

Determination of the Thermal Roughness Length for a Built Environment using High Resolution Weather Stations



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Motivations

Urban population is increasing

- now: 3.3 billion
- 2030 prediction: 5 billion (UN, 2008)



⇒ *Larger stress of built-up areas on the atmosphere*

Need to model land-atmosphere interactions in urban areas

- surface roughness z_0
- thermal roughness length z_{0h}

⇒ *Two methods to do so: morphometric or micrometeorological*

Motivations

Morphometric approaches

- use building geometry to calculate roughness parameters

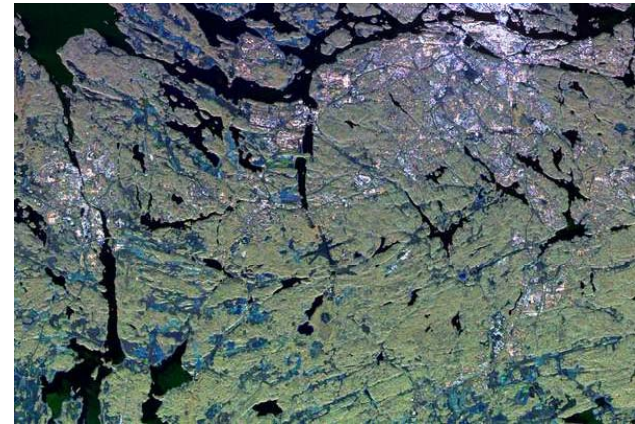
⇒ *different models often lead to widely varying estimates of roughness characteristics*

Micrometeorological approaches

- surface temperature typically inferred from satellite measurements
- MODIS: 1-km spatial resolution for T_{sfc}

⇒ *Resolution too low to account for spatial heterogeneities*

Stockholm area as seen by Modis



Source: NASA, 2008

Motivations

Morphometric approaches

- use building geometry to calculate roughness parameters

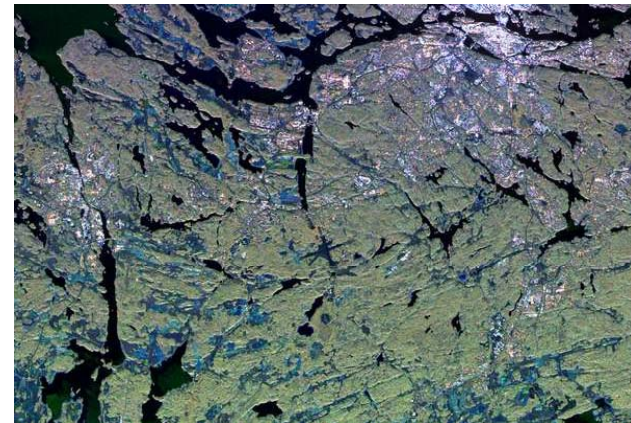
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Stockholm area as seen by Modis

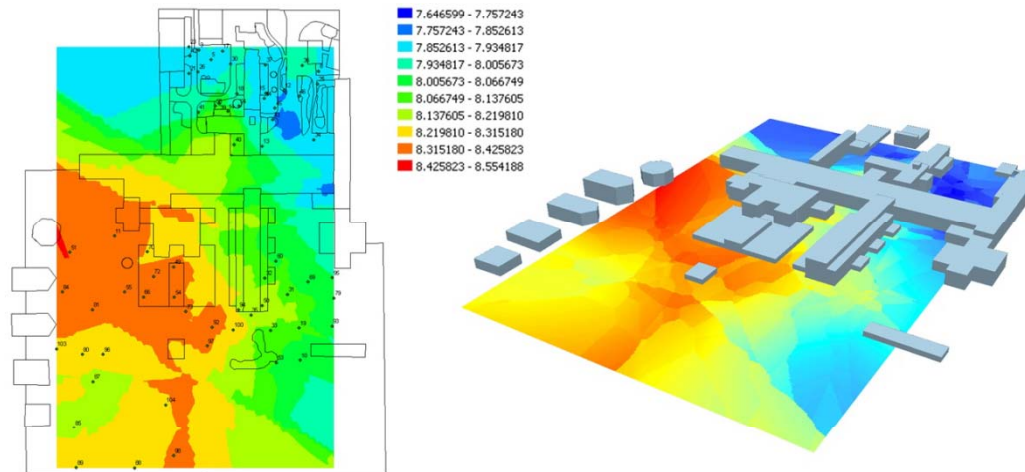


Source: NASA, 2008

Need for **high resolution** measurements of urban surfaces

Research Objectives

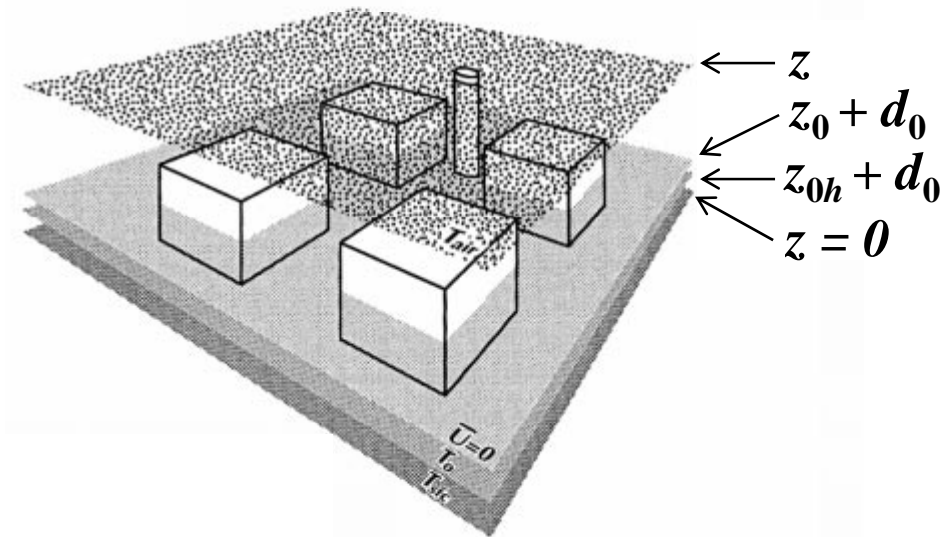
- better understand the impacts of spatial heterogeneities on land-atmosphere interactions over complex urban terrain
- calculate roughness lengths for momentum (z_0) and for heat (z_{0h}) using *in situ* measurements



Source: S. Mortier, 2007

Background

Thermal roughness length z_{0h}



Source: Voogt and Grimmond, *JAM*, 2000

- also referred to as radiometric roughness length or scalar roughness for heat
- intercept of the logarithmic profile for potential temperature in the inertial sublayer

Background

Thermal roughness length z_{0h} over heterogeneous surfaces

vegetated small hills Sugita and Brutsaert (*WRR*, 1990)



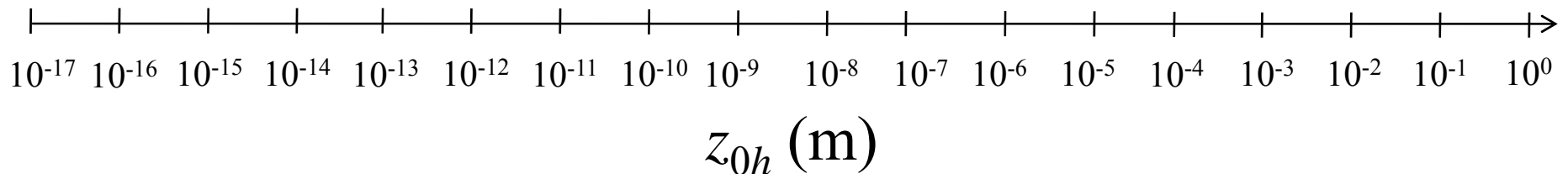
flat grassland with low hedges Hignett (*BLM*, 1994)



sparsely vegetated surfaces Mahli (*QJRMS*, 1996)



light industrial area Voogt and Grimmond (*JAM*, 2000)



Background

Monin-Obukhov Similarity Theory in the ABL

WIND SPEED

$$u = \frac{u_*}{k} \left[\ln \left(\frac{z - d_0}{z_0} \right) - \Psi_m \left(\frac{z - d_0}{L} \right) + \Psi_m \left(\frac{z_0}{L} \right) \right]$$

z_0 : surface roughness (m)

AIR TEMPERATURE

$$\theta_s - \theta = \frac{H}{\rho k u_* c_p} \left[\ln \left(\frac{z - d_0}{z_{0h}} \right) - \Psi_h \left(\frac{z - d_0}{L} \right) + \Psi_h \left(\frac{z_{0h}}{L} \right) \right]$$

z_{0h} : thermal roughness length (m)

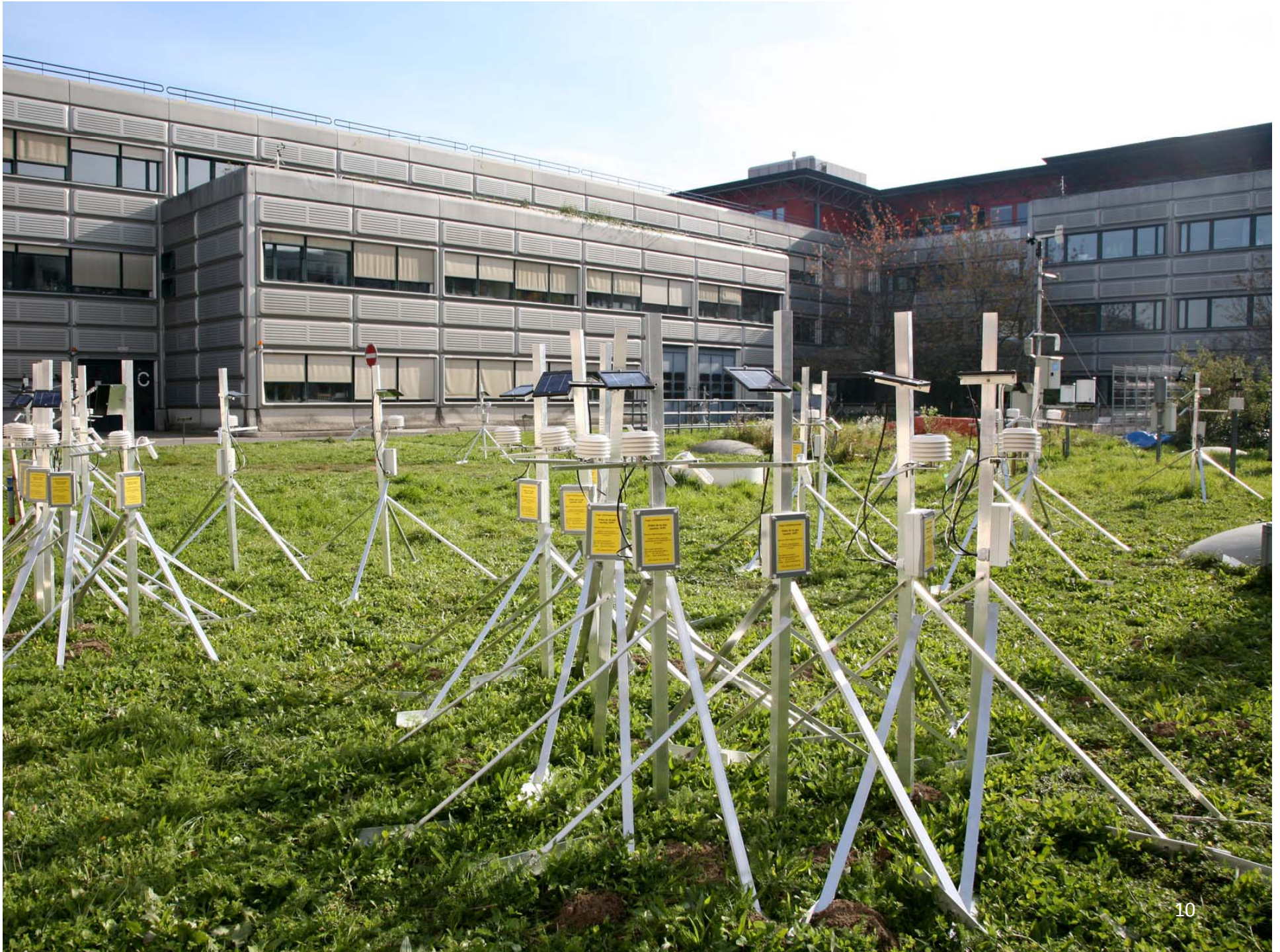
The EPFL Campus



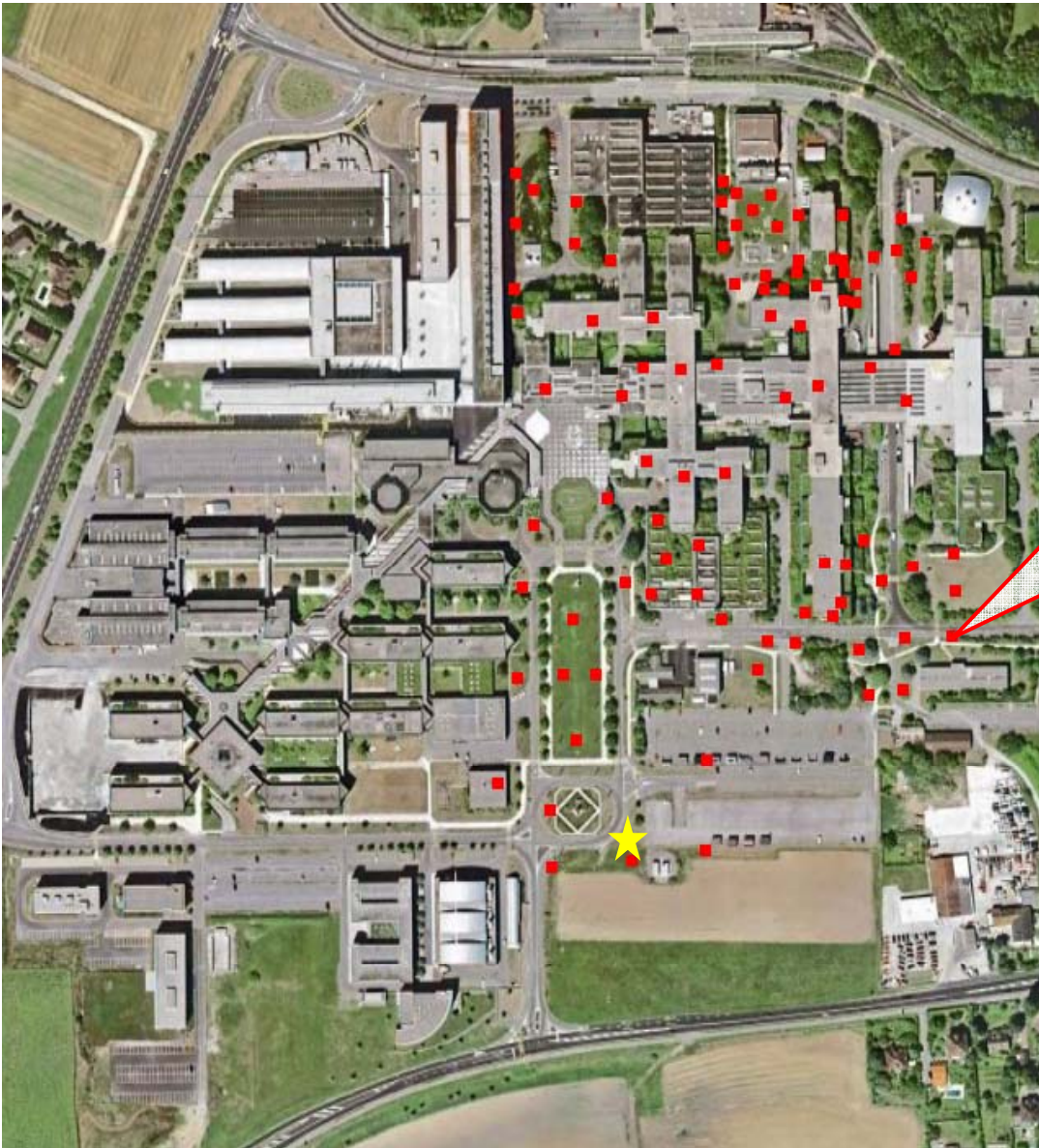
**a 750 x 500 m campus
essentially consisting of
buildings, vegetation,
roads, and parking lots**



Source: EPFL, 2008



The Experimental Setup

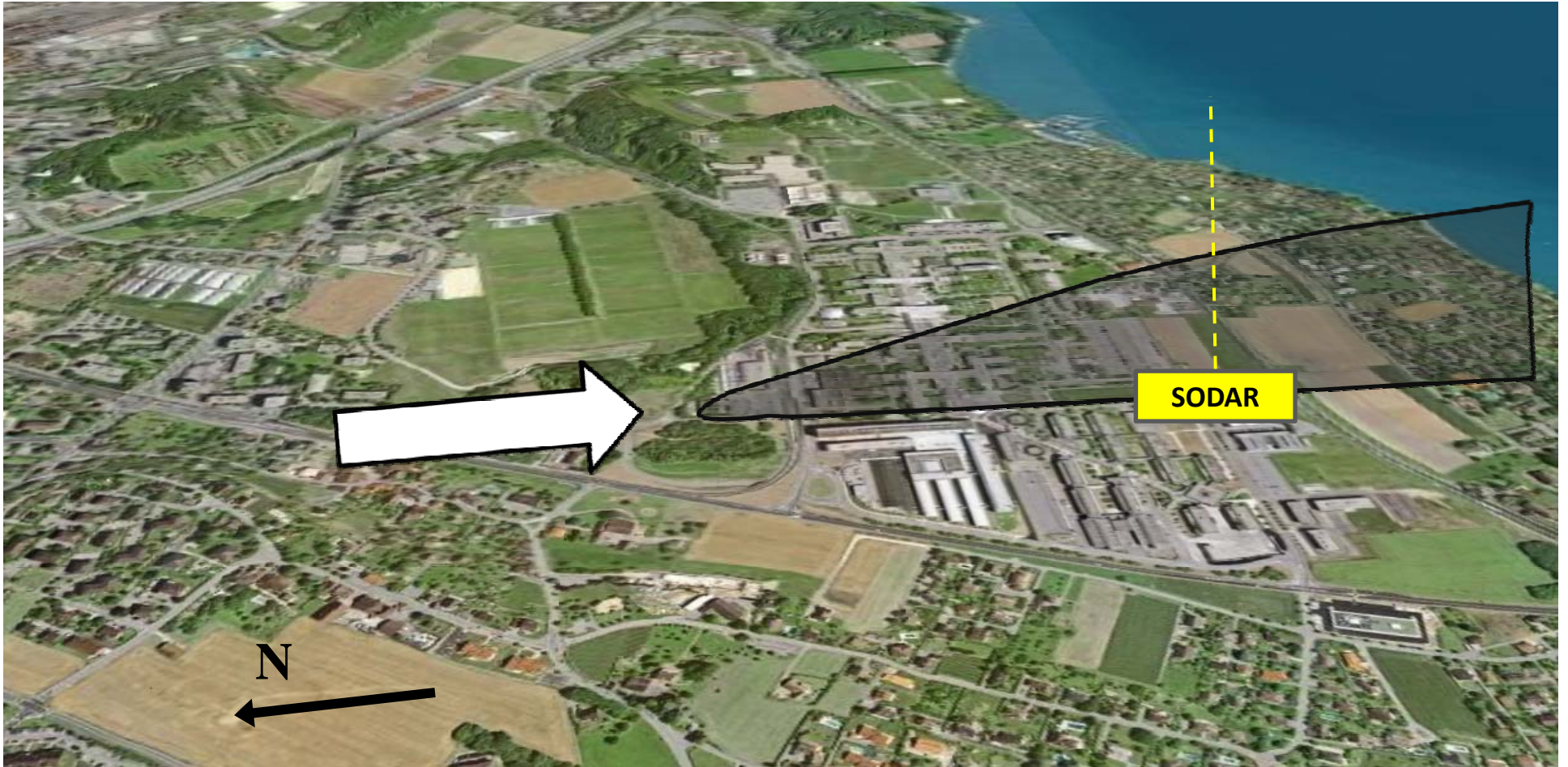


Sensorscope stations

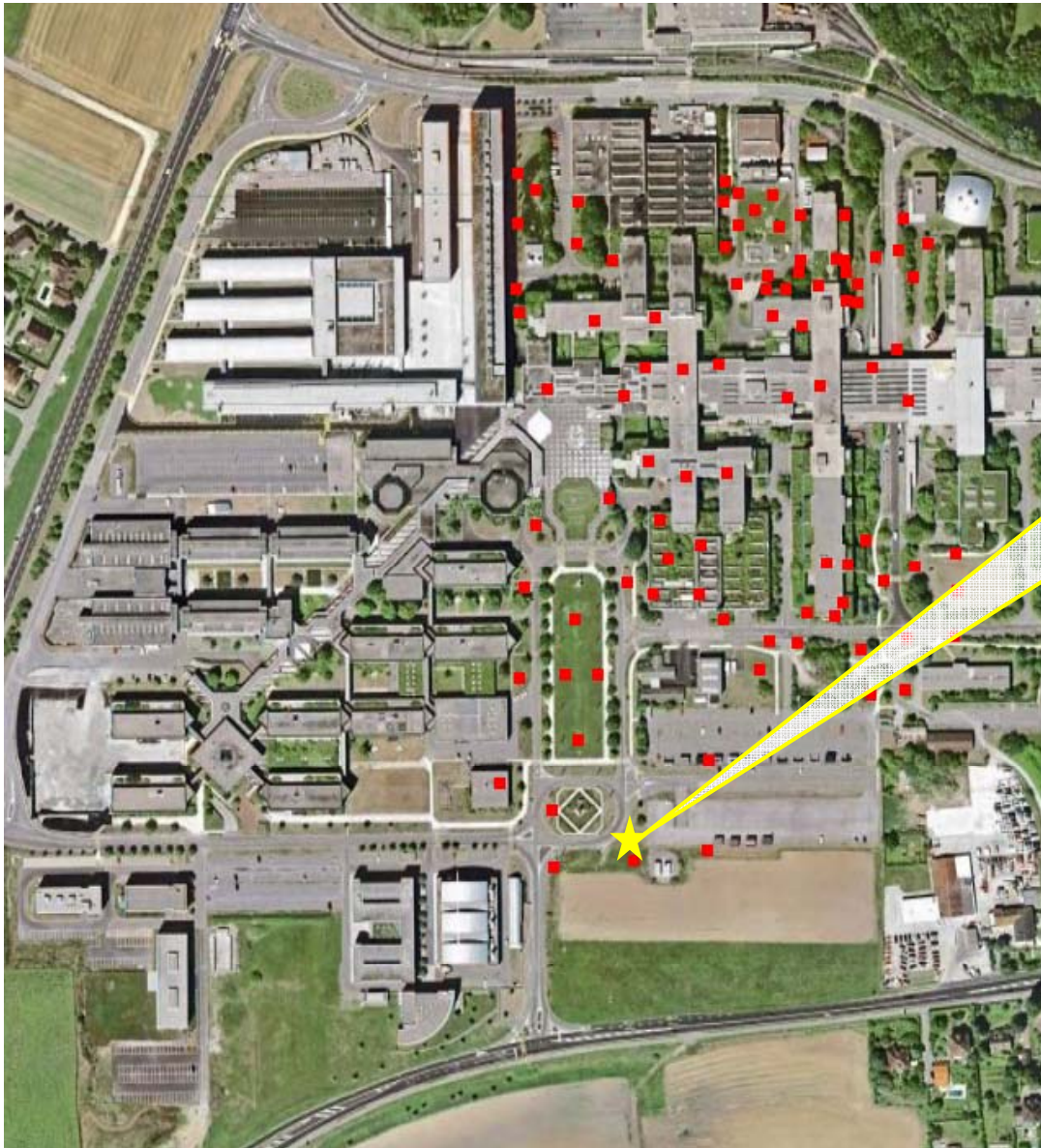


- 92 wireless weather stations
- operating from Nov. 06 to May 07
- sampling time of 2 min, but we use 30 min averages
- parameters measured: skin temperature, air temperature, wind speed, relative humidity, etc.

The Experimental Setup



The Experimental Setup



SODAR / RASS system



- operating from Jul. 06 to May 07
- wind and temperature profiles measured from 40 to 400 m
- averaging time of 30 min

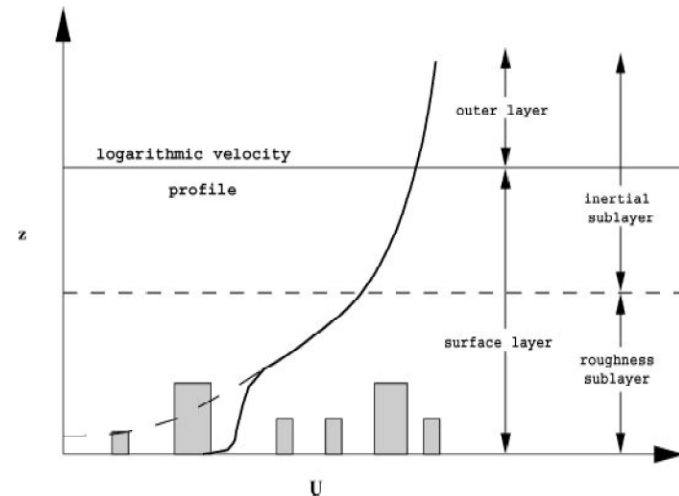
Finding Neutral Profiles

Range of interest

- Buildings range from 5 to 30 m
- Assume blending height $\approx 2 \times h_0$
- $z_{\max}/z_{\min} > 2$ (Bottema, AE, 1997)

$$\Rightarrow z = [z_{\min} = 40, z_{\max} = 100] \text{ m}$$

$$\Rightarrow d_0 = 20 \text{ m} \quad (\text{estimated})$$



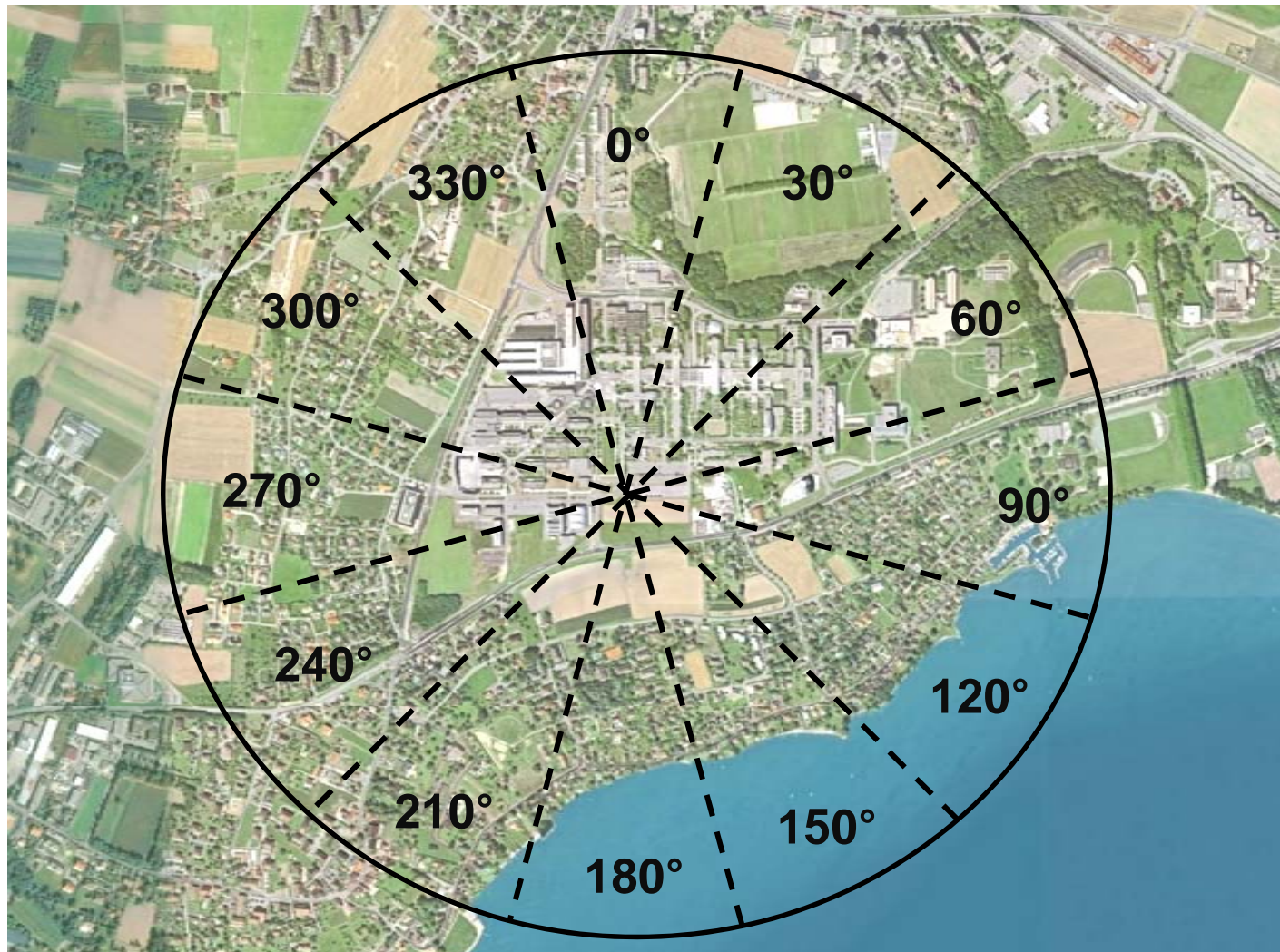
Adapted from Britter and Hanna, *ARFM*, 2003

Criteria for near-neutral conditions

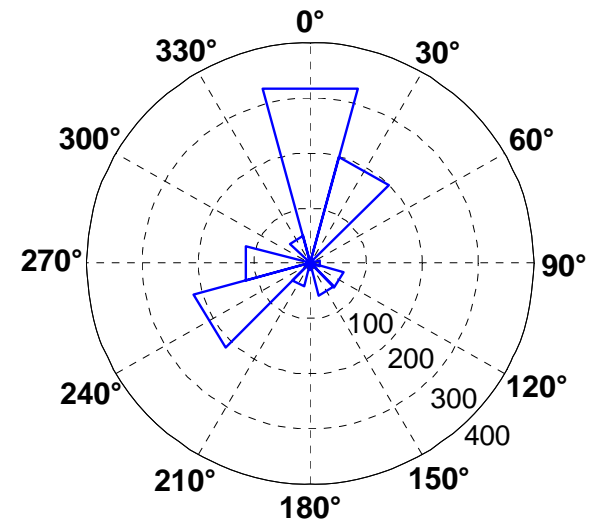
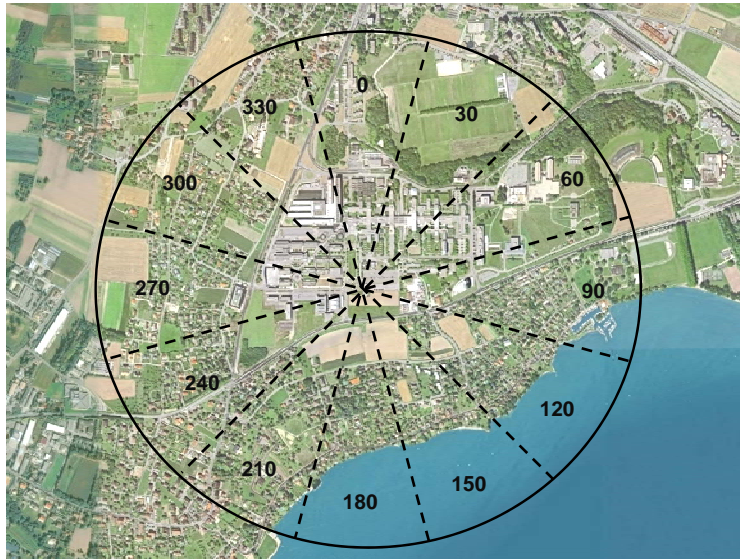
- 1) consistent wind direction with height
- 2) $u > 5 \text{ m/s}$
- 3) Least-square fitting between u and $\ln(z - d_0)$ yields $R^2 \geq 0.5$
- 4) $|Ri_g| \leq 0.1$

$$Ri_g = \frac{\frac{g}{\bar{\theta}_v} \frac{\partial \bar{\theta}_v}{\partial z}}{\left[\left(\frac{\partial \bar{U}}{\partial z} \right)^2 + \left(\frac{\partial \bar{V}}{\partial z} \right)^2 \right]}$$

Wind Sectors

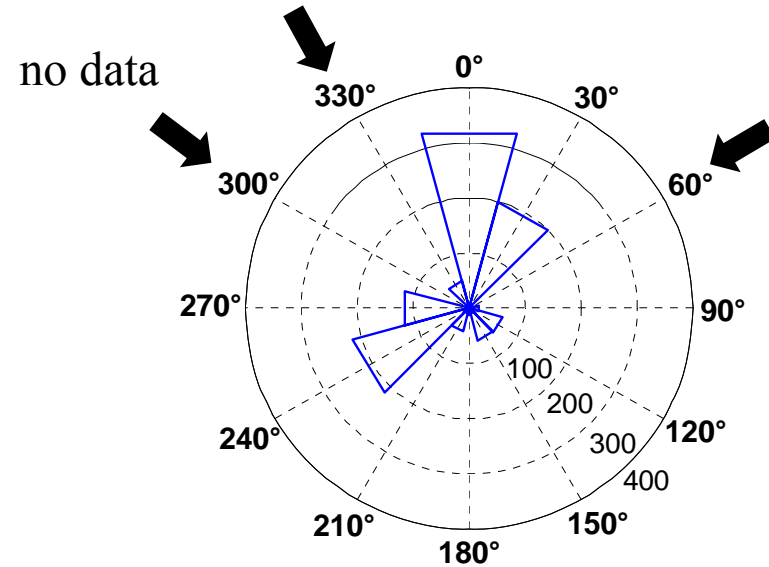
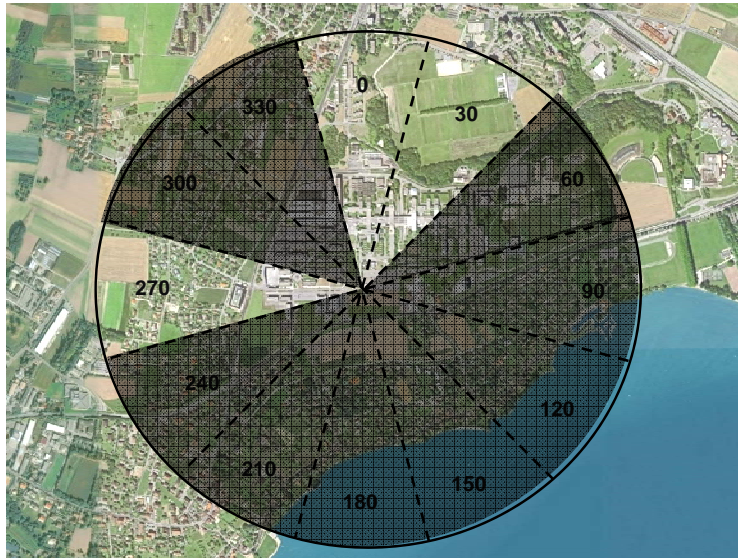


Finding Neutral Profiles

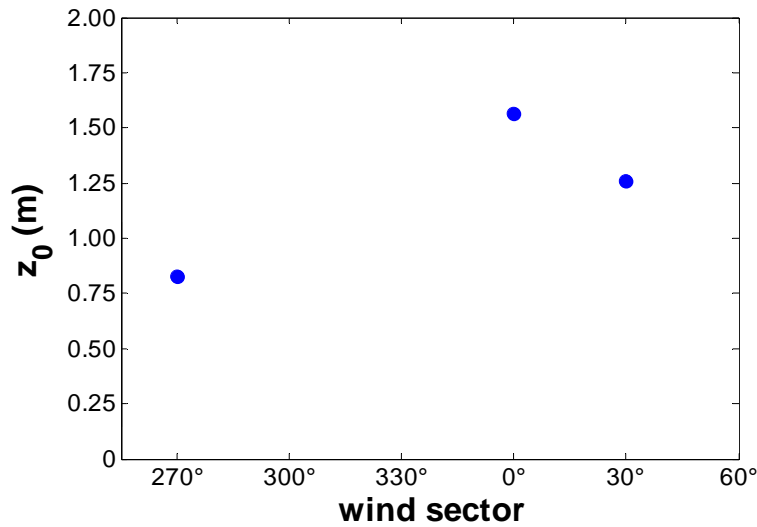


Number of cases of wind speed exceeding 5 m/s.
Measurements at 50 m from July 06 to May 07.

Momentum Surface Roughness



Number of cases of wind speed exceeding 5 m/s.
Measurements at 50 m from July 06 to May 07.



Center of large towns and cities (Stull, 1988)

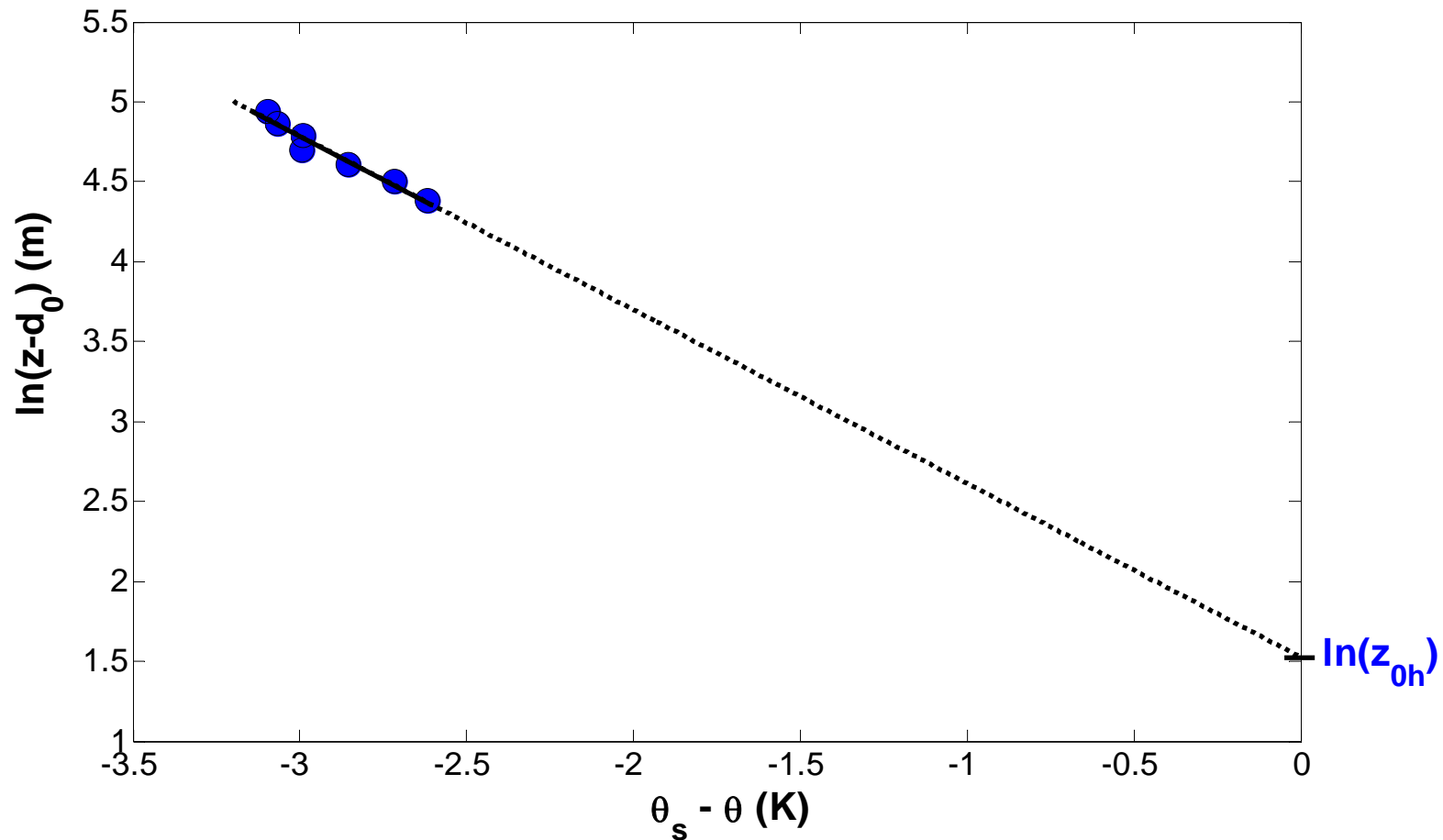
Total number of profiles: 16 128
Near-neutral profiles: **108** (0.7 %)

Median of surface roughness distribution for wind sectors with sufficient data.

Thermal Roughness Length

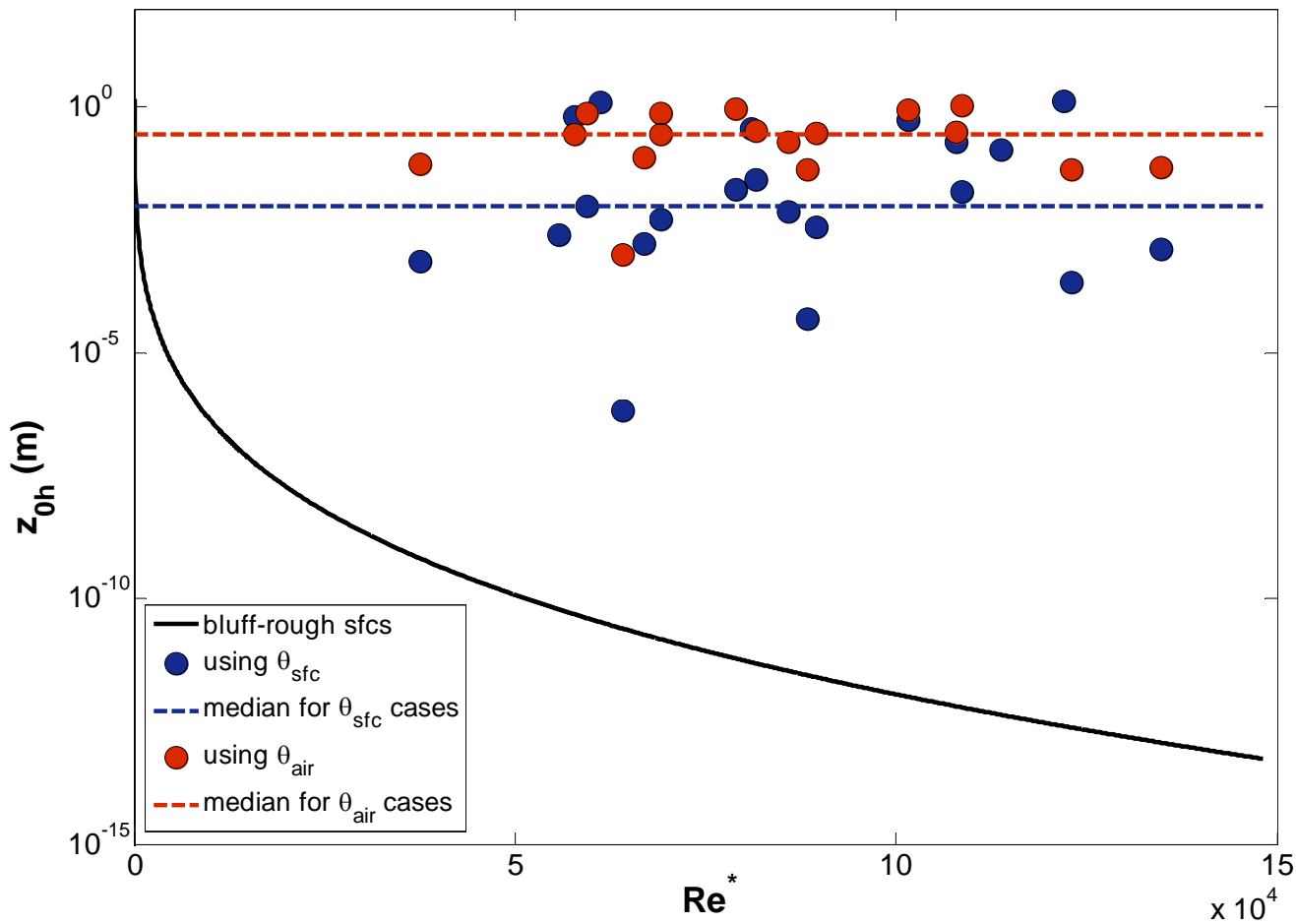
Regression for near-neutral potential temperature profiles

3 Nov. 2006 at 7:30 pm



Thermal Roughness Length

Preliminary results for z_{0h}

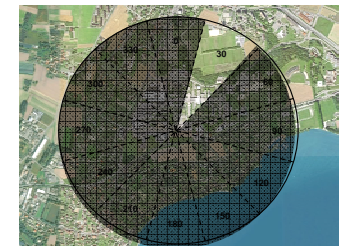


For bluff-rough surfaces

$$z_{0h} = z_0 \exp\left[(-k)(4.31 \text{Re}_*^{0.247} - 5)\right]$$

(Cahill et al., *WRR*, 1997)

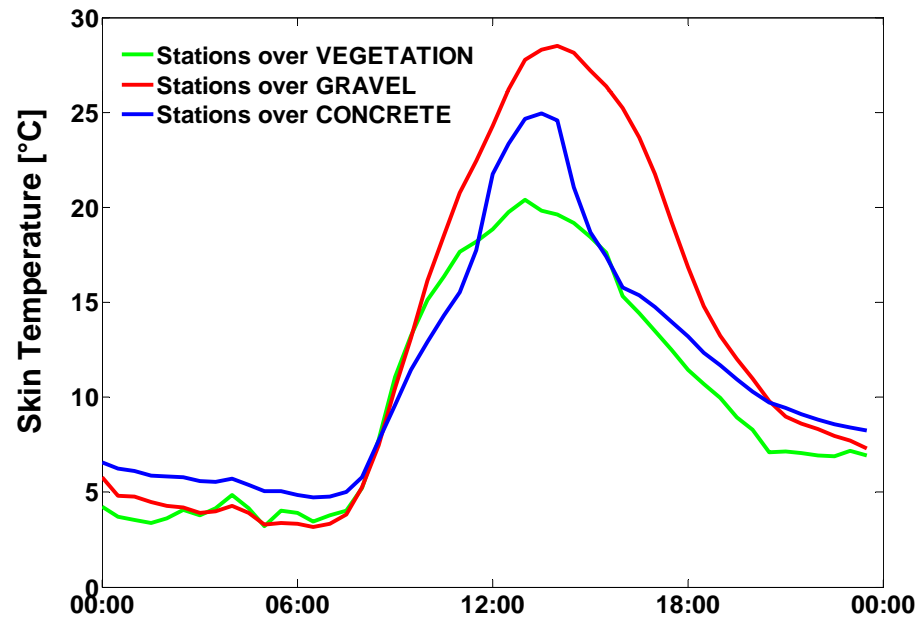
$$\text{Re}_* = \frac{u_* z_0}{\nu}$$



Thermal Roughness Length

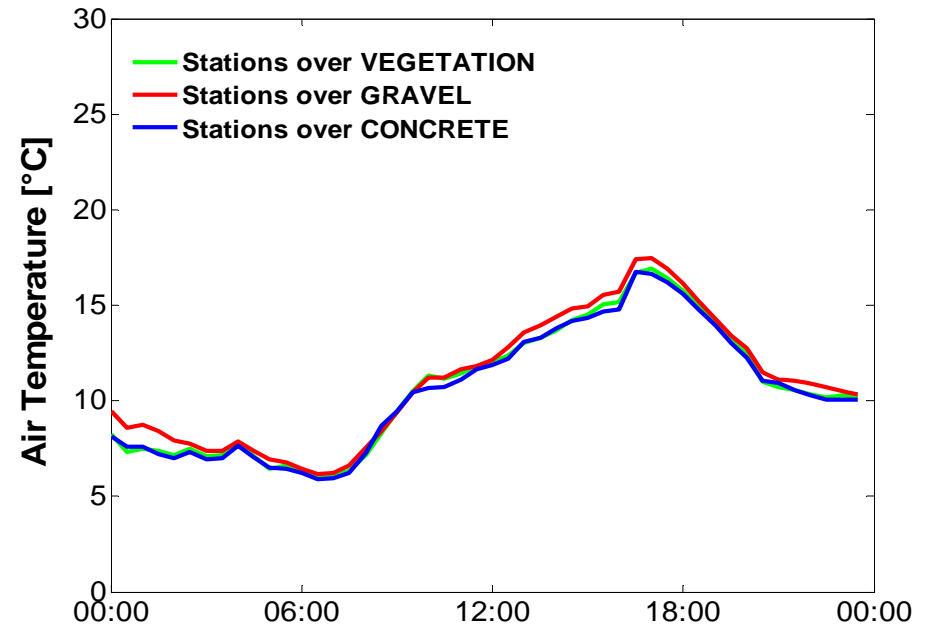
Considering surface type

SKIN TEMPERATURE



14 Mar 2007

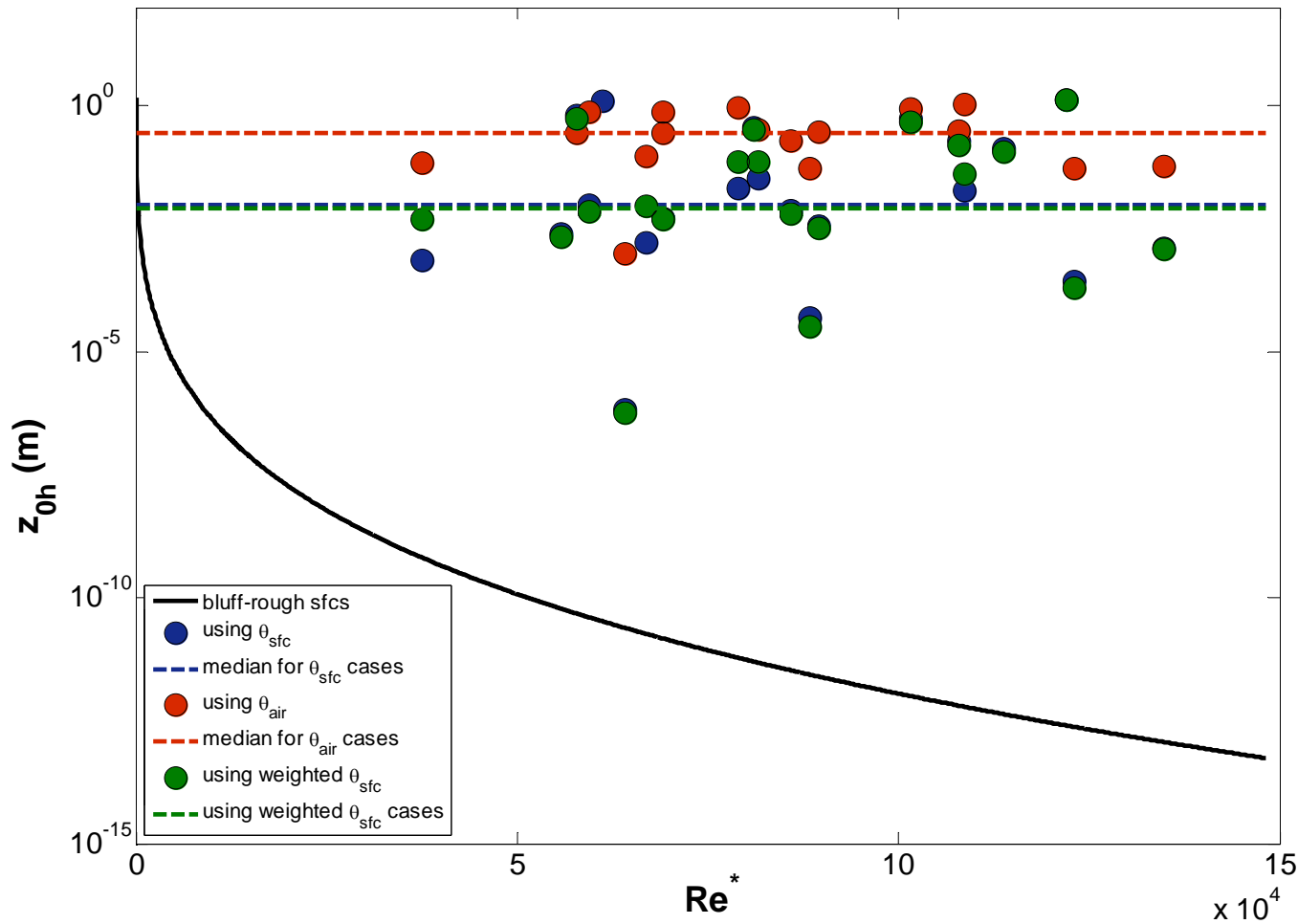
AIR TEMPERATURE



14 Mar 2007

Thermal Roughness Length

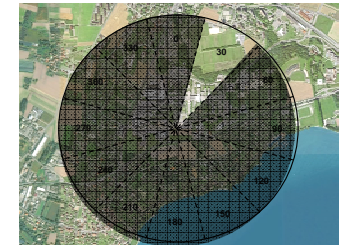
Using a weighted average: $\langle \theta_s \rangle = a\theta_{s,\text{vegetation}} + b\theta_{s,\text{urban}}$



For a 10 km fetch

a : estimated fractional cover of vegetation

b : estimated fractional cover of built-up areas



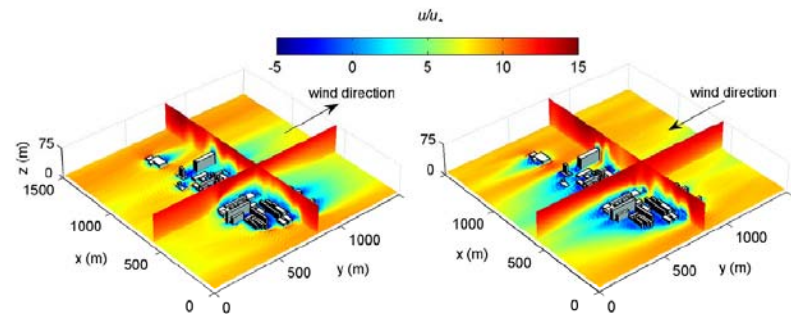
Conclusions and Future Work

Conclusions

- momentum surface roughness obtained by regressing near-neutral profiles
- large values of z_{0h} found (compared to literature): from 10^{-6} to 1 m
- z_{0h} very far from approximation for bluff-rough surfaces

Future work

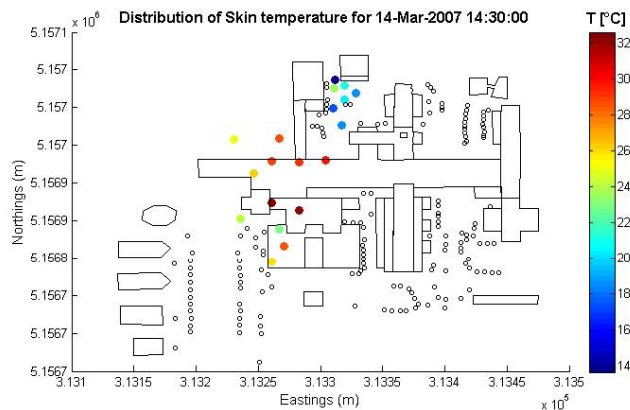
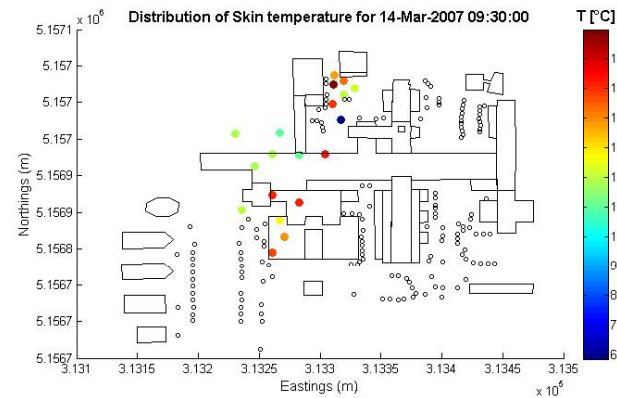
- study convective cases for z_{0h}
- footprint analysis
- compare with morphometric models
- perform LES simulations



Source: E. Ouyang, E. Bou-Zeid, 2007

Future Work

Modeling shaded areas

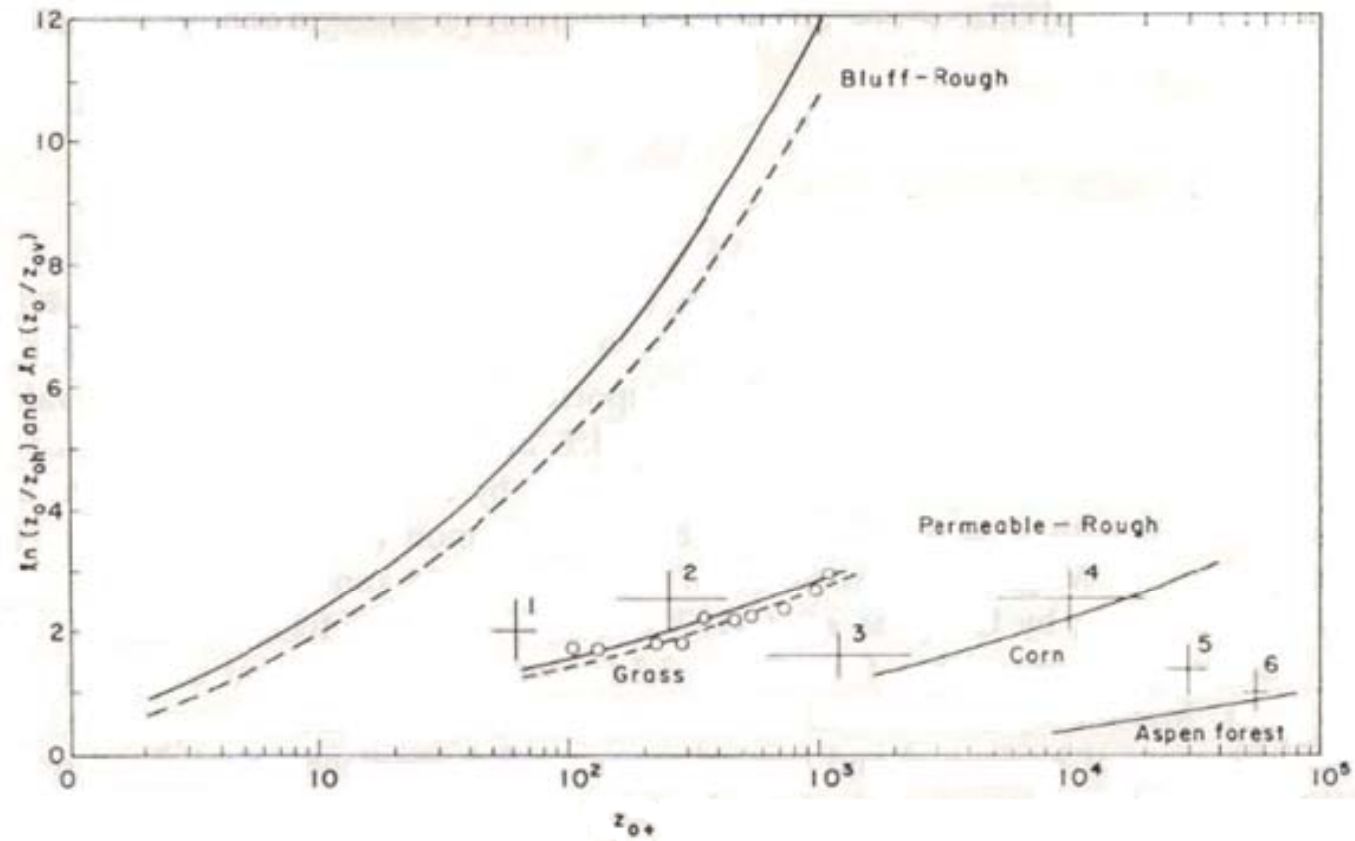


- shaded areas can greatly influence skin temperature and in turn the spatially averaged heat flux (Sun and Mahrt, *BLM*, 1995)
- dependence of z_{0h} on the sun angle (Kustas et al., *AFM*, 1989)
- heat flux dominated by sunlit areas (Voogt and Grimmond, *JAM*, 2000)

Thank you !

Thermal Roughness Length

Dependance of z_0/z_{0h} on the flow



Source: Brutsaert, *Evaporation into the Atmosphere*, 1982

Instruments

SODAR/RASS accuracy

u horizontal: 0.1 - 0.3 m/s

u vertical: 0.03 - 0.1 m/s

wind direction: 2 - 3°

thickness of vertical layers: 5 – 100 m

range: 200 – 500 m

temperature: 0.2 °C

Sensorscope accuracy

surface temperature: 0.6°C

air temperature: 0.3°C



Scintec Flat Array SFAS



Sensorscope station