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Crystalline Electrical Fields in Dilute Rare Earths Studied by Neutron Scattering

by O. Rathmann

March 1976

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March 1976

Crystalline Electrical Fields in Dilute Rare Earths Studied by Neutron Scattering

by

O. Rathmann

Danish Atomic Energy Commission Research Establishment Risø Physics Department

Abstract

The spectra of the crystalline electrical field excitations were measured in the dilute rare earth alloys Y-1% Dy, Y-2% Er, Sc-2% Er and Lu-2% Er by means of inelastic neutron scattering. The results agree with earlier published papers reporting magnetization measurements on the same kinds of alloy, when an improved method of analysis, which takes ordering effects into account, is applied to the magnetization data.

In contrast to the first conclusion of these earlier papers, the present limited results suggest that the fourth- and sixth--order components of the crystalline electrical field $(B_{40}^{\ \ \beta}, B_{60}^{\ \ \gamma})$ and $B_{66}^{\ \ \gamma}$) are almost independent of both rare earth and diluent whereas $(B_{20}^{\ \ \alpha})$ depends on the diluent.

This report is submitted to the Technical University of Denmark, in partial fulfilment of the requirements for obtaining the Lic. tech. (Ph. D.) degree.

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CONTENTS

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			Page
ند ۱	1.	Introduction	5
	2.	Rare Earth Magnetism	5
x*		2.1. Dilute Rare Earths	7
		2.2. Crystalline Electrical Field	8
		2.3. Magneto-elastic Interaction	12
		2.4. Indirect Exchange Interaction	12
		2.5. Measurement of CEF in the Presence of Exchange	15
	3.	Technique of Neutron Scattering	15
		3.1. Neutron Spectrometer	16
		3.2. Resolution	17
		3.3. General Scattering Cross Section	20
		3.4. Nuclear Bragg Scattering	20
		3.5. Magnetic Scattering Cross Sections	22
		3.6. Scattering from a Modulated Magnetic Structure	23
		3.7. Inelastic Magnetic Scattering from Dilute Rare	
		Earths	23
	4.	Inelastic Neutron Scattering Experiments with Dilute	
		Rare Earth Alloys	25
		4.1. Samples, Orientation and Temperature Control .	25
•		4.2. Diffraction Study of Magnetic Order	27
		4.3. Inelastic Scattering Spectra	31
	5.	Analysis of Inelastic Scattering Experiments	37
		5.1. Least Squares Fit	37
		5.2. Y-2% Er	38
		5.3. Y-1% Dy, Sc-2% Er and Lu-2% Er	39
		5.4. Conclusion	40
	6.	Magnetic Ordering in Y-3% Dy Studied by Neutron	
		Diffraction	41
		6.1. Modulated Structure	41
		6.2. Temperature Dependence of (002) Satellite	43
		6.3. Example of Concentrated "Magnetic" System:	
		β -Brass	46
		6.4. Satellite Temperature Dependence Compared to	
		Concentrated Systems	46

	Page
Acknowledgements	47
References	48
Appendix I	50
Appendix II	53
Appendix III.	55
Appendix IV	60
Appendix V.	65

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1. INTRODUCTION

The rare earth metals are perhaps the most exciting of the magnetic elements. The paramagnetism observed in the pure metals, as well as in their alloys, is highly anisotropic, and exotically ordered magnetic structures appear at low temperature.

The main aim of this study was, by means of inelastic neutron scattering, to investigate the so-called Crystalline Electrical Field (CEF) of dilute rare earth alloys because the CEF is the dominant source of the anisotropy. This study was motivated by systematic magnetization measurements by Høg and Touborg on heavy rare earths diluted in non-magnetic matrices¹⁾. These measurements seemed to indicate that, in contrast to the predictions of the simple external charge model (see chapter 2), the rare earth itself was the decisive factor for the CEF.

In close contact with P. Touborg and in the light of the magnetization results, the CEF was therefore deduced from the completely different spectroscopic method of inelastic neutron scattering.

In connection with these measurements some neutron diffraction studies of ordered magnetic structures were additionally performed.

The main results were described in two papers^{2,3}; thus chapters 4 and 5, describing the measurements and the analysis, serve to gather together all results, making reference to the two papers where possible.

All the neutron scattering experiments were performed on triple-axis spectrometers at the DR 3 reactor at Risø.

2. RARE EARTH MAGNETISM

Rare earth magnetism is caused by the unfilled 4f electron $shell^{4)}$, which is quite analogous to the unfilled 3d shell in the iron group. However, because it is well placed inside the filled $5s^2p^6$ -shell, the 4f shell of a rare earth ion (with few exceptions the rare earths appear as tripositive ions in metals) is far better screened and localized than a 3d-shell in an iron-group ion. Quantitatively this means that, at least for the heavy rare earths, the interaction of a 4f shell with its surroundings, a

few hundred K in size, is smaller than the spin-orbit coupling of several thousand K (see Δ_0 in table 2.1) that is the smallest interaction inside a shell.

So, besides the quantum numbers for the total spin, S, and for the orbital angular momentum, L, the quantum number for the total angular momentum J(J = L + S) remains a good quantum number. In table 2.1 these quantum numbers are given for the heavy rare earth ions.



Fig. 2.1. Hexagonal, close-packed (hcp) structure. The structure consists of hexagonal layers stacked in the sequence AMAB The B-layers look exactly like the A-layers but are transposed $(\frac{2}{3} \pm + \frac{1}{3} \pm + \frac{1}{2} \pm)$ with respect to these. The heavy rare earths have c/a ratios about 41 lower than the ideal hcp value $\sqrt{\frac{2}{3}}$.

At and below room temperature all heavy rare earth metals, except Yb, appear in the hcp structure, shown on fig. 2.1. Although the local symmetry is trigonal, the 4f shell renses a hexagonal "effective" symmetry.

The Coulomb interaction between a 4f shell and the surroundings, which produces the magnetic properties, falls naturally into three contributions:



Ind. Exch.: Indirect exchange

3 ⁺ 108	Gđ	Th	Dy	ilo.	Er	10	T	La
H4£	7	•	•	16	11	12	13	14
L	0	3	5	6	6	5	3	•
s	7	3	52	2	3	1	1 2	0
J	7	ŧ	15	٠	15	6	7	0
9	2	32	4	5	\$	7	* 7	0
(g-1) ² (J+1)	J 15.75	10.5	7.08	4.50	2.55	1.17	0.32	0
∆ ₀ (¥)	-	2900	4700	7500	9400	11900	14800	
a2-10 ³ =a-10	o ³ -	-10.1	~6.35	-2.22	2.54	10.1	31.7	
34-10 ⁵ =d-10	9 ⁵ -	12.2	-5.92	-3.33	4.44	16.3	-173	
34-10	o [€] -	-1.12	1.03	-1.39	2.07	-5.60	148	

<u>Table 2.1</u> Quantum numbers and other electronic properties of the heavy tripositive rare earth ions⁶

 $g = \frac{3}{2} + \frac{S(S+1) + L(L+1)}{2J(J+1)}$ is the Lande splitting factor, and

 $\boldsymbol{\lambda}_{0}^{-}$ is the approximate splitting up to the first excited J-multiplet.

 x_2 , x_4 and x_4 are Stevens factors defined in eq. (2.1a).

2.1. Dilute Rare Earths

If a rare earth is sufficiently diluted by substitution in a non-magnetic host metal, the exchange interaction between the rare earth ions may be made negligibly small. In order to keep the CEF-interaction as close as possible to that of the pure rare earths, the non-magnetic diluent must have 1) a crystal structure nearly identical to that of the pure rare earths, and 2) the same outer electronic structure as the pure rare earths.

As seen in table 2.2, the non-magnetic metals Sc, Y and Lu are good candidates for such diluents⁵⁾.

Crystal structure (hcp)				Electronic structure		
	a (Å)	c (Å)	c/a			
Sc	3.309	5.273	1.594	(Ar) 3d 4s ²		
r	3.650	5.741	1.5750	(Kr) <u>4d 5s²</u>		
Lua	3.510	5.567	1.5797	(Kr) 4d ¹⁰ 4f ¹⁴ 5s ² p ⁶ 5d 6s ²		
Гb	3.601	5.694	1.5811	(Rr) 4d ¹⁰ 4f ⁸ 4f 5s ² p ⁶ 6s ²		
Dy	3.593	5.654	1.5735	(Kr) 4410 419 41 552p6 652		
Er	3.561	5.593	1.5706	(Kr) 4d ¹⁰ 4f ¹¹ 4f 5s ² p ⁶ 6s ²		

<u>Table 2.2</u> Crystallographic and electronic properties of rare earths and possible diluents.

The underlined part of the outer electronic configuration forms the conduction band.

The ideal hcp structure has a c/a = $\sqrt{\frac{8}{3}}$ = 1.6330

2.2. Crystalline Electrical Field

Disregarding the interaction between 4f spins for a moment, the simple picture of the origin of the CEF is this: The neighbouring ions around a given rare earth ion form a highly inhomogeneous charge distribution producing a non-uniform electrical field at the place of the 4f-shell.

As the unfilled 4f-shell is non-spherical, it will have preferred orientations in this field and consequently the 4f spin will have preferred directions.

For the rare earth hcp-metals this CEF may be described by 4 parameters. With the standard choice of coordinate system (xaxis along <u>a</u> and z-axis along <u>c</u>), the rystal field acting on the 4f electrons may be multipole expanded from the centre of the 4f-shell⁶:

$$V(\underline{\mathbf{r}}) = \sum_{l=0}^{\infty} \sum_{M=0}^{L} \mathbf{A}_{LM} \mathbf{P}_{LM}(\mathbf{x}, \mathbf{y}, \mathbf{z}).$$
(2.1)

The homogeneous polynomials P_{LM} (with integer coefficients) correspond to the spherical harmonics $r^L Y_{LM}(\phi, \theta)$ and the most important are given in table 2.3.

According to the Wigner-Eckart theorem, we may express V(r)in terms of the more suitable angular momentum variables by using the equivalence

$$P_{LM}(x,y,z) \sim \langle r^{L} \rangle \alpha_{L} \hat{O}_{LM}(\hat{J}). \qquad (2.1a)$$

Here the equivalence sign \sim means that the two operators have equal matrix elements between states of a 4f-shell with fixed J.

The most important of the Stevens operators $\hat{O}_{LM}(\hat{J})$ are given in table 2.3, while the Stevens factors α_L , depending on the rare earth, are listed in table 2.1. $\langle r^L \rangle$ is the L'th moment of the 4f radius decreasing somewhat through the series of tripositive rare earth ions⁷⁾. Two arguments limit the number of terms needed in the multipole expansion. The 4f-electrons (1=3) are insensitive to multipole components with L odd or with L > 6, and of the rest only 4 are consistent with the hcp symmetry. Using $B_{LM}^{+} =$ $\langle r^L \rangle \alpha_{T}^{-} A_{T,M}$ the CEF-Hamiltonian thus reads

$$H_{CEF} = B_{20} \hat{O}_{20} + B_{40} \hat{O}_{40} + B_{60} \hat{O}_{60} + B_{66} \hat{O}_{66}.$$
 (2.2)

For ideal hcp structure with only nearest-neighbour interaction, there are further simplifications⁵⁾:

$$A_{20} = 0$$
 (2.3)

$$A_{66} = -\frac{77}{8} A_{60}$$
 (2.4)

 $A_{20} = 0$ may be understood from a very simple argument. The local symmetry of an ion in an ideal hcp-structure (see fig. 2.1) may be changed to that of a fcc (face centered cubic) structure just by rotating one of the neighbouring hexagonal planes through 180° about the hexagonal axis which passes through the regarded ion. Now A_{20} only describes an axial anisotropy, singling out a particular crystallographic axis and is thus unchanged by this rotation. However, in the cubic fcc structure no single preferred direction exists and thus $A_{20} = 0$. The relation between A_{66} and A_{60} may be derived in a similar way. For non ideal hcp structures one may use a nearest neighbour point charge model to show that λ_{20} depends on the c/a ratio, approximately in proportion to

$$\left\{1 - \left[\frac{(c/a)}{(c/a)}_{ideal}\right]^2\right\}$$

Table 2.3

Some homogeneous polynomials P_k^q of even degree, frequently used in multiple expansions of CEP, together with their equivalent Stevens operators $\hat{O}_k^q(3)$. The notation (A B)_g is used as shorthend for $\frac{1}{2}(AB + BA)$. From⁶.

P1 = 321-71 $P_1^{\mathbf{i}} = x^{\mathbf{i}} \cdot y^{\mathbf{i}}$ PA == 35z4 - 30x4z2 - 3x4 $P_{A}^{a} = (7z^{a} - r^{a})(x^{a} - y^{a})$ $P_{i}^{b} = x z (x^{2} - 3y^{2})$ $P_{i}^{i} = x^{i} - 6x^{i}y^{i} - y^{i}$ $P_{4}^{0} = 231z^{0} - 315r^{3}z^{4} + 105r^{4}z^{3} - 5r^{0}$ $P_{4}^{0} = (11z^{0} - 3r^{0})(z^{0} - 3y^{0})zz$ $P_{n}^{4} = (1)z^{4} - r^{4}(z^{4} - \theta z^{2}y^{2} - y^{4}) \qquad P_{n}^{4} = z^{4} - 10z^{4}y^{4} - 10z^{4}y^{4} - y^{4}$ $k = 2 \qquad \begin{bmatrix} D_1^0 = 3J_1^0 - J(J-1) \\ D_2^0 = \frac{1}{2}(J_1^0 - J_2^0) \end{bmatrix}$ $\begin{bmatrix} \mathcal{O}_{0}^{0} = 35J_{1}^{0} - 30J(J - 1)J_{1}^{0} + 25J_{1}^{0} - 6J(J - 1) - 3J^{2}(J - 1)^{2} \end{bmatrix}$
$$\begin{split} k = 4 & \qquad \{ O_4^2 = \frac{1}{2} \{ (\tilde{J}_4^2 - J(J-1) - 5) (J_4^2 - J^2) \}_{\rm p} \\ O_4^2 = \frac{1}{2} \{ J_4 (J_4^2 - J_2^2) \}_{\rm p} \end{split}$$
11 = +(J + - J +) $[D_4^0 = 231J_4^0 - 315J(J - 1)J_4^0 - 735J_4^0 - 105J^2(J - 1)J_4^0 - 525J(J - 1)J_4^0]$ $294J_1^6 = 5J^6(J = 1)^6 = 46J^4(J = 1)^6 = 60J(J = 1)^6$ $O_{\theta}^{4} = \frac{1}{2} \{ (11J_{\theta}^{4} - J(J-1) - 3B)(J_{\theta}^{4} - J_{\theta}^{4}) \}_{g}$ $LO_{\bullet}^{\bullet} = \frac{1}{2}(J_{\bullet}^{\bullet} - J_{\bullet}^{\bullet})$

For pure and dilute rare earths with c/a ratios close to the ideal value, we may thus expect a rapid $\frac{c}{a}$ -dependence of A_{20} , and (2.4) may be a good approximation.

The calculation of the matrix elements of H_{CEF} , which are necessary to determine the CEF-splitting, is a standard calculation and the details are given in appendix 2. One important result is that only matrix elements $\langle m | O_{T,M} | m' \rangle$ with |m-m'| = M are non-zero.

The crystal field splitting is found (first order perturbation calculation) by diagonalizing the crystal field Hamiltonian, the eigenvalues giving the energy levels and the eigenfunctions giving the wavefunctions of the levels. As H_{CEF} has a restricted number of non-zero matrix elements, the eigenfunctions are composed of at most three components. For example, for Er and Dy with J = 15/2, the following three types of mixings are found, all states being Kramers doublets:

1)
$$a_1 \pm 15/2 + b_1 \pm 3/2 + c_1 \neq 9/2 >$$
,

- 2) $a \pm 13/2 > b \pm 1/2 > c \mp 11/2 >,$
- 3) $a \pm 7/2 > + b \mp 5/2 > .$

From the level scheme and the eigenfunctions follow the magnetic properties of the 4f ion, such as susceptibility and neutron scattering cross section.

Although the Hamiltonian (2.2) is based on an "external charge model" it is the most general CEF Hamiltonian for a 4f ion in hcp symmetry.

The specific property of this simple model is that the λ_{LM} 's are determined completely by the surroundings of the 4f ions. If we neglect the small variance of $\langle r^L \rangle$ through the series of heavy rare earths, this means that for a rare earth ion, diluted in a non-magnetic hcp-host, the parameters B_{LM}/α_L depend solely on the host.

Some comments on the external charge model are necessary.

First, the conduction electrons are not uniformly distributed but may be concentrated between the ions.

Second, the $5s^2p^6$ shell will have a screening effect, so that the 4f-shell will not feel the full value of the external charges.

By use of simple methods these complications may be contained within the framework of the external charge model. Furthermore because the screening effect of the $5s^2p^6$ shell must be nearly the same for all rare earths, this model still predicts that the parameters B_{LM}/α_L of a dilute rare earth depend almost solely on the diluent.

However, a third objection⁸⁾ makes it necessary to consider the possibility that these C_{EF} -parameters also depend on the 4fion itself. As neither the 4f-shell nor the 5d-shell are filled, the Pauli exclusion principle does not prevent the conduction electrons from having a 4f and 5d character, but the wave functions of the conduction electrons must still be orthogonal to the wave function of the 4f shell. The resulting correlation, the strength of which will depend on the number of 4f electrons, makes the 4f shell feel the CEF also "through" the conduction electrons. So, if these correlation effects are strong enough, the observed CEF interaction will depend both on the diluent and on the rare earth.

2.3. Magneto-elastic Interaction

The magnetic interaction of 4f ions with lattice distortion is closely connected to the CEF-interaction. The ME-interaction arises from the shift in CEF-energy caused by a lattice distortion.

For example, in Tb this shift is responsible for the magnetostriction, the spontaneous lattice distortion produced by a macroscopic moment, which may be ferromagnetic or produced by an external field.

2.4. Indirect Exchange Interaction

The interaction Letween the 4f spins is caused by the conduction electrons through indirect exchange. Also dipole interaction exists, but it is negligibly small compared to the indirect exchange. The mechanism⁹⁾ is that one 4f spin, by exchange interaction, polarizes the conduction electrons which in turn interact with neighbouring 4f-spins. We shall denote the lattice sites of 4f ions $\underline{R}_{\underline{L}}$ and their total angular momentum operators $\hat{\underline{J}}_{\underline{L}}$. If the spin-orbit coupling of the conduction electrons is neglected, the total indirect exchange energy takes the simple Heisenberg form

$$H_{ff} = -\sum_{L>L'} \widetilde{J}(\underline{R}_{L} - \underline{R}_{L'}) \hat{\underline{J}}_{L} \cdot \hat{\underline{J}}_{L'}$$
(2.5)

As a consequence of the shape of the Fermi surface, the exchange interaction is long-ranging and oscillating, and this causes the rare earths to order magnetically in modulated, oscillatory structures.

From simple mean field theory (i.e. neglecting spin fluctuations) one finds that J_L^{α} , the time-average cartesian components of the 4f-spins in the ordered structure, will be proportional to $\cos(\underline{Q} \cdot \underline{R}_{L})$. Here \underline{Q} is the point of absolute maximum of $\mathbf{J}(\underline{q})$, the Fourier transform of $\mathbf{J}(\underline{R}_{L})$. This modulation appears in a certain range at and below a Néel temperature, which is given in mean field theory by

$$T_{N} = J(J + 1)(g - 1)^{2} \frac{I(Q)}{3k}$$
 (2.7)

analogous to ferromagnets.

In the heavy rare earths $\underline{Q} = \underline{\tau}_{ool} \xi$, $\xi = 0.1 - 0.3$, where $\tau_{ool} = \frac{2\pi}{c}$ is the c-direction reciprocal lattice vector for the hcp structure. This means that on going from one hexagonal layer to the next, the modulation phase is increased with an interlayer angle = $Q \cdot \frac{c}{2}$, ranging from 20° (Tb) to 50° (Tm) just below T_N^{10} .

Also anisotropic exchange will give modulated structures. Together with the CEF-interaction the effect of the anisotropic exchange is to favour some of the spin directions, and thus to determine the actual form of the modulated structure.

However, when the mean spin components are sine-modulated with no net macroscopic magnetization, the structure may be described by a general expression, using a complex polarization vector μ :

$$\langle \underline{J}_{I} \rangle = \operatorname{Re} \{ \underline{\mu} \ e^{\underline{i}\underline{Q}} \cdot \underline{R}_{I} \}$$
 (2.8)

The actual form is shown below for the two simplest cases, the spiral structure and the c-axis-modulated (CAM) structure:



 μ = $\mu(T)$ is temperature dependent, increasing from 0 as T is lowered from $T_{\rm N}.$

This description also applies to the dilute rare earths. The exchange interaction just seems to be "diluted". The important parameter in this connection is the de Genne's factor

$$x = c(g-1)^2 J(J+1)$$
 (2.9)

where c is the atomic concentration.

As can be seen from fig. 2.2, both the Néel temperature T_N and the interlayer angle at T_N are nearly universal functions of x.

Saturation effects appear at temperatures sufficiently below T_N . For instance, a sine modulation may become square-like, and also the interlayer angle may change somewhat.

Like ferromagnetic structures, modulated structures also support magnons, i.e. spin waves consisting of deviations from the values of the ordered structure.



Fig. 2.2. The ordering temperature T_N and the interlayer angle at T_N are nearly universal functions of the average squared projection of S on J. From ref. 10.

2.5. Measurement of CEF in the Presence of Exchange

In general, the CEF levels break down more or less in the presence of indirect exchange interaction. However, above the Néel temperature and with moderate exchange, we may imagine the CEF levels to be fairly well defined, but as a consequence of the exchange the local CEF excitations, say from the ground state level, are replaced by collective excitations, excitons, with wavevector \mathbf{q} and excitation energies $h\omega = h\omega(\mathbf{q})$ with dispersion. In addition, we may expect a broadening (finite lifetime) of these excitations due to the fluctuations of the exchange field (= the sum of all exchange interactions on a certain 4f ion).

In pure rare earth metals where the exchange interaction is strong, it is very difficult to measure the CEF parameters. At low temperature, where the CEF effects are clearest (only ground state level populated) the magnetic ordering Cominates, and it is hard to distinguish between CEF and anisotropic exchange.

These complications are reduced in the dilute rare earths as all exchange interactions are much smaller than in the pure metals, simply because each 4f ion has far fewer 4f-ions as near neighbours, and T_N is accordingly low. However, even above T_N the CEF levels may be exchange-broadened by the fluctuating exchange field, perhaps enlarged by the random distribution of the rare earth ions. On the other hand, the oscillating long-range nature of the indirect exchange tends to make this effect small because the exchange field is some average over a large number of neighbours.

3. TECHNIQUE OF NEUTRON SCATTERING

As well known, one can observe the crystallographic structure and the lattice vibrations of a solid by neutrons scattered from the solid through nuclear interactions. Thermal neutrons (10-100 meV) are well suited because the de Broglie wavelength at these energies (1-3 Å) is of the same size as the interatomic distances. As neutrons carry a magnetic moment, they also interact magnetically with matter, so by neutron scattering one can also observe magnetic structures and magnetic excitations - neutron scattering is in fact the most direct way of observing these phenomena.

- 15 -

The triple-axis crystal spectrometer for neutron scattering is sketched in fig. 3.1:



Fig. 3.1. Triple-axis crystal spectrometer. From the "white" reactor beam a monochromatic beam of neutrons is extracted by Bragg scattering from a monochromator crystal. The monochromatic, i cident neutrons with wavevector <u>k</u> interact with the sample, and by the analyzer system (same principle as the monochromator system) and a counter the intensity is measured of neutrons scattered to wavevector <u>k</u>', $h_{\rm T}$ and $-\omega$ are the momentum and energy transfer of the observed scattering.

The spectrometer has three variable scattering angles: at the monochromator (θ_{M}) , at the sample, and at the analyzer (θ_{A}) . In addition, the sample can be rotated around a vertical axis. The four axes of the Risø spectrometers are set by motors controlled by a computer that converts momentum and energy transfers (A^{-1}) and meV) into the angle settings. Thus the experimentalist may work directly in $(\underline{x}, \hbar\omega)$ space after a calibration.

The intensity is measured for each setting by counting scattered neutrons for a preset time, or for a preset number of beam monitor counts (BMC). The beam monitor is a low efficiency counter, placed so that the incident monochromatic beam penetrates. Consequently, use of preset BMC automatically corrects for fluctuations in the reactor neutron flux. The number of neutron counts N has a standard error \sqrt{N} , according to Poisson statistics (valid for N > 10).

One disadvantage of the crystal monochromator system is the order contamination, which has the effect that, if set for a wave-vector \underline{k} , the monochromator system also lets through neutrons with wavevectors $2\underline{k}$, $3\underline{k}$, although with decreasing intensity. The order contamination, which also occurs in the analyzer system, may be removed by filters.

In this study use was made of graphite filters, which have a very deep minimum in neutron transmission at 57.6 meV. In order to use this minimum to reduce the second-order contamination, a primary neutron energy of 57.6/4 = 14.4 meV (k = 2.636 Å⁻¹) was used. When scanning in the ($\underline{\mathbf{x}}$, h $\boldsymbol{\omega}$) space either the monochromator or the analyzer system is kept fixed (except for very special cases), and the filter is mounted in the fixed system.

As the reactor beam normally emerges from a water moderator with a temperature around room temperature, the intensity of the incident monochromatic neutron beam depends on the energy with maximum intensity around 25 meV. However, after the installation of the cold source (liquid H_2 around 30 K) at the DR 3 reactor, the intensity of neutrons with energies as low as 5 meV has been sufficiently raised to use them for scattering experiments that require high intensity (such as scattering from CEF transitions).

3.2. Resolution

If we denote the flux of incident neutrons (per m^2 and second) F_{inc} and denote the intensity of scattered neutrons (per second) I_{sc} then the neutron spectrometer in principle measures the partial scattering cross section

$$\frac{d^2\sigma}{d\Omega dE'} = \frac{1}{F_{inc}} \cdot \frac{d^2I_{sc}}{d\Omega dE'}$$

where $d\Omega$ is an element of solid angle around the direction of $\underline{k}^{\,\prime}$.

As explained in appendix 3, the instrument has a finite resolution and a total efficiency depending on the setting $(\frac{4}{20}, \omega_0)$. Thus the number of neutrons detected per second is given as a convolution integral of the cross section and a resolution function $R(\underline{\mathbf{x}}-\underline{\mathbf{n}}_{O}, \omega-\omega_{O})$, see eq. (A 3.4), which implicitly also depends on $\underline{\mathbf{n}}_{O}$ and $\underline{\mathbf{u}}_{O}$. This function has approximately Gaussian dependence on $(\underline{\mathbf{x}}-\underline{\mathbf{n}}_{O})$ and $(\omega-\omega_{O})$, while the implicit dependence on $\underline{\mathbf{n}}_{O}$ and ω_{O} is rather weak.

Appendix 3 gives the different "sources" of the resolution from which it is possible to approximately calculate the resolution function, e.g. the important pure energy resolution. The most relevant results of the appendix are given here.



Fig. 3.2. Sensitivity factor normalized to unity at $\omega_0 = 0$ for fixed monochromator energy = 14.4 meV and pyrolytic graphite in (002) reflection as analyzer. Varying resolution, counter efficiency, analyzer reflectivity and the factor $\frac{k^2}{k}$ are included. The sensitivity was checked by the integrated intensity (open circles) of some phonons in the Y-2% Er sample at T = 300 K.

At the setting $\omega_0 = 0$ the shape of the resolution function may be determined experimentally. The resolution width in any direction in the $(\underline{\mathbf{w}}, \omega)$ space may be determined from a Bragg reflection, while the pure energy width, uncorrelated to $\underline{\mathbf{w}}$, may be measured by scattering from vanadium, a nearly purely incoherent scatterer. In fig. 3.3 the resolution energy as a function of the setting ω_0 is shown for relevant cases, and the values for $\omega_0 = 0$ are checked by V-scans. In most cases in this study the energy resolution was around 1 meV using $E_{MON} = 14.4$ meV. A much finer resolution of 0.2 meV may be obtained at $E_{MON} = 5$ meV, but at the cost of a drastic fall in the incident neutron intensity.



Fig. 3.3. Energy resolution widths for typical collimations and scan types. The (002) reflection of pyrolytic graphite is assumed for monochromator and analyzer. The widths are defined as the full width at half maximum (FWNM), as shown in the V-scans in the left column. The right column shows the widths as functions of $h_{\rm NW}$, and the widths of the corresponding V-scans are indicated. The use of 5 meV incident neutrons gives a very fine resolution of 0.2 meV.

In many cases only the total inelastic cross section is important, and not the shape, e.g. when the cross section is a sharp, δ -like function peaking around $\omega = \omega^*$. In this case one may use the integrated intensity $u = \int I(\underline{m}_0, \omega_0) d\omega_0$, which is connected to the total inelastic cross section by a simple m-independent sensitivity $s(\omega^*)$, see eq. (A 3.8). Figure 3.2 shows the sensitivity function valid for most of the measurements in this study.

3.3. General Scattering Cross Section

We will now go through the relevant neutron scattering cross sections linking the spectra of scattered intensity and the structures or excitations in the investigated sample. As unpolarized neutrons (random spin orientation) were used in this study, this sort of neutron beam will be assumed in the following.

The master formula for all scattering cross sections is the Born approximation. We denote all possible initial and final target states by $\{\lambda >, P_{\lambda} \text{ (pichability of state } \lambda) \text{ and } \{\lambda > \text{ and their energies by } E_{\lambda} \text{ and } E_{\lambda}^{*}$.

In the same manner the initial and final neutron states are $|k\sigma\rangle$ and $|k'\sigma'\rangle$ (σ = spin state, P_{σ} = probability of spin state). If we further denote the neutron mass by m and let \hat{V} be the neutron-target interaction potential, the Born approximation to the partial cross section reads¹¹

$$\frac{d^{2}\sigma}{d\Omega dE^{*}} = \frac{k^{*}}{k} \left(\frac{m}{2\pi\hbar^{2}}\right)^{2} \sum_{\lambda\sigma} P_{\lambda}P_{\sigma} \sum_{\lambda'\sigma'} \left| \langle \underline{k}'\sigma'\lambda' | \hat{v} | \underline{k}\sigma\lambda \rangle \right|^{2} \delta(i\omega + E_{\lambda} - E_{\lambda}). \quad (3.1)$$

This master formula is, of course, rather useless in practice unless specific cases are considered, and in the following the cross sections relevant to this study will be given.

3.4. Nuclear Bragg Scattering

Perhaps the best known kind of scattering is the elastic nuclear Bragg scattering from single crystals (the cross section is derived in standard test books). Let the crystal have reciprocal lattice vectors $\underline{\tau}$ and let it consist of N unit cells of volume V_{0} . The Bragg cross section is then

$$\frac{d^{2}\sigma}{d\Omega dE^{T}}\Big)_{Bragg} = \frac{N(2\pi)^{3}}{V_{O}} \sum_{\tau} \delta(\underline{u} - \underline{\tau}) |F_{N}(\tau)|^{2} \delta(\hbar\omega). \qquad (3.2)$$

Two important features are observed: first, the scattering is purely elastic; second, scattering will only be observed when the spectrometer setting corresponds to a wave vector transfer \underline{x} coincident with a reciprocal lattice vector $\underline{\tau}$ of the crystal.

In general, the intensity of a reflection depends on $\underline{\tau}$ through the structure factor

$$\mathbf{F}_{\mathbf{N}}(\underline{\tau}) = \int_{\underline{d}} e^{\underline{i}\underline{\tau}\cdot\underline{d}} b_{\underline{d}} \exp\left(-\mathbf{W}_{\underline{d}}(\tau)\right), \qquad (3.3a)$$

where <u>d</u> is the position of atoms inside the unit cell and $b_{\underline{d}}$ is the coherent scattering length of the atom at site <u>d</u>. exp $-\overline{W}_{\underline{d}}(\tau)$] is the so-called Debye-Waller factor, accounting for the "smearing out" of lattice points because of lattice vibrations. In the harmonic approximation we have

$$W_{\underline{d}}(\mathbf{x}) = \frac{1}{2} < (\underline{\mathbf{x}} \cdot \underline{\mathbf{u}}_{\underline{d}})^2 >_{av.} , \qquad (3.3b)$$

 $\underline{u}_{\underline{d}}$ being the atomic displacement from the mean position. With only one type of atom (3.3a) is simplified to $F_{N}(\tau) = b e^{-W(\underline{\tau})} G(\underline{\tau})$ with the geometric structure factor

$$G(\underline{\tau}) = \sum_{\underline{d}} e^{\underline{i}\underline{\tau}\cdot\underline{d}} . \qquad (3.4)$$

A Bragg reflection is denoted by its Bragg indices (hkl). This means that $\underline{\tau}_{(hkl)} = h \underline{a} + k \underline{b} + l \underline{c}$, where $(\underline{a}, \underline{b}, \underline{c})$ are the basis for the reciprocal lattice. Table 3.1 gives the properties of the reciprocal lattice of an hcp structure and the geometrical structure factor $G(\underline{\tau}_{hkl})$.

The Bragg scattering is a result of the interference between scattered neutron waves and thus it involves the coherent scattering length b, corresponding to the mean neutron/nucleus interaction. Besides, the fluctuations (nuclear spin, 1sotopes) in this interaction cause the incoherent scattering. Due to the lack of interference, this scattering is uniformly distributed in all directions. Vanadium is a well known example of a nearly pure incoherent scatterer.

Tabl	•	3	•	ı
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Properties of the reciprocal lattice corresponding to the hop structure. FA, FM, and FK are the group theoretical notation for the symmetry directions.

	hki	Direc	tion of 1	Equivalent directions	G(T) ²
	(0 (1)	Γ Α ,	c-axis	······	0
٠	(0 0 2)	Γ Α ,	C-axis		4
•	(1,0,0)	ſΗ,	C-axis	± (0,1,0)	1
				± (1,-1,0)	
•	(1,1,0)	ΓК.	<u>l</u> ~axis	± (1,-2,0)	4
				1 (2,-1,0)	
	(1 0 1)				3

3.5. Magnetic Scattering Cross sections

The magnetic scattering cross sections are somewhat more complicated because the magnetic moment, which interacts with the neutron, is distributed over an area comparable with the neutron wavelength, and also because of the directional properties of the magnetic interactions. In the dipole approximation, valid when $\mathbf{x} \cdot \mathbf{r}_{s} \ll 1$ (\mathbf{r}_{s} = extent of an atomic spin), the magnetic scattering from an isolated atomic spin with conserved J(e.g. a 4f~ion) corresponds to a "magnetic scattering length" operator

 $P_{O} g f(x) J^{\perp}$

Here $\underline{J^{\perp}} = \frac{1}{n^2} \times \underline{n} \times (\underline{J} \times \underline{n})$ is the component of \underline{J} that is $\underline{[n]}, f(n)$ is the magnetic form factor (= Fourier-transformed spin density) going to 1 when $n \cdot r_s \div 0$, g is the Lande factor and $p_0 = \frac{1}{2} 1.91 \frac{e^2}{m_e c^2} = 2.69$ fm is the scattering length per Bohr magneton. The magnetic scattering from a single crystal without lattice vibrations and with one type of magnetic atom, located at sites \underline{R}_t , is thus described by the cross section¹³

 $\frac{d^{2}c}{d\Omega dE'} = (\mathbf{p}_{0} \ \mathbf{gf}(\mathbf{x}))^{2} \frac{\mathbf{k}'}{\mathbf{k}} \sum_{\lambda \lambda'} \mathbf{p}_{\lambda} \sum_{\mathbf{L}, \mathbf{L}'} \mathbf{e}^{\mathbf{i}\mathbf{k} \cdot (\mathbf{R} - \mathbf{R})}_{\mathbf{L}, \mathbf{L}'} \times \frac{1}{2} \lambda^{2} \lambda^{2} \lambda^{2} \cdot \frac{1}{2} \lambda^{2} \lambda^{2} \cdot \frac{1}{2} \lambda^{2} \lambda^{2} \lambda^{2} \cdot \frac{1}{2} \lambda^{2} \lambda^{2}$

This general expression is reduced when we consider the specific cases, e.g. elastic scattering from an ordered structure or inelastic scattering from crystal field transitions, that are relevant here.

3.6. Scattering from a Modulated Magnetic Structure

A modulated magnetic structure described by e.g. (2.8) with $\underline{Q} \neq \frac{1}{2} \times (any \ reciprocal \ lattice \ vector \ \underline{\tau})$ has an elastic magnetic cross section¹⁰

$$\frac{d^{2}}{d\Omega dE} \left(\right)_{\text{El.magn.}}^{2} = \frac{N(2\pi)^{3}}{v_{0}} \frac{1}{4} \underline{\mu} \cdot \underline{\mu} \left(p_{0} g f(\mathbf{x}) \right)^{2}$$

$$\sum_{\sigma} G(\tau) \left\{ \delta(\mathbf{x} - \tau + Q) + \delta(\mathbf{x} - \tau - Q) \right\} \delta(h\omega)$$

$$\underline{\tau}$$
(3.6a)

Similar to J^{\perp} , μ^{\perp} is the component $\lfloor \underline{n} \rfloor$, and $G(\tau)$ is the geometrical structure factor.

It is seen that the magnetic scattering is concentrated in satellites $\underline{\mathbf{x}} = \underline{\tau} \pm \underline{\mathbf{Q}}$ around each nuclear Bragg reflection. Through $\underline{\mu}^{\pm} \cdot \underline{\mu}^{\pm}$, the τ -dependence of the satellite intensities contains information about the polarization in the structure. In the heavy rare earths we have for the most frequent cases:

	<u>н</u>	<u>⊬</u> ⊥•⊭*⊥	
spiral	(µ, iµ, O)	$\mu^2(1+\cos^2\theta)$	$\theta = <(x, c-axis)(3.6b)$
САМ	(0,0,µ)	$\mu^2 \sin^2 \theta$	_

3.7. Inelastic Magnetic Scattering from Dilute Rare Earths

We now turn to a dilute rare earth alloy containing N_{RE} rare earth ions. We shall assume that the rare earth concentration is small enough to make the exchange interaction between the rare earth ions negligible. In this case the spins J_L are uncorrelated, and the cross section (3.5) reduces to N_{RE} (single-ion cross section). We denote the energies and states of the crystal field levels E_n and $|\Gamma_n|v>$, v labelling the degenerate states of the

$$\frac{d^2\sigma}{d\Omega dE^{\dagger}}\Big)_{CEF} = N_{RE} \frac{k'}{k} A(x) \sum_{nn'} T_{nn'} \delta(E_n - E_{n'} + h\omega) \qquad (3.7)$$

with

$$A(\mathbf{x}) = [p_0 g f(\mathbf{x})]^2 e^{-2W(\mathbf{x})},$$

and the transition probability

$$T_{nn'} = P_n \sum_{vv'} \langle v \Gamma_n | \underline{J}^{\perp} | \Gamma_n, v' \rangle \langle c.c. \rangle$$

By definition, the ground state energy $E_0 = 0$.

In an energy scan with $\underline{\mathbf{x}}$ kept fixed, each transition $\Gamma_{\mathbf{n}} + \Gamma_{\mathbf{n}}$, will possibly give rise to a peak in the intensity spectrum at $h_{\omega} = E_{\mathbf{n}} - E_{\mathbf{n}}$. Under the present assumption of negligible exchange interaction, the transition energies do not depend on the chosen wavevector transfer $\underline{\mathbf{x}}$, but as \mathbf{x} is increased the transition intensities will fall smoothly in proportion to $\frac{\mathbf{k}^{\prime}}{\mathbf{k}} f(\mathbf{x})^2 e^{-2W(\mathbf{x})}$. Of special interest is the dependence of the intensity on

Of special interest is the dependence of the intensity on the orientation of $\underline{\mathbf{k}}$ with respect to the crystal axes. This dependence derives from $\underline{\mathbf{J}}^{\perp}$. Through this dependence, additional information may be obtained on the wave functions $[]_{\mathbf{k}}^{\perp} \mathbf{v}^{*}$.

As mentioned in chapter 2, the effect of residual exchange interaction will be 1) level broadening, and 2) dispersion (i.e. \underline{x} -dependence) of the excitation energies \underline{E}_n . To estimate the dispersion, the energy scans need only be performed for \underline{x} -values throughout one Brillouin zone.

The <u>intensity</u> of some transition $\Gamma_n \neq \Gamma_n$, depends on the temperature through the probability P_n . At low temperatures, i.e. $kT \ll E_1$, a Kramers doublet ground state will have $P_0 \sim \frac{1}{2}$ and other states $P_n \sim 0$. Such temperatures are experimentally preferable as only transitions $\Gamma_0 \neq \Gamma_n$ are observed, giving simple spectra with only neutron energy loss. With increasing temperature, the corresponding scattering intensities will fall in proportion to P_0 .

In contrast, the scattering intensity from a phonon¹²⁾ with frequency $\omega_p \frac{\text{increases}}{2}$ both with T and *, as it is proportional to *² $(n(\omega) \pm \frac{1}{2})$, where $n(\omega) = [\exp(\frac{h\omega}{kT}) - 1]^{-1}$ is the Bose population number. This dependence also applies to other types of lattice vibration such as local modes. Thus, scattering from CEF transitions can easily be distinguished from phonon scattering by the * - and T-dependence of the intensity because it is totally different in the two types of scattering.

4. INELASTIC NEUTRON SCATTERING EXPERIMENTS WITH DILUTE RARE EARTH ALLOYS

This chapter reports on neutron spectroscopic investigations of the CEF levels in some dilute rare earth alloys.

4.1. Samples, Orientation and Temperature Control

Five samples were investigated; each consisted of one or two large single crystals with a total weight of 4-20 g. The detailed compositions and weights are given in table 4.1.

Table 4.1

Sample properties

Alloy [#]	Number of single crystals	Vertical cryst. axis	Total weight (g)	Abscrption
Y-3.0% Dy	1	[110]	4.5	0.58
Y-1.18 Dy	1	[110]	9.2	0.34
Y-2.0% Er	2	[100]	22.5	0.18
Sc-2.0% Er	2	[100]	7.9	0.65
Lu-2.0% Er	2	[100]	10.7	0.79

The absorption is calculated for 14.4 meV neutrons taking the shortest route through the sample.

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Throughout this report all the percentages are atomic percentages.

The crystals were prepared by P. Touborg by arc-melting and strain annealing¹⁵⁾ of the alloy. Finally, suitable single crystals were spark-cut. A primary orientation within a few degrees was performed on an X-ray diffractometer.

The crystals were mounted on standard sample holders made of Al. The orientations of the samples are given in table 4.1, the vertical axis being perpendicular to the scattering plane and hence to \underline{w} .



Fig. 4.1. Y-2% Er sample mounted on a standard sample holder of Al The two crystals were kept in orientation by means of Al pins inserted in spark-cut holes in the crystals.

Figure 4.1 shows the mounting of the Y-2% Er sample. As was the case for all the samples with Er, the two crystals were held correctly orientated with respect to one another by means of small Al-pins. In order to avoid neutron scattering from screws, etc., close to the crystals, such parts were shielded by the neutronabsorbing metal Cd.

During a neutron scattering experiment the sample on the sample holder was mounted in a He-flow-cryostat designed for neutron scattering. The sample was surrounded by He exchange gas, ensuring thermal equilibrium with the so-called temperature block that contained a heater and a thermosensor. An electronic temperature controller allowed the sample temperature to be kept constant with an accuracy around 0.1 K, and temper: tures down to 4.5 K could be reached. Calibrated Ge- and GaAs-thermosensors were used.

The cryostat was fastened to a large goniometer on the spectrometer sample table, allowing a final adjustment of the sample orientation. This was done by maximizing the intensities of two Bragg reflections with $\underline{\tau}$ in the scattering plane and perpendicular to one another: (002), (110) for the Er-samples and (002), (200) for the Dy-samples.

4.2. Diffraction Study of Magnetic Order

At the lowest possible temperature the samples were investigated for magnetic order. With $h\omega = 0$ scans of the wavevector transfer <u>w</u> were performed through the points (in reciprocal space) of possible magnetic satellites $(h,k,1) = (0,0,2-\zeta)$, $(0,0,2+\zeta)$, $(1,1,\zeta)$ or $(1,0,\zeta)$ with $\zeta \gtrsim 0.3$. The Y-3% Dy was clearly ordered at 5 K, and the Néel temperature was found to be $T_N = 9$ K, $^{3)}$ fig. 1). A more detailed investigation of the magnetic order of this sample is reported in chapter 7.

The elastic scans for the remainder of the samples are shown in figs. 4.2, 4.3, 4.4 and 4.5. The resolution in <u>m</u>-space can be seen from the width of the nuclear Bragg peak. Of these samples, only Lu-2% Er showed any magnetic order.

The satellites of Lu-2% Er persist nearly unchanged up to at least 20 K and presumably derive from small spots of rather concentrated Er (pure Er has $T_N = 85 \text{ K}^{10}$). From cross sections (3.2) and (3.6), it was possible to estimate the amount of "concentrated" Er by the intensity ratio r between the (0,0,2- ζ) satellite and the (0,0,2) nuclear reflection. The coherent nuclear scattering length of Lu is $b_{\text{coh}} = 7.3 \text{ fm}$. The ordered moment was assumed to be $g_N = 4.3 \mu_B$, the maximum value in pure Er. Further, the orientation factor (1 + cos²0) in eq. (3.6) is $\frac{12}{2}$. The magnetic form factor was $f(x) \approx 0.9$. (The Tb value was used¹⁹). With these numbers and X being the concentration of magnetically ordered Er, we have

$$r \triangleq \frac{I_{(0,0,2-\zeta)}}{I_{(0,0,2)}} = 2 \cdot \left(\frac{g\mu \cdot p_0 f(\pi)}{2 \cdot b_{coh}}\right)^2 \cdot x = 1.05 x.$$



Fig. 4.2. Elastic scattering from Y-1.1% Dy for magnetic order. No (0, 0, 2-5) satellite is seen around 5 = 0.3. The peak at 5 = 0.17 is caused by spurious (100) reflections from small, misoriented grains.



Reduced Wavevector 5

Fig. 4.3. Elastic scattering from Y-2% Er for magnetic order. No $(0, 0, 2-\zeta)$ satellite is seen around $\zeta = 0.3$. The peak at $\zeta = 0.15$ is caused by spurious (100) reflections from small, misoriented grains.

Experimentally, $r = 6 \cdot 10^{-4}$, so $X = 5.7 \cdot 10^{-4}$. This is an upper limit because the neutrons have a finite penetration depth at the strong (0,0,2) Bragg reflection. Thus less than 3% of the Er takes part in the magnetic ordering and this is negligible for inelastic neutron scattering.



Fig. 4.4. Elastic scattering from Sc-2% Er for magnetic order. Neither (1, 1, 4) nor (0, 0, 2-4) satellites are seen for 4 % 0.3.



Fig. 4.5. Elastic scattering from Lu-21 Er for magnetic order. Clear (0, 0, 2-4), (1, 1, 4) and (1, 1, -4) satellites are seen for 4 = 0.31, at least up to T = 20 K. As shown in the text, the satellites are presumably caused by ordering in small, concentrated Er regions formed by less than 31 of the Er atoms.

4.3. Inelastic Scattering Spectra

For each sample the main inelastic experiment consisted of an energy $(\omega\omega)$ scan from -2 to 6 meV, approximately. Unless stated otherwise, the nonochromator energy was fixed at 14.4 meV, filtered with graphite.

The wavevector transfer \underline{n} was kept fixed at a value between 1.6 λ^{-1} and 2.0 λ^{-1} , and except for the Y-3% Dy sample two directions of \underline{n} were used: 1) TA and 2) TM or TK. It was hoped that the difference in intensity between the two corresponding spectra would give additional information on the CEF-states. Unfortunately, for most of the samples the two spectra could not be compared directly because of the rather large neutron absorption (see table 4.1).

From the diffraction scans it was seen that no spurious scattering occured at $h_{s} = 0$, and relevant phonon dispersion measurements^{16,17,18} ensured that no phonon scattering could occur in the part of the (u_{s},h_{s}) space where the inelastic scans were performed.



Fig. 4.6. Inelastic scattering spectrum from Y-3t Dy above $T_{\rm N}$. The spectrum was taken with a fixed analyzer energy of 14.4 meV filtered with graphite. The energy resolution (FWHH) is denoted by a horizontal error bar, while the vertical error bar shows the statistical standard error of the single neutron counts. The dashed line is a guide-to-the-eye. These signatures are used in the remaining inelastic scattering spectra.

Figure 4.6 shows the spectrum from the Y-3% Dy above the ordering temperature. Apart from the incoherent nuclear scattering at $h_{\omega} = 0$, no structure can be seen, only some very broadened intensity, and no information on the CEF levels was gained. It is thought that this is due to a large level boradening caused by the strong exchange interaction that was also responsible for the high ordering temperature.

Spectra from the Y-1.1% Dy sample are shown in³⁾ fig. 4. As was the case for the main spectra from the remainder of the samples, at the low temperature around 5 K only transitions from the ground state level to higher levels were observable. On the side of the elastic incoherent peak a "shoulder" is seen around 1.4 meV. This is believed to be caused by the CEF transition $\Gamma_0 - \Gamma_1$. As expected,



Fig. 4.7. Inelastic scattering spectrum from Y-1.1% Dy with 0.2 meV resolution. The observed width of the shoulder is thus purely intrinsic. The fine resolution was obtained by using a fixed monochromator energy of 5 meV, filtered with Be at 77 K. The (high flux) reactor beam was obtained from the cold source at the DR 3 reactor.

at T = 30 K the intensity of the shoulder was decreased; thus although it was impossible to resolve the shoulder completely by a finer resolution (see fig. 4.7), there is no doubt that the scattering is caused by a CEF transition. This is further proved by the decreasing intensity with increasing w, as seen from the spectra in fig. 4.8.



Fig. 4.8. =-dependence of inelastic scattering spectrum from Y-1.10 Dy. The spectra are measured with a fixed analyser energy of 14.4 meV in connection with a graphite filter. The reduced wavevectors ξ and ζ are defined by $(h, k, 1) = (1, 0, 0) = (\xi, 0, 0)$ and (h, k, 1) = (0, 0, 2) + (0, 0, 5).

Although not too clear, these spectra also indicate that the dispersion is at most 0.4 meV.

The inelastic scattering experiment with the Y-2% Er sample was the most satisfactory of the five measurements. All the features expected from CEF transitions were displayed very clearly. The results were published in $^{2)}$.

The 5 K spectra are shown in fig. 1 of this paper. We see three clearly resolved peaks caused by transitions from the CEP ground state level to three excited levels at approximately 2.1, 3.8, and 5.1 meV. As this alloy has a small neutron absorption, the intensities of the two spectra with $\underline{\mathbf{n}}$ TA and $\underline{\mathbf{n}}^{-1}$ TK may be compared directly. The validity of this comparison was further demonstrated by a measurement of intensity versus sample orientation (²⁾ fig. 2) in close agreement with the prediction of the cross section, eq. (3.7).

Thus the difference in elastic intensity between the two spectra seems to be caused by elastic magnetic scattering from the CEF ground state, formally a $\mathbb{F}_0^+\mathbb{F}_0^-$ transition. The effect of raising the temperature to 20 K is shown in fig. 4.9.



Fig. 4.9. Temperature dependence of inelastic scattering spectra from V=28 Er. As the temperature is raised from 5 to 20 K, a peak at 2.1 meV neutron energy gain appears at the expense of the instensity in the neutron energy loss part of the spectra.
The intensities of the $r_0 + r_n$ transitions are reduced, but at h $\omega = -2.1$ (neutron energy gain) there appears a peak caused by the $r_1 + r_0$ transition. This transition becomes visible as r_1 becomes populated (P₁ is increased) at 20 K. The interpretation of the difference in elastic intensity at 5 K is supported by the fact that raising the temperature reduces this intensity only in the spectrum with $\mathbf{x} \in \mathbf{I} \times \mathbf{x}$. The peak at $r_0 = 2.1$ meV was measured at 4.5 K for different \mathbf{x} -values (fig. 4.10) and no dispersion was observed.



Fig. 4.10. w-dependence of the peak at hw = 2.1 meV ($\Gamma_0 + \Gamma_1$ transition) in Y-2% Er spectra. As w is increased no dispersion is observed but the intensity decreases. The reduced wavevector ξ is defined by (h, k, 1) = (1, 1, 0) - (ξ , ξ , 0).

As expected, the intensity decreased approximately in proportion to $f(x)^2$. (The form factor for Tb was used¹⁹⁾).

The Sc-2% Er and Lu-2% Er samples had a rather large neutron absorption, thus yielding less detailed results. The main spectra are shown in ³⁾, figs. 2 and 3. In Sc-2% Er transitions to the first and second excited levels were observed (hu = 2.5 and 4.4 meV). The Lu-2% Er spectra showed only one clear transition peak (hu = 2.1 meV), but the analysis indicates a further small peak around hu = 4 meV.

The checks for the expected alterations with increasing \underline{u} and T for the two samples are shown in figs. 4.11 and 4.12, and no dispersion was observed.



Fig. 4.11. = and temperature dependence of the peak at 2.6 meV $(\Gamma_0 + \Gamma_1)$ in the Sc-2% Er spectra. No significant dispersion is seen, but the intensity shows a tendency to decrease with increasing x or T. ξ has the same meaning as in fig. 4.10.



Fig. 4.12. Temperature and m-dependence of the peak at 2.15 meV $(\Gamma_0^{-}+\Gamma_1^{-})$ in the Lu-2% Er spectra. The behaviour is similar to that of the Er-alloys except for the peak at 4 meV in the $\xi = 0.26$ spectrum. No phonons exist at this point, but as a small part of the Er is ordered this peak may be caused by magnons. ξ has the same meaning as in fig. 4.10.

5. ANALYSIS OF INELASTIC SCATTERING EXPERIMENTS

In principle, one may determine all 4 CEF parameters of the Hamiltonian (2.2) from inelastic neutron scattering spectra. In this study the aim of the analysis was more modest because suggested values were available, deduced from magnetization measurements. As reported, Høg and Touborg measured the susceptibilities of Tb, Dy, Er and Ho diluted in $\gamma^{20,21}$, Lu^{22} and Sc^{23} , and from the temperature dependence they deduced the CEF parameters B_{20}/α , B_{40}/β , B_{60}/γ and B_{66}/γ .

A striking result was the uniqueness of the parameters obtained from the alloys containing Dy.

5.1. Least Squares Fit

The main neutron scattering spectra, measured at low temperature (T \sim 5 K) and low momentum transfer ($\kappa \sim 1.8$ Å⁻¹), were analyzed as described below. In a model expression, representing

the "experimental outlook" of the scattering cross section eq. (3.7)

$$I(L_{+}) = \sum_{n}^{U_{n}} \frac{U_{n} \cdot S(E_{n})}{1.0645 \cdot W_{n}} \exp(-(\frac{E_{0} - E_{n}}{0.6006 \cdot W_{n}})^{2}) + B, \quad (5.1)$$

each peak of the spectra was, above a background B, represented by a Gaussian distribution with transition energy E_n , width (FWHM) W_n and intensity U_n . As the instrumental sensitivity $S(E_n)$ was included, the intensities U_n with n>0 were proportional to the transition probability factors T_{on} when absorption effects were disregarded. Besides magnetic intensity, U_o (elastic peak) also contained nuclear intensity. The expression (5.1) was fitted to the measured spectra by a least squares fitting procedure (see appendix 1). Depending on the quantity of detail in the spectra, the fitting was performed for each alloy in one of two ways as described below.

5.2. Y-2% Er

The spectra of this alloy were little influenced by absorption. Moreover, as four magnetic peaks were seen with , in two directions, a simultaneous LS-fit to both spectra was performed, where the CEF parameters were determined directly. The details of this procedure are described in $\frac{2\pi}{2}$. In principle, the model expression (5.1) was used, but E and U were given in terms of the CEF parameters and a common scaling factor. The CEF parameters deduced agreed with the magnetization results within the uncertainty. In addition, the first 3 excited levels were found to have an intrinsic width of 1.1 meV, presumably due to exchange broadening. As can be observed directly (²⁾ fig. 1) the fit was statistically poor $(r^2 - 21)$, because the intensity at the 2.1 meV peak could not be reproduced properly by the model expression (5.1). Further, the best fit value of the magnetic scaling factor S was 30% higher than expected from scattering from a V sample. As the elastic intensity varied as \cos^2 with the crystal rotating angle (see^{2}) fig. 2) this discrepancy cannot be due to the absorption but must be ascribed to a modification of the 4f wavefunctions \mathbb{C}_n and hence \mathbb{U}_{nn} . This could

be caused by interaction of a given 4f shell either with the conduction electrons or maybe with the $5s^2p^6$ outer shells.

5.3. Y-1% Dy, Sc-2% Er and Lu-2% Er

The spectra from these samples were analyzed separately by LS-fitting directly using the model expression (5.1). Thus the LS-fits only served to extract the most accurate values and uncertainties of the energy, width and intensity of the observed transitions to be compared to the magnetization results. This course was taken because the spectra, which were affected by absorption or which had only one observed transition, were judged not to contain enough information for an independent determination of CEF-parameters. For the Sc-Er and Lu-Er alloys, a further reason was that the published magnetization CEF parameters gave transition energies that at a first glance seemed to agree well with the scattering spectra.

Direction of <u>m</u>	ñ	E				2
		(meV)	ีก (meV)	³ n	U _n	×*
ir A	1	2.5805	1.8322		310:28	1 05
	<u>²</u>	4.451.09	1.17:.16		122:25	1.03
. K	I	2.55*.06	1.591.23		390-61	, ,
*******	2	4.33:.2	1.24		89:36	
Mean of	ì	2.56+.06	1.7:.2	1.50+.22		
СА, К	2	4.451.09	1.18+.16	0.95:.19		
Er K	1	2.14+.04	1.81.1	1.61	351-18	1.7
	2	4.0 ^{%}}	1.11.3	0.94	38+12	
Α.	1	1.33+.20	1.35+.45	1.1+.5	-	2.8
	т (A . E E 	IF "A 1 .F 1 .F 1 .F 1 .F 2 .F 2 .F 2 .F 2 .F 1 .F 2 .F 1 .F	Ir "A 1 2.58:.05	1r "A 1 2.58:.05 1.83:.22	$\frac{1}{2} = \frac{1}{2} = \frac{1}$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

Table 5.1

For Sc-1M Er, the "best"values of $E_{\rm p}$ and $W_{\rm p}$ are the mean of the CA-and the "F-values. The intrinsic widths $z_{\rm p}$ are defined by $W_{\rm p}^2 = (W_{\rm ints} (E_{\rm p}))^2 + z_{\rm p}^2$.

^{**} Γ_{j} was kept fixed during the fitting at the value deduced from momentization. ,² was raised to 5 when using a model function where the $\Gamma_{j} + \epsilon_{j}$ transition was simply omitted. This fact rives evidence for the existence of this tranoition in the spectrum. The results of the fits are given in table 5.1. The observation of the transition $\Gamma_0 + \Gamma_2$ in Lu-2% Er is not fully proved but the statistical evidence is fairly good. The intrinsic widths are 1.0-1.6 meV, and therefore, as in the case of Y-2% Er, they may be explained by exchange broadening.

In $^{3)}$ the deduced transition energies are compared to the reported magnetization results. For Sc-2% Er and Lu-2% Er, the present neutron scattering data agree with these results. As expected some deviation is found for the transition intensities, see table 5.2, due to neutron absorption.

Table 5.2

Intensity ratios between the $\Gamma_0+\Gamma_1$ and $\Gamma_0+\Gamma_2$ transitions. The magnetization results are calculated from deduced CEF pa emeters.

	Direction of <u>m</u>	Neutron Scattering	Magnetization Tol ^{/T} o2
Sc-21 Er	ΓA	2.5±C.8	0.9+0.07
	ГК	4.4:1.5	3.6.0.1
Lu-28 Er	ГК	4.2±1.5	4.3±0.2

The most important result of ³⁾ is that for Y-1% Dy the observed transition energy (1.33 meV) cannot at all be explained by the reported magnetization results ($E_1 ~ 3.5$ meV). However, close agreement was obtained when the magnetization measurement was reanalyzed taking ordering effects into account, and new CEF parameters were deduced. It should be stressed that this reanalysis was completely independent of the neutron results (no fitting), only consisting of a better method to derive the susceptibility from the isothermal magnetization curves. In contrast to the earlier published values, it is seen that the rederived values for B_{20}/α etc., are, within uncertainties, the same for the alloys with Dy and with Er. Further, they almost coincide with the earlier published magnetization results for diluted Tb-alloys.

5.4. Conclusion

The earlier published magnetization results suggested that the crystal field parameters B_{20}/α , B_{40}/β , B_{60}/γ in a dilute rare

earth alloy depend crucially on the specific rare earth (the Dy result). These results disagree with an external charge model.

However, the spectroscopic method of inelastic neutron scattering gave independent values for the first CEF levels in 4 important alloys, and the result for one of these alloys clearly disagrees with the published magnetization results and therefore make questionable the conclusion drawn from them. This fact proved the motivation for a more accurate method of analyzing the magnetization data. Such a method is important when ordering effects are present such as in alloys containing Dy. The neutron scattering results confirm this improved analysis.

For the limited number of rare earth alloys the neutron results have "reversed" the conclusion about the CEF-parameters because the rederived values are now in accordance with an external charge model: B_{20}/α depends almost exclusively on the diluent (through the c/a ratio), whereas B_{40}/β , B_{60}/γ and B_{66}/γ are nearly independent of both the diluent and the specific rare earth.

More experimental data are necessary in order to decide whether this statement applies to the whole series of rare earths. The present work suggests that CEF parameters for the remainder of the series may be obtained from magnetization measurements combined with the improved method of analysis described in $^{3)}$, and that further inelastic neutron scattering experiments are unnecessary.

6. MAGNETIC ORDERING IN Y-3% Dy STUDIED BY NEUTRON DIFFRACTION

As mentioned in chapter 4, the Y-3% Dy sample was observed to have a modulated order below 9 K. This chapter reports on a more detailed investigation of this ordering: 1) The specific modulated structure (spiral, CAM or mixture?), 2) The temperature dependence.

6.1. Modulated Structure

Besides the (002)⁻ and (002)⁺ satellites ((h,k,1) = (0,0,2.5), ³⁾, fig. 1, also the (100)⁻ satellite at (h,k,1) = (1,0,-5) was observed by neutron diffraction at 4.6 K. All satellites had a reduced wavevector $\zeta = .275$, corresponding to an interlayer turn--angle of $\omega = 49.5^{\circ}$. The intensity ratio between the (002)⁻ and the (100)⁻ satellites was found (corrected for resolution effects) to be 10.2. According to eq. 3.6, this ratio is 0 for CAM-structures and 8 for a spiral. Ascribing the deviation from 8 to the absorption of the sample, it is concluded that the structure is a spiral.

The magnitude of the ordered moment (, in eq. 3.6) is found from the intensity ratio between the (002)⁻ satellite and the (002) nuclear Bragg reflection because the absorption is nearly the same for (002)⁻ and (002). With $b_{coh,Y} = 7.9$ f.m., the same procedure was used as described for the Lu-2% Er sample in chapter 4.

From the temperature dependence of the (002) satellite (fig. 6.2, following section), the "saturated" (T+0) intensity ratic, corrected for resolution effects, is found to be

$$\frac{I(002)^{-}}{I(002)} \bigg|_{sat.} = 7.7 \cdot 10^{-3} .$$

Using the magnetic form factor $f(x) \in 0.9$, the experimental value for the ordered moment . may be expressed as

$$\dots \quad \mathbf{x} = 2.3 \quad \mu_{\mathbf{B}}$$

where x is the fraction of Dy atoms taking part in the ordering. As finite penetration depth at the (002) reflection (extinction) has been neglected, the true value may be even lower.

It is natural to compare these results with the CEF ground state found for Y-1.1% Dy that is dominated by the term $0.99 | M_J =$ -1/2.. In accordance with the observed spiral structure, this ground state predicts the moment to lie in the basal plane, but in contrast to the Dy³⁺ free spin of 10 u_B the maximum basal plane moment of the ground state is 5.2 u_B, "quenched" by the CEF. However, as the indirect exchange has a magnitude ($T_N = 9$ K) comparable to the energy of the first excited CEF-state (15 K), admixture of this state may increase the saturated magnetization to about 7 u_B. Thus the fraction x is around 15%.

6.2. Temperature Dependence of (002) Satellite

At temperatures from 2.2 to 9.5 K, the (002) satellite was investigated by transverse diffraction scans ($h\omega = 0$) as seen in fig. 6.1. The measurements below 4.5 K were performed with the sample in a He pump cryostat, while a flow cryostat was used at the higher 'emperatures.



Fig. 6.1. Transverse neutron diffraction scans of the $(002)^{-1}$ magnetic satellite. As seen at the bottom, near $T_{\rm N}$ the scan is dominated by critical-scattering-like wings. In the insert at the top, the scan in reciprocal space is illustrated and the orientation of the resolution ellipse is indicated.

The peak intensity of the satellite decreased as the temperature was raised until the satellite disappeared at $T_N \approx 9.12$ K. This gradual fading away is a typical second-order phase transition.

At the low temperatures the width of the satellite was small, determined by the instrumental resolution, but approaching T_N the satellite became increasingly dominated by "wings", much broader than the resolution, as seen in fig. 6.1. This is rather similar to the so-called critical scattering, caused by short-range spin order, that is observed close to the ordering temperature in concentrated magnetic systems (e.g. in Tb^{24}).

In order to distinguish between the wings and the sharp "Bragg part" of the satellite, the scans were analyzed by a least squares fit with the following model expression:

$$I(q) = B + P_B R(q) + \frac{P_L}{1 + (\frac{q}{W_L})^2}$$
 (6.1)

where B is a constant background and R(q) is the experimental resolution function (see upper part of fig. 6.1), approximately described by

$$R(q) = .726 \exp\left(-\frac{q^2}{\tau_1^2}\right) + .274 \exp\left(-\frac{q^2}{\tau_2^2}\right)$$

$$\sigma_1 = 5.35 \cdot 10^{-3} A^{-1}, \quad \sigma_2 = \sqrt{5} \sigma_1,$$
(6.2)

As normal for critical scattering, the "wings" were represented by a Lorentzian with a full width at half maximum W_{L} .

The results of the least squares fit are shown in fig. 6.2. The Bragg intensity seems to saturate at 2 K, and in the range 3 K < T < 8 K it decreases nearly linearly until it goes to zero at the Néel temperature 9.12 K with a decreasing slope.

The "critical scattering" has a nearly constant width of 0.035 Å⁻¹ and a broad intensity maximum around 6 K.



Fig. 6.2. Temperature dependence of the (002)⁻ magnetic satellite: Peak value and width of "critical scattering" and peak value of resolution-shaped Bragg scattering. The two components of the scattering have been separated by least squares fitting with a suitable model function (see text).

6.3. Example of Concentrated "Magnetic" System: β-Brass

For comparison, the corresponding behaviour of a concentrated system is discussed. β -brass is a nearly 50 at.% Cu - 50 at.% Zn alloy which goes from an ordered to a disordered bcc phase when the temperature is raised through $T_c = 740$ K. Although not magnetic, this phase transition is quite similar to that of a spin 1/2 pure antiferromagnetic system. (Using the notation of chapter 2: $\underline{Q} = \underline{a}$ of the cubic reciprocal lattice). This is the case because the configurational energy of β -brass, associated with the different types of nearest neighbours: Cu-Cu, Zn-Zn or Cu-Zn, has the torm of an exchange energy. One lets $S_1 = 1/2$ or -1/2 correspond to site 1 being occupied by a Cu or a Zn atom, respectively, and only nearest neighbour interaction is assumed. The simplicity of this so-called Ising system has made detailed theoretical predictions possible, and experimental results have been obtained by neutron diffraction $\frac{25,26}{2}$.

In accordance with theory, the equivalent magnetization goes to zero as $\mu^{\alpha} (T_{\rm C}^{-}T)^{\beta}$, $\beta = 0.293$, that is the diffraction "satel-lite" intensity $I^{\alpha}u^{2}(T_{\rm C}^{-}T)^{2\beta}$ goes to zero with an infinite slope. At lower temperature, the measured magnetization is not in complete agreement with theory on an absolute scale, as first imigined on the basis of earlier neutron diffraction results, but up to 10% larger.

Again in agreement with theory, the critical scattering is observed to vary with a peak intensity $I_p \propto |T-T_c|^{-\gamma}$ and width $w \propto T-T_c$, $\gamma = 1.25$, $\gamma = 0.65$.

6.4. Satellite Temperature Dependence Compared to Concentrated Systems

In the temperature dependence of the satellite of Y-3% Dy, although only observed by scans in the (100)-direction, two features have been observed that differ clearly from concentrated systems:

- The Bragg intensity does not go to zero with infinite, but with decreasing slope, and
- 2) The "critical" scattering is rather temperature independent with no distinct maximum and no narrowing at the Néel temperature.

It is not quite clear what causes these effects, but it may be fruitful to see them in the light of recent spin-glass experiments by Sarkissian and Coles²⁷⁾. According to their results, Y_{1-x} -Dy_x alloys with x less than a "critical" concentration of 2.6% display a short-range ordered spin-glass phase rather than the magnetic spiral phase seen in more concentrated alloys. It is tempting to see the very "soft" spiral-to-disorder transition observed in Y-3% Dy as a consequence of the proximity to the critical Dy concentration.

Another, less exciting, explanation is that variations in the local Dy-concentration may "broaden" the Néel temperature. A 10% T_N-broadening is required to give the observed temperature dependence of the Bragg intensity. This effect is made likely by the fact that only 10-20% of the Dy atoms seem to take part in the ordering.

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APPENDIX I

Linearized Least Squares Fit

The least squares fit (LS-fit) is a very convenient method of analyzing experimental data when these are functions of some independent variable, e.g. neutron counts as function of energy transfer in a neutron scattering experiment. The data points are denoted:

Here the measured values Y, are assumed to be uncorrelated.

The idea is to fit the experimental data with a suitable function $F(X;\underline{P})$, depending on a number (M) of parameters (P_1 , P_2, P_M) = \underline{P} . Usually these parameters describe the properties to be extracted from the experimental data. The overall error of the fit is given in terms of a weighted sum

$$\sum_{i=1}^{n} (\mathbf{Y}_{i} - \mathbf{f}(\mathbf{X}_{i}; \underline{P}))^{2} \mathbf{W}_{i}.$$
 (A1.2)

The statistically best fit is given by the parameters <u>P</u> for which $\frac{1}{2}$ takes its absolute minimum, and with weights given by

$$W_i = \sigma_i^{-2}. \tag{A1.3}$$

To ensure that $x^2 = \frac{2}{x}^2$ (P) takes a minimum value, we require the derivatives to be zero

$$\frac{1}{\delta P_k} x^2 = 0, \quad k = 1, 2... N.$$
 (A1.4)

Unfortunately, this equation only ensures a local minimum or maximum. Other (physical or mathematical) arguments must be used to prove it to be an absolute minimum.

For fitting functions $F(X;\underline{P})$ linear in the parameters \underline{P} , these may be found directly, but in general an iterative method

must be used, and, most practically, on a digital computer. For a "guessed" parameter set $\underline{P}^{(n)}$, not too far from the optimal values, one may calculate corrections $\Delta \underline{P}$ to $\underline{P}^{(n)}$ by linearizing F(X; P) with respect to P. By inserting into eq. (A1.4) we find

$$\Delta \underline{P} = \underline{A}^{-1} \underline{G}$$
 (A1.5)

where the symmetric matrix A is given by

$$A_{jk} = \sum_{i=1}^{N} W_{i} \left[\frac{\partial}{\partial P_{j}} F(X_{i}; \underline{P}^{(n)}) \right] \left[\frac{\partial}{\partial P_{k}} F(X_{i}; \underline{P}^{(n)}) \right]$$
(A1.6)

and the gradient vector \underline{G} by

$$G_{k} = -\frac{1}{2} \frac{\partial}{\partial P_{k}} \chi^{2} = \sum_{i=1}^{N} W_{i}(Y_{i} - F(X_{i}; \underline{P}^{(n)})) - \frac{\partial}{\partial P_{k}} F(X_{i}; \underline{P}^{(n)}). \quad (A1.7)$$

Now, $\underline{P}^{(n+1)} = \underline{P}^{(n)} + \underline{AP}$ is expected to be a better set of parameters that may be used as a basis for the calculations Al.5-Al.7 in a new iteration cycle (n+1). In the normal iteration, , 2 and the ${\it LP}_k$'s become smaller and smaller as the minimum of χ^2 is approached (convergence). The iteration is stopped when the \mathbb{P}_k 's become sufficiently small, that is small compared to the statistical uncertainties $\sigma(P_k)$ which will be explained below or to the P_k 's themselves. The weakness in the method is obviously that one has to guess the first set of parameters to start the iteration, and these parameters must be in the neighbourhood of the minimum of χ^2 . If the guess parameters are too far off, the iteration may diverge, that is χ^2 gets larger and larger. In the LS-fit computer program used in this study, the algorithm described above was modified to reduce the tendency to diverge. According to the algorithm by D.W. Marquard, the parameter corrections (Al.5) were modified

$$\underline{\Delta p} = (\underline{A} + \underline{1}\lambda)^{-1} \underline{G}.$$
 (A1.8)

Here λ is a positive number which in the case of good convergence is kept negligibly small. However, as soon as tendencies to diverge appear (χ^2 is increased), the program will successively

increase λ towards 1. This has the effect of forcing $\Delta \underline{P}$ towards the direction of the steepest decline of χ^2 , given by the gradient $\underline{G} = -1/2 \text{ grad } \chi^2$.

When an iteration has successfully converged, the goodness of the fit may be judged from the value of χ^2 obtained. If the chosen weights were realistic and if the fitting function F(X;P)was physical, describing the measurements correctly, we expect $\chi^2 \approx 1$. In this case the uncertainty of the obtained parameters is approximately given by the matrix of covariance

$$\underline{C} = \frac{\chi^2}{N-M} \underline{A}^{-1}, \quad C_{kj} = \text{cov.} \{P_k, P_j\}.$$
 (A1.9)

So, for example, the standard error is $\Im\{P_k\} = \sqrt{C_{kk}}$. The derivation of (Al.9) is rather similar to that of the standard error of a mean value.

One of the limitations of the least squares fitting is the influence of non-statistical errors. Besides systematic instrumental errors, this kind of error may originate from experimental data that contain more details than can be accounted for by the model function $F(X;\underline{P})$. This may cause "statistically best fits" which are physically poor. For example, in certain cases in the present study it was necessary to increase the weights of the most important experimental data in order to get good physical fits.

APPENDIX II

Matrix Elements of Stevens Operators

The Stevens operators O_{LM} are closely related to the so-called Racah operators O_{LM} . These operators are the angular-momentum equivalents to the spherical harmonics and transform like these. The reason for introducing Racah operators is that the matrix elements of these may be expressed in a more convenient form than is the case for the matrix elements of the Stevens operators.

Following Danielsen and Lindegård²⁸⁾, the connection between the Stevens and the Racah operators may be expressed as

$$\hat{O}_{LM} = \frac{1}{K_{LM}} \sqrt{\frac{2L+1}{4\pi}} \begin{cases} \frac{1}{2} (\hat{O}_{L-M} + (-1)^{M} \hat{O}_{LM}), & M > 0 \\ \\ O_{LG} & M = 0 \end{cases}$$

Some of the normalization coefficients, which make the Stevens operators have integral coefficients, are given in table A2.1.

The matrix elements of the Racah operators may be expressed by the 3-J symbols

$$(J m_1 O_{LM} J m_2) = (-1)^{J-m_1} \frac{1}{2^L} \frac{(2J+L+1)!}{(2J-L)} \frac{J L J}{(-m_1 M m_2)} .$$
 (A2.2)

The 3-J symbol, which is only non-zero for $M+m_2-m_1 = 0$ and if J,L and J fulfil the triangle inequalities, is expressed as the complicated sum

$$= \frac{(j_1 + j_2 - j_3)!(j_1 - j_2 + j_3)!(j_1 - j_2 + j_3)!(j_1 + j_2 + j_3 + 1)}{(j_1 + j_2 + j_3)!(j_1 - m_1)!(j_2 + m_2)!(j_2 - m_2)!(j_3 + m_3)!(j_3 - m_3)!}$$

 $\frac{(-1)^{k}}{k!(j_{1}+j_{2}-j_{3}-k)!(j_{1}-m_{1}-k)!(j_{2}+m_{2}-k)!(j_{3}-j_{2}+m_{1}+k)!(j_{3}-j_{1}-m_{2}+k)!}$

L	м	$\frac{1}{R_{LM}} \sqrt{\frac{2L+1}{4\pi}}$	L	M	$\frac{1}{R_{LM}}\sqrt{\frac{2L+1}{4\pi}}$
2	0	2	6	0	16
2	2	73	6	2	32 7210
6	0	8	6	3	16 7210
4	2	-4	6	4	16 377
4	3	770	6.	6	
4	4	8 735			

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 $\frac{\text{Table A2.1}}{\text{Coefficients connecting Racah and Stevens operators. From }^{28}.$

APPENDIX III

Resolution of the TAS

The finite resolution of the triple-axis spectrometer derives from the monochromotor and analyzer systems that define the incident and scattered wavevectors \underline{k} and \underline{k}' unsharply.

Although the vertical resolution is quite large it is disregarded here because the vertical components (perpendicular to the scattering plane) of \underline{k} and \underline{k} ' have a minor influence on the energy transfer.

Because the monochromator and analyze- systems are quite similar, we shall only consider the monochromator system set for the (mean) wavevector \underline{k}_0 . The two independent sources of the \underline{k} unsharpness are indicated in fig. A3.1: finite collimations and mosaic spread. The collimators, consisting of parallel Cd-coated steel plates, may be characterized by their horizontal angular



Fig. A3.1 Wavevector spread of monochromator (or analyzer). The two independent sources are indicated:

- (1) Upper part: The divergence of the collimators (in comnation: σ) produces a spread \underline{X}_1 (FWRM).
- (2) Lower part: The mosaic spread (of the crystal orientation throughout the monochchromator crystal) produces a spread X₂ (FWHM).

divergences σ_1 and σ_2 , i.e. (plate distance)/(collimator length). The probability for a neutron to pass through a collimator is approximately a Gaussian function of the angular deviation of the neutron path from the collimator direction. The mosaic spread, the slight variation in orientation of the reflecting plane when going from one mosaic block of the monochromator crystal to another, is also approximately Gaussian-distributed with an angular width η (FWHM).

The wavevector deviations X_1 and X_2 , indicated in fig. A3.1, correspond to a FWHM of the unsharpness introduced by finite collimation and mosaic spread, respectively, and they are connected to σ_1 , σ_2 and n by ²⁹⁾:

$$\begin{cases} x_{1 E} = 2 E \cot \theta_{\perp} \frac{\sigma_{1}^{2} \sigma_{2}^{2}}{\sigma_{1}^{2} + \sigma_{2}^{2}} \end{bmatrix}^{1/2} \\ x_{1 u} = \frac{k_{1}}{\sin \theta_{\perp}} \frac{\sigma_{1}^{2} \sigma_{2}^{2} \sigma_{1}^{1/2}}{\sigma_{1}^{2} + \sigma_{2}^{2}} \qquad (A3.1) \\ U_{1} = \theta \\ \\ \begin{cases} x_{2E} = 2 E \cot \theta \frac{\sigma_{2}^{2} - \sigma_{1}^{2}}{\sigma_{2}^{2} + \sigma_{1}^{2}} + \frac{1}{\sigma_{1}^{2} + \sigma_{2}^{2}} + \frac{1}{\sigma_{1}^{2}} \end{bmatrix}^{-1/2} \\ x_{2u} = \frac{k_{1}}{\sin \theta_{2}} \frac{2\sigma_{2}^{2}}{\sigma_{1}^{2} + \sigma_{2}^{2}} + \frac{1}{\sigma_{1}^{2} + \sigma_{2}^{2}} + \frac{1}{\sigma_{1}^{2}} \end{bmatrix}^{-1/2} \\ x_{2u} = \frac{k_{1}}{\sin \theta_{2}} \frac{2\sigma_{2}^{2}}{\sigma_{1}^{2} + \sigma_{2}^{2}} + \frac{1}{\sigma_{1}^{2} + \sigma_{2}^{2}} + \frac{1}{\sigma_{1}^{2}} \end{bmatrix}^{-1/2} \qquad (A3.2) \\ tan U_{2} = tan \theta \frac{2\sigma_{2}^{2}}{\sigma_{2}^{2} - \sigma_{1}^{2}}, \qquad 0 \le U_{2} \le 180^{\circ} \end{cases}$$

Here the subscripts "*" and "E" indicate the "normal" wavevector diviation $\underline{X} = \underline{k} - \underline{k}_0$ and the corresponding energy deviation, respectively. U is the angle between \underline{X} and \underline{k}_0 , while \underline{v} is the Bragg angle.

The total probability for passing through the monochromator is thus approximately

$$F_{M}(\Delta) = \exp \{-\left(\frac{\Delta_{1}}{x_{1}} - 2\sqrt{\ln 2}\right)^{2} - \left(\frac{\Delta_{2}}{x_{2}} - 2\sqrt{\ln 2}\right)^{2}\}, \quad (A3.3)$$

where Δ_1 and Δ_2 are the components of $\underline{\Delta} = \underline{k} - \underline{k}_0$ along \underline{x}_1 and \underline{x}_2 with $\underline{\Delta}_1 + \underline{\Delta}_2 = \underline{\Delta}$.

In the same way one finds the resolutional widths \underline{X}_3 and \underline{X}_4 for the analyzer system.

In all, the observed intensity for the setting $(\underline{w}_0, \omega_0)$ may be written in terms of a total resolution function

$$I(\underline{\mathbf{n}}_{0}, \omega_{0}) = \iint R(\underline{\mathbf{n}} - \underline{\mathbf{n}}_{0}, \omega - \omega_{0}) \frac{d^{2}\sigma}{d\Omega d\mathbf{E}}(\underline{\mathbf{n}}, \omega') d\mathbf{n}' d\omega'. \quad (A3.4)$$

The derivation of the total resolution function $R(\underline{k} - \underline{m}_{O}, \omega - \omega_{O})$ from the monochromator and analyzer distributions, $F_{M}(\underline{k} - \underline{k}_{O})$ and $F_{A}(\underline{k}' - \underline{k}'_{O})$, is not given here. It will depend on the spectrometer setting $(\underline{m}_{O}, \omega_{O})$, including reflectivity factors $R_{M}(k)$ and $R_{A}(k')$ for the monochromator and analyzer crystals respectively, and a counter efficiency factor E(k'). Fortunately, as the four sources of resolution are independent, one may find the resolutional width in some scan by finding the four contributions separately and adding them quadratically

$$w = (\sum_{i=1}^{4} w_{i}^{2})^{1/2}$$
(A3.5)

Effect on Bragg reflection

The scattering from a Bragg reflection with wavevector transfer $\underline{\tau}$ directly gives, apart from a multiplicative factor, the resolution function for the setting ($\underline{u} = \underline{\tau}, u = 0$). This appears from the Bragg cross section

$$\frac{\mathrm{d}^2}{\mathrm{d}\Omega \ \mathrm{d}E^{\,\mathrm{r}}})_{\mathrm{B}} \propto \delta(\underline{\mathbf{x}} - \underline{\tau}) \ \delta(\omega) ,$$

so that the measured intensity from eq. (A3.4) is

$$I(\underline{\mathbf{m}}_{0}, \omega_{0}) \propto \iint R(\underline{\mathbf{m}} - \underline{\mathbf{m}}_{0}, \omega - \omega_{0}) \, \delta(\underline{\mathbf{m}} - \underline{\tau}) \, \delta(\omega) \, d\underline{\mathbf{m}} d\omega \qquad (A3.6)$$
$$= R_{\underline{\tau}, \underline{0}}(\underline{\tau} - \underline{\mathbf{m}}_{0}, - \omega_{0})$$

Effect on inelastic scattering without dispersion

When observing inelastic scattering from excitations(e.g. magnetic or clastic), one must generally take into account the correlation between \underline{w} and ∞ in the resolution function. However, when dispersion-free excitations are dealt with

$$\frac{\mathrm{d}^2}{\mathrm{d}\hat{z}_{\mathrm{o}}\mathrm{d}E^*} \propto f(\mathbf{x}) \quad \delta(u - u_0),$$

one may clearly disregard the <u>m</u>-part of the resolution function. In this simple case we get the energy resolution

$$\tilde{w}_{E} = \frac{(2 x_{Ei}^{2})^{1/2}}{i}.$$
 (A3.7)

Examples of this sort of scattering are inelastic scattering from CEF-excitations and the elastic incoherent scattering from V. Equation (A3.7) was used to calculate the energy resolutions presented in fig. 3.3.

Integrated Intensity of Energy Scan

The integrated intensity

 $U = \int \mathbf{I}(\mathbf{n}, \omega) \, \mathrm{d} \omega$

of a constant <u>m</u> energy scan may be expressed in terms of a simple sensitivity function $S(\omega)^{29}$. The condition is that the <u>m</u>-dependence of the intensity of the underlying δ -function-like scattering cross section

$$\frac{d^2 e}{dldE^{\dagger}} = a(\mathbf{x}) \frac{\mathbf{k}^{\dagger}}{\mathbf{k}} \pm (h_{\rm e} - h_{\rm e}(\mathbf{x}))$$

is negligible within the area of the resolution function. The expression is

$$C = a(k) \frac{k'}{k} + R_{M}(k) A_{M}(k) R_{A}(k') A_{A}(k') E(k') \Phi(k)$$
 (A3.8)

Here $A_{M}^{-}(k)$ and $A_{\widetilde{A}}^{-}(k')$ are the areas of the "resolution ellipses"

$$A_{M}(k) = \frac{\pi}{4} X_{1n} X_{2n} \sin(U_{1}-U_{2})$$
, $A_{A}(k') = \frac{\pi}{4} X_{3n} X_{4n} \sin(U_{3}-U_{4})$

and ‡ is the neutron flux per energy unit in the reactor beam.

In the analyzer scans only $F_A(k^*)$, $A_A(k^*)$ and $E(k^*)$ vary with w, so that the sensitivity factor is

$$S(\omega) \propto k' R_A(k') A_A(k') E(k') \propto \frac{(k')^3}{\tan\theta_A} R_A(k') E(k')$$

For the most important spectrometer set-up in this study, this equation was used to calculate the sensitivity, normalized to 1 at = 0, as shown in fig. 3.2. The analyzer reflectivity $R_A(k^*)$ was taken from³⁰⁾ (see fig. A3.2) and the counter efficiency $E(k^*)$ was calculated as shown below

$$E(k') = 1 - \exp(-n_0 - 1 \sigma_c, 25.3 \text{ meV})$$

^oc, 25.3 meV = $5376 \cdot 10^{-24}$ cm² is the capture cross section of the He counter gas at 25.3 meV neutron energy $n_o = 5.36 \cdot 10^{19}$ cm⁻³ is the density of the atoms at 2 atm. and 1 = 5 cm is the counter "length".



Fig. A3.2. Reflectivity of pyrolitic graphite³⁰⁾. The abscissa is the energy $E=\frac{h^2}{2\pi}\,k^2$ of the Brayg-reflected neutron.

APPENDIX IV

PHYSICAL REVIEW B

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Crystal fields in $Er_{0.02}Y_{0.M}$ studied by neutron scattering

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The splitting of the J = 15/2 multiplet of Er in an hcp crystal field has been determined by inelastic neutron scattering from a single crystal of $\text{Er}_{i=0}Y_{i=a+}$ Least-squares fits to the spectra gave crystal-field parameters $B_{ij} = -0.34 \pm 0.04$, $B_{ij} = (0.7 \pm 0.2) + 10 = B_{ij} = (0.21 \pm 0.02) \times 10^{-3}$, and $B_{ijk} = (-0.30 \pm 0.03) + 10^{-3}$ in K. in good agreement with results from bulk magnetization data. A significant line broadening of 1.0 meV full width at half-maximum was clearly observed in the first exacted state at 2.2 meV.

INTRODUCTION

The dominant interactions which determine the magnetism of rare-earth metals and their alloys¹ are the indirect exchange interaction and the crystalline field. In addition, the coupling between the magnetic ions and the lattice often plays an important role. In order to separate out the crystal-field interaction for a systematic study Touborg and Høg² have investigated a number of rare-earth ions diluted in the nonmagnetic metals Y. Lu, and Sc, which all have the hcp structure of the magnetic heavy rare earths. From magnetization measurements they deduced the parameters B_{im} in the single-ion crystal-field Hamiltonian

$$= H_{\rm ef} - B_{20} \hat{O}_{20} + B_{40} \hat{O}_{40} + B_{60} \hat{O}_{60} + B_{66} \hat{O}_{66} \quad , \tag{1}$$

where \hat{O}_{Im} are the usual Stevens operators.³ They found that the point-charge model is totally inapplicable for calculating the crystal fields in the rare-earth metals. This result, perhaps not surprising in itself, contrasts sharply with the conclusions of systematic inelastic-neutron-scattering studies of the rare-earth pnictides4 and Alz compounds,5 from which it was deduced that an effective-point-charge model can account quite well for the crystal-field levels in these metallic or semimetallic compounds. Since the results on the dilute rare-earth alloys seem to have considerable significance for our understanding of the origin of crystal fields in metals, we decided to investigate the rehability of the crystal-field parameters derived. from the magnetization data by using the direct spectroscopic method of neutron scattering. The results which we present here for a single crystal of 2% Er substitutionally disolved in Y are, to our knowledge, the first which have been obtained by neutron scattering on the crystal-field levels of a dilute alloy,

EXPERIMENTAL RESULTS

A single crystal of 22 g was prepared as described in Ref. 6. The intensity spectrum of seattered neutrons versus the energy transfer $\hbar \omega = E$ -E' obtained on a triple-axis spectrometer with a fixed filtered energy E of 14.4 meV and a constant wave-vector transfer h = k' is shown in Fig. 1, top and middle part. In the top part the wave-vector transfer was 1.8 A^{-1} along the *h* axis and in the middle part it was 1.8 A⁻¹ along the c axis in the htp structure. The sample temperature was 5 K, so only elastic scattering or scattering from the crystal-field ground level with energy loss could occur. The neutron spectra contained four well-defined peaks. The small statistical errors of the two peaks at 3.8 and 5.1 meV were obtained by repeating this part of the spectrum six times.

The relatively low background level is quite remarkable considering the fact that the concentration of the magnetic ions is only 2^{17} .

The peak around $\hbar\omega = 0$ for \vec{k} along the *c* axis $(\vec{r}A)$ is predominantly due to nuclear incoherent scattering. For *k* along the *b* axis ($\vec{r}M$) this elastic peak has increased by 75th due to magnetic transitions within the ground-state level.

From the scattering cross section [Eq. (3a)] to be discussed shortly, it can be seen that the elastic magnetic intensity varies as \cos^2 , where \downarrow is the angle between \star and the hexagonal plane. Figure 2 shows the experimental variation with \star and it is concluded that variations in the intensity due to geometrical effects such as those arising from finite sample size in a subomogeneous beam are small. The peaks at 2, 3.8, and 5.1 meV are due to crystal-field transions from the ground state to the excited states. We measured the peak around 2.1 meV for κ out to 3.2 A⁻¹ along ΓM . The intensity varied approximately as the squared

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FIG. 1. Inelastic neutron spectra at wave-vector transfer $\vec{x} < 1$, $= \vec{A}^{(1)}$. The upper and middle parts are from a single crystal with \vec{x} along the b axis and c axis, respectively, while the bottom part derives from a polycrystal-line sample. The full line is a guide to the eve of the $Fr_{0,12}Y_{0,33}$ data. The statistical errors are indicated by error bars where they exceed the size of the circles. In the bottom part, in addition, the scattering from a pute Y polycrystal is shown by crosses with a dotted guide-to-the-eve line. The dashed line is the best simultaneous fit to both single-crystal spectra obtained by diagonalizing Eq. (1) and using a common intrinsic linewidth for all transitions to excited levels. The correction for instrumental resolution effects has been included in this fit.

form factor, 7 demonstrating unambiguously that the scattering is magnetic.

The spectra were also measured at 20 and 50 K. The intensities of all transitions seen at 5 K were observed to decrease due to depopulation of the ground-state level. At the same time a peak at 2.1 meV neutron energy gain appeared, originating from transitions from the now populated first excited level to the ground state.

Scattering from lattice vibrations do not con-

tribute to the single-crystal spectra. The momentum-energy-conservation laws determining phonon scattering are not fulfilled anywhere within the spectra if the dispersion relation for pure Y is used,⁴ and a few observed phonons propagating in the symmetry directions showed that resonant modes of vibration due to the heavy impurity Erions do not change the phonon spectrum appreciately from that of pure Y.

In an intermediate stage of its preparation the $\operatorname{Er}_{0, \operatorname{QE}} Y_{0, \operatorname{ME}}$ sample appeared as a polycrystal. A spectrum from this sample, corresponding to those of the single crystal, is shown in the bottom part of Fig. 1, and the same transitions from the ground level to the excited levels can be identified. For comparison, the scattering from a 25 g pure Y polycrystal at 5 K is also shown. For the polycrystalline material a small phonon contribution is observed around 1-3 meV.

In order to compare the raw spectra with the appropriate scattering cross sections, the instrumental resolution effects must be considered, and the correction for these effects will now be discussed in some detail. With a fixed incident energy in the triple-axis spectrometer, the resolution of the analyzer becomes more and more narrow with increasing Rw, and the observed intensity correspondingly lower. It has been shown by two independent methods^{9,10} that the intensity decrease varies as $k^{2}(\tan(\theta_{\lambda}))$, where θ_{λ} is the Bragg angle in the analyzer. Furthermore, the reflectivity of the analyzer crystal, pyrolytic graphite in (002) reflection, varies with $\#\omega^{11}$ and the detector efficiency also varies slightly with $h\omega_{c}$. All these factors as well as the factor k'/k, which appears in all in-



FIG. 2. Neutron scattering intensity from $h_{1,0,0} Y_{1,0,0}$ single crystal at zero energy transfer and at $s = 1 - \frac{3}{2} \frac{s}{s}^{-1}$ measured as a function of s, the ingle between \tilde{s} and the hexagonal plane.



FIG. 5. Bottom: Phonon scattering data used to check the instrumental resolution correction. The scattering and the scattering control to a scattering of the scattering and the scattering of the reciprocal lattice. Crossess denote phonon annihilation, open circles phonon creation. Middle: Integrated reduced phonon intensities (see text) impared to the calculated instrumental resolution correction Robits wight scale). Top: instrumental resolation with $\sigma_{\rm max}$ defined by the resolution function excels $d = d^2 2\sigma_{\rm max}^2$, with the

clastic scattering cross sections, are taken into account in a correction factor $R(\hbar\omega)$ normalized to unity at $\hbar\omega = 0$ and shown as the dashed curve in the middle part of Fig. 3. Evidently the variation with $\hbar\omega$ is by no means negligible, so we have checked this variation experimentally by phonon scattering from the same Er $_{1,R} Y_{1,89}$ sample at room temperature. In the bottom part of Fig. 3 are shown the phonon scattering from the annihilation and the creation of two TA phonons (left) and one LA phonon eight-all propagating along the c axis. The phonon ross section is in standard notation¹²:

$$\frac{d^{k}r}{dk_{0}H} = \frac{k}{k} \frac{A_{\mathbf{z}}}{A_{\mathbf{z}}} (F_{\mathbf{x}} - L_{\mathbf{ph}})^{k} (\mathbf{k} - \mathbf{q}_{\mathbf{ph}}) \quad (2a)$$

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$$s_{2} = h^{2} \frac{b^{2} a^{2}}{2ME_{ab}} \left[n(E_{ab}) + \frac{1}{2} t^{2} \right] e^{-2\Phi(\sigma)}$$
(2b)

and

$$w T_{\mu\nu} = \exp E_{\mu\mu} - kT \left[+ 1 \right]^{-1} , \qquad (2c)$$

In Eq. (2b) the - sign is used for phonon creation, the - sign for annihilation. In the middle part of Fig. 3 are shown the integrated phonon intensities divided by A_2 . This quantity is expected to vary as $R(\hbar\omega)$ discussed above, and the agreement in the interval 0 $-\hbar\omega = 5$ meV where we apply the resolution correction to the crystal-field spectrum is indeed very good.

ANALYSIS

The 4/ ground-state multiplet of Er, with $J = \frac{H}{4}$, is split by the crystal field into eight doublets. In accordance with the notation of Marshall and Lovesey.¹² we denote the energies by E_n and the states by $(\Gamma_n v)$, with $\kappa = 0$ as the index for the ground state with $E_0 = 0$. The label v distinguishes between the two degenerated wave functions of each level. The cross section for the transition $\Gamma_0 + \Gamma_n$ is then

$$\frac{d^2\sigma}{d\Omega dE'} = cN \frac{k'}{k} A_{\rm c} T_{\rm m} \delta(\hbar\omega - E_{\rm m}) \quad , \tag{3a}$$

with

$$A_{1} = \left(\frac{1.91c^{2}}{m_{e}c^{2}}\frac{1}{2}\kappa F(\vec{\kappa})\right)^{2}e^{-ik^{2}/m_{e}},$$
 (3b)

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$$\begin{split} T_{\mathbf{n}} &= \sum_{\mathbf{a},\mathbf{d}} \left(\delta_{\mathbf{a}\mathbf{b}} - \tilde{\kappa}_{\mathbf{a}} \tilde{\kappa}_{\mathbf{d}} \right) \sum_{\mathbf{c}\mathbf{c}^{*}} P_{\mathbf{b}} \left(r |\mathbf{E}_{\mathbf{b}} \rangle |J_{\mathbf{a}}^{\bullet} | |\mathbf{\Gamma}_{\mathbf{n}} r^{*} \rangle \\ &= \pi \left(r \left(\mathbf{\Gamma}_{\mathbf{n}} |J_{\mathbf{a}} \right) |\mathbf{\Gamma}_{\mathbf{b}} r \right) \right) \end{split}$$

$$(3c)$$

N is the total number of atoms, the fraction c = 0.02 being Er atoms. The g factor is 1.2 for Er and the remaining symbols in Eq. (3b) have their usual meaning.¹² In the expression for the transition probabilities Eq. (3c), \tilde{k}_{0} is the Cartesian α component of $\tilde{\kappa}/\kappa_{0}$ and p_{0} is the occupation probability of one of the two ground states. At 5 K, p_{0} is near 0.5.

The spectra in Fig. 1, $I_{ef}(\hbar\omega)$, were analyzed by a least-squares fit to the expression

$$I_{e,\tau}(\hbar\omega) = S\left(\sum_{n} T_n (\sqrt{2}\pi\sigma_n)^{-1} \exp[-(\hbar\omega - E_n)^2/(2\sigma_n^2)]\right)$$

$$[u_{nt} \exp\{-(h\omega) + 2\pi_0)^2\} + B, \qquad (4)$$

Here the δ function in Eq. (3a) has been changed to a Gaussian distribution of width σ_n in order to take the instrumental resolution as well as an intrinsic linewidth into account. The width σ_n for elastic scattering is known from a scan of the incoherent scattering from V, whereas the widths for inelastic transitions contained one adjustable parameter σ_n in the $e\chi_1$ -ression $\sigma_n^2 = (\sigma^2 + \sigma_{res,n}^2)$, with the resolution width $\sigma_{res,n}$ given in the top part of Fig. 3. The factor $R(\hbar\omega)$ accounts

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	This experiment	From magnetization data
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$H \to K^+$	en i di seri di senti	04,6±0,3410**
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B. IN	u si da ketjada ter 🖷	(= 0,28 ±0,0010 ⁻²
 meVi 	0 43 ± 0 103	

The sign is indetermined by the neutron scattering experiment.

to: the decreasing instrumental sensitivity as explained above. The nuclear moherent scattering is accounted for by the fit parameter $\sigma_{\rm ex}$. The background *E* was determined by the intensities with $E_{\rm ex}=-3$ meV and $E_{\rm ex}=7$ meV.

The transition probabilities T_a and the energies F_a are determined by the crystal-field parameters $L_{2,a}$, $B_{4,a}$, $B_{6,a}$, and $D_{66,a}$. Finally, the scale factor 5 was also a fitting parameter. The best-fit value of 5 agreed with the value obtained from the intensity observed with a V sample of similar shape to the $\operatorname{Er}_{4,a} Y_{4,a6}$ sample.

The calculated spectra obtained in a simultaneous tit to both spectra in Fig. 1 are shown as dashed lines in Fig. 1, and the resulting best-fit parameters are given in Table 1. The dashed line in the bottom part of Fig. 1 is a powder spectrum calculated from this set of parameters. The small phonon contribution is included in this theoretical spectrum.

The corresponding energy levels are shown in the right part of Fig. 1 and the centers of the transition peaks are indicated by arrows on the energy axis.

The ground-state level, from which the strongly anisotropic magnetic elastic scattering originates. turns out mainly to consist of $\pm \frac{12}{2}$ states, while the inelastic peaks in the spectra are due to transtrions to three excited levels dominated by $\pm \frac{10}{2}$, $\pm \frac{\pi}{2}$, and $\pm \frac{\pi}{2}$, respectively. When \overline{k} is along ΓA the magnetic scattering is caused by matrix elements of J_1 and J_2 . Hence, the small elastic magnetic scattering, about $\frac{1}{2}$ of the value for $\tilde{\kappa}$ along Γ^* . is purely due to the small components of other w - states than $-i\frac{W}{2}$, buch are mixed into the ground states via the O_n^4 term of the Hamiltonian in Eq. 1. The transition to the first excited level is hearly is stropic because J_1 , J_2 , and J_2 have matrix mements from the ground level to this level of searly equal size. The last two transitions in the spectra are caused purely by matrix elements. of J_{1} and J_{2} . Hence, the intensity ratio between the K along-EA direction and K along-EM direction should be exactly 2

At first sight it may seen surprising that one can

deduce four crystal-field parameters with reasonable accuracy and a common lifetime from the upper and middle spectra in Fig. 1. The reason is that the different combinations of matrix elements for \vec{k} along ΓA and \vec{k} along ΓM constrain the possible values of the crystal-field parameters significantly.

It is obviously necessary to include a finite lifetime of the excited states as the width of the peak at 2.1 meV exceeds the experimental resolution by more than 50%. The intrinsic width, which of course cannot be accounted for by the Hamiltonian in Eq. (1), is very likely caused by the exchange interaction between the Er ions. In a 2% alloy there is a 24% chance that an Er ion among its 12 neighbors has another Er ion. If we may crudely assume an Ising-like nearest-neighbor-only exchange coupling $-gJ_{t}^{(0)}J_{t}^{(1)}$, it is straightforward by a perturbation calculation to find the corresponding splitting of the degenerate levels in Fig. 1. With $g \simeq 0.02 - 0.04$ meV from the known spinwave dispersion in pure Er^{13,14} we then find a splitting 0.4-0.9 meV, i.e., in the same order of magnitude as the observed widths of the inelastic peaks

CONCLUSION

We conclude that the crystal-field parameters obtained from the magnetization data² for Er diluted in Y are, within the uncertainties of the two experiments, in accordance with those obtained by the more direct spectroscopic method of neutron scattering. This agreement supports the reliability of the crystal-field parameters found in the systematic study of rare-earth (RE) ions in different matrices.² On the other hand, it is also clear from Fig. 1 that the excited states of the Er ions are probed in more detail by neutron scattering than the simple Hamiltonian in Eq. (1) can account for, First there is a significant line broadening, even at 5 K, of the excited levels, most clearly seen in the intense transition to the first excited state. Second, the difference between the best-fit curve based on Eq. (1) and the observed intensities is substantially larger than can be explained by the experimental uncertainties. It seems likely that the interaction between the 47 and the conduction electrons is responsible for these effects, either by the direct interaction¹⁴ or by the indirect exchange coupling to nearby Er ions,

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398F

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APPENDIX V

Crystal Fields in Dilute Alloys of Rare Earths in Sc, Y and Lu Studied by Neutron Scattering

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Abstract

The crystal field levels in Sc-Er, Lu-Er and Y-Dy have been studied by neutron spectroscopy. The spectra for Sc-Er and Lu-Er are similar to earlier published spectra for Y-Er and in agreement with the level schemes deduced from bulk magnetization measurements. Disagreements between the two types of measurement for Y-Dy suggest a correction for magnetic ordering in the analysis of the magnetization data. The reanalysed magnetization results are fully consistent with the neutron results.

Introduction

A number of publications describing magnetization measurements or induce alloys of rare earths in Sc, Y and Lu have recently appeared¹⁻⁵. From these measurements, crystal field parameters B_{lm} have been deduced in the single-ion crystal field Hamiltonian

$$H_{Cf} = B_{20}O_{20} + B_{40}O_{40} + B_{60}O_{60} + B_{66}O_{66}$$
 (1)

where G_{1m} are the usual Stevens' operators⁶. The deduced parameters vary unsystematically with the rare earth solute, and especially the parameters obtained for alloys with Dy differ significantly from those for other solutes. For a given rare earth solute a variation with the host of the quadrupole component (E_{2G}) of the crystal field is observed. Other components show only small variations with the host.

In the present paper we report inelastic neutron scattering experiments on Y-Dy, Sc-Er and Lu-Er alloys. These experiments, together with the earlier published neutron experiment⁷ on Y-2.0 At%Er, provide a check on the variation of crystal field parameters with both solute and host.

Experimental technique

Single crystals of the alloys Sc-2.0At%Er, Y-3.0At%Dy, Y-1.1At%Dy and Lu-2.0At%Er were grown using the technique of annealing arc melted buttons⁸. The chosen shape and size (typically 3 cm³) of the samples were determined from considerations of neutron absorption. Some of the samples consisted of two single crystals aligned with the same orientation. All samples were studied by neutron diffraction, to look for possible ordering, and by inelastic neutron scattering to observe transitions between crystal iel? levels. In the latter experiments the intensity spectrum of scattered neutrons with fixed wave vector transfer (w) and fixed incident energy was measured on a triple axis spectrometer with a counting time determined by a preset number of beam monitor counts (BMC). The incident energy was generally 14.4 meV and a graphite filter was used to remove second-order contamination. The energy resolution was about 1 meV. In one case a 5 meV callent sheigh and side inter colled to ^{off} F were used to obtain a resolution of SLI neV. The measurements were performed at temperatures down to 5 F using a cryostat with Al-windows.

Experimental results

No rearing was observe: at temperatures above 5 K in Sc-2.6A++Er, Y-1.1At+Dy and Y-2.0At+Er. In Y-3.0At+Dy,helical ordering with the moments lying in the basal plane was observed below 9 K. The neutron diffraction scan is illustrated in fig. 1. The spiral arale is 50° per layer. Inelastic scans above the ordering temperature showed no sign of crystal field transitions, probably the to the large exchange interactions responsible for the ordering. Fisc in LG-2.0At+Fr,magnetic satellites were present. The corresponding order existed at least up to 20 K, indicating that the ordering takes place in small regions of high Er concentration. An estimate from satellite intensities showed that less than 3% of the Er takes part in the ordering. Thus the ordering may be meglected in interpreting the inelastic scattering experiment.

The neutron scattering intensity spectrum for Sc-2.0At%Er is shown in fig. 2a. Two transitions, indicated by arrows, are observed. The transition energies determined by a least squares fit of a sum of Gaussians to the spectra are shown in fig. 2b. These results are in agreement with the crystal field parameters determined from analysis of magnetization measurements⁹, as can be seen by comparison with fig. 2c. At the temperature 6.5 F of the neutrum experiment only the crystal field ground level is populated. Thus only transitions from this level to excited levels are observed. Measurements at higher temperatures or with larger wave vector transfer give the same spectrum as fig. 2a, but with demeased intensities of the transition peaks. This behaviour, also over for the other samples, is in agreement with what is expected for pure crystal field transitions.

The spectra for Lu-2.0At%Fr, fig. 3a, show one significant peak arrow at lower energy) and contain evidence of another arrow at higher energy). Also for Lu-2.0At%Er the transition energies, fig. 3b, can be successfully compared with the crystal field level scheme, fig. 3c, obtained from analysis of magnetization measurements⁵.

The spectra at SF for Y-1.1At*Sy show one transition shoulder

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(arrow in fig. 4a). The identification of the shoulder as a crystal field transition is supported by the decrease in intensity at 30K also shown in fig. 4a. An attempt to resolve the transition peak completely by using an energy resolution of 0.2 meV was unsuccessful, because it has an inherent width of about 1 meV. The transition energy 1.33±0.2 meV (fig. 4b) is in clear disagreement with the crystal field levels calculated from earlier deduced parameters (fig. 12 in ref. 1). However, the knowledge that ordering effects are present has made it possible to correct the magnetization data for these effects. An analysis of the corrected data gives crystal field parameters which predict the observed crystal field transition (fig. 4c) and no other observable transitions.

Reanalysis of the magnetization measurements

The crystal field parameters B_{20} , B_{40} , B_{60} and B_{66} are determined, together with two exchange parameters γ_{11} and γ_{1} and the concentration, by fits to the inverse initial susceptibility. The fitting procedure is described in ref. 9. Effects of ordering even in the dilute alloy Y-0.137At%Dy are clearly seen in the measurements of the basal plane anisotropy⁴. The presence of a small ordered region may change the initial susceptibility drastically. However the correct paramagnetic susceptibility can in important cases be obtained from isothermal magnetization curves. For an applied field of sufficient magnitude $(H > H_{min})$ all moments in the crystal will be aligned in the field direction, although acted on by different exchange fields dependent on the local concentration. If the sum of the exchange and the applied fields are within the range for which the pure crystal field susceptibility, X_{CE} , remains at its initial value, we find the following formulae for the differential susceptibility:

$$M_{j} = (H + \gamma_{j} \langle M \rangle) \chi_{CF}$$

$$\langle M \rangle = \frac{1}{N} \sum_{j=1}^{N} M_{j}$$

$$\frac{1}{\chi} = \frac{dH}{d \langle M \rangle}_{H > H_{min}} = \frac{1}{\chi_{CF}} + \langle \gamma \rangle$$

$$\langle \gamma \rangle = \frac{1}{N} \sum_{j=1}^{N} \gamma_{j}$$
(2)

The sums are over sites j, γ_j are site-dependent exchange constants and M_j are the magnetic moments. The only difference of (2) from the formulae for an ideal dilute system is the change of γ to $\langle \gamma \rangle$. The existence of an extended linear range in the magnetically hard directions may be verified theoretically after the parameters have been deduced. (For Y-Dy $\chi_{\rm CF}$ varies less than 2% in the range 0 - 70·10⁵ A/M.)

The validity of the above theory can be verified experimentally by the presence, in the magnetization curves, of a linear range following the initial high slope range. This feature is clearly seen in the magnetization curve shown in fig. 5 which illustrates the difference at 4.2 K between χ_{CF} and the earlier published susceptibility $\chi_{H} = M/H$ measured at the constant field $H = 1.35 \times 10^5 A/M$. χ_{CF} equal χ_{H} for Y-0.137 At%Dy at temperatures above 13 K. For Er alloys χ_{CF} equals χ_{H} in the whole measuring range.

For all alloys measured, the above procedure applies in the hard direction down to 4 K. In the easy directions at low temperature, the initial field independent range of χ_{CF} is too narrow to allow the above procedure. Fortunately the susceptibilities at low temperatures in the easy directions are rather unimportant in determining the parameters.

For Y-0.137 At&Dy, χ_{CF} has been determined from a number of isothermal magnetization curves, and the earlier published $1/\chi$ curves have been corrected. The corrected curves are shown in fig. 6 with new theoretical fits.

For a further check of the revised crystal field parameters for Y-Dy, they were compared to magnetization measurements at higher fields. Figure 7 shows isofield measurements at $44.2 \cdot 10^5$ A/m for Y-0.137 At&Dy¹ together with theoretical curves. The deviation at low temperatures in the c-direction is expected due to the ordering mentioned earlier. In the c-axis magnetization at 4.2 K the deduced crystal field parameters predict a transition at the field $140 \cdot 10^5$ A/m. In a narrow range of $10 \cdot 10^5$ A/m the magnetization should increase 3 $\mu_{\rm B}$ /atom. This is in excellent agreement with the published high field magnetization measurements on Y-Dy³.

Ordering effects in the Er alloys are too small to give any corrections to the initial susceptibility. This is consistent

with the agreement between the magnetization and neutron results for these.

Conclusion

The neutron experiments have demonstrated the necessity of corrections for ordering effects in some dilute alloys. The tendency for ordering of the rare earth solutes decreases in the series Tb, Dy, Ho, Sm and Er which have Néel-De Gennes factors $((g-1)^2 J(J+1))$ 10.50, 7.08, 4.50, 4.46 and 2.55, respectively. The present results suggest that for the typical alloy concentrations used, corrections to $1/\chi$ measurements on Tb and perhaps Ho and Sm alloys may be necessary.

The crystal field parameters obtained from the magnetization data, corrected if necessary in the way described, are in accordance with the results of the independent and direct method of neutron scattering, and are also consistent with high-field measurements.

Table I lists the crystal field parameters divided by corresponding Stevens factors for the 4 alloy systems successfully checked by neutron scattering. The variation with host of B_{20}/α is probably due to the varying c/a ratio. The higher_order parameters B_{40}/β , B_{60}/γ and B_{66}/γ are within uncertainty independent in their determination of both the host and the rare earth solute.

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Crystal field parameters in K divided by Stevens factors for 4 alloy systems. The crystal field parameter B_{66} equal $-\frac{77}{8}B_{60}$, as observed to within the experimental accuracy⁹.

	$\frac{B_{20}}{\alpha}$	^B 40 β	<u>Β₆₀</u> γ
Sc-Er ⁹	-29 ± 3	$8.2 + 5^{-2}$	18.1 ± 2
Lu-Er ^{5,10}	-55.7 ± 7	9.6 ± 2	16.1 ± 2
Y-Er ^{2,10}	-111 ± 13	13.5 ± 6	12.0 ± 3
Y-DY	-115 ± 12	7.5 ± 3.5	13.1 ± 3

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10)	The parameters given here have been obtained by the fitting procedure described in ref. 9 and differ insignificantly from those published earlier.

- 71 -



Fig. 1. Neutron diffractions scan for Y-3.0AttDy along the (002) direction. The satellites $(002)^2$ are not present above 9 K.



Fig. 2 a. Inelastic neutron scattering spectra for Sc-2.0At%Er. The experimental resolution and statistical uncertainties are indicated. The full lines are least squares fits. b. Transition energies with uncertainties obtained from the spectra in fig. 2a. c. Crystal field levels and wave functions calculated from the following crystel field parameters in K: $-2^{-1} = -6^{-0}$

$$B_{20} = (-7.410.7) \cdot 10^{-6}, B_{40} = (3.7 + 2.2) \cdot 10^{-4},$$

$$B_{60} = (37.514.1) \cdot 10^{-6}, B_{66} = -77/8 \cdot B_{60}.$$

These parameters have been obtained from an analysis of magnetization measurements⁸. The uncertainties in energy of the lowest levels and observable transitions at zero temperature are indicated.



Fig. 3 <u>a</u>. Inelastic neutron spectra for Lu-2,0AttEr. Resolution and uncertainties are indicated. The full line is a least squares fit. The dashed line is a guide-to-the-eye, <u>b</u>. Transition energies with uncertainties obtained from the spectra in fig. 3a. <u>c</u>. Crystal field levels and wave function calculated from the following crystal field parameters in K_1

 $B_{20} = -0.141 \pm 0.018$, $B_{40} = (4.25 \pm 0.9) \cdot 10^{-4}$,

 $B_{60} = (33.5\pm4) \cdot 10^{-6}$, $B_{66} = -77/8 \cdot B_{60}$. These parameters have been obtained from an analysis of magnetization measurements^{5,10}. The uncertainties in energy of the lowest levels are indicated. The dashed arrow indicates a possible transition which has too small intensity to be observed experimentally.



Fig. 4 <u>a</u>. Inelastic neutron spectra for Y-1.1AtiDy. Resolution and uncertainties are indicated. The full line is a least squares fit to the spectrum at 5 K. The dashed line is a guide-to-the-eye. <u>b</u>. Transition energy with uncertainties obtained from the spectrum in fig. 4a. <u>c</u>. Crystal field levels and wave function calculated from the following crystal field parameters in K:

 (\cdot)

 $\langle c \rangle$

 $B_{20} = 0.733 \pm 0.07, B_{40} = (-4.5 \pm 2) - 10^{-4},$

 $B_{60} = (13.5:3) + 10^{-6}$, $B_{66} = -77/8 \cdot B_{60}$. These parameters have there obtained by reanalysis of earlier published magnetization measurements¹ as described in the text. The uncertainties in energy of the lowest levels are indicated.



Fig. 5. Hagnetization at T=4.2K for Y=0.14AtBDy in the c-direction. The experimental differential slope at higher fields, m_{CP} (slope of full line) and the earlier published susceptibility $m_{\rm H} = \frac{\rm H}{\rm M}$ at H = 1.35-10⁵ A/m (slope of dashed line) are illustrated.



Fig. 6. Reciprocal susceptibility for Y-0.14Attpy. The experimental points are published data¹ corrected in the c-direction as described in the text. The full curves are theoretical fits, giving the parameters $B_{20} = (0.733\pm0.07) \times B_{40} = (-4.5\pm2) \cdot 10^{-4} \times R$, $B_{60} = (13.5\pm3) \cdot 10^{-6} \times R$, $B_{66} = -77/8 \cdot B_{60}$ $Y_{11} = (-0.3\pm0.1) \cdot 10^{6} (A/m) / \mu_{B}$, $Y_{A} \approx 0$



Fig. 7. Isofield curves at $44.5 \cdot 10^5$ A/m for Y-0.14AtBDy. The experimental points were published earlier¹. The full curves are calculated using the parameters given in the caption to fig. 6.



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