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Wideband polarization splitter and rotator with large fabrication tolerance and simple fabrication process

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We propose and demonstrate a polarization splitter and rotator (PSR) built on a silicon-on-insulator platform. The PSR is constructed with a tapered waveguide followed by a 2 × 2 multimode interferometer and can be simply fabricated in a single lithography and etching step. A low insertion loss (<2.5 dB with minimum insertion loss of 0.6 dB) and a low polarization crosstalk (< - 12 dB) over a wide operation bandwidth (~100 nm) with a large fabrication tolerance (>50 nm) are experimentally demonstrated. © 2013 Optical Society of America OCIS codes: 130.0130, 130.3120, 230.5440.

Silicon-on-insulator (SOI) microphotonic devices are very attractive thanks to their complementary metal oxide semiconductor (CMOS)-compatible fabrication technology, their high refractive index contrast, and compact size [1]. Those advantages make SOI microphotonic devices promising candidates for all-optical signal processing subsystems. However, the high refractive index contrast also introduces large polarization dependency, which becomes one of the major challenges for their practical use. In particular, if the device is to be used in a subsystem deployed over an optical fiber link, the polarization state of the optical signal at its input may change randomly over time, making standard SOI microphotonic devices no longer compatible with optical processing functionalities. To realize polarization independence, polarization diversity (Pol-D) circuits based on polarization splitter and rotator (PSR) technologies are typically used [2–4]. In this scheme, the input light contributions along the two orthogonal polarizations axes are first split by a polarization splitter [5]. After that, one of the two polarizations is rotated by 90° by a polarization rotator [6]. Thus, in the rest of the circuit, only one polarization needs to be processed. Many approaches have been proposed and demonstrated to realize PSRs. However, they all require a rather complex fabrication process [6–11]. To simplify the fabrication process, asymmetrical directional coupler (DC)-based PSRs have been recently proposed and demonstrated [12–14]. One of the main practical issues with many PSR designs is their limited fabrication tolerance, which makes them impractical for high-yield production. The best reported fabrication tolerance of ~14 nm for a DC-based PSR was recently obtained using a tapered DC design [15].

In this Letter we propose and demonstrate a PSR built on the SOI platform. In this device, an adiabatically tapered waveguide first converts the TM_0 to the TE_1 mode, while also preserving the TE_0 mode. A 2 × 2 multimode interference (MMI) coupler, which is well-known for its large fabrication tolerance [16] and has been utilized for wide bandwidth polarization splitting/combining [17], is introduced afterward to effectively couple the TE_0 and TE_1 modes at the end of the TM_0 – TE_1 mode converter to two distinct TE_0 outputs. Simulation results show a large fabrication tolerance of 63 nm thanks to the use of the MMI. A low insertion loss better than 2.5 dB, with minimum insertion loss of only 0.6 dB and polarization crosstalk lower than -12 dB over a wide bandwidth of 100 nm, is demonstrated experimentally, together with a large fabrication tolerance better than 50 nm.

The principle of the proposed PSR is schematically depicted in Fig. 1(a). Light is first injected into a tapered waveguide and then split into two beams by a Y-splitter. Before being injected into the 2×2 MMI, an extra phase difference of $\pi/2$ is introduced between the two beams. In case of TE_0 input, the mode will be preserved during the adiabatic taper and split into two TE₀ beams with the same phase. Thus, at the MMI input, the two beams will have a $\pi/2$ phase difference. By properly designing the MMI, light will output from arm 1 on the TE_0 mode with little crosstalk in arm 2 [Fig. 1(b)]. On the other hand, in case of TM₀ input, the light is converted to the TE₁ mode during the adiabatic tapering $[\underline{14}]$ and split into two TE_0 beams with π phase difference. Thus, at the MMI input, the two beams will have a $-\pi/2$ phase difference, and light will consequently output from arm 2 on the TE_0 mode



Fig. 1. (Color online) (a) Schematic structure of the proposed PSR. TE_0 (b) and TM_0 (c) light are input to the PSR, and output from arm 1 and 2, respectively, on the TE_0 mode.



Fig. 2. (Color online) Effective indices of the TE₀, TE₁, and TM₀ modes of an air-clad SOI waveguide as a function of the waveguide width w for a waveguide height h = 250 nm (simulated by FIMMWAVE [18]).

with little crosstalk in arm 1 [Fig. 1(c)]. To achieve an efficient TM_0-TE_1 polarization conversion, a material that is different from the buffer layer (silicon oxide) should be applied as top-cladding layer [14]. In our design, air is employed as top cladding material. To decrease the tapering length, the TM_0-TE_1 converter is divided into three sections, as shown in Fig. 1(a). The first section L_1 is from input single mode silicon waveguide ($w_1 = 450$ nm) to $w_2 = 650$ nm. Since in this section there is no mode conversion, a short tapering length of 10 μ m is employed. Considering the TM₀ and TE₁ modes are hybridized around $w_c = 700$ nm, as shown in Fig. 2, the second tapering section L_2 is from w_2 to $w_3 = 750$ nm with a tapering length as long as 120 μ m, which can guarantee an efficient TM_0-TE_1 conversion, as shown in the inset of Fig. 3(a). The third section L_3 is from w_3 to $w_4 = 800$ nm with tapering length of 10 $\mu m.$ The output end of the $TM_0\text{--}TE_1$ converter is then split to two arms with widths of 400 nm and connected to the 2×2 MMI through tapering to $w_0 = 700$ nm to improve the fabrication tolerance [16]. With a calculated effective index of 2.234, the two arms are designed to have a length difference of 173 nm to introduce the required $\pi/2$ phase difference. The 2×2 MMI is designed to be of the symmetric type (excited at $w_{\rm MMI}/4$) with width of $w_{\rm MMI} = 2 \ \mu m$ and length of $L_{\rm MMI} = 13.7 \ \mu m$ based on three-dimensional finite difference time domain (3D FDTD) simulations. A restricted type MMI (excited at $w_{\rm MMI}$ /6), which could efficiently decrease $L_{\rm MMI}$, could also be used. In this case, $w_{\rm MMI}$ should be larger in order to sufficiently separate the two output waveguides.

In reality, a size deviation Δw_{device} may be introduced by the fabrication process for the whole device. Such a size deviation will influence the TM_0-TE_1 mode conversion in the adiabatic taper section and introduce a phase deviation from $\pi/2$ between the two arms before the MMI, which further influences the whole performance of the device. Figure 3(a) shows the TM_0-TE_1 conversion efficiency for different width deviations of the adiabatic taper calculated using the eigenmode expansion method [18]. A large tolerance of ± 40 nm is expected for the adiabatic taper to guarantee a high TM_0-TE_1 conversion efficiency above 95%. To investigate the impact of a



Fig. 3. (Color online) Calculated fabrication tolerance of (a) adiabatic taper based TM_0-TE_1 mode converter and (b) 2×2 MMI. The inset in (a) shows the TM_0-TE_1 conversion efficiency as a function of L_2 . The insets in (b) show the field distributions simulated by 3D FDTD.

width deviation of the two arms before the MMI, the width deviation is first converted to an effective index deviation according to Fig. 2, then to a phase deviation $\Delta \phi$ for the two beams. 3D FDTD simulations are used to investigate the tolerance. In the simulations, two beams of light with phase difference of $\pi/2 + \Delta \phi$ are injected into the MMI, and the two output powers are calculated as shown in the insets of Fig. 3(b). A large tolerance of ± 100 nm is obtained while the crosstalk is kept below 15 dB. Finally, for the MMI, in a Rayleigh range, a length tolerance can be estimated as $\Delta L_{\rm MMI} = \pi n_r w_0^2 / 4\lambda_0$ [16], where w_0 is defined as the input Gaussian beam waist, n_r is the material refractive index, and λ_0 is the operating wavelength. The corresponding width tolerance and operation bandwidth can be calculated as $\Delta w_{\rm MMI} =$ $w_{\rm MMI}\Delta L_{\rm MMI}/2L_{\rm MMI}$ and $\Delta\lambda_0 = \lambda_0\Delta L_{\rm MMI}/L_{\rm MMI}$, respectively [16]. With $w_0 = 700$ nm, $n_r = 3.476$, and $\lambda_0 = 1550$ nm, a length tolerance $\Delta L_{\rm MMI}$ of 860 nm, a width tolerance $\Delta w_{\rm MMI}$ of 63 nm, and a bandwidth $\Delta \lambda_0$ of 98 nm are expected. Thus, an overall size deviation tolerance of $\Delta w_{\text{device}} = 63 \text{ nm}$ is expected for the whole device with a bandwidth of 98 nm.

The device was fabricated on a SOI wafer (top silicon thickness 250 nm, buried silicon dioxide 3μ m) by a single step of E-beam lithography (JEOL JBX-9300FS) and inductively coupled plasma reactive ion etching (STS Advanced Silicon Etcher). Figure <u>4(a)</u> shows the fabricated device with design parameters as introduced previously.

The total length of the device, including the 140 μ m long adiabatic taper-based TM₀–TE₁ mode converter, is 190 μ m. Note that the smallest feature size of the device is the inner corner of the Y-splitter, enabling our scheme to be fabricated with other methods [19]. Figure 4(b)



Fig. 4. (Color online) (a) Scanning electron microscope (SEM) picture of the fabricated device. (b) Measured coupling efficiency to the two output ports for TE_0 and TM_0 inputs. (c) Measured TM_0 -TE₀ conversion efficiency for different device size deviations.

shows the measurement results. Details on the measurement setup and calibration procedure can be found in [12]. A low insertion loss (from inputs on either the \overline{TM}_0 or TE_0 mode to output arm 1 or 2 on the TE_0 mode, normalized to a straight waveguide) better than 2.5 dB with a minimum insertion loss of 0.6 dB and polarization crosstalk lower than -12 dB are obtained over a wide bandwidth of 100 nm. To improve the insertion loss, more efficient Y splitters with lower insertion loss should be used [20]. In addition, the polarization crosstalk can be improved by increasing the width of the 2×2 MMI so that the two output waveguides are separated sufficiently to avoid evanescent coupling between them. To further investigate the fabrication tolerance of the device, six devices with device size deviations from -20 nm to 30 nm were fabricated and characterized, as shown in Fig. 4(c). One can find that similar high

conversion efficiencies are obtained over a better than 50 nm device size deviation, in good agreement with the simulations.

In conclusion, we have proposed and demonstrated a PSR built on the SOI platform, which is fabricated by simple processing. A low insertion loss better than 2.5 dB with a minimum insertion loss of 0.6 dB and polarization crosstalk lower than -12 dB over a wide bandwidth of 100 nm are demonstrated together with a large fabrication tolerance better than 50 nm.

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