

Evaluation strategies in CT scanning

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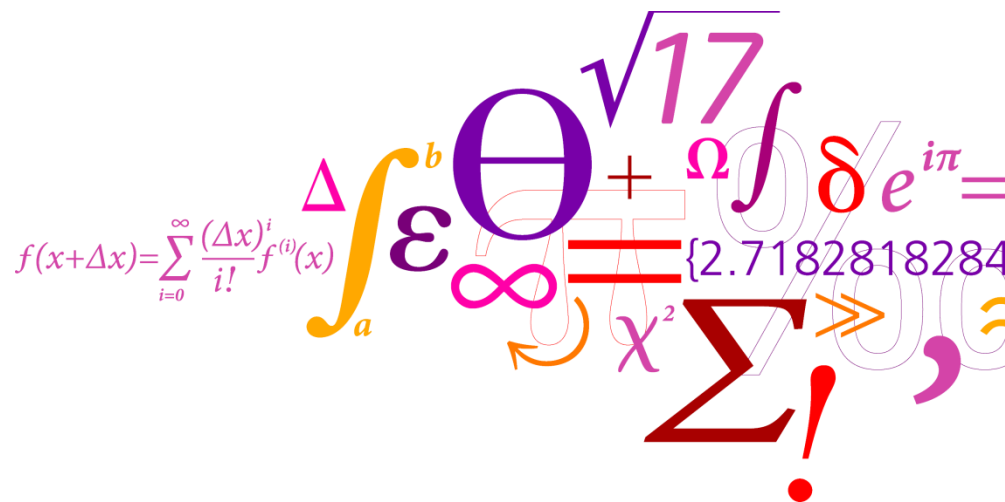
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Evaluation strategies in CT scanning – A case study

Jochen Hiller

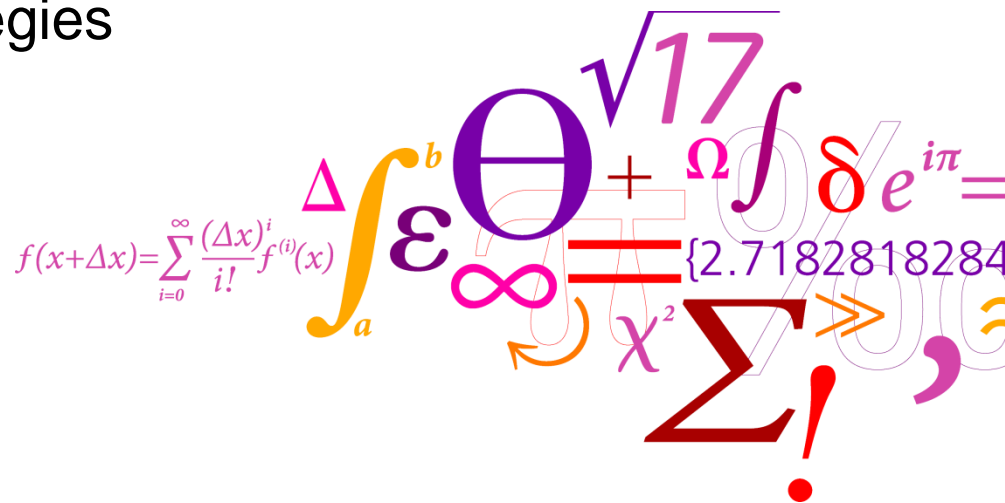
CT Conference
12th June 2012, DTU

DTU Mechanical Engineering
Department of Mechanical Engineering



Overview

- Motivation
- Objectives and description of a performed case study
- Measuring setup for tactile, optical and CT measurements
- Uncertainty assessment
- Definition of measuring strategies
- Results
- Conclusions



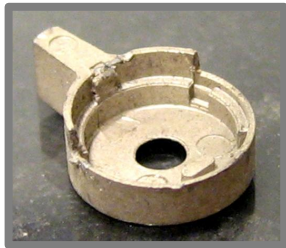
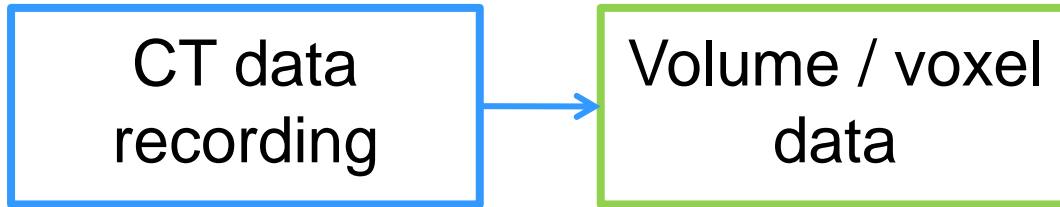
Sample

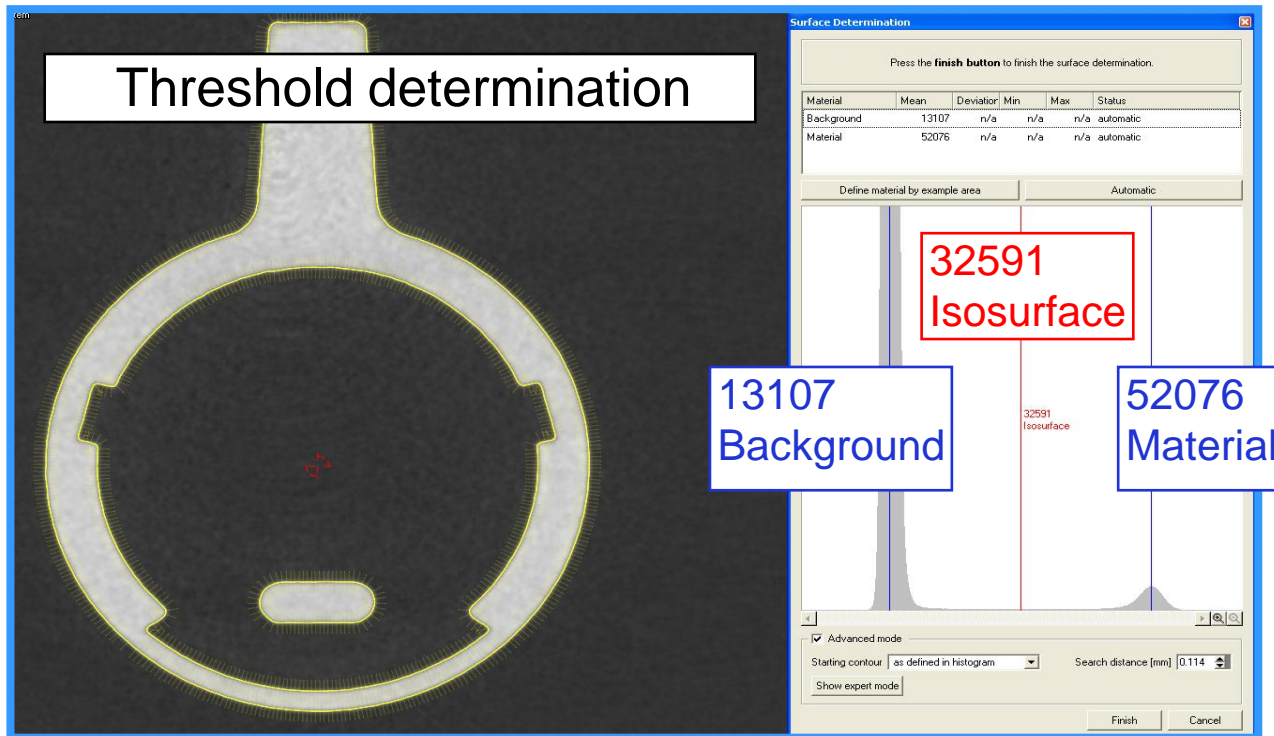
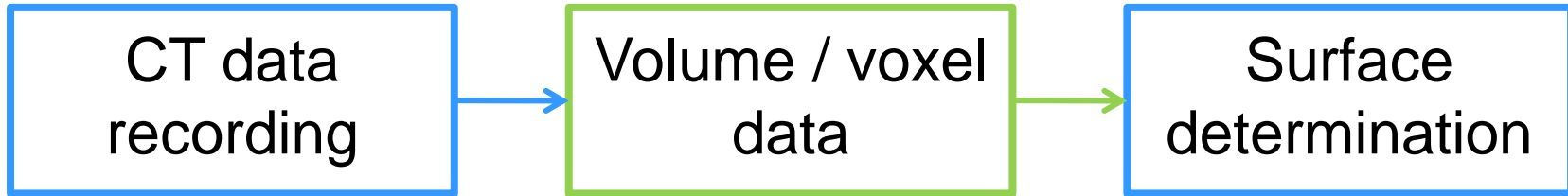


CT data
recording



Motivation

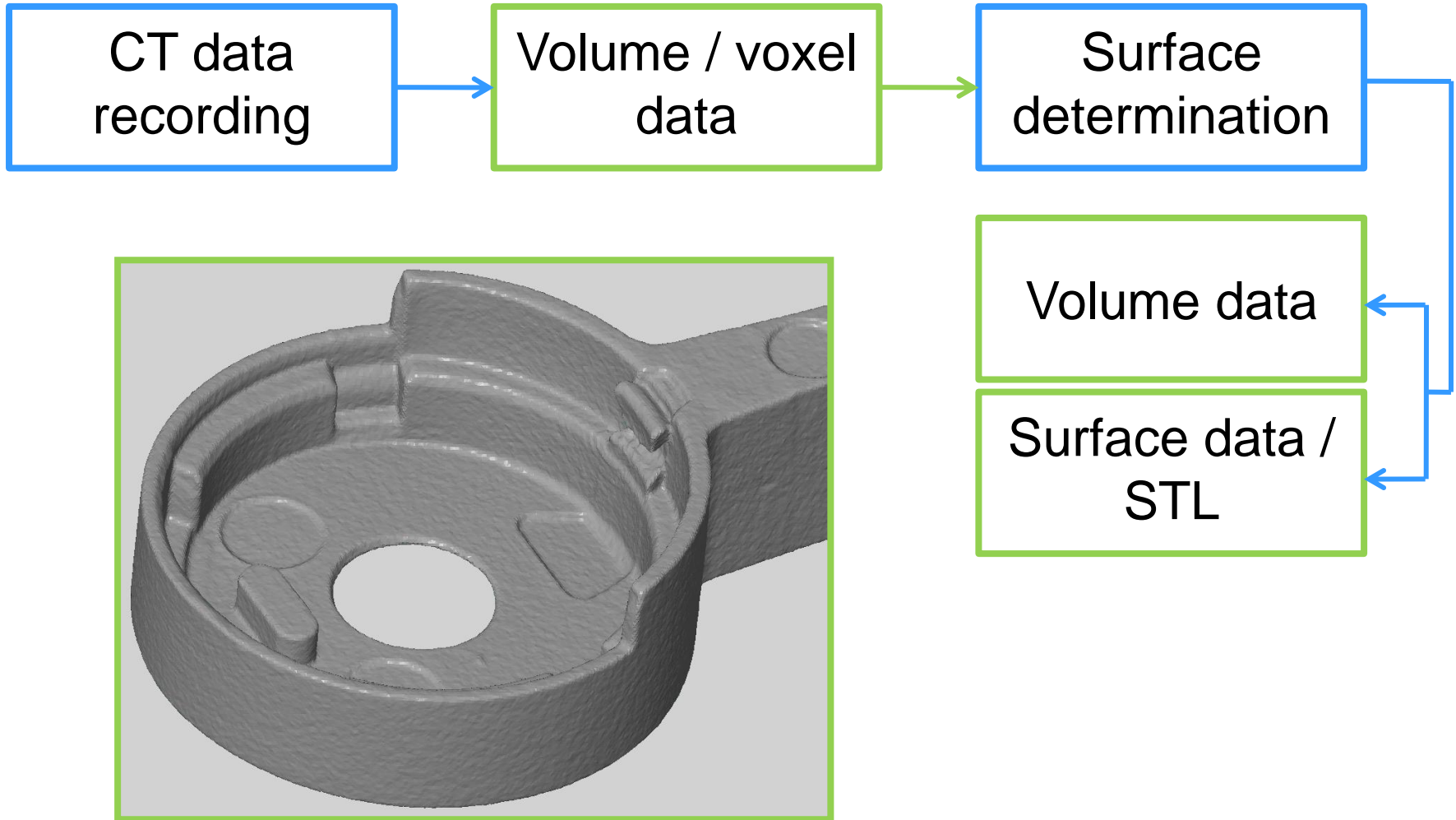




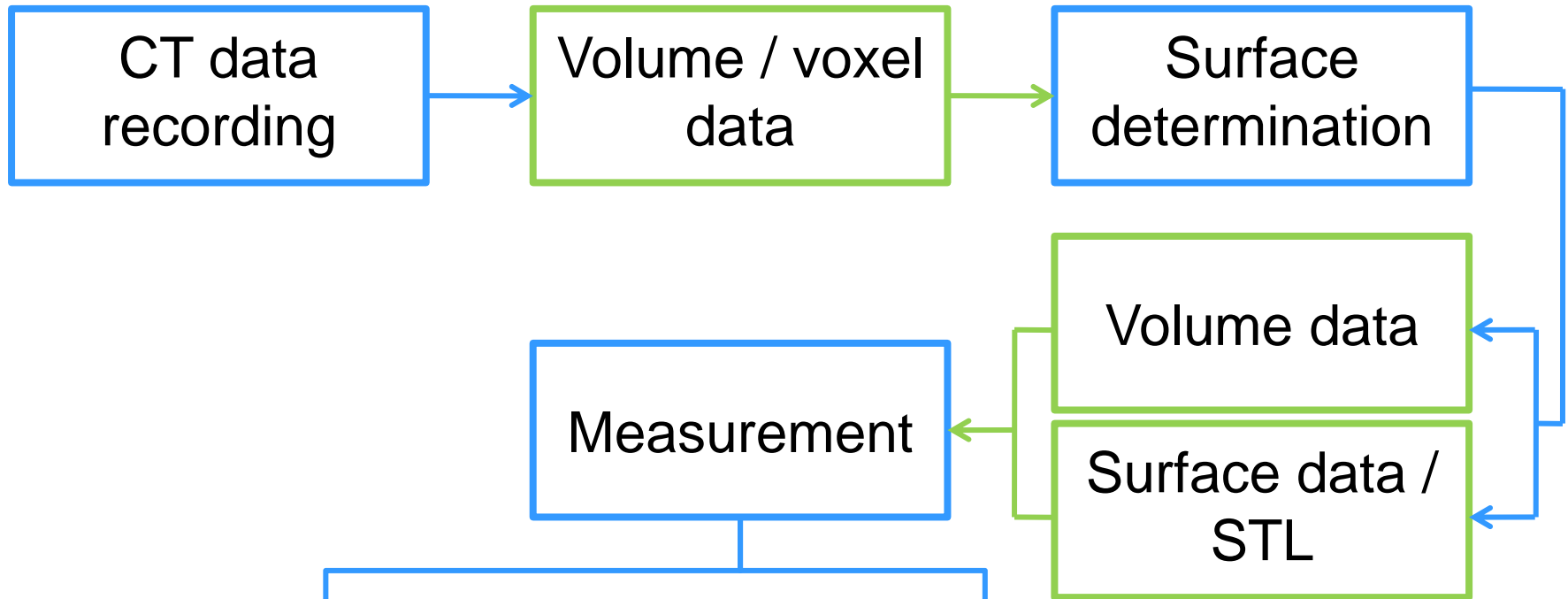
Material	Mean	Deviation	Min	Max	Status
Background	13107	n/a	n/a	n/a	automatic
Material	52076	n/a	n/a	n/a	automatic

Advanced mode
Starting contour: as defined in histogram
Search distance [mm]: 0.114

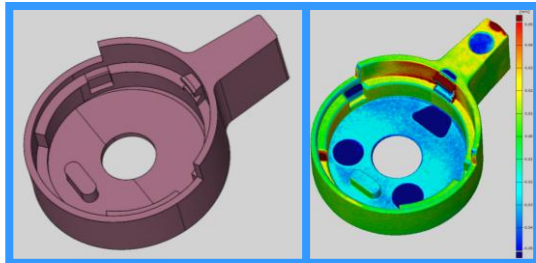
Motivation



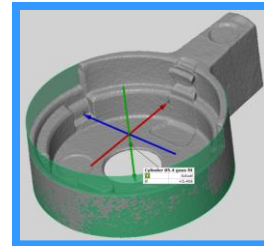
Motivation

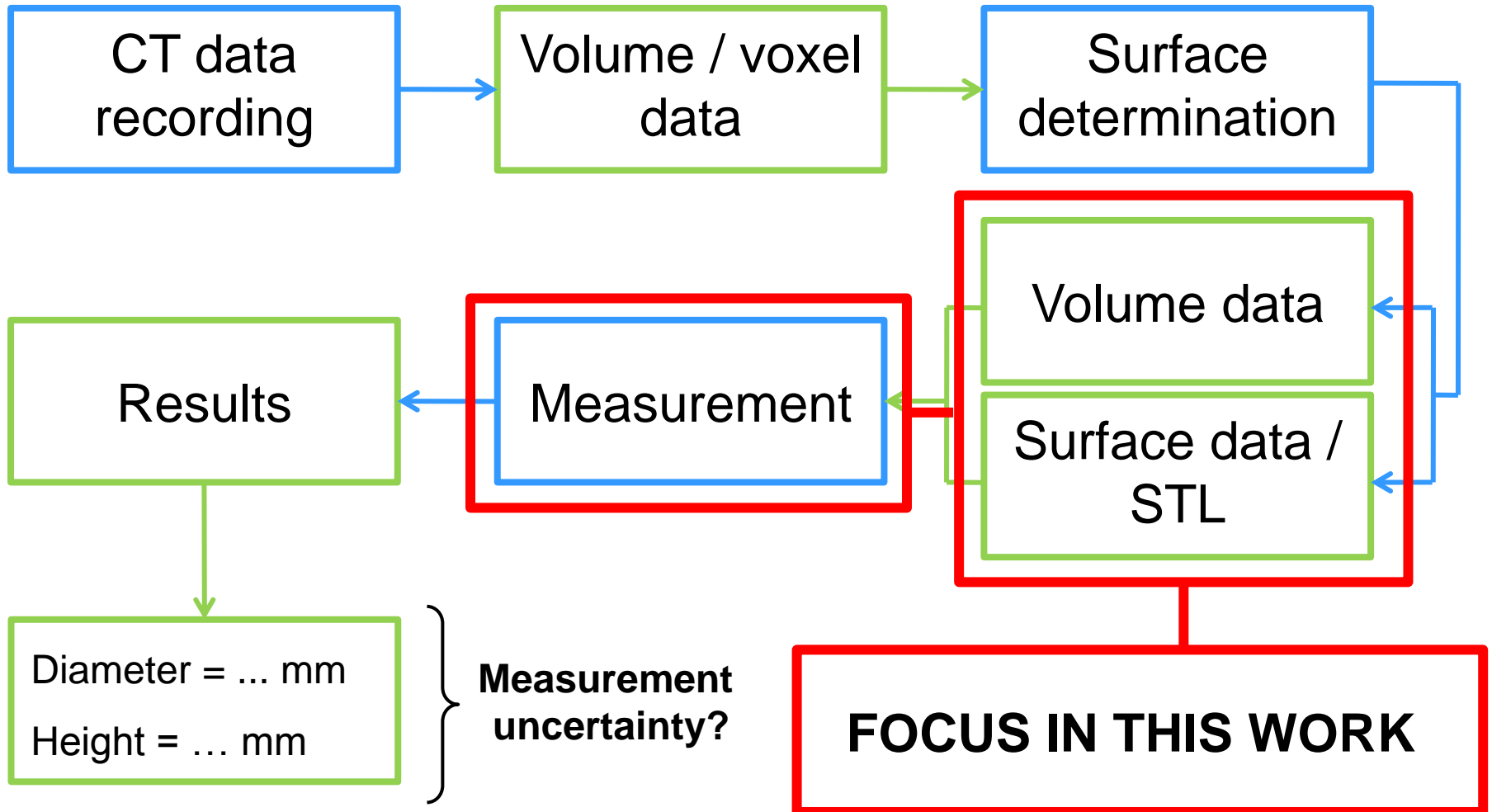


Reference data or CAD model



Geometry fitting





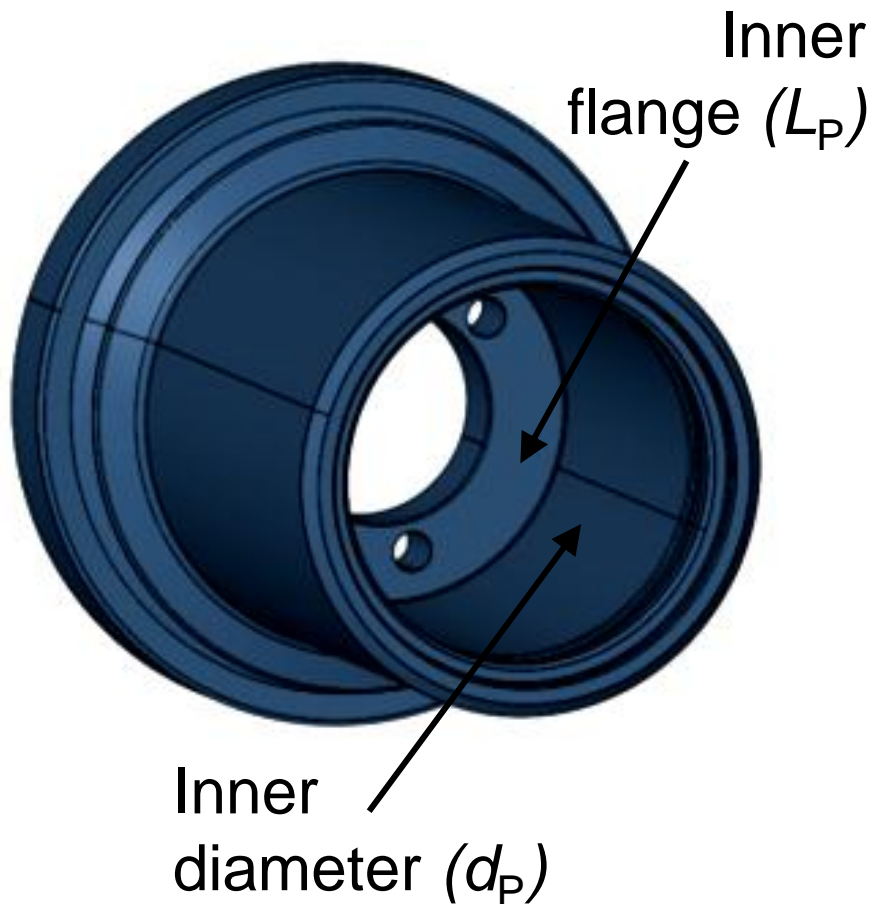
The objective was to perform geometrical measurements on selected industrial parts using a micro CT system

The specific aims are:

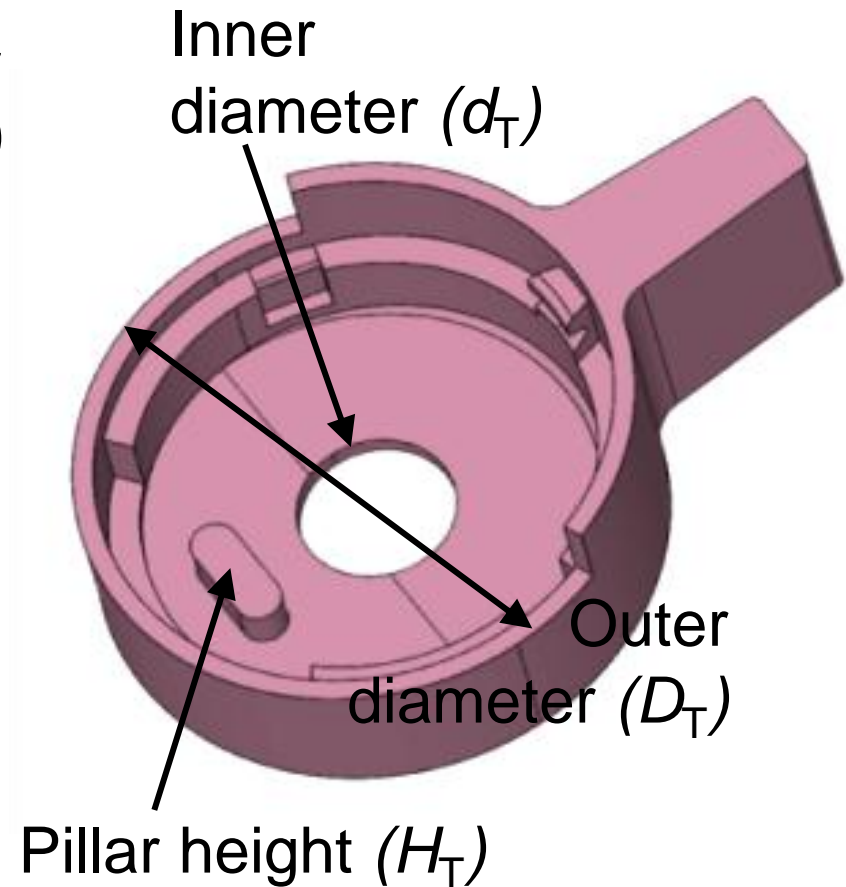
- The comparison of available evaluation software for 3D-CT inspection with respect to data representation and measuring strategies.
- The calculation of the measurement uncertainty as the quality parameter of the measurements.

Software	Software producer	Measurement performed on
Calypso CT 4.8.10.16	Zeiss	Volume data
VGStudio MAX 2.1	Volume Graphics	Volume data
ATOS Professional V7 SR2	GOM Inspect	Polygonal mesh

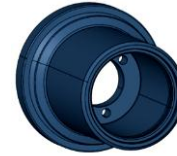
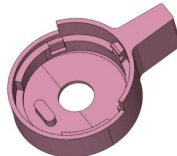
PIPE CONNECTOR



TOGGLE



Measuring setup for tactile, optical and CT measurements



Tactile CMM
OMC 850, ZEISS



Optical CMM
DeMeet 220, DeMeet



CT scanner
Metrotom 1500, ZEISS



$$MPE_{TCMM} = (2.5 + L/300) \mu\text{m in } x, y, z$$

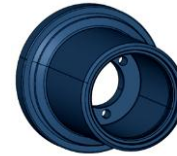
$$MPE_{OCMM} = (4 + L/150) \mu\text{m in } x, y \text{ and } 3.5 \mu\text{m in } z$$

$$MPE_{CT} = (9 + L/50) \mu\text{m in } x, y, z$$

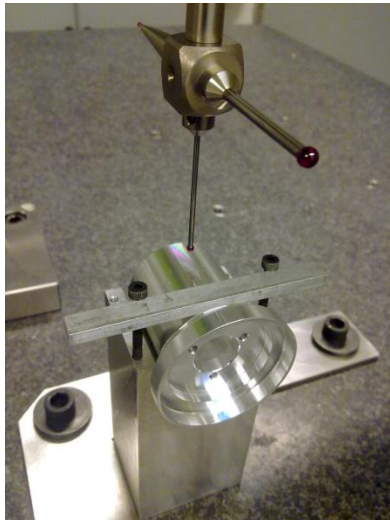
REFERENCE MEASUREMENTS

ACTUAL MEASUREMENTS

Measuring setup for tactile, optical and CT measurements

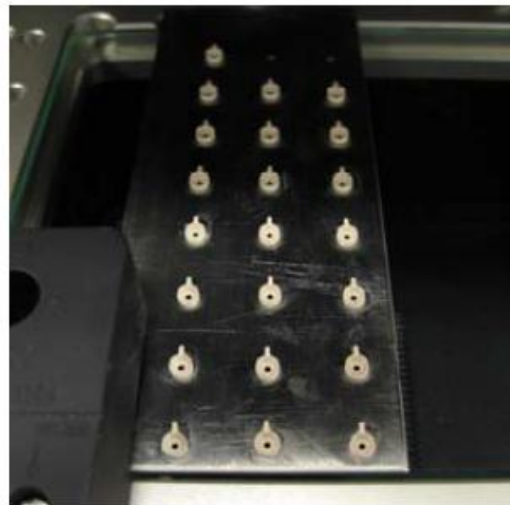


Tactile CMM
OMC 850, ZEISS



Acquisition of single points

Optical CMM
DeMeet 220, DeMeet



Edge detection and auto-focusing routine

CT scanner
Metrotom 1500, ZEISS



Acquisition of virtual points on reconstructed workpiece

REFERENCE MEASUREMENTS

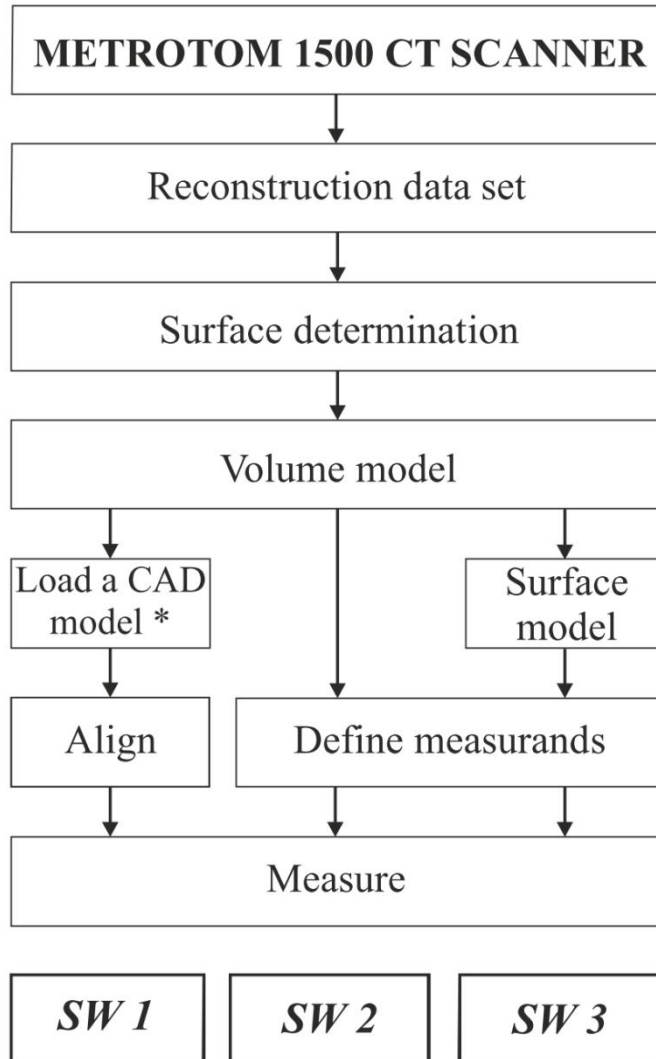
ACTUAL MEASUREMENTS

Measuring uncertainty evaluated according to GUM procedures as:

$$U_{CT} = k \cdot \sqrt{u_{ref}^2 + u_p^2 + u_e^2 + b^2}$$

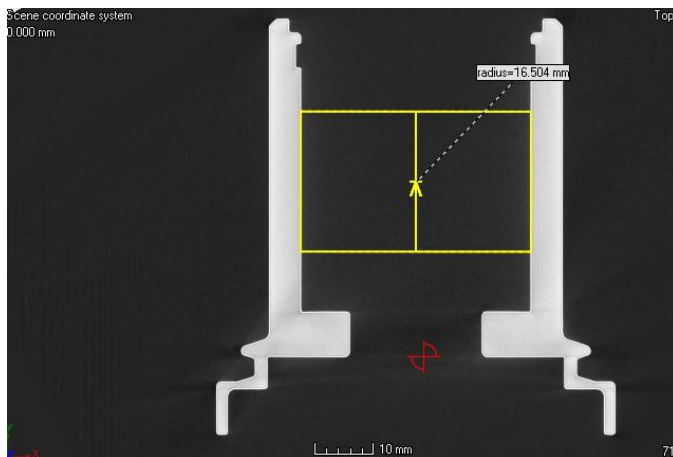
- k : coverage factor ($k = 2$ for a confidence interval of 95%);
- u_{ref} : standard uncertainty from reference measurements on tactile and optical CMM, respectively;
- u_p : standard uncertainty of the measuring procedure for each measurand, $u_p = h \cdot (s/\sqrt{n})$ where $n = 3$ and $s = 2.3$;
- u_e : temperature-related standard uncertainty calculated for a deviation of ± 0.5 °C from standard temperature. Coefficient of linear expansion for aluminum: $23 \cdot 10^{-6}$ °C⁻¹ and $49 \cdot 10^{-6}$ °C⁻¹ for LPC;
- b : Measurement bias from expected value of reference measurements.

Definition of measuring strategies



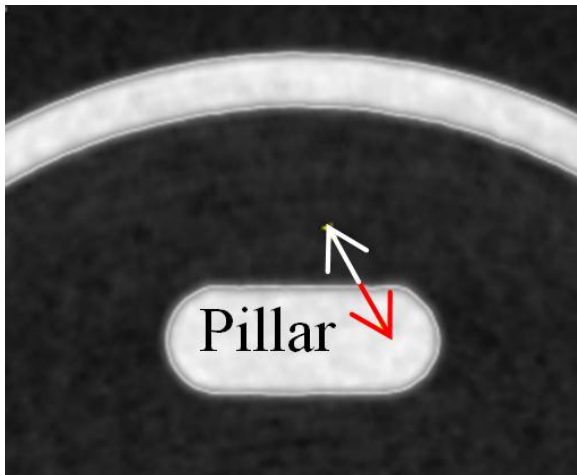
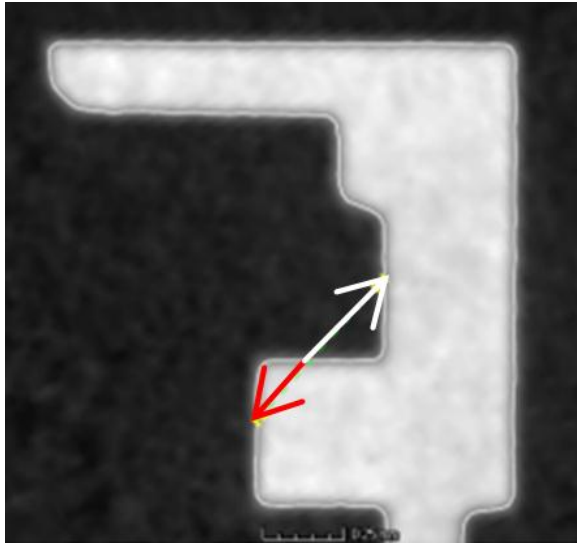
Software tool	Data set	Product
SW1	Voxel model / volume data	Calypso 4.8
SW2	Voxel model / volume data	VGStudio MAX 2.1
SW3	STL model / surface data	ATOS V7

Definition of measuring strategies



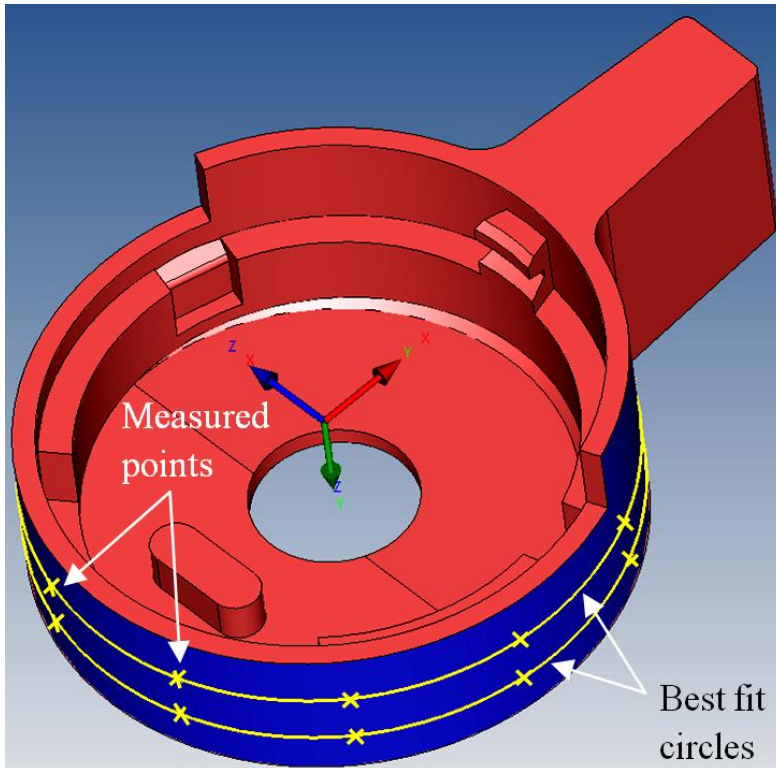
Measurand	SW1	SW2	SW3
Diameter (d_P , D_T)	Circle	Circle	Circle
	Spiral	Feature fit	Feature fit
	Recall	Cylinder circle	Cylinder circle
Distance (L_P) and Height (H_T)	Plane-Plane	Plane-Plane	Plane-Plane
	Point-Plane	Point-Plane	Point-Plane

Definition of measuring strategies



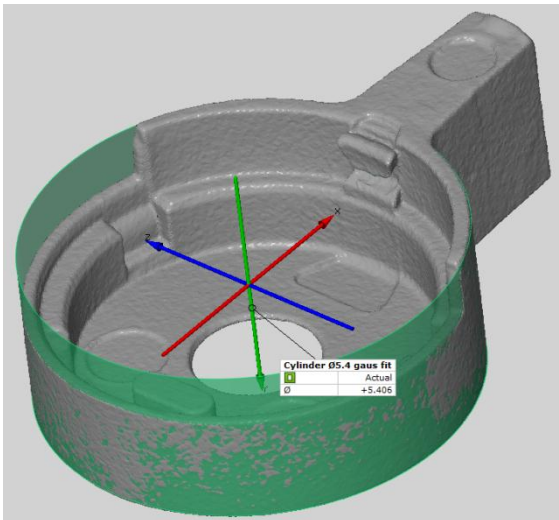
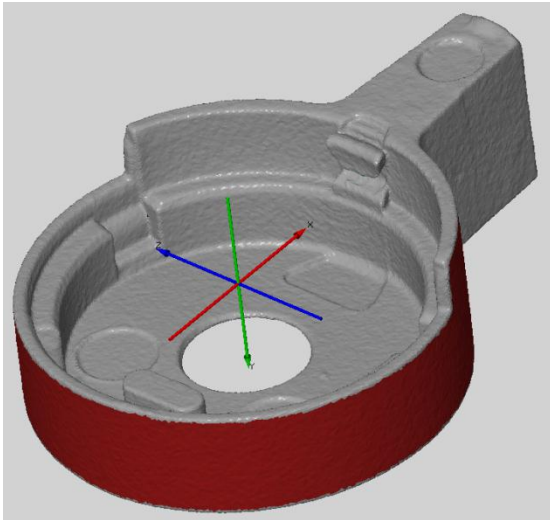
Measurand	SW1	SW2	SW3
Diameter (d_P , D_T)	Circle	Circle	Circle
	Spiral	Feature fit	Feature fit
	Recall	Cylinder circle	Cylinder circle
Distance (L_P) and Height (H_T)	Plane-Plane	Plane-Plane	Plane-Plane
	Point-Plane	Point-Plane	Point-Plane
Angle (α_P)	Circle	Circle	Circle
		Cylinder	Cylinder

Definition of measuring strategies



Measurand	SW1	SW2	SW3
Diameter (d_P , D_T)	Circle	Circle	Circle
	Spiral	Feature fit	Feature fit
	Recall	Cylinder circle	Cylinder circle
Distance (L_P) and Height (H_T)	Plane-Plane	Plane-Plane	Plane-Plane
	Point-Plane	Point-Plane	Point-Plane

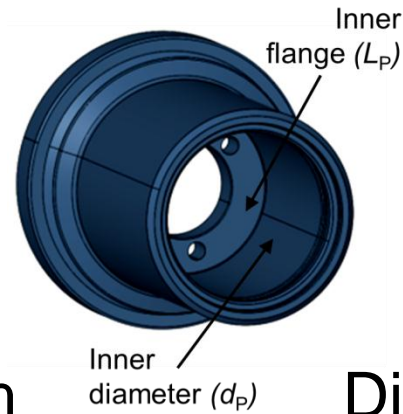
Definition of measuring strategies



Measurand	SW1	SW2	SW3
Diameter (d_P , D_T)	Circle	Circle	Circle
	Spiral	Feature fit	Feature fit
	Recall	Cylinder circle	Cylinder circle
Distance (L_P) and Height (H_T)	Plane-Plane	Plane-Plane	Plane-Plane
	Point-Plane	Point-Plane	Point-Plane

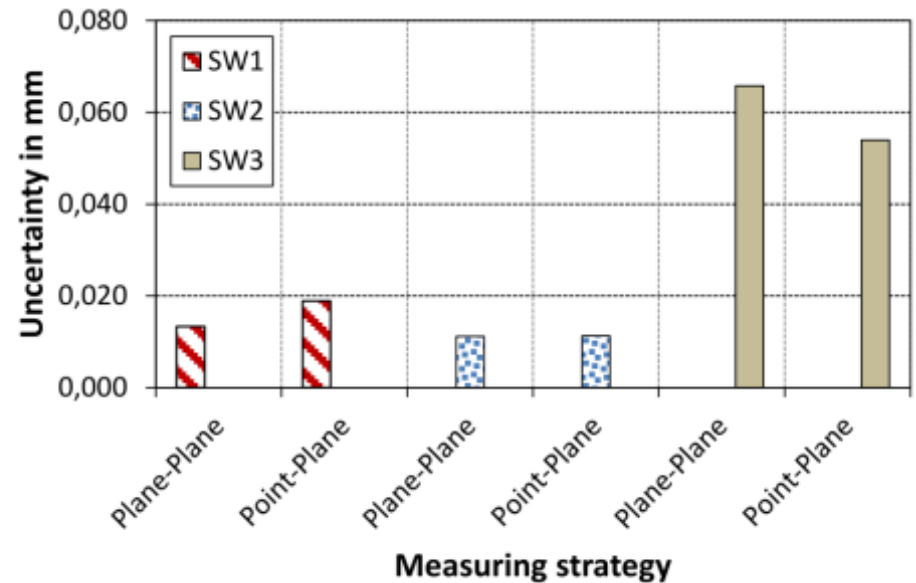
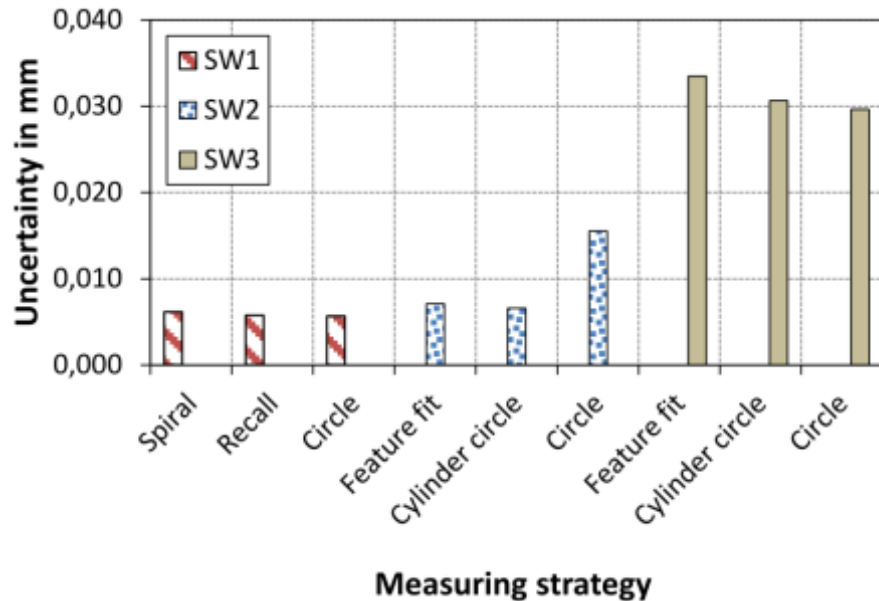
Results: Pipe connector

Voxel size: 108 μm

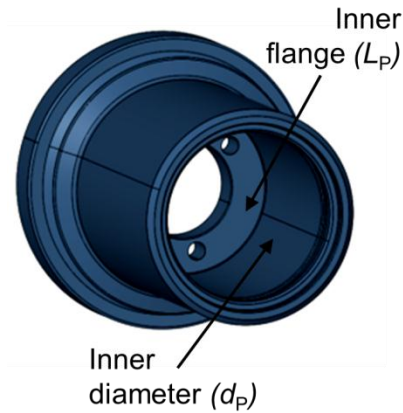


Diameter: $d_p = 33 \text{ mm}$

Distance: $L_p = 6.4 \text{ mm}$

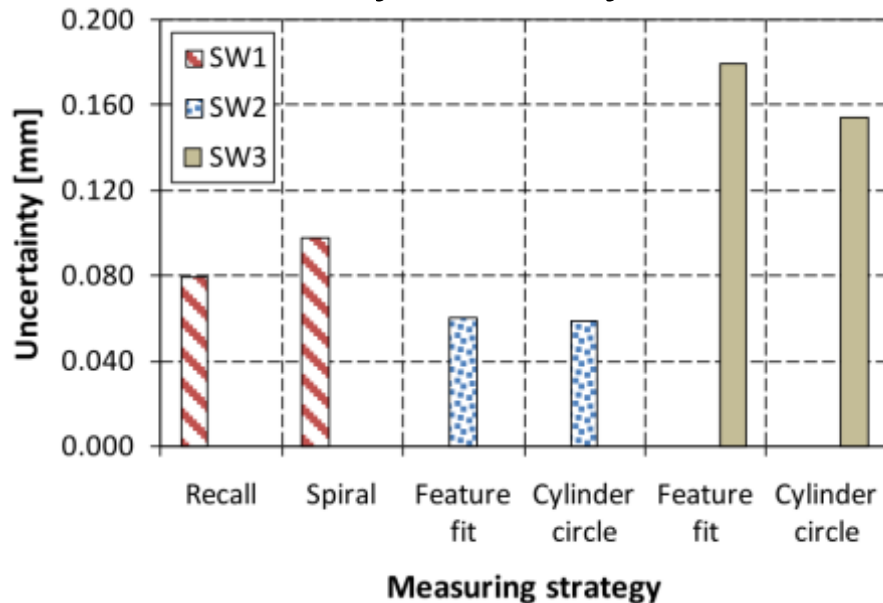


Results: Pipe connector

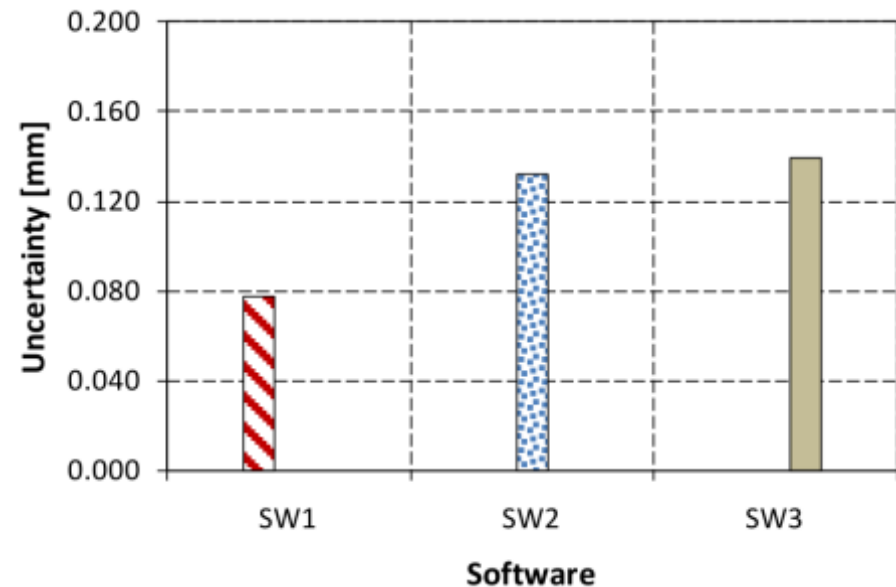


Voxel size: 108 μm

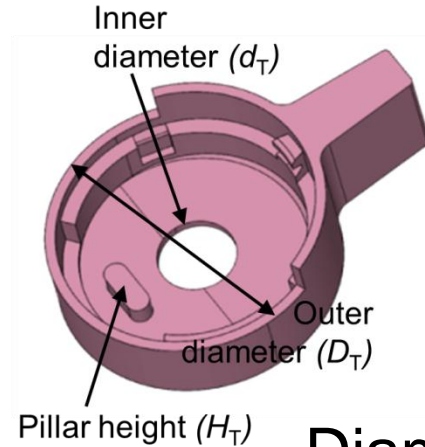
Cylindricity



Parallelism



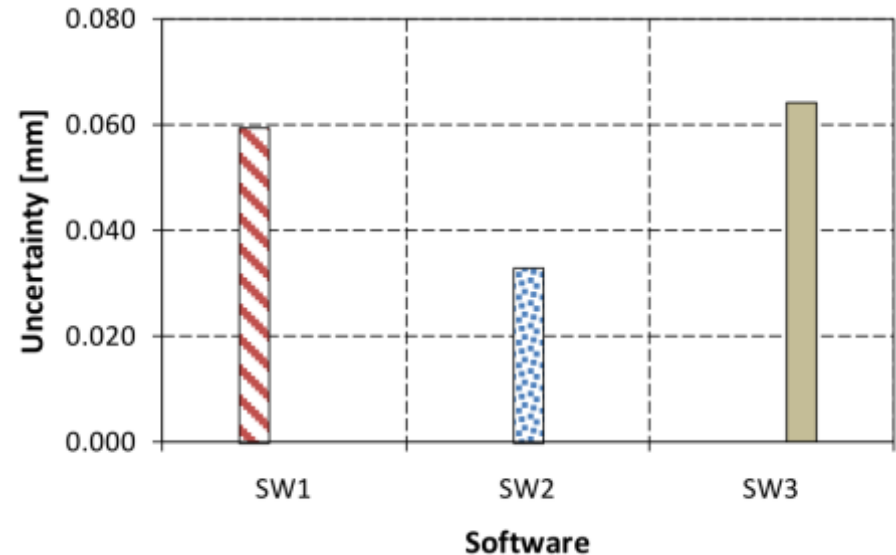
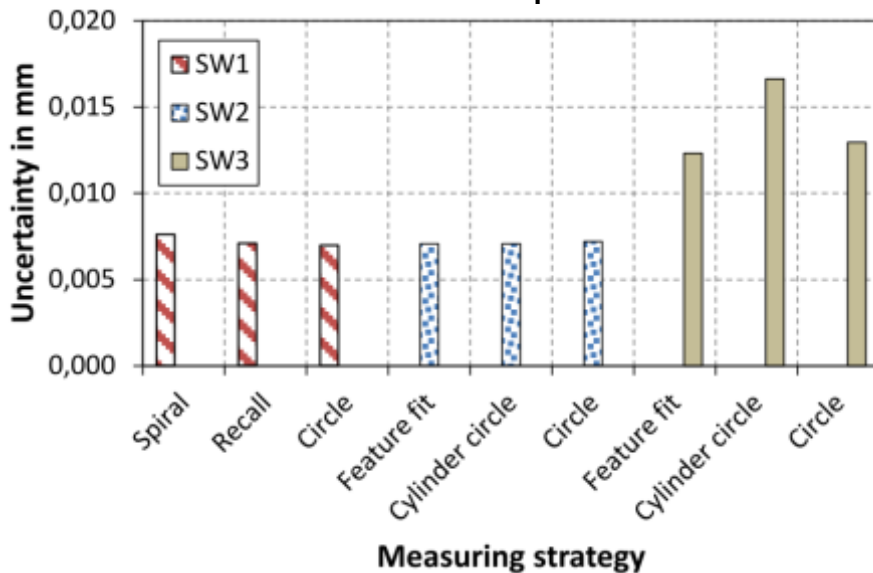
Results: Toggle



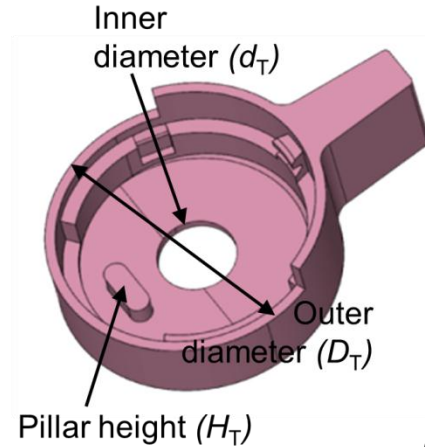
Voxel size: 19 μm

Diameter: $D_T = 5.4 \text{ mm}$

Diameter: $d_T = 1.55 \text{ mm}$



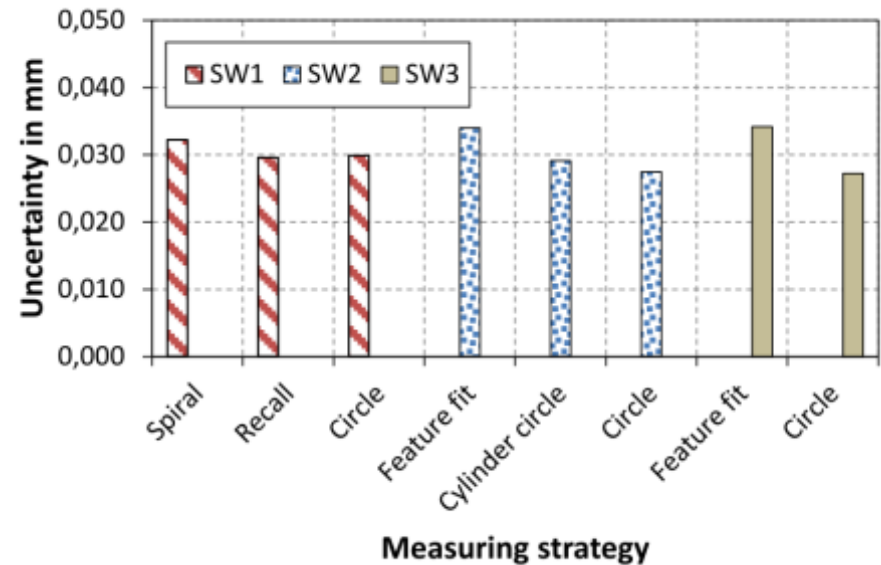
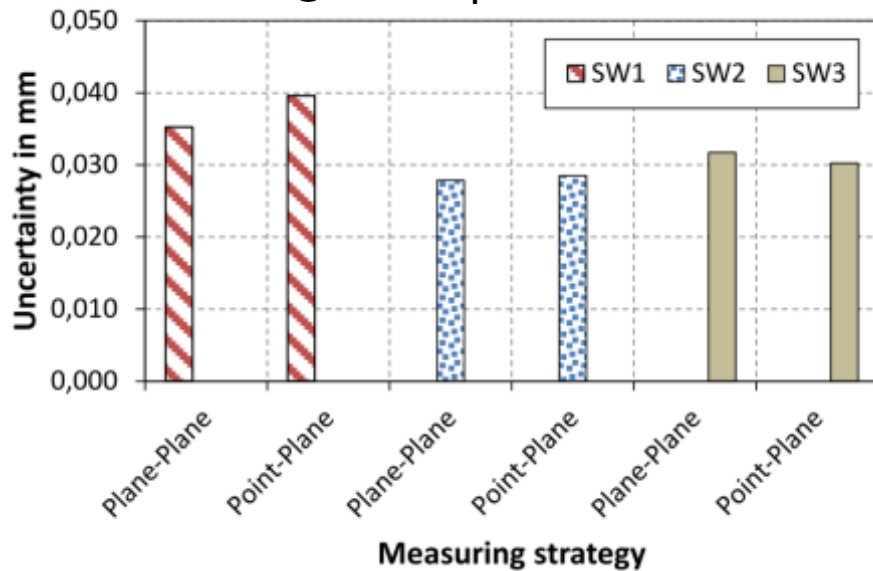
Results: Toggle



Voxel size: 19 μm

Height: $H_T = 0.38 \text{ mm}$

Concentricity



- Different measuring strategies were applied using 2 different CT data representations in 3 commercial inspection software tools to document its influence on selected measurands by the assessment of the measurement uncertainties.
- To estimate the task-specific measurement uncertainties the experimental method was used.
- Two industrial parts were used: a pipe connector and a toggle.

- Pipe connector (voxel size: 108 μm):
 - Using STL data in ATOS (SW3) the uncertainties for diameter, cylindricity, and distance measurements are significantly higher in contrast to uncertainties obtained using Calypso (SW1) and VG (SW2)
- Toggle (voxel size: 19 μm):
 - For the outer diameter D_T the uncertainties are significantly higher in contrast to uncertainties obtained using Calypso (SW1) and VG (SW2)
- The main contributor is the measurement bias ***b***

What can we say in general?

There are measuring strategies where the measurement uncertainty is twice as high compared to others!

Good practice:

Testing of different strategies in order to perform a relative comparison of the result of the measurements



Using traceable reference data for uncertainty estimations

THANK YOU FOR YOUR
ATTENTION