



UNIVERSITY
of
GLASGOW

Borriello, G. and Chalmers, M. and LaMarca, A. and Nixon, P. (2005)
Delivering real-world ubiquitous location systems. *Communications of
the ACM* 48(3):pp. 36-41.

<http://eprints.gla.ac.uk/3450/>

Delivering Real-World Ubiquitous Location Systems

Gaetano Borriello (University of Washington and Intel Research Seattle, USA)

Matthew Chalmers (University of Glasgow and Kelvin Institute, UK)

Anthony LaMarca (Intel Research Seattle, USA)

Paddy Nixon (University of Strathclyde and Kelvin Institute, UK)

Abstract

Location-enhanced applications are poised to become the first real-world example of ubiquitous computing [11]. In this paper, we emphasize the practical aspects of getting location-enhanced applications deployed on existing devices, such as laptops, tablets, PDAs, and cell phones, without the need to purchase additional sensors or install special infrastructure. Our goal is to provide readers with an overview of the practical considerations that are currently being faced, and the research challenges that lie ahead. We ground the article with a summary of initial work on two deployments of location-enhanced computing: multi-player location-based games and a guide for the Edinburgh Festival.

Ubiquitous Location Systems

A large number of research and commercial location systems have been developed over the past two decades [7]. In general, these systems have one of two goals: providing highly accurate location estimates, on the order of centimetres, within a small area, or providing lower accuracy over a wide coverage area [8]. Systems with a focus on accuracy typically require both extensive infrastructure and relatively expensive sensors. AT&T Cambridge's Active Bats [1] system, for example, employs active ultrasonic badges and requires the installation of ceiling-mounted ultrasound receivers every square meter.

GPS is perhaps the most familiar example of a location system that provides wide-area coverage. GPS is truly ubiquitous, covering the entire Earth's surface by using a constellation of low-orbit satellites. Unfortunately, GPS coverage has limitations in practice. The radio signals sent by the GPS satellites are too weak to penetrate most buildings or pass through dense vegetation. This leads to the *urban canyon* effect experienced in cities, where GPS functionality is lost because buildings occlude GPS signals, or scatter them in multi-path reflections. As a result, GPS works well outdoors but provides little to no coverage indoors where people spend most of their time. Unsurprisingly, GPS has been the dominant location system in navigation and way-finding applications, but has seen little use in other application domains.

Another class of wide-area location technologies is provided by wireless phone service providers, and uses cell tower observations of cell phones to estimate a user's location. In both Europe and the US, governments have mandated that providers be able to locate cell

phones being used to make emergency calls to within 100m. To meet this constraint, providers are experimenting with a variety of techniques, including sophisticated signal propagation models and augmentation of handsets with GPS. As the cell phone is the most ubiquitous computing platform, it is an excellent candidate for location-based service deployment. Three concerns with cell-phone based location are accuracy, privacy and cost. Unlike GPS, where the user's device only listens to satellites, cell-phone based location solutions currently compute the user's location in the infrastructure and relay it back to the user's phone. Implicitly, users must trust that their service provider is protecting their location information, and not selling it or using it in other inappropriate ways. Second, while 100m may be accurate enough for rescue workers to find someone in an emergency, it may prove too inaccurate for many classes of location-based applications. Finally, cell phone providers are not giving location information to users for free; rather they are selling it for as much as \$1 US per location request. This also threatens to constrain the class of applications for which this location platform make sense.

A final, interesting category of location systems uses ambient 802.11 signals to estimate a user's location. Microsoft Research's RADAR system showed that estimating location based on nearby 802.11 base stations can provide location estimates with 3 meter accuracy on standard laptops. In RADAR, an initial calibration is performed in which 802.11 readings are taken on a 1 meter grid, in effect creating a map of which access points can be heard where. Location estimates are produced by comparing radio scans to this map, to find the closest matching location. This approach has also been used in commercial products by Ekahau, Inc. and others. Unfortunately, these systems require extensive calibration and do not scale to cover large areas. Furthermore, the signal strength fingerprints can vary due to changes in the environment, such as weather or moved furniture, and are sensitive to variation across hardware. As a result, these 802.11-based location systems wind up somewhere in the middle of the accuracy/coverage spectrum, providing less accuracy and requiring less infrastructure than other indoor location systems, and better accuracy, but less coverage than GPS.

These example systems are representative of the wide variety and large number of ubiquitous location systems available today. On the whole, they rely on listening to radio frequency signals, and interpreting their relative timing and/or signal strength. These systems are limited by inherent technology problems such as limits on coverage, signal interference, and reliance on infrastructure, and by broader issues such as privacy concerns.

Towards Truly Ubiquitous Location Systems

Attempts have been made to alleviate many of the hurdles and disadvantages of today's wide-area location solutions. There are a number of variants of the basic GPS strategy that improve the accuracy and time-to-lock for GPS handsets. Both ground-based and satellite-based versions of differential GPS improve accuracy to 5 meters from 8-10 meters for a non-enhanced unit. GPS chipsets are being integrated into mainstream cell phones and PDAs, lowering cost and decreasing the users' barrier to entry. To help meet

the E911/E112 requirements [6], cell phone manufacturer have started to produce handsets that use a mix of location technologies. When GPS is not available, the locations of nearby cell towers are used to produce a coarse location estimate. Based on this coarse location, the phone can download the expected position of the satellites, allowing the handset to lock on to GPS much more quickly (on the order of seconds instead of a minute or more) when GPS does become available. By 2008 the European Union will deploy Galileo, a next-generation GPS system that promises greater accuracy and, due to stronger radio signals that should penetrate most of today’s buildings, operation indoors as well as out.

Place Lab is a research project that is attempting to solve the ubiquity issues surrounding 802.11-based location estimation [12]. Like RADAR, Place Lab uses a device’s built in 802.11 interface, but does not rely on pre-calibrated fingerprints. Instead it predicts location via the known positions of the access points detected by the device [9]. The positions of these access points are provided by a database cached on the same device. This cache in turn can be filled from a variety of access point databases that have been created by universities, radio hobbyists, ‘war driving’ and wi-fi clubs. The largest of these databases, *wigle.net*, contains nearly two million access point locations, providing reasonable coverage in many large cities in the United States and Europe. The most recent “World Wide Wardrive” suggests that mapping efforts may keep up with the rapid deployment rate of 802.11 access points: over an 8 day period in June 2004, nearly 300,000 new access points were mapped. A more geographically limited but similar approach to Place Lab was used in the Lancaster Tour Guide [4].



Figure 1. Place Lab and GPS are compared in this approximately 1km loop through downtown Seattle. The user started at the bottom and moved in a counter-clockwise direction around the loop. The red line is the series of location estimates based on wi-fi access points with Place Lab. The blue line is the series of location estimates from a GPS receiver – note the gaps in GPS coverage when the user rides a bus (on the left side of the loop) and enters a large shopping area (at the top).

A problem for 802.11-based location systems is the lack of 802.11 in less populated areas. While many cities have near-ubiquitous 802.11 coverage, coverage is close to zero

in rural areas. To address this, Place Lab uses GSM cell towers and fixed Bluetooth devices as well as 802.11 access points. The near perfect coverage in Europe and the rapid deployment of GSM in the US gives Place Lab improved coverage; the small range of Bluetooth devices improves Place Lab's accuracy when they are available. Due to the small amount of calibration required, Place Lab's location estimates are less accurate than those produced by systems like RADAR. In residential and urban settings with GSM coverage and moderate 802.11 density, Place Lab produces location estimates with 20-25 meters of accuracy, almost a factor of 10 worse than systems that maintain a more detailed radio map. Interestingly, Place Lab's accuracy falls between the 8-10 meter accuracy of GPS and the mandated 100 meter accuracy of cell phone-based location estimates.

More significantly, however, Place Lab matches the privacy model of GPS. In this model, devices listen to RF signals and compute location estimates autonomously rather than divulging their location to an infrastructure. Users can use the location information as they see fit, and divulge it only when they want to [2, 5]. Many services can be provided using cached information on the user's device such as maps and schedules. Of course, more dynamic data such as traffic conditions and arrival/departure times will still require a connection to a network.

Two Case Studies

We present two case studies to show both the challenges and opportunities in real-world deployment of a location-enhanced application. The first is a guide for the Edinburgh Festival that starts from a set of requirements and develops the necessary technology elements. The second is a location-based game that starts with a location technology, and incorporates and exploits the limitations of the technology to create game strategies.

Ubiquitous location systems are part of the design of a visitor guide to the Edinburgh Festival, the largest arts festival in the world, with thousands of events taking place in hundreds of venues. The Kelvin Institute, in collaboration with Intel Research Seattle and the Edinburgh Festival's organizers, is undertaking research into systems that support the visitor experience in terms of events to attend, places to go and information to read.

Edinburgh is an old city in the UK. It has many narrow streets and high buildings, and has a latitude of 55° north—almost as far north as Alaska. GPS alone is not a reliable location system here, primarily because of urban canyon effects. To assess the viability of Place Lab as a location system to either replace or complement GPS, a small pilot study was carried out. In the summer of 2004, a war driving survey of 802.11 coverage in the city center was made, and nine festival visitors were recruited for a study. Each carried a PDA running Place Lab during a day out in the festival, and a camera to take photographs of routes and destinations. The photographs and Place Lab logs were used in post-visit interviews to better understand the availability and accuracy of positioning, and to inform system development. While analysis is ongoing, some preliminary results are available.

For 61% of the time, on average, no access points were detected and Place Lab could not provide a location. Two or more access points were detected for only 17% of the time. Excluding periods of time when visitors appeared to be indoors reduced the overall detection rate from 61% to 36%. It was also noted that, on different days, each of three visitors had walked along one particular street. On that street, 28% of the access points were detected by just one or another of the three visitors and, on average, each of them detected 81% of the access points. Overall, the study suggested that in an ‘old world’ city like Edinburgh, 802.11 density is far lower than that of cities in the US. Location systems that use combinations of 802.11, GPS and other sources of data, such as the newest release of Place Lab, seem highly appropriate for increasing location system availability and accuracy in such settings. Using multiple technologies also allows festival organizers to add further 802.11 and Bluetooth ‘beacons’ where greater accuracy is needed. Such beacons need not provide network access, necessarily, since only their identification is needed for the purpose of positioning.

In the light of the variable and local availability of RF-based systems, some researchers are exploring a *seamful design* approach, taking advantage of the limits, gaps and *seams* of RF-based systems for location and communication. One example is the Seamful Game [3], a mobile multiplayer game developed within the UK’s Equator project (www.equator.ac.uk) for PDAs with 802.11 and GPS. Two teams of players gain information from a server about the locations of periodically appearing *coins* and the locations of other players. They also receive updates of a map overlay showing wi-fi signal strength, sampled by players as they play the game. To gain points, a player has to get close to a coin (according to GPS), and then use a GUI ‘Pickup’ command to pick it up. If in network coverage, the player can ‘Upload’ the coin to receive points, or use the ‘Pickpocket’ command to steal coins out of the PDAs of any nearby players. The game interface is shown in Figure 1.

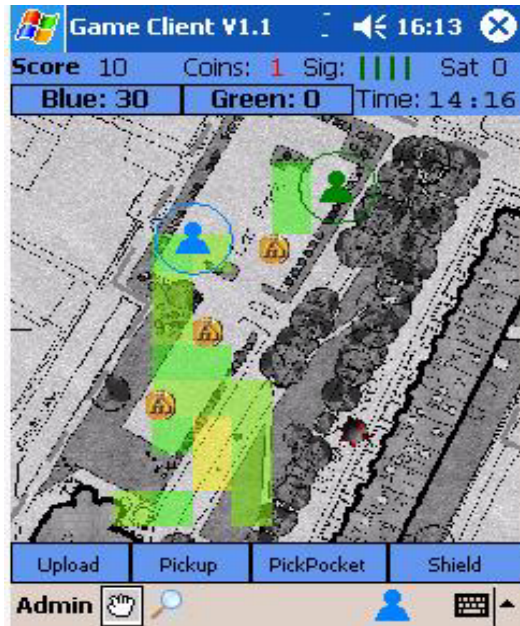


Figure 2. In the Seamful Game, a map overlay shows 802.11 signal strength as transparent squares of green and yellow, on top of a monochrome street map. The maps are built up over time from samples gathered during game play, and are made available as a resource for players' system use and development of game tactics.

The game has an inbuilt tension between being in network coverage and being out. Coins often appear in areas where there is no coverage and poor GPS, but one needs network coverage in order to upload coins, get game points and receive game state updates. However, when in coverage with a good GPS fix, one gives away one's location and becomes open to pickpockets. Initially, players are uncertain as to where there is coverage, but they can watch and talk to other players as they move, and use the 802.11 map overlay as they reveal sampled coverage to each other.

Apart being played on campus at the University of Glasgow, the game has also been demonstrated and evaluated at the Ubicomp 2004 and Mobile HCI 2004 conferences. A number of practical and environmental effects on RF became apparent in these trials. The game designers were surprised, for example, that rain, snow and leaves on trees strongly affect wi-fi and GPS. Even the angle of a PDA with regard to the player's body affects its performance. Metal near to 802.11 access points also varies the distribution of RF, e.g. a truck parked in front of an access point was found to radically inhibit its coverage. Lastly, communication *gray zones* are created by the differences between the antennae of access points and mobile devices, and by the different bit rates used for broadcasts and for data transmissions. Transfer of packets to and from access points can show significant asymmetry, and high packet loss can occur despite apparent network reachability.

Summary

Location systems are not yet ubiquitous, but are increasing their accuracy, coverage and availability, and maintaining moderate cost. A number of candidate technologies are already in the marketplace, and new ones are continually being developed. Alongside the developments of such infrastructure, commercial and research-oriented applications are

being developed in significant numbers. In the future, the development of new location systems is likely to be influenced by market trends in the hardware and software platforms of mobile devices—most particularly cell phones—as much as the technology options within location systems themselves.

Privacy is clearly a major factor in location systems' development and deployment. As discussed in another article in this issue [10], privacy remains contentious. There is a high demand from users for security, privacy and trustworthiness, but the very features that enable location identification also contribute to the privacy problem. The architecture shared by Place Lab and GPS gives users a degree of control over when and how their locations are revealed. Nevertheless, networked applications will appear that request this location information from the user, suggesting that new techniques will have to be developed that extend the user's control beyond his or her own device.

Developers of applications will, for some time, have to accept variation in the accuracy and availability of location data. Fusing multiple sources of location data will be a key attribute of location systems that can handle the range of environments in which mobile devices are used, for example, shifting from GPS data, used in open areas, to GSM, wi-fi and Bluetooth beacons in built-up areas and indoors. Place Lab and a number of other location systems are already responding to this challenge. In order to construct and maintain comprehensive databases to support such systems, it is likely that further work is needed on generating database updates as a by-product of mobile devices' everyday use.

In addition, we see significant potential in deliberately showing some of the seams in the infrastructure of ubiquitous computing systems, going beyond the simple displays of signal strength in phones and laptops, to offer people maps of availability of wi-fi coverage and location services. Again, such information may be gathered as a by-product of use, as in the Seamful Game, or by simulation [13]. Systems that expose the variable accuracy and availability of location systems should not be seen as standing in opposition to research aimed at improving accuracy and broadening availability. Instead, such approaches should be seen as complementary. We should offer pragmatic solutions for developers delivering real world applications for widespread use, while we continue to improve, adapt and evaluate the underlying technology of ubiquitous location systems.

References

1. Addlesee M., et al., Implementing a Sentient Computing System, IEEE Computer, Vol. 34, No. 8., August 2001.
2. Cahill V., et al., Using Trust for Secure Collaboration in Uncertain Environments, IEEE Pervasive Computing Magazine, July-September 2003.
3. Chalmers M., et al., Seamful Design: Showing the Seams in Wearable Computing, Proc. IEE Eurowearable, Birmingham, UK, 11-17, 2003.
4. Cheverst K., et al., Developing a Context-aware Electronic Tourist Guide: Some Issues and Experiences, Proceedings of the SIGCHI conference on Human factors in computing systems, 2000, The Hague, The Netherlands.

5. Consolvo S., et al., Exploring User Attitudes about Location Privacy, Workshop on Ubicomp Privacy: Current Status and Future Directions at 6th International Conference on Ubiquitous Computing, Nottingham, UK, September 2004.
6. Geer, D. The E911 dilemma. *Wireless Business and Technology*, November/December 2001.
7. Hazas M., Scott J., Krumm J., Location-Aware Computing Comes of Age, *IEEE Computer*, Vol. 37, No. 2, February 2004
8. Hightower J., Borriello G., Location Systems for Ubiquitous Computing, *IEEE Computer*, Vol. 34, No. 8., August 2001.
9. Hightower J., Borriello G., Particle Filters for Location Estimation in Ubiquitous Computing: A Case Study, 6th International Conference on Ubiquitous Computing, Nottingham, UK, September 2004.
10. Lahlou S., Langheinrich M., Röcker C., Privacy and Trust with Invisible Computers, *Communications of the ACM*, (this issue).
11. Rao B., Minakakis L., Mobile commerce opportunities and challenges: Evolution of mobile location-based services, *Communications of the ACM*, Vol. 46, No. 12, December 2003.
12. Schilit B., et al., Ubiquitous Location-Aware Computing and the “Place Lab” Initiative, 1st ACM International Workshop on Wireless Mobile Applications and Services on WLAN Hotspots, San Diego, CA, September 2003.
13. Steed A., Supporting Mobile Applications with Real-Time Visualisation of GPS Availability. *Proceedings of Mobile HCI 2004*, Springer LNCS 3160.