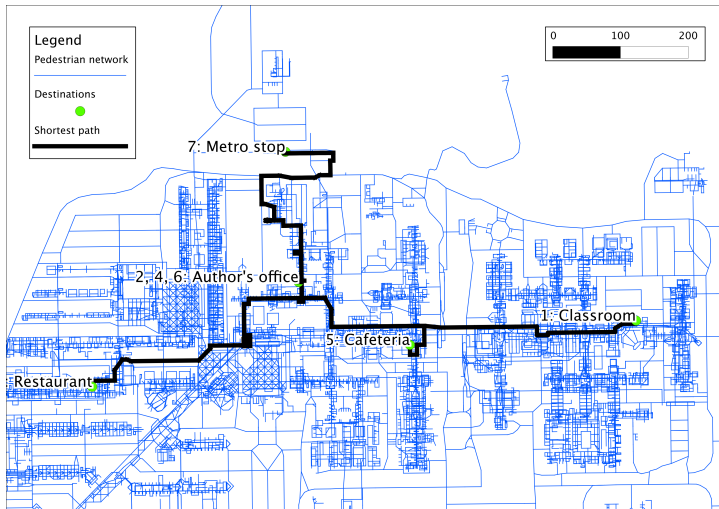


We keep L (here, $L = 5$) most likely activity-episode sequences

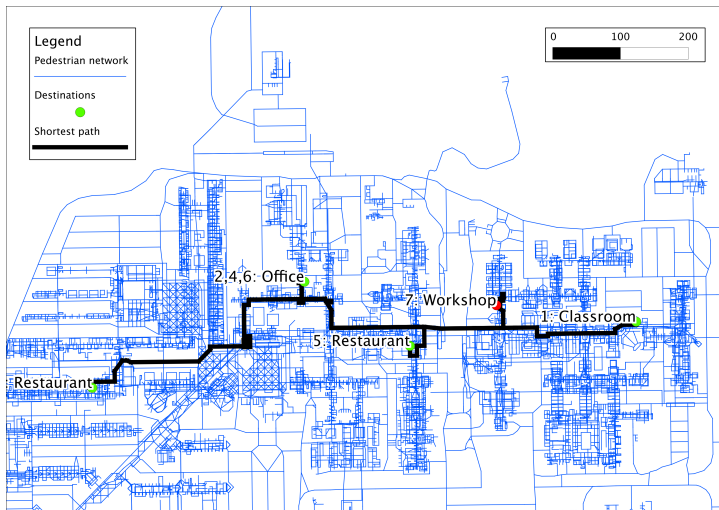
Results: me on EPFL campus, raw data



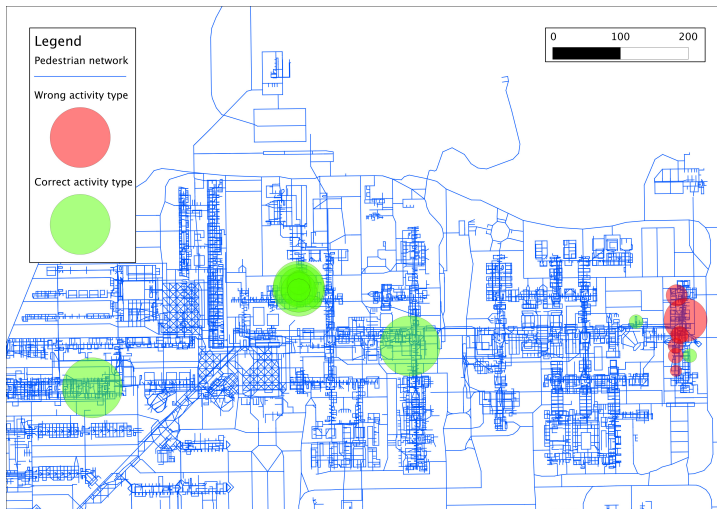
Results: me on EPFL campus, truth



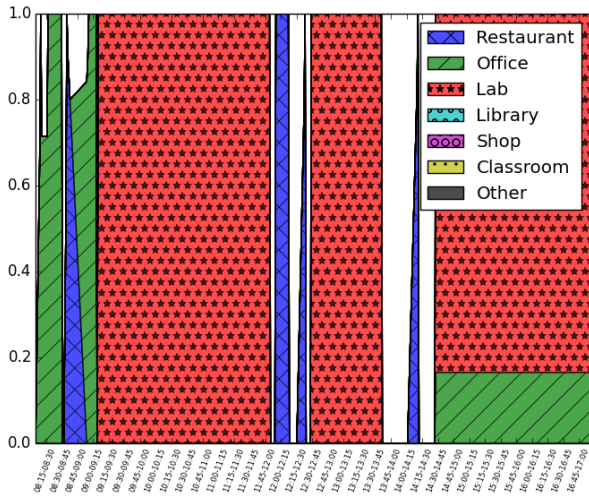
Results: me on EPFL campus, model, $L = 1$



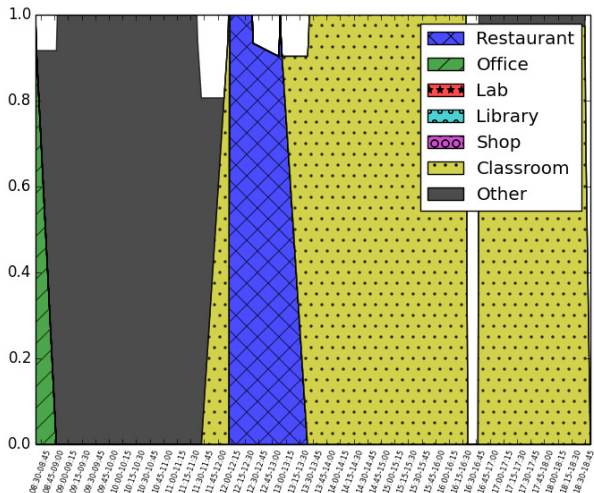
Results: me on EPFL campus, model, $L = 100$



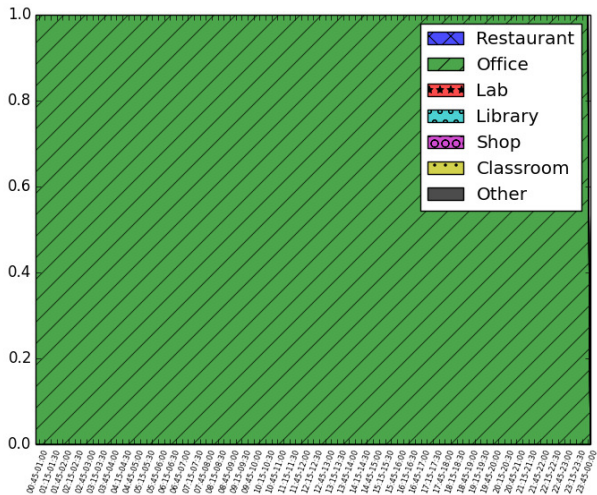
Results: an employee on EPFL campus, $L = 20$



Results: an computer science student, $L = 20$

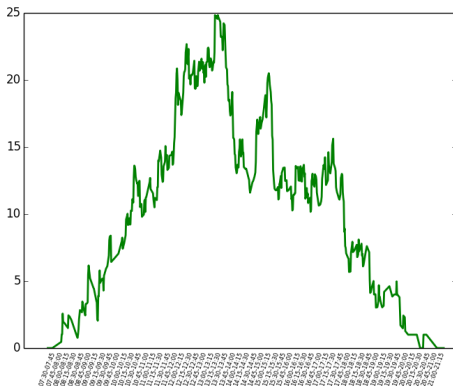


Results: an employees?, $L = 20$



Detection: Results for full population

- 3 activity episodes on average
- 1h37 on each activity
- Devices detected in restaurant during lunch break (see figure)



More details

- Article: [DFB14]
- Chapter 3 in [Dan15b]



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Modeling assumption

- Sequential choice:
 1. activity type, sequence, time of day and duration
 2. destination choice conditional on 1.
- Motivations:
 - Behavioral: precedence of activity choice over destination choice [BBA01, AT04, HB04, AZBA12, KR13]
 - Dimensional: destinations \times time \times position in the sequence is not tractable

Observations: activity patterns in a transport hub

Activity types

Waiting for the train

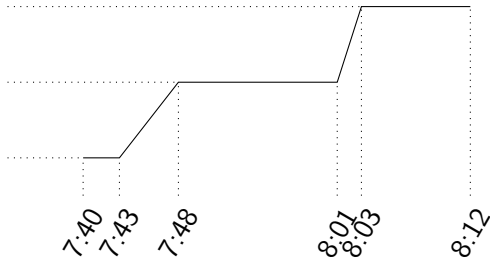
(on platform 9)

Having a tea

(in Starbucks)

Buying a ticket

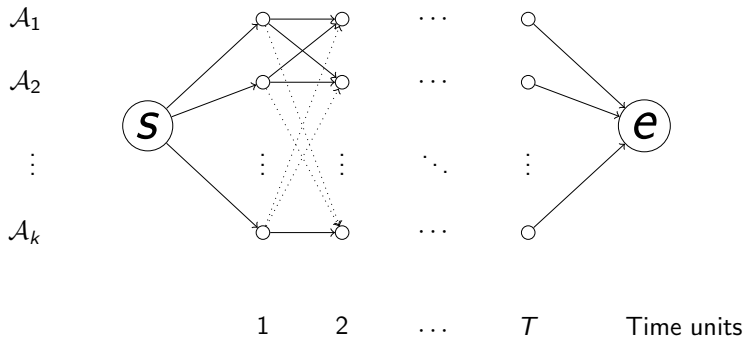
(at the machine)



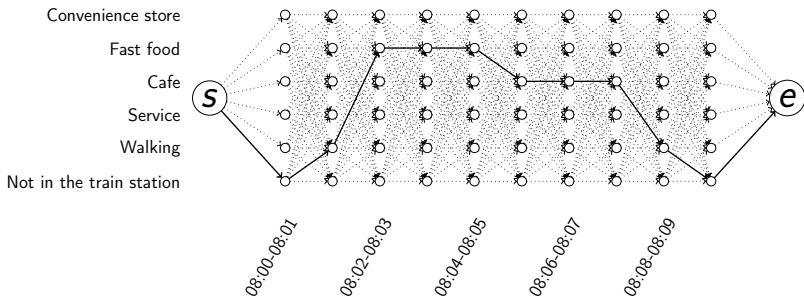
Activity network

Activity types

Activity network



Activity path

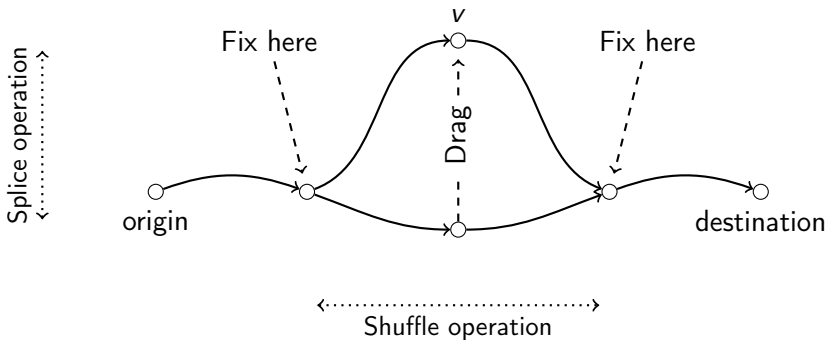


Sampling strategies for choice set generation

- Simple random sampling (SRS)
- Importance sampling using Metropolis-Hastings algorithm [FB13] and strategic sampling [LK12]



Metropolis-Hastings sampling of paths



[FB13]

Metropolis-Hastings sampling of paths

- Sample paths from given distribution, without full enumeration
- To be defined:
 - Target weight: Also with non-node-additive utility
 - Proposal distribution:

$$P_{\text{insert}} = \frac{e^{-\tilde{\mu}\delta_{SP}(\text{origin},v)+\delta_{SP}(v,\text{destination})}}{\sum_w e^{-\tilde{\mu}\delta_{SP}(\text{origin},w)+\delta_{SP}(w,\text{destination})}}$$

Relies on shortest paths, node-additive cost.

Strategic sampling

- Target weight:
previously estimated model
- Proposal distribution:
previously estimated model using only time-of-day preferences
(node-additive)



Utility structure

- Utility of activity pattern:
 - Node utility $V(\mathcal{A}_{k,t})$
 - ▶ time-of-day preferences
 - Activity-episode utility $V(a)$
 - ▶ satiation effects: decreasing marginal utility, $\eta \ln(\text{duration})$
 - ▶ scheduling constraints: schedule delay
 - Activity path utility $V(\Gamma)$
 - ▶ primary activity
 - ▶ number of episodes
- Sampling correction

$$\mu \left(\sum_{k=1}^K \sum_{\tau=1}^T V(\mathcal{A}_{k,\tau}) + \sum_{a \in \mathcal{A}_{1:T}} V(a) + V(\Gamma) \right) + \ln \frac{k_{\Gamma n}}{b(\Gamma)}$$

Case study: pedestrians on EPFL campus

- 13'000 people per day
- 8 activity types:
 - classrooms,
 - shops,
 - offices,
 - restaurant,
 - library,
 - lab,
 - other and
 - not being detected
- 12 time units in the activity network, from 7am to 7pm



Proposal distribution (using simple random sampling)

Description	Coeff. estimate	Robust Asympt. std. error	t-stat
β NA, 17-19, employees	0.263	0.0302	8.70
β NA, 14-17, students	-0.222	0.191	-1.16
β NA, 7-8, students	0.349	0.0281	12.44
β NA, 7-9, employees	0.326	0.0262	12.43
β NA, 17-19, students	1.14	0.187	6.09
β classroom, 12-14, students	-0.336	0.337	-1.00
β classroom, 7-12, employees	-0.723	0.397	-1.82
β classroom, 7-12, students	0.598	0.262	2.28
β library, 14-19, employees	-0.624	0.553	-1.13
β library, 12-14, employees	-0.575	0.481	-1.20
β library, 7-12, employees	-1.57	0.508	-3.09
β office, 14-19, employees	1.41	0.246	5.73
β office, 7-12, employees	1.12	0.228	4.92
β restaurant, 14-19, students	-0.410	0.185	-2.21
β restaurant, 12-14, employees	0.136	0.0259	5.26
β restaurant, 12-14, students	0.665	0.286	2.32

...

Number of observations = 1087

Number of estimated parameters = 43

$$\mathcal{L}(\beta_0) = -5016.636$$

$$\mathcal{L}(\hat{\beta}) = -453.225$$

$$\rho^2 = 0.910$$

$$\bar{\rho}^2 = 0.901$$

Target weight (using simple random sampling)

Description	Coeff. estimate	Robust Asympt. std. error	t-stat
β library 7-12, employees	-2.08	0.422	-4.93
β office 7-12, 14-19, employees	1.69	0.393	4.30
β restaurant 12-14, employees	1.22	0.502	2.43
β shop 12-14, students	-7.36	1.24	-5.92
β shop 7-12, 14-19, students	-1.16	0.538	-2.16
β NA 7-8, students	4.27	0.995	4.29
β NA 8-12, students	1.40	0.498	2.82
β NA 17-19, students	1.75	0.568	3.08
β NA 9-17, employees	1.43	0.296	4.84
β NA 7-9, 17-19, employees	3.34	0.554	6.02
η Office, Lab, Classroom	5.22	0.764	6.83
η Restaurant, Library, Other	7.85	1.11	7.10
η Shop	7.33	0.894	8.20
η NA	2.75	0.393	7.00
β 3+ lab episodes	-5.03	0.952	-5.28
β 3+ resto episodes	-2.50	0.759	-3.29

...

Number of observations = 1087

Number of estimated parameters = 22

$\mathcal{L}(\beta_0) = -5016.636$

$\mathcal{L}(\hat{\beta}) = -47.218$

$\rho^2 = 0.991$

$\bar{\rho}^2 = 0.986$

Model using strategic sampling

Description	Coeff. estimate	Robust Asympt. std. error	t-stat
β classroom 7-12, students	0.478	0.238	2.01
β restaurant 12, students	2.69	0.527	5.10
β shop 14-19, students	1.46	0.343	4.27
β NA 7-12, students	2.33	0.285	8.17
β NA 17-19, students	2.83	0.343	8.24
β NA 7-9, 17-19, employees	2.91	0.303	9.60
η office, lab, classroom	-6.85	0.379	-18.09
η restaurant, library, other	-6.58	0.360	-18.31
η shop	-3.72	0.278	-13.40
η NA	-7.63	0.541	-14.12
β_0 restaurant episode	4.11	0.365	11.28
β_0 classroom episodes, employees	10.3	0.887	11.65
β_1 shop episodes	-3.87	0.573	-6.76
β_2 shop episodes	-3.49	1.08	-3.24
β_0 library episode, employees	2.72	0.335	8.10
β_0 library episode, students	4.77	0.495	9.64
...			

Number of observations = 1087

Number of estimated parameters = 39

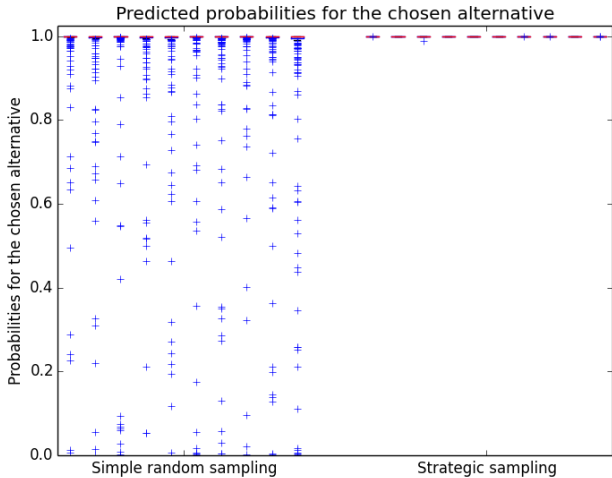
$$\mathcal{L}(\beta_0) = -5016.636$$

$$\mathcal{L}(\hat{\beta}) = -400.633$$

$$\rho^2 = 0.920$$

$$\bar{\rho}^2 = 0.912$$

Validation



More details

- Conference proceeding: [DB15]
- Chapter 4 in [Dan15b]



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Goal

- Model location choice conditional on an activity type
 - Adapted to panel data
-

Static model

$$U_{int} = V_{int} + \varepsilon_{int}$$

Ignores two aspects:

- Dynamics
- Serial correlation



Dynamic model without agent effect

$$U_{int} = V_{int} + \rho y_{in(t-1)} + \varepsilon_{int}$$

Assumes

- Dynamic process of order one
- Location-specific dependence
- Previous choice $y_{in(t-1)}$ independent of error term ε_{int}



Relaxing the independence assumption of error terms

- Agent effect α_{in} : time-invariant factor (*“between” individual variability*)
- Unobserved heterogeneity ε'_{int} : short-term variation of probabilities (*“within” an individual variability*)

$$U_{int} = V_{int} + \rho y_{in(t-1)} + \alpha_{in} + \varepsilon'_{int}$$

Endogeneity issue:

- $y_{in(t-1)}$ and α_{in} are correlated
-

An approach by Wooldridge [Woo05]

For activity location i , individual n , at time t :

$$U_{int} = V_{int} + \rho y_{in(t-1)} + \alpha_{in} + \varepsilon'_{int}$$

Lagged variable Agent effect

$$\alpha_{in} = a + by_{in0} + c'\bar{x}_n + \xi_{in}$$

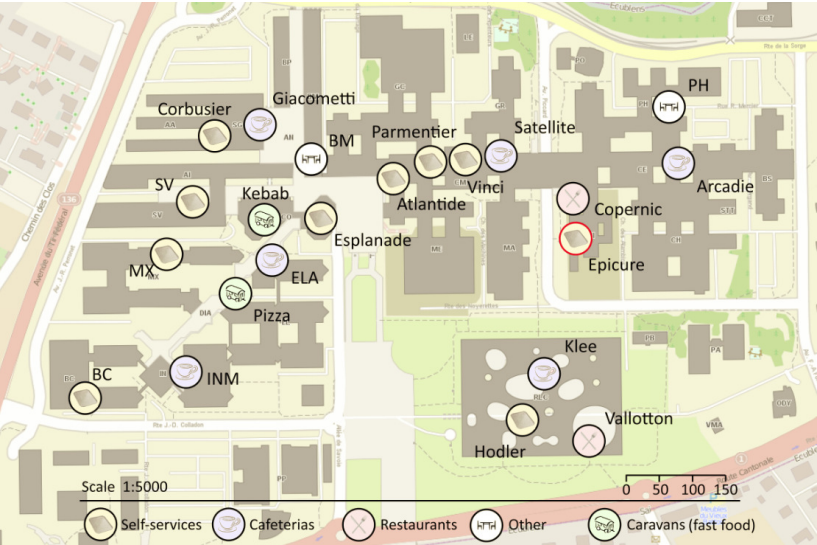
$\sim N(0; \Sigma_\alpha)$

Endogeneity issue solved [Woo05]

3 different models

Static model	Dynamic model without agent effect	Dynamic model with agent effect
$\rho = 0$ $a, b, c, \sigma_\alpha^2 = 0$	$\rho \neq 0$ $a, b, c, \sigma_\alpha^2 = 0$	$\rho \neq 0$ $a, b, c, \sigma_\alpha^2 \neq 0$

Case study: EPFL catering locations




Two specifications of the agent effect

- First choice

$$\alpha_{in} = a + by_{in0} + \xi_n$$

- First choice and frequency

$$\alpha_{in} = a + by_{in0} + cy_{int}^{\text{count}} + \xi_n$$


$$\sum_{t'=1}^{t-1} I(y_{int'})$$

4 models estimated

Static model	Dynamic model without agent effect	Dynamic model with agent effect correction	
		First choice	First choice and frequency
$\rho = 0$	$\rho \neq 0$	$\rho \neq 0$	$\rho \neq 0$
$a = 0$	$a = 0$	$a \neq 0$	$a \neq 0$
$b = 0$	$b = 0$	$b \neq 0$	$b \neq 0$
$c = 0$	$c = 0$	$c = 0$	$c \neq 0$
$\sigma_{\alpha}^2 = 0$	$\sigma_{\alpha}^2 = 0$	$\sigma_{\alpha}^2 \neq 0$	$\sigma_{\alpha}^2 \neq 0$

Estimation results

- Distance has a **negative** impact
 - Yearly evaluation has a **positive** impact
 - Beer after 14:00 has a **positive** impact
 - Cost has a **negative** impact
 - Dinner has a **positive** impact
 - Capacity has a **positive** impact
-

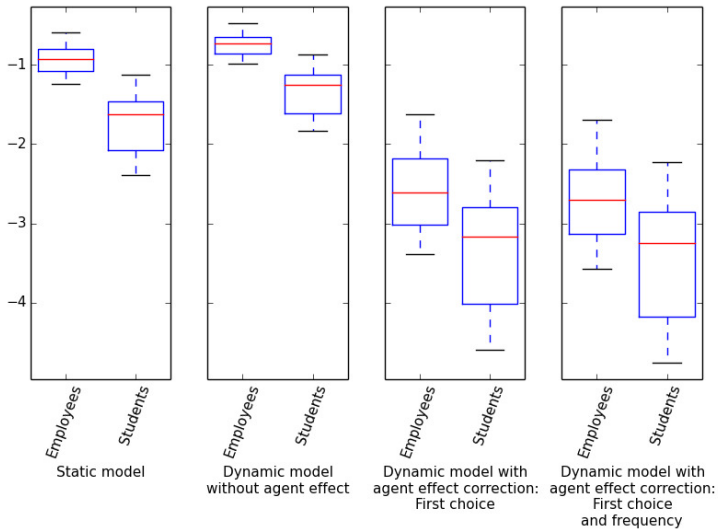
Likelihood ratio tests

Static model	Dynamic model without agent effect	Dynamic model with agent effect correction First choice	Dynamic model with agent effect correction First choice and frequency
354.003 (> 5.99)	920.354 (> 58.12)	16.172 (> 5.99)	

Validation

	Predicting last observations based on past observations			
	Static model	Dynamic model without agent effect	Dynamic model with agent effect correction	
			First choice	First choice and frequency
Sum of the squares of the errors	232.95	204.01	184.16	173.85

Elasticities to price



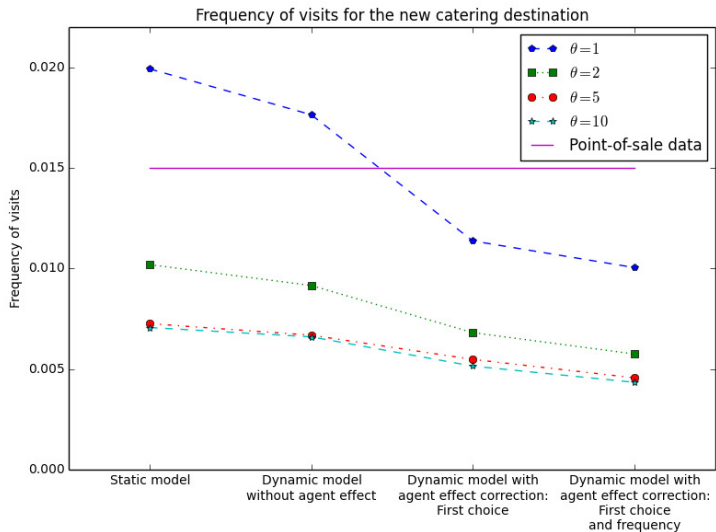
Forecasting: opening a new catering location

Nesting structure with the most similar alternative

- Nesting parameter $\theta = 1$: logit model, independent error terms
- Nesting parameter $\theta \rightarrow \infty$: perfectly correlated error terms



Forecasting: opening a new catering location



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- Explicit modeling of the imprecision in the measure
- Usage of prior knowledge of the infrastructure
- Avoidance of the pingpong effect



Activity-path choice model

- No tours, no priorities
- Managing large choice sets
- Unique utility for activity type, time-of-day and duration choices



Location choice model

- Including panel data
- Correcting for serial correlation



Limitations

- Activity purpose is extracted from map data
 - No mode detection
 - No congestion
-

Future work

- Congested case study
 - Include the uncertainty from detection in modeling
 - Metropolis-Hastings algorithm for the sampling of activity paths
 - More complex correlation structure for the choice of an activity path
 - Include other sources of endogeneity (group, queue)
-

Thank you

PhD thesis:

**Activity choice modeling
for pedestrian facilities**

Antonin Danalet

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Bibliography I



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Privacy issues in this thesis

- EPFL ethics committee:
 - “No personal identifier when sharing data”
- In practice:
 - We have no access to MAC addresses in our dataset
 - The dataset is public [Dan15a]

