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Published in: I E E E Transactions on Antennas and Propagation

Publication date: 1964

Document Version Publisher's PDF, also known as Version of record

Link back to DTU Orbit

Citation (APA): Christiansen, P. L. (1964). Z-transform theory in general array analysis. I E E E Transactions on Antennas and Propagation, 12(5), 647.

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1964

The simple formulas for $\eta^{a,m}$ hold only when $\omega_{\epsilon_0}/\sigma_2 \ll 1$ and $k_0 b \ll 1$; hence for values of b/d such that $\eta^{e,m}$ is substantially less than unity the input power to these antennas will be very nearly equal to the power dissipated. Under these conditions $\eta^{e,m}$ can be taken as the radiation efficiency of the electric or magnetic dipole surrounded by a shell of lossy dielectric.

By equating η^e and η^m for the same size shell but different conductivities, the results of this paper and those of Galeis show that for a given radiation efficiency it is possible to tolerate a much higher conductivity dielectric in the near zone of a small magnetic type antenna than with an electric type.

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² J. Galejs, "Small electric and magnetic antennas with cores of a lossy dielectric," J. Research Natl. Bur. Stds., vol. 67D, p. 445; July-August, 1963.

Z-Transform Theory in General Array Analysis

In a recent communication¹ Cheng has stated that arrays with nonuniform spacing can be studied by means of a complex envelope function. In this communication the array factor $G(\theta, \phi)$ for an arbitrary array with n elements is written as a Z transform, and the usefulness of Z-transform theory in general array analysis is discussed.

Let the real vector envelope function for the positions of the elements and the complex scalar envelope function for the currents on them, be defined as

$$\bar{r}(x) = x\hat{\xi} + \bar{s}(x) \tag{1}$$

and

$$\sigma(x) = A(\bar{r}(x))$$
$$\cdot \exp\left(j\left[\frac{\alpha}{d}\,\bar{r}(x)\cdot\hat{\xi} + \phi(\bar{r}(x))\right]\right) \quad (2)$$

Manuscript received April 6, 1964. ¹ D. K. Cheng, "Z-transform theory for linear array analysis," IEEE TRANS. ON ANTENNAS AND PROPAGATION (Commun.), vol. AP-11, p. 593; September, 1963.



respectively, where $x = \nu d$ on the ν th element, $\bar{s}(x)$ and $\phi(\bar{r}(x))$ are nonlinear functions of x and \bar{r} , respectively, and $A(\bar{r}(x))$ is the amplitude of $\sigma(x)$. $\hat{\xi} = (1, 0, 0)$ and

 $\hat{R} = \hat{\xi} \sin \theta \cos \phi + \hat{\eta} \sin \theta \sin \phi + \hat{\zeta} \cos \theta.$ (3)

If $\bar{s}(x) = 0$, d is the distance between the elements and α is the linear phase progression. We then obtain

$$G(\theta, \phi) = \sum_{\nu=0}^{n-1} A(\bar{r}(\nu d))$$

$$\cdot \exp\left(j\left[\frac{\alpha}{d}\,\bar{r}(\nu d)\cdot\hat{\xi} + \phi(\bar{r}(\nu d))\right]\right)$$

$$\cdot \exp\left[jk\bar{r}(\nu d)\cdot\hat{R}\right]$$

$$= Z\left\{A(\bar{r}(x))\exp\left(j\left[\phi(\bar{r}(x))\right] + \left(\frac{\alpha}{d}\,\hat{\xi} + k\hat{R}\right)\cdot\bar{s}(x)\right]\right)\gamma_n(x)\right\} \quad (4)$$

where k is the propagation constant, $\gamma_n(x)$ is the unit gate function,² and the following transformation³ has been used:

$$\exp\left\{j\left[\alpha + kd\hat{\xi}\cdot\hat{R}\right]\right\} = z^{-1}.$$
 (5)

In (4) the array factor is written as a polynomial of (n-1)th degree in z^{-1} . Only two classes of polynomials in which the number of terms depends on the degree appear to have been given in a closed form (i.e., a form in which the number of terms does not depend on the degree):

1) Polynomials where new roots do not enter when the degree is increased beyond a certain value, e.g., the binomial distribution⁴

$$(1 - z^{-1})^{n-1} = Z\left\{\frac{1}{\left\{\frac{x}{d} B\left(\frac{x}{d}, \frac{nd-x}{d}\right)\right\}}\right\} (6)$$

² P. L. Christiansen, "On the closed form of the array factor for linear arrays," IEEE TRANS. ON ANTENNAS AND PROPAGATION (Commun.), vol. AP-11, p. 198; March, 1963. ³ S. A. Schelkunoff, "A mathematical theory of linear arrays," Bell Sys. Tech. J., vol. 22, pp. 80–107; January, 1943. ⁴ Join Stone Stone, U. S. Patents 1,643,323 and 1,715,433.

in which B denotes Euler's beta function, and the unit gate function does not appear explicitly. In general, however, it is difficult to give analytical expressions for the envelope functions and Z-transform theory is not helpful. This is also the case when the principle of pattern multiplication⁵ is applied.

2) Polynomials which can be obtained from the formula

 $Z\{(\omega x)^p e^{-ax} \gamma_n(x)\}$

$$= (-\omega)^{p} \frac{\partial^{p}}{\partial a^{p}} \frac{1 - e^{-and_{z}-n}}{1 - e^{-ad_{z}-1}} \quad (7)$$

which is given in a previous communication² and derived in a report⁶ by means of Z-transform theory. In this case new roots enter in an interesting way when n is increased. For p=0 they will all lie on the circle $|e^{-adz^{-1}}| = 1$; $(e^{-adz^{-1}} \neq 1)$. For p = 1 all roots will lie inside the circle $e^{-ad}z^{-1} = 1$ (this case is shown in Fig. 1 for $n = 2, 3, \cdots, 25$). The root configuration for higher values of p can be studied by means of the Schur-Cohn criterion.7

We have thus considered coefficients and roots in the two classes of polynomials which can be given in a closed form. Z-transform theory was only relevant in the second class. Also, since very special requirements must be placed on the position and the current envelope functions before (7) can be applied to (4), severe limitations are imposed on the applicability of Z-transform theory in obtaining a closed form for the array factor in general array analysis.

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⁵ J. D. Kraus, "Antennas," McGraw-Hill Book Co., Inc., New York, N. Y., p. 94; 1950, ⁶ P. L. Christiansen, "List of Z-transforms," R 32, Lab. of Electromagnetic Theory, The Technical Uni-versity of Denmark, Copenhagen, pp. 5-7; July, 1963, ⁷ M. Marden, "The geometry of the zeros of a polynomial in a complex variable," Am. Math. Soc., New York, N. Y., p. 152; 1949.