Fast Multi-view Face Tracking With Pose Estimation

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# **Overview**

- Introduction to face detection and tracking
- Face class modeling
- Multi-view face modeling
- Fast tracking and pose estimation
- Experiments and results
- Conclusions

LTS

EPFI



# Introduction to face detection

- Face detection:
  - Feature-based approaches
    - Geometrical models
    - Skin colour,...
  - Example based approaches:
    - Use a sliding window to scan an image and perform binary classification:
    - Template matching
    - SVMs

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• AdaBoost,...



4

#### Face class modeling

- Asymmetric AdaBoost is used for learning face vs. non face classifiers
- Haar-like filters: computationally efficient



• Anisotropic Gaussian filters: more discriminant







### Haar-like vs. Gaussian filters

Test error function of AdaBoost iterations







#### Multi-view face modeling

• Idea: use specific binary classifiers for each pose:







### Multi-view face modeling

• A binary pose classifier:

{Pose( $\theta_i, \phi_i$ )} vs. {other poses + non faces}

• Hierarchical sampling of the pose plane:







#### **Multi-view face modeling**







# Fast face tracking

- Condensation is used for tracking detected faces
- Tracking in two steps:
  - 1. Track the position:

2. Track the pose at the given position





# **Experiments**

- Datasets
  - CMU Pose, Illumination and Expression (PIE): 47954 images
  - INIRIALPES: 2597 images
  - Feret dataset
  - Non face examples: bootstrapping on randomly selected images
- System
  - 20x20 pixels images
  - 1 GC: a cascade of Haar filters (≈150 filters)
  - 59 PC: each PC is a cascade of GF with ≈75 filters





### Results

- 93% of correct classification on complex videos
- Very precise out-of-plane estimation
- Average estimation on elevation







# **Results – time performances**

 Tests on 1500 frames of a sequence of 320x240 pixels

Detector	fps
Detection frame by frame	6.36
Tracking	23.45





# Conclusions

- Fast multi-view face tracking
- Tree of classifiers (from general to specific)
- Tracking in 2 steps: position + pose



