# Reducing Randomness in Matrix Models for Wireless Communication 

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On the mountains of truth you can never climb in vain: either you will reach a point higher up today, or you will be training your powers so that you will be able to climb higher tomorrow.

- Friedrich Nietzsche


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## Abstract

Pushed by the proliferation of antennas and of multiuser scenarios, matrices with random entries are appearing more and more frequently in information theory. This leads to the study of matrix channels, where the capacity depends on the distribution of the matrix's eigenvalues. These eigenvalues are complicated functionals of the entries of the matrix and the challenge lies therein. It is often the case that in order to better model different communication scenarios, one is driven away from matrix models typically studied in pure mathematics and physics. One cannot simply resort to the standard tools developed over the years in these fields and must come up with new approaches. In this thesis, our goal is to obtain results in scenarios where the randomness is limited by the nature of the channel, in order to widen applicability in real life scenarios.

We first discuss line of sight communication in ad hoc wireless networks. We investigate a distributed MIMO setup where two clusters of users want to communicate, the difficulty arising from the fact that the distance between users is highly variable. Here, the channel matrix which is of interest is given by $h_{j k}=\frac{e^{2 \pi i r_{j k}}}{r_{j k}}$ where $r_{j k}$ is the distance between two nodes $j$ and $k$. The distribution of the singular values of this matrix is intractable and we therefore approximate this matrix with a closely related matrix more amenable to analysis: $g_{i j}=e^{2 \pi m i y_{j} z_{k}}$ where $y_{j}$ and $z_{k}$ are i.i.d. random variables uniformly distributed on an interval and $m$ is a parameter of key importance deduced from the characteristics of the network. We derive, in the large $n$ limit, a bound on the largest singular value of this matrix as well as a bound on the number of significant singular values. This is related to the number of degrees of freedom in the channel under study.

The second topic of this thesis relates to channels experiencing fading in both the time and the frequency domain. Results concerning these channels depend on the concept of freeness, the equivalent of independence in the noncommutative world. As such, we introduce free probability, a noncommutative analog of classical probability well suited to answer questions concerning the spectrum of large matrices. We show that if we consider i.i.d. time fading with arbitrary frequency domain fading, the resulting matrices are not free, as was previously hoped. While the usual free probability tools to deduce the capacity of such a channel can no longer be applied, we indicate partial results allowing the computation of the moments of the eigenvalue distribution for a matrix modelling both types of fading. We also give an explicit criterion preventing two matrices from being free.

Abstract

Key words: wireless communication, ad hoc network, random matrices, free probability, Fourier matrix, fading, degrees of freedom, eigenvalue distribution.

## Résumé

Poussées par la prolifération d'antennes et de scénarios de communication à multiples utilisateurs, les matrices avec entrées aléatoires apparaissent de plus en plus fréquemment en théorie de l'information. Dans le cas des canaux matriciels, la capacité se calcule à partir de la distribution des valeurs propres de la matrice, les complications émanant du fait que ces dernières sont des fonctionnelles compliquées des entrées de la matrice. Lors de la modélisation de scénarios de communication, on doit souvent s'éloigner des modèles de matrices typiquement étudiés en mathématiques pures et en physique, limitant donc l'utilité de plusieurs des outils développés dans ces domaines au cours des années. Il est donc nécessaire d'avoir recours à de nouvelles approaches. Dans cette thèse, nous nous intéresserons plus particulièrement à la réduction de l'aléa dans les modèles de matrices, cette réduction pouvant être due à un désir de mieux modéliser un phénomène physique, ou encore à une volonté de généraliser l'applicabilité de résultats obtenus précédemment.

Nous discuterons d'abord de communication à ligne de visée directe dans les réseaux sans-fil ad hoc. Nous nous intéressons à un système MIMO distribué où deux groupes d'utilisateurs veulent communiquer. La difficulté tient au fait que la distance entre les utilisateurs est hautement variable. La matrice du canal d'intérêt est donnée par $h_{j k}=\frac{e^{2 \pi i r} r_{j k}}{r_{j k}}$ où $r_{j k}$ est la distance entre les utilisateurs $j$ et $k$. La distribution des valeurs singulières de cette matrice est réfractaire à l'analyse et nous l'approximons par une matrice pouvant être plus facilement étudiée : $g_{i j}=e^{2 \pi m i y_{j} z_{k}}$ où $y_{j}$ et $z_{k}$ sont des variables aléatoires i.i.d. distribuées uniformément sur un intervalle et $m$ est un paramètre clef qui se déduit des caractéristiques du réseau. Nous obtenons, dans la limite lorsque le nombre d'utilisateur tend vers l'infini, une borne sur la plus grande valeurs singulière de la matrice étudiée, ainsi qu'une borne sur le nombre de valeur singulières significatives. Ces quantités sont reliées au nombre de degrés de liberté du canal étudié.

Le second chapitre de cette thèse s'intéresse aux canaux soumis à des évanouissements dans les domaines temporels et fréquentiels. Certains résultats concernant ces canaux dépendent de la notion de liberté, un équivalent de l'indépendance de variables aléatoires dans le cas non commutatif. Ceci nous motive à introduire les probabilités libres, un analogue non commutatif aux probabilités classiques qui est particulièrement bien adapté pour répondre aux questions concernant le spectre de matrices de grande dimension. Nous démontrons que si l'évanouissement temporel est i.i.d. et que l'évanouissement fréquentiel est arbitraire, les ma-
trices qui entrent en jeu ne sont pas libres, contrairement à ce qui avait été conjecturé. Même si les outils habituels des probabilités libres ne peuvent plus être utilisés, nous indiquons des résultats partiels nous permettant de calculer la distribution des valeurs propres de la matrice modélisant le canal. Nous donnons aussi un critère explicite empêchant les deux matrices d'être libres.

Mots clefs : communication sans-fil, réseaux ad hoc, matrices aléatoires, probabilités libres, matrice de Fourier, degrés de liberté, distribution des valeurs propres.

## Contents

Acknowledgements ..... i
Abstract (English/Français) ..... iii
List of figures ..... ix
List of tables ..... xi
1 Introduction ..... 1
Introduction ..... 1
1.1 Random Matrices in Wireless Networks ..... 2
1.1.1 Multiple Antenna Channel ..... 2
1.1.2 Ad Hoc Wireless Networks ..... 2
1.2 On the use of freeness ..... 4
1.2.1 A seemingly simple communication problem ..... 4
1.2.2 What is free probability? ..... 6
1.2.3 Towards a more general model ..... 6
2 Line of sight in Wireless Communication ..... 9
2.1 Modelling the situation ..... 9
2.2 Spatial degrees of freedom ..... 11
2.3 Maximal Eigenvalue ..... 22
2.3.1 All indices are different ..... 24
2.3.2 Some indices repeat ..... 26
2.4 Discussion ..... 28
2.5 Conclusion and perspectives ..... 29
3 Free Probability ..... 31
3.1 Noncommutative Probability Spaces and Free Independence ..... 31
3.1.1 Free independence ..... 33
3.1.2 Transforms and convolutions ..... 34
3.1.3 Asymptotic liberation ..... 37
3.2 Traffics ..... 40
3.2.1 Criteria ensuring the lack of asymptotic freeness ..... 45
3.3 Examples of lack of freeness ..... 48
3.3.1 Examples relying on arithmetic structure ..... 48
3.3.2 Projection with contiguous values ..... 49
3.3.3 Markov Chains ..... 50
3.4 Traffic distributions ..... 53
3.4.1 A more direct computation ..... 57
3.5 Conclusion and perspectives ..... 58
Bibliography ..... 61
Curriculum Vitae ..... 63

## List of Figures

2.1 Node distribution ..... 10
2.2 Interplay between the degrees of freedom and the distance $d$. ..... 11
2.3 Parametrization ..... 12
2.4 Eigenvalues of $N P H H^{*}$ and $G G^{*}$ ..... 14
2.5 Histogram of the eigenvalues of $N P H H^{*}$ and $G G^{*}$ ..... 15
2.6 Histogram of the eigenvalues of $G G^{*}$ and $L L^{*}$ for $L$ i.i.d. ..... 23
2.7 Significant eigenvalues of $G G^{*} / n$ ..... 24
2.8 A graph representation of successive cancellation ..... 27
3.1 Example of empirical free multiplicative convolution ..... 39
3.2 Example of theoretical free multiplicative convolution ..... 40
3.3 The graph $T_{0}$ ..... 41
3.4 Example of the construction of $\bar{T}$ ..... 44
3.5 Eigenvalues for the contiguous case ..... 51
3.6 Eigenvalues when one matrix's entries form a 2 states Markov chain ..... 52
3.7 Empirical eigenvalue distribution in the case of an explicit computation ..... 57

## List of Tables

3.1 The different partitions having a potentially non-zero contribution and their associated graphs47

## 1 Introduction

The classical problem of communication over a non deterministic channel has evolved in a multitude of directions since Shannon's original statement. In particular, in today's setting, multiparty communication has taken the centre stage. Whether it is users or antennas, the number of entities to take into account in a typical scenario can now easily reach the hundreds or thousands. It is therefore not surprising that new tools have been introduced to deal with this new development. While at first sight the increasing number of users leads only to nightmares of complexity, in some cases the increased randomness allows one to make precise probabilistic statements about the asymptotic behaviour of the system under study. Moreover, the characteristics of moderate size systems are remarkably close to the limiting theoretical predictions. A prime example of this is the use of matrices to describe the fading between large groups of antennas. Here, the parameters of the problem are described by a channel matrix, and the quality of the channel is governed by the singular values of this matrix.

Wigner's seminal paper [33] concerning the convergence of the empirical eigenvalue distribution of Hermitian matrices with i.i.d. entries to the semicircle law launched the study of random matrix theory we are familiar with today. Wigner's original motivation was to model the spectra of heavy nuclei. This was followed by the study of the limit of the empirical eigenvalue distribution of Wishart matrices in [15]. Random matrix theory has since then bloomed into a rich field with connections to other areas of mathematics, as well as physics and engineering. We refer the reader to two introductory books on the matter [1], [17]. More recently, results concerning bounded rank perturbation [4], or the convergence of the empirical eigenvalue distribution of i.i.d. (not necessarily Hermitian) matrices [26] have also been proved. While there exist (sometimes surprisingly) precise results concerning the behaviour of eigenvalues for matrices with many i.i.d. entries, much less is known in other cases, notably about the matrices presented in the present work.

The use of random matrices in the analysis of communication systems is the main topic of this thesis. We will analyze different models of random matrices, and deduce probabilistic estimates on the behaviour of the eigenvalues. This in turn leads to quantitative statements on the behaviour of variables of interest for engineering purposes such as channel capacity.

While many probabilistic estimates exist for a variety of channels, our aim is to recover results in cases with decreased stochasticity. We want to widen the applicability of results and to glean a better understanding of the objects under study. On the other hand, the price to pay is that the many methods typically used in random matrix theory become inapplicable.

We will now describe the two problems we address in the present thesis. For more applications of random matrix theory to problems in wireless communication, we refer the reader to the monograph [29].

### 1.1 Random Matrices in Wireless Networks

### 1.1.1 Multiple Antenna Channel

Consider a channel where both the transmitter and the receiver have many antennas at their disposal (MIMO, for Multiple Input Multiple Output). Channels with many transmitters and (equally) many receivers are a prime example of the use of random matrices in wireless communication. Each entry of the matrix describes the fading between a pair of antennas and the so called channel matrix $H$ captures the state of the channel. This was first studied in [8] and [27]. Depending on how this fading is modelled and the hypotheses, the channel's characteristics can be quite different. Two common assumptions are that the receiver has channel state information and that the fading coefficients between any two antennas are independent and identically distributed. This is reasonable in a point-to-point scenario: the communication wavelength is small and the antennas, while close, are still sufficiently distant to ensure independence. Assuming the fading between any two antennas is an independent complex Gaussian of unit variance, one can obtain the following expression for the capacity of the channel with additive, independent Gaussian noise

$$
\begin{equation*}
\mathbb{E}\left[\log \operatorname{det}\left(I+(P / t) H H^{*}\right)\right]=\mathbb{E}\left[\sum \log \left((P / t) \lambda_{i}\right)\right] \tag{1.1}
\end{equation*}
$$

where $P$ is the total power budget, $t$ the number of transmit antennas and $\lambda_{i}$ are the eigenvalues of the matrix $H H^{*}$. We see here appear the eigenvalues of the channel matrix, explaining our interest in their stochastic properties. After investigating the properties of these eigenvalues, one concludes that the capacity of this channel grows linearly with the number of transmitter antennas if there are at least as many receiver antennas. In the single antenna point to point scenario, the capacity grows only logarithmically with the input power. By adding more antennas, we stand to increase overall capacity while keeping the same total power budget.

### 1.1.2 Ad Hoc Wireless Networks

Consider the problem of establishing communication in an ad-hoc wireless network of $n$ nodes distributed uniformly at random over some large area, where we form $n$ transmitter-
receiver pairs that want to communicate. Given the complexity of this multiparty scenario, one quickly abandons the hope of finding an explicit formula for the capacity and instead has to rely on asymptotic results in the dimension of the problem. In particular, we are interested in information theoretic bounds on how the capacity scales with the number of users. Lower bounds are provided by particular communication schemes. While a promising solution at first sight would be to use a multihop strategy where neighbours relay messages to the intended destination, it has been shown in [11] that this achieves a scaling of the total throughput of the order of $\sqrt{n}$. As such, the rate per user decreases as $1 / \sqrt{n}$ as the size of the network grows and each node can send less and less information.

New strategies have been suggested, including hierarchical cooperation, introduced in [19]. The idea is to leverage the properties of MIMO communication to achieve linear scaling.This is done by dividing the nodes into groups, and letting each group act as one large MIMO cluster of antennas. The performance analysis of this strategy presents new challenges since it involves the computation the eigenvalues of the matrix whose entries are modelled as

$$
h_{j k}=\frac{e^{i \phi_{j k}}}{r_{j k}}
$$

where $r_{j k}$ is the distance between the nodes $j$ and $k$, and $\phi_{j k}$ models the phase fading between the two nodes and $i$ is the imaginary unit. Since the distance between two nodes varies greatly, so does the variance of the entries of the channel matrix $H$, making the analysis more involved. Still, by making the hypothesis that the $\phi_{j k}$ are i.i.d., sufficiently many results can be recovered to conclude that the linear scaling of the total throughput of the network with the number of antennas (or in this case, users in a group) is maintained. This i.i.d. modelling of the phases can be justified by observing that the wavelength of the transmission $\lambda$ is typically orders of magnitude smaller than the distance between users. On top of this, any multipath fading adds to the randomness in the phase [7].

This linear scaling of the number of degrees of freedom of ad hoc wireless networks was questioned in [9], where another approach, based on a physical modelling of the operators involved in the communication channel, pointed towards a strictly sublinear scaling. One must therefore question the validity of the i.i.d. assumption of the phases for the channel matrix: it is not physically realistic for all scenarios.

By completely stripping away this i.i.d. modelling of the phases, we are left with the other extreme: line of sight communication where fading is uniquely determined by the distance between the nodes.

$$
h_{j k}=\frac{e^{i 2 \pi r_{j k} / \lambda}}{r_{j k}}
$$

We see here a fundamental difference: whereas i.i.d. fading involves $n^{2}$ independent random variables, line of sight fading involves only of the order of $n$ independent random variables as it depends only on the positions of the nodes. This reduction in stochasticity, as well as the complexity of the functionals involved in each entry of the channel matrix, makes this problem much less tractable. Indeed, many sophisticated results are no longer available since we are far from the classically studied ensembles of random matrices. One must therefore resort to more elementary methods, necessarily yielding less precise results. In particular, we are interested in results concerning the order of the largest eigenvalue, as well as the number of significant eigenvalues. This relates directly to Equation (1.1) : non-vanishing eigenvalues correspond to degrees of freedom that could be exploited by a communication scheme. Even with this goal in mind, the line of sight matrix is difficult to handle directly since the functional form of each entry of the matrix is unwieldy. We are led to considering a matrix obtained by approximating every entry to quadratic order. While we cannot obtain a theoretical result to quantify how much this interferes with the eigenvalue distribution of the line of sight matrix, numerical experiments suggest a remarkable fit between the eigenvalue distributions of the two matrices. We therefore attack the problem of obtaining bounds on the number of significant eigenvalues, as well as on the order of the largest eigenvalue of this approximated matrix. This is the topic of the first chapter of the present thesis.

### 1.2 On the use of freeness

We now take a look at another example where a channel is modelled by a random matrix and we hope to reduce the stochasticity involved to make the analysis more robust to real world scenarios.

### 1.2.1 A seemingly simple communication problem

We will elaborate on one particular problem in communication systems: frequency and time selective fading ([30]).

The time-selective coherent channel is modelled as (in vector form):

$$
\mathbf{y}=\sqrt{\gamma} H \mathbf{x}+\mathbf{n}
$$

where $\mathbf{x}$ is subject to an average power constraint $\mathbb{E}\left[x_{i}\right] \leq P, n_{i}$ are i.i.d. random variables of unit variance, $\gamma$ is the Signal to Noise Ratio (SNR) and $H$ is a diagonal matrix whose entries come from a fading process known to the receiver, stationary and ergodic. Here, $N$ is the dimension of the matrices and vectors.

Assuming the decoder knows the realizations of the fading process, the capacity of this channel
(in the limit as $N \rightarrow \infty$ ) is known:

$$
\begin{equation*}
C(\gamma)=\mathbb{E}\left[\log \left(1+\gamma|h|^{2}\right)\right] \tag{1.2}
\end{equation*}
$$

where $h$ is a random variable distributed according to the stationary distribution of $H$.
The frequency selective channel is defined analogously

$$
\mathbf{y}=\sqrt{\gamma} F G F^{*} \mathbf{x}+\mathbf{n}
$$

where $G$ is a diagonal matrix of fading coefficients, and $F$ is the unitary Fourier matrix, defined as $f_{j k}=\frac{1}{\sqrt{N}} e^{2 \pi i(j-1)(k-1)}$ for $j, k=1, \ldots, N$.

It now seems natural to look at the following channel

$$
\begin{equation*}
\mathbf{y}=\gamma H F G F^{*} \mathbf{x}+\mathbf{n} \tag{1.3}
\end{equation*}
$$

where we concatenate the effects of the two channels: we have both frequency-selective and time-selective fading. The problem becomes much more difficult to analyze as the interplay between the two types of fading is hard to control.

If we suppose that both fading processes are i.i.d., we have the following theorem, which satisfyingly answers our question concerning capacity.

Theorem 1.1 ([30]). Consider the channel model (1.3) with fading unknown at the transmitter, full channel state information at the receiver and $H$ and $G$ having i.i.d. entries. The capacity of this channel is given by

$$
\begin{equation*}
C(\gamma)=\mathbb{E}\left[\log \left(1+\alpha \gamma|g|^{2}\right)\right]+\mathbb{E}\left[\log \left(1+v \gamma|h|^{2}\right)\right]-\log (1+\alpha v \gamma) \tag{1.4}
\end{equation*}
$$

where

$$
\begin{aligned}
& 0 \leq \alpha \leq \mathbb{E}\left[|h|^{2}\right] \\
& 0 \leq v \leq \mathbb{E}\left[|g|^{2}\right]
\end{aligned}
$$

are coefficients that depend on $\gamma$ and on the fading distributions, and are defined to be the solution to

$$
\begin{equation*}
\mathbb{E}\left[\left(1+\alpha \gamma|g|^{2}\right)^{-1}\right]=(1+\alpha v \gamma)^{-1}=\mathbb{E}\left[\left(1+v \gamma|h|^{2}\right)^{-1}\right] \tag{1.5}
\end{equation*}
$$

The proof of this theorem relies on the fact that the matrices $H$ and $F G F^{*}$ are asymptotically free, a noncommutative analog of independence which we introduce next.

### 1.2.2 What is free probability?

In the now classical treatment of (commutative) probability theory, there is not much difference between measure theory and probability theory until the introduction of the concept of independence. This is arguably where the fields of analysis and probability diverge significantly in their vision of the objects under study. Similarly, it is with the notion of free independence (or freeness) [32] that noncommutative probability theory takes a life of its own. It is the noncommutative analog of independence in that it allows one to compute the joint distribution of random variables from their marginals. While this field of mathematics is rich and intricate and has shed some light on long standing conjectures in noncommutative geometry, it is the results concerning one particular noncommutative probability space which will be of interest to us: random matrices. Indeed, while finite dimensional matrices with random entries are typically difficult to handle outside of very specific cases, the situation is quite different when we let the dimension grow to infinity. Indeed, in many cases, and this is the main topic of investigation of the second chapter of this thesis, sets of random matrices converge to noncommutative random variables that are free: we say that these matrices are asymptotically free. With this notion in mind, it is possible to handle products such as the one that is of interest to us: $H F G F^{*}$.

### 1.2.3 Towards a more general model

We have seen that freeness is the tool that allows us to compute quantities of interest concerning the channel experiencing both frequency and time selective fading. One natural question is whether a wider class of channels could be analyzed in a similar way. Indeed, in the quoted result from [30], one of the fading processes can be replaced with a strongly mixing process instead of an i.i.d. process. The hope is to be able to model a wider array of channels, for example bursty channels. In [6], the concept of asymptotically liberating sequences was introduced and provides a satisfying framework to explain why the matrices $H$ and $F G F^{*}$ are asymptotically free. It yields freeness for a large class of matrices and brings forward the importance of the distribution invariance of the matrices under the action of the permutation group, obviously satisfied in the case of diagonal i.i.d. matrices.

One could hope to obtain similar results while decreasing the randomness of the model, for example introducing more dependencies between the entries, or asking for invariance under a strict subgroup of the group of permutations. In particular, extending these results to cases where one channel is deterministic would increase the robustness of the applicability to real life scenarios.

It is to answer this question that we look into the theory of traffics [14], a setting generalizing the notion of freeness between noncommutative random variables. We present a computable criterion prohibiting two matrices from being free and use it to show that for many reasonable generalizations the matrices $H$ and $F G F^{*}$ cannot be free. Using an extension of freeness appropriately coined traffic-freeness, it is possible to compute the moments of the joint distribution. However, the combinatorial nature of the problem makes this computationally prohibitive. Nonetheless, we manage to shed some light on certain cases of particular interest: the case where the entries of one of the diagonal matrices is a Markov chain with long range dependencies and the case where one of the matrices is deterministic.

## 2 Line of sight in Wireless Communication

While random matrices are useful tools for modelling different communication scenarios, they have certainly enjoyed their greatest success with the wireless medium. Due to the fading and to the mobility of users, several parameters of a wireless transmission are probabilistic quantities. When many users interact together, all the ingredients are present for the tools of random matrix theory to be most useful.

### 2.1 Modelling the situation

We will study the number of spatial degrees of freedom of distributed multiple-input multipleoutput (MIMO) transmissions in a wireless network with homogeneously distributed nodes, under the following classical line-of-sight propagation model between node $k$ and node $j$ in the network:

$$
\begin{equation*}
h_{j k}=\frac{e^{2 \pi i r_{j k} / \lambda}}{r_{j k}} . \tag{2.1}
\end{equation*}
$$

In the above equation, $\lambda$ is the carrier wavelength and $r_{j k}$ is the internode distance. From a mathematical point of view, these matrices are interesting objects, as they are halfway between purely random matrices with i.i.d. entries and fully deterministic matrices. Indeed, the internode distances $r_{j k}$ are random due to the random node positions, but there is a clear correlation between the matrix entries.

Let us recall that the degrees of freedom of a MIMO transmission are defined as the number of independent streams of information that can be conveyed simultaneously and reliably over the channel at high SNR. Under the assumption of a channel fading matrix $H$ with i.i.d. entries, this number of degrees of freedom is directly proportional to the number of antennas used for transmission and reception [27].

The performance of MIMO systems in line-of-sight environment has been analyzed by various authors (see e.g. [10,23]) in the literature. Our intention here is to study this performance in
the context of wireless networks, where large clusters of nodes are used as virtual multiple antenna arrays. In this case, MIMO transmissions may not benefit from all possible degrees of freedom; it was indeed observed in [9] that under the above propagation model (2.1), MIMO transmissions suffer from a spatial limitation; if $A$ denotes the network area, $n$ the number of nodes in the network (assumed to be uniformly distributed) and $\lambda$ the carrier wavelength, then the number of spatial degrees of freedom of any MIMO transmission in the network cannot exceed

$$
\begin{equation*}
\min (n, \sqrt{A} / \lambda) \tag{2.2}
\end{equation*}
$$

up to logarithmic factors. In case the network area $A$ remains reasonably large, this does not prevent the possibility of transmissions with full degrees of freedom in the network. Yet, transmissions between clusters of nodes confined to smaller areas and moreover separated by long distances may suffer from even more spatial limitations.


Figure 2.1 - Node distribution

In [13, 20], it was shown independently that for two clusters of area $A$ separated at distance $d$, as illustrated on Figure 2.1, at least the following spatial degrees of freedom could be achieved ${ }^{1}$ :

$$
\begin{cases}\min (n, \sqrt{A} / \lambda), & \text { when } 1 \leq d \leq \sqrt{A}  \tag{2.3}\\ \min (n, A /(\lambda d)), & \text { when } \quad \sqrt{A} \leq d \leq A / \lambda\end{cases}
$$

The situation is summarized on the graph in Figure 2.2, again up to logarithmic factors:

We see that the lower bound (2.3) matches the upper bound (2.2) in the case where the intercluster distance is smaller than or equal to the cluster radius $(d \leq \sqrt{A})$, but nothing similar holds for $d \geq \sqrt{A}$. Our aim in the present chapter is to close this gap and to show that in the regime where $d \geq \sqrt{A}$, the actual spatial degrees of freedom of the MIMO transmission do not exceed those found in (2.3) (up to logarithmic factors). As a corollary, this would imply that

[^0]

Figure 2.2 - Interplay between the degrees of freedom and the distance $d$.
when $d \geq A$, the number of degrees of freedom is bounded by 1 .
In order to show this, we rely on an approximation whose validity is not fully proven here; it is however discussed in detail at the end of this chapter. Our approach leads to an interesting result on the asymptotic behavior of the spectrum of random matrices that appear not to have been previously studied in the mathematical literature.

### 2.2 Spatial degrees of freedom

Let us consider two square clusters of area $A$ separated by a distance $d$, one containing $n$ transmitters and the other containing $n$ receivers uniformly distributed in their respective clusters, as illustrated on Figure 2.1. We are interested in estimating the number of spatial degrees of freedom of a MIMO transmission between the two clusters:

$$
Y_{j}=\sum_{k} \sqrt{F} h_{j k} X_{k}+Z_{j}, \quad j=1, \ldots, n,
$$

where $F$ is Friis' constant, the coefficients $h_{j k}$ are given by the line-of-sight fading model (2.1), the transmitted signal $X_{k}$ are subject to an average power constraint $\mathbb{E}\left[X_{k}\right]^{2} \leq P$ and $Z_{j}$ represents additive white Gaussian noise of power spectral density $N_{0}$ at receiver $j$. We denote by $W$ the bandwidth. The distance $r_{j k}$ between node $j$ at the receiver side and node $k$ at the transmitter side is given by

$$
\begin{equation*}
r_{j k}=\sqrt{\left(d+\sqrt{A}\left(x_{j}+w_{k}\right)\right)^{2}+A\left(y_{j}-z_{k}\right)^{2}} \tag{2.4}
\end{equation*}
$$

where $x_{j}, w_{k}, y_{j}, z_{k} \in[0,1]$ are normalized horizontal and vertical coordinates, as illustrated on Figure 2.3.

## Chapter 2. Line of sight in Wireless Communication



Figure 2.3 - The chosen parametrization

Assuming full channel state information and perfect cooperation of the nodes on both sides, the maximum number of bits per second and per Hertz that can be transferred reliably from the transmit cluster to the receive cluster over this MIMO channel is given by the following expression:

$$
\begin{array}{rlr}
C_{n} & =\max _{p_{X} \text { s.t. }}^{\mathbb{E}^{\left(\left|X_{i}\right|^{2}\right) \leq P, \forall i}} \mathfrak{I}(X, Y) & \text { maximizing mutual information } \\
& =\max _{p_{X} \text { s.t. } \mathbb{E}\left(\left|X_{i}\right|^{2}\right) \leq P, \forall i} H(Y)-H(Y \mid X) & \\
& =\max _{p_{X} \text { s.t. } \mathbb{E}\left(\left|X_{i}\right|^{2}\right) \leq P, \forall i} H(Y)-H(Z) & \\
& =\max _{Q_{X} \geq 0:\left(Q_{X}\right)_{i i} \leq P, \forall i} \log \operatorname{det}\left(\pi e Q_{Y}\right)-\log \operatorname{det}\left(\pi e\left(N_{0} W\right) I\right) & \text { WLOG } X \text { is Gaussian and centered } \\
& =\max _{Q_{X} \geq 0:\left(Q_{X}\right)_{i i} \leq P, \forall i} \log \operatorname{det}\left(I+\left(F /\left(N_{0} W\right)\right) H Q_{X}^{*} H^{*}\right) &
\end{array}
$$

where $Q_{X}$ is the covariance matrix of the input signal vector $X=\left(X_{1}, \ldots, X_{n}\right), Q_{Y}=F H Q_{X} H^{*}+$ $\left(N_{0} W\right) I$ and $P$ is the power constraint at each node. In order to simplify notation, we choose units so that the other parameters, such as Friis' constant $F$, the noise power spectral density $N_{0}$ and the bandwidth $W$ do not appear explicitly in the capacity expression:

$$
C_{n}=\max _{Q_{X} \geq 0: Q_{i i} \leq P, \forall i} \log \operatorname{det}\left(I+H Q H^{*}\right)
$$

One has to keep in mind here that unlike in the fast fading scenario, there is no expected value in front of this quantity. Indeed, the randomness comes from the node positions. This does not change over the time of the transmission.

In the sequel, we make the following two assumptions:

1) $d, A$ both increase ${ }^{2}$ with $n$ and satisfy the relation $\sqrt{A} \leq d \leq A / \lambda$, which is the regime of

[^1]interest to us (see Figure 2.2).
2) $P=\frac{(d+\sqrt{A})^{2}}{n}$; because the average distance between two nodes in opposite clusters is $d+\sqrt{A}$ and because the MIMO power gain is of order $n$, this power constraint ensures that the SNR of the incoming signal at each receiving node is of order 1 on average, so that the MIMO transmission operates at full power. Imposing this power constraint allows us to focus our attention on the spatial degrees of freedom of the system.

By choosing to transmit i.i.d. signals (i.e. taking $Q=P I$ ), we obtain a lower bound

$$
C_{n} \geq \log \operatorname{det}\left(I+P H H^{*}\right)
$$

and using Paley-Zygmund's inequality, the following result was further shown in [20].
Theorem 2.1. Under assumptions 1) and 2), there exists a constant $K_{1}>0$ such that

$$
C_{n} \geq \log \operatorname{det}\left(I+P H H^{*}\right) \geq K_{1} \min \left(n, \frac{A /(\lambda d)}{\log (A /(\lambda d))}\right)
$$

with high probability as $n$ gets large.

This result shows that the number of spatial degrees of freedom of the MIMO transmission can reach $A /(\lambda d)$ (up to a logarithmic factor), when the number of nodes participating to the MIMO transmission is large enough.

As mentioned in the introduction, a natural question is whether it is possible to find a corresponding matching upper bound on the capacity. In order to answer this question, let us first observe that any matrix $Q_{X}$ satisfying $Q_{X} \geq 0$ and $\left(Q_{X}\right)_{i i} \leq P$ for all $i$ also satisfies $Q_{X} \leq n P I$. Thus,

$$
\begin{equation*}
C_{n} \leq \log \operatorname{det}\left(I+n P H H^{*}\right)=\sum_{k=1}^{n} \log \left(1+\lambda_{k}\right) \tag{2.5}
\end{equation*}
$$

where $\lambda_{1} \geq \lambda_{2} \geq \ldots \geq \lambda_{n}$ are the eigenvalues of $n P H H^{*}$. The number of significant eigenvalues of $n P H H^{*}$ therefore determines the number of spatial degrees of freedom. The direct analysis of these eigenvalues appears to be difficult, so we proceed by approximating the matrix $n P H H^{*}$ by another matrix $G G^{*}$, easier to analyze.

Let $m=A /(\lambda d)$ (hence, by Assumption $1, m=n^{\delta}$ for $\delta>0$ ) and let $G$ be the matrix whose entries are given by

$$
\begin{equation*}
g_{j k}=e^{-2 \pi i m y_{j} z_{k}} \tag{2.6}
\end{equation*}
$$

where $y_{j}, z_{k}, l \leq j, k \leq n$ are the same random variables as in expression (2.4).

Claim 2.2. Under Assumptions 1 and 2, the following approximation holds:

$$
\log \operatorname{det}\left(I+n P H H^{*}\right)=\log \operatorname{det}\left(I+G G^{*}\right)(1+o(1))
$$

with high probability as $n$ gets large.

We discuss this approximation in detail in Section 2.4. For the time being, observe first that by expression (2.5), the above approximation is equivalent to saying that the number of significant eigenvalues of $n P H H^{*}$ and $G G^{*}$ do not differ in order as $n$ gets large. Some numerical evidence of this fact is provided on Figure 2.4 for a given set of parameters (a similar behaviour is observed for a wide range of parameters).


Figure 2.4 - Eigenvalues of $n P H H^{*}$ (blue) and $G G^{*}$ (red) for the parameters $n=500, A=$ $10^{\prime} 000 m^{2}, d=300 m, \lambda=0.1 m$ (so $m=A /(\lambda d) \simeq 333$ ).

It can be observed on Figure 2.4 that the eigenvalues drop to zero after a threshold of order $m=A /(\lambda d)$ for both matrices $n P H H^{*}$ and $G G^{*}$. Figure 2.5, a histogram of the two sets of eigenvalues greater than a small threshold, highlights the fact that the empirical eigenvalue distributions are also quite similar.

The rest of the present section is devoted to the proof of the following statement.
Theorem 2.3. Let $m=A /(\lambda d)$ be such that ${ }^{3} m \gg \sqrt{n}$. Then under assumptions 1) and 2),

[^2]

Figure 2.5 - Histogram of the eigenvalues of $n P H H^{*}$ and $G G^{*}$ greater than 0.1 for the parameters $n=500, A=10^{\prime} 000 m^{2}, d=300 m, \lambda=0.1 m$ (so $m=A /(\lambda d) \simeq 333$ ).
there exist constants $K_{2}, K_{3}>0$ independent of $\delta$ such that

$$
\frac{K_{2} \min (m, n)}{\log (n)} \leq \log \operatorname{det}\left(I+G G^{*}\right) \leq K_{3} \min (n, m) \log n
$$

with high probability as $n$ gets large.

This result shows that the lower bound found in Theorem 2.1 is tight (provided Claim 2.2 holds true and $m \gg \sqrt{n}$ ), which is saying that the number of spatial degrees of freedom of a MIMO transmission between two clusters of area $A$ separated by distance $d$ is of order $m=A /(\lambda d)$, up to logarithmic factors.

This result on matrices $G$ of the form (2.6) is interesting in itself, as these do not appear to have been studied before in the random matrix literature.

Proof of Theorem 2.3. We divide the proof of the theorem in 3 parts: a concentration result, the proof of the lower bound and finally the proof of the upper bound. We begin with the concentration argument.

Let $g_{n}=\log \operatorname{det}\left(I+G G^{*}\right)=\sum_{j=1}^{n} \log \left(1+\lambda_{j}\right)=g_{n}\left(y_{1}, \ldots, y_{n}, z_{1}, \ldots, z_{n}\right)$. We show that changing one argument cannot change the value of this function by too much. By symmetry, we can suppose that we are changing a $y$ variable, which amounts to changing a row of the matrix

## Chapter 2. Line of sight in Wireless Communication

$G$. Suppose this is the $k^{t h}$ row, corresponding to $y_{k}$. Consider the matrix $\tilde{G}$ with the $k^{t h}$ row replaced by a row of zeros. By the Cauchy interlacing property, we have that

$$
\lambda_{i-1} \leq \tilde{\lambda}_{i} \leq \lambda_{i}
$$

We can conclude that $\left|g_{n}-\tilde{g_{n}}\right| \leq \log \left(1+\lambda_{\max }\right)$. We can upper bound $\lambda_{\max }$ by the Frobenius norm of $G$ and so

$$
\left|g_{n}-\tilde{g_{n}}\right| \leq \log (1+n)
$$

Using the triangle inequality, we have that

$$
\left|g_{n}\left(y_{1}, \ldots, y_{k}, \ldots, y_{n}, z_{1}, \ldots, z_{n}\right)-g_{n}\left(y_{1}, \ldots, y_{k}^{\prime}, \ldots, y_{n}, z_{1}, \ldots, z_{n}\right)\right| \leq 2 \log (1+n)
$$

With this result in hand, we can turn to a standard result to prove concentration.
Theorem 2.4 (McDiarmid's inequality, see [16]). Let $X_{1}, \ldots X_{n}$ be a family of i.i.d. random variables and $f_{n}$ a measurable function. Suppose that the exists a constant $K_{n}$ such that

$$
\left|f_{n}\left(x_{1}, \ldots, x_{k}, \ldots, x_{n}\right)-f_{n}\left(x_{1}, \ldots, x_{k}^{\prime}, \ldots, x_{n}\right)\right| \leq K_{n}
$$

for any $1 \leq k \leq N, x_{k}^{\prime}$ being defined over the same set as the $x_{i}$ 's. Then for all $t>0$,

$$
\mathbb{P}\left(\left|f_{n}-\mathbb{E} f_{n}\right| \geq t\right) \leq 2 \exp \left(\frac{-2 \epsilon^{2}}{n K_{n}^{2}}\right)
$$

Applied to our particular case, we take $t=n^{1 / 2+\epsilon}$ and obtain

$$
\mathbb{P}\left(\left|g_{n}-\mathbb{E} g_{n}\right| \geq n^{1 / 2+\epsilon}\right) \leq 2 \exp \left(\frac{-2 n^{1+2 \epsilon}}{n 4 \log ^{2}(1+n)}\right)
$$

We therefore have the following concentration result: for all $\varepsilon>0$, there exists some constant $K>0$ such that

$$
\left|\log \operatorname{det}\left(I+G G^{*}\right)-\mathbb{E}\left(\log \operatorname{det}\left(I+G G^{*}\right)\right)\right| \leq K n^{1 / 2+\varepsilon}
$$

with high probability as $n$ gets large. As $m \gg \sqrt{n}$ by assumption, what remains to be shown is that there exist constants $K_{2}, K_{3}>0$ such that

$$
\frac{K_{2} \min (m, n)}{\log (m)} \leq \mathbb{E}\left(\log \operatorname{det}\left(I+G G^{*}\right)\right) \leq K_{2} \min (n, m) \log n
$$

as $n$ gets large. Observe that this is the only part of the proof that requires $m \gg \sqrt{n}$. It follows that a sharper concentration bound would immediately yield a stronger result in Theorem 2.3.

We now apply a similar technique as in [20] to obtain the lower bound on $\log \operatorname{det}\left(I+G G^{*}\right)$.

Let us consider $\lambda$, an eigenvalue of $G G^{*}$ picked uniformly at random. We have the following inequality

$$
\mathbb{E} \log \operatorname{det}\left(I+G G^{*}\right)=\mathbb{E} \sum_{j=1}^{n} \log \left(1+\lambda_{j}\right)=n \mathbb{E}(\log (1+\lambda)) \geq n \log (1+t) \mathbb{P}(\lambda \geq t)
$$

We will now use the Paley-Zygmund inequality to bound this last quantity.
Proposition 2.5 (Paley-Zygmund). Let $X$ be a non negative random variable. Then for $0 \leq t \leq$ $\mathbb{E}(X)$,

$$
\mathbb{P}(X \geq t) \geq \frac{[\mathbb{E}(X)-t]^{2}}{\mathbb{E}\left[X^{2}\right]}
$$

We therefore proceed to obtain a lower bound on the first moment and an upper bound on the second moment of $\lambda$.

The first moment of $\lambda$ is

$$
\mathbb{E}[\lambda]=\mathbb{E}\left(\frac{1}{n} \sum_{j} \lambda_{j}\right)=\mathbb{E} \frac{1}{n} \operatorname{Tr}\left(G G^{*}\right)=\frac{1}{n} \mathbb{E} \sum_{i j}\left|g_{i j}\right|^{2}=n
$$

An upper bound for the second moment is given by

$$
\begin{align*}
& \mathbb{E}\left[\lambda^{2}\right]=\mathbb{E}\left(\frac{1}{n} \sum_{j} \lambda_{j}^{2}\right)=\mathbb{E}\left(\frac{1}{n} \operatorname{Tr}\left(G G^{*} G G^{*}\right)\right)=\mathbb{E} \frac{1}{n} \sum_{i j k l} g_{i j} \overline{g_{k j}} g_{k l} \overline{g_{i l}}  \tag{2.7}\\
&=\frac{1}{n} \sum_{i j k l} \mathbb{E} e^{2 \pi i m\left(y_{j}-y_{k}\right)\left(z_{i}-z_{l}\right)} \leq \sum_{j k l} \int_{0}^{1} d y_{j} \int_{0}^{1} d y_{k}\left|\int_{0}^{1} e^{2 \pi i m z_{l}\left(y_{j}-y_{k}\right)} d z_{l}\right| \tag{2.8}
\end{align*}
$$

Observe that we can split the integral over the $y$ variables over two domains: $\Omega$ where $\left|y_{j}-y_{k}\right| \leq$ $\epsilon$ and the complement $\Omega^{c}$. Over $\Omega$, we can bound the integral by the volume of $A$, that is $2 \epsilon$, since the integrand is upper bounded by 1 . Over $\Omega^{c}$, we obtain

$$
\left|\iint d y_{j} d y_{k} \frac{1-e^{2 \pi i m z_{k}\left(y_{j}-y_{k}\right)}}{2 \pi i m\left(y_{j}-y_{k}\right)}\right| \leq \int_{0}^{1} d y_{j} 1_{\left\{\left|y_{j}-y_{k}\right| \geq \varepsilon\right\}} \frac{1}{\pi m} \frac{1}{\left|y_{j}-y_{k}\right|} \leq \frac{1}{2 \pi m} \log \left(\frac{1}{\epsilon}\right)
$$

By choosing $\epsilon=1 / m$, we get that Equation (2.7) is upper bounded by $\frac{2 n^{3} \log m}{m}$. The above derivation is correct if $j \neq k$ and $i \neq l$. If $j=k$ or $i=l$, by bounding the integrand by 1 in (2.7),
we get that the sum is at most of the order of $n^{2}$.
We will use a similar technique in Section 2.3 to upper bound the largest eigenvalue. Plugging these moment estimates into the Paley-Zygmund inequality yields

$$
\begin{aligned}
\mathbb{E} \log \operatorname{det}\left(I+G G^{*}\right) & \geq n \log (1+t) \mathbb{P}(\lambda \geq t) \\
& \geq n \log (1+t) \frac{[\mathbb{E}(\lambda-t)]^{2}}{\mathbb{E}\left(\lambda^{2}\right)} \\
& \geq n \log (1+t) \frac{(n-t)^{2}}{n^{3} \log (m) / m} \\
& \geq K m / \log (m) \quad \text { choosing for example } t=n / 2
\end{aligned}
$$

This completes the proof of the lower bound. There now remains to upper bound the expected value $\mathbb{E}\left(\log \operatorname{det}\left(I+G G^{*}\right)\right)$. Let us first state the Cauchy-Binet theorem, which will be of use in the proof. For a matrix $A$, let $A_{\mathscr{\mathscr { C }} \times \mathscr{\mathscr { I }}}$ represent the matrix where only the rows in the index set $\mathscr{J}$ and only the columns in the index set $\mathscr{I}$ are present.

## Lemma 2.6.

$$
\operatorname{det}(I+A)=\sum_{\mathscr{\mathscr { C }}\{\{1, \ldots, n\}} \operatorname{det}\left(A_{\mathscr{J} \times \mathscr{J}}\right)
$$

Lemma 2.7 (Cauchy-Binet Theorem). Let $A$ and $B$ be two matrices of dimensions $m \times n$ and $n \times m$ respectively. Then

$$
\operatorname{det}(A B)=\sum_{\substack{\mathscr{\mathscr { C }}\{\{1, \ldots, n\} \\|\mathscr{A}|=m}} \operatorname{det}\left(A_{m \times \mathscr{J}}\right) \operatorname{det}\left(B_{\mathscr{\mathscr { A }} \times m}\right)
$$

In order to upperbound $\mathbb{E}\left(\log \operatorname{det}\left(I+G G^{*}\right)\right)$, let us now expand the determinant:

$$
\begin{align*}
& \mathbb{E}\left(\log \operatorname{det}\left(I+G G^{*}\right)\right)  \tag{2.10}\\
& =\mathbb{E}\left(\log \left(1+\sum_{k=1}^{n} \sum_{\substack{\mathcal{C}[1] 11, n) \\
|\mathcal{A}|=k}} \operatorname{det}\left(G_{\mathscr{J} \times n} G_{\mathscr{\mathscr { A }} \times n}^{*}\right)\right)\right)  \tag{2.11}\\
& \leq \log \left(1+\sum_{k=1}^{n} \sum_{\substack{\mathcal{G}[1](n) \\
|\mathcal{A}|=k}} \mathbb{E}\left(\operatorname{det}\left(G_{\mathscr{\mathscr { O }} \times n} G_{\mathscr{J} \times n}^{*}\right)\right)\right. \tag{2.12}
\end{align*}
$$

where we used Jensen's inequality. Using the fact that the $y_{j}$ are i.i.d., we further obtain that $\mathbb{E}\left(\operatorname{det}\left(G_{\mathscr{g} \times n} G_{\mathscr{g} \times n}^{*}\right)\right)$ only depends on the size $k$ of the subset $\mathscr{J}$, so

$$
\begin{align*}
& \mathbb{E}\left(\log \operatorname{det}\left(I+G G^{*}\right)\right)  \tag{2.13}\\
& \leq \log \left(1+\sum_{k=1}^{n}\binom{n}{k} \mathbb{E}\left(\operatorname{det} G_{k \times n} G_{k \times n}^{*}\right)\right) \tag{2.14}
\end{align*}
$$

$$
\begin{align*}
& =\log \left(1+\sum_{k=1}^{n}\binom{n}{k} \mathbb{E}\left(\sum_{\substack{\mathscr{C}\{\{1, \ldots n\} \\
|\mathscr{A}|=k}} \operatorname{det}\left(G_{k \times \mathscr{I}} G_{k \times \mathscr{I}}^{*}\right)\right)\right)  \tag{2.15}\\
& =\log \left(1+\sum_{k=1}^{n}\binom{n}{k}^{2} \mathbb{E}\left(\operatorname{det}\left(G_{k \times k} G_{k \times k}^{*}\right)\right)\right) \tag{2.16}
\end{align*}
$$

where we have used this time the Cauchy-Binet formula together with the fact that the $z_{k}$ are i.i.d. We thus see that in order to upperbound $\mathbb{E}\left(\log \operatorname{det}\left(I+G G^{*}\right)\right)$, it is enough to control $\mathbb{E}\left(\operatorname{det}\left(G_{k \times k} G_{k \times k}^{*}\right)\right)$, where $G_{k \times k}$ is the upper left $k \times k$ submatrix of $G$.

We show in the following that, similarly to what has been observed numerically for the eigenvalues $\lambda_{k}$, $\mathbb{E}\left(\operatorname{det}\left(G_{k \times k} G_{k \times k}^{*}\right)\right)$ drops rapidly for $k$ greater than a given threshold of order $m$, which implies the result.

Let $S_{k}$ denote the group of permutation on $k$ elements. Using the definition of the determinant, we obtain

$$
\begin{aligned}
& \mathbb{E}\left(\operatorname{det}\left(G_{k \times k} G_{k \times k}^{*}\right)\right) \\
& =\sum_{\sigma, \tau \in S_{k}}(-1)^{|\sigma|+|\tau|} \mathbb{E}\left(\prod_{j=1}^{k} g_{j, \sigma(j)} \overline{g_{j, \tau(j)}}\right) \quad \text { the determinant is multiplicative } \\
& =k!\sum_{\sigma \in S_{k}}(-1)^{|\sigma|} \mathbb{E}\left(\prod_{j=1}^{k} g_{j j} \overline{g_{j, \sigma(j)}}\right) \quad \text { using symmetry, we suppose one permutation is the identity, }
\end{aligned}
$$

which in turn leads to

$$
\begin{align*}
& \mathbb{E}\left(\operatorname{det}\left(G_{k \times k} G_{k \times k}^{*}\right)\right)  \tag{2.17}\\
& =k!\sum_{\sigma \in S_{k}}(-1)^{|\sigma|} \mathbb{E}_{Z}\left(\prod_{j=1}^{k} \mathbb{E}_{Y}\left(e^{-2 \pi i m y_{j}\left(z_{j}-z_{\sigma(j)}\right)}\right)\right) \quad \text { by independence of the } y_{i}  \tag{2.18}\\
& =k!\sum_{\sigma \in S_{k}}(-1)^{|\sigma|} \mathbb{E}_{Z}\left(\prod_{j=1}^{k} \frac{1-e^{-2 \pi i m\left(z_{j}-z_{\sigma(j)}\right)}}{2 \pi i m\left(z_{j}-z_{\sigma(j)}\right)}\right)  \tag{2.19}\\
& =k!\mathbb{E}_{Z}\left(\operatorname{det}\left(\left\{\frac{1-e^{-2 \pi i m\left(z_{j}-z_{l}\right)}}{2 \pi i m\left(z_{j}-z_{l}\right)}\right\}_{1 \leq j, l \leq k}\right)\right) . \tag{2.20}
\end{align*}
$$

Multiplying row $j$ by $e^{\pi i m z_{j}}$ and column $l$ by $e^{-\pi i m z_{l}}$, we reduce the problem to computing the following determinant:

$$
E_{k}:=\mathbb{E}_{Z}\left(\operatorname{det}\left(\left\{\frac{\sin \left(\pi m\left(z_{j}-z_{l}\right)\right)}{\pi m\left(z_{j}-z_{l}\right)}\right\}_{1 \leq j, l \leq k}\right)\right)
$$

Operators and Fredholm Theory. The key observation is that the above expected value of the determinant can be seen as a classically studied quantity in the Fredholm theory of integral operators. This allows us to deduce precise estimates. A reference for the material discussed below is [21].

Consider the continuous kernel $K_{m}(x, y)=\frac{\sin (m(x-y))}{\pi(x-y)}$ on $[0,1]^{2}$ and the associated operator $K_{m}: C([0,1]) \rightarrow C([0,1])$ defined as

$$
K_{m} \phi(x)=\int_{0}^{1} \frac{\sin (m(x-y))}{\pi(x-y)} \phi(y) d y
$$

The $p^{t h}$ iterated kernel $K^{p}$ of an operator $K$ is defined as $K^{1}=K$ and

$$
K^{p}(x, y)=\int_{0}^{1} K^{p-1}(x, z) K(z, y) d z
$$

Associated to this is the $p^{t h}$ trace of $K$ :

$$
A_{p}=\int_{0}^{1} K^{p}(x, x) d x
$$

Define as well the compound kernel $K_{[p]} \in C\left([0,1]^{2 p}\right)$ as

$$
K_{[p]}(\mathbf{x}, \mathbf{y})=\operatorname{det}\left(\begin{array}{cccc}
K\left(x_{1}, y_{1}\right) & K\left(x_{1}, y_{2}\right) & \ldots & K\left(x_{1}, y_{p}\right) \\
\vdots & \vdots & \ddots & \vdots \\
K\left(x_{p}, y_{1}\right) & K\left(x_{p}, y_{2}\right) & \ldots & K\left(x_{p}, y_{p}\right)
\end{array}\right)
$$

for $\mathbf{x}=\left(x_{1}, \ldots, x_{p}\right)$ and $\mathbf{y}=\left(y_{1}, \ldots, y_{p}\right)$. In this notation, the quantity we are interested in is

$$
\mathbb{E}_{Z}\left(\operatorname{det}\left(\left\{\frac{\sin \left(\pi m\left(z_{j}-z_{l}\right)\right)}{\pi m\left(z_{j}-z_{l}\right)}\right\}_{1 \leq j, l \leq k}\right)\right)=k!\frac{1}{m^{k}} d_{k}
$$

where

$$
d_{k}=\frac{1}{k!} \int_{[0,1]^{k}} K_{m,[k]}(\mathbf{x}, \mathbf{x}) d x_{1} \cdots d x_{k}
$$

Since our original kernel $K_{m}$ is a compact operator, it has a discrete spectrum $\mu_{1} \geq \mu_{2} \geq \ldots$. By the definition of $A_{p}$, we see that $A_{p}=\sum \mu_{i}^{p}$.

The following lemma relates the quantity of interest $d_{k}=\frac{m^{k}}{k!} E_{k}$ to the eigenvalues $\mu_{i}$ of the kernel $K_{m}$.

Lemma 2.8.

$$
\begin{equation*}
d_{k}=\sum_{j_{1}<j_{2}<\ldots<j_{k}} \mu_{j_{1}} \mu_{j_{2}} \cdots \mu_{j_{k}} . \tag{2.21}
\end{equation*}
$$

Proof. This follows from the fact that $d_{k}$ and $A_{p}$ are related by the following recurrence relation:

$$
k d_{k}=\sum_{p=1}^{k}(-1)^{p-1} A_{p} d_{k-p}
$$

which follows from expanding the determinant in the definition of $K_{[p]}$ and regrouping equal
terms (see [21]).Using the fact that $A_{p}=\sum_{i} \mu_{i}^{p}$, it can be seen that the only solution to the above recurrence (with $d_{0}=1$ ) is given by Equation (2.21).

We conclude that it is sufficient to estimate the eigenvalues of the operator $K_{m}$ in order to upperbound $d_{k}$.

Since the kernel $K_{m}$ is translation invariant, it can be defined equivalently on [ $-1 / 2,1 / 2$ ], and this new operator has the same eigenvalues. This operator is called the sinc kernel and is well known in signal processing, since it is the Fourier transform of the indicator function. It was originally studied by D. Slepian in [24] and precise estimates exist on its eigenvalues. In particular, we have the following recent result from [2, Theorem 3]:
Theorem 2.9. Let $\delta>0$. There exists $M \geq 1$ and $c>0$ such that, for all $m \geq 0$ and $k \geq$ $\max (M, c m)$,

$$
\mu_{k} \leq e^{-\delta(k-c m)}
$$

This theorem essentially says that the eigenvalues $\mu_{k}$ decay exponentially for $k \geq \mathrm{cm}$. The direct consequence of this is that $d_{k}$ decays like $\exp \left(-\delta(k-c m)^{2} / 2\right)$ for $k \geq c m$, as we show below.

Indeed, it follows that if we take $k$ sufficiently large (i.e. larger than cm ), the sum in (2.21) always contains at least one term with exponential decay. We will upperbound all terms coming before $c m$ by 1 . Let $a_{i}$ be the sum of the terms with exactly $i$ terms after $\mathrm{cm}^{\text {th }}$ eigenvalue.

$$
a_{i}=\sum_{j_{1}<j_{2}<\ldots<j_{k-i}<c m} \delta_{j_{1}} \delta_{j_{2}} \ldots \delta_{j_{k-i}} \sum_{c m \leq j_{k-i+1}<\ldots<j_{k}} \delta_{j_{k-i+1}} \delta_{j_{k}}
$$

All the $\delta_{j}$ in the first sum are upperbounded by 1 and there are $\binom{c m}{k-i}$ ways to pick the indices. As such,

$$
\begin{aligned}
a_{i} & \leq\binom{ c m}{k-i}_{j_{k-i+1}=c m+1<\ldots j_{k}} e^{-\delta j_{k-i+1}} \ldots e^{-\delta j_{k}} \\
& \leq\binom{ c m}{k-i}_{j_{k-i+1} \geq c m+1, j_{j-i+2} \geq c m+2, \ldots j_{k} \geq c m+i} e^{-\delta j_{k-i+1}} \ldots e^{-\delta j_{k}} \quad \text { relaxing the ordering constraint } \\
& \leq\binom{ c m}{k-i} \frac{e^{-\delta}}{1-e^{-\delta}} \frac{e^{-2 \delta}}{1-e^{-\delta}} \cdots \frac{e^{-i \delta}}{1-e^{-\delta}} \\
& \leq\binom{ c m}{k-i} \frac{1}{\left(1-e^{-\delta}\right)^{i}} e^{-\delta i(i+1) / 2}
\end{aligned}
$$

$$
\leq 4^{c m / 2}\left(1-e^{-\delta}\right)^{-i} e^{-\delta i(i+1) / 2}
$$

using Stirling's approximation

We can crudely upper bound the sum of the $a_{i}$ as

$$
d_{k}=\sum_{i=k-c m}^{k} a_{i} \leq c m 4^{c m / 2} C^{(k-c m)} e^{-\delta(k-c m)^{2}}
$$

for some constant $C>0$.
This gives us the estimate we were after for $d_{k}$ :

$$
d_{k} \leq \begin{cases}1, & \text { if } k \leq c m  \tag{2.22}\\ c m 4^{c m / 2} C^{k-c m} e^{-\delta(k-c m)^{2} / 2}, & \text { if } k>c m\end{cases}
$$

Gathering the estimates (2.12) (2.14) and (2.22) together, we finally obtain

$$
\begin{aligned}
& \mathbb{E}\left(\log \operatorname{det}\left(I+G G^{*}\right)\right) \\
& \leq \log \left(1+\sum_{k=1}^{n}\binom{n}{k}^{2} \frac{k!^{2}}{m^{k}} d_{k}\right) \leq \log \left(1+\sum_{k=1}^{n} \frac{n^{2 k}}{m^{k}} d_{k}\right) \\
& \leq \log \left(1+\sum_{k=1}^{c m} n^{2 k}+\sum_{k=c m+1}^{n} n^{2 k} c m 4^{c m / 2} C^{k-c m} e^{-\delta(k-c m)^{2} / 2}\right) \\
& \leq(c m+1) \log n+O(1),
\end{aligned}
$$

which concludes the proof of Theorem 2.3.

Remark 2.10. Since Theorem 2.3 states that in the case of $n=m$ there are $n$ degrees of freedom, one might get the impression that the matrix $G G^{*}$ behaves as an i.i.d. matrix. We refer to Figure 2.6 where the histograms of the eigenvalues of $G G^{*}$ and $L L^{*}$ for $L$ i.i.d. are plotted. We see that these distributions are quite different. However, numerical simulations indicate that if we set $m=n^{2}$, the histograms of the eigenvalues match almost perfectly.

### 2.3 Maximal Eigenvalue

Our second contribution concerns the spectral radius (or largest eigenvalue) of the matrix $G G^{*} / n$. The largest eigenvalue is of interest in many practical scenarios, for example when several antennas are to be aligned for a beamforming gain. In our case, it allows us get a better idea of the size of the significant eigenvalues, which is related to the number of degrees of freedom. We show below that, again in the regime where $m=n^{\delta}$ and $1 / 2<\delta<1$, and again


Figure 2.6 - Histogram of the eigenvalues of $G G^{*}$ and $L L^{*}$ for $L$ i.i.d.
up to a logarithmic factor, this spectral radius does not exceed $n / m$. Observe that

$$
n=\operatorname{tr}\left(G G^{*} / n\right)=\sum_{j=1}^{n} \lambda_{j}
$$

where $\lambda_{1}, \ldots, \lambda_{n}$ are the eigenvalues of $G G^{*} / n$. The two results concerning the scaling of the spectral radius and the behaviour of $\log \operatorname{det}\left(I+G G^{*}\right)$ indicate that the $m$ significant eigenvalues of $G G^{*} / n$ are roughly of the same order $n / m$ (otherwise they could not sum up to $n$ ). In Figure 2.7, we see that indeed, while there is some fluctuation, many eigenvalues lie close to $\mathrm{n} / \mathrm{m}$.

Theorem 2.11. Let $m=n^{\delta}$ with $1 / 2<\delta \leq 1$. Then there exists a constant $K_{3}>0$ such that

$$
\mathbb{E}\left(\lambda_{\max }\left(G G^{*} / n\right)\right) \leq K_{3}(n / m) \log n
$$

and for every $\varepsilon>0$,

$$
\lambda_{\max }\left(G G^{*} / n\right) \leq K_{3}(n / m) n^{\varepsilon}
$$

with high probability as $n \rightarrow \infty$.

Proof. We use the following inequality, valid for any integer $l \geq 0$, as well as Jensen's inequality,


Figure 2.7 - Plot of the eigenvalues of $G G^{*} / n$ with $n=500$ and $m=333$.
to obtain:

$$
\begin{equation*}
\mathbb{E}\left(\lambda_{\max }\left(G G^{*} / n\right)\right) \leq \mathbb{E}\left[\left(\operatorname{Tr}\left(\frac{G G^{*}}{n}\right)^{l}\right)^{1 / l}\right] \leq\left[\mathbb{E}\left(\operatorname{Tr} \frac{G G^{*}}{n}\right)^{l}\right]^{1 / l} \tag{2.23}
\end{equation*}
$$

This reduces the problem to computing

$$
\begin{equation*}
\frac{1}{n^{l}} \mathbb{E}\left(\sum_{\substack{1 \leq j_{1}, j_{2}, \ldots j_{l} \leq n \\ 1 \leq k_{1}, k_{2}, \ldots k_{l} \leq n}} g_{j_{1} k_{1}} \overline{g_{j_{2} k_{1}}} \ldots g_{j_{l} k_{l}} \overline{g_{j_{1} k_{l}}}\right) \tag{2.24}
\end{equation*}
$$

We analyze the expected value of each summand. We start with a subcase easier to deal with.

### 2.3.1 All indices are different

Suppose first all the indices are different, i.e. $j_{1} \neq j_{2} \neq \ldots \neq j_{l}$ and $k_{1} \neq k_{2} \neq \ldots \neq k_{l}$. There are of the order of $n^{2 l}$ such terms. Concretely, we get the following multiple integral for each term.

$$
\begin{equation*}
\frac{1}{n^{l}} \int_{[0,1]^{2 l}}\left\{d y_{j} d z_{k}\right\} e^{-2 \pi i m\left[z_{1}\left(y_{2}-y_{1}\right)+z_{2}\left(y_{3}-y_{2}\right)+\ldots+z_{l}\left(y_{1}-y_{l}\right)\right]} \tag{2.25}
\end{equation*}
$$

For every $j$, we have

$$
\int_{0}^{1} d z_{j} e^{-2 \pi i m z_{j}\left(y_{j+1}-y_{j}\right)}=\frac{1-e^{-2 \pi i m\left(y_{j+1}-y_{j}\right)}}{2 \pi i m\left(y_{j+1}-y_{j}\right)}
$$

so

$$
\left|\int_{0}^{1} d z_{j} e^{-2 \pi i m z_{j}\left(y_{j+1}-y_{j}\right)}\right| \leq \max \left\{1, \frac{1}{\pi m} \frac{1}{\left|y_{j+1}-y_{j}\right|}\right\}
$$

where the first term is obtained by simply using that the integrand on the left-hand side is upperbounded by 1 . Observe next that

$$
\int_{0}^{1} d y_{j} 1_{\left\{\left|y_{j+1}-y_{j}\right| \geq \varepsilon\right\}} \frac{1}{\pi m} \frac{1}{\left|y_{j+1}-y_{j}\right|} \leq \frac{1}{\pi m} \log \left(\frac{1}{\varepsilon}\right)
$$

The above computation works because we can integrate over $y_{j}$. We therefore pick a component of the exponential, say $z_{1}\left(y_{2}-y_{1}\right)$, and upperbound $e^{2 \pi i m z_{1}\left(y_{2}-y_{1}\right)}$ by 1 . We can now apply the above procedure to $z_{2}\left(y_{3}-y_{2}\right)$ since $y_{2}$ appears only once in the integral. Observe that by integrating $y_{2}$, we obtain a bound which is independent of $y_{3}$, the other variable multiplying $z_{2}$. We have thus reduced the occurrence of $y_{3}$, which now only appears once in the integrand. We can therefore repeat the above procedure with $z_{3}$. Repeating this procedure $l-1$ times, each time removing the volume where the $y$ variables are less than $\epsilon$ apart, we obtain a bound of the form

$$
\int_{[0,1]^{2 l}}\left\{d y_{j} d z_{k}\right\} e^{-2 \pi i m\left[z_{1}\left(y_{2}-y_{1}\right)+z_{2}\left(y_{3}-y_{2}\right)+\ldots+z_{l}\left(y_{1}-y_{l}\right)\right]} \leq\left[\frac{1}{\pi m} \log \left(\frac{1}{\varepsilon}\right)\right]^{l-1}
$$

We will call this procedure successive integration.
One must also take care of the part of the domain of integration where $\left|y_{j+1}-y_{j}\right|<\epsilon$ for any of the $j=1,2 \ldots l$. Since this has volume at most $2 \epsilon$ and the original integrand is bounded by 1 , one can apply the same integration trick as above when $\left|y_{j+1}-y_{j}\right|>\epsilon$ and bound by $\epsilon$ when $\left|y_{j+1}-y_{j}\right|<\epsilon$.

Suppose that exactly $i$ of the $y$ variables are less than $\epsilon$ apart. We then get a bound of the form

$$
\left(\frac{2 \log (1 / \varepsilon)}{\pi m}\right)^{l-i-1}(2 \varepsilon)^{i}
$$

Since there are $\binom{l}{i}$ ways to choose these variables, if one takes $2 \varepsilon=\frac{1}{m}$, one gets that (2.25) is
bounded above by

$$
\begin{aligned}
\frac{1}{n^{l}} \sum_{i=0}^{l}\binom{l}{i}\left(\frac{2 \log (m)}{\pi m}\right)^{l-i-1}\left(\frac{1}{m}\right)^{i} & \leq \frac{1}{n^{l}} \sum_{i=0}^{l}\binom{l}{i}\left(\frac{2 \log (m)}{\pi m}\right)^{l-1} \\
& \leq 2 \frac{1}{n^{l}}\left(\frac{1}{m}\right)^{l-1}\left(\frac{4 \log (m)}{\pi}\right)^{l-1}
\end{aligned}
$$

As there are of the order of $n^{2 l}$ such terms, this gives us the desired bound in the particular subcase where all the indices are different.

$$
\frac{1}{n^{l}} \mathbb{E}\left(\sum_{\substack{1 \leq j_{1}, j_{2}, \ldots j j_{l} \leq n \\ 1 \leq k_{1}, k_{2}, \ldots k_{l} \leq n}} g_{j_{1} k_{1}} \overline{g_{j_{2} k_{1}}} \ldots g_{j_{l} k_{l}} \overline{g_{j_{1} k_{l}}}\right) \leq 2\left(\frac{4 n \log (m)}{\pi m}\right)^{l-1} n
$$

Indeed, after choosing $l$ sufficiently large and taking the $l^{t h}$ root, we will obtain the scaling we are after.

### 2.3.2 Some indices repeat

When indices repeat, the situation becomes a bit more involved. If $y_{j}=y_{j+1}$ or $z_{k}=z_{k+1}$ then, after relabeling, we have simply reduced the problem to the case $l-1$, so we can without loss of generality assume that no consecutive indices are the same. We start with the following lemma

Lemma 2.12. If successive cancellation is possible when no $z$ variables are identified, then it is possible when some $z$ variables are identified.

Proof. Key to successive cancellation as presented in the above section is the fact that integrating out a $y$ variable eliminates the occurrence of another $y$ variable. This allow to continue the procedure with this last variable. When $z_{j}=z_{j^{\prime}}$ for $j^{\prime} \neq j+1$, we get a term of the form $\left(\frac{1}{y_{j+1}-y_{j}+y_{k+1}-y_{k}}\right)$ after integration over $z_{j}$. When we integrate over $y_{j}$, the occurrence of all remaining $y$ variables will be reduced. There will therefore certainly be one $y$ variable which occurs only once in the remaining integral. Observe that this will make the splitting of the domain of integration more involved (i.e. we must ensure that $\left|y_{j+1}-y_{j}+y_{k+1}-y_{k}\right| \geq \epsilon$ ) but that does not compromise the rest of the argument.

Having taken care of repetitions in the $z$ variables, we now take a look at identified $y$ variables. Observe that if $i$ pairs of $y$ variables are identified, there will be of the order of $n^{2 l-i}$ terms in the sum of (2.24), and so to get the same bound as in the previous section, we can afford to bound an extra $i$ of the $z$ variables by 1 in the original integral (2.25). We therefore have some
liberty in making the integrand similar to the situation without identification.
We introduce a combinatorial way to look at the problem. We use Lemma 2.12 to assume that all the $z$ variables are different. Consider a graph whose vertices are the variables $y_{j}$ and with an edge between two vertices if the $y$ variables appear in front of the same $z$ variable in (2.25), after possible identifications of $y$ variables. A leaf in this graph is a $y$ variable to which we can apply successive cancellation. For example, when all the $y_{j}$ 's are different, the graph we obtain is a cycle. When we initiate successive cancellation, we then delete one edge (the equivalent of bounding a term by 1 in the original integral) and get a line. This allows us to use successive cancellation since the graph is a tree. Hence, we must show that, given a cycle, if we remove $i$ vertices by identification (without creating 1-edge loops), we can remove $i+1$ edges and obtain a tree. Consider a Eulerian cycle in such a graph (all the degrees are even). We count the number of cycles we encounter by travelling on this cycle. By the definition of a cycle, it must start and end at the same vertex, i.e. a vertex that has been identified. Hence, there can be no more cycles than identified vertices (not counting the full Eulerian cycle). This shows that the number of cycles is upper bounded by $i+1$, proving the claim. See Figure 2.8.


Figure 2.8 - Illustration of the graphical representation of the successive cancellation procedure. Here the partition of the vertices is $\{\{1,4,6\},\{3,8\},\{2\},\{5\},\{7\}\}$.

Therefore, if $i$ of the $y$ variables are identified, we obtain the following estimate

$$
\frac{1}{n^{l}} \mathbb{E}\left(\sum_{\substack{1 \leq j_{1}, j_{2}, \ldots . . j \leq n \\ 1 \leq k_{1}, k_{2}, \ldots k_{l} \leq n}} g_{j_{1} k_{1}} \overline{g_{j_{2} k_{1}}} \ldots g_{j_{l} k_{l}} \overline{g_{j_{1} k_{l}}}\right) \leq 2\left(\frac{4 n \log (m)}{\pi m}\right)^{l-i-1} n
$$

We can now do the same over all possible identifications and so the sum over all indices gives us the desired bound:

$$
\mathbb{E}\left(\lambda_{\max }\left(G G^{*} / n\right)\right) \leq\left[\frac{1}{n^{l}} \mathbb{E}\left(\sum_{\substack{1 \leq j_{1}, j_{2}, \ldots j_{l} \leq n \\ 1 \leq k_{1}, k_{2}, \ldots k_{l} \leq n}} g_{j_{1} k_{1}} \overline{g_{j_{2} k_{1}}} \ldots g_{j_{l} k_{l}} \overline{g_{j_{1} k_{l}}}\right)\right]^{1 / l}
$$

$$
\begin{aligned}
& \leq\left[\frac{1}{n^{l}} \sum_{i=0}^{l}\binom{l}{i} 2\left(\frac{4 \log (m)}{\pi m}\right)^{l-i-1} n^{2 l-i}\right]^{1 / l} \\
& \leq\left[C 2^{l+1}\left(\frac{4 \log (m) n}{\pi m}\right)^{l-1} n\right]^{1 / l} \\
& \leq C^{\prime} \frac{n \log (m)}{m}
\end{aligned}
$$

for $l$ sufficiently large

Here the index $i$ counts the number of $y$ indices that are paired up.
The second inequality may be obtained using Markov's inequaility:

$$
\begin{aligned}
\mathbb{P}\left(\lambda_{\max }\left(G G^{*} / n\right) \geq K_{3}(n / m) n^{\varepsilon}\right) & \leq \frac{\mathbb{E}\left(\left(\lambda_{\max }\left(G G^{*} / n\right)\right)^{l}\right)}{\left(K_{3}(n / m)\right)^{l} n^{\varepsilon l}} \\
& \leq \frac{(\log n)^{l}}{n^{\varepsilon l}}
\end{aligned}
$$

which, for any fixed $\varepsilon>0$, can be made arbitrarily small by taking $l$ sufficiently large.

### 2.4 Discussion

Our aim in the following is to provide a justification for Claim 2.2. Here, we use the stronger assumption that $A^{3 / 2} / d^{2} \rightarrow 0$. Let us first recall the definition of both $H$ and $G$ :

$$
h_{j k}=\frac{e^{2 \pi i r_{j k} / \lambda}}{r_{j k}} \quad \text { and } \quad g_{j k}=e^{-2 \pi i m y_{j} z_{k}}
$$

where $m=A /(\lambda d)$ and

$$
r_{j k}=\sqrt{\left(d+\sqrt{A}\left(x_{j}+w_{k}\right)\right)^{2}+A\left(y_{j}-z_{k}\right)^{2}}
$$

Given the chosen power constraint $P$ and the fact that $d \geq \sqrt{A}$, it follows that the amplitude of the normalized fading coefficent $\sqrt{n P} h_{j k}$ is of order 1 , matching that of $g_{j k}$. Let us now compare the phases of these two coefficients. Using a Taylor approximation to quadratic order $\sqrt{1+x} \simeq 1+x / 2-x^{2} / 8$, we get

$$
\begin{aligned}
& r_{j k}= d \sqrt{1+2 \frac{\sqrt{A}}{d}\left(x_{j}+w_{k}\right)+\frac{A}{d^{2}}\left[\left(x_{j}+w_{k}\right)^{2}+\left(y_{j}-z_{k}\right)^{2}\right]} \\
& \simeq d\left[1+\frac{1}{2}\left[2 \frac{\sqrt{A}}{d}\left(x_{j}+w_{k}\right)+\frac{A}{d^{2}}\left[\left(x_{j}+w_{k}\right)^{2}+\left(y_{j}-z_{k}\right)^{2}\right]\right]\right. \\
&\left.-\frac{1}{8}\left[1+2 \frac{\sqrt{A}}{d}\left(x_{j}+w_{k}\right)+\frac{A}{d^{2}}\left[\left(x_{j}+w_{k}\right)^{2}+\left(y_{j}-z_{k}\right)^{2}\right]\right]^{2}\right]
\end{aligned}
$$

$$
\begin{aligned}
& \simeq d+\frac{1}{2}\left[2 \sqrt{A}\left(x_{j}+w_{k}\right)+\frac{A}{d}\left[\left(x_{j}+w_{k}\right)^{2}+\left(y_{j}-z_{k}\right)^{2}\right]\right] \\
&-\frac{1}{8}\left[4 \frac{A}{d}\left(x_{j}+w_{k}\right)^{2}+2 \frac{A^{3 / 2}}{d^{2}}[\ldots]\right] \\
& \simeq d+\sqrt{A}\left(x_{j}+w_{k}\right)+\frac{A}{2 d}\left(y_{j}-z_{k}\right)^{2}
\end{aligned}
$$

Hence,

$$
e^{2 \pi i r_{j k} / \lambda} \simeq \widetilde{h}_{j k}:=e^{2 \pi i\left(u_{j}+v_{k}-(A /(\lambda d)) y_{j} z_{k}\right)}
$$

where

$$
\left\{\begin{array}{l}
u_{j}=\left(d / 2+\sqrt{A} x_{j}+(A / d) y_{j}^{2} / 2\right) / \lambda \\
v_{k}=\left(d / 2+\sqrt{A} w_{k}+(A / d) z_{k}^{2} / 2\right) / \lambda
\end{array}\right.
$$

Notice moreover that the eigenvalues of $\widetilde{H} \widetilde{H}^{*}$ do not depend on the particular values of the $u_{j}$ 's or $\nu_{k}$ 's; they are therefore the same as the eigenvalues of $G G^{*}$.

This entry-by-entry approximation adds some plausibility to Claim 2.2.
Remark 2.13. Observe that while the above justification works under the stronger assumption that $A^{3 / 2} / d^{2} \rightarrow 0$, the parameters used for the graphs in this chapter are such that $A^{3 / 2} / d^{2} \nrightarrow 0$

### 2.5 Conclusion and perspectives

The goal of this chapter is to give precise estimates on the number of spatial degrees of freedom in large MIMO systems in a line-of-sight environment. An upper bound for a model closely related to the line-of-sight model has been given, and the similarity of the models is supported numerically. As such, it remains to be shown that the eigenvalues of the two models are indeed very close, in order to bound $\left|\log \operatorname{det}\left(I+n P H H^{*}\right)-\log \operatorname{det}\left(I+G G^{*}\right)\right|$.

As a by-product, the spectral properties of random matrices $G$ of the form $g_{j k}=e^{-2 \pi i m y_{j} z_{k}}$ have been studied. These matrices are not unrelated to both Vandermonde matrices and random DFT matrices that appear in other contexts in the literature on wireless communications [18, 22, 28, 30] and compressed sensing [3,5]. In particular, random DFT matrices are obtained by selecting only certain rows/columns of the Fourier matrix, which is equivalent to picking the $y_{j}$ and $z_{k}$ randomly among uniformly spaced points on the circle. These matrices will be discussed in the next chapter.

## 3 Free Probability

In the introduction, the channel matrices $H$ and $F G F^{*}$ were brought up, as well as the problem of describing their product's eigenvalue distribution. In this chapter, we introduce the notions of asymptotic freeness and asymptotic traffic-freeness between matrices. The former is an essential tool in the proof of the main theorem of [30] concerning the capacity of the channel with matrix $H F G F^{*}$. The hope to generalize this theorem to cases when one matrix is deterministic is the main impetus behind the work presented in this chapter. We begin with the definitions required for the introduction of free probability.

### 3.1 Noncommutative Probability Spaces and Free Independence

We will first discuss the notion of free independence, as opposed to classical independence. It is by its very nature a noncommutative concept and so some care must be taken in defining the objects we are interested in. This theory will serve as a basis for the concept of traffic-freeness to be discussed in Section 3.2. While the case that will interest us most is the one of random matrices, we will still introduce general noncommutative probability spaces, since, as we will see, random matrices tend to be freely independent only asymptotically. In this spirit, we will not introduce the most general setting in which to view each notion, but will rather choose the objects that naturally arise in the context of large dimensional random matrices.

Definition 3.1. A Banach algebra $A$ is a an algebra which is normed, complete with respect to this norm, and such that $\|a b\| \leq\|a\|\|b\|$ for all $a, b \in A$. A $C^{*}$-algebra is a Banach algebra over $\mathbb{C}$ equipped with an involution operator $*$ such that $\left\|a a^{*}\right\|=\|a\|^{2}$. By involution operator, we mean an operator $*: A \rightarrow A$ such that $\left(a^{*}\right)^{*}=a,(a+b)^{*}=a^{*}+b^{*},(a b)^{*}=b^{*} a^{*}$ and, for $\gamma \in \mathbb{C},(\gamma a)^{*}=\bar{\gamma} a^{*}$.

Definition 3.2. A bounded linear map $L$ between two $C^{*}$-algebras $A$ and $B$ is said to be a *homomorphism if $L(a b)=L(a) L(b)$ and $L\left(a^{*}\right)=L(a)^{*}$ for $a, b \in A$. A bijective *-homomorphism is called a *-isomorphism.

A natural example of $C^{*}$-algebra is the set $B(H)$ of bounded (equivalently continuous) linear
operators defined on a complex Hilbert space $H$. The Gelfand-Naimark theorem states that any $C^{*}$-algebra is *-isomorphic to a subalgebra of such a $B(H)$ for some $H$. The set of matrices of dimension $N$ constitutes an example of a $C^{*}$-algebra. Since we will consider matrices whose dimension $N$ goes to infinity, the requirement for such definitions becomes apparent.

Definition 3.3. An element $a \in A$ is said to be nonnegative if there exists $a_{0} \in A$ such that $a=a_{0} a_{0}^{*}$.

Definition 3.4. A noncommutative probability space ${ }^{1}(A, \phi)$ is a pair consisting of a $C^{*}$-algebra $A$ and a state $\phi$, i.e. a linear map $\phi: A \rightarrow \mathbb{C}$ sending the unit of $A$ to 1 and mapping nonnegative elements of $A$ to $\mathbb{R}_{+}$. An element of $A$ is called a noncommutative random variable. We will always assume that our states are tracial, i.e. $\phi(a b)=\phi(b a)$ for all $a, b \in A$. In the case of large dimensional matrices, the most common state is $\tau_{N}=\frac{1}{N} \mathbb{E T r}$, explaining the terminology tracial.

Definition 3.5. Let $a_{i}$ be a finite set of noncommutative random variables and $\mathbb{C}\left\langle a_{i},\right\rangle$ be the set of noncommutative polynomials in the $a_{i}$ 's. The law (or distribution) of the family $\left\{a_{i}\right\}$ is defined as the application $\mu_{\left\{a_{i}\right\}}: \mathbb{C}\left\langle a_{i}\right\rangle \rightarrow \mathbb{C}$

$$
\mu_{\left\{a_{i}\right\}}(P)=\phi\left(P\left(\left\{a_{i}\right\}\right)\right)
$$

Observe that in the case of a single random variable (in which case the polynomials are necessarily commutative), we recover here the moments of a random variable. Indeed, for a monomial $a^{k}$, we have that $\phi\left(a^{k}\right)$ is the $k^{t h}$ moment of the random variable $a$. In many cases, the moments of a random variable uniquely determine its distribution and we will restrict ourselves to such cases (where by distribution we mean the object studied in (commutative) probability theory, see [12]). We see that this definition is the natural extension to the noncommutative setting of the notion of joint moments of (commutative) random variables.

Definition 3.6. The empirical eigenvalue distribution of a matrix $M$ with eigenvalues $\lambda_{i}$ is given by $\frac{1}{N} \sum_{i=1}^{N} \delta_{\lambda_{i}}$. This is a sum of Dirac $\delta$ 's at each eigenvalue and as such it is the distribution of an eigenvalue picked at random from the eigenvalues of $M$. When considering a single random matrix in the space of $N$ dimensional matrices, the state $\frac{1}{N} \mathbb{E} \operatorname{Tr}$ gives the moments of the empirical eigenvalue distribution. Indeed, we have, for $\lambda$ an eigenvalue of $M$ picked uniformly randomly and $P$ a polynomial

$$
\frac{1}{N} \mathbb{E} \operatorname{Tr} P(M)=\mathbb{E} \frac{1}{N} \sum_{i=1}^{N} P\left(\lambda_{i}\right)=\mathbb{E}(P(\lambda))
$$

Definition 3.7. We say that a sequence $\left\{a_{i}^{N}\right\}$ converges in distribution to $a_{i}^{\infty}$ if for all $P \in \mathbb{C}\left\langle a_{i},\right\rangle$

$$
\lim _{N \rightarrow \infty} \mu_{\left\{a_{i}^{N}\right\}}(P)=\mu_{\left\{a_{i}^{\infty}\right\}}(P)
$$

[^3]Remark 3.8. We will sometimes treat objects such as *-distributions or *-polynomials. The *indicates that we allow both the element and its adjoint as input. Observe that the *-distribution is a more precise object, as it specifies the moments of a larger family of objects. Similarly, the set of *-polynomials in a variable $a$ is strictly larger than the set of polynomials in $a$. When the element is self-adjoint, i.e. $a=a^{*}$, the distinction between distribution and *-distribution is no longer relevant.

### 3.1.1 Free independence

Given two Hermitian matrices $M$ and $N$, what can we say about the eigenvalue distribution of their sum $M+N$ ? Unless they share the same eigenvectors, this is a very difficult question to answer. What we can hope to answer is how the empirical eigenvalue distribution of the sum relates to the individual empirical eigenvalue distributions. In the commutative case, little can be said of the sum of two random variables from the distribution of the summands. One key property that allows such computation is independence. In this section, we will introduce the concept of free independence (or freeness) which allows one to make the analogous computation in the noncommutative setting. The empirical eigenvalue distribution of the product of the matrices can also be obtained (provided the product is Hermitian), hence allowing us to characterize a random eigenvalue of the matrix $H F G F^{*}$ from the introduction. The reader will immediately see that this last matrix is not Hermitian. However, if $H$ can be written as $H_{0} H_{0}^{*}$, $H F G F^{*}$ will have the same eigenvalues as the matrix $H^{1 / 2} F G F^{*} H^{1 / 2}$ and we can work with this matrix.

Much like in the commutative setting, the essence of non commutative probability theory comes into play once we introduce the concept of free independence. Suppose given a nc probability space $(A, \phi)$. Given a finite number of subalgebras $A_{i}$ containing the unit of $A$, we say that they are free (or freely independent) if for any integer $n$, any indices $k(1) \neq k(2), k(2) \neq$ $k(3), \ldots k(n-1) \neq k(n)$ and any $a_{j} \in A_{k(j)}$ with $\phi\left(a_{j}\right)=0$, we have that

$$
\phi\left(a_{1} a_{2} \ldots a_{n}\right)=0
$$

We say that subsets of elements of the noncommutative probability space are (*-)free if the algebras they $\left({ }^{*}-\right)$ generate are free. Let us make this definition explicit in the case of random matrices.

Definition 3.9. We say that a collection of self-adjoint random matrices $M_{i}$ are asymptotically free if for all $i_{1}, \ldots, i_{l} \in I$ such that $i_{1} \neq i_{2}, i_{2} \neq i_{3}, \ldots, i_{l-1} \neq i_{l}$, and for all $f_{i}$ polynomials, one has

$$
\begin{equation*}
\lim _{N \rightarrow \infty} \frac{1}{N} \mathbb{E} \operatorname{Tr}\left[\left(f_{1}\left(M_{1}\right)-\tau_{N}\left(f_{1}\left(M_{1}\right)\right) I\right) \ldots\left(f_{l}\left(M_{l}\right)-\tau_{N}\left(f_{l}\left(M_{l}\right)\right) I\right)\right]=0 \tag{3.1}
\end{equation*}
$$

Note that the polynomials $f_{i}$ appear here in connection with the generated subalgebras.
It is worth unpacking this definition a little bit to understand better its usefulness. The main
point is that, if subalgebras $A_{i}$ are free, it is sufficient to know the restriction of $\phi$ on the subalgebras to evaluate $\phi$ on the whole algebra $A$. In the case of two random matrices being asymptotically free, this means that we can compute the moments of any (noncommutative) product of the matrices from the knowledge of the moments of the individual matrices. This is in direct analogy with the commutative case where the commutativity allows us to group the different appearances of each factor together: the expected value factors for independent random variables: $\mathbb{E}(c d)=\mathbb{E}(c) \mathbb{E}(d)$.

Since its introduction by Voiculescu [31], free analogs of several probabilistic constructions and results have been discovered including, but not limited to, law of large numbers, central limit theorem [1] and stochatic calculus [32].

One of the first model that was studied in random matrix theory is the Gaussian Unitary Ensemble (GUE): all upper diagonal entries are i.i.d. standard complex gaussian random variables with unit variance, and the matrix is required to be Hermitian (and thus real on the diagonal). It was recognized early on that an important feature of the GUE was its invariance under conjugation by the unitary group. What we mean here is that given $G$ a GUE matrix and $U$ a deterministic unitary matrix, $G$ and $U G U^{*}$ have the same distribution. It is this feature that allows one to conclude that two independent matrices drawn from the GUE ensemble are asymptotically free. As such, it is natural to look at matrices of the form $U C U^{*}$ as the next example of asymptotically free matrices. Here $C$ is a deterministic matrix and $U$ is picked uniformly at random from the set of all unitary matrices. This intuition turns out to be correct: given two deterministic matrices $C, D$ and a matrix $U$ uniformly distributed over the set of unitary matrices, the matrices $U C U^{*}$ and $D$ are indeed asymptotically free.

It is a rule of thumb that independent matrices with eigenvectors in sufficiently general position will be asymptotically free. This is in stark opposition with classical independence. Indeed, one case where one can compute the empirical eigenvalue distribution of a sum of two random matrices is the case where these two matrices are independent and diagonal, the entries of each matrix being i.i.d. as well. In this case, one obtains the classical convolution between the two distributions. In the next section, we give the noncommutative analog of these results, crucially using the freeness assumption.

### 3.1.2 Transforms and convolutions

One might ask how, given two Hermitian noncommutative random variables, one can compute explicitly the distribution of their sum and product. The answer is given by the R and S transforms respectively. The R transform plays the same role as the log of the Fourier transform in classical probability. They are analytical tools allowing for efficient computation. Before introducing these objects, let us recall the definition of the Stieljes (or Cauchy) transform, a more classical and well-known object:

Definition 3.10. Given a probability distribution $\mu$, the Stieljes transform $\mathscr{S}_{\mu}$ of $\mu$ is given by

$$
\mathscr{S}_{\mu}(z):=\int_{\mathbb{R}} \frac{\mu(d x)}{x-z}, z \in \mathbb{C} \backslash \mathbb{R}
$$

An inversion formula ensures that the knowledge of the Stieljes transform is equivalent to the knowledge of $\mu$ itself. In the special case where $\mu$ is absolutely continuous with respect to Lebesgue measure, with density function $\rho$, we have

$$
\rho(x)=\lim _{\epsilon \rightarrow 0^{+}} \frac{\operatorname{Im} \mathscr{S}_{\mu}(x+i \epsilon)}{\pi}
$$

Moreover, of particular usefulness is the fact that the Stieljes transform can characterize convergence:

Definition 3.11. We say that $\mu_{n}$ converges weakly to $\mu$ if for any continuous bounded function $f$ on $\mathbb{R}$ we have that $\int f d \mu_{n} \rightarrow \int f d \mu$.
Proposition 3.12. - Let $\mathscr{S}_{\mu}$ be the Stieljes transform of a probability measure $\mu$ and $\mu_{n}$ a sequence of probability measures. Then $\mathscr{S}_{\mu_{n}}(z)$ converges for each $z \in \mathbb{C} \backslash \mathbb{R}$ to $S_{\mu}(z)$ if and only if $\mu_{n}$ converges weakly to $\mu$.

- If the probability measures $\mu_{n}$ are themselves random and, for each $z \in \mathbb{C} \backslash \mathbb{R}, \mathscr{S}_{\mu_{n}}(z)$ converges in probability to a deterministic limit $\mathscr{S}(z)$ that is the Stieljes transform of a probability measure $\mu$, then $\mu_{n}$ converges weakly in probability to $\mu$.

For this and more, see [1].

## R transform

Fix a probability distribution $\mu$. Let $K_{\mu}(z)$ be the functional inverse of $\mathscr{S}_{\mu}(z)$ the Stieljes transform of $\mu$. We then define the R transform as

$$
R_{\mu}(z):=K_{\mu}(z)-1 / z
$$

It turns out that with this definition, if we take $a$ with distribution $\mu$ and $a^{\prime}$ with distribution $\mu^{\prime}$, and suppose that $a$ and $a^{\prime}$ freely independent, we have

$$
R_{a+a^{\prime}}=R_{a}+R_{a^{\prime}}
$$

Let $\mu \boxplus \mu^{\prime}$ be the distribution of $a+a^{\prime}$, called the additive free convolution (here, $a$ and $a^{\prime}$ must be free). The way to obtain $\mu \boxplus \mu^{\prime}$ from $\mu$ and $\mu^{\prime}$ is now clear from a conceptual point of view:

1. Compute $\mathscr{S}_{\mu}$ and $\mathscr{S}_{\mu^{\prime}}$
2. From this, obtain $R_{\mu}(z)$ and $R_{\mu^{\prime}}(z)$
3. $R_{\mu \boxplus \mu^{\prime}}=R_{\mu}+R_{\mu^{\prime}}$
4. Obtain $\mathscr{S}_{\mu \boxplus \mu^{\prime}}$ from the R transform
5. Use Stieljes inversion to finally obtain the distribution $\mu \boxplus \mu^{\prime}$

Let us remark that it is possible to define the coefficients of the formal power series of the $R$ transform from a combinatorial point of view which puts the spotlight on the relationship between its coefficients (called free cumulants) and the freeness property. We refer to the excellent monograph [17] for a comprehensive treatment.

## Other Transforms

There is a multiplicative analog of the R transform, called the S transform. It can be obtained from the the moment generating function of a random variable $a$ as follows.

Let $m_{a}(z):=\sum_{n \geq 1} \phi\left(a^{n}\right) z^{n}$ and denote its functional inverse by $m_{a}^{-1}$. If $\phi(a) \neq 0$, we define the S transform of $a$ as

$$
S_{a}(z):=\frac{1+z}{z} m_{a}^{-1}(z)
$$

We have

$$
S_{a a^{\prime}}(z)=S_{a}(z) S_{a^{\prime}}(z) \text { when } a \text { and } a^{\prime} \text { are free. }
$$

Similarly to the additive case, we let $\mu \boxtimes \mu^{\prime}$ be the distribution of $a a^{\prime}$ and call it the multiplicative free convolution (here, $a$ and $a^{\prime}$ must be free).

We will present an example of multiplicative free convolution after Corollary 3.20.
With applications to wireless communication in mind, two more transforms have been introduced, see [29]. They both can be obtained from the Stieljes transform, yet they simplify many computations and their expression has a more immediately relatable significance with respect to some wireless scenarios.

Definition 3.13. The $\eta$-transform is given by

$$
\eta_{a}(z):=\mathbb{E}\left[\frac{1}{1+z a}\right]
$$

Definition 3.14. The Shannon transform is given by

$$
\Upsilon_{a}(z):=\mathbb{E}[\log (1+z a)]
$$

### 3.1.3 Asymptotic liberation

We have seen how freeness allows us to compute the distribution of a random eigenvalue from the product or the sum of matrices in the large $N$ limit when one knows the marginal distributions and the matrices are asymptotically free. We would like to understand when this freeness relation holds for the matrices $A$ and $F \Delta F^{*}$ where $A$ and $\Delta$ are independent diagonal matrices with i.i.d. entries and $F$ is the unitary Fourier matrix. The eigenvalues of the product of these matrices have been investigated before in the case of random diagonal projection matrices, see [5]. Prior to this work, the more general assertion that these matrices are asymptotically free had been proven in [30]. This result is a priori surprising when one thinks that asymptotically free matrices should have eigenvectors in general positions. Indeed, in this particular case, the eigenvectors are deterministic. In [6], the concept of liberating matrices was introduced and it puts this result in context and provides a framework to explain why it holds. For $W$ a uniformly distributed permutation matrix, the matrices $\{W, F\}$ are asymptotically liberating, i.e. they make other matrices become free, in a sense to be made precise in this section.

Notation 3.15. We will denote the spectral norm of a matrix with the symbol ||| $\|_{s p}$. For a random variable $Z$, let $\|Z\|_{l}=\left(\mathbb{E}|Z|^{l}\right)^{1 / l}$ for $l \geq 1$.

We first state what it means for a family of matrices to be asymptotically liberating, a new terminology introduced in [6]:

Definition 3.16. Let $I$ be a finite set. A sequence of families of unitary matrices $\left\{\left\{U_{i}\right\}_{i \in I}\right\}_{N=1}^{\infty}$ is said to be asymptotically liberating if for indices $i_{1}, \ldots i_{l} \in I$ satisfying $i_{1} \neq i_{2}, \ldots i_{l-1} \neq i_{l} \neq i_{1}$, there exist a constant $c$ depending only on $l$ such that

$$
\left|\mathbb{E} \operatorname{Tr}\left(U_{i_{1}} A_{1} U_{i_{1}}^{*} \ldots U_{i_{l}} A_{l} U_{i_{l}}^{*}\right)\right| \leq c(l)\left\|A_{1}\right\|_{s p} \ldots\left\|A_{l}\right\|_{s p}
$$

for all determnistic matrices $A_{i}$ of trace 0 .

To understand the meaning of the definition of asymptotic liberating sequences, let $I$ be a finite indexing set and for every $i \in I$, let $U_{i}$ be a unitary matrix, $E_{i}$ a matrix of bounded spectral norm and $M_{i}=U_{i} E_{i} U_{i}^{*}$. Suppose we want to show that the $M_{i}$ are asympotically free, recalling the definition of asymptotic freeness for matrices, see Definition 3.9. For a polynomial $f$, we have that $f\left(M_{i}\right)=U_{i} f\left(E_{i}\right) U_{i}^{*}$, using the fact that $U_{i}$ is unitary. We can rewrite the lefthand side of the equation in Definition 3.9 as

$$
\lim _{N \rightarrow \infty} \frac{1}{N} \mathbb{E} \operatorname{Tr}\left(U_{1} A_{1} U_{1}^{*} \ldots U_{l} A_{l} U_{l}^{*}\right)
$$

where $A_{i}=f\left(E_{i}\right)-\left(\frac{1}{N} \mathbb{E} \operatorname{Tr} f\left(E_{i}\right)\right) I$. Hence, if the $U_{i}$ form an asymptotically liberating family, $\mathbb{E} \operatorname{Tr}\left(U_{1} A_{1} U_{1}^{*} \ldots U_{l} A_{l} U_{l}^{*}\right)$ is uniformly bounded in $N$ and the factor $\frac{1}{N}$ will drive the limit to 0 .

The $M_{i}$ are therefore asymptotically free. The terminology is now clear: a family of asymptotically liberating matrices will make other matrices free from each other by conjugating them. This is the case in particular for uniformly distributed unitary matrices, which make other matrices free by conjugating them.

Let us restate Theorem 2.8 from [6]:
Theorem 3.17. Let $I$ be a finite index set and $U_{i}$ be unitary matrices. Let $U_{i i^{\prime}}=U_{i^{\prime}}^{*} U_{i}$ for $i \neq i^{\prime}$. Make the following assumptions:

1. For any deterministic signed permutation matrix $W$, one has $\left\{W^{*} U_{i i^{\prime}} W\right\} \stackrel{d}{=}\left\{U_{i i^{\prime}}\right\}$, i.e. they have the same distribution.
2. For each positive integer $l$, one has

$$
\sup _{N=1}^{\infty} \max _{i, i^{\prime} \in I, i \neq i^{\prime}} \max _{\alpha, \beta=1}^{N} \sqrt{N}\left\|\left(U_{i i^{\prime}}\right)_{\alpha, \beta}\right\|_{l}<\infty
$$

Then the family $\left\{U_{i}\right\}$ is asymptotically liberating.

Let us comment on these conditions. The first one requires invariance under the group of permutation matrices. Observe that here the randomness requirements are much less stringent than invariance under the conjugation action of a uniformly distributed unitary matrix. The second condition asks that the entries of the matrices be "spread out". Since the rows and columns of unitary matrices have $l_{2}$ norm equal to 1 , we require the mass of rows and columns not to be concentrated on a few entries. One can think of the identity matrix as a unitary matrix which is a counterexample.

We will now come to the main application: the case of Hadamard matrices (and thus Fourier matrices as a special case).

Definition 3.18. $H$ is a Hadamard matrix (respectively complex Hadmard matrix) if $\frac{H}{\sqrt{N}}$ is orthogonal (respectively unitary) and $\left|h_{j k}\right|=1$ for all $j, k$. This is the case for the Fourier matrix, $f_{j k}=e^{2 \pi i(j-1)(k-1) / N}$.

Proposition 3.19. For each positive integer $N$, let $H_{N}$ be a deterministic $N \times N$ Hadamard matrix and $W_{N}$ a uniformly distributed random signed permutation matrix. Then

$$
\left\{W_{N} \bigcup \frac{H_{N} W_{N}}{\sqrt{N}}\right\}_{N=1}^{\infty}
$$

is a sequence, in $N$, of families of matrices which is asymptotically liberating.

We can now use the invariance under the permutation group of the diagonal matrices with i.i.d. entries to deduce the following:

Corollary 3.20. Let $A$ and $\Delta$ be independent diagonal matrices with i.i.d. entries from two distributions having bounded support. Then $F \Delta F^{*}$ and $A$ are asymptotically free.


Figure 3.1 - The empirical eigenvalue distribution of $A F \Delta F^{*}$ with $A$ and $\Delta$ i.i.d. diagonal with Bernoulli(0.5) entries.

In particular, we can compute the limiting eigenvalue distribution of the matrix $A F \Delta F^{*}$. By taking the entries of $A$ and $\Delta$ to be Bernoulli $0-1$ variables with parameter $p$ and $q$, we obtain a concrete example where we can easily do computations. The distribution of a diagonal entry of the product $A \Delta$ is given by a Bernoulli of parameter $p q$. The empirical eigenvalue distribution of $A F \Delta F^{*}$ is given (in the large $N$ limit) by the free multiplicative convolution of the two measures $\operatorname{Bern}(\mathrm{p})$ and $\operatorname{Bern}(\mathrm{q})$ since the two matrices are asymptotically free. See Figure 3.1.

The multiplicative free convolution Bern $(p) \boxtimes \operatorname{Bern}(q)$ is given by

$$
f_{p, q}(x)=\frac{\sqrt{\left(1-\left(r_{-} / x\right)\right)\left(\left(r_{+} / x\right)-1\right.}}{2 \pi(1-x))} \mathbb{1}_{r_{-}<x<r_{+}}+(1-\min (p, q)) \delta_{0}+\max (0, p+q-1) \delta_{1}
$$

where $r_{-}=(\sqrt{(1-p) q}-\sqrt{(1-q) p})^{2}$ and $r_{+}=(\sqrt{(1-p) q}+\sqrt{(1-q) p})^{2}$.
We see on Figure 3.2 evidence of a stark difference between the multiplicative convolution and the free multiplicative convolution. In particular, observe that the free multiplicative convolution of two discrete probability distributions has a nonzero absolutely continuous component.


Figure 3.2 - Plots of the continuous density of $\operatorname{Bern}(p) \boxtimes \operatorname{Bern}(q)$ for different choices of parameters.

### 3.2 Traffics

As we have seen, the invariance by permutation of one of our matrices is one of the important ingredients that allows us to make significant progress in describing the product's empirical eigenvalue distribution. We will now introduce the concept of traffics, which are noncommutative random variables naturally suited to the invariance by permutation.

Traffic spaces are spaces of noncommutative random variables which are equipped with extra structure and are particularly well suited to study matrices invariant by permutation, the cases of interest. There exists an associated notion of traffic freeness and it also allows one to compute joint moments of noncommutative random variables from the individual moments, much like freeness. It is the interplay between freeness and traffic freeness that will interest us. We will mostly be concerned with large random matrices, but a more general setting can be elaborated and we encourage the algebraically-inclined reader to read [14] where this is developed.

Notation 3.21. In this section, we will use a subscript to indicate the dimension of the matrices, i.e. $A_{N}$.

Definition 3.22. We say that $A_{N}$ is invariant by permutation if, for any fixed permutation matrix $W_{N}, W_{N} A_{N} W_{N}^{*}$ has the same distribution as $A_{N}$.

Hypothesis 3.23. Throughout this section, we let $A_{N}$ be a diagonal matrix with i.i.d. entries, with distribution having bounded support, and $B_{N}=F_{N} \Delta_{N} F_{N}^{*}$ of the form a diagonal deterministic matrix $\Delta_{N}=\operatorname{diag}\left(\delta_{1}, \ldots, \delta_{N}\right)$ conjugated by the unitary Fourier matrix $F_{N}$ We suppose


Figure 3.3 - The graph $T_{0}$ and an example of the vertex identification process.
that the $\delta_{i}$ are bounded and converge in distribution.

The idea behind traffics is to evaluate matrices not only on polynomials, but more generally on graphs, which have a richer structure. We will now define what we mean by evaluating a matrix on a graph. For the remainder of this document, we will consider $T$ a finite connected oriented graph. Also, for $V$ the vertex set of $T$, let $\Pi_{|V|}$ be the set of partitions of the vertices of $T$. For $\pi \in \Pi_{|V|}$, we let $T^{\pi}$ be the graph obtained by identifying the vertices of $T$ according to the partition $\pi$.

Example 3.24. Let $T_{0}$ be the oriented cycle on 3 edges, with a loop on one vertex. We will use it as a running example of a graph to illustrate definitions. See Figure 3.3.

Definition 3.25 ((injective) trace). Let $T$ be a (finite, connected, oriented) graph with edge set $E$ and vertex set $V$, and $\mathbf{X}_{N}=\left(X_{i}\right)_{i \in I}$ a family of (possibly random) matrices of dimension $N$. Let there be given two functions $\epsilon: E \rightarrow\{1, *\}$ and $\gamma: E \rightarrow I$. We can see these functions as follows: $\gamma$ chooses a matrix for each edge, and for this matrix, $\epsilon$ picks between the matrix and its adjoint. We define $\tau_{N}\left(T\left(\mathbf{X}_{N}\right)\right)$ as

$$
\tau_{N}\left(T\left(\mathbf{X}_{N}\right)\right):=\frac{1}{N} \mathbb{E} \operatorname{Tr}\left(T\left(\mathbf{X}_{N}\right)\right)=\frac{1}{N} \mathbb{E} \sum_{\phi: V \rightarrow[N]} \prod_{e=(\nu, w) \in E} X_{\gamma(e)}^{\epsilon(e)}(\phi(\nu), \phi(w))
$$

where $[N]=\{1,2, \ldots, N\}$. If the summation in the above definition is over all functions $\phi$ which are injective, we call this object the injective trace and denote it $\tau_{N}^{0}\left(T\left(\mathbf{X}_{N}\right)\right)$.

This object $\tau_{N}\left(T\left(X_{N}\right)\right)$ can be interpreted as follows: to each edge is attached a matrix from the family $\mathbf{X}_{N}$. The summation is over all possible assignments of indices for the vertices, which for every edge picks an entry from the attached matrix.

Example 3.26. The (injective) trace of the graph $T_{0}$ evaluated on a single matrix $\mathbf{X}_{N}=X_{N}$ with $\epsilon$ always equal to 1 gives

$$
\tau_{n}\left(T_{0}(X)\right)=\frac{1}{N} \mathbb{E} \sum_{i j k} X(i, j) X(j, j) X(j, k) X(k, i)
$$

$$
\tau_{n}^{0}\left(T_{0}(X)\right)=\frac{1}{N} \mathbb{E} \sum_{i \neq j \neq k \neq i} X(i, j) X(j, j) X(j, k) X(k, i)
$$

Remark 3.27. We have the following relationship between the trace and the injective trace.

$$
\tau_{N}\left(T\left(\mathbf{X}_{N}\right)\right)=\sum_{\pi \in \Pi_{|V|}} \tau_{N}^{0}\left(T^{\pi}\left(\mathbf{X}_{N}\right)\right)
$$

We can express $\tau^{0}$ in terms of $\tau$ by using the Möbius inversion formula on the lattice $\Pi_{|V|}$.

$$
\begin{equation*}
\tau_{N}^{0}\left(T\left(\mathbf{X}_{N}\right)\right)=\sum_{\pi \in \Pi_{|V|}} \mu(\pi) \tau_{N}\left(T^{\pi}\left(\mathbf{X}_{N}\right)\right) \tag{3.2}
\end{equation*}
$$

where $\mu$ is the so-called Möbius function that depends on the structure of the partially ordered set. In our case, this is the lattice $\Pi_{|V|}$ of all partitions of the set $V$, ordered by the relationship of inclusion, i.e. a finer partition is below a coarser one. This means the bottom element is the partition of singletons, and the top element is the partition consisting of one block. See [25] for many applications, as well as explicit computations of the Möbius function.

Definition 3.28. Similarly to moments, we define the map $T \rightarrow \tau_{N}\left(T\left(\mathbf{X}_{N}\right)\right)$ as the traffic distribution. By convergence in traffic distribution, we mean the pointwise convergence of this map.

Remark 3.29. In the above definition, we only ask that for every fixed graph $T$, the sequence $\tau_{N}\left(T\left(X_{N}\right)\right)$ has a finite limit as $N \rightarrow \infty$. This will be sufficient for our purposes. The appropriate concept of spaces of traffics where this convergence takes place has been introduced in [14], and we refer the reader to this article for the concepts surrounding spaces of traffics.

Observe that by taking the graph to be a cycle, we can recover any given $*$-monomial. This means that convergence in traffic distribution implies convergence in *-distribution. Given Hypothesis 3.23 on $A_{N}$ and $B_{N}$, we have the following result concerning the joint distribution of $\left(A_{N}, B_{N}\right)$.

Theorem 3.30 ([14], Theorem 3.4). Suppose that $B_{N}$ is deterministic and that for all graphs $T$, $\tau_{N}\left(T\left(B_{N}\right)\right)$ converges as $N \rightarrow \infty$. Then $\left(A_{N}, B_{N}\right)$ converges in traffic distribution, and hence in $*$-distribution.

The matrix $B_{N}=F_{N} \Delta F_{N}^{*}$ is of particular interest to us. Let $\omega$ be a primitive $N^{\text {th }}$ root of unity, $\mathbb{1}$ denote the indicator function and $(N)$ the operation of reducing modulo $N$. Using the fact that $\sum_{j=0}^{N-1} \omega^{j k}=N \mathbb{1}_{k=0(N)}$, we have the following lemma.

Lemma 3.31. The value of $\tau_{N}\left[T\left(B_{N}\right)\right]$ is

$$
\frac{1}{N^{1+|E|-|V|}} \sum_{j_{1}, \ldots j_{|E| \in \mid N]}} \delta_{j_{1}} \ldots \delta_{j_{|E|}} \prod_{\nu \in V} \mathbb{1}_{\sum_{e \text { entering }} \nu} j_{e}-\sum_{e \text { exiting } v} j_{e}=0(N) .
$$

Proof. First, observe that the fact that $B_{N}=F_{N} \Delta_{N} F_{N}^{*}$ immediately yields that $\left(b_{n}\right)_{j k}=\frac{1}{N} \sum_{l=1}^{N} \delta_{l} \omega^{(j-k) l}$. By Definition 3.25,

$$
\begin{aligned}
\tau_{N}\left[T\left(B_{N}\right)\right] & =\frac{1}{N} \sum_{i_{1}, \ldots i_{|V|} \in[N]} \prod_{e \in E} B_{N}\left(e_{\text {source }}, e_{\text {destination }}\right) \\
& =\frac{1}{N} \sum_{i_{1}, \ldots i_{|V|} \in[N]} \sum_{j_{1}, \ldots j_{|E|} \in[N]} \prod_{e \in E} \frac{\omega^{\left(i_{\text {source }}-1\right)\left(j_{e}-1\right)}}{\sqrt{N}} \delta_{j_{e}} \frac{\omega^{-\left(i_{\text {dest }}-1\right)\left(j_{e}-1\right)}}{\sqrt{N}} \\
& =\frac{1}{N^{1+|E|}} \sum_{j_{1}, \ldots j_{|E| \in \mid N]}} \delta_{j_{1}} \ldots \delta_{j_{|E|}} \sum_{i_{1}, \ldots i_{|V|} \in[N]} \prod_{\nu \in V} \omega^{\left(i_{v}-1\right) \sum_{e \text { entering } v} j_{e}-\sum_{e \text { exiting } v} j_{e}} \\
& =\frac{1}{N^{1+|E|-|V|}} \sum_{j_{1}, \ldots j_{|E| \in \mid N]}} \delta_{j_{1}} \ldots \delta_{j_{|E|}} \prod_{\nu \in V} \mathbb{1}_{\sum_{e \text { entering }} j_{e}-\sum_{e \text { exiting } v} j_{e}=0(N)}
\end{aligned}
$$

Remark 3.32. Exactly $|V|-1$ of the linear equations in the last indicator function are linearly independent. Indeed, these linear equations $e_{i}$ come from the graph, and as such, each $j$ variable appears once with a plus sign and once with a minus sign. It is clear that the sum of all equations is 0 , and so at most $|V|-1$ of the equations are linearly independent. Suppose we can find a linear dependence $\sum \alpha_{i} e_{i}$ with at most $|V|-1$ summand. For any variable $j$ appearing in equation $e_{i}$ in the linear dependence equation, the other equation containing $j$, call it $e_{i}^{\prime}$ must also appear with the same coefficient, i.e. $\alpha_{i}=\alpha_{i}^{\prime}$. Since for any subset of vertices of cardinality strictly less than $|V|$ there is always an edge between this subset and its complement by the connectedness of the graph, we can find a $j$ variable that is not cancelled, and thus a contradiction. We conclude that $|V|-1$ of these linear equations are linearly independent.

We give an example which will be of use later: we evaluate the matrix $B_{N}$ on a particular graph with 2 vertices and 4 edges.

Corollary 3.33. Evaluated on the matrix $B_{N}$, we have

$$
\tau_{N}[\overbrace{2}]=\frac{1}{N^{3}} \sum_{j_{1} \ldots j_{4}} \delta_{j_{1}} \ldots \delta_{j_{4}} \mathbb{1}_{j_{1}+j_{2}-j_{3}-j_{4}=0(N)}
$$

We now have the necessary background to introduce the concept of traffic freeness.
Definition 3.34. Let $X_{1}, \ldots, X_{p}$ be families of different random matrices and let $T$ be a graph with the associated $\epsilon$ and $\gamma$ functions. Denote by $T_{1}, \ldots, T_{k}$ the connected components of $T$ that are labelled by variables in the same family. Consider $\bar{T}$ the graph whose vertices are given by $T_{1}, \ldots, T_{K}$, as well as the vertices $v_{i}$ of $T$ that are common to at least 2 components $T_{j}$. There is an edge between $v_{i}$ and $T_{j}$ in $\bar{T}$ if $v_{i} \in T_{j}$ in $T$. Finally, we say that $T$ is a free product in $\mathbf{X}_{1}, \ldots, \mathbf{X}_{p}$ whenever $\bar{T}$ is a tree.

$T$

$\bar{T}$

Figure 3.4 - Example of the construction of $\bar{T}$. On the righthand side, the round nodes represent connected components of $T$ and the square nodes represent shared vertices.

Definition 3.35. Two families of random matrices $\mathbf{X}_{1}$ and $\mathbf{X}_{2}$ are said to be asymptotically traffic free if their joint distribution converges to some limit and for any graph $T$, we have that

$$
\tau^{0}\left[T\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right)\right]= \begin{cases}\prod_{j=1}^{k} \tau^{0}\left[T_{j}\left(\mathbf{X}_{i_{j}}\right)\right] & \text { if } T \text { is a free product in } \mathbf{X}_{i}  \tag{3.3}\\ 0 & \text { otherwise }\end{cases}
$$

Concretely this means that if two families of matrices are traffic free, we can compute the injective trace (and therefore also the trace) on any graph from the traffic distribution of the marginals, as it is a product according to equation (3.3).

Theorem 3.36 ([14] Theorem 3.4). Let $E_{N}^{(1)}$ and $E_{N}^{(2)}$ be two independent families of matrices such that:

1. $E_{N}^{(1)}$ is invariant by permutation.
2. $E_{N}^{(1)}$ and $E_{N}^{(2)}$ converge in traffic distribution.
3. For $j=1,2$ and for any family of finite graphs $T_{i}$ in the variable $x_{j}$, we have that

$$
\mathbb{E}\left[\prod_{i=1}^{n} \frac{1}{N} \operatorname{Tr}\left[T_{i}\left(E_{N}^{(j)}\right)\right]\right] \underset{N \rightarrow \infty}{\rightarrow} \prod_{i=1}^{n} \tau\left[T_{i}\left(x_{j}\right)\right]
$$

Then the matrices $E_{N}^{(1)}$ and $E_{N}^{(2)}$ are asymptotically traffic free.
Corollary 3.37. With Hypothesis $3.23, A_{N}$ and $B_{N}$ are asymptotically traffic free. Indeed, the only condition to check in Theorem 3.36 is point 3 , which is true both for the i.i.d. diagonal matrices $A_{N}$ and for the deterministic matrix $B_{N}$.

### 3.2.1 Criteria ensuring the lack of asymptotic freeness

In this section, we compute explicit criteria that prevent matrices from being asymptotically free. Let $A^{0}$ be the recentred matrix $A_{N}-\frac{1}{N} \mathbb{E} \operatorname{Tr}\left(A_{N}\right) I$ and let $\delta_{i}^{0}$ be the diagonal entries of the recentred matrix $\Delta_{N}^{0}$. The strategy is the following: we use the rules of traffic freeness to compute the quantity $\frac{1}{N} \mathbb{E} \operatorname{Tr}\left[\left(A_{N}^{0} B_{N}^{0}\right)^{k}\right]$. If the two matrices are free, this quantity should converge to 0 . If this is not the case, we know that our matrices cannot be free.

## Criterion of order 2

This approach has already been used in [14] to deduce the following theorem. Here, since the entries the matrix conjugated by the Fourier matrix could be random, we use a different notation, $M_{N}=F_{N} \Xi_{N} F_{N}^{*}$ with $\Xi_{N}=\operatorname{diag}\left(\xi_{1}, \ldots, \xi_{N}\right)$.

Theorem 3.38 ([14] Corollary 3.5). Let $M_{N}$ be a random matrix asymptotically traffic free from a diagonal matrix $A_{N}$, and let $P$ and $Q$ be *-polynomials. If the limiting empirical eigenvalue distribution of neither $M_{N}$ nor $A_{N}$ is a Dirac mass and

$$
\begin{equation*}
\lim _{N \rightarrow \infty} \frac{1}{N} \mathbb{E} \operatorname{Tr}\left[P\left(M_{N}\right) \circ Q\left(M_{N}\right)\right]-\lim _{N \rightarrow \infty} \frac{1}{N} \mathbb{E} \operatorname{Tr}\left[P\left(M_{N}\right)\right] \lim _{N \rightarrow \infty} \frac{1}{N} \mathbb{E} \operatorname{Tr}\left[Q\left(M_{N}\right)\right] \neq 0 \tag{3.4}
\end{equation*}
$$

then the matrices $A_{N}$ and $M_{N}$ are not asymptotically *-free. Here, o denotes the Hadamard product, i.e. $(M \circ N)_{j k}=m_{j k} n_{j k}$.

By choosing $P(X)=X$ and $Q(X)=X$, we obtain a simple, easy to apply criterion that applies to all matrices, not only deterministic matrices. Observe that the diagonal entries of $M_{N}$ are all equal to $\frac{1}{N} \sum_{i=1}^{N} \xi_{i}$. We can reformulate the criterion (3.4) as

$$
\begin{equation*}
\lim _{N \rightarrow \infty} \mathbb{E}\left[\left[\frac{1}{N} \sum_{i=1}^{N} \xi_{i}\right]^{2}\right]-\left[\frac{1}{N} \mathbb{E} \sum_{i=1}^{N} \xi_{i}\right]^{2}=\lim _{N \rightarrow \infty} \operatorname{Var}\left[\frac{1}{N} \sum_{i=1}^{N} \xi_{i}\right] \neq 0 \tag{3.5}
\end{equation*}
$$

In Section 3.3, we will use this criterion, which relies on the moment of order 2, to deduce that some matrices are not asymptotically free. However, if the matrix $M_{N}$ in 3.4 is deterministic, this criterion will always evaluate to 0 . This prompts us to compute a criterion to check asymptotic freeness which relies on the moment of order 4.

Remark 3.39. $A_{N}$ and $M_{N}$ are asymptotically traffic free, as long as $M_{N}$ is independent of $A_{N}$ and that it converges in traffic-distribution. This can be deduced using the fact that $A_{N}$ is diagonal from the proof of [14, Theorem 3.4].

## Criterion of order 4

We now compute the criterion of order 4 for deterministic matrices $B_{N}$. Let us remark that if the deterministic matrix $B_{N}$ is replaced by the random matrix $M_{N}$ from the previous section, a slightly more complex criterion can be obtained, but the essential features are the same.

We have

$$
\begin{array}{rlrl}
\frac{1}{N} \mathbb{E} \operatorname{Tr}\left(\left(A_{N}^{0} B_{N}^{0}\right)^{4}\right) & =\tau_{N}\left[\begin{array}{ll}
\text { er }
\end{array} \quad \text { edges alternating in } A_{N}^{0} \text { and } B_{N}^{0}\right. \\
& =\tau_{N}[ & & \text { as } A^{0} \text { is diagonal } \\
& =\sum_{\pi \in \Pi_{|V|}} \tau_{N}^{0}\left[T^{\pi}\left(A_{N}^{0}, B_{N}^{0}\right)\right] & \tag{3.8}
\end{array}
$$

Let us call $C_{k}$ the cyclic graph with loops, $C_{4}$ appearing in Equation (3.7). Recall that $T^{\pi}$ is the graph induced from $T$ by quotienting by the relation induced by the partition $\pi$. We now use the fact that $A_{N}$ and $B_{N}$ are asymptotically traffic free. The following is a reformulation for this particular case of Definition 3.35.

For a graph $T$, denote by $T_{\mathbf{b}}$ be the graph obtained by keeping only the edges with labels $B_{N}$. We then have that

$$
\begin{equation*}
\lim _{N \rightarrow \infty} \tau_{N}^{0}\left[T^{\pi}\left(A_{N}, B_{N}\right)\right]=\lim _{N \rightarrow \infty} \tau^{0}\left[T_{b}^{\pi}\left(B_{N}\right)\right] \prod_{\beta \in \pi} \lim _{N \rightarrow \infty} \frac{1}{N} \mathbb{E} \operatorname{Tr}\left(A_{N}^{|\beta|}\right) \tag{3.9}
\end{equation*}
$$

where for $\beta \in \pi$ a block of the partition $\pi$, we denote $|\beta|$ the size of this block. Observe that since $A_{N}$ is diagonal, the graphs $T_{b}^{\pi}$ are always connected.

In principle, this gives us a formula to compute any moment of the product $A_{N} B_{N}$. However, the complexity grows very quickly when the order of the moment increases and this is why we use the moment of order 4.

Moreover, Equation (3.9) involves $\tau^{0}$ and Lemma 3.31 gives a formula for $\tau$. We will therefore use the formula $\tau=\sum_{\pi \in \Pi_{|V|}} \tau^{0}$ to relate $\tau$ and $\tau^{0}$. Since the partitions are small, we can do it by hand, but, in general, we would use Möbius inversion to express $\tau^{0}$ in terms of $\tau$.

We must therefore enumerate all possible partitions of the 4 vertices and look at their contribution in Equation (3.9). Observe that since the entries are centred, if a partition has a singleton, the contribution is 0 . Moreover, since $A_{N}^{0}$ and $B_{N}^{0}$ are traffic free, the induced graph $\overline{T^{\pi}}$ should be a tree for the contribution to be non-zero. This last condition is always satisfied. Only 4 partitions are left, 2 of them yielding the same graph, see Table 3.1. Writing out Equation (3.9),

| $\{1,2,3,4\}$ | $\{1,2\}\{3,4\}$ <br> OR <br> $\{1,4\}\{2,3\}$ | $\{1,3\}\{2,4\}$ |
| :---: | :---: | :---: |

Table 3.1 - The different partitions having a potentially non-zero contribution and their associated graphs
$\frac{1}{N} \operatorname{Tr}\left[\left(A_{N}, B_{N}\right)^{4}\right]$ equals
and we have to compute the value of the 3 different graphs in $B_{N}$. This is what follows:

## 1st Graph

$$
\tau_{N}^{0}\left[\bigotimes_{0}^{\infty}\right]=\tau_{N}\left[@_{0}^{\infty} \sum_{j_{1}, \ldots, j_{4}} \delta_{j_{1}}^{0} \ldots \delta_{j_{4}}^{0}=\left[\frac{1}{N} \sum_{j} \delta_{j}^{0}\right]^{4}=0\right.
$$

## 2nd Graph

$$
\begin{aligned}
& \tau_{N}^{0}[\underset{\sim}{1} \\
& \tau_{N}\left[\prod_{2}\right]=\frac{1}{N^{3}} \sum_{j_{1}, \ldots, j_{4}} \mathbb{1}_{j_{2}-j_{3}=0(N)} \delta_{j_{1}}^{0} \ldots \delta_{j_{4}}^{0}=\frac{1}{N^{3}} \sum_{j_{1}, j_{2} j_{4}} \delta_{j_{1}}^{0}\left(\delta_{j_{2}}^{0}\right)^{2} \delta_{j_{4}}^{0} \\
& =\left[\frac{1}{N} \operatorname{Tr}\left(\Delta^{0}\right)\right]^{2}\left[\frac{1}{N} \operatorname{Tr}\left(\Delta^{0}\right)^{2}\right]=0
\end{aligned}
$$

## 3rd Graph

$$
\tau_{N}^{0}\left[\begin{array}{c}
0 \\
N_{0}
\end{array}\right]=\tau_{N}\left[\tau_{N}^{0}\left[Q_{0}^{0}\right]=\frac{1}{N^{3}} \sum_{j_{1}, \ldots, j_{4}} \mathbb{1}_{j_{1}+j_{2}-j_{3}-j_{4}=0(N)} \delta_{j_{1}}^{0} \ldots \delta_{j_{4}}^{0}\right.
$$

Putting the last 3 computations together into Equation (3.10), we conclude that

$$
\frac{1}{N} \mathbb{E} \operatorname{Tr}\left(\left(A_{N}^{0} B_{N}^{0}\right)^{4}\right) \underset{N \rightarrow \infty}{\rightarrow} \mathbb{E}\left[\lim _{N \rightarrow \infty} \frac{1}{N} \operatorname{Tr}\left(\left(A_{N}^{0}\right)^{2}\right)\right]^{2} \frac{1}{N^{3}} \sum_{j_{1}, \ldots, j_{4}} \delta_{j_{1}}^{0} \ldots \delta_{j_{4}}^{0} \mathbb{1}_{j_{1}+j_{2}-j_{3}-j_{4}=0(N)}
$$

The conclusion that we can draw from this is that if the quantity

$$
\begin{equation*}
S_{N}\left(\Delta_{N}^{0}\right):=\frac{1}{N^{3}} \sum_{j_{1}, \ldots, j_{4}} \delta_{j_{1}}^{0} \ldots \delta_{j_{4}}^{0} \mathbb{1}_{j_{1}+j_{2}-j_{3}-j_{4}=0(N)} \tag{3.11}
\end{equation*}
$$

is not asymptotically 0 , the matrices $A_{N}$ and $B_{N}$ cannot be asymptotically free.
Remark 3.40. We can rewrite $S_{N}\left(\delta_{N}^{0}\right)$ as

$$
\frac{1}{N} \sum_{h=0}^{N-1} \frac{1}{N} \sum_{j_{1}-j_{3}=h(N)} \delta_{j_{1}}^{0} \delta_{j_{3}}^{0} \frac{1}{N} \sum_{j_{4}-j_{2}=h(N)} \delta_{j_{2}}^{0} \delta_{j_{4}}^{0}=\frac{1}{N} \sum_{h} \operatorname{Cov}^{2}(h)
$$

where we denote $\operatorname{Cov}(h)=\frac{1}{N} \sum_{i-j=h(N)} \delta_{i}^{0} \delta_{j}^{0}$.

### 3.3 Examples of lack of freeness

After this theoretical intermission, we return to our problem concerning wireless communication. In order to generalize the capacity theorem from [30] to a wider family of channels, the two channel matrices modelling the time and frequency fading must be freely independent. In this chapter's notation, these are the matrices $A_{N}$ and $B_{N}$ (or $M_{N}$ ). We will therefore apply our criteria to these matrices with particular models for $B_{N}$ (or $M_{N}$ ) to identify cases where the matrices cannot possibly be free.

We begin with deterministic examples.

### 3.3.1 Examples relying on arithmetic structure

Fix a prime $q$ such that $N=n q$ and let the matrix $\Delta_{N}$ be defined as

$$
\delta_{i}=\left\{\begin{array}{l}
1 \text { if } i=0(q) \\
0 \text { if } i \neq 0(q)
\end{array}\right.
$$

This represents very regular on-off fading. The associated $\Delta_{N}^{0}$ matrix is

$$
\delta_{i}^{0}=\left\{\begin{array}{l}
1-\frac{1}{q} \text { if } i=0(q) \\
-\frac{1}{q} \text { if } i \neq 0(q)
\end{array}\right.
$$

In this case we can see that $\operatorname{Cov}(h)$ evaluates to

$$
\operatorname{Cov}=\left\{\begin{array}{l}
\frac{1}{q}\left(\frac{q-1}{q}\right) \text { if } h=0(q) \\
-\left(\frac{1}{q}\right)^{2} \text { if } h \neq 0(q)
\end{array}\right.
$$

This is because if $h=0(q)$, then $j_{1}, j_{2}=0(q)$, whereas if $h \neq 0(q)$ then at most one of $j_{1}$ or $j_{2}$ will be zero modulo $q$. We can therefore compute

$$
\begin{aligned}
\frac{1}{N} \sum_{h=0}^{N} \operatorname{Cov}^{2}(h) & =\frac{1}{N} \frac{N}{q}\left[(q-1) \frac{1}{q^{4}}+\left(\frac{1}{q} \frac{q-1}{q}\right)\right] \\
& =\frac{q-1}{q^{4}}
\end{aligned}
$$

We see that this expression is never 0, proving that the matrices cannot be asympotically free. We hasten to point out that in this particular case, we can compute explicitly the limiting moments of the product $A_{N} B_{N}$ for a well chosen $A_{N}$ matrix, see Section 3.4.

### 3.3.2 Projection with contiguous values

Fix $0<\eta<1$ and consider the diagonal matrix

$$
\delta_{i}= \begin{cases}1 & \text { if } i<\eta N \\ 0 & \text { otherwise }\end{cases}
$$

This matrix has two blocks of values, and represents on off fading where the fading blocks are very long. The associated $\Delta_{N}^{0}$ matrix is

$$
\delta_{i}^{0}= \begin{cases}1-\eta & \text { if } i<\eta N \\ -\eta & \text { otherwise }\end{cases}
$$

We can make the explicit computation of $S_{N}\left(\Delta_{N}^{0}\right)$ in this case. For the sake of exposition, we will take $\eta=1 / 2$ and $N$ even, $N^{\prime}=N / 2$. Similar results can be obtained for $0<\eta<1, \eta \neq 1 / 2$. In the table below, we indicate by $+(-)$ if the index is in the first (second) half of the $N$ indices. Since the entries are $\pm \frac{1}{2}$, only the signs matter.


We add the contributions with an even number of + and subtract those with an odd number and obtain

$$
S_{N}\left(\Delta_{N}^{0}\right)=\frac{8}{N^{3}} *\left[N^{\prime 2}+\frac{N^{\prime}\left(N^{\prime}-1\right)\left(N^{\prime}-2\right)}{3}\right] * \eta^{4}=\frac{1}{16}\left(\frac{1}{3}+\frac{8}{3 N^{2}}\right)
$$

This will not converge to 0 as $N \rightarrow \infty$, showing the lack of asymptotic freeness in this case.

### 3.3.3 Markov Chains

Let us consider the case where the matrix $M_{N}$ is not deterministic and the entries $\xi_{i}$ are distributed according to a stationary Markov chain. It is sufficient to use the criterion of order 2, Equation (3.5).

For concreteness, we examine a Markov chain $\xi_{i}$ with two states, but the discussion carries to any Markov chain whose stationary distribution has zero expectation.

Let the chain have two states $s_{1}$ and $s_{2}$ with transition probabilities $\alpha$ and $\beta$. The chain remains in its current state with probabilities $1-\alpha$ and $1-\beta$ respectively. The stationary distribution is given by


Figure 3.5 - We see very different behaviour for the eigenvalues. Here $N=1000$ and we plot the eigenvalues of $A F \Delta F^{*}$ where $A$ is i.i.d. Bernoulli(0.5) and $\Delta$ is either i.i.d. or contiguous (we remove a weight of 0.5 from the origin for better visibility).

$$
\pi=\left(\frac{\beta}{\alpha+\beta}, \frac{\alpha}{\alpha+\beta}\right)
$$

and so we require that $\beta s_{1}+\alpha s_{2}=0$. We set $\xi_{0}$ the initial state to have distribution $\pi$.
The transition probabilities $p_{i j}(n)$ can easily be computed by diagonalizing the transition matrix.

$$
p_{i j}(n)=\left(\begin{array}{ll}
\frac{\beta}{\alpha+\beta}+\frac{\alpha}{\alpha+\beta}(1-\alpha-\beta)^{n} & \frac{\alpha}{\alpha+\beta}-\frac{\alpha}{\alpha+\beta}(1-\alpha-\beta)^{n} \\
\frac{\beta}{\alpha+\beta}-\frac{\beta}{\alpha+\beta}(1-\alpha-\beta)^{n} & \frac{\alpha}{\alpha+\beta}+\frac{\beta}{\alpha+\beta}(1-\alpha-\beta)^{n}
\end{array}\right)
$$

Lemma 3.41. On the above Markov chain, we have that Equation (3.5) in the criterion of order 2 evaluates to

$$
\begin{equation*}
\frac{2}{N^{2}} \frac{\alpha \beta}{(\alpha+\beta)^{2}}\left(s_{1}-s_{2}\right)^{2}\left[(N-1) \frac{1-\alpha-\beta}{\alpha+\beta}+\frac{(1-\alpha-\beta)^{2}}{(\alpha+\beta)^{2}}-\frac{(1-\alpha-\beta)^{N+1}}{(\alpha+\beta)^{2}}\right]+\frac{1}{N}\left[\frac{\beta}{\alpha+\beta} s_{1}^{2}+\frac{\alpha}{\alpha+\beta} s_{2}^{2}\right] \tag{3.12}
\end{equation*}
$$

Remark 3.42. Equation (3.12) will be zero if we take $\alpha$ and $\beta$ such that $\frac{1}{\alpha}, \frac{1}{\beta} \in O(N)$. Note
that in the case where $\alpha$ and $\beta$ are constants, the asymptotic freeness of $A_{N}$ and $M_{N}$ has already been proven in [30]. Equation (3.12) will however be nonzero if we take $\alpha=k / N$, $\beta=k^{\prime} / N$ for $k, k^{\prime}$ constants. When looking at the Markov chain $\xi_{i}$, this would typically result in blocks whose length is of order $N$. In our communication scenario, this would translate to a bursty channel. See Figure 3.6 for the empirical eigenvalue distribution of the product $A_{N} M_{N}$ associated to these Markov chains.


Figure 3.6 - We see here that if the transition probability between states is very low, the eigenvalue distribution is different (we remove a weight of 0.5 from the origin for better visibility).

Proof of Lemma 3.41. According to Equation (3.5), we must compute $\mathbb{E}\left[\left(\frac{1}{N} \sum_{i}^{N} \xi_{i}\right)^{2}\right]=\frac{1}{N^{2}} \mathbb{E}\left[\sum_{i j}^{N} \xi_{i} \xi_{j}\right]$ since the diagonal entries of $F \Xi F^{*}$ are the same across the diagonal. It suffices to compute the second moment and by stationarity we can suppose $i=0$.

First, $\mathbb{E}\left(\xi_{i}^{2}\right)=\frac{\beta}{\alpha+\beta} s_{1}^{2}+\frac{\alpha}{\alpha+\beta} s_{2}^{2}$.
Now, for $k>0$,

$$
\begin{aligned}
\mathbb{E}\left(\xi_{0} \xi_{k}\right)= & \mathbb{E}\left(\xi_{0} \xi_{k} \mid \xi_{0}=s_{1}\right) \mathbb{P}\left(\xi_{0}=s_{1}\right)+\mathbb{E}\left(\xi_{0} \xi_{k} \mid \xi_{0}=s_{2}\right) \mathbb{P}\left(\xi_{0}=s_{2}\right) \\
= & {\left[\mathbb{P}\left(\xi_{k}=s_{1} \mid \xi_{0}=s_{1}\right) s_{1}^{2}+\mathbb{P}\left(\xi_{k}=s_{2} \mid \xi_{0}=s_{1}\right) s_{1} s_{2}\right] \frac{\beta}{\alpha+\beta} } \\
& +\left[\mathbb{P}\left(\xi_{k}=s_{1} \mid \xi_{0}=s_{2}\right) s_{1} s_{2}+\mathbb{P}\left(\xi_{k}=s_{2} \mid \xi_{0}=s_{2}\right) s_{2}^{2}\right] \frac{\alpha}{\alpha+\beta}
\end{aligned}
$$

$$
=\frac{\alpha \beta}{(\alpha+\beta)^{2}}\left(s_{1}-s_{2}\right)^{2}(1-\alpha-\beta)^{k}
$$

With this expression in hand, we can compute the second moment

$$
\begin{aligned}
2 \sum_{i>j} \mathbb{E}\left(\xi_{i} \xi_{j}\right) & =2 \frac{\alpha \beta}{(\alpha+\beta)^{2}}\left(s_{1}-s_{2}\right)^{2} \sum_{i>j}(1-\alpha-\beta)^{i-j} \\
& =2 \frac{\alpha \beta}{(\alpha+\beta)^{2}}\left(s_{1}-s_{2}\right)^{2}\left[\sum_{j=2}^{N} \frac{1-(1-\alpha-\beta)^{j}}{\alpha+\beta}-1\right] \\
& =2 \frac{\alpha \beta}{(\alpha+\beta)^{2}}\left(s_{1}-s_{2}\right)^{2}\left[(N-1) \frac{1-\alpha-\beta}{\alpha+\beta}+\frac{(1-\alpha-\beta)^{2}}{(\alpha+\beta)^{2}}-\frac{(1-\alpha-\beta)^{N+1}}{(\alpha+\beta)^{2}}\right]
\end{aligned}
$$

The quantity to consider is therefore

$$
\begin{equation*}
2 \frac{\alpha \beta}{(\alpha+\beta)^{2}}\left(s_{1}-s_{2}\right)^{2}\left[(N-1) \frac{1-\alpha-\beta}{\alpha+\beta}+\frac{(1-\alpha-\beta)^{2}}{(\alpha+\beta)^{2}}-\frac{(1-\alpha-\beta)^{N+1}}{(\alpha+\beta)^{2}}\right]+N\left[\frac{\beta}{\alpha+\beta} s_{1}^{2}+\frac{\alpha}{\alpha+\beta} s_{2}^{2}\right] \tag{3.13}
\end{equation*}
$$

allowing us to conclude.

### 3.4 Traffic distributions

In this section, we will explicitly compute the eigenvalue distribution of the product $A_{N} F \Delta_{N} F^{*}$ for some well chosen matrices $A_{N}$ and $\Delta_{N}$. Since we are interested in the moments of the product, we do not need to recentre the matrices and this will simplify computations.

Recall that Equation (3.9) allows us to write $m_{k}$, the limiting $k^{t h}$ moment of $A_{N} B_{N}$, as the product of a component involving $B_{N}$ and a component involving $A_{N}$, this last component being particularly simple since the matrix $A_{N}$ is diagonal. Recall that $C_{k}$ is the cyclic graph with $k$ edges, with one loop attached to each vertex and let $C_{k}^{\prime}$ be the cyclic graph without these loops. Let $a$ be a random variable distributed as a diagonal element of $A_{N}$. Using Equation (3.9), we can compute

$$
m_{k}=\lim _{N \rightarrow \infty} \tau_{N}\left[C_{k}\left(A_{N}, B_{N}\right)\right]=\lim _{N \rightarrow \infty} \sum_{\sigma \in \Pi_{|V|}} \tau_{N}^{0}\left[C_{k}^{\sigma}\left(A_{N}, B_{N}\right)\right]
$$

$$
\begin{array}{ll}
=\lim _{N \rightarrow \infty} \sum_{\sigma \in \Pi_{|V|}} \tau_{N}^{0}\left[C_{k}^{\prime \sigma}\left(B_{N}\right)\right] \prod_{\beta \in \sigma} \mathbb{E}\left[a^{|B|}\right] & \text { using that } A_{N} \text { is diagonal } \\
=\lim _{N \rightarrow \infty} \sum_{\sigma \in \Pi_{V \mid}} \sum_{\pi \geq \sigma} \mu(\sigma, \pi) \tau_{N}\left[C_{k}^{\prime \pi}\left(B_{N}\right)\right] \prod_{\beta \in \sigma} \mathbb{E}\left[a^{|\beta|}\right] & \text { by Möbius inversion } \\
=\lim _{N \rightarrow \infty} \sum_{\pi \in \Pi_{|V|}} \sum_{\sigma \leq \pi} \mu(\sigma, \pi) \tau_{N}\left[C_{k}^{\prime \prime}\left(B_{N}\right)\right] \prod_{\beta \in \sigma} \mathbb{E}\left[a^{|\beta|}\right] & \text { Inverting the two sums } \\
=\lim _{N \rightarrow \infty} \sum_{\pi \in \Pi_{|V|}} \tau_{N}\left[C_{k}^{\prime \pi}\left(B_{N}\right)\right] \sum_{\sigma \leq \pi} \mu(\sigma, \pi) \prod_{\beta \in \sigma} \mathbb{E}\left[a^{|\beta|}\right] &
\end{array}
$$

Let us now assume that $A_{N}$ is an i.i.d. matrix with 0-1 Bernoulli(p) entries. We therefore have $\mathbb{E}\left(a^{i}\right)=p$ for all $i>0$. This simplifies the above formula as

$$
\begin{equation*}
\sum_{\pi \in \Pi_{|V|}} \tau\left(C_{k}^{\prime \pi}\right)\left(B_{N}\right) \sum_{\sigma \geq \pi} \mu(\sigma, \pi) \prod_{\beta \in \sigma} \mathbb{E}\left[a^{|\beta|}\right]=\sum_{\pi \in \Pi_{|V|}} \tau\left(C_{k}^{\prime \pi}\right)\left(B_{N}\right) \sum_{\sigma \geq \pi} \mu(\sigma, \pi) p^{\# \sigma} \tag{3.14}
\end{equation*}
$$

where for a partition $\sigma$ we denote $\# \sigma$ the number of blocks in $\sigma$.
Proposition 3.43. Let $\Delta_{N}$ to be the deterministic matrix whose $i^{t h}$ entry is $\mathbb{1}_{i=0(q)}$. Then the $k^{t h}$ moment of $A_{N} B_{N}$ is

$$
\sum_{j=1}^{q}(j / q)^{k}\left[\frac{1}{q} \sum_{l=j}^{q} p^{l}\binom{q}{l}\binom{l}{j}(-1)^{l-j}\right]
$$

and the empirical eigenvalue of converges to the measure $\frac{q-1}{q} \delta_{0}+\frac{1}{q} v$ where $v \sim \operatorname{Binomial}(q, p)$.

Proof. Since we are evaluating the $k^{t h}$ moment, $k=|E|$. Let us evaluate $\tau\left(C_{k}\right)\left(B_{N}\right)$ according to Lemma 3.31.

$$
\begin{aligned}
\frac{1}{N^{1+k-|V|}} & \sum_{j_{1}, \ldots j_{k} \in[N]} \delta_{j_{1}} \ldots \delta_{j_{k}} \mathbb{1}_{\sum_{e \text { entering } \nu} j_{e}-\sum_{e \text { exiting } \nu} j_{e}=0(N)} \\
& =\frac{1}{N^{1+k-|V|}} \sum^{1} \mathbb{1}_{\text {all } \mathrm{j} \text { are } 0(q)} \mathbb{1}_{\sum_{e \text { entering } \nu} j_{e}-\sum_{e \text { exiting } v} j_{e}=0(N)} \\
& =\frac{1}{N^{1+k-|V|}} \sum_{j_{1}, \ldots j_{|E|}}^{N / q} \mathbb{1}_{\sum_{e \text { entering } \nu} q j_{e}-\sum_{e \text { exiting } \nu} q j_{e}=0(N)} \\
& =\frac{1}{q^{1+k-|V|}}
\end{aligned}
$$

The last equality follows from the fact that we have $N / q$ possible values for each index $j_{i}$, and we have exactly $k-|V|+1$ choices to make, since precisely $|V|-1$ of the linear equations in
the second indicator function are linearly independent. We can see the linear equations as a linear map between modules and use a cardinality argument (the linear independence means that the image module is free of rank $|V|-1)$. Otherwise, one can observe that adding the two equations containing a given variable $j$ together yields a third equation, and on the graph this is equivalent to merging two nodes together. This allows one to express $j$ in terms of the other variables (fixes the value of $j$ ) and reduces the number of equations by 1 . This can be repeated $|V|-1$ times. Crucially, we use that the coefficient in front of $j$ is $\pm 1$, hence invertible in $\mathbb{Z} /(N / q) \mathbb{Z}$.

Observe that when we identify the vertices of the graph according to the partition $\pi$, the number of edges is constant and the number of vertices is equal to the number of blocks of the partition $\pi$. As such, we can rewrite Equation (3.14) as

$$
\begin{equation*}
\frac{1}{q^{1+k}} \sum_{\pi} \sum_{\sigma \leq \pi} \mu(\sigma, \pi) q^{\# \pi} p^{\# \sigma}=\frac{1}{q^{1+k}} \sum_{\sigma} p^{\# \sigma} \sum_{\sigma \leq \pi} \mu(\sigma, \pi) q^{\# \pi} \tag{3.15}
\end{equation*}
$$

We recognize the inner sum as the characteristic polynomial of the lattice $\Pi_{\# \sigma}$ evaluated at q , whose value is $(q)_{\# \sigma}$, see [25, Section 3.10]. Here, by $(n)_{k}$ we denote the combinatorial coefficient $n *(n-1) \ldots(n-k+1)$. Substituting this, the sum on the right hand in Equation (3.15) only depends on the number of blocks of the partition $\sigma$. Let $S(k, l)$ be the Stirling number of the second kind, which count the number of partitions of $k$ elements into $l$ blocks. We now get an expression for the $k^{t h}$ moment:

$$
\begin{align*}
m_{k} & =\frac{1}{q^{k+1}} \sum_{l=1}^{k} p^{l}(q)_{l} S(k, l)  \tag{3.16}\\
& =\frac{1}{q^{k+1}} \sum_{l=1}^{k} p^{l}(q)_{l} \frac{1}{l!} \sum_{j=1}^{l}(-1)^{l-j}\binom{l}{j} j^{k}  \tag{3.17}\\
& =\frac{1}{q^{k+1}} \sum_{l=1}^{q} p^{l}(q)_{l} \frac{1}{l!} \sum_{j=1}^{l}(-1)^{l-j}\binom{l}{j} j^{k}  \tag{3.18}\\
& =\frac{1}{q^{k+1}} \sum_{l=1}^{q} p^{l}\binom{q}{l} \sum_{j=1}^{l}(-1)^{l-j}\binom{l}{j} j^{k}  \tag{3.19}\\
& =\frac{1}{q^{k+1}} \sum_{j=1}^{q} j^{k}\left[\sum_{l=j}^{q} p^{l}\binom{q}{l}\binom{l}{j}(-1)^{l-j}\right]  \tag{3.20}\\
& =\sum_{j=1}^{q}(j / q)^{k}\left[\frac{1}{q} \sum_{l=j}^{q} p^{l}\binom{q}{l}\binom{l}{j}(-1)^{l-j}\right] \tag{3.21}
\end{align*}
$$

changing the range of the summation

From the second to the third line, we have changed the range of the summation. If $k>q$, then $(q)_{l}$ is 0 for any $l>q$. If $k<q$, we must check that, for $l>k$

$$
\sum_{j=1}^{l}(-1)^{l-j}\binom{l}{j} j^{k}=0
$$

For $k=1$, we can rework the sum to be

$$
(-1)^{l} \sum_{j=1}^{l}(-1)^{j} \frac{l!}{(j-1)(l-j)!}=(-1)^{l} \sum_{j=1}^{l}(-1)^{j}\binom{l-1}{j-1} l=0
$$

We will prove the statement for $k$ by induction, assuming it holds for $k-1$.

$$
\begin{aligned}
& \sum_{j=1}^{l}(-1)^{l-j}\binom{l}{j} j^{k}=\sum_{j=1}^{l}(-1)^{l-j}\binom{l}{j}\left[(j)_{k}+Q(j)\right] \\
& =\sum_{j=k}^{l}(-1)^{l-j}(l)_{k}\binom{l-k}{j-k} \\
& =(-1)^{l}(l)_{k} \sum_{j=k}^{l}(-1)^{j}\binom{l-k}{j-k}=0
\end{aligned}
$$

Here, the polynomial $Q$ is of degree strictly less than $k$ and so we can assume by induction that $\sum_{j=1}^{l}(-1)^{l-j}\binom{l}{j} Q(j)=0$. This completes the induction and the reasoning to obtain the $k^{t h}$ moment.

Equation (3.21) gives the moment of order $k$. We can recover the (discrete) distribution by observing that the expression brackets is the weight at $j / q$ and can be rewritten as

$$
\begin{aligned}
\frac{1}{q} \sum_{l=j}^{q} p^{l}\binom{q}{l}\binom{l}{j}(-1)^{l-j} & =\frac{1}{q} \sum_{m=0}^{q-j} p^{m+j}\binom{q}{m+j}\binom{m+j}{j}(-1)^{m} \\
& =\frac{1}{q} \sum_{m=0}^{q-j} p^{m+j} \frac{q!}{(q-m-j)!} \frac{1}{j!m!}(-1)^{m} \\
& =\frac{p^{j}}{j!q} \sum_{m=0}^{q-j}(-p)^{m} \frac{q!}{(q-j)!} \frac{(q-j)!}{(q-m-j)!m!} \\
& =\frac{1}{q} p^{j}\binom{q}{j} \sum_{m=0}^{q-j}(-p)^{m}\binom{q-j}{m} \\
& =\frac{1}{q}\binom{q}{j} p^{j}(1-p)^{q-j}
\end{aligned}
$$



Figure 3.7 - Empirical eigenvalue distribution of the matrix in Proposition 3.43 with $q=7$ (We omit the mass in 0 ). The convergence is slow since most of the mass is in 0.

The rest of the mass is at 0 , hence the result.

### 3.4.1 A more direct computation

Let $N$ be even. We can compute $\frac{1}{N} \mathbb{E} \operatorname{Tr}(A B)^{k}$ directly for $A$ i.i.d. Bernoulli(p) and $\Delta_{i i}=\mathbb{1}_{i=0(2)}$, i.e. $\mathrm{q}=2$. Indeed, the $j k$ entry of the matrix $B_{N}$ is given by

$$
\left(B_{N}\right)_{j k}=\frac{1}{N} \sum_{l=0}^{N / 2-1} e^{2 \pi i(j-k) l / N}= \begin{cases}1 / 2 & \text { if } j=k  \tag{3.22}\\ 1 / 2 & \text { if } j-k=N / 2(N) \\ 0 & \text { otherwise }\end{cases}
$$

Therefore, if we consider a summand of $\frac{1}{N} \mathbb{E} \operatorname{Tr}(A B)^{k}=\frac{1}{N} \mathbb{E} \operatorname{Tr}(A B A)^{k}$, it is of the form

$$
c_{i_{1} i_{2}} c_{i_{2} i_{3} \ldots c_{i_{k-1}} i_{k}}
$$

with $c_{i j}=\delta_{i} \delta_{j}$, since the $\delta_{i}$ are $0-1$ valued. As such, we can use the special form of $B_{N}$ to conclude that for a fixed initial index $i$, the only possibilities for $c$ are $c_{i i}, c_{i, N / 2+i}, c_{N / 2+i, i}$ and $c_{N / 2+i, N / 2+i}$. With a bit of combinatorics, we conclude that the expected value of such
a summand is $\frac{1}{2^{k}}\left[p+p^{2}\left(2^{k-1}-1\right)\right]$. The term in $p$ comes from choosing exclusively the term $c_{i i}$ and the term in $p^{2}$ comes from having 2 choices at every step except the last one. This is independent of the initial index $i$ and so $\frac{1}{N} \mathbb{E} \operatorname{Tr}(A B)^{k}=\frac{p^{2}}{2}+\frac{p(p-1)}{2^{k}}$, matching the expression found previously.

### 3.5 Conclusion and perspectives

In this chapter, we have recalled the concepts of freeness and traffic-freeness in noncommutative probability spaces and seen how these allow us to describe the eigenvalue distribution of sums and products of large random matrices. We have described the main contribution of this thesis in this field: the two criteria preventing asymptotic freeness between particular families of matrices. We have discussed examples were these criteria do not evaluate to 0 , hence providing an answer to questions concerning freeness raised in [30]. This sheds new light and gives a better understanding of channels experiencing both time and frequency domain fading. We have also made explicit computations of the moments of a particular matrix model using the theory of traffics.

One interesting research direction would be the development of $R$ and $S$ transforms for traffics. Indeed, we have seen that while we can get expressions for the limiting moments of say the products of matrices, the complexity grows exponentially. A traffic equivalent of the $S$ transform would allow us to compute the limiting eigenvalue distributions and would perhaps allow us to characterize the capacity of channels with deterministic frequency fading (and i.i.d. time domain fading) in a manner similar to what was done in [30].

One particular deterministic model where an explicit description of the moments might be within grasp is the following. Consider the matrix $\Delta$ where $\delta_{i}=1$ if $i \leq r(q)$ and 0 otherwise. The case $r=0$ has been treated at the beginning of 3.3. By letting $r, q$ go to infinity at the same rate, perhaps some insight can be gained.

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Convex Optimization, Information Theory, Probability, Random Walks, Analyse 3.
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[^0]:    ${ }^{1}$ See Section 2.2, Theorem 2.1 for a precise statement.

[^1]:    ${ }^{2}$ By "increasing with $n$ ", we mean that $A=n^{\beta}$ and $d=n^{\gamma}$ for some powers $\beta, \gamma>0$.

[^2]:    ${ }^{3}$ i.e. $m=n^{\delta}$, where $\delta>1 / 2$.

[^3]:    ${ }^{1}$ or nc probability space

