1	Running head: Route familiarity and visual attention
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8	Familiarity breeds contempt for the road ahead:
9	The real-world effects of route repetition on visual attention in an expert driver
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26

Abstract

27 The majority of journeys by car take place on familiar roads, with many routes being driven 28 time and time again. This familiarity has been linked to mind wandering and reduced attention to specific elements of the visual scene (e.g. speed signs). The current study 29 30 presents on-road eye tracking data from a driving instructor who drove the same route 28 31 times, incorporating two types of suburban roads, dual and multi-lane carriageways, and a country road. Data reveal a significant positive correlation between the number of times the 32 same route is navigated and off-road dwell time across all five road sections. In addition, 33 34 route familiarity was associated with decreasing dwell time on safety-relevant aspects of the road ahead in four out of the five sections. These data suggest that route familiarity can lead 35 to undesirable changes in visual attention on real roads, even for expert drivers under 36 observation. 37

39

1. Introduction

40 While most tests of driving skill or hazard perception involve drivers encountering a novel environment in videos, simulation or the real-world, the majority of the drives we 41 42 complete are on routes with which we are familiar. In the UK, 15.3 million people report that they usually drive to work (ONS, 2013), many of whom presumably drive the same route 43 44 twice a day, five days a week, potentially for many years. Repetition of a task leads to the 45 automatization of its subroutines, with a reduction in conscious attention to the task (Schneider and Shiffrin, 1977). In many cases, this automatization is helpful. Novice drivers 46 47 will eventually benefit from the freeing up of cognitive resources, as activities such as changing gear become automated and these resources can be allocated to other aspects of the 48 49 driving task (e.g. Shinar et al., 1998). However, researchers have argued that the 50 development of such open-loop behaviour can render drivers insensitive to changes in the driving environment (e.g. Charlton and Starkey, 2013; Harms and Brookhuis, 2016), 51 52 potentially leaving them vulnerable to hazards.

53 A deciding factor in whether automation of certain driving sub-routines is beneficial 54 may lie in what the driver chooses to devote their spare attention to. In demanding conditions, 55 as capacity is freed from operational, and perhaps even tactical demands, a driver can pay 56 more attention to strategic problems ahead (e.g. mitigating potential hazards in the road 57 ahead; Pradhan and Crundall, 2017). However, in undemanding conditions, this spare 58 capacity may be redirected to less relevant aspects of the external world in an effort to maintain arousal (e.g. Wilde, 1982), or may even be directed inwards to task-unrelated 59 60 images and thoughts (TUITS; Chapman, Ismail and Underwood, 1999), often called mindwandering (Burdett, Charlton & Starkey, 2016), day dreaming (e.g. Berthié et al., 2015) or 61 driving without awareness mode (DWAM; Kerr, 1991). Crucially for the current study. 62 63 instances of driving without awareness are reported more often in relation to highly familiar

64 roads, as well as under conditions of fatigue (Burdett et al., 2016), as if navigation of whole routes become automated. While this extreme argument for automation is unlikely (Groeger, 65 2000), the evidence that route familiarity reduces awareness is compelling. Given the 66 importance of driving on familiar routes, experimental investigations of repeated-route 67 driving are relatively limited, due to the resources required to familiarise participants with a 68 69 route. However, simulator studies, in which participants drive parts of the same route on a 70 number of occasions, have begun to indicate that there are measurable changes in driving 71 performance as a route becomes well-practiced. Speed and lane variability have been seen to 72 decrease across a number of free-drives (Charlton and Starkey, 2011). These changes might 73 be indicative of better prediction of the physical road layout, meaning that fewer corrections 74 are required, but this could also suggest that the drivers are less sensitive to the vagaries of 75 on-road hazard levels., perhaps suggesting that drivers are less sensitive to the vagaries of on-76 road hazard levels. In a follow-up simulator study Charlton and Starkey (2013) had drivers 77 undertake 20 sessions on the same simulated route and assessed their ability to detect changes across the number of sessions (and compared to a control group). They found that drivers' 78 79 attention for changes in the driving scene (the removal and additional of buildings, the 80 changing of road signs, etc.) diminished with increased route familiarity, suggesting that they 81 were driving without awareness. Certain changes were still detected with high accuracy 82 however, such as the removal of lane markings. Road markings are typically viewed 83 peripherally in order to maintain lane position, and are thus used perhaps more implicitly. The 84 removal of these cues may have thus degraded the otherwise automated task of steering, 85 drawing attention to the absence of lane markings.

The decrease of attention to road-signs with increased route familiarity has been noted by other researchers (e.g. Harms and Brookhuis, 2016), but is this a problem? It is understandable that drivers should pay less attention to a sign that explains a dip in the road

ahead, if they are already expecting the dip and therefore have no need to be warned
(Charlton and Starkey, 2013). Problems arise however when changes to road layout result in
the addition or modification of road signs that may be missed.

92

Even more concerning however is the possibility that route familiarity may influence the way we behave on the road. In a car following task, Yanko and Spalek (2013) found that on the fifth occasion of driving the same route participants followed the lead car more closely, braked more slowly in response to the lead cars' brake lights, and were slower to respond to pedestrians crossing the road, compared to a control group who had driven five different routes.

99 The above studies discuss results that have been obtained through simulated driving. 100 This poses one clear possible confound: Drivers may be more willing to allow their minds to 101 wander in a situation where the threat to their safety is only virtual. While it appears easy to 102 accept that reduced attention to road signs should transfer from simulators to the real world 103 (see Martens and Fox, 2007), are drivers really likely to pay less attention to safety-critical 104 aspects of highly familiar roads when they risk injury or even death?

105 While such on-road studies of familiarity are extremely rare, there is some evidence 106 that speed increases with route-repetition (Colonna, Intini, Berloco and Ranieri, 2016). 107 Without a direct measure of how dangerously the participants were driving however, one 108 could argue that this is a result of the driver better calibrating the demands of the road to their self-perceived skill level (though their participants' choice of speed often exceeded the posted 109 110 limit). A harder finding to argue against is that of Rosenbloom et al., (2007) who observed drivers on both familiar and unfamiliar routes, noting that dangerous behaviours and driving 111 violations increased on the most familiar of roads. It is unclear however what mechanism lies 112 113 behind such increases in risk-taking with familiarity.

114 The current study attempts to bridge the gap between simulator studies of inattention 115 in familiar route driving and studies that suggest on-road behavioural changes. If drivers do become more inattentive on familiar routes on real roads, as suggested by the simulator 116 117 studies, then this may provide one cause of increased danger on familiar routes. The experiment reported here looks at the effect of increasing route familiarity on an expert driver 118 119 (an experienced ADI) on a real-world driving route. Specifically, we expand on recent 120 findings by looking, not just at whether the driver does or does not attend to specific signs or 121 markings, but at how they allocate their visual attention across the driving scene and how this 122 changes with exposure. This is examined across five different driving environments, to 123 establish whether different driving demands may affect how attention changes with 124 familiarity. 125 126 2. Method 127 2.1. Expert driver The same driver was used in all of the drives. To examine the effect of route 128 repetition for a very experienced driver, we recruited a fully-qualified UK Approved Driving 129 130 Instructor. The instructor was female, aged 45 and had been a practicing ADI for 8 years. 131 The instructor was paid £20 for each drive. 132 2.2. Apparatus 133 SMI Eve Tracking Glasses (ETG2), sampling binocularly at 60Hz and used a forward facing camera recording at 60 frames per second. Fixations were automatically overlaid onto 134 135 the recorded video from the forward-facing camera by the eye tracking hardware. Eye

- 136 movements were calibrated using the standard SMI ETG one-point calibration at the start of
- 137 each drive. The driver could turn her head naturally, while eye tracking continued.

- 138 The driver drove in her own vehicle, so that route practice was not confounded with
- 139 practice with the vehicle, as she was already familiar with it.

140 **2.3. Driving route**

- 141 A loop was driven that took around 25 minutes to complete and was a total of 11.6
- 142 miles in length. On each drive the loop was driven in the same direction, from the same
- 143 starting point. Although eye tracking data was recorded throughout, the targeted sections for

144 analysis were five different sections of the route. These are described in Table 1.

145

No.	Name	Length (metres)	Speed Limit (mph)	Description
1	Multi-lane Carriageway	1450	50	Varying between two and four lanes of traffic in the direction of travel. Includes 3 off-ramps and 3 slip-roads.
2	Dual Carriageway	1040	50	Two lanes in the direction of travel, with a central reservation separating oncoming traffic from the instructor's vehicle.
3	Country Road	1250	60	Two way traffic. Hedges and fields to the side of the road.
4	Open Suburban	850	30	Two way traffic. Houses set well back from the pavement, allowing good visibility. No parked vehicles on the road.
5	Closed Suburban	640	20	Two way traffic. Houses set close to pavement. Parked vehicles on the road mean the driver must frequently decide whether to proceed or give-way to oncoming traffic.
17				

146 Table 1. The Five Road Sections Analysed

147

148 **2.4. Procedure**

149 Each experimental session began in a car park on Nottingham Trent University,

150 Clifton campus in Nottingham, UK. As part of a separate experiment, each drive included a

151 different passenger, who also wore eye tracking glasses while occupying the passenger seat 152 throughout the drive. At several points during each drive a simple conversation would be undertaken between the driver and passenger, but the parts of the drive included in this paper 153 included no conversation or interaction with the passenger or experimenter. The 154 experimenter sat in the rear seat of the vehicle and conducted eye tracking calibrations before 155 156 each drive began. The earliest drive started at 10:00 and the latest drive ended at 16:30, 157 meaning that morning and evening rush hours were avoided and all drives took place in full 158 daylight. The driver was asked to drive as normal.

159

160 **2.5. Data Cleaning**

In the first two drives the driver was given on-road directional instructions, whilst she learnt the route. These two drives were excluded from the analysis, as the verbal interaction and need to follow instructions may impact the observed eye movements. In the following drives, the instructor was able to drive the route from memory, without the need for verbal directions. Data from drive 11 had to be discarded due to poor calibration throughout the drive.

167 The length of time taken to drive a road section was calculated in milliseconds, as was the sum of duration of all fixations made within the section. The eve tracking glasses' 168 algorithm does not classify saccades, so 10% of section time was deducted to account for 169 170 saccades. Percent missing data was then calculated as the percentage of the section time, 171 after 10% deduction for saccades. Any section with more than 40% missing data was 172 removed from the analysis. This meant the removal of two drives from the multilane 173 carriageway section and two drives for the dual carriageway section. Included number of 174 drives (n) for each section is shown in table 3.

- 175 In order to establish where the driver was looking in a dynamic visual environment, it
- 176 was necessary to manually code each fixation as belonging to a particular category. Each
- 177 fixation was initially coded by the specific sub-category to which it corresponded. These
- 178 were then grouped into larger categories for analysis, as shown in Table 2.
- 179

180 Table 2. Fixation Coding Categories and Descriptions

In-Car spec spec Mirrors All view Road ahead - near The road head far The ahead of tr Any	evelometer, any other in-car location excluding the rear view mirror) I mirrors in the driver's car (left wing mirror, right wing mirror, rear ew mirror) e road in front of our driver, in the bottom two-thirds of the visible adway ahead (near tarmac, near oncoming vehicles, near vehicles ading in the direction of travel) e road in front of our driver, in the top one-third of the visible roadway ead (far tarmac, far oncoming vehicles, far vehicles heading in direction travel)
Road ahead - near The road head Road ahead - far The ahea of tr Any	e road in front of our driver, in the bottom two-thirds of the visible adway ahead (near tarmac, near oncoming vehicles, near vehicles ading in the direction of travel) e road in front of our driver, in the top one-third of the visible roadway ead (far tarmac, far oncoming vehicles, far vehicles heading in direction
Road ahead - near Road ahead - far Any	adway ahead (near tarmac, near oncoming vehicles, near vehicles ading in the direction of travel) e road in front of our driver, in the top one-third of the visible roadway ead (far tarmac, far oncoming vehicles, far vehicles heading in direction
far ahead - ahea far of tr	ead (far tarmac, far oncoming vehicles, far vehicles heading in direction
-	
	y fixations on a side road or vehicle in a side road, regardless of ection of travel (vehicles with and without priority in side roads oving towards or away from our driver, tarmac on any side road)
Addacent lanes	y lanes that could contain traffic going in the same direction of the ver (adjoining slip roads, other lanes)
hazards at road but	portant locations that were either not on the road, or were on the road t were not other vehicles (parked vehicles at least partially on the road, y pedestrians)
Signage Any	y signs (warning or speed sign, direction or location sign)
	by fixation that could not be attributed to any other category, but was own in the video (off-road left, off-road centre, off-road right)
vide Unclassifiable the	e eye tracking range of the glasses was somewhat wider than that of the leo camera, meaning fixations could sometimes be recorded outside of visible area. These fixations were recorded as unclassifiable and cluded from later analyses.

182 Dwell times were calculated as the sum of all fixation durations in a given category. For example, if two 200ms fixations were made on the mirrors in the country road section of 183 a drive, then the dwell time on mirrors in the country road section would be 400ms for that 184 drive. The total dwell time for a section was then calculated as the sum of the durations of all 185 fixations made while the driver completed that section of the drive. Finally, dwell times in 186 187 each category were then converted to a percent of the total dwell time for a road section, in 188 order to account for variation in time taken to complete a given section across different 189 drives.

Any fixation that fell outside of the area that could be recorded by the video camera built into the goggles could not be allocated to a location and were not included in the analyses. These fixations accounted for 0.9% of the total dwell time across all road sections.

194

3. Results

195 Table 3 shows mean dwell time in each location type as a percentage of total dwell time across the drive section, giving an indication of where the driver typically looked 196 197 overall. In the open suburban road the driver generally spent most time looking off-road 198 (34%), followed by the distant road ahead (31%) and the close road ahead (11%). A similar 199 pattern was observed in the closed suburban road with 34% of dwell falling off-road, but with a much more even split between road near and far ahead (both accumulating 16% of dwell). 200 201 The closed suburban route was also the only route to result in a substantial amount of dwell given to potential road-side hazards. In the dual and multi-lane carriageways, most time was 202 203 spent looking at the road far ahead (37% and 43%, respectively), yet our driver still devoted a considerable amount of dwell off-road (28% and 26%, respectively). Finally, on the country 204 road most dwell time was again devoted off-road (40%) though the far road location also 205 206 commanded a substantial amount of dwell (39%).

207

208 Table 3. Mean (SD) percentage of dwell time in each road section spent fixating each of the

	Mean Percent Dwell Time (SD)							
Fixation Locations	Open Suburban	Closed Suburban	Dual Carriageway	Multilane Carriageway	Country Road			
	n = 25	n = 25	n = 23	n = 23	n = 25			
Road ahead - far	31.07 (11.68)	16.02 (7.49)	36.58 (16.75)	42.61 (16.64)	38.57 (15.81)			
Road ahead - near	11.47 (6.79)	16.28 (5.94)	8.42 (9.00)	3.97 (4.41)	8.76 (12.20)			
Side roads	1.64 (2.48)	3.48 (1.26)	3.20 (2.23)	0.07 (0.27)	0.39 (1.04)			
Adjacent lanes	0.00 (0.00)	0.00 (0.00)	4.62 (3.55)	6.71 (3.24)	0.04 (0.21)			
Potential hazards at road side	1.62 (1.93)	15.28 (5.02)	0.42 (0.95)	0.00 (0.00)	0.41 (1.42)			
Mirrors	11.16 (2.96)	9.53 (2.17)	12.27 (2.97)	12.89 (3.65)	7.68 (2.42)			
Signage	0.89 (1.02)	0.00 (0.00)	1.38 (1.14)	1.66 (1.67)	0.00 (0.00)			
In-Car	7.32 (3.60)	4.18 (2.43)	3.60 (2.35)	5.29 (3.40)	3.28 (1.95)			
Off road	34.25 (11.21)	34.17 (9.56)	28.05 (16.65)	25.58 (13.12)	40.22 (13.43)			

209 possible fixation location categories.

Note: n refers to the number of drives included in the analysis, after removal of drive sections
with poor eye tracking data. Italics denote cells where mean dwell time was below 1%, these
were not analysed further.

213

Data were analysed separately for each of the five different types of road. In each case, correlations were conducted between the drive number and the percent of the dwell time

216 in the road section that was given to a particular scene category. Positive correlations show 217 increasing overt visual attention to particular scene categories as familiarity with the route 218 increases, while negative correlations show decreasing overt visual attention across drives. 219 Any category within a drive section that received an average dwell time of less than 1% was 220 not included in the correlations, as such a small proportion of attentional time typically meant that the location type was not present or very rarely present. For example, there were very 221 222 few potential hazards at the road side (e.g. pedestrians/parked vehicles) on the dual 223 carriageway, the multilane carriageway or the country road. Conversely, the category of 224 'adjacent lanes' was only relevant to dual and multi-lane carriageways. See Table 4 for all 225 correlations between dwell percentage and drive number.

226

Table 4. Correlations between drive number and percent dwell time in each of the 10

228 different fixation locations. Separate correlations are presented for each of the 5 different

229	road	types	that	the	driver	encountere	d.

Fixation Locations	Open Suburban	Closed Suburban	Dual Carriageway	Multilane Carriageway	Country Road
Road ahead - far	279	573**	588**	546**	450*
Road ahead - near	538**	369	274	241	090
Side roads	271	313	282		_
Adjacent lanes		—	.048	.062	_
Potential hazards at road side	115	.008	_	—	_
Mirrors	.219	.197	.131	105	.166
Signage			.127	078	
In-Car	255	.156	.462*	.410	.033
Off road	.691***	.597**	.673**	.686***	.535**

230	Notes: A dash denotes that this fixation location was not included in the correlations due to
231	receiving less than 1% of average dwell time. Bold text highlights significant correlations.
232	* $p < .05$, ** $p < .01$, *** $p < .001$

233

234 As shown in Table 4, significant positive correlations were observed for every road 235 type, with percentage dwell time on non-road relevant areas increasing across drives. On the dual-carriageway section in-car fixations also increased across drives (r(21) = .462, p = .026). 236 Significant negative correlations between drive number and percentage dwell time on 237 238 far road ahead locations were observed on closed suburban (r(23) = -.573, p = .003), dualcarriageway (r(21) = -.588, p = .003), multi-lane carriageway (r(21) = -.561, p = .007) and 239 country road (r(23) = -.450, p = .024) sections, while a significant negative correlation 240 241 between drive number and percentage dwell on near road ahead locations was observed for open-suburban locations (r(23) = -.538, p = .006). 242

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- 244

4. Discussion

Evidence from previous research suggests that route familiarity may reduce attention for important safety-relevant stimuli (e.g. Charlton and Starkey, 2013, Burdett et al., 2016), though the majority of such research has been undertaken in simulators, or has involved selfreport of remembered instances. This study demonstrates that these effects translate to real roads, even with a highly expert driver, which may partly explain why observation studies have identified an increase in dangerous behaviour on familiar roads (e.g. Rosenbloom et al., 2007).

Detailed coding of our expert driver's eye movements across five different types of road revealed a decrease in attention to the road ahead. In four out five road sections, this decrease was noted for gaze on the far roadway. Where was the spare attention reallocated? It

might be plausible to expect gaze to retreat closer to the vehicle, as happens with novice
drivers who are presumably under greater processing demands (e.g. Mourant and Rockwell,
1972). This did not occur however. Indeed, the non-significant tendency was for attention to
the near roadway to also decrease with route familiarity.

Instead, the driver appeared to allocate spare attentional capacity to off-road, safety-259 260 irrelevant aspects of the scene. This increase in off-road attention was observed in all five 261 road types, even on the rural route. This particular section contained very little off-road stimuli of particular salience, with occasional houses separated by hedgerow and fields. 262 263 Nonetheless, our driver found elements within the roadside scenery of sufficient interest to 264 capture overt attention. As the naturalistic nature of the study precluded probe questions to assess driver thoughts, we cannot be sure however that she was actively engaging with off-265 266 road stimuli. It is possible that this increased off-road gaze reflected internal distractions.

267 The lack of relationships between mirror inspections and route familiarity is notable. 268 Often mirror-glances are reported to be one of safety checks that suffer from increased roadway demands (Yang, McDonald and Zheng, 2010). In the current study, mirror glances 269 270 accrued approximately 10% of dwell across all road types. What little variation was found in 271 mirror dwell across the road types suggests that the least demanding road accrued the fewest 272 mirror fixations. The relative uniformity of mirror dwell across road types, along with the 273 insensitivity to route familiarity, suggests that the mirror-checking schema is entrenched. This 274 is understandable with our participant – a driving instructor who must instruct her students in the importance of mirror awareness. Again however we do not know whether the efficacy of 275 276 these mirror checks was impacted by route familiarity, as eye tracking can only tell us what 277 people look at, rather than what they are thinking about.

278 On-road studies do not allow us to manipulate hazards, so we cannot empirically test 279 whether the change in attention with route familiarity is associated with poorer hazard

280 response and reduced safety on the road. Certainly, no events occurred that were classed as 281 hazardous by the experimenters, and the instructor was not involved in any collisions during the experiment. One could argue, therefore, that the decrease in fixation time on the road 282 283 could be attributed to more efficient processing. However, even if processing is more efficient, because the spare capacity was allocated off-road the driver ultimately spends less 284 285 time looking at the road. It seems reasonable to suggest that readiness to respond to the 286 development of hazards relies upon the driver looking at either the road itself, vehicles, pedestrians, signage, or other safety-related features, and that an increase in time spent 287 288 attending to safety-irrelevant stimuli is likely to represent increased risk, as a hazard could 289 begin to develop while the driver is looking off-road.

It was interesting to note that dwell on signage was not particularly related to route familiarity, as would be argued by other researchers (Harms and Brookhuis, 2016, Martens and Fox, 2007). However, it appears that the removal of the first two practice drives of the route may have removed almost all overt attention to road signs. Thus, the drop of dwell on signage is so abrupt that the relationship with route familiarity does not feature in our more longitudinal measure.

296

4.1. Conclusions

The current results demonstrate that roadway familiarity, developed through route repetition over several weeks, appears to shift our driver's overt attention from the road itself (particularly at far locations) to off-road areas of the scene that are irrelevant to driving safety. This may reflect a decrease in arousal due to the repetitive nature of the task, with a concomitant desire to seek out novel stimuli in order to redress the balance. Fixating discrete off-road stimuli may reflect an attempt to maintain engagement with external stimuli and prevent the mind wandering onto internal thoughts, though without probing the thoughts of

the driver, either during the drive (disrupting the natural flow of task), or retrospectively (which depends on whether those fleeting thoughts were laid down in memory), we cannot be sure of this. Whether drivers attempt to influence the choice of an external or internal focus of their mind wandering, and its relationship with eye movements, offers an interesting avenue for future research.

310 While the current results do not link familiarity-related off-road dwell with unsafe 311 driving behaviours, it is plausible to assume that the sudden appearance of a hazard is more 312 problematic if the driver is not looking at the road. It is important to note that these results 313 pertain to only one professional driving instructor, and as such, it is difficult to draw any strong generalised conclusions. Since familiarity-induced degradation of attention to the 314 315 roadway may have much more dangerous implications for the average driver, there is a clear need for further investigation of the effects of familiarity on visual search of the road scene in 316 317 expert, experienced and novice drivers alike.

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