# VECTORS AND TRANSFERS IN HEXAGONAL QUASIGROUP 

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#### Abstract

Hexagonal quasigroup is idempotent, medial and semisymmetric quasigroup. In this article we define and study vectors, sum of vectors and transfers. The main result is the theorem on isomorphism between the group of vectors, group of transfers and the Abelian group from the characterization theorem of the hexagonal quasigroups.


## 1. Hexagonal quasigroup

Hexagonal quasigroups are defined in article [3].
Definition 1.1. A quasigroup $(Q, \cdot)$ is called hexagonal if it is idempotent, medial and semisymmetric; i.e. if its elements $a, b, c, d$ satisfy

$$
\begin{aligned}
& a \cdot a=a \\
& (a \cdot b) \cdot(c \cdot d)=(a \cdot c) \cdot(b \cdot d) \\
& a \cdot(b \cdot a)=(a \cdot b) \cdot a=b
\end{aligned}
$$

When it doesn't cause confusion, we can omit the sign ".", e.g. instead of $(a \cdot b) \cdot(c \cdot d)$ we shall write $a b \cdot c d$.

Theorem 1.2. In any hexagonal quasigroup ( $Q, \cdot \cdot$ ) the identities

$$
a \cdot b c=a b \cdot a c \quad a n d \quad a b \cdot c=a c \cdot b c
$$

hold for all $a, b, c \in Q$. The equalities $a b=c, b c=a$ and $c a=b$ are equivalent.
The basic example of a hexagonal quasigroup studied in [3] is the following.

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Example 1.3. The set $\mathbb{C}$ of complex numbers, with the operation $*$ :

$$
a * b=\frac{1-i \sqrt{3}}{2} \cdot a+\frac{1+i \sqrt{3}}{2} \cdot b
$$

is a hexagonal quasigroup.
If we identify complex numbers with the points of the Euclidean plane, the points $a, b$ and $a * b$ turn out to be vertices of positively oriented regular (equilateral) triangle.

Finite hexagonal quasigroups are interesting as well.
Example 1.4. Two quasigroups defined by table 1 are hexagonal. We shall call them $Q_{3}$ and $Q_{4}$.

Table 1. Finite quasigroups $Q_{3}$ and $Q_{4}$

| $\cdot$ | $A$ | $B$ | $C$ |
| :---: | :---: | :---: | :---: |
| $A$ | $A$ | $C$ | $B$ |
| $B$ | $C$ | $B$ | $A$ |
| $C$ | $B$ | $A$ | $C$ |


| $\cdot$ | 1 | 2 | 3 | 4 |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 1 | 3 | 4 | 2 |
| 2 | 4 | 2 | 1 | 3 |
| 3 | 2 | 4 | 3 | 1 |
| 4 | 3 | 1 | 2 | 4 |

The direct product of hexagonal quasigroups is also a hexagonal quasigroup.

Example 1.5. The product of quasigroups $Q_{3}$ and $Q_{4}$.
We shall denote the element $(B, 3) \in Q_{3} \times Q_{4}$ by $B_{3}$, and similarly. Multiplication table in $Q_{3} \times Q_{4}$ is then:

| $\cdot$ | $A_{1}$ | $A_{2}$ | $A_{3}$ | $A_{4}$ | $B_{1}$ | $B_{2}$ | $B_{3}$ | $B_{4}$ | $C_{1}$ | $C_{2}$ | $C_{3}$ | $C_{4}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $A_{1}$ | $A_{1}$ | $A_{3}$ | $A_{4}$ | $A_{2}$ | $C_{1}$ | $C_{3}$ | $C_{4}$ | $C_{2}$ | $B_{1}$ | $B_{3}$ | $B_{4}$ | $B_{2}$ |
| $A_{2}$ | $A_{4}$ | $A_{2}$ | $A_{1}$ | $A_{3}$ | $C_{4}$ | $C_{2}$ | $C_{1}$ | $C_{3}$ | $B_{4}$ | $B_{2}$ | $B_{1}$ | $B_{3}$ |
| $A_{3}$ | $A_{2}$ | $A_{4}$ | $A_{3}$ | $A_{1}$ | $C_{2}$ | $C_{4}$ | $C_{3}$ | $C_{1}$ | $B_{2}$ | $B_{4}$ | $B_{3}$ | $B_{1}$ |
| $A_{4}$ | $A_{3}$ | $A_{1}$ | $A_{2}$ | $A_{4}$ | $C_{3}$ | $C_{1}$ | $C_{2}$ | $C_{4}$ | $B_{3}$ | $B_{1}$ | $B_{2}$ | $B_{4}$ |
| $B_{1}$ | $C_{1}$ | $C_{3}$ | $C_{4}$ | $C_{2}$ | $B_{1}$ | $B_{3}$ | $B_{4}$ | $B_{2}$ | $A_{1}$ | $A_{3}$ | $A_{4}$ | $A_{2}$ |
| $B_{2}$ | $C_{4}$ | $C_{2}$ | $C_{1}$ | $C_{3}$ | $B_{4}$ | $B_{2}$ | $B_{1}$ | $B_{3}$ | $A_{4}$ | $A_{2}$ | $A_{1}$ | $A_{3}$ |
| $B_{3}$ | $C_{2}$ | $C_{4}$ | $C_{3}$ | $C_{1}$ | $B_{2}$ | $B_{4}$ | $B_{3}$ | $B_{1}$ | $A_{2}$ | $A_{4}$ | $A_{3}$ | $A_{1}$ |
| $B_{4}$ | $C_{3}$ | $C_{1}$ | $C_{2}$ | $C_{4}$ | $B_{3}$ | $B_{1}$ | $B_{2}$ | $B_{4}$ | $A_{3}$ | $A_{1}$ | $A_{2}$ | $A_{4}$ |
| $C_{1}$ | $B_{1}$ | $B_{3}$ | $B_{4}$ | $B_{2}$ | $A_{1}$ | $A_{3}$ | $A_{4}$ | $A_{2}$ | $C_{1}$ | $C_{3}$ | $C_{4}$ | $C_{2}$ |
| $C_{2}$ | $B_{4}$ | $B_{2}$ | $B_{1}$ | $B_{3}$ | $A_{4}$ | $A_{2}$ | $A_{1}$ | $A_{3}$ | $C_{4}$ | $C_{2}$ | $C_{1}$ | $C_{3}$ |
| $C_{3}$ | $B_{2}$ | $B_{4}$ | $B_{3}$ | $B_{1}$ | $A_{2}$ | $A_{4}$ | $A_{3}$ | $A_{1}$ | $C_{2}$ | $C_{4}$ | $C_{3}$ | $C_{1}$ |
| $C_{4}$ | $B_{3}$ | $B_{1}$ | $B_{2}$ | $B_{4}$ | $A_{3}$ | $A_{1}$ | $A_{2}$ | $A_{4}$ | $C_{3}$ | $C_{1}$ | $C_{2}$ | $C_{4}$ |

The characterisation theorem of hexagonal quasigroups was proven in [3].

Theorem 1.6. A hexagonal quasigroup $(Q, \cdot)$ exists if and only if an Abelian group $(Q,+)$ and an automorphism $\varphi$ satisfying

$$
\begin{equation*}
(\varphi \circ \varphi)(a)-\varphi(a)+a=0, \quad \forall a \in Q \tag{1.1}
\end{equation*}
$$

exist. Each of the two binary operations + and $\cdot$ is defined by means of the other by the equalities

$$
\begin{gather*}
a \cdot b=a+\varphi(b-a)  \tag{1.2}\\
a+b=0 a \cdot b 0, \tag{1.3}
\end{gather*}
$$

where 0 is the neutral element of the group $(Q,+)$.
In the rest of this article, $Q$ will always be a hexagonal quasigroup.

## 2. GEOMETRY OF HEXAGONAL QUASIGROUP

In [3] and [4] some geometric terms are defined and studied in hexagonal quasigroups, motivated by the quasigroup $(\mathbb{C}, *)$.

The elements of a hexagonal quasigroup are called points. A pair of points is called a segment, and a cyclic triple of points is called a triangle.


Figure 1. $\operatorname{Par}(a, b, c, d)$

Definition 2.1. It is said that the points $a, b, c, d$ form $a$ parallelogram, $i f b c \cdot a b=d$. This is denoted by $\operatorname{Par}(a, b, c, d)$.

Remark 2.2. The relation Par is defined in any medial quasigroup ([2]). According to that definition, in a hexagonal quasigroup $\operatorname{Par}(a, b, c, d)$ holds if $a x \cdot b=d x \cdot c$. It follows

$$
c=(a x \cdot b) \cdot d x=(a b \cdot x b)(d x)=(a b \cdot d)(x b \cdot x)=(a b \cdot d) b
$$

which is equivalent to $b c=a b \cdot d$ or $d=b c \cdot a b$, and is therefore equivalent with our definition. Hence, we may use all the results from [2].

According to [2], ( $Q$, Par) is a parallelogram space, i.e. the following properties hold:

Par1. Any three of the four points $a, b, c, d$ uniquely determine the fourth, such that $\operatorname{Par}(a, b, c, d)$ holds.
Par2. The statements $\operatorname{Par}(a, b, c, d), \quad \operatorname{Par}(b, c, d, a), \quad \operatorname{Par}(c, d, a, b)$, $\operatorname{Par}(d, a, b, c), \quad \operatorname{Par}(c, b, a, d), \quad \operatorname{Par}(b, a, d, c), \quad \operatorname{Par}(a, d, c, b) \quad$ and $\operatorname{Par}(d, c, b, a)$ are equivalent.
Par3. From $\operatorname{Par}(a, b, c, d)$ and $\operatorname{Par}(c, d, e, f)$ it follows $\operatorname{Par}(a, b, f, e)$.
Definition 2.3. A point $m$ is called $a$ midpoint of the segment $\{a, b\}$, if $\operatorname{Par}(a, m, b, m)$ holds. If this is the case, we write $M(a, m, b)$.

Remark 2.4. A midpoint of a segment may not exist, and even when it exists, it may not be unique. E.g. in the hexagonal quasigroup $Q_{3} \times Q_{4}$ from example 1.5 the segment $\left\{A_{1}, B_{2}\right\}$ has no midpoint, while the segment $\left\{A_{1}, B_{1}\right\}$ has four midpoints: $C_{1}, C_{2}, C_{3}$ and $C_{4}$.

However, for any two points $a$ and $m$ there exists unique point $b=a m \cdot m a$ such that $\mathrm{M}(a, m, b)$.

Here we give some more results from [2] we shall need.
Theorem 2.5. From $\operatorname{Par}\left(a_{1}, b_{1}, c_{1}, d_{1}\right)$ and $\operatorname{Par}\left(a_{2}, b_{2}, c_{2}, d_{2}\right)$, it follows $\operatorname{Par}\left(a_{1} a_{2}, b_{1} b_{2}, c_{1} c_{2}, d_{1} d_{2}\right)$.

THEOREM 2.6. If $M(a, m, c)$ holds, the statements $M(b, m, d)$ and $\operatorname{Par}(a, b, c, d)$ are equivalent.

Definition 2.7. The point $m$ is called $a$ center of the parallelogram $\operatorname{Par}(a, b, c, d)$ if $M(a, m, c)$ and $M(b, m, d)$ hold.

REMARK 2.8. Similarly the midpoint of a segment, a parallelogram may have no center, or have more than one center.

Theorem 2.9. From $\operatorname{Par}(a, b, d, e)$ and $\operatorname{Par}(b, c, e, f)$ it follows $\operatorname{Par}(c, d, f, a)$.

## 3. Vectors

Accordingly to [4], the relation $\sim$ defined on $Q \times Q$ by means of

$$
(a, b) \sim(c, d) \Leftrightarrow \operatorname{Par}(a, b, d, c)
$$

is the equivalence relation on $Q \times Q$. The equivalence class containing the pair $(a, b)$ is denoted by $[a, b]$ and is called a vector. The set of all vectors is denoted by $\mathcal{V}$.

It follows immediately
Corollary 3.1. The two vectors $[a, b]$ and $[c, d]$ are equal if and only if $\operatorname{Par}(a, b, d, c)$. For any given $o \in Q$, and any vector $[a, b]$ there exists exactly one $x \in Q$ such that $[o, x]=[a, b]$.

Corollary 3.2. The statement $M(a, m, b)$ is equivalent with the equation $[a, m]=[m, b]$.

Lemma 3.3. If $(x, y),\left(x^{\prime}, y^{\prime}\right) \in[a, b],(y, z),\left(y^{\prime}, z^{\prime}\right) \in[c, d]$ and $(x, z) \in$ $[u, v]$, then $\left(x^{\prime}, z^{\prime}\right) \in[u, v]$.

Proof. From the assumptions, it follows $\operatorname{Par}(x, y, b, a), \operatorname{Par}\left(b, a, x^{\prime}, y^{\prime}\right)$, $\operatorname{Par}(y, z, d, c), \operatorname{Par}\left(d, c, y^{\prime}, z^{\prime}\right)$ and $\operatorname{Par}(x, z, v, u)$. The first two statements, because of the property Par3, imply $\operatorname{Par}\left(x, y, y^{\prime}, x^{\prime}\right)$, and the other two $\operatorname{Par}\left(y, z, z^{\prime}, y^{\prime}\right)$. Therefore $\operatorname{Par}\left(x^{\prime}, x, z, z^{\prime}\right)$ also holds, and now from the last assumption it follows $\operatorname{Par}\left(x^{\prime}, z^{\prime}, v, u\right)$; i.e. $\left(x^{\prime}, z^{\prime}\right) \in[u, v]$.

Definition 3.4. The vector $[u, v]$ is said to be the sum of the vectors $[a, b]$ and $[c, d]$ if $(x, y) \in[a, b]$ and $(y, z) \in[c, d]$ imply $(x, z) \in[u, v]$. If this is the case, we write $[a, b]+[c, d]=[u, v]$.

Theorem 3.5. The set of all vectors $\mathcal{V}$ with the binary operation + is a commutative group.

Proof. First note that $[x, y]+[y, z]=[x, z]$.
We have

$$
\begin{aligned}
& ([x, y]+[y, z])+[z, w]=[x, z]+[z, w]=[x, w], \\
& {[x, y]+([y, z]+[z, w])=[x, y]+[y, w]=[x, w],}
\end{aligned}
$$

hence $([x, y]+[y, z])+[z, w]=[x, y]+([y, z]+[z, w])$, which proves the associativity.

Since $\operatorname{Par}(x, x, y, y),[x, x]=[y, y], \forall x, y$. The vector $[a, a]$ will be denoted 0 . Obviously, $[x, y]+0=[x, y]+[y, y]=[x, y]$ and $0+[x, y]=[x, x]+[x, y]=$ $[x, y]$, i.e. 0 is the neutral element for the operation + .

Since $[x, y]+[y, x]=[x, x]=0$, the inverse of the vector $[x, y]$ is $[y, x]$.
We still need to prove the commutativity; i.e. that: $[a, b]+[c, d]=[c, d]+$ $[a, b]$.

Let $a, b, c$ and $d$ be any points, and let $p$ and $q$ be points such that $[a, b]=[d, p]$ and $[c, d]=[b, q]$; i.e. $\operatorname{Par}(a, b, p, d)$ and $\operatorname{Par}(c, d, q, b)$. From Theorem 2.9 it follows $\operatorname{Par}(q, p, c, a)$; i.e. $[a, q]=[c, p]$.

Finally,

$$
\begin{aligned}
& {[a, b]+[c, d]=[a, b]+[b, q]=[a, q]} \\
& {[c, d]+[a, b]=[c, d]+[d, p]=[c, p]}
\end{aligned}
$$

concludes the proof.
Definition 3.6. We say that the vectors $[a, b],[c, d]$ and $[e, f]$ form a triangle if there exist points $p, q$ and $r$ such that $[p, q]=[a, b],[q, r]=[c, d]$, and $[r, p]=[e, f]$.

Lemma 3.7. Vectors $[a, b],[c, d]$ and $[e, f]$ form a triangle if and only if $[a, b]+[c, d]+[e, f]=0$.

Proof. If the vectors $[a, b],[c, d]$ and $[e, f]$ form a triangle, then there exist $p, q$ and $r$ such that $[p, q]=[a, b],[q, r]=[c, d]$ and $[r, p]=[e, f]$. Then $[a, b]+[c, d]+[e, f]=[p, q]+[q, r]+[r, q]=[p, p]=0$.

Let $[a, b]+[c, d]+[e, f]=0$. Let $p$ be any point, and $q$ and $r$ such that $[p, q]=[a, b]$ and $[q, r]=[c, d]$. Then $[e, f]=-([a, b]+[c, d])=-([p, q]+$ $[q, r])=-[p, r]=[r, p]$.

Theorem 3.8. Vectors $[a, b],[c, d]$ and $[e, f]$ form a triangle if and only if $d e \cdot a d=c f \cdot b c$.

Proof. Let $x$ be any point, and $y, z, x^{\prime}$ points such that $[a, b]=[x, y]$, $[c, d]=[y, z]$ and $[e, f]=\left[z, x^{\prime}\right]$. From $\operatorname{Par}(a, b, y, x)$ and $\operatorname{Par}(d, c, y, z)$ and Theorem 2.5 it follows $\operatorname{Par}(a d, b c, y, x z)$, and from $\operatorname{Par}(c, d, z, y)$ and $\operatorname{Par}\left(f, e, z, x^{\prime}\right)$ it follows $\operatorname{Par}\left(c f, d e, z, y x^{\prime}\right)$. Finally, from $\operatorname{Par}\left(d e, c f, y x^{\prime}, z\right)$ and $\operatorname{Par}(a d, b c, y, x z)$ we obtain $\operatorname{Par}\left(d e \cdot a d, c f \cdot b c, x^{\prime}, x\right)$.

Accordingly to Lemma 3.7 the vectors $[a, b],[c, d]$ and $[e, f]$ form a triangle if and only if $[x, y]+[y, z]+\left[z, x^{\prime}\right]=0$, i.e. if and only if $x=x^{\prime}$, which is equivalent to $d e \cdot a d=c f \cdot b c$.

From this proof (from $\left.\operatorname{Par}\left(d e \cdot a d, c f \cdot b c, x^{\prime}, x\right)\right)$ we obtain:
Corollary 3.9. The sum of the vectors $[a, b],[c, d]$ and $[e, f]$ is a vector [ $\left.x, x^{\prime}\right]$, where

$$
x^{\prime}=(d e \cdot a d)(c f \cdot b c) \cdot x(d e \cdot a d)
$$

Theorem 3.10. Let $a, b, c$ be any points, $a_{1}$ and $c_{1}$ points such that $M\left(b, a_{1}, c\right)$ and $M\left(a, c_{1}, b\right)$ hold, and $b_{1}$ the point for which $\operatorname{Par}\left(a_{1}, b, c_{1}, b_{1}\right)$ hold. Then $M\left(a, b_{1}, c\right)$ and the vectors $\left[a, a_{1}\right],\left[b, b_{1}\right]$ and $\left[c, c_{1}\right]$ form a triangle.

Proof. From $\operatorname{Par}\left(a, c_{1}, b, c_{1}\right)$ and $\operatorname{Par}\left(b, c_{1}, b_{1}, a_{1}\right)$ it follows that $\operatorname{Par}\left(a, c_{1}, a_{1}, b_{1}\right)$, i.e. one has $\left[a, b_{1}\right]=\left[c_{1}, a_{1}\right]$. $\operatorname{From} \operatorname{Par}\left(c, a_{1}, b, a_{1}\right)$ and $\operatorname{Par}\left(b, a_{1}, b_{1}, c_{1}\right)$ it follows $\operatorname{Par}\left(c, a_{1}, c_{1}, b_{1}\right)$, i.e. $\left[c_{1}, a_{1}\right]=\left[b_{1}, c\right]$. Hence $\left[a, b_{1}\right]=\left[b_{1}, c\right]$, i.e. $\mathrm{M}\left(a, b_{1}, c\right)$.

To prove the other part of the statement we need to check that $b_{1} c \cdot a b_{1}=$ $b c_{1} \cdot a_{1} b$.

From $\operatorname{Par}\left(a_{1}, b, c_{1}, b_{1}\right)$ we have $b c_{1} \cdot a_{1} b=b_{1}$, so the righthand side of the upper equation equals $b_{1}$.

From $\mathrm{M}\left(a, b_{1}, c\right)$ it follows

$$
\begin{gathered}
c=a b_{1} \cdot b_{1} a, \quad a b_{1}=b_{1} a \cdot c \\
a=c b_{1} \cdot b_{1} c, \quad b_{1} c=a \cdot c b_{1} \\
b_{1} c \cdot a b_{1}=\left(a \cdot c b_{1}\right)\left(b_{1} a \cdot c\right)=\left(a \cdot b_{1} a\right)\left(c b_{1} \cdot c\right)=b_{1} b_{1}=b_{1}
\end{gathered}
$$

so, the left hand side also equals $b_{1}$.


Figure 2. Theorem 3.10

Remark 3.11. In the quasigroup $(\mathbb{C}, *)$ this theorem proves the known fact that medians of any triangle (as vectors) form a triangle. However the statement: "If $\mathrm{M}\left(b, a_{1}, c\right), \mathrm{M}\left(c, b_{1}, a\right)$ and $\mathrm{M}\left(a, c_{1}, b\right)$, then the vectors $\left[a, a_{1}\right]$, [ $\left.b, b_{1}\right]$ and $\left[c, c_{1}\right]$ form a triangle" is not valid in every hexagonal quasigroup. E.g., in the quasigroup $Q_{3} \times Q_{4}$, for $a=A_{1}, b=B_{1}, c=C_{1}, a_{1}=A_{2}$, $b_{1}=B_{2}$ and $c_{1}=C_{2}$ the assumptions are satisfied, but the sum of the vectors $\left[A_{1}, A_{2}\right],\left[B_{1}, B_{2}\right]$ and $\left[C_{1}, C_{2}\right]$ equals $\left[A_{1}, A_{2}\right] \neq 0$.

Let us prove one more theorem about parallelograms:
Theorem 3.12. $\operatorname{From} \operatorname{Par}\left(a_{1}, b_{1}, a_{2}, c_{1}\right), \operatorname{Par}\left(a_{2}, b_{2}, a_{3}, c_{2}\right), \operatorname{Par}\left(a_{3}, b_{3}, a_{4}\right.$, $\left.c_{3}\right), \operatorname{Par}\left(a_{4}, b_{4}, a_{1}, c_{4}\right)$ and $\operatorname{Par}\left(b_{1}, b_{2}, b_{3}, b_{4}\right)$ it follows $\operatorname{Par}\left(c_{1}, c_{2}, c_{3}, c_{4}\right)$.

Proof. From the definition of the vectors, $\operatorname{Par}(a, b, c, d)$ is equivalent to $[a, b]=[d, c]$. Using the properties of vectors from the assumptions we obtain:

$$
\begin{aligned}
{\left[c_{1}, c_{2}\right] } & =\left[c_{1}, a_{2}\right]+\left[a_{2}, c_{2}\right]=\left[a_{1}, b_{1}\right]+\left[b_{2}, a_{3}\right] \\
& =\left[a_{1}, b_{4}\right]+\left[b_{4}, b_{1}\right]+\left[b_{2}, b_{3}\right]+\left[b_{3}, a_{3}\right]=\left[a_{1}, b_{4}\right]+\left[b_{3}, a_{3}\right] \\
& =\left[c_{4}, a_{4}\right]+\left[a_{4}, c_{3}\right]=\left[c_{4}, c_{3}\right],
\end{aligned}
$$

and finally $\operatorname{Par}\left(c_{1}, c_{2}, c_{3}, c_{4}\right)$.


Figure 3. Theorem 3.12

## 4. Transfers

In the article [1] Lettrich and Perenčaj studied functions $L_{a}(x)=a x$, $R_{a}(x)=x a$ and $T_{a, b}(x)=L_{a b} \circ R_{a}(x)=a b \cdot x a$ in a structure called Rstructure. In our terminology, the R -structure is a hexagonal quasigroup in which no two different elements commute. The geometric meaning of $T_{a, b}$ in the quasigroup $(\mathbb{C}, *)$ is the transfer by vector $[a, b]$. We shall repeat some results from [1], and prove some new for any hexagonal quasigroup.

Definition 4.1. The function $T_{a, b}: Q \rightarrow Q$,

$$
T_{a, b}(x)=a b \cdot x a
$$

is called transfer by the vector $[a, b]$.
We have immediately
Lemma 4.2. For any $a, b, x \in Q$ the statement $\operatorname{Par}\left(x, a, b, T_{a, b}(x)\right)$, and the equation $\left[x, T_{a, b}(x)\right]=[a, b]$ are valid.

THEOREM 4.3. The following statements are equivalent
$1^{\circ} T_{a, b}(x)=T_{c, d}(x)$, for some $x \in Q$
$2^{\circ} T_{a, b}=T_{c, d}$
$3^{\circ} \operatorname{Par}(a, b, d, c)$
$4^{\circ}[a, b]=[c, d]$.
Proof. From the definition of vector, $3^{\circ} \Leftrightarrow 4^{\circ}$. Obviously, from $2^{\circ}$ follows $1^{\circ}$. Let us prove $1^{\circ} \Rightarrow 3^{\circ}$ and $3^{\circ} \Rightarrow 2^{\circ}$.


Figure 4. Transfer by the vector $[a, b]$

Let $1^{\circ}$ hold. Let $y=T_{a, b}(x)=T_{c, d}(x)$. Then $\operatorname{Par}(a, b, y, x)$ and $\operatorname{Par}(c, d, y, x)$ (i.e. $\operatorname{Par}(y, x, c, d))$ and because of the property Par3 it follows $\operatorname{Par}(a, b, c, d)$; i.e. $3^{\circ}$.

Let $3^{\circ}$ hold, i.e. let $\operatorname{Par}(a, b, d, c)$ and let $T_{a, b}(x)=y$. Then $\operatorname{Par}(x, a, b, y)$, i.e. $\operatorname{Par}(y, x, a, b)$. It follows $\operatorname{Par}(y, x, c, d)$ and $T_{c, d}(x)=y$. Hence, $2^{\circ}$ holds.

Corollary 4.4. Let $T$ be a transfer such that $T(a)=b$. Then $T=T_{a, b}$.
Proof. $T_{a, b}(a)=a b \cdot a a=a b \cdot a=b=T(a)$. Because of the implication $1^{\circ} \Rightarrow 2^{\circ}$ from Theorem 4.3 $T_{a, b}=T$.

Corollary 4.5. Transfer with a fixed point is the identity.
Proof. Let $T$ be a transfer, and $x$ point such that $T(x)=x$. From the corollary 4.4 it follows $T=T_{x, x}=$ identity.

Theorem 4.6. For any points $a, b, c$, the equation $T_{b, c} \circ T_{a, b}=T_{a, c}$ holds.
Proof. Let $x \in Q, y=T_{a, b}(x), z=T_{b, c}(y)$. We need to prove $T_{a, c}(x)=z$. Since $\operatorname{Par}(a, b, y, x)$ and $\operatorname{Par}(b, c, z, y)$, it follows $\operatorname{Par}(a, c, z, x)$, i.e. $\operatorname{Par}(x, a, c, z)$, which is, because of Lemma 4.2, equivalent with $z=T_{a, c}(x)$.
$\square$

Corollary 4.7. $\left(T_{a, b}\right)^{-1}$ is $T_{b, a}$.
Proof. From Theorem 4.6 we have $T_{a, b} \circ T_{b, a}=T_{a, a}$, which proves the statement because $T_{a, a}$ is the identity.

Theorem 4.8. The set of all transfers $\mathcal{T}$ with composition $\circ$ as binary operation is a commutative group which acts strictly transitively on the set $Q$.

Proof. Strict transitivity follows from Corollary 4.4.
Accordingly to the above results, $(\mathcal{T}, \circ)$ is a group, so we need only to prove the commutativity.

Let $T_{1}$ and $T_{2}$ be transfers. Let $o$ be any point, and let $a=T_{1}(o)$, $b=T_{2}(a)$ and $c=T_{2}(o)$. From the corollary 4.4 we obtain $T_{1}=T_{o, a}$ and $T_{2}=T_{o, c}$, and also $T_{2}=T_{a, b}$. Now from $T_{a, b}=T_{o, c}$ it follows $\operatorname{Par}(a, b, c, o)$ and $T_{o, a}=T_{c, b}$. Finally,

$$
\begin{aligned}
& T_{2} \circ T_{1}=T_{a, b} \circ T_{o, a}=T_{o, b} \\
& T_{1} \circ T_{2}=T_{o, a} \circ T_{o, c}=T_{c, b} \circ T_{o, c}=T_{o, b} .
\end{aligned}
$$

Theorem 4.9. The groups $(\mathcal{T}, \circ)$ and $(\mathcal{V},+)$ are isomorphic.
Proof. Let $\mathcal{F}: \mathcal{V} \rightarrow \mathcal{T}$ be a function defined by $\mathcal{F}([a, b])=T_{a, b}$. Since

$$
\mathcal{F}([a, b])=\mathcal{F}([c, d]) \Leftrightarrow T_{a, b}=T_{c, d} \Leftrightarrow \operatorname{Par}(a, b, d, c) \Leftrightarrow[a, b]=[c, d]
$$

we conclude that the function $\mathcal{F}$ is well-defined and injective. It is obviously surjective.

Let $o, a, b$ and $c$ be points such that $[o, a]+[o, b]=[o, c]$. Then $[o, a]=$ $[b, c]$, and therefore:

$$
\begin{aligned}
\mathcal{F}([o, a]+[o, b]) & =\mathcal{F}([o, c])=T_{o, c}=T_{b, c} \circ T_{o, b} \\
& =\mathcal{F}([b, c]) \circ \mathcal{F}([o, b])=\mathcal{F}([o, a]) \circ \mathcal{F}([o, b]) .
\end{aligned}
$$

Hence, $\mathcal{F}$ is an isomorphism.
Accordingly to Theorem 1.6, for any hexagonal quasigroup ( $Q, \cdot)$, and any point $o \in Q$, with $a+b=o a \cdot b o$ the structure $(Q,+)$ is a Abelian group, and its automorphism $\varphi(a)=o a$ satisfies (1.1).

Note that $f(a)=[o, a]$ is an isomorphism between groups $(Q,+)$ and $(\mathcal{V},+)$. Indeed, $f$ is bijection because of the property Par1, and

$$
f(a)+f(b)=[o, a]+[o, b]=[o, a+b]=f(a+b),
$$

since the addition in $Q$ is defined so that $\operatorname{Par}(o, a, a+b, b)$.
We have proved:
ThEOREM 4.10. Let $(Q, \cdot)$ be a hexagonal quasigroup, and $(Q,+)$ the Abelian group defined as in theorem 1.6, let $(\mathcal{V},+)$ be the group of vectors, and $(\mathcal{T}, \circ)$ the group of transfers in the quasigroup $(Q, \cdot)$. Then the groups $(\mathcal{V},+),(\mathcal{T}, \circ)$ and $(Q,+)$ are isomorphic.

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