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1 **Short Note on Two Output-dependent Hidden**  
2 **Markov Models**

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5 **Abstract**

6 The purpose of this note is to study the assumption of “mutual information inde-  
7 pendence”, which is used by Zhou (2005) for deriving an output-dependent hidden  
8 Markov model, the so-called discriminative HMM (D-HMM), in the context of deter-  
9 mining a stochastic optimal sequence of hidden states. The assumption is extended  
10 to derive its generative counterpart, the G-HMM. In addition, state-dependent rep-  
11 resentations for two output-dependent HMMs, namely HMMSDO (Li, 2005) and  
12 D-HMM, are presented.

13 *Key words:* Discriminative models; Generative models; Mutual information  
14 independence; Output-dependent hidden Markov model

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## 1 Introduction

2 Generative models like normal-based discriminant analysis and discriminative  
3 models like logistic regression are comprehensively investigated and compared  
4 in the machine learning literature (Rubinstein and Hastie, 1997; Ng and Jordan,  
5 2001). Amongst the latent (hidden) variable models for structured data  
6 such as time series, hidden Markov models (HMMs) for discrete-valued hidden  
7 states and state-space models (SSMs) for continuous-valued hidden states are  
8 widely used.

9 Traditionally, an HMM is generative because it models a distribution  $P(O_1^n|S_1^n)$ ,  
10 the data generation process (DGP) of the observed output sequence,  $O_1^n =$   
11  $o_1, \dots, o_n$ , given the hidden state sequence,  $S_1^n = s_1, \dots, s_n$ , and thus  $P(O_1^n|S_1^n)$ ,  
12 a state-dependent term, is included in the criterion for determining a sto-  
13 chastic optimal sequence of hidden states. Recently, Zhou (2005) proposes  
14 a discriminative hidden Markov model (D-HMM), which includes output-  
15 dependent terms  $P(s_t|O_1^n), t = 1, \dots, n$ , in the criterion, based on an assump-  
16 tion of “mutual information independence”. Meanwhile, Li (2005) presents  
17 the so-called “hidden Markov models with states depending on observations”  
18 (HMMSDO), which assumes that the current state  $s_t$  depends not only on  
19 the last state  $s_{t-1}$  but also on the last output  $o_{t-1}$ , so that output-dependent  
20 terms  $P(s_t|s_{t-1}, o_{t-1})$  are included in the criterion.

21 Both the D-HMM and HMMSDO show superior performance in determining  
22 the optimal state sequence for certain applications. Zhou (2005) shows that the  
23 D-HMM outperforms the corresponding generative hidden Markov model (G-  
24 HMM) for part-of-speech tagging and phrase chunking; Li (2005) shows that

1 HMMSDO outperforms the standard HMM for prediction of protein secondary  
 2 structures when the training set is large enough.

3 In this note, we shall study the assumption of “mutual information indepen-  
 4 dence” that is used for deriving the D-HMM (Zhou, 2005) in the context of  
 5 determining an optimal state sequence, and then extend it to derive its gener-  
 6 ative counterpart, the G-HMM. In addition, state-dependent representations  
 7 for these two output-dependent HMMs will be presented.

## 8 **2 Generative HMM**

9 Following the notation used by Zhou (2005), the definition of the optimal  
 10 hidden state sequence  $S_1^n$  based on the observed output sequence  $O_1^n$  is that  
 11 of the maximum a posteriori (MAP) estimator  $S^*$  of  $S_1^n$ :

$$S^* = \operatorname{argmax}_{S_1^n} \{ \log P(S_1^n | O_1^n) \} . \quad (1)$$

12 The G-HMM rewrites the criterion (1) through applying Bayes’ theorem and  
 13 ignoring the item determined purely by  $O_1^n$  as

$$S^* = \operatorname{argmax}_{S_1^n} \{ \log P(S_1^n) + \log P(O_1^n | S_1^n) \} ,$$

14 which is further factorised as

$$S^* = \operatorname{argmax}_{S_1^n} \left\{ \log P(S_1^n) + \log \left( P(o_1 | S_1^n) \prod_{k=2}^n P(o_k | O_1^{k-1}, S_1^n) \right) \right\} .$$

15 In order to make this formulation tractable, an assumption that  $O_1^n$  is condi-  
 16 tionally independent given  $S_1^n$  is in general introduced as, for all  $k \in \{2, \dots, n\}$ ,

$$P(o_k | O_1^{k-1}, S_1^n) = P(o_k | S_1^n) , \quad (2)$$

1 and thus based on such a conditional independence assumption, the MAP  
 2 estimator for the G-HMM is simplified to

$$S^* = \operatorname{argmax}_{S_1^n} \left\{ \log P(S_1^n) + \sum_{i=1}^n \log P(o_i | S_1^n) \right\} . \quad (3)$$

3 The G-HMM is regarded as being generative because it directly models the  
 4 DGP  $P(o_i | S_1^n)$  of the observed  $o_i$  from the hidden  $S_1^n$ .

5 In practice, as for the standard HMM, the assumption (2) is further simplified  
 6 to

$$P(o_k | O_1^{k-1}, S_1^n) = P(o_k | S_1^n) = P(o_k | s_k) , \quad (4)$$

7 and thus the MAP estimator of the standard HMM is

$$S^* = \operatorname{argmax}_{S_1^n} \left\{ \log P(S_1^n) + \sum_{i=1}^n \log P(o_i | s_i) \right\} . \quad (5)$$

### 8 3 Discriminative HMM from Mutual Information Independence

9 The D-HMM rewrites the criterion (1) through applying Bayes' theorem, but  
 10 not ignoring the item determined purely by  $O_1^n$ , as

$$S^* = \operatorname{argmax}_{S_1^n} \left\{ \log P(S_1^n) + \log \frac{P(S_1^n, O_1^n)}{P(S_1^n)P(O_1^n)} \right\} .$$

11 To make this formulation tractable, an assumption that the mutual informa-  
 12 tion ( $MI(S_1^n, O_1^n) = \log \frac{P(S_1^n, O_1^n)}{P(S_1^n)P(O_1^n)}$ ) between  $S_1^n$  and  $O_1^n$  is independent with  
 13 respect to each hidden  $s_i$  was introduced by Zhou (2005) as

$$MI(S_1^n, O_1^n) = \sum_{i=1}^n MI(s_i, O_1^n) , \quad (6)$$

14 or, in more detail,

$$\log \frac{P(S_1^n, O_1^n)}{P(S_1^n)P(O_1^n)} = \sum_{i=1}^n \log \frac{P(s_i, O_1^n)}{P(s_i)P(O_1^n)} = \sum_{i=1}^n \log \frac{P(s_i | O_1^n)}{P(s_i)} . \quad (7)$$

1 Based on such a representation, the MAP estimator for the D-HMM is sim-  
 2 plified as (Zhou, 2005)

$$S^* = \operatorname{argmax}_{S_1^n} \left\{ \log P(S_1^n) + \sum_{i=1}^n \log P(s_i|O_1^n) - \sum_{i=1}^n \log P(s_i) \right\}. \quad (8)$$

3 The D-HMM is regarded as being discriminative because the criterion (8)  
 4 includes directly the discriminative process  $P(s_i|O_1^n)$ , representing an output-  
 5 dependence of a hidden state  $s_i$  on all the observed outputs  $O_1^n$ .

6 We shall make four observations about the D-HMM.

7 First, it is noted that the criterion (8) is simultaneously to maximise the max-  
 8 imum posterior marginal (MPM) estimator  $\sum_{i=1}^n \log P(s_i|O_1^n)$  of  $\log P(S_1^n|O_1^n)$   
 9 and to maximise the distance between the state transition model  $\log P(S_1^n)$   
 10 and its independent-based counterpart  $\sum_{i=1}^n \log P(s_i)$ .

11 Second, in order to satisfy the assumption (7) underlying the D-HMM, it is  
 12 required that

$$\prod_{k=2}^n \frac{P(s_k|S_1^{k-1}, O_1^n)}{P(s_k|S_1^{k-1})} = \prod_{k=2}^n \frac{P(s_k|O_1^n)}{P(s_k)}.$$

13 Since this is valid for any value of  $s_k$ , it follows that, for all  $k \in \{2, \dots, n\}$ ,

$$\frac{P(s_k|S_1^{k-1}, O_1^n)}{P(s_k|S_1^{k-1})} = \frac{P(s_k|O_1^n)}{P(s_k)}. \quad (9)$$

14 Third, the assumption (7) can be rewritten as

$$\log \frac{P(S_1^n, O_1^n)}{P(S_1^n)P(O_1^n)} = \sum_{i=1}^n \log \frac{P(s_i, O_1^n)}{P(s_i)P(O_1^n)} = \sum_{i=1}^n \log \frac{P(O_1^n|s_i)}{P(O_1^n)}. \quad (10)$$

15 Based on such a representation, the MAP estimator (8) for the D-HMM can  
 16 be rewritten, with the term  $\sum_{i=1}^n \log P(O_1^n)$  determined purely by  $O_1^n$  being  
 17 ignored, as

$$S^* = \operatorname{argmax}_{S_1^n} \left\{ \log P(S_1^n) + \sum_{i=1}^n \log P(O_1^n|s_i) \right\}. \quad (11)$$

1 Therefore, the D-HMM can also be represented as being generative because  
 2 the criterion (11) includes a generative-like process  $P(O_1^n|s_i)$ , representing a  
 3 state-dependence of all the observed outputs  $O_1^n$  on a hidden state  $s_i$ .

4 Fourth, it can be seen that, when the assumption (6) of mutual information  
 5 independence develops from independence between pairs  $(s_i, O_1^n)$  into that be-  
 6 tween local pairs  $(s_i, o_i)$  such that  $MI(S_1^n, O_1^n) = \sum_{i=1}^n MI(s_i, o_i)$ , the criteria  
 7 (11) and (8) degenerate into the criterion (5), indicating that the D-HMM  
 8 degenerates into the standard HMM.

#### 9 4 Generative HMM from Mutual Information Independence

10 Furthermore, similarly to the assumption (6) proposed by Zhou (2005), an  
 11 assumption that mutual information between  $S_1^n$  and  $O_1^n$  is independent with  
 12 respect to each observed  $o_i$  can be introduced here as

$$MI(S_1^n, O_1^n) = \sum_{i=1}^n MI(S_1^n, o_i) , \quad (12)$$

13 or, in more detail,

$$\log \frac{P(S_1^n, O_1^n)}{P(S_1^n)P(O_1^n)} = \sum_{i=1}^n \log \frac{P(S_1^n, o_i)}{P(S_1^n)P(o_i)} = \sum_{i=1}^n \log \frac{P(o_i|S_1^n)}{P(o_i)} . \quad (13)$$

14 Based on such a representation, we can obtain another generative model and  
 15 its MAP estimator, with the term  $\sum_{i=1}^n \log P(o_i)$  determined purely by  $O_1^n$   
 16 being ignored, as

$$S^* = \operatorname{argmax}_{S_1^n} \left\{ \log P(S_1^n) + \sum_{i=1}^n \log P(o_i|S_1^n) \right\} . \quad (14)$$

17 This estimator is in fact the estimator (3) of the G-HMM, *i.e.*, the G-HMM  
 18 can be derived under the assumption (12), a type of mutual information in-

1 dependence.

2 Similarly, we shall make three observations about this G-HMM, which is de-  
3 rived from mutual information independence.

4 First, in order to satisfy the assumption (13) of the G-HMM, it is required  
5 that, for all  $k \in \{2, \dots, n\}$ ,

$$\frac{P(o_k | O_1^{k-1}, S_1^n)}{P(o_k | O_1^{k-1})} = \frac{P(o_k | S_1^n)}{P(o_k)}. \quad (15)$$

6 Therefore, under the MAP criterion (1), the conditions (15) and (2) have the  
7 same effect on determining the optimal hidden  $S_1^n$ .

8 Second, the assumption (13) can be rewritten as

$$\log \frac{P(S_1^n, O_1^n)}{P(S_1^n)P(O_1^n)} = \sum_{i=1}^n \log \frac{P(S_1^n, o_i)}{P(S_1^n)P(o_i)} = \sum_{i=1}^n \log \frac{P(S_1^n | o_i)}{P(S_1^n)}. \quad (16)$$

9 Based on such a representation, the MAP estimator (14) for the G-HMM can  
10 be rewritten, with the terms related to  $\log P(S_1^n)$  being combined, as

$$S^* = \operatorname{argmax}_{S_1^n} \left\{ (1 - n) \log P(S_1^n) + \sum_{i=1}^n \log P(S_1^n | o_i) \right\}. \quad (17)$$

11 Therefore, in this sense, the G-HMM can also be represented as being dis-  
12 criminative because the criterion (17) includes a discriminative-like process  
13  $P(S_1^n | o_i)$ , representing an output-dependence of all the hidden states  $S_1^n$  on  
14 an observed output  $o_i$ .

15 Third, it can be seen that, when the assumption (12) of mutual information  
16 independence develops from independence between pairs  $(S_1^n, o_i)$  into that be-  
17 tween local pairs  $(s_i, o_i)$  such that  $MI(S_1^n, O_1^n) = \sum_{i=1}^n MI(s_i, o_i)$ , the criteria  
18 (17) and (14) degenerate into the criterion (5), indicating that the G-HMM  
19 degenerates into the standard HMM.



## 1 5 Equivalence between G-HMM and D-HMM

2 Once we assume a fully independent mutual information between any state-  
 3 output combination  $(s_i, o_j)$  as

$$MI(S_1^n, O_1^n) = \sum_{i=1}^n \sum_{j=1}^n MI(s_i, o_j) , \quad (18)$$

4 or, in more detail,

$$\begin{aligned} \log \frac{P(S_1^n, O_1^n)}{P(S_1^n)P(O_1^n)} &= \sum_{i=1}^n \sum_{j=1}^n \log \frac{P(s_i, o_j)}{P(s_i)P(o_j)} \\ &= \sum_{i=1}^n \sum_{j=1}^n \log \frac{P(o_j|s_i)}{P(o_j)} = \sum_{i=1}^n \sum_{j=1}^n \log \frac{P(s_i|o_j)}{P(s_i)} , \end{aligned} \quad (19)$$

5 this assumption results in two criteria, one generative and the other discrimi-  
 6 native, with the MAP estimators as

$$S^* = \operatorname{argmax}_{S_1^n} \left\{ \log P(S_1^n) + \sum_{i=1}^n \sum_{j=1}^n \log P(o_j|s_i) \right\} , \quad (20)$$

$$S^* = \operatorname{argmax}_{S_1^n} \left\{ \log P(S_1^n) + \sum_{i=1}^n \sum_{j=1}^n \log P(s_i|o_j) - \sum_{i=1}^n \{n \log P(s_i)\} \right\} , \quad (21)$$

8 respectively. These two criteria are equivalent.

9 In the context of determining an optimal sequence of hidden states, apart  
 10 from the equivalence above, up to now, we find two occurrences of equivalence  
 11 between a discriminative representation of the MAP criterion and its genera-  
 12 tive counterpart: one is for the D-HMM between the criteria (8) and (11), the  
 13 other is for the G-HMM between the criteria (17) and (14).

14 We shall further illustrate such equivalence with two simple but related HMMs:  
 15 one is a generative-like state-dependent model, which assumes that the current  
 16 output  $o_t$  depends not only on the current state  $s_t$  but also on the last state  
 17  $s_{t-1}$ ; the other is a discriminative-like output-dependent model, the so-called

1 HMMSDO (Li, 2005), which assumes that the current state  $s_t$  depends not  
 2 only on the last state  $s_{t-1}$  but also on the last output  $o_{t-1}$ .

3 The joint distribution of the first generative-like state-dependent model is

$$P(S_1^n, O_1^n) = P(s_1)P(o_1|s_1) \prod_{i=2}^n P(s_i|s_{i-1})P(o_i|s_i, s_{i-1}) . \quad (22)$$

4 This distribution can be rewritten as

$$\begin{aligned} P(S_1^n, O_1^n) &= P(o_1, s_1) \prod_{i=2}^n P(s_i, o_i|s_{i-1}) \\ &= P(o_1)P(s_1|o_1) \prod_{i=2}^n P(o_i|s_{i-1})P(s_i|s_{i-1}, o_i) , \end{aligned} \quad (23)$$

5 which leads to a discriminative-like output-dependent part  $P(s_i|s_{i-1}, o_i)$  in the  
 6 distribution. In fact, the difference between the probabilistic directed acyclic  
 7 graphs (DAGs) corresponding to the joint distributions (22) and (23) is only  
 8 in that directions of edges from  $s_i$  to  $o_i$  are reversed.

9 Similarly, the joint distribution of the discriminative-like output-dependent  
 10 HMMSDO, with  $P(s_i|s_{i-1}, o_{i-1})$  included, is (Li, 2005)

$$P(S_1^n, O_1^n) = P(s_1)P(o_1|s_1) \prod_{i=2}^n P(s_i|s_{i-1}, o_{i-1})P(o_i|s_i) . \quad (24)$$

11 This distribution can be rewritten as

$$\begin{aligned} P(S_1^n, O_1^n) &= P(s_1)P(o_n|s_n) \prod_{i=2}^n P(s_i, o_{i-1}|s_{i-1}) \\ &= P(s_1)P(o_n|s_n) \prod_{i=2}^n P(s_i|s_{i-1})P(o_{i-1}|s_i, s_{i-1}) , \end{aligned} \quad (25)$$

12 which leads to a no longer discriminative-like output-dependence in the dis-  
 13 tribution. In fact, the difference between the DAGs corresponding to the joint  
 14 distributions (24) and (25) is only in that directions of edges from  $s_i$  to  $o_{i-1}$   
 15 are reversed. In practice, whether or not  $P(o_{i-1}|s_i, s_{i-1})$  is reasonable needs  
 16 to be justified, because it means that the current output depends on the next

1 state.

## 2 **6 Summary**

3 This note has suggested that the mutual information assumption (12) resulted  
4 in the G-HMM, while another mutual information assumption (6) resulted in  
5 the D-HMM. However, in practice, whether or not the assumptions are reason-  
6 able and how the corresponding HMMs perform can be data-dependent; re-  
7 search efforts to explore an adaptive switching between or combination of these  
8 two models may be worthwhile. Meanwhile, this note has suggested that the  
9 so-called output-dependent HMMs could be represented in a state-dependent  
10 manner, and vice versa, essentially by application of Bayes' theorem.

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