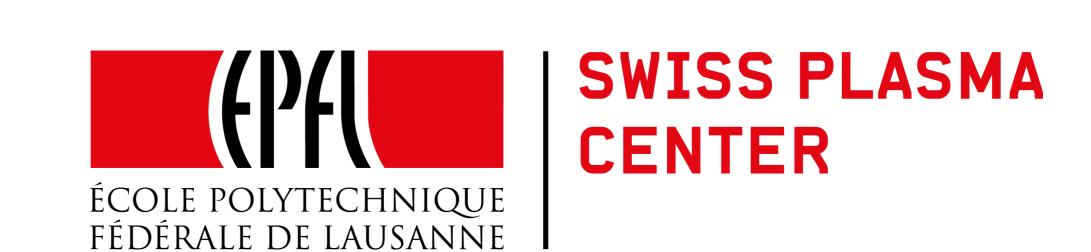
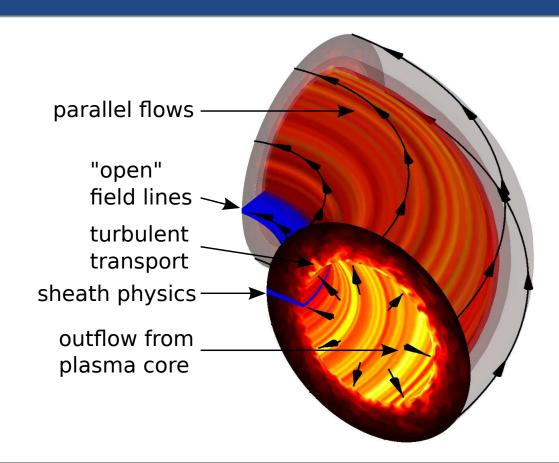
## Effects of plasma shaping on tokamak scrape-off layer turbulence

F. Riva, E. Lanti, F. D. Halpern, S. Jolliet, P. Ricci

École Polytechnique Fédérale de Lausanne (EPFL), Swiss Plasma Center, CH-1015 Lausanne, Switzerland



#### Introduction

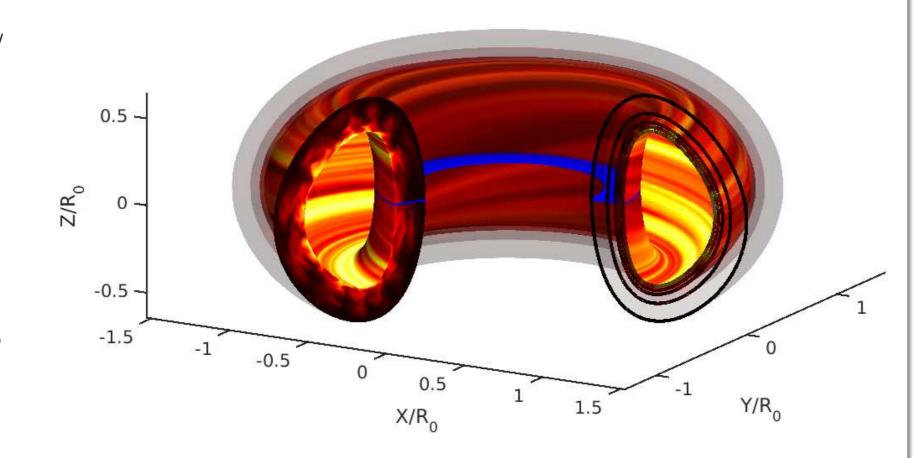


- ▶ In Scrape-Off Layer (SOL) of tokamaks, magnetic field lines intersect the walls of the fusion device
- ► Heat and particles flow along magnetic field lines and are exhausted to the vessel

The Global Braginskii Solver (GBS) code: a 3D, two-fluid, flux-driven, global turbulence code in limited geometry used to study plasma turbulence in the SOL

## Development and achievements of GBS

- Achivements:
- ► Non-linear turbulent regimes in the SOL
- SOL width scaling as a function of dimensionless /
- engineering plasma parameters Origin and nature of intrinsic toroidal plasma
- rotation in the SOL
- ► Mechanisms regulating the SOL equilibrium electrostatic potential
- ▶ In the past: simulations in circular limited configuration
- ▶ Described here: **generalization** of the GBS magnetic geometry to include Shafranov shift, plasma elongation, and non-zero triangularity



## The Global Braginskii Solver (GBS) code

▶ Two-fluid Drift-reduced Braginskii equations,  $d/dt \ll \omega_{ci}$ :

 $rac{\partial n}{\partial t} = -rac{
ho_{\star}^{-1}}{B}[\phi, n] + rac{2}{B}[C(p_e) - nC(\phi)] - \nabla \cdot (nv_{\parallel e}\mathbf{b}) + S_n$ Continuity:  $\frac{\partial \omega}{\partial t} = -\frac{\rho_{\star}^{-1}}{B} [\phi, \omega] - v_{\parallel i} \nabla_{\parallel} \omega + \frac{B^2}{n} \nabla \cdot (j_{\parallel} \mathbf{b}) + \frac{2B}{n} C(p_e)$ Charge conservation:  $\frac{\partial v_{\parallel e}}{\partial t} = -\frac{\rho_{\star}^{-1}}{B} [\phi, v_{\parallel e}] - v_{\parallel e} \nabla_{\parallel} v_{\parallel e} + \frac{m_i}{m_e} \left( \nu \frac{j_{\parallel}}{n} + \nabla_{\parallel} \phi - \frac{1}{n} \nabla_{\parallel} p_e - 0.71 \nabla_{\parallel} T_e \right)$ Ohm's law:

 $\frac{\partial v_{\parallel i}}{\partial t} = -\rho_{\star}^{-1}[\phi, v_{\parallel i}] - v_{\parallel i}\nabla_{\parallel}v_{\parallel i} - \frac{1}{n}\nabla_{\parallel}p_{e}$ Parallel momentum:  $\frac{\partial T_e}{\partial t} = -\frac{\rho_{\star}^{-1}}{B}[\phi, T_e] - v_{\parallel e} \nabla_{\parallel} T_e + \frac{4}{3} \frac{T_e}{B} \left[ \frac{C(p_e)}{n} + \frac{5}{2} C(T_e) - C(\phi) \right]$ Electron temperature :  $+\frac{2}{3}T_{e}\left|0.71\frac{
abla\cdot(j_{\parallel}\mathbf{b})}{n}abla\cdot(v_{\parallel}e\mathbf{b})\right|+S_{T_{e}}$ 

- ▶ Equations implemented in **GBS**, system closed by  $\omega = \nabla^2_{\perp} \phi$  [Ricci *et al.*, PPCF 2012]
- ► System completed with a set of first-principles boundary conditions applicable at the magnetic pre-sheath entrance where the magnetic field lines intersect the limiter [Loizu et al., PoP 2012]
- ▶ Note:  $L_{\perp} \rightarrow \rho_s$ ,  $L_{\parallel} \rightarrow R_0$ ,  $t \rightarrow R_0/c_s$ ,  $\nu = ne^2 R_0/(m_i \sigma_{\parallel} c_s)$  normalization

### **GBS** operators

► The magnetic geometry allows to compute GBS operators

$$[\phi, A] = \mathbf{b} \cdot (\nabla \phi \times \nabla A) = \frac{1}{\mathcal{J}} \epsilon_{ijk} b_i \frac{\partial \phi}{\partial \xi^j} \frac{\partial A}{\partial \xi^k}$$

$$\nabla_{\parallel} A = \mathbf{b} \cdot \nabla = b^j \frac{\partial A}{\partial \xi^j}$$

$$\nabla \cdot \mathbf{b} = \frac{1}{\mathcal{J}} \frac{\partial}{\partial \xi^i} (b^i \mathcal{J})$$

$$\nabla^2_{\perp} A = -\nabla \cdot [\mathbf{b} \times (\mathbf{b} \times \nabla A)] = \frac{1}{\mathcal{J}} \frac{\partial}{\partial \xi^k} \left[ \mathcal{J} \left( g^{ki} - b^k b^i \right) \frac{\partial}{\partial \xi^i} \right]$$

▶ Note: use of curvilinear coordinates and of Einstein summation,  $\mathcal{J}$  is the Jacobian of the metric

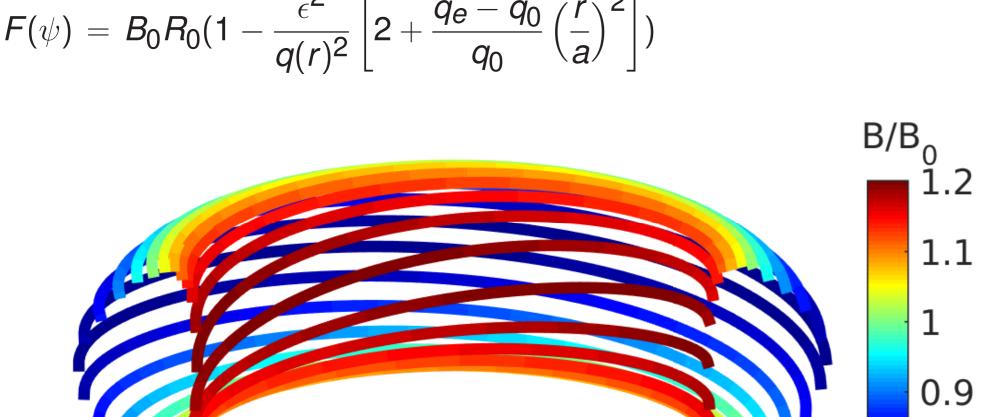
#### The magnetic field geometry

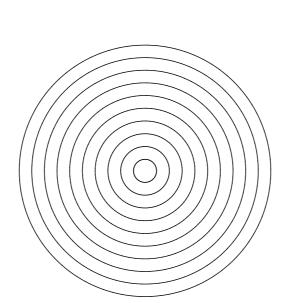
- ► Toroic coordinate system  $(r, \theta, \varphi)$ , general **axisymmetric magnetic field B** =  $F(\psi)\nabla\varphi + \psi'\nabla r \times \nabla\varphi$
- ► GBS uses the  $(\theta_*, r, \varphi)$  coordinate system, where  $\theta_*(r, \theta) = \frac{1}{q(r)} \int_0^\theta d\theta' \frac{\mathbf{B} \cdot \nabla \varphi}{\mathbf{B} \cdot \nabla \theta'}$  is the straight-field-line angle
- ▶ The Grad-Shafranov equation is solved in the  $\epsilon = r/R_0 \to 0$  limit to obtain  $R(r,\theta)$ ,  $Z(r,\theta)$ , and  $F(\psi)$  as function of  $\kappa$ ,  $\delta$ , and q(r) [J. P. Graves, PPCF 2013]

$$R(r,\theta) = R_0 \left( 1 + \epsilon \cos \theta + \frac{\Delta(r)}{R_0} + \sum_{m=2}^{3} \frac{S_m(r)}{R_0} \cos[(m-1)\theta] - \frac{P(r)}{R_0} \cos \theta \right)$$

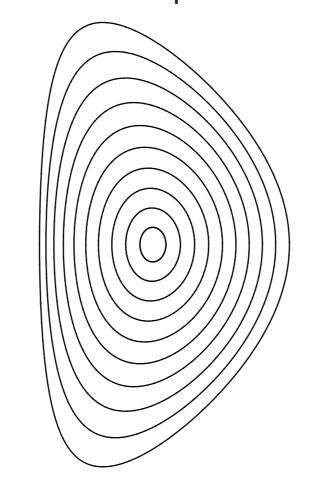
$$Z(r,\theta) = R_0 \left( \epsilon \sin \theta - \sum_{m=2}^{3} \frac{S_m(r)}{R_0} \sin[(m-1)\theta] - \frac{P(r)}{R_0} \sin \theta \right)$$

$$F(\psi) = B_0 R_0 \left( 1 - \frac{\epsilon^2}{q(r)^2} \left[ 2 + \frac{q_e - q_0}{q_0} \left( \frac{r}{a} \right)^2 \right] \right)$$





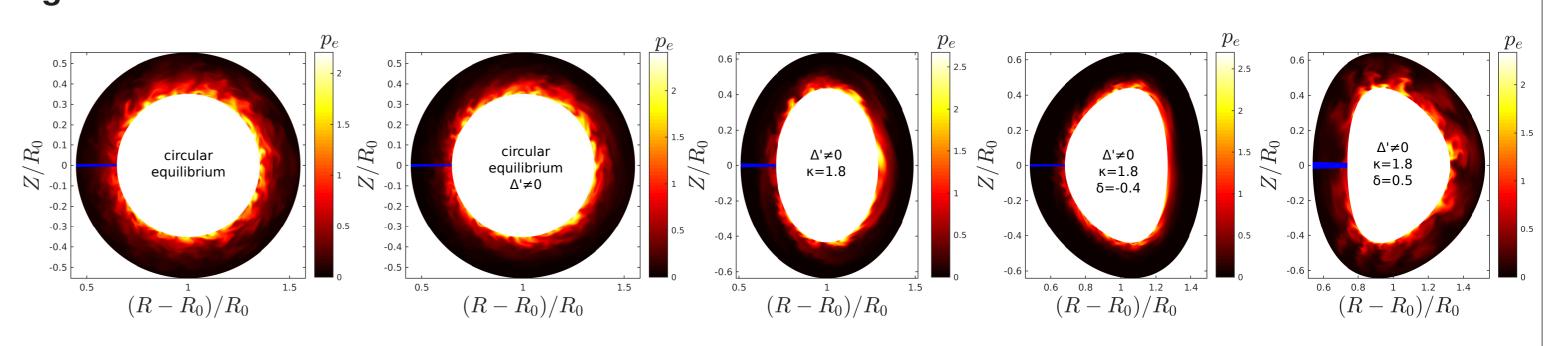
circular equilibrium



D-shaped equilibrium

#### Non-linear simulations

► Fully-turbulent non-linear simulations with same physical parameters, in different magnetic geometries



• Mitigation of turbulence by  $\Delta'$ ,  $\kappa$ , and negative  $\delta$ ; enhancement of turbulence by positive  $\delta$ 

### Gradient removal saturation mechanism

- ► The radial gradient of the **perturbed** plasma pressure comparable to the radial gradient of the background plasma pressure
- ▶ Leading order term of the pressure equation gives the perturbed potential
- Balance between radial flux  $\Gamma_{\mathcal{D}} = \tilde{\mathcal{D}}\partial_{\theta}\tilde{\phi}$  and parallel losses
- ▶ Assuming  $k_r = \sqrt{k_\theta/L_p}$  and choosing **linear growth**

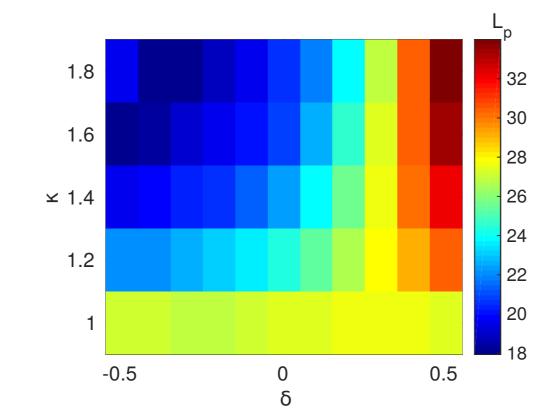
$$\partial_r \tilde{p} \sim \partial_r \bar{p} \Rightarrow k_r \tilde{p} \sim \bar{p}/L_p$$

$$\partial_t \tilde{p} \simeq \partial_\theta \tilde{\phi} \partial_r \bar{p} \Rightarrow \tilde{\phi} \sim \gamma \tilde{p} L_p / (\bar{p} k_\theta)$$

$$\partial_r \Gamma_p \sim \nabla_{||}(\bar{p}v_{||}) \Rightarrow \Gamma_p/L_p \sim \bar{p}c_s/(qR)$$

Assuming 
$$k_r = \sqrt{k_\theta/L_p}$$
 and choosing linear growth rate  $\gamma$  and wavenumber  $k_\theta$  to maximize the transport

► Good agreement between non-linear simulations and Gradient Removal theory

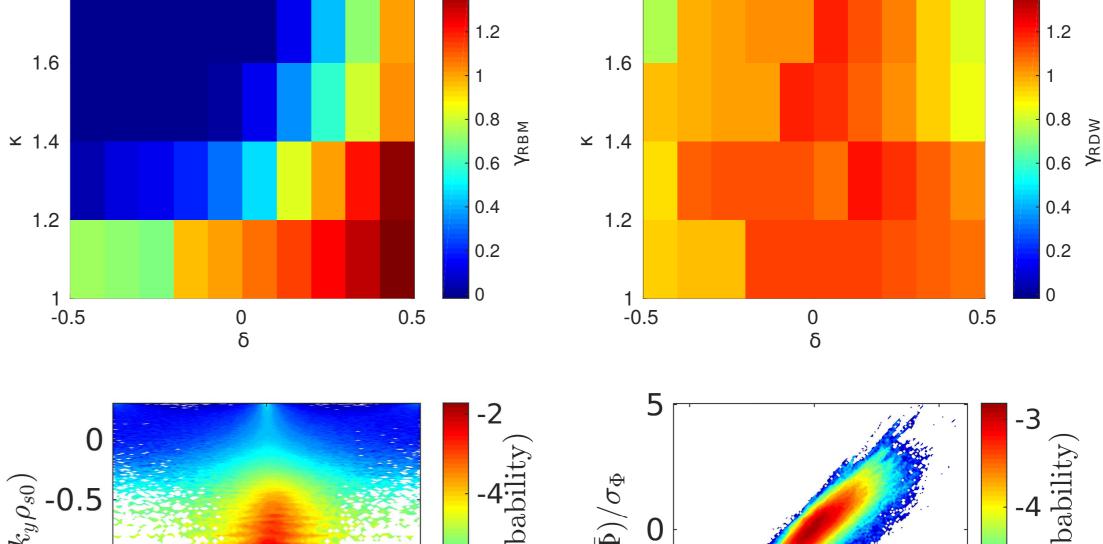


Removal theory

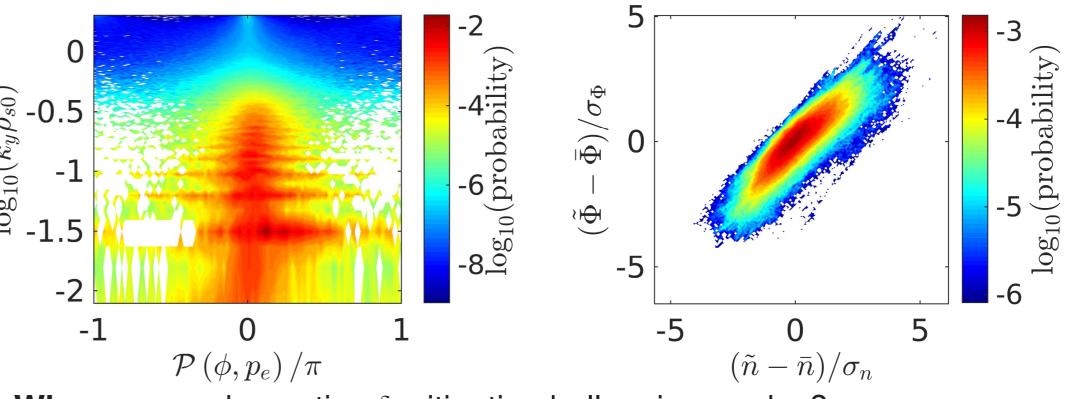
- **Linear scan** over  $\kappa$  and  $\delta$  confirms the trend observed for the non-linear simulations
- Preliminary study indicates the curvature as the most **important** operator in setting  $L_D$

# Non-linear turbulent regimes

▶ Investigation of the turbulent regimes to **understand the mitigation of turbulence** by  $\kappa$  and negative  $\delta$ 

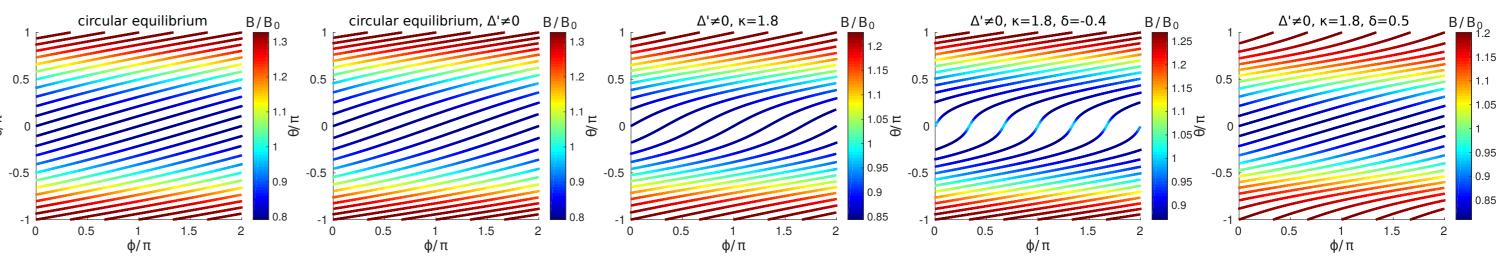


- Resistive ballooning modes mitigated by  $\kappa$ and negative  $\delta$ **▶** Resistive drift waves
- slightly affected by **shaping** effects



▶ Non-linear simulations confirm that **turbulence** is dominated by drift waves for negative  $\delta$ 

▶ Why are  $\kappa$  and negative  $\delta$  mitigating ballooning modes?



- ► Shafranov shift, elongation and negative triangularity stretch magnetic field lines near the outer midplane
- ▶ Positive triangularity compress magnetic field lines near the outer midplane
- ► Curvature less effective with Shafranov shift, elongation and negative triangularity, and more effective for positive triangularity
- ▶ Ballooning modes strongly mitigated by Shafranov shift, elongation and negative triangularity, enhanced by positive triangularity

## Conclusion

- ► Simulations of SOL turbulence in shaped plasmas
- ▶ Scan of  $L_p$  and  $\gamma$  over  $\kappa$  and  $\delta$ , showing how ballooning modes and drift waves are affected by different magnetic configurations
- Qualitative understanding of the mechanism mitigating/enhancing the ballooning character of turbulence