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Abstract

Network science has become increasingly popular over the last several years as people have realized that networks have the ability to represent the relationships or connections between any objects. While some networks are small and easy to gather information from, others can be very large. It can be very difficult and time consuming to map out these large networks if we collect data from all the nodes in the network.

Instead of examining all nodes, we seek to collect data incrementally from a portion of the network at a time to discover the whole network. This discovery occurs by successively placing monitors which can see a local portion of the graph. We then tested all of our algorithms on four different networks. Although there was no one algorithm that did best overall, we were able to see some of the strengths and weaknesses of each on various structures of networks.

Networks

- The primary networks used to test algorithms were:
- Synthetic Networks:
- *Synthetic networks are sets of data made for the purpose of testing algorithms \rightarrow Erdos-Renyi
- a random graph in generated by edges being placed between nodes using probability \rightarrow Barabasi-Albert
- a random graph generated by preferential attachment
- Real Networks [3]:
- \rightarrow Facebook Combined
- a social network from friend's lists on a subset of Facebook
- \rightarrow General Relativity on arXiv
- a collaboration graph where nodes are authors and edges represent co-authorship



A visualization of the General Relativity Collaboration Network from SNAP at Stanford [3]

Algorithm Rules

The Basics:

- All of the Test Algorithms begin with a random start
- Monitors placed have the ability to see:
 - all of the edges adjacent to it
 - all of its neighbor nodes
 - the degrees of all of its neighbor nodes
- Every algorithm places monitors on 50% of the network

Bound Algorithms:

These algorithms were written to provide somewhat of an upper and lower bound for our test algorithms.

• Random Placement Smart (RPS):

- \rightarrow Randomly places monitors on nodes
- \rightarrow No strategy, just random
- \rightarrow Will not place monitor on a node that already has a monitor
- Upper Bound Discovery Nodes/Upper Bound Discovery Edges (UBDn/UBDe):
- \rightarrow Ideal algorithms for nodes and edges respectively
- \rightarrow Under the assumption that we can see the entire network
- \rightarrow Place monitor on node with the highest "fake degree"
- \rightarrow Used to approximate an "upper bound" on our discovery

Network Visualization Project

Brittany Reynolds & Dr. Karl Schmitt Collaborators: Erin Moore & Dr. Ralucca Gera





The following are the 5 different algorithms we created along with a description of what

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 \rightarrow Places monitor on neighbor of current monitor with highest degree \rightarrow If this neighbor already has a monitor, restarts to a seen node in the network with the

 \rightarrow Places monitor on any previously seen node with the highest degree \rightarrow If multiple nodes have the maximum degree, the node that has been seen the least is

 \rightarrow Places monitor on any previously seen node with highest "fake degree"

 \rightarrow The "fake degree" is defined as the degree of the node minus the number of neighbors it has that have already been seen by a previously placed monitor

• High Global Degree Least Seen with Restart (HGD_LSwR)

Fake Degree Discovery w/ Restart (FDD_wR2):

 \rightarrow Same as HGD_LS and FDD respectively except that it has a random restart once two monitors in a row are placed with no additional discovery

	Best Nodes	Best Edges	Best Overall		
nyi	1. FDD_wR 2. FDD	1. FDD 2. HGD_LS	FDD		
Albert	1. FDD 2. FDD_wR	1. FDD 2. HGD_LS	FDD		
(subset)	1. FDD & FDD_wR	1. FDD 2. HGD_LS	FDD		
Relativity	1. FDD_wR 2. RPS	1. FDD_wR 2. HC	FDD_wR		
Algorithms that incorporate in a restart are highlighted					

• Table 1 shows which algorithms perform best on each of the four networks

• When FDD does not perform best, it is due to a restart being necessary

• We do not have an algorithm that runs exceptionally well on General Relativity

• Some algorithms do exclusively better on the synthetic graphs

 \rightarrow These synthetic graphs can be helpful for looking at patterns in graphs, but they might not be the most accurate representations of actual networks.

• Speed up our algorithms so that they can run larger networks efficiently (as all of the

• Create new algorithms that pick monitors by some value other than degree

• Create new algorithms that can run on directed networks in addition to undirected net-

• Run current algorithms on more graphs to see if there are any patterns of algorithms that

[1] Gera, Ralucca. "Network Science Support to the Department of Defense". June 2015.

[2] Newman, M.E.J. Networks: An Introduction. Oxford: Oxford UP, 2010. Print.

[3] Krevl, Andrej and Leskovec, Jure. "Stanford SNAP." Stanford Large Network Dataset

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