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<p>Title and author(s)</p> <p>Monte Carlo Superposition Calculations of Resonance Integrals in a Reactor Cell by Peter Kirkegaard</p>	<p>Date July 1970</p> <p>Department or group Reactor Physics Department</p> <p>Group's own registration number(s)</p>
<p>52 pages + 0 tables + 3 illustrations</p>	
<p>Abstract</p> <p>A description is given of a computer program, AEK P-598 MCSUP, which calculates the resonance integral for a single resonance in a square reactor lattice cell, containing a cylindrical fuel zone surrounded by a moderator zone. The fuel zone contains only one nuclide type, while the moderator may be composed by several nuclide types. Scattering interference and Doppler broadening is included.</p> <p>MCSUP is a Monte Carlo code based on the superposition method devised by Spanier and Gelbard. The code is well-suited for calculations on isolated fuel rods. It is written in FORTRAN IV.</p>	<p>Copies to</p> <p>Standard distribution</p> <p>Abstract to</p>
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1. INTRODUCTION

In a forthcoming report, Mikkelsen ¹⁾ describes a computer program RESAB which carries out a multigroup calculation of the resonance absorption and flux spectrum in a reactor cell, using collision probability technique. His calculation scheme relies on the validity of certain approximations making possible very efficient computing. In developing such an approximate model there arises a natural need of checking the model or parts of it against some exact calculation method; in view of the complexity of the problem Monte Carlo seems to be the only practical way of performing such reference calculations.

This paper describes a Monte Carlo FORTRAN IV computer program, AEK P-598 MCSUP, designed to calculate resonance integrals by the method of superposition. The superposition principle was developed and first put into practical operation by Spanier and Gelbard ^{2,3)}. MCSUP works fairly efficiently for most problems, and it is possible that it may be valuable also for other purposes than comparative.

2. STATEMENT OF THE PROBLEM

Consider an infinite-cylindrical reactor lattice cell with a cross-section as shown in fig. 1. The heterogeneous resonance capture problem is idealized to a two-zone configuration, the cladding zone being neglected. The fuel cylinder radius is a , and the lattice pitch is denoted d . The cross sectional areas of the two zones are $A_1 = \pi a^2$ and $A_2 = d^2 - A_1$.

The fuel zone contains only one isotope (e. g. U-238), while the moderator may be composed of several media types. Scattering in the fuel is assumed to proceed isotropically in the L-system, scattering in the moderator isotropically in the L-system or in the CM-system depending on the user's choice. No absorption is allowed in the moderator. The cell is assumed to be a part of an infinite lattice, so that the boundary scattering boundary conditions are neglected in terms of the resonance capture probabilities. The resonance integrals are calculated by the self-starting method.

where $\langle \sigma_s \rangle$ is the average slowing-down power of the cell per absorber atom⁹⁾.

The energy band taken into account is the interval $E_L \leq E \leq E_U$ containing the resonance energy E_0 . We assume that the flux at the upper energy cut-off is an unperturbed $1/E$ -flux. The resonance absorption mechanism to be considered here concerns a single resolved resonance. The resonance cross sections are expressed by the single level Breit-Wigner formulas and include the scattering interference and Doppler broadening.

The scattering cross section of the moderator is assumed to be independent of the energy.

3. THE RESONANCE CROSS SECTIONS

The total microscopic cross section σ_t of the resonance absorber may be written as a sum of a resonance cross section and an energy-independent potential scattering cross section:

$$\sigma_t = \sigma_r + \sigma_p \quad (2)$$

The resonance cross section itself is composed by an absorbing and a scattering component

$$\sigma_r = \sigma_a + \sigma_{rs} \quad (3)$$

The expression for σ_a and σ_{rs} read^{1,4)}
 $\sigma_a(E) = \sigma_0 \frac{\Gamma}{\Gamma^2 + (E - E_0)^2} \sqrt{\frac{E}{E_0}} \cdot \eta \cdot u(E) \cdot \sqrt{\frac{E - E_0}{E}}$
 $\sigma_{rs}(E) = \sigma_0 \frac{\Gamma}{\Gamma^2 + (E - E_0)^2} \sqrt{\frac{E}{E_0}} \cdot \eta \cdot u(E) \cdot \sqrt{\frac{E - E_0}{E}} \cdot \frac{v}{u} \cdot \frac{1}{2} \left[1 + \frac{v}{u} \right]$
where $\sigma_0 = \frac{4\pi}{3} \frac{A^2}{kT} \frac{1}{E_0}$ and $\eta = \frac{A}{2kT} \frac{1}{E_0}$.
The parameter η is the Doppler broadening parameter. The parameter v/u is the scattering to absorption ratio. The parameter u is the real part of the complex error function. The parameter v is the imaginary part of the complex error function. The parameter χ is the scattering interference parameter. The parameter ϕ is the scattering interference phase. The parameter χ and ϕ are defined by the relations $\chi(\theta, x) = 2\sqrt{\pi} \eta v$ and $\phi(\theta, x) = \sqrt{\pi} \eta u$.

$$\eta = \sqrt{\frac{A^2}{16 kT E_0}} \quad \left[\frac{1}{\chi(\theta, x)} \right] \exp - \quad (4)$$

$u + iv = w$ is the value of the complex error function corresponding to the argument $2\eta \frac{E - E_0}{\Gamma} + i\eta$. The complex error function may be defined by¹¹⁾

$$\text{erf}(z) = \text{erf}(x+iy) = \exp(-z^2) \left[1 + \frac{2i}{\sqrt{\pi}} \int_0^z \exp(t^2) dt \right] \quad (7)$$

Γ_n , Γ_v and Γ are the neutron, radiative and total widths of the level, respectively. The parameter σ_0 is the value of σ_r for $E = E_0$. It can be shown that¹⁾

$$\sigma_0 = 2.603 \cdot 10^6 \left(\frac{1.00897 + A}{A} \right)^2 \cdot \frac{\Gamma_n}{\Gamma} \cdot \frac{1}{E_0} \quad (8)$$

The remaining parameters to be defined is A , the atomic weight of the absorber; k is Boltzmann's constant $k = 8.61 \cdot 10^{-5} \text{ eV/}^\circ\text{K}$, and T is the absolute temperature.

u and v are connected with the well-known formulas $\phi(\theta, x)$ and $\chi(\theta, x)$ defined in Dresner⁴⁾, by the relations

$$\phi(\theta, x) = \sqrt{\pi} \eta u \quad (9)$$

$$\chi(\theta, x) = 2\sqrt{\pi} \eta v \quad (10)$$

where $x = \frac{E - E_0}{\Gamma}$ and $\theta = 2\eta$.
 $\eta = \frac{A}{2kT} \frac{1}{E_0}$

In this work, the code was made of a FORTRAN IV version¹³⁾ of a code written in the FORTRAN III and IV¹⁴⁾ languages. The code is intended for computing the scattering cross sections developed by Dresner⁴⁾. The scattering cross sections are calculated as a function of the energy of the neutron. The code is self-contained and does not require any other programs. The code is written in FORTRAN IV and is suitable for use on any computer which can execute FORTRAN IV programs.

4. THE SUPERPOSITION PRINCIPLE

In this section we shall mainly follow Spanier and Gelbard²⁾ in giving a brief exposition of the superposition principle when applied to resonance absorption calculations.

The superposition principle states that the flux produced by the sum of two sources is the sum of the fluxes produced, separately, by each source. This follows immediately from the linearity of the transport equation. The idea is now that the problem to be solved ("problem α ") is superimposed by another problem ("problem β ") in such a way that the sum problem has a simple analytical solution. Hence, the Monte Carlo work is confined to problem β , and sometimes this method of attack leads to significant reduction of variance.

This basic approach has to be extended a little in order to yield an efficient model for resonance calculations. Consider again fig. 1 showing the fuel zone R_I and the moderator zone R_{II} with a reflecting boundary. As before we wish to solve problem α . The source $Q_\alpha(E, r)$ in this problem is a slowing-in density in both zones from above E_u . Problem α has the solution (angular flux) $F_\alpha = F_\alpha(E, r, \omega)$, where E is energy, r position, and ω the unit vector of direction. Above E_u , F_α is assumed to be the unperturbed $1/E$ -flux. We normalize in such a way that $F_\alpha = \frac{1}{4\pi E}$ for $E > E_u$.

In the following it is essential to distinguish between resonance and potential scattering in the fuel. The macroscopic fuel cross section is therefore considered as composed by one absorption and two scattering terms:

$$\Sigma_{Tf}(E) = \Sigma_{af}(E) + \Sigma_{sf}(E) = \Sigma_{af}(E) + \Sigma_{srf}(E) + \Sigma_{pf}(E) = \Sigma_{rf}(E) + \Sigma_{pf}(E) \quad (11)$$

We now define a problem β with the same geometry but with a source $Q_\beta(E, r)$ in the moderator. The operator cross sections are calculated in the interval $E_u > E > E_r$ before the Monte Carlo work in the fuel. No source is present in the moderator. Let the problem β

have the solution F_β .

The sum problem of α and β has the solution F_T . Now, it is not F_T itself that has a simple expression but that part of it, F_{Tu} , which has not yet undergone resonance scatterings. In fact,

$$F_{Tu}(E, r, \omega) = \frac{1}{4\pi E}, \quad E_L \leftarrow E \leftarrow E_u \quad (13)$$

To see this we write down the transport equations satisfied by F_{Tu} in R_I and R_{II} :

$$L F_{Tu}(E, r, \omega) = \int d\omega' \int_{E_L}^{E_u} dE' \Sigma_{Pf}(\omega, \omega', E' - E, r) F_{Tu}(E', r, \omega') + \frac{1}{4\pi} Q_\beta(E, r) + \frac{1}{4\pi} Q_f(E), \quad r \in R_I$$

and

$$L F_{Tu}(E, r, \omega) = \int d\omega' \int_{E_L}^{E_u} dE' \Sigma_S(\omega, \omega', E' - E, r) F_{Tu}(E', r, \omega') + \frac{1}{4\pi} Q_S(E, r), \quad r \in R_{II} \quad (14)$$

$\Sigma_{Pf}(\omega, \omega', E' - E, r)$ is the differential cross section for potential scattering in the fuel. The operator L is defined by

$$L F = \Sigma_{Tf} F - \Sigma_{sf} F = \Sigma_{af} F + \Sigma_{srf} F - \Sigma_{sf} F = \Sigma_{af} F + \Sigma_{srf} F - \Sigma_{srf} F = \Sigma_{af} F \quad (27)$$

Otherwise the notation is conventional.

(28) In (14) all scattering cross sections are energy independent. This is a simplification of (14) and (15) for the purpose of the present work. The actual energy dependence is neglected in the present work.

$$F_{\alpha} = F_{Tu} + F_{TS} - F_{\beta} = \frac{1}{4\pi E} + F_{TS} - F_{\beta} \quad (16)$$

It is now practical to split up F_{β} into four components, according to the history of the flux. Let

$$\begin{aligned} F_{\beta} = & F_{\beta} \text{ (unscattered before exit, unreturned)} \\ & + F_{\beta} \text{ (unscattered before exit, returned)} \\ & + F_{\beta} \text{ (resonance scattered before exit)} \\ & + F_{\beta} \text{ (potential scattered before exit), or} \end{aligned}$$

$$F_{\beta} = F_{\beta uu} + F_{\beta ur} + F_{\beta sr} + F_{\beta sp} \quad (17)$$

"Exit" means here absorption in or escape from the fuel. By (16) and (17),

$$F_{\alpha} = \frac{1}{4\pi E} - F_{\beta uu} - F_{\beta ur} - F_{\beta sp} + F_{TS} - F_{\beta sr} \quad (18)$$

We are interested in calculating the resonance capture probability $1-p$, or, equivalently, the mean absorption rate per ccm in the fuel

$$A_T = \frac{1}{A_1} \int_{E_L}^{E_u} dE \int_I dr \Sigma_{af} \Phi_{\alpha}(E, r) \quad (19)$$

where Φ , of course, stands for a scalar flux and I symbolizes the two-dimensional fuel region R_1 . The connection between A_T and $1-p$ is

$$1-p = \frac{A_T}{\Sigma_{af}} \quad (20)$$

where Σ_{af} is the macroscopic absorption cross-section of the fuel.

$\langle \Sigma_{af} \rangle$ is the average over energy and space of Σ_{af} corresponding to $\Phi_{\alpha}(E, r)$ and is expressed as $\langle \Sigma_{af} \rangle = \frac{A_T}{\int_{E_L}^{E_u} dE \int_I dr \Phi_{\alpha}(E, r)}$

$$\langle \Sigma_{af} \rangle = \frac{NA_1 \langle \Sigma_{af} \rangle}{A_1 + A_2} \quad (21)$$

where N is the number density of the absorber.

Defining

$$I'_0 = \frac{1}{A_1} \int_{E_L}^{E_u} dE \int_I dr \Sigma_{af}(E) \left[\frac{1}{E} - \Phi_{\beta uu}(E, r) \right] \quad (22)$$

$$I'_1 = \frac{1}{A_1} \int_{E_L}^{E_u} dE \int_I dr \Sigma_{af}(E) \Phi_{\beta ur}(E, r) \quad (23)$$

$$I_2 = \frac{1}{A_1} \int_{E_L}^{E_u} dE \int_I dr \Sigma_{af}(E) \Phi_{\beta sp}(E, r) \quad (24)$$

$$J = \frac{1}{A_1} \int_{E_L}^{E_u} dE \int_I dr \Sigma_{af}(E) \left[\Phi_{TS}(E, r) - \Phi_{\beta sr} \right] \quad (25)$$

then

$$A_T = I'_0 - I'_1 - I_2 + J \quad (26)$$

It can be shown that

$$I'_0 = \int_{E_L}^{E_u} dE \Sigma_{af}(E) \left[P_0(E) + \frac{P_1}{\Sigma_{af}(E)} (1 - P_0(E)) \right] \quad (27)$$

where $P_0(E)$ is the escape probability from the fuel region R_1 and P_1 is the collision probability from fuel to moderator. P_1 can be expressed in terms of $P_0(E)$ and $\Sigma_{af}(E)$. The quantity is discussed in detail in the literature.

It can be shown that I'_1 is the absorption rate produced by an outgoing source on the surface of the fuel

$$Q_{1P}(E, \omega) = \frac{\Sigma_{rf}(E)}{4\pi E} \frac{\mu(1 - \exp(-l \cdot \Sigma_{Tf}(E)))}{\Sigma_{Tf}(E)} \quad (28)$$

Here, $\mu = \omega \cdot n > 0$, n being the outward unit normal at the surface point P , and l is the backward intersection path from P in the fuel (due to the scattering interference, $Q_{1P}(E, \omega)$ may become negative at some energies, this tending to increase variance somewhat). Integrating (28) over directions gives $Q'_1(E) = \int Q_{1P}(E, \omega) d\omega$, which is proportional to the density function for selecting starting energies. It follows that ²⁾

$$Q'_1(E) = \frac{\Sigma_{rf}(E)}{E} \cdot P_0(E) \quad (29)$$

The Monte Carlo calculation of I'_1 includes such starters which have been absorbed on their first collision. This contribution will in our model be deleted from I'_1 and included in the deterministic term I'_0 . In other words, we write

$$I'_0 - I'_1 = I_0 - I_1 \quad (30)$$

where now I_0 is to be evaluated deterministically and I_1 by Monte Carlo. One can show that ²⁾

$$I_0 = \int_{E_L}^{E_U} \frac{dE}{E} \Sigma_{af}(E) \left[P^*(E) + \frac{\Sigma_{Pf}}{\Sigma_{Tf}(E)} (1 - P^*(E)) \right] \quad (31)$$

where P^* is the collision probability ^{2, 6)} from fuel to moderator. P^* is discussed in Appendix V, and the quadrature evaluation of I_0 in Appendix VI. Going from I'_1 to I_1 (28) is changed to ²⁾

$$Q_1(E) = \frac{\Sigma_{rf}(E)}{E} \left[P_0(E) - \frac{\Sigma_{af}(E)}{\Sigma_{Tf}(E)} (P_0(E) - P^*(E)) \right] \quad (32)$$

Hence, to sample I_1 we have to pick the starting energy from (32) and then sample an ω from (28). How these steps are carried out in detail is discussed in sec. 5. However, if a starter is absorbed on its first collision, it is rejected; a new ω is sampled from (28) without changing E .

The next term in (26), I_2 , is generated by neutrons which are potential scattered before exit. The mean rate of such scatterings are

$$Q_2(E) = \frac{\Sigma_{rf}(E)}{E} (1 - P_0(E)) \frac{\Sigma_{Pf}}{\Sigma_{Tf}(E)} \quad (33)$$

From $|Q_2(E)|$ we pick a starting energy. Then a starting point P is selected uniformly in the fuel and an ω with isotropic distribution. If the starter leaves the fuel on its first flight it is rejected; without changing E we sample a new P and a new ω . Otherwise we regard its first collision as a potential scattering. Subsequent sampling proceed conventionally.

The last term to be computed by Monte Carlo is J (eq. (25)). We show that this term requires two Monte Carlos. Let us define

$$F_{AS} = F_{TS} - F_{\beta Sr} \quad (34)$$

By writing down the transport equations for F_{TS} and $F_{\beta Sr}$ one sees that F_{AS} satisfies the equations

$L F_{AS}(E, r, \omega) = \int d\omega' \int dV' \Sigma_{Tf}(r, \omega', E) F_{AS}(E, r', \omega')$
The first history uses a sample value ξ_1 for ξ and the second history uses $\xi_2 = 1 - \xi_1$. The third history uses a new sample value ξ_3 that is independent of the first two. The Monte Carlo method is applied here in a very efficient way to obtain variance reduction: the first history uses a sample value ξ_1 for ξ and the second history uses $\xi_2 = 1 - \xi_1$. The third history uses a new sample value ξ_3 that is independent of the first two. The Monte Carlo method is applied here in a very efficient way to obtain variance reduction: the first history uses a sample value ξ_1 for ξ and the second history uses $\xi_2 = 1 - \xi_1$. The third history uses a new sample value ξ_3 that is independent of the first two.

$$L F_{\Delta S}(E, r, \omega) = \int d\omega' \int_{E_L}^{E_U} dE' \Sigma_S(\omega, \omega', E' \rightarrow E, r) F_{\Delta S}(E', r, \omega'),$$

$$r \in R_{II} \quad (35)$$

Hence, $F_{\Delta S}$ is generated by resonance scattering in R_I in the flux $F_{Tu} - F_{\beta uu}$. One can show that this latter quantity itself satisfies a transport equation,

$$L [F_{Tu}(E, r, \omega) - F_{\beta uu}(E, r, \omega)] = \frac{\Sigma_{PI}}{4\pi E}, \quad r \in R_I \quad (36)$$

and

$$F_{Tu}(E, r_P, \omega) - F_{\beta uu}(E, r_P, \omega) = \frac{1}{4\pi E} \quad (37)$$

where r_P is a point of the fuel-moderator interface, and ω is an inward direction ($\omega \cdot n < 0$).

Eqs. (36) and (37) reflect the fact that $F_{Tu} - F_{\beta uu}$ is produced by the joint action of a uniform isotropic volume source $\Sigma_{PI}/4\pi E$ and an inward-directed surface source with strength $\omega \cdot n/4\pi E$.

This leads to the following procedure for the calculation of the corresponding components, I_3 and I_4 , of J . In the I_3 -case we write

$$Q_3(E) = \frac{\Sigma_{PI}}{E} (1 - P_0(E)) \frac{F_{Su}(E)}{F_{Tu}(E)}, \quad (38)$$

select an energy from $|Q_3(E)|$ and proceed just as in the I_2 -case (cf. eq. (33) et seq.), but here we force the starter to resonance-scatter in the fuel.

In the I_4 -case we write

$$Q_4(E) = \frac{F_{Su}(E)}{F_{Tu}(E)} \quad (39)$$

select an energy from $|Q_4(E)|$ and a starting point from a distribution uniform over the surface. The starting direction has to be inward, but

otherwise this sampling is quite analogous to the I_1 -case. The first collision is forced to be a resonance scattering in R_I . Hereafter, the sampling proceeds conventionally.

To recapitulate, we have expressed the rate of absorption A_f as a sum of five terms

$$A_f = I_0 - I_1 - I_2 + I_3 + I_4 \quad (40)$$

where I_0 can be evaluated by quadrature, but I_1, I_2, I_3, I_4 each requires one Monte Carlo. In the following section we discuss some problems in connection with the Monte Carlo sampling.

5. MONTE CARLO SAMPLING IN MCSUP

5.1. Sampling of Initial Energy

From the formulas (32), (33), (38), (39), it is seen that the Monte Carlo for each of the four terms I_1, I_2, I_3, I_4 , requires an initial energy sampling from a density function proportional to some known function $Q(E)$. How this is done is shown schematically in fig. 2. $Q(E)$ is approximated by a step function corresponding to a division of the energy interval $E_L \leq E \leq E_U$ in 1000 equal subintervals (only 8 shown in fig. 2) with step heights equal to $Q(E)$ taken in the subinterval midpoints. This matches the discrete cross-section evaluation mentioned in sec. 3. The step function is normalized to a density function and is next converted to a distribution function $F(E)$ of the polygon type. After selection of a random number ξ , E is given by $F^{-1}(\xi)$.

To increase speed we prefer not to use F itself, but the nearest discrete representation ξ_i corresponding to a division of the interval $0 < \xi < 1$ in 1000 equal subintervals (only 8 shown in fig. 2). The values $\xi_i = F^{-1}(\xi_i)$ are calculated and stored before the Monte Carlo is executed. Of course, this procedure involves a sacrifice in accuracy.

As pointed out in ref. 2 the technique of arithmetic variables is applied here in a very simple way to obtain very fast random numbers. The history files contain values ξ_i after the calculation of F . The values ξ_i are used for calculation of $F^{-1}(\xi_i)$ and F is then used to generate ξ_i and F is then used to generate ξ_i . This technique was first introduced by...

5.2. Surface Source Sampling

Having selected the initial energy one turns to sample the source position and direction. Starters of types 2 and 3 (cf. sec. 4) have an isotropic and uniform volume distribution which is easily sampled, while the types 1 and 4 have an outgoing, resp. ingoing surface source distribution, which is considered in more detail now. As the surface positions are selected from a uniform distribution, we need only discuss the direction sampling. Because the sampling is quite similar in the two cases, we consider only the outgoing source (type 1).

The relevant sampling formula is (28), which now, when position and energy is known, reduces to

$$Q(\omega) = \mu [1 - \exp(-l(\omega) \cdot \Sigma)] \quad (41)$$

apart from a constant factor. As before, $\mu = \omega \cdot n$, and $l(\omega)$ is the back-wards intersection path in the fuel.

A straightforward way would be to sample ω from either an isotropic or a cosine distribution and adjust the weight of the starter according to (41). Fluctuating weights have, however, a deleterious influence on variance, unless the fluctuations reflect the importance of the events²⁾.

A better alternative seems here to be a cosine sampling combined with rejection^{2, 19)}. As we then sample from a distribution proportional to μ , the quantity in square brackets in (41) governs the rejection. Hence we pick a random number ζ and accepts or rejects the starter according to the events $1 - \exp(-l(\omega) \cdot \Sigma) \geq \zeta$. In case of rejection a new ω -sampling is carried out. The efficiency for this rejection is supposed to be high, because the rod for most initial energies is fairly black²⁾.

5.3. Coveyou Sampling from Truncated Exponential

As mentioned in sec. 4, starters of type 4 are forced to resonance-scatter in the fuel. This leads naturally to sampling from a truncated exponential with the density function

$$f(x) = \frac{e^{-x}}{1 - e^{-1}} \quad 0 \leq x \leq 1 \quad (42)$$

where 1 is the path from the source point to the rod intersection point along the flight. With a random number ζ , the standard sampling formula corresponding to (42) becomes

$$x = -\frac{1}{\Sigma} \log \left[1 - \zeta (1 - \exp(-\Sigma)) \right] \quad (43)$$

involving both a log- and an exp-calculation. Here, an alternative sampling formula due to Coveyou is used^{2, 16, 20)}:

$$x = \frac{1}{\Sigma} \text{UDR} \left[\frac{-\log \zeta}{\Sigma} \right] \quad (44)$$

UDR stands for the undivided remainder, e.g. $\text{UDR} \left(\frac{13.83}{6} \right) = 1.83$.

5.4. Conventional Transport Sampling

Apart from the special methods discussed above and the choice of estimator (see 5.5), the sampling of the neutron transport and energy degradation processes elapses quite conventionally and will not be discussed here; details will be found elsewhere^{2, 14, 16)}. However, it should be quite easy to follow the various steps on the computer code print-out reproduced in Appendix III; it is hoped that the rather numerous comments will facilitate this work.

5.5. Choice of Estimator

Before the program reached its final form, some experimentation was done to find an efficient estimator for the resonance absorption. Three estimators were tried.

- 1) The Wasov estimator²⁾ with forbidden absorption and corresponding weight reductions at collisions. History termination only by energy degradation.

- 2) The analog estimator²⁾, which is substantially independent of Γ for a

- 3) The modified track length estimator.

From our calculations it is clear that the modified track length estimator is the most efficient. This estimator was first introduced by...

track length estimator refers to an analog random walk process. Scoring takes place every time a neutron collides in, or escape from the fuel, after the following rule:

- a) When a neutron starts at the fuel point P (a source or scattering point, or a point on the fuel boundary) and thereafter escapes uncollided at E or scatters at S, then the scoring is $\Sigma_a \cdot d$ where d is the track length PE or PS.
- b) When a neutron starts at the fuel point P and is absorbed in the fuel at A (whereby the history is terminated), then the scoring is

$$\frac{\Sigma_a}{\Sigma_t} \cdot \frac{1 - \exp(-\Sigma_t d) \{ \Sigma_t d + 1 \}}{1 - \exp(-\Sigma_t d)} \quad (45)$$

where d = PE, E denoting the hypothetic escape point if no collision had occurred. (45) is constructed by averaging the estimator $\Sigma_a \cdot PA$ over all possible A².

5.6. Statistical Processing

In order to carry out a statistical analysis of the Monte Carlo data, histories are collected in groups of 500 each. How many groups that are processed depends on the user's choice of computing time (see 6.1). Group averages are calculated, and from these a final average and a sample variance is found (a confidence analysis based on Student's distribution is not carried out). Finally, the "statistical quality" Q is calculated (see 6.2).

The statistical procedure has to be modified a little by the introduction of the optimization device discussed in Appendix VIII.

6. CALCULATION WITH THE MCSUP PROGRAM

6.1. Preparation of Input Data

Input data for the FORTRAN IV program P-598 MCSUP is prepared according to the input data given in Appendix I. This program is used for a single problem calculation (a user when using the program will see a message and a row with

pure hydrogen as the moderator, and anisotropic moderator scattering is taken into account. Format and type of data items are derived from the sheet. The first item is the problem no; a negative problem no. stops the computations. The two integers in the next line are: random initial number (any nine-digit integer will do) and the number m of different nuclide types in the moderator (here m = 1). The next two lines in the sheet contain real numbers; they are (in the notation previously used): $E_n, E_u, E_L, \sigma_p, \Gamma_n, \Gamma_\gamma, A, T, a, d$, number density of absorber $\times 10^{24}$, maximum time t_{max} . All energies are in eV. t_{max} is given in minutes and refers to the time spent in the Monte Carlo phase of the problem; to be safe, the user should not choose a t_{max} greater than $t_{job} - 2$ where t_{job} is the maximum time in minutes stated on the job request card (this rule is relevant for calculations on the IBM 7094 at NEUCC in Denmark; modifications may be necessary for other computing centers). Hereafter come m data lines, one for each nuclide type in the moderator. Each line contains three real numbers and one integer: atomic weight, cross section (barn), number density $\times 10^{24}$, and the scattering mode I which is 0 for isotropic scattering on that nuclide and 1 for anisotropic scattering.

As here only a single job is to be executed, one has written -1 in the last line.

6.2. Interpretation of Output

The result for the sample problem given by the input data in Appendix I appears in Appendix II.

The output interpretation should follow immediately from the text given. It remains only to define the "statistical quality" Q:

$$Q = \frac{Res^2}{\sigma^2} \cdot \frac{1}{Res}$$

where Res is the output quantity and σ is the standard deviation. t is the computer time consumed (sec). Q is substantially independent of t for a fixed computer and for a fixed number of groups. It is a function of the history length based on 500 or more. The MCSUP program has a group size of 100; due to this the error is increased by the negative starters this is too small for the group averaging to be effective in the normal distribution of the statistical analysis results. The program has a group size of 100 has an error of 10% in the output results.

1	1	1	1
2	1	1	1
3	1	1	1
4	1	1	1
5	1	1	1
6	1	1	1
7	1	1	1
8	1	1	1
9	1	1	1
10	1	1	1
11	1	1	1
12	1	1	1
13	1	1	1
14	1	1	1
15	1	1	1
16	1	1	1
17	1	1	1
18	1	1	1
19	1	1	1
20	1	1	1
21	1	1	1
22	1	1	1
23	1	1	1
24	1	1	1
25	1	1	1
26	1	1	1
27	1	1	1
28	1	1	1
29	1	1	1
30	1	1	1
31	1	1	1
32	1	1	1
33	1	1	1
34	1	1	1
35	1	1	1
36	1	1	1
37	1	1	1
38	1	1	1
39	1	1	1
40	1	1	1
41	1	1	1
42	1	1	1
43	1	1	1
44	1	1	1
45	1	1	1
46	1	1	1
47	1	1	1
48	1	1	1
49	1	1	1
50	1	1	1
51	1	1	1
52	1	1	1
53	1	1	1
54	1	1	1
55	1	1	1
56	1	1	1
57	1	1	1
58	1	1	1
59	1	1	1
60	1	1	1
61	1	1	1
62	1	1	1
63	1	1	1
64	1	1	1
65	1	1	1
66	1	1	1
67	1	1	1
68	1	1	1
69	1	1	1
70	1	1	1
71	1	1	1
72	1	1	1
73	1	1	1
74	1	1	1
75	1	1	1
76	1	1	1
77	1	1	1
78	1	1	1
79	1	1	1
80	1	1	1
81	1	1	1
82	1	1	1
83	1	1	1
84	1	1	1
85	1	1	1
86	1	1	1
87	1	1	1
88	1	1	1
89	1	1	1
90	1	1	1
91	1	1	1
92	1	1	1
93	1	1	1
94	1	1	1
95	1	1	1
96	1	1	1
97	1	1	1
98	1	1	1
99	1	1	1
100	1	1	1

6.3. Solutions of Various Problems by MCSUP

In the following is collected results for MCSUP calculations for a number of problems. Actually, many of these results have been produced by earlier (and less efficient) versions of the code. Due to these variable conditions, computing times and qualities are not stated.

The computations were carried out on the IBM 7094 at NEUCC, Lyngby, Denmark.

Three different resonances with the following data were treated:

Resonance no.	E_o	E_u	E_L	σ_p	Γ_n	Γ_γ
1	6.7	14	3	9.5	0.00152	0.0246
2	38.7	42	32	10.64	0.03114	0.02633
3	190.34	200	180	10.64	0.15038	0.02321

Five different moderators with the following data were treated:

Moderator	σ_1	N_1	σ_2	N_2
H	20.4	0.066633	-	-
D	3.4	0.068633	-	-
C	4.65	0.080307	-	-
H ₂ O	20.4	0.066633	3.8	0.033317
D ₂ O	3.4	0.068253	3.8	0.033128

(for compound moderators index 1 refers to the light component).

Six configurations with the following data were treated:

Configuration no.	a	d
1	0.2	$0.3\sqrt{\pi}$
2	1	2
3	1	$1.5\sqrt{\pi}$
4	1	$100\sqrt{\pi}$
5	1.2	$120\sqrt{\pi}$
6	1.7	$170\sqrt{\pi}$

Configurations 4, 5, 6 are, virtually, isolated fuel rods. In all the calculations to be presented, the absorber was assumed to be U-238 ($N = 0.046974$, $T = 300^\circ\text{K}$).

The MCSUP results are given in the table below. Concerning the scattering mode I (cf. 6.1), this refers for compound moderators to the light components: isotropic scattering is throughout assumed for the heavy component.

Resonance no.	Moderator	I	Config. no.	Resonance integral RI	Standard dev. σ_{RI}^*	Escape probability i-p	Standard dev. σ_{i-p}^*
1	H	1	1	4.512	0.014	0.11704	0.00036
1	H	0	2	1.806	0.008	0.20245	0.00094
1	H	0	3	2.7327	0.0022	0.075379	0.000058
2	H	0	3	0.9841	0.0084	0.02683	0.00023
1	H	0	5	2.740	0.009	$0.9471_{10^{-5}}$	$0.0031_{10^{-5}}$
3	H	0	3	0.1563	0.0018	0.0043018	0.000453
1	C	0	5	2.638	0.012	$0.21015_{10^{-3}}$	$0.00097_{10^{-3}}$
1	C	0	4	2.9327	0.0113	$0.23385_{10^{-3}}$	$0.00090_{10^{-3}}$
1	H	0	4	3.0319	0.0040	$0.10478_{10^{-4}}$	$0.00014_{10^{-4}}$
1	D	0	4	3.0609	0.0083	$0.87507_{10^{-4}}$	$0.00238_{10^{-4}}$
1	H	1	4	3.0793	0.0044	$0.10642_{10^{-4}}$	$0.00015_{10^{-4}}$
2	H	0	4	1.0471	0.0032	0.36188	$0.00111_{10^{-5}}$
2	H	1	4	1.0557	0.0030	$0.36485_{10^{-5}}$	$0.00105_{10^{-5}}$
3	H	0	4	0.15835	0.00168	$0.54723_{10^{-6}}$	$0.00581_{10^{-6}}$
1	D ₂ O	0	4	3.0047	0.0043	$0.79084_{10^{-4}}$	$0.00114_{10^{-4}}$
1	H	1	3	2.7639	0.0055	0.076240	0.000151
1	H	0	6	2.2492	0.0050	$0.77640_{10^{-5}}$	$0.00174_{10^{-7}}$
1	H	1	6	2.2887	0.0045	$0.79003_{10^{-5}}$	$0.00157_{10^{-7}}$
1	H ₂ O	1	4	3.0575	0.0042	$0.10450_{10^{-4}}$	$0.00015_{10^{-4}}$
1	H ₂ O	0	4	3.0174	0.0045	$0.10318_{10^{-4}}$	$0.00015_{10^{-4}}$

* Later experiences indicated that these estimates of σ were low, in many cases by 50% or more. This underestimation was traced back to the history averaging in groups (cf. 5.6). The earlier MCSUP versions had a group size of 100; due to fluctuations induced by the negative starters this is too small for the group averages to settle down to the normal distribution as the statistical analysis requires. The present value of 500 has eliminated or greatly reduced the underestimation of σ .

7. POSSIBLE GENERALISATIONS

The MCSUP program in its present form has a number of limitations, arising from the fact that the code hitherto has served purely comparative purposes. It should, however, be possible to remove some of these limitations fairly easily, if the need occurs.

First, the lattice cell was assumed to be square, but implementation of the hexagonal geometry requires only moderate changes in the main program and in the collision probability subroutine PINCA (cf. Appendix V). The same is true for the inclusion of a cladding zone around the fuel (the RESQ-2 program³⁾ works in hexagonal geometry with cladding).

Next, the resonance absorption has been confined to single resonances for a single absorbing nuclide type; one could perhaps desire an extension to a mixture of absorbers with quite general resonance cross sections (probably to be read in from tape). Although possible, this extension would call for fairly much editorial programming.

Inclusion of non-absorbing materials in the fuel region would, in contrast, be very easy.

Concerning the sampling method, a useful extension would be to introduce some sort of correlated sampling, which could improve the possibility of studying differential effects (e. g. the difference between isotropic and anisotropic moderator scattering). A simple way to apply correlated sampling is to force the corresponding histories in the two calculations to begin with the same random number²⁾. In any case, correlated sampling requires a considerable extension of the statistical analysis.

8. SUMMARY AND CONCLUSIONS

The present report has discussed a Monte Carlo method, based on the superposition principle, devised to calculate the resonance absorption in a reactor lattice cell.

The relevant features of the corresponding FORTRAN IV computer program MCSUP (AEK P-598) have been treated, including instructions for the use of the code.

The results of a serial of problems solved by MCSUP have been presented.

The experience from the work has been that the calculation efficiency proved to be quite high for most problems.

As MCSUP was intended as a reference program, it is not able to solve general resonance problems; as indicated in sec. 7, however, this restriction could probably be removed by extension of the model in various ways.

9. ACKNOWLEDGEMENT

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11. APPENDIX I: MCSUP Data Sheet



IBM Data Centre
Punching Instructions

NAME	Page	of	APPLICATION							
92th Michigan 246-1470			Sample Input Data for P-598 MCSUP							
	10	20	30	40	50	60	70	80		
5555555555	1									
14	31	91,15	01,101115121	01,1012146	23171	310101				
246587	01,0166714	81								
2014	01,01666313	1								
-1										

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12. APPENDIX II: RESULT FOR SAMPLE PROBLEM

SUPERPOSITION CALCULATION AFTER SPANIER'S SECOND METHOD

PROBLEM NO 1

RANDOM INITIAL INTEGER = 555555555

NUMBER OF MODERATOR NUCLEI TYPES = 1

RESONANCE ENERGY = 0.67000E 01 UPPER ENERGY LIMIT = 0.14000E 02 LOWER ENERGY LIMIT = 0.30000E 01

SCATTERING CROSSSECTION OF ABSORBER = 0.95000E 01

GAMMA-GAMMA = 0.15200E 02 GAMMA-GAMMA = 0.24600E 01

ATOMIC WEIGHT OF ABSORBER = 0.23800E 03

TEMPERATURE OF MODERATOR = 0.30000E 03

RADIUS = 0.10000E 01 PITCH = 0.26587E 01

CONCENTRATION OF ABSORBER NUCLEI = 0.46974E 01

BEAM TIME = 13.00 MINUTES

CROSSSECTION	NUMBER DENSITY	SCATTERING MODE
0.20400E 02	0.46439E 01	1

CONTRIBUTION OF THE FIVE TERMS TO RESONANCE INTEGRAL

SURFACE SOURCE TERM =	0.12803E 00	DEVIATION = 0.31685E 02
POINT SOURCE TERM =	0.11266E 01	DEVIATION = 0.43621E 02
SCATTERING SOURCE TERM =	0.57935E 01	DEVIATION = 0.31629E 02
SCATTERING SOURCE TERM =	0.81731E 01	DEVIATION = 0.33945E 02
RESONANCE INTEGRAL =	0.17600E 01	DEVIATION = 0.71130E 02
SCATTERING SOURCE PROBABILITY =	0.76134E 01	DEVIATION = 0.19621E 03

SCATTERING MODE QUALITY = 100

13. APPENDIX III: COMPUTER CODE PRINT-OUT

```

COMMON/CON2/ETA, ER, A1, A2, A3, A4, SPA, CONCA
COMMON/CON3/U, V, W, SIN2, IX, TCOS(1000), T5IN(1000), AM(5), ASGPL(5), J
COMMON/CON4/PI, DIA, SHM, RK, PINVS(46)
COMMON/CON5/ROI
DIMENSION PH(1000), SIGT(1000), SIGSR(1000), SAST(1000), TLOG(1000),
IDEG(1000,4), EQ(1000,4), RINT(5), PRES(5), DPRS(4), TDEL(4), ISMAX(2,4)
2, SMNI(5), SMNA(5), CCNCN(5), RKSIN(5), ALN(5), ONALN(5), RAND(5)
3, IANIS(5)
LOGICAL LABEL
C SPECIFICATION OF I/O UNITS
NIN=5
NOL1=6
200 FORMAT(5I10)
201 FORMAT(8E10,5)
199 FORMAT(3E10,5,110)
WRITE(NOUT,101)
103 FORMAT(1H0,54HSUPERPOSITION CALCULATICA AFTER SPANTERS SECCND METH
100)
86 READ(5IN,200)IPND
IF(IPND,LT,0)STOP
NMAX=500
FN=NMAX
READ(NIN,200)IX,IMOD
READ(15IN,201)ER,EU,EL,SPA,GN,GG,AA,T,RC1,RK2,CCNCA,TIDMAX
DD C3 I=1,IMOD
23 READ(4IN,199)AM(I),SMNI(I),CCNCN(I),IANIS(I)
WRITE(NOUT,103)IPND
103 FORMAT(1H1,10HPROBLEM NO,12)
WRITE(NOUT,104)IX
104 FORMAT(1H0,23HRANDCM INITIAL INTEGER=,110)
WRITE(NOUT,105)IMOD
105 FORMAT(1H0,34HNUMBER OF MODERATOR NUCLIDE TYPES=,12)
WRITE(NOUT,106)ER,EU,EL
106 FORMAT(1H0,27HRESONANCE ENERGY=,E12,5,3X,19HUPPER ENERGY LIMIT=,
E12,5,3X,19HLOWER ENERGY LIMIT=,E12,5)
WRITE(NOUT,107)SPA
107 FORMAT(1H0,46HPOTENTIAL SCATTERING CROSSSECTION OF ABSORBER=,E12,5
1)
WRITE(NOUT,108)GN,GG
108 FORMAT(1H0,8HGAMMA-N=,E12,5,3X,12HGAMMA-GAMMA=,E12,5)
WRITE(NOUT,109)AA
109 FORMAT(1H0,26HATOMIC WEIGHT OF ABSORBER=,E12,5)
WRITE(NOUT,110)T
110 FORMAT(1H0,25HTEMPERATURE OF MODERATOR=,E12,5)
WRITE(NOUT,111)RC1,RK2
111 FORMAT(1H0,17HRC1=,E12,5,3X,6HRK2=,E12,5)
WRITE(NOUT,112)ONALN
112 FORMAT(1H0,15HCONCENTRATION OF ABSORBER NUCLEI=,E12,5)

```

```

WRITE(NOUT,113)TIDMAX
113 FCFMAT(1H0,13HMAXIMUM TIME=,FC,2,2X,7HMINUTES)
WRITE(NOUT,114)
114 FCFMAT(1H0,14HMODERATOR DATA)
WRITE(NOUT,115)
115 FCFMAT(1H,13HATOMIC WEIGHT,4X,12HCROSSSECTION,4X,14HNUMBER DENSIT
1Y,4X,15HSCATTERING MODE)
DC C4 I=1,IMOD
64 WRITE(NOUT,116)AM(I),SMNI(I),CCNCN(I),IANIS(I)
116 FCFMAT(1H, E12,5,5X,E12,5,4X,E12,5,11X,I2)
RK=FK2/2.
PI=2.14159265
TOP1=2.*PI
DC 250 I1=1,1000
R=FLOAT(I1)/1000.-0.0005
ARGL=TOP1+R-PI
TCOS(I1)=COS(ARGU)
T5IN(I1)=SIN(ARGU)
250 TLOG(I1)=ALOG(R)
C=GN+GG
ETA=G+SQRT(AA/0.0013776/T/ER)
E0=2.*C*CE*([AA+1.00057]/AA)**2*GN/G/ER
M1=50/G+SQRT(PI)*ETA
A1=M1*GG
A2=M1*GN
A3=2.*SQRT(50*SPA+GN*PI/G)*ETA
DELE=(EU-EL)/1000.
A4=2.*ETA/G
DC E0 I=1,1000
MC=I
E=EL+DELE*(MC-0.5)
M7=AA*(E-ER)
CALL ERFCHL(H7,ETA,U,V)
SA=A1+U*SQRT(ER/E)
SSR=A2+U+A3*V
SS=SSR+SPA
S1=SA+SS
SAST(I)=SA/ST
SIGER(I)=SSR+CONCA
50 SIGT(I)=S1*CONCA
SPAN=SPA*CONCA
CIA=2.*ROI
R150=ROI**2
AREA1=PI*R150
AREA2=RK2**2-AREA1
CPAL1=4.*AA/(AA+1)**2
RKS1=6./(3.*AA+2.)
SOLR=RKS1 I+SPAN*AREA1
SHM=0.
DC C6 I=1,IMOD
ASGPL(I)=AM(I)**2+1.
SMNA(I)=CCNCN(I)*SMNI(I)
SPR=SHM+SMNA(I)
CPAL(I)=4.*AM(I)/(AM(I)+1)**2
ALN(I)=ONALN(I)
RKSIN(I)=1.

```



```

IF (AM(I),GT,1,5)RKSI(I)=1.+ALN(I)/CHALD(I)*ALOG(ALN(I))
66 SOUR=SOUR+RKSI(I)*SMMA(I)*AREAZ
CALL PINCA
IF (IMOD,EQ,1)GOTOE7
RAND(I)=SMMA(I)/SHM
DO 68 I=2,IMOD
68 RAND(I)=RAND(I-1)+SMMA(I)/SHM
67 COEF=DELE/CONCA
DO 61 I=1,1000
M1=I
E=EL+DELE*(M1-0.5)
STF=SIGT(I)
OPT=STF*ROI
PZERO=PO(OPT)
PSTAR=PS(OPT)
ASRF=ABS(STF-SPAM)
DEG(I,1)=ASRF*(PZERO-SAST(I)+(PZERO-PSTAR))/E
H2=SPAM*(1.-PZERO)/STF/E
DEG(I,2)=ASRF*H2
H3=ABS(SIGSR(I))
DEG(I,3)=H3*H2
51 DEG(I,4)=H3*PZERO/E
RINT(I)=SELIN(EL,EU,126,10CC.)/DELE
PRES(I)=COEF*RINT(I)
DO 62 L=1,4
RINT(L)=0.
DO 62 I=1,1000
62 RINT(L)=RINT(L)+DEG(I,L)
CO 63 L=1,4
J=1
M4=0.
M5=0.0005
SUM=0.
CO 54 I=1,1000
H2=DEG(I,L)
M3=M4
ELN=SUM+H2
M4=SUM/RINT(L)
65 IF (M4,LT,M5)GOTO54
M1=I-1
EQ(J,L)=EL+DELE*((M5-M3)/(M4-M3)+M1)
J=J+1
M=PLCAT(J)/1000.-0.0005
GOTO5E
54 CONTINUE
53 CCNTINUE
TC=0.
J=1
DO 368 M=1,2
TPM=TIMAX/16.
GO 350 L=1,4
IF (M,EQ,2)THAX=TDEL(L)
IE=0
CALL TIME(ISTART)
61 REI=0.
N=0

```

```

IEVEN=1
E2 N=1+1
IF (N,EG,NMAX+1)GOTCEG
C INITIAL ENERGY
LAEEL=.FALSE.
IEVEN=IEVEN
IF (IEVEN)60,60,61
60 CALL FANDL(IX,R)
FOCE=R
GCTCE2
61 R=1.-RODD
62 I1=1000.*R+1.
E=EQ(I1,L)
I=(E-EL)/DELE+1.
GCTO(206,202,202,203),L
C STARTER OF TYPE 1
C INITIAL DIRECTION RELATIVE TO SURFACE NORMAL
206 WG=SIGN(I1,SIGT(I))-SPAM)
LAEEL=.TRUE.
207 CALL FANDL(IX,R)
U1=SQRT(R)
M1=SQRT(1.-R)
CALL RANDL(IX,R)
I1=1000.*R+1.
M=1+ITSIN(I1)
SIN2=1.-M**2
C REJECTION CALCULATION
M2=DEXP(DIA*U1/SIN2+SIGT(I))
CALL FANDL(IX,R)
IF (M2,LE,R)GOTO207
V1=M1+TCDS(I1)
C INITIAL SURFACE POSITION AND CORRECTION OF DIRECTION
CALL FANDL(IX,R)
I1=1000.*R+1.
COSV=TCDS(I1)
SINV=TSIN(I1)
X=FO1+COSV
Y=FO1*SINV
U=COSV*U1-SINV*V1
V=SINV*U1+COSV*V1
K=1
GCTOS
C STARTER OF TYPE 2 OR 2
C INITIAL POSITION IN ZONE 1
202 CALL FANDL(IX,R)
RCSC=R*RSO
RC=SQRT(RSO)
CALL FANDL(IX,R)
I1=1000.*R+1.
M=RC*TCDS(I1)
Y=FC*TSIN(I1)
CALL ISO
C INITIAL PATH LENGTH IN ZONE 1
CALL FANDL(IX,R)
I1=1000.*R+1.
RL=-TLOG(I1)/SIGT(I1)

```

C REJECTION CALCULATION

```

X=X+U*RL
Y=Y+V*RL
RDSQ=X**2+Y**2
IF (RDSQ.GT.R1SQ) GOTO202
K=1
IF (L.EQ.3) GOTO204
WG=SIGN(1.,SIGT(I))-SPAW
GOTO15
204 WG=SIGN(1.,SIGSR(I))
GOTO15

```

C STARTER OF TYPE 4

C INITIAL DIRECTION RELATIVE TO SURFACE NORMAL

```

203 CALL RANDL(IX,R)
U1=-SQRT(R)
V1=SQRT(1.-R)
CALL RANDL(IX,R)
I1=1000.*R+1.
V=V1*TSIN(I1)
SIN2=1.-V**2

```

C REJECTION CALCULATION

```

H2=-CIA*U1/SIN2*SIGT(I)
CALL RANDL(IX,R)
IF (CEXP(H2).LE.R) GOTO203
V1=H1*TCOS(I1)

```

C INITIAL SURFACE POSITION AND CORRECTION OF DIRECTION

```

CALL RANDL(IX,R)
I1=1000.*R+1.
COSV=TCOS(I1)
SINV=TSIN(I1)
X=R01+COSV
Y=FC1+SINV
U=COSV*U1-SINV*V1
V=SINV*U1+COSV*V1

```

C COVEYU SAMPLING OF INITIAL RESONANCE SCATTERING IN ZONE 1

```

CALL RANDL(IX,R)
I1=1000.*R+1.
H1=-TLOG(I1)
I1=H1/H2
H3=I1
RL=(H1-H3*H2)/SIGT(I)

```

C POSITION OF INITIAL SCATTERING

```

X=X+U*RL
Y=Y+V*RL
RDSQ=X**2+Y**2
WG=SIGN(1.,SIGSR(I))
K=1

```

C NOW BEGINS COMMON HISTORY BLOCK

C SAMPLING OF ENERGY AFTER SCATTERING IN ZONE 1

```

CALL RANDL(IX,R)
E=E*(1.-R*OMAL1)
IF (E.LT.EL) GOTO82
I=(E-EL)/DELE*1.

```

C ISOTROPIC DIRECTION ZONE 1

```

CALL ISO

```

C PATH LENGTH IN ZONE 1

6 CALL RANDL(IX,R)

```

I1=1000.*R+1.
RL=-TLOG(I1)/SIGT(I)

```

C DISTANCE TO ZONE INTERFACE

```

DELTA=U*X+V*Y
IF (K.EQ.2) GOTO13
SL=(SQRT(DELTA**2+SIN2*(R1SQ-RDSQ))-DELTA)/SIN2
GCTC14

```

```
13 K=1
```

```
SL=-2.*DELTA/SIN2
```

```
14 IF (SL.CE.RL) GOTO4
```

```
X=X+U*SL
```

```
Y=Y+V*SL
```

C MODIFIED TRACK LENGTH SCORING IN CASE OF PASSAGE

```
RES=RES+WG*SAST(I)*SIGT(I)*SL
GOTO5

```

C COLLISION IN ZONE 1

```
4 CALL RANDL(IX,R)
IF (R-SAST(I))16,17,17

```

C ABSORPTION

```
18 IF (LABEL) GOTO207
```

C MODIFIED TRACK LENGTH SCORING IN CASE OF ABSORPTION

```

H1=SL*SIGT(I)
I2=OEXP(H1)
RES=RES+WG*SAST(I)*(1.-(1.-H2)*(H1+1.))/H2
GOTO62

```

C SCATTERING IN ZONE 1

```
17 IF (LABEL) GOTO19
```

C MODIFIED TRACK LENGTH SCORING IN CASE OF SCATTERING

```
RES=RES+WG*SAST(I)*SIGT(I)*RL
```

```
19 X=X+U*RL
```

```
Y=Y+V*RL
```

```
RDSQ=X**2+Y**2
```

```
GCTC18
```

C PATH LENGTH IN ZONE 2

```
5 CALL RANDL(IX,R)
```

```
I1=1000.*R+1.
```

```
RL=-TLOG(I1)/SHM
```

```
IF (K.EQ.1) GOTO7
```

```
DELTA=U*X+V*Y
```

```
IF (DELTA.GT.0.) GOTO7
```

```
8 DELTA**2-SIN2*(RCSQ-R1SQ)
```

```
IF (DELTA.GT.0.) GOTO7
```

C DIRECTION TOWARDS ZONE 1

```
T=(DELTA-SQRT(D))/SIN2
```

```
IF (T.GT.RL) GOTO9
```

```
X=X+U*T
```

```
Y=Y+V*T
```

```
GCTO6
```

C DIRECTION TOWARDS OUTER BOUNDARY

```
7 K=2
```

```
H1=SIGN(RK,U)
```

```
T=(H1-X)/U
```

```
H1=SIGN(RK,V)
```

```
T=(H1-Y)/V
```

```
T=TY
```

```

      IF (TX,LT, TY) T=TX
      IF (T,GT,RL) GOT09
C REFLECTION
      X=X+U*T
      Y=Y+V*T
      ROSQ=X**2+Y**2
      RL=RL-T
      IF (TX-TY) 10,11,11
10  L=U
      GCTC12
11  V=-V
12  DELTA=U*X+V*Y
      IF (DELTA) 8,8,7
C ENERGY SAMPLING FOR ZONE 2 COLLISION
9  CALL RANDL(IX,R)
      IF ((INCO,EG,1) GOT065
          DO 70 J=1,IMOD
70  IF (R,LT,RAND(J)) GOT071
71  H1=0.
      IF (J,GT,1) H1=RAND(J-1)
      R=(R-H1)/(RAND(J)-H1)
69  E=E*(1.-R*ONALM(J))
      IF (E,LT,EL) GOT082
          I=(E-EL)/DELE+1.
C POSITION FOR ZONE 2 COLLISION
      LABEL=,FALSE.
      X=X+U*RL
      Y=Y+V*RL
      ROSQ=X**2+Y**2
C ISOTROPIC DIRECTION ZONE 2
      IF (IANIS(J),EQ,1) GOT072
          CALL ISO
          GOTCS
72  CALL ANIS
          GOT08
60  IS=IS+1
          PW[IS]=RES
          CALL TIME(ISLUT)
          TID=FLOAT(ISLUT-1START)/3600.
          IF (TID,LT,TMAX,AND,IS,LT,100) GOT081
              TC=TD+TID
              H1=0.
              H2=0.
              DO 85 I=1,IS
                  H2=H2+(I)
                  H1=H1+H3
85  P2=H2+H3**2
              R2=IS
              H1=H1/RS
              H2=H2/RS
              H3=CCOFPRINT(L)/RN
              H4=1+H3
              H5=SQRT((H2-H1**2)/(R2-1.))*H3
              ISMAX(N,L)=IS
              IF (N,EG,1) GOT087
                  H1=ISMAX(1,L)

```

```

          H2=ISMAX(2,L)
          H3=1+H2
          PRES(L)=(H1*PRES(L)+H2*H4)/P3
          DPRS(L)=SQRT((H1*DPRS(L)**2+(H2*H5)**2)/H3
          GCT0350
87  PRES(L)=H4
          DPRS(L)=H5
350  CONTINUE
          IF (N,EQ,2) GOT0352
              H1=0.
              DO 353 L=1,4
353  H1=1+DPRS(L)
              DO 354 L=1,4
                  TDEL(L)=TIDMAX*(DPRS(L)/H1-C,625)
354  IF (TDEL(L),LT,0.2) TDEL(L)=0.2
352  CONTINUE
          P=PRES(5)-PRES(1)-PRES(2)+PRES(3)+PRES(4)
          H1=C.
              DO 351 L=1,4
351  H1=H1+DPRS(L)**2
              CP=SQRT(H1)
              TC=(P/DP)**2/TD/60.+0.5
              WRITE(NOUT,121)
121  FCFMAT(1M0,52HCONTRIBUTION OF THE FIVE TERMS TO RESONANCE INTEGRAL
          1)
              WRITE(NOUT,122)PRES(5)
122  FCFMAT(1H ,37HDETERMINISTIC TERM= ,E12.5)
              WRITE(NOUT,123)PRES(1),DPRS(1)
123  FCFMAT(1H ,37HNEGATIVE OUTWARD SURFACE SOURCE TERM=,E12.5,3X,
          110HDEVIATION=,E12.5)
              WRITE(NOUT,124)PRES(2),DPRS(2)
124  FCFMAT(1H ,37HNEGATIVE VOLUME SOURCE TERM= ,E12.5,3X,
          110HDEVIATION=,E12.5)
              WRITE(NOUT,117)PRES(3),DPRS(3)
117  FCFMAT(1H ,37HPOSITIVE VOLUME SOURCE TERM= ,E12.5,3X,
          110HDEVIATION=,E12.5)
              WRITE(NOUT,118)PRES(4),DPRS(4)
118  FCFMAT(1H ,37HPOSITIVE INWARD SURFACE SOURCE TERM= ,E12.5,3X,
          110HDEVIATION=,E12.5)
              WRITE(NOUT,119)P,DP
119  FCFMAT(1M0,37HRESONANCE INTEGRAL= ,E12.5,3X,
          110HDEVIATION=,E12.5)
              H1=AREA1+CCNCA/SOUR
              F=H1*F
              CP=1+14DP
              WRITE(NOUT,120)P,DP
120  FCFMAT(1M0,37HRESONANCE CAPTURE PROBABILITY= ,E12.5,3X,
          110HDEVIATION=,E12.5)
              WRITE(NOUT,122)IQ
125  FCFMAT(4M0,20HSTATISTICAL QUALITY=,IS)
          GCT0351
          END

```

```

SLEFCLTIME IS9
CCMNCN/CCN3/U,V,W,SIN2,IX,TCCS(1000),TSIN(1000),AM(5),ASCPL1(5),J
CALL RANDL(IX,R)
V=I.*R-1.
SIN2=1.-W**2
F1=SQRT(SIN2)
CALL RANDL(IX,R)
I1=(00.*R+1)
L=F1*TCOS(I1)
V=F1*TSIN(I1)
RETURN
ENC

```

```

SUERCLTIME ANIS
CCMNCN/COM3/U,V,W,SIN2,IX,TCCS(1000),TSIN(1000),AM(5),ASCPL1(5),J
CALL RANDL(IX,R)
IF(AM(J).LT.1.E)GOTC1
RMY=2.*R-1.
H1=AM(J)*RMY
A=(1.+H1)/SQRT(ASOPL1(J)+1.*H1)
E=SQRT(1.-A**2)
GOTO2
1 A=SQRT(R)
B=SQRT(1.-R)
2 CALL RANDL(IX,R)
I1=1000.*R+1.
C=TCOS(I1)
D=TSIN(I1)
ECh=E*C*W
BE=E*C
SUIW=SQRT(SIN2)
UEF=(BCW*U-BD*V)/SUIW+A*U
V=(BCW*V+BD*U)/SUIW+A*V
L=UEF
W=U*W-E*C*SUIW
SIN2=1.-W**2
RETURN
ENC

```

```

FUNCTION PS(T)
CCMNCN/COM4/PI,DIA,SPW,RK,PINVS(46)
IF(T.GE.0.)GOTO1
IF(T.LE.1.)GOTC2
A=20.
B=1.
GOTO3
2 A=C.
B=1C.
3 F1=A+T+3
I=F1
F2=PINVS(I)
F3=PINVS(I+1)
F4=3-F2
H8=I
V6=F1-H8
H7=H8+V6*H4
F5=1./H7
RETURN
1 PI=C./PINVS(46)/T
RETURN
ENC

```

```

SLEFCLTIME PINCA
CCMNCN/COM4/PI,DIA,SPW,RK,PINVS(46)
CCMNCN/CCN5/RO1
DIMENSION XI(8),Y1(8),W1(8),L1(64),V1(64),ST1(10),PESC(10),
1RESULT(10),OPTCH(10),CPT1(10),OPT2(10),CAM(10),RESNO(10),
2STMCH(10),PSTAR1(46),YG(8),W61(8)
DATA YG,W61/0.,001992.,020442.,02226E.,2C6855.,394469.,617311,
1.225652.,984756.,002255.,017R43.,045439.,079200.,106047.,112506,
2.051119.,044551/
CPTFO=RO1*SHW
CFR1SQ=CPTRD**2
OPTRK=RK*SHW
DO 301 I=1,8
Y1(I)=OPTFO*(1.-YG(I))
301 XI(I)=SQRT(OPR1SQ-Y1(I)**2)
CA=PI/126.
CC 302 J=1,32
ARCL=CA*(FLOAT(J)-C.E)
H1=CCS(ARGU)
F2=SIW(ARGU)
U1(J)=H1
V1(J)=H2
J2=C5-J
U1(J2)=H1
302 V1(J2)=-H2
DO 303 K=1,10
F1=1.2*FLOAT(K)
STMCH(K)=H1
ST1(K)=H1/DIA
PESC(K)=PO(H1/2.)
RESNO(K)=0.
303 RESLLT(K)=0.
CC 350 I=1,8
XC=X1(I)
YC=Y1(I)
WC=W61(I)
F1=2.*XC/SHW
DO 3C4 K=1,10
F2=-1*ST1(K)
OPTCH(K)=H2
304 RESACH(K)=RESACH(K)+BIC3(H2)*WC
CC 350 J=1,64
U=C1(J)
V=Y1(J)
X=X0*U-V*V
Y=X*V+Y0*U
DO 305 K=1,10
CPT1(K)=0.
305 OPT2(K)=OPTCH(K)
306 CPTMOD=0.
307 TX=(OPTRK-X)/U
H1=SIGN(OPTRK,V)
TY=(H1-Y)/V
IF(TY.LT.TX)GOTO311
CPTMOD=OPTMOD+TX
X=X-CPTRK
Y=Y+V*TX
CPTD312
311 CPTMOD=OPTMOD+TY
X=X+U*TY
Y=Y+V*TY
312 C=CFR1SQ-(U*Y-V*X)**2
IF(C)307,313,313
313 T=U*Y-V*X=SQRT(D)

```

```

CFYMOD=OPTMOD+7
CC 308 K=1,10
CP1AC=OPT2(K)
CPTBC=OPT1(K)
OPTAD=OPTAC+OPTMOD
CPTBC=OPTBC+OPTMOD
H1=RIC3(OPTBC)-RIC3(OPTAC)-RIC3(OPTED)+RIC3(OPTAD)
308 RESULT(K)=RESULT(K)+H1*NG
Y=Y+U*Y
V=Y+V*Y
DELTA=U*X+V*Y
SL=-2.*DELTA
X=X+U*SL
Y=Y+V*SL
SL=SL/SHM
IF(OPT1(1)+SL*ST1(1)+EPTMCC.GT.7.)GOTO350
CC 309 K=1,10
H1=SL*ST1(K)+CFTMOD
CPT1(K)=OPT1(K)+H1
309 CPT2(K)=OPT2(K)+H1
GOTO306
306 CONTINUE
H2=PI/8.
CC 311 K=1,10
311 RESULT(K)=RESULT(K)*PESC(K)/64./{H2-RESNCK(K)}
PSTAR1(1)=1.
PSTAR1(13)=RESULT(1)
CC 316 K=2,10
L=2*K+16
316 PSTAR1(L)=RESULT(K)
DO 317 K=1,10
X=STPCK(K)
P=PESC(K)
PST=RESULT(K)
H1=X*P*PST
317 GAM(K)=H1/(P-PST+H1)
GAMMA=GAM(1)
CC 318 L=2,12
H1=L
X=(H1-1.)/10.
P=PO(X/2.)
318 PSTAR1(L)=P*GAMMA/(1.-(1.-GAMMA)*(1.-X*P))
H2=GAM(1)
H3=GAM(2)-H2
CC 319 L=14,21
H1=L
X=(H1-1.)/10.
GAMMA=H2+H3/1.2*(X-1.2)
P=PO(X/2.)
319 PSTAR1(L)=P*GAMMA/(1.-(1.-GAMMA)*(1.-X*P))
CC 320 K=3,10
H1=K
X1=1.2*H1-1.2
H3=CAM(K-1)
H4=CAM(K)-H3
CC 320 M=1,2
H2=H
X=X1+C.4*H2
GAMMA=H3+H4/2.*H2
P=PO(X/2.)
L=2*K+H+3
320 PSTAR1(L)=P*GAMMA/(1.-(1.-GAMMA)*(1.-X*P))
CC 321 L=1,40
321 PSTAR1(L)=L./PSTAR1(L)

```

- 37 -

```

FUNCTION SELIN(A,B,X,FM)
COMMON/COM1/XX,YY
DIMENSION FUNC(129)
F=(E-A)/FLOAT(N)
NF=N+1
DO 11 I=1,NP1
XX=A+FLOAT(I-1)*H
CALL FCT
11 FUNC(I)=YY
DEL=C.
CC 1 I=1,N
1 CEL=DEL+ABS(FUNC(I+1)-FUNC(I))
RI=C.
CC 2 I=1,N
XL=A+FLOAT(I-1)*H
PJ=FM*ABS(FUNC(I+1)-FUNC(I))/DEL+1.
PJ2=H/FLOAT(PJ)
HJ=HJ2/2.
RIJ=FLNC(I)+FUNC(I+1)
XX=XL-HJ
H3=0.
CC 3 J=1,MJ
XX=XX+HJ2
CALL FCT
3 H1=H1+YY
RIJ=RIJ+4.*H1
IF(PJ.EQ.1)GOTO2
XX=XL
MJ1=MJ-1
H2=0.
CC 4 J=1,MJ1
XX=XX+HJ2
CALL FCT
4 H2=H2+YY
FIJ=RIJ+2.*H2
2 FI=RI+RIJ*HJ/3.
SELIN=FI
RETURN
END

```

```

SLEROLTIME FCT
COMMON/COM2/ETA,ER,A1,A2,A3,A4,SPA,CCNCA
COMMON/COM3/RO1
H7=A4*(XX-ER)
CALL ERFCPL(H7,ETA,U,V)
SA=A1+U*SQRT(ER/XX)
E5=A2*U+A3*V+SPA
ST=SA+SS
CPT1=ST*CCNCA*RC1
PSTAR=PS(OPT)
YY=SA*CONCA*(PSTAR+SPA/ST*(1.-PSTAR))/XX
RETURN
END

```

```

SLEFOLTIME ERFCPL(X,Y,U,V)
C=C.
E=C.
N=1
IF (Y. CE. 0.) GOTO1
C=(X+Y)*(X-Y)
E=-2.0*X*Y
X=-X
Y=-Y
1 IF (X. CE. 0.) GOTC2
N=N+1
2 IF (X+Y. GE. 3. OR. Y+C. 2*X. GE. 1.7) GOTC3
A=(X+Y)*(X-Y)
E=2.0*X*Y
T=C. 4*A
FN=-0.04*(A**2+B**2)
P1=-14.3+T*3.3
P2=210.21+T*P1+RN*3.3
P3=-519.3045+T*P2+RN*P1
P4=3267.20821+T*P3+RN*P2
P5=-4455.53759+T*P4+RN*P3
P6=14448.00589+T*P5+RN*P4
P7=(-4488.78070+T*P6+RN*P5)/E.
T1=12056.5125+A*P1+RN*P2
T2=E*P1
P3=11.0+T
P2=89.14+T*P3+RN
P1=814.8+T*P2+RN*P3
P3=2207.205+T*P1+RN*P2
P2=7121.3442+T*P3+RN*P1
P1=17421.0636+T*P2+RN*P3
P2=31837.26576+T*P1+RN*P2
P1=35914.35158+T*P3+RN*P1
P1=(-21822.52762+T*P2+RN*P3)/E.
FN1=12096.5125+A*P1+RN*P2
FN2=E*P1
P3=1.1283761271/(RN1**2+RN2**2)
P2=P3*(RN1+T1+RN2+T2)
P1=P3*(RN1+T2+RN2+T1)
T=EXP(-A)
L=1+CCS(B)-X*P1-Y*P2
V=-T*SIN(B)+X*P2-Y*P1
GTC4
1 P1=Y**2
U=C.
V=C.
T=C.
5 A=X+T*0.31424057E3
E=C. 161479E122/(A**2+P1)
U=L+8
V=4+A*8
A=X+0.6477883912+T
E=C. 62917277E3/(A**2+P1)
L=L+8
V=4+A*8
A=X+1.857662E3E2+T

```

```

E=C. 01642733E203/(A**2+P1)
L=L+8
V=4+A*8
A=X+2.2765C7C805+T
E=C. 01243124432/(A**2+P1)
U=L+8
V=4+A*8
A=X+3.02063702E1+T
E=0. 0C02726C85347/(A**2+P1)
L=L+8
V=4+A*8
A=X+3.8897248579+T
E=0. 0C0000E462432E41/(A**2+P1)
L=L+8
V=4+A*8
IF (T. L. T. 0.) GOTO6
T=-1.
GOTO5
6 U=U*Y
4 V=V*LOGAT(N)
IF (C. EQ. 0. AND. D. EQ. 0.) RETURN
C=EXP(-C)
U=2.0*C*COS(D)-U
V=5.0*C*SIN(D)-V
RETURN
END

```

```

FUNCTION BIC3(X)
IF (X. GE. 1.) GOTO1
BIC3=X*(X*(X*(X*(X* 1.1645E17E-2-1.73373703E-1)
+3.42522057E-1)-5.0E60279E-1)+7.48517345E-1)-9.98434740E-1)
+7.85279789E-1
RETURN
1 IF (X. GE. 2.) GOTO2
BIC3=X*(X*(X*(X* 1.18535064E-2-1.07572888E-1)+4.13393840E-1)
-6.23631468E-1)+7.44150729E-1
RETURN
2 IF (X. GE. 4.) GOTO3
BIC3=X*(X*(X*(X*(-4.26476343E-4)+8.2363987E-3)-6.59959216E-2)
+4.80376616E-1)-6.442C9563E-1)+6.53752728E-1
RETURN
3 IF (X. GE. 8.) GOTO4
BIC3=X*(X*(X*(X*(-1.50015616E-8)+8.2CC87758E-4)-7.282442E-3)
+6.1716435E-2)-1.07368576E-1)+2.7875179E-1
RETURN
4 IF (X. GE. 10.) GOTO5
BIC3=-8.48E-6*(X-10.)
RETURN
5 BIC3=0
RETURN
END

```


15. APPENDIX V: FUEL-TO-MODERATOR COLLISION PROBABILITY P^*

We now turn to discuss the calculation of the fuel-to-moderator collision probability P^* , which occurs in (31) and (32).

Also here we shall follow Spanier and Gelbard²⁾, but only to a certain extent; we found it much more satisfactory to compute P^* by purely deterministic methods instead of using Monte Carlo.

$P^*(E)$ is defined as the probability that a source neutron with energy E drawn from a uniform distribution in the fuel will make its first collision in the moderator.

As the moderator cross section is assumed energy independent, we first notice that P^* for a fixed configuration is a function only of the optical radius $\zeta = a \Sigma$ of the fuel.

As for P_0 (Appendix IV) we want to construct a table of $P^*(\zeta)$, or rather $1/P^*(\zeta)$, this quantity behaving more linearly. This table is of course not universal but depends on the actual configuration. This table has (like the $1/P_0$ -table) 46 entries with $\zeta = 0, 0.05, 0.1, \dots, 0.95, 1.0, 1.2, \dots, 5.8, 6.0$, and linear interpolation should be quite adequate to find $P^*(\zeta)$ for arbitrary ζ . Now Spanier and Gelbard²⁾ point out that it is not necessary to calculate all the corresponding 46 P^* -values. They take advantage of Nordheim's approximate formula²²⁾

$$P^*(\zeta) \approx \frac{P_0(\zeta) G_m}{1 - (1 - G_m)(1 - G_f(\zeta))} \quad (50)$$

where G_m and $G_f(\zeta)$ is the sticking probability^{2, 22)} for the moderator and fuel, respectively, and define a quantity $\gamma_m(\zeta)$ which exactly satisfies the following equation

$$P^*(\zeta) = \frac{P_0(\zeta) \gamma_m(\zeta)}{1 - (1 - \gamma_m(\zeta))(1 - G_f(\zeta))} \quad (51)$$

Due to (50), $\gamma_m(\zeta)$ is a slowly varying function of ζ . Now, $G_f(\zeta)$ is given by²⁾

$$G_f(\zeta) = 2\zeta P_0(\zeta) \quad (52)$$

so, assuming $P_0(\zeta)$ to be known, $\gamma_m(\zeta)$ becomes a unique function of $P^*(\zeta)$. The idea is now to compute (in some way) $P^*(\zeta)$ at rather few ζ -values, e.g. $\zeta = 0.6, 1.2, \dots, 6.0$. Via (51) one obtains 10 corresponding γ_m -values, and linear interpolation in this coarse γ_m -table renders next a full, 46-entry table for $\gamma_m(\zeta)$, which finally, again via (51), is converted to the desired 46-entry table for $P^*(\zeta)$.

Now it still remains to calculate $P^*(\zeta)$ at $\zeta = 0.6, 1.2, \dots, 6.0$, and in doing so, we now digress from the exposition of Spanier and Gelbard²⁾, who recommend a Monte Carlo procedure for this job. We have found that an approach, inspired by Carlvik^{6, 24)}, yield a both faster and more accurate calculation scheme.

Consider fig. 3 which shows a part of the infinite lattice system. P^* may be expressed by the double integral

$$P^* = \frac{2}{\pi} \int_{-\pi/4}^{\pi/4} da \int_0^a dy l(y) \frac{1}{2\pi a \Sigma} p(y, a) \quad (53)$$

where $p(y, a)$ is the probability that a starter drawn uniformly from the chord of length $l(y)$ after travelling in the direction a makes its first collision in the moderator. Referring to the optical scale on the a -ray depicted in fig. 3 below, one can show that $p(y, a)$ is given by the expression

$$p(y, a) = \frac{\sum_{i=1}^{\infty} \left\{ \left[K_{1/3}(t_i) - K_{1/3}(t_i + \lambda) \right] - \left[K_{1/3}(u_i) - K_{1/3}(u_i + \lambda) \right] \right\}}{\Sigma \cdot l(y)} = \frac{p(y, a)}{\Sigma \cdot l(y)} \quad (54)$$

where $K_{1/3}(x)$ is the Bickley function

* Mikkelsen¹⁾ has noticed a pronounced maximum in the relative error of (50) in the range $0 < \zeta < 0.6$ for small cells, perhaps making the above procedure questionable for such cells. We have, however, not revealed any significant errors for the final calculation results.

$$K_{in}(x) = \int_0^{\frac{\pi}{2}} \exp\left(-\frac{x}{\cos\theta}\right) \cos^{n-1} \theta d\theta \quad (55)$$

Then (53) may be written

$$P^* = \frac{4}{\pi^2 \lambda a^2} \int_{-\frac{\pi}{4}}^{\frac{\pi}{4}} da \int_0^a dy \varphi(y, a) \quad (56)$$

In the numerical calculation of the double integral (56), a discrete representation is chosen for both variables:

- 1) a-integration: 64 equidistant a-values in $-\frac{\pi}{4} < a < \frac{\pi}{4}$
- 2) y-integration: 8 non-equidistant y-values in $0 < y < a$.

The y-integration is of the Gaussian type. We choose a weight function mimicking the behaviour of the integrand near $y = 0$. For small y, $\varphi(y, a)$ tends to be proportional to $l(y)$ and thereby to $y^{1/2}$. Hence, by introducing the new variable $x = (y/a)^2$, one could hope that the Gaussian representation

$$\int_0^1 x f(x) dx = \sum_{i=1}^n w_i f(x_i) \quad \text{with} \quad \sum_{i=1}^n w_i = \frac{1}{2} \quad (57)$$

would yield a good approximation to the integral in question. Ref. 18 gives tables of the x_i and w_i for different choices of n. With such a set of (x_i, w_i) one would then write

$$\int_0^a dy \varphi(y, a) \approx 2a \sum_{i=1}^n w_i \varphi(a \eta_i, a) \quad (58)$$

where $\eta_i = x_i^{1/2}$. In fact, (58) has proved to be a surprisingly accurate approximation, and it seems rather difficult to justify mathematically the success of this procedure, which has been used widely in collision prob-

ability problems*. In our case, $n = 8$ was found to give an adequate compromise between speed and precision.

Hence, (56) is replaced by

$$P^* \approx \frac{1}{16\pi\lambda a} \sum_{i=1}^8 w_i \sum_{j=1}^{64} \varphi(a\eta_i, a_j) \quad (59)$$

where η_i and w_i are given below

i	η_i	w_i
1	0.001992	0.003295
2	0.020842	0.017843
3	0.082268	0.045439
4	0.206855	0.079200
5	0.394469	0.106047
6	0.617311	0.112506
7	0.825693	0.091119
8	0.984756	0.044551

We go a step further in refining the formula for P^* by reducing the discretization error. We observe that an expression quite similar to (59) exists for P_0 :

$$P_0 \approx \frac{1}{16\pi\lambda a} \sum_{i=1}^8 w_i \sum_{j=1}^{64} \varphi_0(a\eta_i, a_j) \quad (60)$$

where φ_0 is the function $\varphi(y, a)$ appropriate for an isolated fuel rod; (54) gives

*The method should presumably be credited to E. Tollander and I Carlvik, Sweden.

$$\varphi_0(y, a) = Ki_3(0) - Ki_3(\tau) = \frac{\pi}{4} - Ki_3(\tau) \quad (61)$$

As we already have an efficient algorithm for P_0 to our disposal we recast (59) to the following form

$$P^* \approx \frac{\sum_{i=1}^8 w_i \sum_{j=1}^{64} \varphi_0(a_{i1}, a_{ij})}{\sum_{i=1}^8 w_i \sum_{j=1}^{64} \varphi_0(a_{i1}, a_{ij})} \cdot P_0 \quad (62)$$

Formula (62) has the further advantage of yielding the exact limit P_0 when the cell expands towards the isolated fuel rod.

The evaluation of the Ki_3 -functions is performed by the function subprogram BIC3, developed originally by B. Tollander in connection with Carlvik's work⁶⁾. This procedure zeros $Ki_3(x)$ for $x > 10$, and this leads to a natural truncation of the infinite series in (54).

The calculation technique suggested in this Appendix has been programmed as to form the subroutine PINCA. PINCA delivers the 46 P^* -values discussed earlier. Computation of $P^*(\zeta)$ by linear interpolation in the $1/P^*$ -table so constructed is done by another subprogram, PS. For $\zeta > 6$ PS uses the approximation²⁾

$$P^*(\zeta) \approx P^*(6) \cdot \frac{6}{\zeta} \quad (63)$$

16. APPENDIX VI: A SELECTIVE INTEGRATION ROUTINE

The evaluation of the integral (31) is carried out by a special, selective integration routine SELIN. This was found useful because the integrand in (31) varies rather sharply around the resonance energy; as one wishes to limit the number N of integrand computations (here, $N = 1000$ was chosen) it is important to make a selective choice of the corresponding N abscissas.

SELIN does this in a crude, yet adequate manner. It works roughly in such a way that it divides the integration interval in a coarse equidistant subdivision. Thereafter, each of these subintervals Δ_i is submitted to a further subdivision in m_i new subintervals δ_{ij} , m_i being roughly proportional to the derivative of the integrand at Δ_i . Finally, Simpson's rule is applied to all subintervals and the results added. SELIN is in no way an "optimal" routine, but has nevertheless proved useful in the calculation of various definite integrals with a pronounced variation of the integrand.

SELIN is here supplied with function values from the function subprogram FCT.

17. APPENDIX VII: A FAST EXPONENTIAL ROUTINE

During the Monte Carlo calculations performed by MCSUP it is frequently required to calculate the exponential e^{-x} , or, more often, the function $1 - e^{-x}$. Of course the standard exponential function available at the computer may be applied, but in view of the rather limited demands for precision in Monte Carlo calculations it is better policy to use a faster routine and sacrifice some accuracy. Spanier and Gelbard²⁾ recommend the use of the so-called g -function defined by

$$g(x) = \frac{x}{1 - e^{-x}} \quad (64)$$

After tabulating $g(x)$ from e. g. 0 to 7 with steps of 0.2 it is possible by linear interpolation to calculate $g(x)$ to an accuracy within 0.1% for $x > 7$ they set $1 - e^{-x}$ equal to one.

Another alternative is to construct a simple polynomial approximation of $1 - e^{-x}$, and this method performed quite well on the IBM 7094 and was

$x = 0.1$	$g(x) = 1.0517$	$1 - e^{-x} = 0.0952$
$x = 0.2$	$g(x) = 1.1052$	$1 - e^{-x} = 0.1813$
$x = 0.3$	$g(x) = 1.1625$	$1 - e^{-x} = 0.2592$
$x = 0.4$	$g(x) = 1.2235$	$1 - e^{-x} = 0.3291$
$x = 0.5$	$g(x) = 1.2881$	$1 - e^{-x} = 0.3913$
$x = 0.6$	$g(x) = 1.3561$	$1 - e^{-x} = 0.4461$
$x = 0.7$	$g(x) = 1.4274$	$1 - e^{-x} = 0.4930$
$x = 0.8$	$g(x) = 1.5019$	$1 - e^{-x} = 0.5323$
$x = 0.9$	$g(x) = 1.5794$	$1 - e^{-x} = 0.5643$
$x = 1.0$	$g(x) = 1.6598$	$1 - e^{-x} = 0.5890$
$x = 1.1$	$g(x) = 1.7430$	$1 - e^{-x} = 0.6061$
$x = 1.2$	$g(x) = 1.8289$	$1 - e^{-x} = 0.6160$
$x = 1.3$	$g(x) = 1.9174$	$1 - e^{-x} = 0.6182$
$x = 1.4$	$g(x) = 2.0083$	$1 - e^{-x} = 0.6123$
$x = 1.5$	$g(x) = 2.1014$	$1 - e^{-x} = 0.5980$
$x = 1.6$	$g(x) = 2.1965$	$1 - e^{-x} = 0.5750$
$x = 1.7$	$g(x) = 2.2934$	$1 - e^{-x} = 0.5430$
$x = 1.8$	$g(x) = 2.3920$	$1 - e^{-x} = 0.5017$
$x = 1.9$	$g(x) = 2.4921$	$1 - e^{-x} = 0.4510$
$x = 2.0$	$g(x) = 2.5936$	$1 - e^{-x} = 0.3918$
$x = 2.1$	$g(x) = 2.6963$	$1 - e^{-x} = 0.3250$
$x = 2.2$	$g(x) = 2.8001$	$1 - e^{-x} = 0.2515$
$x = 2.3$	$g(x) = 2.9049$	$1 - e^{-x} = 0.1722$
$x = 2.4$	$g(x) = 3.0106$	$1 - e^{-x} = 0.0880$
$x = 2.5$	$g(x) = 3.1171$	$1 - e^{-x} = 0.0000$

adopted in MCSUP as the function subprogram OEXP. It was decided to divide the interval $0 < x < 8$ in four intervals in such a manner that third order polynomials chosen in the best possible way would yield absolute errors of almost the same magnitude in the four intervals. "Best possible" is understood in the Chebyshev sense, i. e. one minimizes the max. absolute error in each interval. The relevant approximation formula is given by Lance ⁷⁾:

$$\exp(kx) = I_0(k) + 2 \sum_{n=1}^{\infty} I_n(k) T_n(x), \quad -1 \leq x \leq 1 \quad (65)$$

where I_n is the modified Bessel function of first kind and order n , while $T_n(x)$ is the Chebyshev polynomial of degree n . By truncating (65) at T_3 and making a variable transformation, this formula yields the polynomial coefficients. After some numerical experimentation the interval subdivision and coefficients stated in OEXP (Appendix III) was obtained. The OEXP approximations are not quite those of the Chebyshev type, because small constant terms had been added in order to keep the mean arithmetic error in the whole range $0 < x < 8$ as low as possible, whereby $\int_0^8 e^{-x} dx$ calculated by OEXP becomes 1 with a high degree of precision (OEXP sets $1 - e^{-x}$ equal to one for $x > 8$).

The performance of the g-function method (G) and OEXP has been measured on an IBM 7094 (model I) with the result shown in the table below.

	G	OEXP
netto time (μ S) for a single call	240	180
root-mean-square error	$1.10 \cdot 10^{-4}$	$1.27 \cdot 10^{-4}$
max. error	$3.01 \cdot 10^{-4}$	$2.37 \cdot 10^{-4}$
abscissa for max. error	0.90	0.98
mean arithmetic error	$-0.73 \cdot 10^{-4}$	10^{-6}
mean absolute error	$0.73 \cdot 10^{-4}$	$1.13 \cdot 10^{-4}$
truncation error	$9.1 \cdot 10^{-4}$	$3.35 \cdot 10^{-4}$
zero value	0	$1.98 \cdot 10^{-4}$

The time for a call of the IBM 7094 standard function $1 - e^{-x}$ was found to 262 μ S.

18. APPENDIX VIII: OPTIMIZATION OF COMPUTER TIME FOR THE FOUR TYPES OF STARTERS

The resonance absorption rate was in sec. 3 expressed as the sum of 5 terms (eq. (40)), where one is deterministic and the remaining four are Monte Carlo terms. The combined Monte Carlo expression

$$R = -I_1 - I_2 + I_3 + I_4 = R_1 + R_2 + R_3 + R_4 \quad (66)$$

was composed of four mutually independent terms to be calculated separately according to the principles laid down in sec. 3. Now, some possibilities exist for carrying out a more refined composition of the terms in (66). Spanier and Gelbard ²⁾ propose a sampling technique, where the initial energy E is sampled from a combined density function, derived from the four individual density functions, whereafter the category of starter is selected. This procedure implies saving of computer storage.

In our case, small computing time rather than storage saving is at a premium, and then another approach is feasible.

We still calculate the four terms in (66) separately, but we assume that a certain amount of computer time T is at our disposal and try to find a division

$$T = T_1 + T_2 + T_3 + T_4 \quad (67)$$

where T_1 is the time spent in calculation of R_1 , so that a minimum-variance estimate of R is obtained. We have

$$\sigma^2(R) = \sum_1^4 \sigma^2(R_1) \quad (68)$$

At this point we assume that

$$\sigma^2(R_i) = \frac{k_i}{T_i} \quad (69)$$

where the k_i are known positive constants. Hence we minimize the functional

$$\varphi(T_1, T_2, T_3, T_4) = \sum_1^4 \frac{k_i}{T_i} \quad (70)$$

under the constraint (67). The method of Lagrange's multipliers yields easily the solution

$$T_i = \frac{\sqrt{k_i}}{\sum_1^4 \sqrt{k_i}} T \quad (71)$$

In practice we have to estimate the k_i . This is done in MCSUP by applying a preliminary computation with time length T' distributed equally with $T_i' = \frac{T'}{4}$ to each type of starters. Preliminary variance estimates

$$\sigma_i'^2 \cong \sigma^2(R_i') \quad (72)$$

are used to calculate k_i as

$$k_i = T_i' \sigma_i'^2 \quad (73)$$

Now (71) is recast to

$$T_i = \frac{\sigma_i'}{\sum_1^4 \sigma_i'} \cdot T \quad (74)$$

Hereafter the main calculation is executed. Utilizing also the preliminary calculation, we have

$$T_i'' = T_i - T_i' \quad (75)$$

where T_i'' is the time spent in calculation of R_i in the main calculation. The MCSUP program uses $T' = \frac{T}{4}$ and with this choice we finally obtain

$$T_i'' = \left(\frac{\sigma_i'}{\sum_1^4 \sigma_i'} - \frac{1}{16} \right) T \quad (76)$$

19. APPENDIX IX: COMPUTER DEPENDENT FEATURES OF MCSUP

MCSUP in its present form is intended for use on the IBM 7094 at the NEUCC center in Lyngby, Denmark. In view of the possibility of its use on other computers, we give in this appendix those features of the code that are specific for our system, and which perhaps have to be implemented in other ways for other machines.

19.1. The Timing Routine

It is essential that a timing routine is available. The call is of the type

CALL TIME (ICLOCK)

where the integer ICLOCK measures the computer time in units of 1/80 sec. The actual position of the zero on the time scale is irrelevant for our purpose.

19.2. The Random Number Generator

The random number calls are of the type

CALL RANDL (IX, R)

In our case, a standard multiplicative generator²³⁾ is used. IX is a current integer and is not used (yet it has to be initialized, cf. the input description in 6.1). R is the resulting random number between 0 and 1.

19.3. Input/Output Units

The symbolic nos. of the input and output units are 5 and 6 for the IBM 7094 at NEUCC. Only the statements

NIN = 5

NOU = 6

(at the beginning of the code print-out, cf. Appendix III) should be changed to fit other conventions.

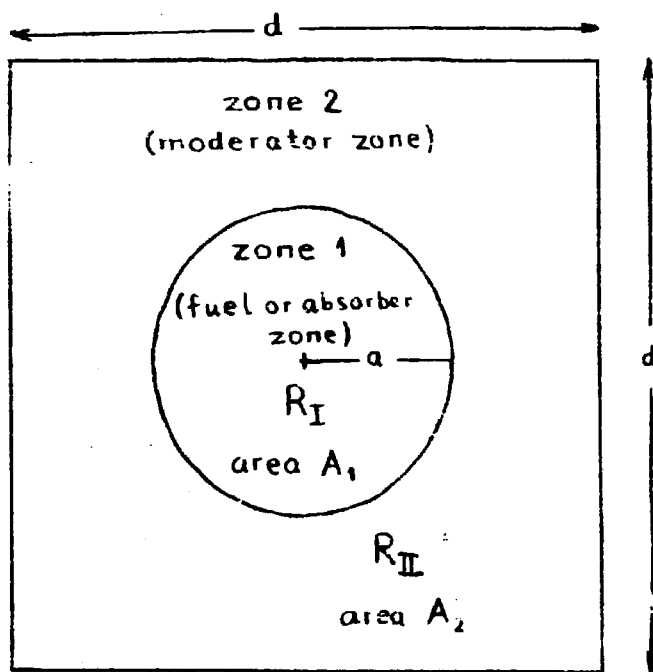


Fig. 1. MCSUP geometry

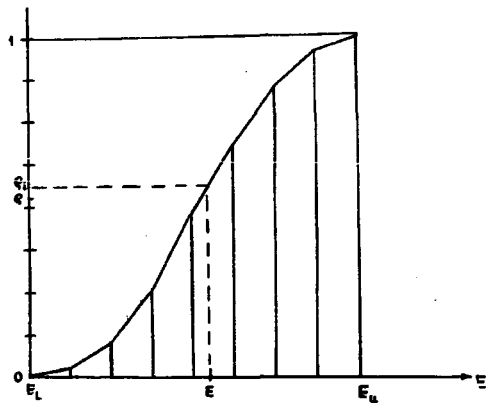
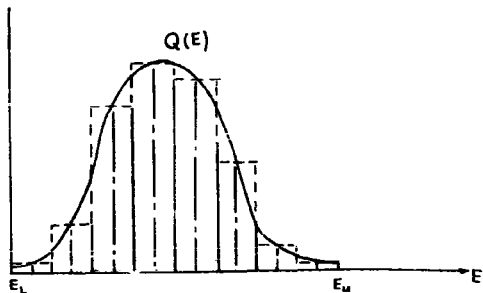


Fig. 2. Sampling of initial energy, schematic.

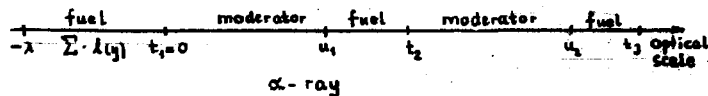
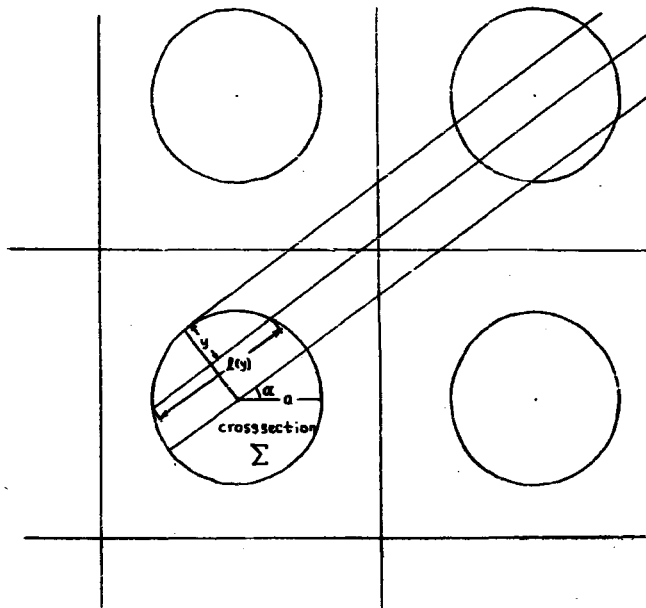


Fig. 3. Calculation of P^*