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# Butterflies in the Isotropic Plane

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### ABSTRACT

A real affine plane  $A_2$  is called an isotropic plane  $I_2$ , if in  $A_2$  a metric is induced by an absolute  $\{f, F\}$ , consisting of the line at infinity  $f$  of  $A_2$  and a point  $F \in f$ . In this paper the well-known Butterfly theorem has been adapted for the isotropic plane. For the theorem that we will further-on call an Isotropic butterfly theorem, four proofs are given.

**Key words:** isotropic plane, butterfly theorem

**MSC 2000:** 51N025

## Leptiri u izotropnoj ravnini

### SAŽETAK

Realna afina ravnina  $A_2$  se naziva izotropnom ravninom  $I_2$  ako je metrika u  $A_2$  inducirana apsolutnom figurom  $\{f, F\}$ , koja se sastoji od neizmjereno dalekog pravca  $f$  ravnine  $A_2$  i točke  $F \in f$ . U ovom je radu poznati Leptirov teorem smješten u izotropnu ravninu. Za taj teorem, kojeg od sada nazivamo Izotropnim leptirovim teoremom, dana su četiri dokaza.

**Ključne riječi:** izotropna ravnina, leptirov teorem

## 1 Isotropic Plane

Let  $P_2(\mathbf{R})$  be a real projective plane,  $f$  a real line in  $P_2$ , and  $A_2 = P_2 \setminus f$  the associated affine plane. The *isotropic plane*  $I_2(\mathbf{R})$  is a real affine plane  $A_2$  where the metric is introduced with a real line  $f \subset P_2$  and a real point  $F$  incidental with it. The ordered pair  $\{f, F\}$ ,  $F \in f$  is called *absolute figure* of the isotropic plane  $I_2(\mathbf{R})$  ([3], [5]). In the affine model, where

$$x = x_1/x_0, \quad y = x_2/x_0, \quad (1)$$

the absolute figure is determined by the *absolute line*  $f \equiv x_0 = 0$ , and the *absolute point*  $F (0:0:1)$ . All projective transformations that are keeping the absolute figure fixed form a 5-parametric group

$$G_5 \left\{ \begin{array}{l} \bar{x} = c_1 + c_4x \\ \bar{y} = c_2 + c_3x + c_5y \end{array} \right. , \quad \begin{array}{l} c_1, c_2, c_3, c_4, c_5 \in \mathbf{R} \\ \& \quad c_4c_5 \neq 0. \end{array} \quad (2)$$

We call it *the group of similarities* of isotropic plane.

Defining in  $I_2$  the usual metric quantities such as the distance between two points, the angle between two lines etc., we look for the subgroup of  $G_5$  for those quantities to be invariant. In such a way one obtains the fundamental group of transformations that are the mappings of the form:

$$G_3 \left\{ \begin{array}{l} \bar{x} = c_1 + x \\ \bar{y} = c_2 + c_3x + y \end{array} \right. \quad (3)$$

It is called *the motion group* of isotropic plane. Hence, the group of isotropic motions consists of translations and rotations, that is

$$\left\{ \begin{array}{l} \bar{x} = c_1 + x \\ \bar{y} = c_2 + y \end{array} \right. \quad \text{and} \quad \left\{ \begin{array}{l} \bar{x} = x \\ \bar{y} = c_3x + y \end{array} \right. .$$

In the affine model, rotation is understood as stretching along the y-axis.

## 2 Terms of Elementary Geometry within $I_2$

We will first define some terms and point out some properties of triangles and circles in  $I_2$  that are going to be used further on. The geometry of  $I_2$  could be seen for example in Sachs [3], or Strubecker [5].

### *Isotropic straight line, parallel points, isotropic distance, isotropic span*

All straight lines through the point  $F$  are called *isotropic straight lines* (isotropic lines). All the other straight lines are simply called *straight lines*. Two points  $A, B$  ( $A \neq B$ ) are called *parallel* if they are incidental with the same isotropic line. For two no parallel points  $A(a_1, a_2), B(b_1, b_2)$ , the *isotropic distance* is defined by  $d(A, B) := b_1 - a_1$ . Note that the isotropic distance is directed. For two parallel points  $A(a_1, a_2), B(b_1, b_2)$ ,  $a_1 = b_1$ , the quantity known as *isotropic span* is defined by  $s(A, B) := b_2 - a_2$ . A straight line  $p$  through two points  $A$  and  $B$  will be denoted by  $p \equiv A \vee B$ , or simply  $p \equiv AB$ .

**Invariants of a pair of straight lines**

Each no isotropic straight line  $g \subset I_2$  can be written in the normal form  $y = ux + v$ , that is, in line coordinates,  $g(u, v)$ . For two straight lines  $g_1(u_1, v_1)$ ,  $g_2(u_2, v_2)$  the *isotropic angle* is defined by  $\varphi = \angle(g_1, g_2) := u_2 - u_1$ . Note that the isotropic angle is directed as well. The Euclidean meaning of the isotropic angle can be understood from the affine model that is given in figure 1.

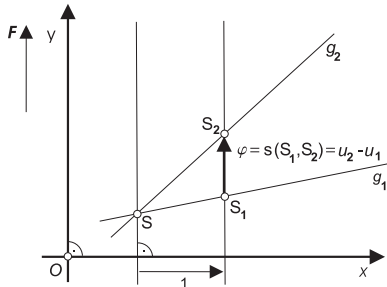


Fig. 1

For two parallel straight lines  $g_1(u_1, v_1)$ ,  $g_2(u_1, v_2)$  there exists an isotropic invariant defined by  $\varphi^*(g_1, g_2) := v_2 - v_1$  (see fig. 2).

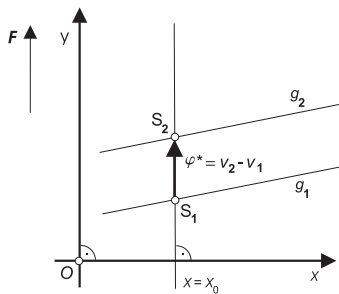


Fig. 2

**Isotropic normal**

An *isotropic normal* to the straight line  $g(u, v)$  in the point  $P(p_1, p_2)$ ,  $P \notin g$  is an isotropic line through  $P$ . Inversely holds as well, i.e. each straight line  $g \subset I_2$  is a normal for each isotropic straight line. Denoting by  $S$  the point of intersection of the isotropic normal in the point  $P$  with the straight line  $g$ , the isotropic distance of the point  $P$  from the line  $g$  is given by  $d(P, g) := s(S, P) = p_2 - s_2 = p_2 - up_1 - v$  (see fig. 3).

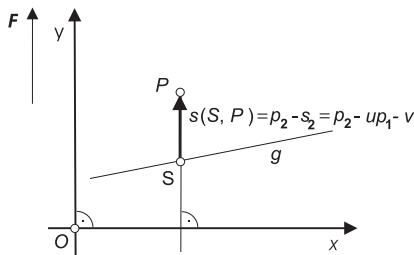


Fig. 3

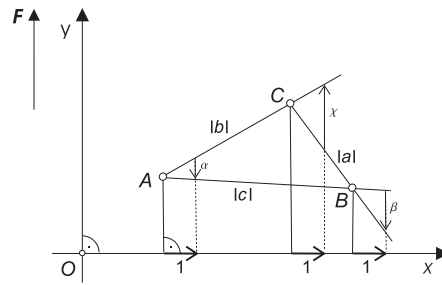


Fig. 4

**Triangles and circles**

Under a *triangle* in  $I_2$  an ordered set of three no collinear points  $\{A, B, C\}$  is understood.  $A, B, C$  are called *vertices*, and  $a := B \vee C$ ,  $b := C \vee A$ ,  $c := A \vee B$  *sides* of a triangle. A triangle is called *allowable* if no one of its sides is isotropic. In a allowable triangle the *lengths* of the sides are defined by  $|a| := d(B, C)$ ,  $|b| := d(C, A)$ ,  $|c| := d(A, B)$ , with  $|a| \neq 0$ ,  $|b| \neq 0$ ,  $|c| \neq 0$ . For the directed angles we have  $\alpha := \angle(b, c) \neq 0$ ,  $\beta := \angle(c, a) \neq 0$ ,  $\gamma := \angle(a, b) \neq 0$  (see figure 4).

*Isotropic altitudes*  $h_a, h_b, h_c$  associated with sides  $a, b$ , and  $c$  are isotropic straight lines passing through the vertices  $A, B, C$ , i.e. normals to the sides  $a, b$ , and  $c$ . Their lengths are defined by  $|h_a| := s(L(A), A)$ , where  $L(A) = a \cap h_a$ , etc. The Euclidian meaning is given in figure 5.

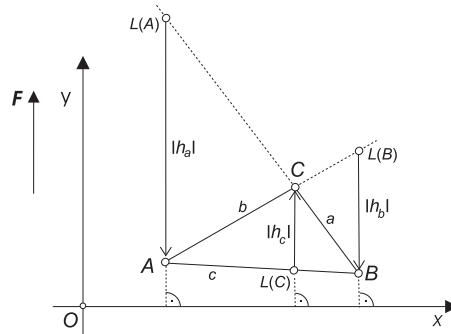


Fig. 5

An *isotropic circle* (*parabolic circle*) is a regular  $2^{nd}$  order curve in  $P_2(\mathbf{R})$  which touches the absolute line  $f$  in the absolute point  $F$ . According to the group  $G_3$  of motions of the isotropic plane there exists in  $I_2$  a three parametric family of isotropic circles, given by  $y = Rx^2 + \alpha x + \beta$ ,  $R \neq 0$ ,  $\alpha, \beta \in \mathbf{R}$ . Using transformations from  $G_3$ , each isotropic circle can be reduced in the normal form  $y = Rx^2$ ,  $R \neq 0$ .  $R$  is a  $G_3$  invariant and it is called the *isotropic radius* of the parabolic circle.

### 3 The Isotropic Butterfly Theorem

**Theorem 1 (Euclidean version)** Let  $M$  be the midpoint of a chord  $PQ$  of the circle, through which two other chords  $AB$  and  $CD$  are drawn;  $AD$  cuts  $PQ$  at  $X$  and  $BC$  cuts  $PQ$  at  $Y$ .  $M$  is also the midpoint of  $XY$ .

This theorem has been proved in a series of books and papers (e.g. [1], [2], [4]).

**Theorem 2 (Isotropic version)** Let  $M$  be the midpoint of a chord  $\overrightarrow{PQ}$  of the parabolic circle, through which two other chords  $\overrightarrow{AB}$  and  $\overrightarrow{CD}$  are drawn;  $\overrightarrow{AD}$  cuts  $\overrightarrow{PQ}$  at  $X$  and  $\overrightarrow{BC}$  cuts  $\overrightarrow{PQ}$  at  $Y$ .  $M$  is also the midpoint of  $\overrightarrow{XY}$ .

**Proof 1**

The point coordinates are:  $P(p_1, p_2)$ ,  $Q(q_1, q_2)$ ,  $M(m_1, m_2)$ ,  $X(x_1, x_2)$ ,  $Y(y_1, y_2)$ , with  $p_1 \neq q_1$ , since  $\overrightarrow{PQ}$  is a chord and as such a no isotropic line, wherefrom we derive that  $x_1 \neq y_1 \neq m_1$  must be fulfilled as well. Let us drop perpendiculars  $h_1, h_2$  from  $X$ , and  $g_1, g_2$  from  $Y$  on  $AB$  and  $CD$ . Let's also denote

$$\begin{aligned} d(P, M) = d(M, Q) &= |s|, \\ d(X, M) = |x|, \quad d(M, Y) &= |y|, \end{aligned} \tag{4}$$

$$\begin{aligned} H_1 = h_1 \cap AM, \quad H_2 = h_2 \cap DM, \\ G_1 = g_1 \cap MB, \quad G_2 = g_2 \cap MC. \end{aligned} \tag{5}$$

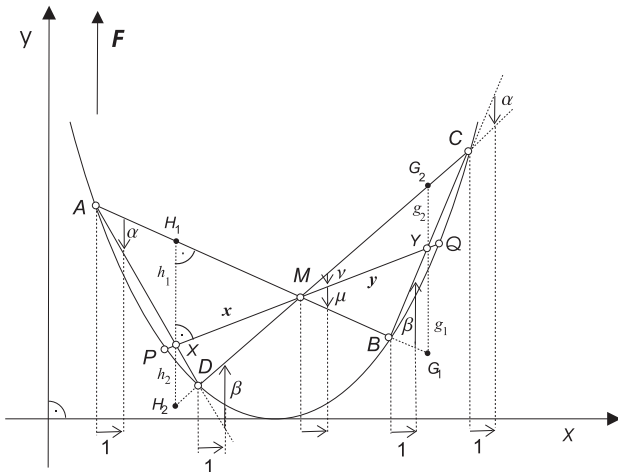


Fig. 6: The Isotropic butterfly theorem in the affine model

As first we need the following:

**Lemma 1** Let  $P, Q, P \neq Q$ , be two points on a parabolic circle  $k$ , and  $A \neq P, A \neq Q$ , any other point on the same circle  $k$ . The isotropic angle  $\varphi = \angle(\overrightarrow{PA}, \overrightarrow{QA})$  does not depend on the position of point  $A$ .

The proof is given in [3, p. 32].

**Lemma 2** The relations

$$\frac{|a|}{\alpha} = \frac{|b|}{\beta} = \frac{|c|}{\chi}, \quad |h_a| = |c|\beta, \quad |h_b| = |a|\chi, \quad |h_c| = |b|\alpha$$

hold for every allowable triangle.

The proof is given in [3, p. 28].

**Lemma 3** Let  $k$  be a parabolic circle in  $I_2$ , a point  $P \in I_2, P \notin k$ , and  $S_1, S_2$  two points of intersection of a no isotropic straight line  $g$  through  $P$  with  $k$ . The product  $f(P) := d(P, S_1) \cdot d(P, S_2)$  doesn't depend of the line  $g$ , but only of  $k$  and  $P$ .

The proof is given in [3, p. 38].

Let's now continue the proof of the isotropic Butterfly theorem.

According to lemma 1,

$$\alpha = \angle(\overrightarrow{AB}, \overrightarrow{AD}) = \alpha' = \angle(\overrightarrow{CB}, \overrightarrow{CD}),$$

and

$$\beta = \angle(\overrightarrow{DA}, \overrightarrow{DC}) = \beta' = \angle(\overrightarrow{BA}, \overrightarrow{BC}). \tag{6}$$

We will also need

$$\mu = \angle(\overrightarrow{XM}, \overrightarrow{MA}) = \mu' = \angle(\overrightarrow{YM}, \overrightarrow{MB}),$$

and

$$\nu = \angle(\overrightarrow{DM}, \overrightarrow{MX}) = \nu' = \angle(\overrightarrow{CM}, \overrightarrow{MY}). \tag{7}$$

Let's apply furthermore lemma 2 on the following pairs of allowable triangles:

1st)  $\triangle AXM$  &  $\triangle MBY$ ,    2nd)  $\triangle XDM$  &  $\triangle MYC$ ,

3rd)  $\triangle AXM$  &  $\triangle MYC$ ,    4th)  $\triangle XDM$  &  $\triangle MBY$ ,

marking sides, angles and altitudes as given in figure 7.

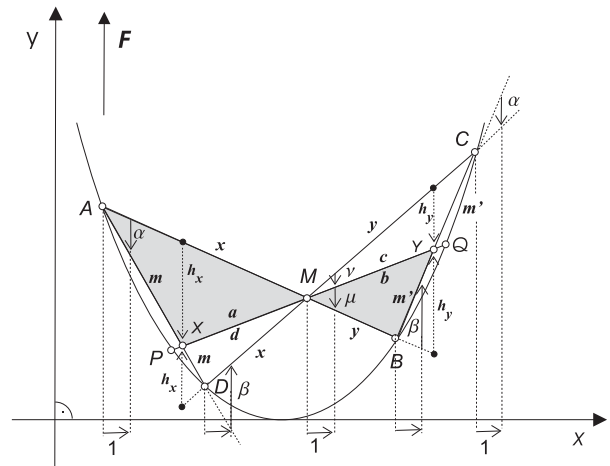


Fig. 7

$$\begin{aligned}
 \text{1st) } \triangle AXM &\Rightarrow \frac{|x|}{\angle(\overrightarrow{AX}, \overrightarrow{XM})} = \frac{|a|}{\alpha} = \frac{|m|}{\mu}, \\
 |h_x| &= |a| \cdot \mu; \\
 \triangle MBY &\Rightarrow \frac{|y|}{\angle(\overrightarrow{BY}, \overrightarrow{YM})} = \frac{|m'|}{\mu} = \frac{|b|}{\beta}, \\
 |h_y| &= |b| \cdot \mu;
 \end{aligned}$$

$\Rightarrow \frac{|h_x|}{|h_y|} = \frac{|a|}{|b|}$ , and using marks from fig. 6 we get

$$\frac{|x|}{|y|} = \frac{|h_1|}{|g_1|}. \tag{8}$$

$$\begin{aligned}
 \text{2nd) } \triangle XDM &\Rightarrow \frac{|x|}{\angle(\overrightarrow{MX}, \overrightarrow{XD})} = \frac{|d|}{\beta} = \frac{|m|}{\nu}, \\
 |h_y| &= |m| \cdot \beta = |d| \cdot \nu; \\
 \triangle MYC &\Rightarrow \frac{|y|}{\angle(\overrightarrow{MY}, \overrightarrow{YC})} = \frac{|c|}{\alpha} = \frac{|m'|}{\nu}, \\
 |h_y| &= |m'| \cdot \alpha = |c| \cdot \nu;
 \end{aligned}$$

$\Rightarrow \frac{|h_x|}{|h_y|} = \frac{|d|}{|c|}$ , and using marks from fig. 6 we have

$$\frac{|x|}{|y|} = \frac{|h_2|}{|g_2|}. \tag{9}$$

Analogously, for the third pair of triangles we get

$$\frac{|h_1|}{|g_2|} = \frac{d(A, X)}{d(Y, C)}. \tag{10}$$

Finally, for the fourth pair of triangles we have

$$\frac{|h_2|}{|g_1|} = \frac{d(X, D)}{d(B, Y)}. \tag{11}$$

From (4), (8), (9), (10), (11), and lemma 3 one computes

$$\begin{aligned}
 \frac{|x|^2}{|y|^2} &= \frac{|h_1|}{|g_1|} \cdot \frac{|h_2|}{|g_2|} = \frac{|h_1|}{|g_2|} \cdot \frac{|h_2|}{|g_1|} = \\
 &= \frac{d(A, X)}{d(Y, C)} \cdot \frac{d(X, D)}{d(B, Y)} = \frac{-d(X, A) \cdot d(X, D)}{-d(Y, C) \cdot d(Y, B)} = \\
 &= \frac{d(X, P) \cdot d(X, Q)}{d(Y, P) \cdot d(Y, Q)} = \frac{(p_1 - x_1)(q_1 - x_1)}{(p_1 - y_1)(q_1 - y_1)} = \\
 &= \frac{(p_1 - m_1 + m_1 - x_1)(q_1 - m_1 + m_1 - x_1)}{(p_1 - m_1 + m_1 - y_1)(q_1 - m_1 + m_1 - y_1)} = \\
 &= \frac{-(|s| - |x|)(|s| + |x|)}{-(|s| + |y|)(|s| - |y|)} = \frac{|s|^2 - |x|^2}{|s|^2 - |y|^2}. \tag{12}
 \end{aligned}$$

$$\frac{|x|^2}{|y|^2} = \frac{|s|^2 - |x|^2}{|s|^2 - |y|^2} \Rightarrow |x|^2 = |y|^2 \Rightarrow |x| = \pm |y|$$

The solution  $|x| = -|y| \Rightarrow d(X, M) = -d(M, Y) = d(Y, M)$ , wherefrom it follows that points X and Y are parallel points, which has been excluded earlier. So,  $|x| = |y| \Rightarrow d(X, M) = d(M, Y)$ .  $\square$

**Proof 2**

Let's use the notation given in (4), that is,  $d(P, M) = d(M, Q) = |s|$ ,  $d(X, M) = |x|$ ,  $d(M, Y) = |y|$ , as well as (6) and (7) for the observed angles.

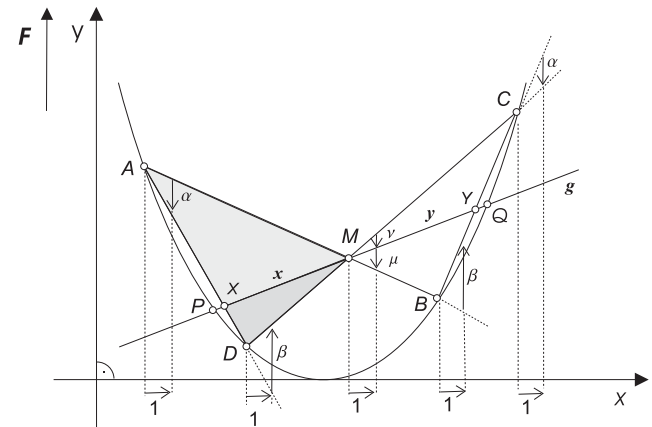


Fig. 8

From lemma 3, as shown in (12), we have

$$d(X, A) \cdot d(X, D) = d(X, P) \cdot d(X, Q),$$

$$d(X, P) \cdot d(X, Q) = -(|s| - |x|)(|s| + |x|) = |x|^2 - |s|^2. \tag{13}$$

Lemma 2 applied on the allowable triangles  $\triangle DMX$  and  $\triangle AXM$  yields

$$\begin{aligned}
 \triangle DMX &\Rightarrow \frac{d(X, D)}{\nu} = \frac{d(D, M)}{\angle(\overrightarrow{MX}, \overrightarrow{XD})} = \frac{d(M, X)}{\beta} \\
 &\Rightarrow \frac{d(X, D)}{\nu} = \frac{d(M, X)}{\beta} \tag{14}
 \end{aligned}$$

$$\begin{aligned}
 \triangle AXM &\Rightarrow \frac{d(A, X)}{\mu} = \frac{d(X, M)}{\alpha} = \frac{d(M, A)}{\angle(\overrightarrow{AX}, \overrightarrow{XM})} \\
 &\Rightarrow \frac{d(A, X)}{\mu} = \frac{d(X, M)}{\alpha}. \tag{15}
 \end{aligned}$$

**Lemma 4** *The sum of the directed sides of an allowable triangle in  $I_2$  equals zero; the sum of the directed angles of an allowable triangle in  $I_2$  equals zero as well.*

The proof is given in [3, p. 22].

For the allowable triangle  $\triangle ADM$ , from lemma 4,

$$v + \mu + \alpha + \beta = 0 \Rightarrow \beta = -(v + \mu + \alpha). \quad (16)$$

Using (13)-(16) together, we obtain

$$d(X,A) \cdot d(X,D) = -d(X,M) \cdot \frac{\mu}{\alpha} \cdot d(M,X) \cdot \frac{v}{\beta} =$$

$$= |x|^2 \frac{v\mu}{-\alpha(v + \mu + \alpha)} = |x|^2 - |s|^2$$

$$\Rightarrow |x|^2 \left( 1 + \frac{v\mu}{\alpha(v + \mu + \alpha)} \right) = |s|^2$$

$$\Rightarrow |x|^2 = \frac{|s|^2 [\alpha(v + \mu + \alpha)]}{v\mu + \alpha(v + \mu + \alpha)}. \quad (17)$$

Following the same procedure ((13)-(16)) for the segment  $|y| = d(M,Y)$ , due to the symmetry in  $v$  and  $\mu$  in the latter expression, we'll get exactly same result. So,  $|x|^2 = |y|^2$ , that is  $|x| = \pm |y|$ , and following the conclusion from proof 1,  $|x| = |y| \Rightarrow d(X,M) = d(M,Y)$ .  $\square$

**Proof 3**

The proof is based on the following:

**Lemma 5** *If in two allowable triangles in  $I_2$  a directed angle of one is equal to a directed angle of the other, then the areas of the triangles are in the same ratio as the products of the sides composing the equal angles.*

**Proof** According [3, p. 26] the isotropic area of an allowable triangle  $ABC$ ,  $A(a_1, a_2)$ ,  $B(b_1, b_2)$ , and  $C(c_1, c_2)$  is given by

$$F_{ABC} = \frac{1}{2} \begin{vmatrix} 1 & 1 & 1 \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix}.$$

Let's mark the directed angles as given before in (6) and (7) (see figure 6), and let's observe the allowable triangles  $AXM$  and  $MYC$  (figure 9).

Lemma 1 yields that  $\alpha = \angle(\vec{MA}, \vec{AX}) = \alpha' = \angle(\vec{YC}, \vec{CM})$ , hence, we have to proof the equality:

$$\frac{F_{AXM}}{F_{MYC}} = \frac{d(M,A) \cdot d(A,X)}{d(Y,C) \cdot d(C,M)}. \quad (18)$$

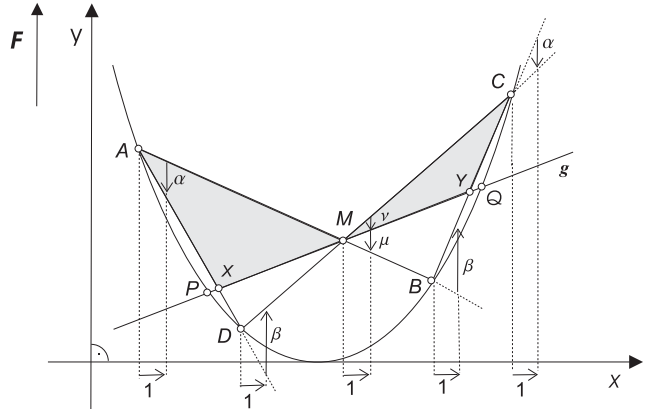


Fig. 9

For the points  $A(a_1, a_2)$ ,  $C(c_1, c_2)$ ,  $M(m_1, m_2)$ ,  $X(x_1, x_2)$  and  $Y(y_1, y_2)$ , the isotropic areas of the triangles are given by

$$F_{AXM} = \frac{1}{2} \begin{vmatrix} 1 & 1 & 1 \\ a_1 & x_1 & m_1 \\ a_2 & x_2 & m_2 \end{vmatrix},$$

and

$$F_{MYC} = \frac{1}{2} \begin{vmatrix} 1 & 1 & 1 \\ m_1 & y_1 & c_1 \\ m_2 & y_2 & c_2 \end{vmatrix}.$$

The sides composing the equal angles are  $d(M,A) = (a_1 - m_1)$ ,  $d(A,X) = (x_1 - a_1)$ ,  $d(Y,C) = (c_1 - y_1)$ , and  $d(C,M) = (m_1 - c_1)$ . For the directed angles  $\alpha$  and  $\alpha'$  we have

$$\alpha = \angle(\vec{MA}, \vec{AX}) = \frac{x_2 - a_2}{x_1 - a_1} - \frac{a_2 - m_2}{a_1 - m_1}$$

$$\alpha' = \angle(\vec{YC}, \vec{CM}) = \frac{m_2 - c_2}{m_1 - c_1} - \frac{c_2 - y_2}{c_1 - y_1}$$

$$\begin{aligned} \alpha = \alpha' &\Rightarrow \frac{x_2 - a_2}{x_1 - a_1} - \frac{a_2 - m_2}{a_1 - m_1} = \frac{m_2 - c_2}{m_1 - c_1} - \frac{c_2 - y_2}{c_1 - y_1} \\ &\Rightarrow \frac{x_1 m_2 - x_2 m_1 - a_1 m_2 + a_2 m_1 + a_1 x_2 - a_2 x_1}{y_1 c_2 - y_2 c_1 - m_1 c_2 + m_2 c_1 + m_1 y_2 - m_2 y_1} = \\ &= \frac{a_1 x_1 - x_1 m_1 + m_1 a_1 - a_1^2}{m_1 c_1 - m_1 y_1 + c_1 y_1 - c_1^2}. \end{aligned}$$

The latter equation can be reach writing extensively equation (18).  $\square$

Let's apply now lemma 5 on the following pairs of allowable triangles:

$\triangle MAX$  and  $\triangle YCM \Rightarrow$

$$\frac{F_{MAX}}{F_{YCM}} = \frac{d(M,A) \cdot d(A,X)}{d(Y,C) \cdot d(C,M)}, \quad (19)$$

$\triangle CMY$  and  $\triangle DMX \Rightarrow$

$$\frac{F_{CMY}}{F_{DMX}} = \frac{d(C,M) \cdot d(M,Y)}{d(D,M) \cdot d(M,X)}, \quad (20)$$

$\triangle XDM$  and  $\triangle MBY \Rightarrow$

$$\frac{F_{XDM}}{F_{MBY}} = \frac{d(X,D) \cdot d(D,M)}{d(M,B) \cdot d(B,Y)}, \quad (21)$$

$\triangle YMB$  and  $\triangle XMA \Rightarrow$

$$\frac{F_{YMB}}{F_{XMA}} = \frac{d(Y,M) \cdot d(M,B)}{d(X,M) \cdot d(M,A)}. \quad (22)$$

$$(19) \cdot (20) \cdot (21) \cdot (22) = \frac{F_{MAX}}{F_{YCM}} \cdot \frac{F_{CMY}}{F_{DMX}} \cdot \frac{F_{XDM}}{F_{MBY}} \cdot \frac{F_{YMB}}{F_{XMA}} = 1$$

$$\begin{aligned} &\Rightarrow \frac{d(A,X) \cdot d(M,Y)}{d(Y,C) \cdot d(M,X)} \cdot \frac{d(X,D) \cdot d(Y,M)}{d(B,Y) \cdot d(X,M)} = 1 \\ &\Rightarrow \frac{d(A,X) \cdot d(X,D)}{d(B,Y) \cdot d(Y,C)} = \frac{d(M,X) \cdot d(X,M)}{d(M,Y) \cdot d(Y,M)}. \quad (23) \end{aligned}$$

According lemma 3, and using the notation given in (4), we have

$$d(A,X) \cdot d(X,D) = d(P,X) \cdot d(X,Q) = |s|^2 - |x|^2, \quad (24)$$

and

$$d(B,Y) \cdot d(Y,C) = d(P,Y) \cdot d(Y,Q) = |s|^2 - |y|^2. \quad (25)$$

Inserting (24) and (25) in (23) we obtain

$$\frac{|s|^2 - |x|^2}{|s|^2 - |y|^2} = \frac{-|x|^2}{-|y|^2} \Rightarrow |x|^2 = |y|^2 \Rightarrow |x| = \pm |y|,$$

and finally, as it has been shown before,

$$|x| = |y| \Rightarrow d(X,M) = d(M,Y). \square$$

**Proof 4**

Let  $k$  be a parabolic circle in  $I_2$ , and let  $M$  be the midpoint of the chord  $\overrightarrow{PQ}$  of  $k$ . Let's choose the coordinate system as shown (in the affine model) in figure 10, i.e, the tangent on the circle  $k$  parallel to the chord  $\overrightarrow{PQ}$  as the  $x$ -axis, and the isotropic straight line through  $M$  as the  $y$ -axis.

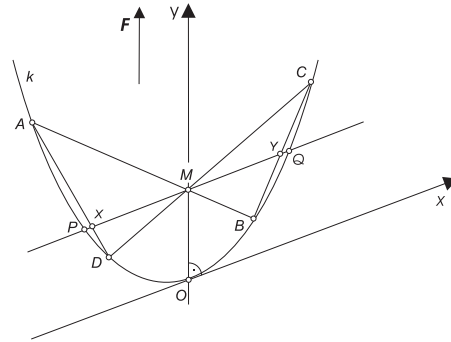


Fig. 10

Let  $A(a_1, Ra_1^2)$ ,  $B(b_1, Rb_1^2)$ ,  $A \neq B \Rightarrow a_1 \neq b_1$ , and  $C(c_1, Rc_1^2)$ ,  $D(d_1, Rd_1^2)$ ,  $C \neq D \Rightarrow c_1 \neq d_1$ , be four points on the parabolic circle  $k$ . Choosing  $M(0, m)$ , for the chord  $\overrightarrow{PQ}$  we have  $\overrightarrow{PQ} \equiv y = m$ . Besides, for  $\overrightarrow{AB}$  being a chord through  $M$ , the following relations are obtained:

$M, A, B$  collinear points  $\Leftrightarrow$

$$\begin{vmatrix} 0 & m & 1 \\ a_1 & Ra_1^2 & 1 \\ b_1 & Rb_1^2 & 1 \end{vmatrix} = 0 \Leftrightarrow a_1 b_1 = -\frac{m}{R}. \quad (26)$$

Analogously, for  $\overrightarrow{CD}$  being a chord through  $M$ , we have:

$M, C, D$  collinear points  $\Leftrightarrow$

$$\begin{vmatrix} 0 & m & 1 \\ c_1 & Rc_1^2 & 1 \\ d_1 & Rd_1^2 & 1 \end{vmatrix} = 0 \Leftrightarrow c_1 d_1 = -\frac{m}{R}. \quad (27)$$

Let's denote further on  $X(x_1, m)$  and  $Y(y_1, m)$ .

One obtains the following:

$A, D, X$  collinear points  $\Leftrightarrow$

$$\begin{vmatrix} x_1 & m & 1 \\ a_1 & Ra_1^2 & 1 \\ d_1 & Rd_1^2 & 1 \end{vmatrix} = 0 \Leftrightarrow Rx_1(a_1 + d_1) = m + Ra_1 d_1. \quad (28)$$

$C, B, Y$  collinear points  $\Leftrightarrow$

$$\begin{vmatrix} y_1 & m & 1 \\ b_1 & Rb_1^2 & 1 \\ c_1 & Rc_1^2 & 1 \end{vmatrix} = 0 \Leftrightarrow Ry_1(b_1 + c_1) = m + Rb_1 c_1. \quad (29)$$

Finally, using (26), (27), (28), and (29) it follows:

$$\begin{aligned} x_1 + y_1 &= \frac{m + Ra_1d_1}{R(a_1 + d_1)} + \frac{m + Rb_1c_1}{R(b_1 + c_1)} = \\ &= \frac{(m + Ra_1d_1)(b_1 + c_1) + (m + Rb_1c_1)(a_1 + d_1)}{R(a_1 + d_1)(b_1 + c_1)} = \\ &= \frac{R(a_1b_1d_1 + a_1c_1d_1 + a_1b_1c_1 + b_1c_1d_1) + m(a_1 + b_1 + c_1 + d_1)}{R(a_1 + d_1)(b_1 + c_1)} = \\ &= \frac{R(-\frac{m}{R}d_1 - \frac{m}{R}a_1 - \frac{m}{R}c_1 - \frac{m}{R}b_1) + m(a_1 + b_1 + c_1 + d_1)}{R(a_1 + d_1)(b_1 + c_1)} = 0 \end{aligned}$$

$\Rightarrow M$  is the midpoint of  $\overrightarrow{XY}$ .  $\square$

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