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# Nasics: A 'Fabric-Centric' Approach Towards Integrated Nanosystems

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**NASICS: A 'FABRIC-CENTRIC' APPROACH TOWARDS  
INTEGRATED NANOSYSTEMS**

A Thesis Presented

by

PRITISH NARAYANAN

Submitted to the Graduate School of the  
University of Massachusetts Amherst in partial fulfillment  
of the requirements for the degree of

DOCTOR OF PHILOSOPHY

February 2013

Electrical and Computer Engineering

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# NASICS: A 'FABRIC-CENTRIC' APPROACH TOWARDS INTEGRATED NANOSYSTEMS

A Thesis Presented

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## ABSTRACT

# NASICS: A ‘FABRIC-CENTRIC’ APPROACH TOWARDS INTEGRATED NANOSYSTEMS

FEBRUARY 2013

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This dissertation addresses the fundamental problem of how to build computing systems for the nanoscale. With CMOS reaching fundamental limits, emerging nanomaterials such as semiconductor nanowires, carbon nanotubes, graphene etc. have been proposed as promising alternatives. However, nanoelectronics research has largely focused on a ‘device-first’ mindset without adequately addressing system-level capabilities, challenges for integration and scalable assembly.

In this dissertation, we propose to develop an integrated nano-fabric, (broadly defined as nanostructures/devices in conjunction with paradigms for assembly, interconnection and circuit styles), as opposed to approaches that focus on MOSFET replacement devices as the ultimate goal. In the ‘fabric-centric’ mindset, design choices

at individual levels are made compatible with the fabric as a whole and minimize challenges for nanomanufacturing while achieving system-level benefits vs. scaled CMOS.

We present semiconductor nanowire based nano-fabrics incorporating these fabric-centric principles called NASICs and N<sup>3</sup>ASICs and discuss how we have taken them from initial design to experimental prototype. Manufacturing challenges are mitigated through careful design choices at multiple levels of abstraction. Regular fabrics with limited customization mitigate overlay alignment requirements. Cross-nanowire FET devices and interconnect are assembled together as part of the uniform regular fabric without the need for arbitrary fine-grain interconnection at the nanoscale, routing or device sizing. Unconventional circuit styles are devised that are compatible with regular fabric layouts and eliminate the requirement for using complementary devices.

Core fabric concepts are introduced and validated. Detailed analyses on device-circuit co-design and optimization, cascading, noise and parameter variation are presented. Benchmarking of nanowire processor designs vs. equivalent scaled 16nm CMOS shows up to 22X area, 30X power benefits at comparable performance, and with overlay precision that is achievable with present-day technology. Building on the extensive manufacturing-friendly fabric framework, we present recent experimental efforts and key milestones that have been attained towards realizing a proof-of-concept prototype at dimensions of 30nm and below.

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# CHAPTER 1

## INTRODUCTION

As MOSFET critical dimensions have progressed through the deep-submicron to nanoscale regimes, CMOS technology is facing new challenges across both device characteristics as well as manufacturability and may in the near future reach fundamental barriers. With aggressive scaling, it becomes increasingly difficult to achieve the manufacturing precision required to keep variability and defect rates within acceptable limits. For example, ITRS 2011 [26] projects  $3\sigma = \pm 1.3nm$  Critical Dimension (CD) control and  $3\sigma = \pm 3nm$  overlay control for 16nm CMOS, precisions for which manufacturing solutions are not known. Optical system complexity and design rules for manufacturing are becoming increasingly intractable. These extremely stringent manufacturing requirements are a consequence of the general fabric architecture of CMOS, which requires a high degree of customization, including arbitrary placement and complex interconnectivity schemes. Furthermore, at the device-level challenges include the need for complementary devices with precise sizing and ultra-sharp doping profiles (1nm-2nm lateral doping abruptness [10]) for source-channel and drain-channel junctions. Arbitrary layouts with complex interconnection also imply increased power consumption, because of the need to switch large interconnect load capacitances.

Emerging nanomaterials such as semiconductor nanowires [11, 12], carbon nanotubes [23, 24], graphene [22, 42], molecular devices [7], spintronic/spin-wave devices [64] etc. have been suggested as alternatives to conventional CMOS technology. However, research in the field of emerging electronics has largely concentrated on a



‘device-first’ approach i.e. discovering and optimizing MOSFET replacement devices with the assumption that CMOS circuit styles and paradigms for interconnection to build logic gates/integrated systems will be preserved intact. However, at the present time, there are no immediately obvious replacement devices/state-variables available [15]. Furthermore, the device-first approach does not address the aforementioned challenges. This implies that given several levels of logic and routing, system-level capabilities may not necessarily scale in proportion to individual device performance.

By contrast, at the nanoscale, it would be desirable to minimize lithographic customization requirements on devices and layouts (e.g. eliminating arbitrary sizing and placement of devices and arbitrary routing between them) by moving towards simple device structures and regular layouts such as parallel arrays and grids that are more easily realizable with both unconventional and photolithography-based manufacturing approaches. Furthermore, ultra-dense nanosystems could be realized if both devices and local interconnects could be formed at the same time as part of these regular layouts, as opposed to requiring fine-grain arbitrary interconnections of individual devices at nanoscale dimensions. This integrated approach across multiple design levels including manufacturing, devices, circuits and architecture is called the ‘fabric-centric’ mindset. This mindset is anchored in a belief that at nanoscale developing a complete fabric framework, rather than focusing on devices alone, is how significant progress could be made. The twin objectives of this fabric-centric approach are reducing manufacturing requirements while concurrently improving system-level capabilities.

The goal of this dissertation is to develop integrated nanoscale fabrics based on the principles of the fabric-centric approach, validate core concepts at all fabric design levels and explore manufacturing solutions towards demonstrating a proof-of-concept prototype. Nanoscale Application Specific Integrated Circuits (NASICs) is a semiconductor nanowire-based fabric that implements logic and memory functionalities on

regular 2-D semiconductor nanowire grids with crossed-nanowire field effect transistors (xnwFETs) at certain crosspoints. Previous work on NASICs has focused more on architectural and defect tolerance aspects. A simple general purpose processor called WIre Streaming Processor version-0 (WISP-0) [35, 56] was built on the NASIC fabric. Built-in defect tolerance schemes [35, 57] were also developed to provide resilience against high levels of manufacturing defects. In this dissertation, we discuss key physical layer aspects, device-circuit co-design and experimental directions towards realizing a nanowire fabric. The main technical contributions are:

- We show how manufacturing and device-level requirements can be significantly alleviated through design optimizations including novel circuit style and control schemes.
- We develop an integrated device-circuit methodology for evaluating nanodevice behavior in-fabric and validating core physical fabric concepts. This methodology is generic and ties physical layer assumptions and accurate 3-D physics based simulations of device structures with extensive circuit-level simulation and validation. Using the device-circuit methodology, we evaluate noise, cascading and functionality aspects that are apparent only when considering interacting devices and associated control schemes.
- We extend the generic integrated device-fabric methodology to address parameter variability and present evaluations at device, circuit and system levels.
- We discuss scalable manufacturing pathways for NASICs and identify remaining manufacturability challenges for integration.
- We present N<sup>3</sup>ASICs, a new 3D integrated nanoscale computing fabric which combines unconventional manufacturing with CMOS design rules and can be assembled with no special manufacturing requirements. We also present bench-

marking of NASICs and N<sup>3</sup>ASICs WISP-0 processor designs vs. equivalent 16nm scaled CMOS.

- Building on this extensive theoretical framework and manufacturing-friendly fabric design, we present recent progress towards fabrication and experimental demonstration of N<sup>3</sup>ASICs in Cleanroom settings.

The rest of this dissertation proposal is organized as follows: Chapter 2 presents a brief overview of the NASIC fabric. Chapter 3 discusses single-type FET NASICs. Chapter 4 describes integrated device-fabric methodologies for validating cascading, noise mitigation and functionality. The methodology for handling device parameter variation and detailed evaluations at all fabric levels are presented in Chapter 5. Chapter 6 discusses scalable manufacturing pathways. Chapter 7, presents a new 3-D integrated fabric with no special manufacturing constraints. Chapter 8 describes recent experimental efforts and demonstrations targeting a proof-of-concept prototype. Chapter 9 concludes this dissertation.

## CHAPTER 2

# NANOSCALE APPLICATION SPECIFIC INTEGRATED CIRCUITS (NASICS): AN OVERVIEW

This chapter provides a brief overview of NASICs. NASICs are targeted as a CMOS replacement technology for general purpose computing as well as specialized applications such as image processing. NASICs rely on regular 2-D grids of semiconductor nanowires, motivated by the need for simpler manufacturability at the nanoscale without arbitrary layouts or extensive nanoscale customization. Logic and interconnect are achieved as part of the grid itself, without the need for arbitrary connections at nanoscale dimensions post device-formation. Devices and circuit styles amenable to implementation on these grids are used. Computational streaming/cascading is supported from external reliable circuitry. Built-in fault tolerance is used to provide resilience against permanent manufacturing defects, transient faults and parameter variations. More details are presented below.

### 2.1 NASIC Building Blocks: Semiconductor Nanowires and Crossed Nanowire Field Effect Transistors

Semiconductor nanowires are nanostructures made of semiconductor material with diameters typically between 2nm – 100nm. Nanowires can be grown to up to a few microns in length and have been shown with a variety of materials including Silicon [11, 31], Germanium [17, 61], Zinc Oxide [29], Indium Phosphide [13] and Indium Antimonide [28]. By using non-conventional or self-assembly techniques [16, 21, 54], it may be possible to assemble these materials into regular arrays and grids.

The NASIC fabric is built on these types of 2-D semiconductor nanowire grids with crossed nanowire field-effect transistors (xnwFETs) at certain crosspoints. The channel of a xnwFET is aligned along one NW while the perpendicular NW above it acts as gate. A typical xnwFET behavior has been reported in Silicon NWs in [20].

## 2.2 NASIC Circuits

Fig. 2.1 shows an example of a NASIC circuit that implements a 1-bit full adder. This consists of a semiconductor nanowire grid with peripheral microwires (MWs) that carry  $V_{DD}$ ,  $V_{SS}$  and dynamic control signals. Both  $n$ - and  $p$ -type xnwFETs are shown at certain crosspoints in the diagram. Channels of xnwFETs are oriented horizontally on the left plane, and vertically on the right. Inputs are received from vertical nanowires in the left plane. These act as gates to  $n$ -type horizontal nanowire FETs implementing an AND stage of a two-level logic. The outputs of the horizontal AND plane act as gates to  $p$ -type xnwFETs whose channels are aligned in the vertical direction (right OR plane). Multiple such NASIC tiles are cascaded together to form more complex circuitry such as processors [56]. In keeping with the fabric-centric mindset, all crossed nanowire devices used in one logic stage of the circuit are identical with no arbitrary doping or sizing requirement. Customization of the grid is limited to defining the positions of transistors and interconnect, which determines the logic function implemented without arbitrary placement or routing.

NASICs use dynamic signals driven from external reliable CMOS circuitry. Control signals coordinate the flow of data through NASIC tiles: horizontal and vertical signals are different, supporting cascading. Fig. 2.2 shows a typical NASIC control scheme but other schemes are also possible. Horizontal nanowire outputs are initially discharged to logic ‘0’ by asserting  $hdis$ .  $hdis$  is then switched off and  $heva$  is asserted to evaluate inputs. If all inputs are ‘1’ an output of ‘1’ is achieved, realizing AND logic. In the next phase, both  $hdis$  and  $heva$  are switched off, and the horizontal

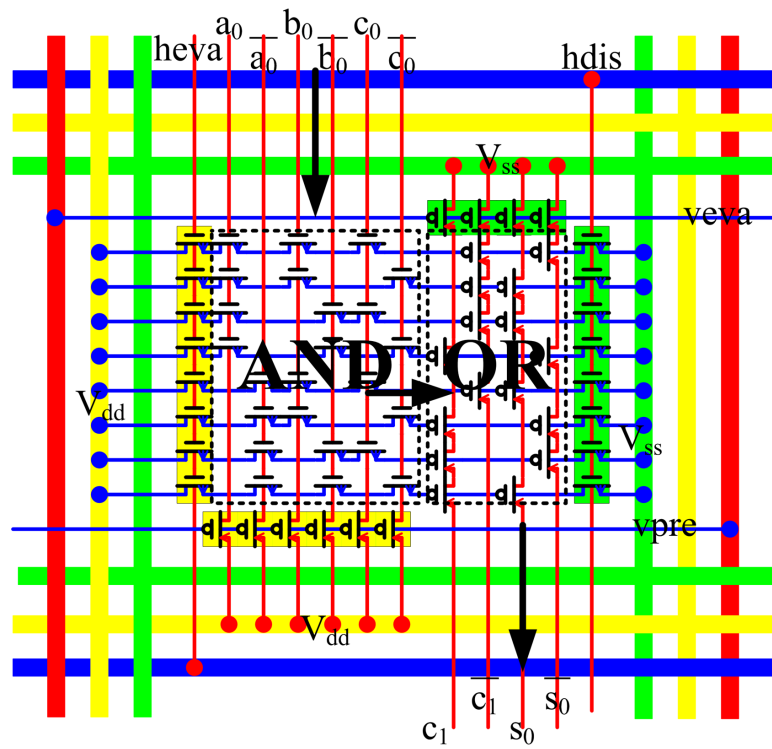
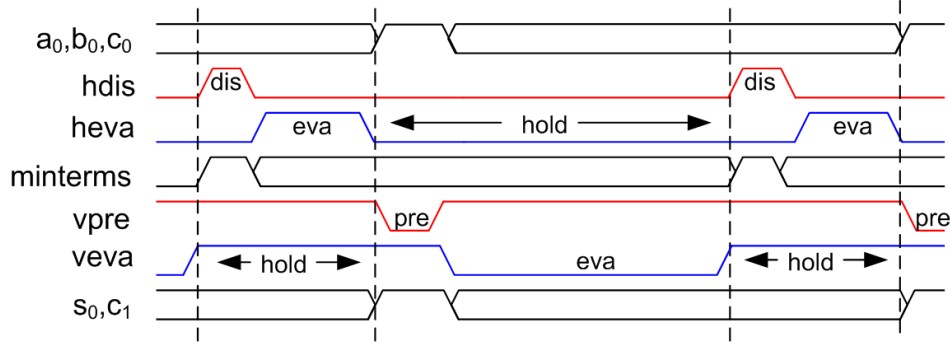


Figure 2.1. NASIC 1-bit Full adder using AND-OR 2-level logic



**Figure 2.2.** Dynamic control scheme for NASIC 2-level AND-OR logic

nanowires are in hold phase, during which time vertical nanowires are precharged ( $vpre$  is asserted) to ‘1’.  $veva$  is then asserted and outputs from the tile are evaluated. The staggered evaluation of dynamic stages with inserted hold phases is critical to NASIC operation. The hold phase enables implicit latching of the nanowire output after evaluation without the need for expensive flip-flops, and is essential for cascading multiple nanowire stages [37].

### 2.3 WISP-0 Architecture

NASIC tiles may be cascaded together to form large scale systems/architectures. Wire Streaming Processor version 0 (WISP-0) is a stream processor that implements a 5-stage microprocessor pipeline architecture including fetch, decode, register file, execute and write back stages. WISP-0 consists of five nanotiles: Program Counter (PC), ROM, Decoder (DEC), Register File (RF) and Arithmetic Logic Unit (ALU). Fig. 2.3 shows its layout. In WISP designs, in order to preserve the density advantages of the fabric, data is streamed through the fabric with minimal control/feedback paths. All hazards are exposed to the compiler. It uses dynamic circuits and pipelining on the wires to eliminate the need for explicit flip-flops and therefore improve the density considerably. WISP-0 is used as a design prototype for evaluating key metrics such as area and performance as well as the impact of various fault-tolerance techniques

on chip yield and process variation mitigation. A NASIC WISP-0 processor has been shown to be up to 33X denser than an equivalent 16nm CMOS implementation.

## **2.4 Chapter Summary**

This chapter presents a brief overview of the NASIC fabric. The rest of the dissertation addresses key physical fabric issues in building integrated nanosystems in general, and NASICs in particular, including integrated device-circuit explorations, fabric-friendly design optimizations for functionality and reducing manufacturing requirements, parameter variation, fabrication etc.



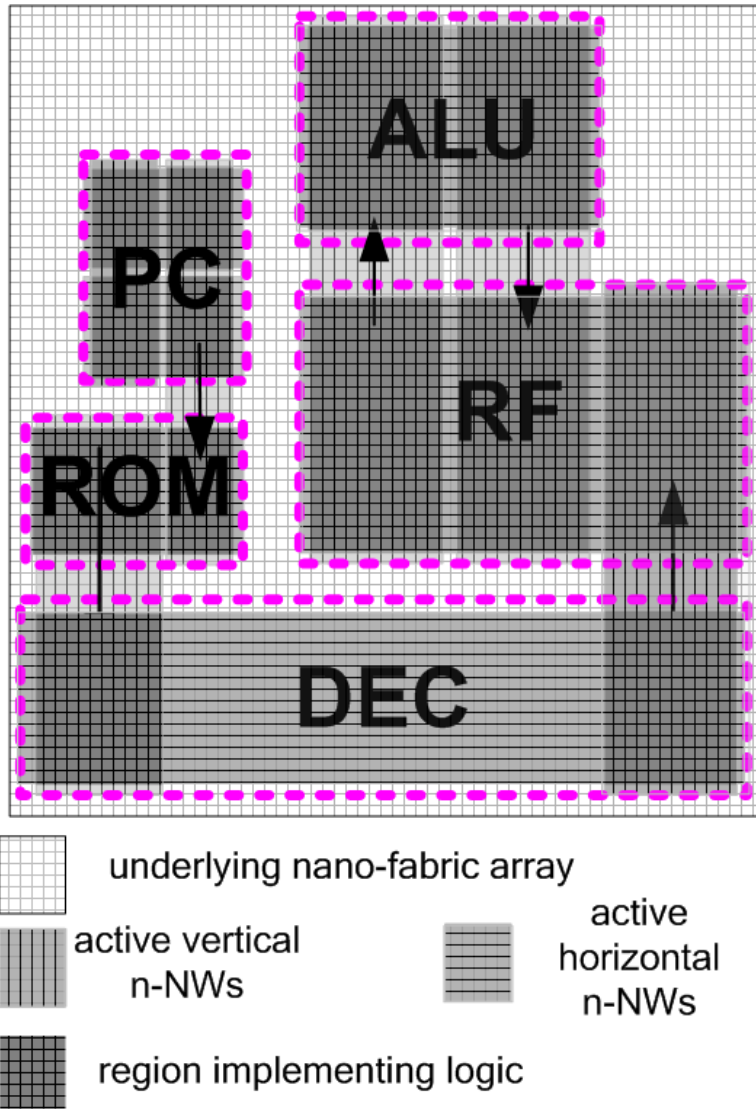


Figure 2.3. WISP-0 Nanoprocessor layout

## CHAPTER 3

### CMOS CONTROL ENABLED SINGLE-TYPE FET NASIC

In nano-systems based on semiconductor nanowires, it may be difficult to build both  $p$ - and  $n$ -FETs using the same material. While complementary FETs have been demonstrated in zinc oxide [41], silicon [11], and germanium [17] nanowires, in all cases large differences in transport properties were found between the two types of FETs, sometimes much greater than those seen in today's traditional CMOS transistors. As the transistor characteristics are certain not to be symmetric between  $n$ -FETs and  $p$ -FETs, this would make timing closure more complicated thereby making it harder to manufacture systems reliably. Consequently, when designing at the nanoscale, it would be advantageous if only one type of device were required.

However, in general, conventional logic systems designed using mostly one type of FETs, such as pseudo-NMOS, suffer from major power and performance drawbacks as compared to CMOS [45]. This is one reason why such designs have not found widespread applicability.

In NASIC designs, instead of using a scheme such as pseudo-NMOS, the dynamic control from external CMOS can be modified such that the associated nanoscale circuits could function with only one type of FET. The static power consumption can be eliminated by ensuring that the control scheme never causes direct paths between ground and the power supply voltage.

This chapter introduces new types of dynamic circuit styles utilizing only one type of xnwFETs in the logic portions of the design. In keeping with the fabric-centric mindset, this approach has the following key advantages:

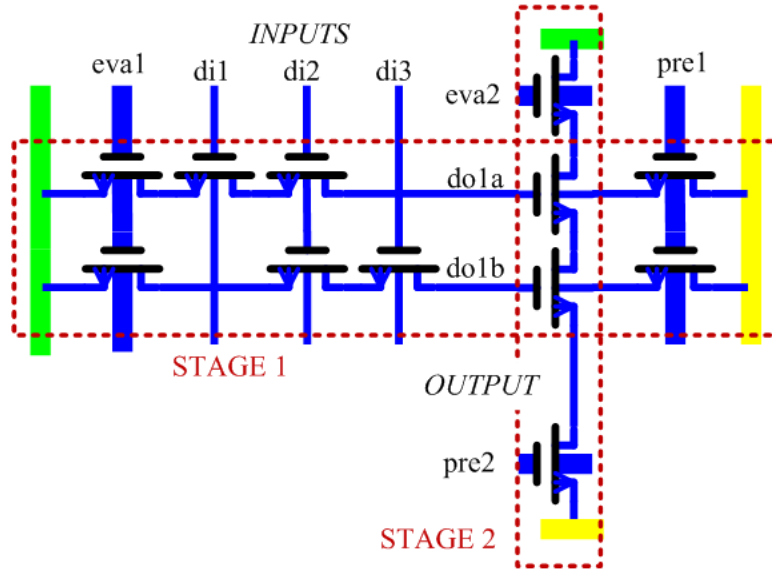
- It eases manufacturing requirements by eliminating one doping type.
- It reduces device design and optimization requirements, since characteristics of dissimilar devices need not be balanced.
- By eliminating slower  $p$ -type devices, it enables system-level performance improvement.

Furthermore, as will be shown in this chapter, these benefits come with no loss in the overall density of the fabric.

### 3.1 Modifications to the Control Scheme

It has been found that altering the CMOS control scheme obviates the need for two types of devices to implement arbitrary logic functions on the nanogrid. The scheme may thus be used with manufacturing processes where complementary devices are difficult or impossible to achieve. A design using only  $n$ -type FETs will implement a NAND-NAND cascaded logic whereas a design using  $p$ -type FETs will implement a NOR-NOR logic. Fundamentally, these are equivalent with the original AND-OR (Fig. 2.1).

Fig. 3.1 shows two NASIC stages implementing NAND-NAND functionality with only  $n$ -type xnwFETs. Outputs from the horizontal NAND stage ( $do1a$  and  $do1b$ ) become gate inputs for the vertical NAND stage as part of the crossbar grid structure without additional routing requirement. The associated timing scheme is shown in Fig. 3.2. On comparison with the AND-OR timing scheme (Fig. 2.2), it is seen that the dynamic scheme of precharge, evaluate and hold is still in place. However the behaviour of the control signals has been modified. There is no predischarge phase; all planes are precharged. Outputs are initially at logic ‘1’, and if all inputs are ‘1’, they are evaluated to ‘0’, achieving NAND functionality. Also, all control signals are

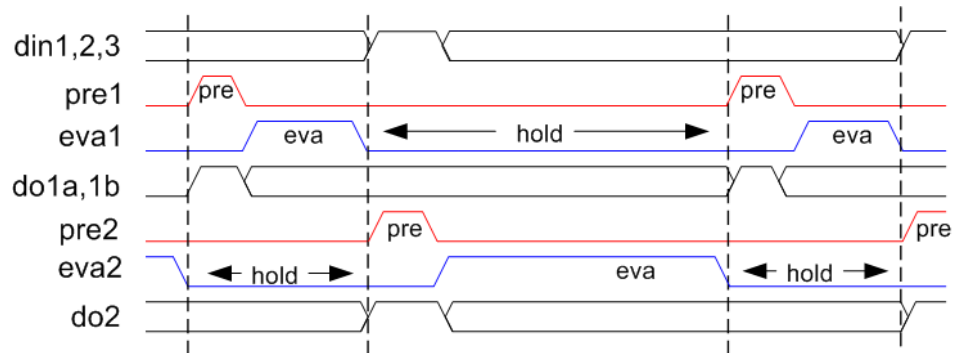


**Figure 3.1.** NASIC circuit with two dynamic NAND stages - Output of one stage is cascaded to the next.

active high, since they gate only  $n$ -type FETs. Similar to the previous case, hold phases are inserted for implicit latching and correct cascading.

### 3.2 NASIC Logic Implementation with One Type of Devices

Fig. 3.3 shows a 1-bit full adder built using only  $n$ -type devices. Fig. 3.3(a) shows a 3-D physical fabric diagram with the crossed nanowire grid, xnwFET channels (blue regions) and peripheral microwires for power rails and dynamic control. Fig. 3.3(b)



**Figure 3.2.** Control scheme for NAND-NAND NASIC logic with implicit latching

shows the circuit equivalent implementing NAND-NAND logic. In comparison with the previous implementation (Fig. 2.1) it may be noted that the relative positions of the transistors in the NAND-NAND example is identical to the AND-OR implementation. The only change from AND to NAND is in the swapping of the control signals,  $V_{DD}$  and  $V_{SS}$ . The output node is precharged rather than predischarged and evaluated to ground as opposed to logic ‘1’, which results in the inversion of the function. On the second plane, the change is more significant: from OR to NAND. Both the type of the transistor and polarity of the control scheme have been changed. Also, the inputs to the vertical NW are now inverted from their values in the AND-OR scheme. The inversion of the inputs in conjunction with the change from OR to NAND results in a transformation of the logic function. DeMorgan’s Laws tell us that this transformation should produce the same result as the AND-OR scheme. This allows us to maintain the transistors in their original positions, even though the logic functions used have changed. It can thus easily be seen that there will be no impact on the area of the overall design.

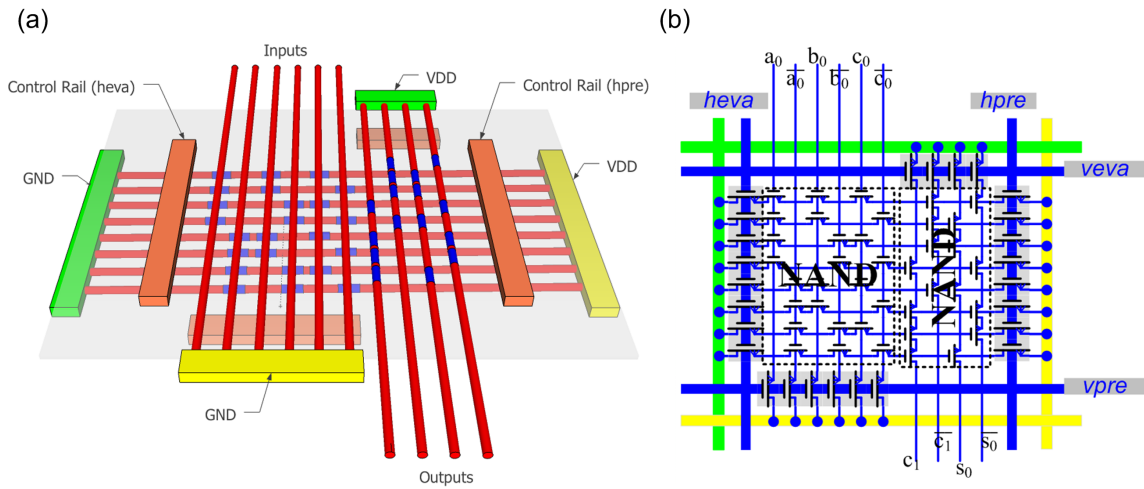
All WISP-0 tiles were implemented using the new control scheme and  $n$ -type xnwFETs. Two examples are shown below.

### 3.2.1 WISP-0 Program Counter

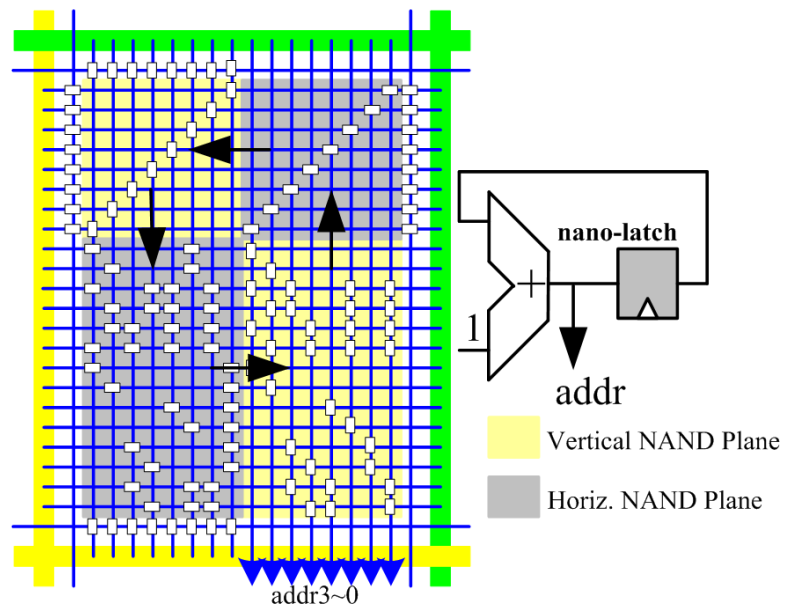
The WISP-0 program counter is implemented as a 4-bit accumulator. Its output is a 4-bit address that acts as input to the ROM. The address is incremented each cycle and fed back using a nano-latch. Fig. 3.4 shows implementation of the Program Counter using NAND-NAND. Diagonal FETs on upper NAND planes delay output by one cycle and allow signals to turn the corner.

### 3.2.2 WISP-0 Arithmetic Logic Unit

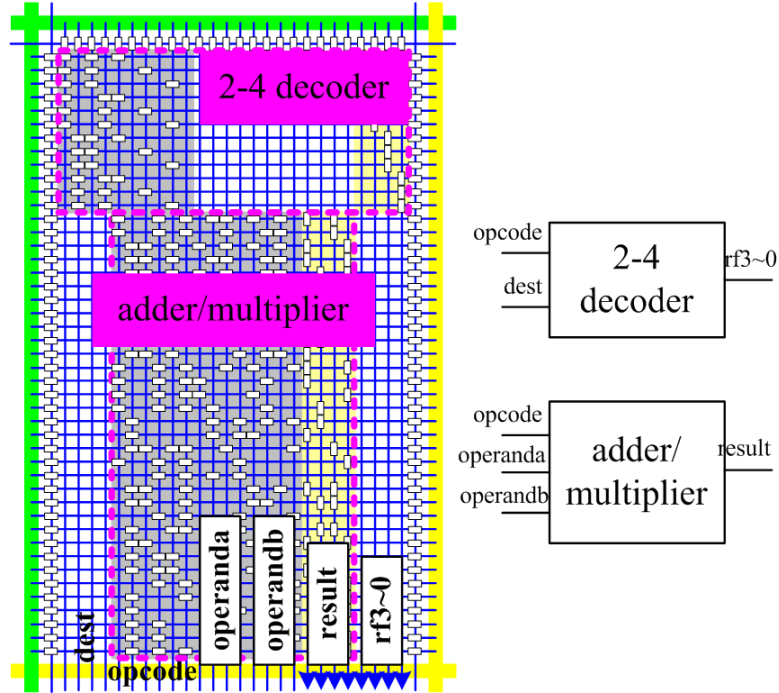
Fig. 3.5 shows the layout of the WISP-0 ALU that implements both addition and multiplication functions. The arithmetic unit integrates an adder and multiplier



**Figure 3.3.** NASIC 1-bit full adder with NAND-NAND logic (a) 3-D physical fabric view with nanowire grid, xnwFETs, oxide and peripheral control. (b) circuit-equivalent implementation



**Figure 3.4.** WISP-0 Program Counter implemented using NAND-NAND logic



**Figure 3.5.** WISP-0 Arithmetic Logic Unit implemented using NAND-NAND logic

together to save area and ease routing constraints. It takes the inputs (at the bottom) from the register file and produces the write-back result. At the same time, the write-back address is decoded by the 2-4 decoder on the top and transmitted to the register file along with the result. The result is written to the corresponding register in the next cycle.

### 3.3 Cascading and Noise Considerations for Single-Type FET Designs

With single-type xnwFET schemes,  $n$ -type precharge devices are used to pull up output nodes. If the gate voltage were  $V_{DD}$ , this would lead to output potentials below  $V_{DD}$ , typically around  $(V_{DD} - V_{TH})$  [45]. One important consideration is, will cascading of multiple dynamic stages lead to accumulation of  $V_{TH}$  drops, causing

incorrect functionality? The NASIC logic style is designed such that this catastrophic noise build-up scenario never occurs.

Firstly, the gate voltage for the precharge device is controlled from external CMOS circuitry and not from logic. This implies that the driving voltage can be higher than  $V_{DD}$ , leading to a full voltage swing at the output node. Furthermore, NASICs use a NAND-NAND logic style which, in addition to being able to implement any arbitrary logic function, is also inverting in nature. Output nodes at any stage are always cascaded to a xnwFET in the next stage that is part of a pull down network. In other words, the logic style is such that logic ‘1’ inputs when evaluated will cause logic ‘0’ output at the next stage. Output signals at any stage do not gate xnwFETs in pull-up networks; the pull-up is accomplished entirely by precharge signals. Therefore, a combination of circuit and inverting logic style prevents noise accumulation in NASIC designs. Extensive device-fabric noise simulations have shown that there is no noise accumulation in cascaded dynamic circuits 40 stages deep. Detailed evaluations of noise and cascading issues are presented in the next chapter.

### **3.4 Chapter Summary**

A fabric-friendly approach towards elimination of dissimilar devices in the NASIC fabric was presented. The new circuit-style is enabled by changes to the external CMOS control scheme and is achieved with no loss of density and has benefits at manufacturing, device, and architectural levels. The use of single-type FETs for NASIC designs implies that manufacturing requirements are considerably eased since complementary doped nanowire devices are not needed. Device-design and optimization effort may be reduced since balancing device characteristics across dissimilar devices through sizing or other approaches are not required. System-level performance benefits are also achieved due to the elimination of slower devices. The next chapter will



discuss detailed device and circuit level evaluations of the NAND-NAND circuit style including noise implications and further improvements to the control scheme.

## CHAPTER 4

# INTEGRATED DEVICE-FABRIC EXPLORATION AND NOISE MITIGATION IN NANOSCALE FABRICS

Integration of nanofabrics requires extensive validation of device interactions. Charge sharing and capacitance effects that cause glitches are apparent only when considering multiple devices together and could cause loss of functionality and/or performance. Therefore, while device choices and optimizations must target key electrical parameters such as threshold voltage and intrinsic delay, in keeping with the fabric-centric mindset, they should also i) be fully validated at the circuit/fabric level for noise implications and functionality and ii) not impose insurmountable challenges for the fabric manufacturing sequence.

In this chapter we present an integrated device-fabric exploration with simulations at the circuit level built on accurate 3-D physics based simulations of nanodevice electrostatics and operations. Using an integrated approach, co-design of devices and circuits can be accomplished with accurate physics-based device models. We extract device I-V characteristics, parasitic capacitances and key electrical parameters such as threshold voltage and on/off current ratios for different xnwFETs. We then create behavioral models of the data for a circuit simulator and use these to evaluate devices in-fabric for noise resilience, signal integrity and validation of worst-case test circuits. We also discuss implications of device and fabric choices for manufacturing. While the work is focused on xnwFETs and NASICs, the approach and methodology are fairly generic and may be applicable to other nanoscale fabrics.

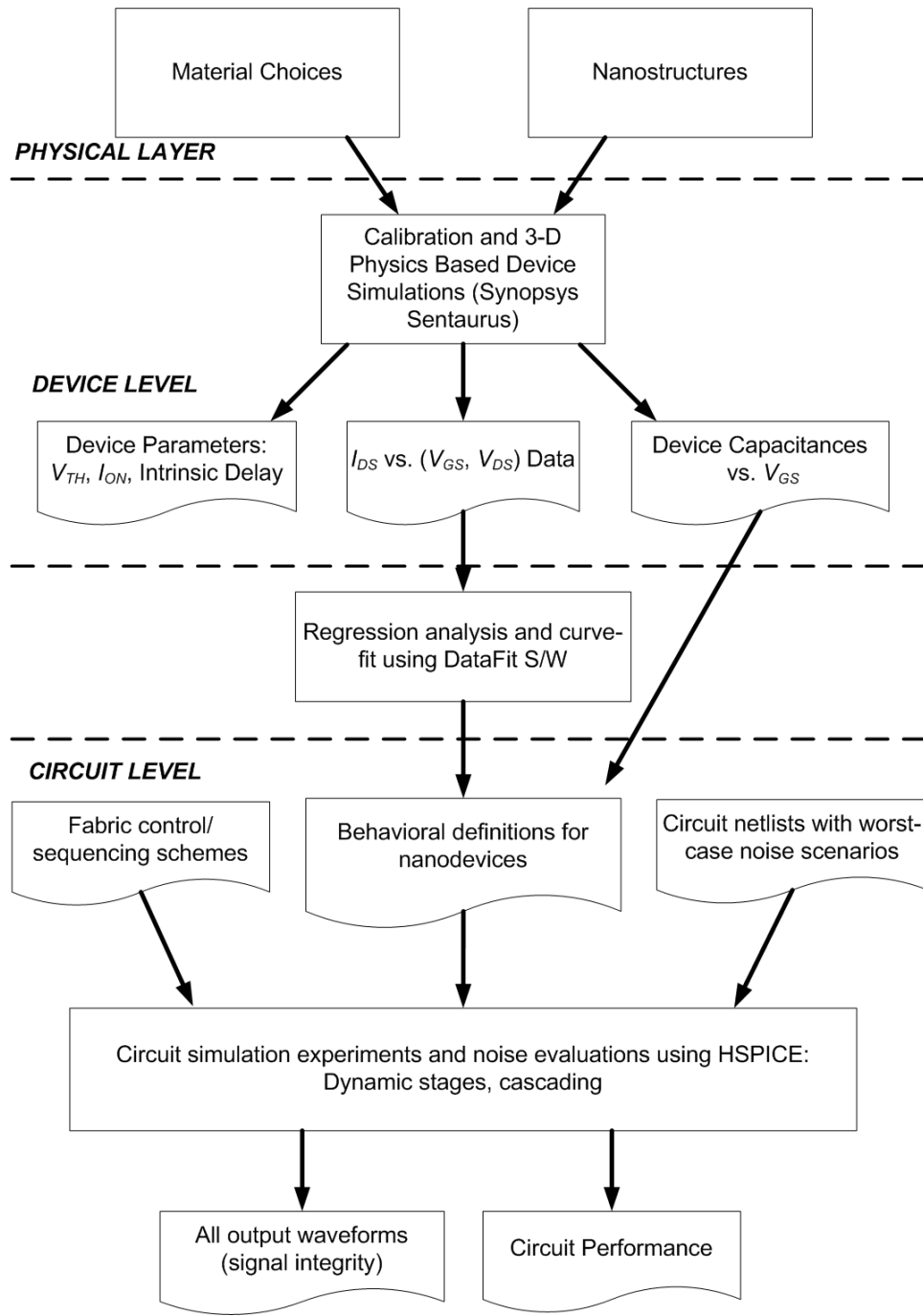
## 4.1 Methodology for Integrated Device-Fabric Exploration

The methodology for bottom-up integrated device-fabric explorations is detailed in this section. It encompasses physical layer assumptions, device level explorations and implications at higher design levels and is summarized in a flow diagram (Fig. 4.1).

A variety of physical layer assumptions such as choice of gate material and the structure of devices can be made targeting device metrics such as the threshold voltage, on-currents and intrinsic delay. For example, the gate material used in NASIC crossed nanowire field effect transistors (xnwFETs) could be composed of crystalline silicon, nickel silicide or metals. Similarly, the structure of the device may be a top nanowire gate or an Omega gated structure for tighter electrostatics. In accordance with the fabric-centric mindset, these assumptions need to be evaluated in terms of implications for manufacturing as well as for other design levels.

The electrical properties of individual xnwFETs may be characterized using accurate 3-D physics based simulation of the nanostructures using Synopsys Sentaurus Device [3]. Calibration of the tool against experimental data at similar dimensions is required to account for nanoscale effects such as increased surface roughness and interface trap states. These device-level simulations provide 3 sets of data: i) Current data for different values of drain-source ( $V_{DS}$ ) and gate-source ( $V_{GS}$ ) voltages, ii) Device capacitances at different values of  $V_{GS}$ , and iii) key device parameters/metrics that determine noise margins and performance of the devices such as the on-currents ( $I_{ON}$ ), threshold voltage ( $V_{TH}$ ) and the intrinsic delays of the devices. These device parameters may be adjusted by changing underlying physical layer assumptions as well as the substrate bias (e.g. a higher threshold voltage may be obtained by modifying the metal work function or using a more negative back gate bias).

The current data is fitted as a function of  $V_{GS}$  and  $V_{DS}$  using regression analysis and curve fitting. This step expresses the current as a mathematical function of  $V_{GS}$  and  $V_{DS}$ . The expression for the current, in conjunction with a piecewise linear



**Figure 4.1.** Methodology for Integrated Device-Fabric Exploration and Noise Evaluation

approximation for the device capacitances forms a behavioral model of the xnwFET, which may be incorporated into a standard circuit simulator such as HSPICE to carry out circuit level evaluations.

The circuit-level simulations take as inputs the behavioral models for individual devices, circuit netlists with worst-case noise scenarios as well as fabric-specific control and sequencing schemes. As will be shown, different sequencing schemes have different implications while considering noise margins and signal integrity; they control the flow of data and influence capacitive interactions and glitching in between successive cascaded stages. Different cascading and noise scenarios are evaluated and output waveforms are checked for signal integrity. Circuit-level delay and fabric performance implications are also quantified from these simulations. The methodology thus explores implications of physical layer and device assumptions on the fabric as a whole. While it has been explored extensively for the NASIC fabric, this integrated methodology is fairly generic and is applicable to other nano-fabrics as well.

## 4.2 Physical Layer and Device Explorations<sup>1</sup>

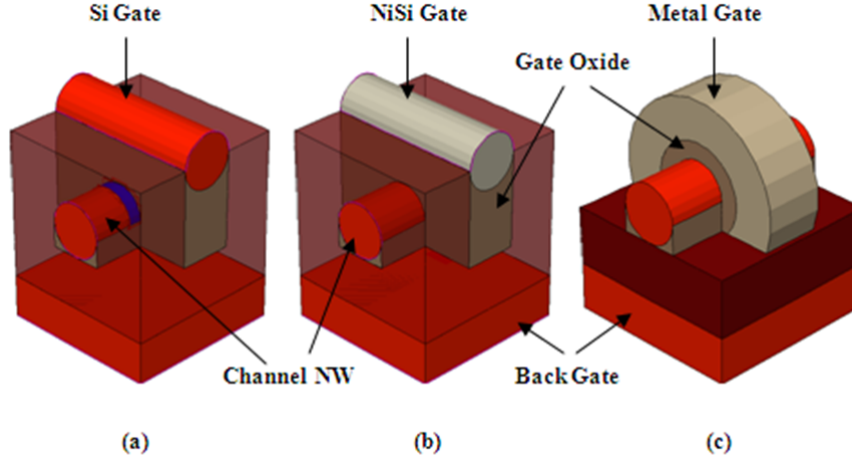
### 4.2.1 Devices Explored

We have considered three different xnwFET structures. Fig. 4.2 shows an image of each nanowire transistor structure used for this study. The first structure considered is the silicon gate xnwFET. This transistor consists of a bottom nanowire that acts as the channel and a top nanowire, orthogonal to the bottom nanowire, which acts as the gate electrode. These two nanowires are separated by a thin dielectric, which acts as the gate insulator.

The second structure considered is the fully silicided (FUSI) gate xnwFET. This structure is similar to the previous one, except that the gate nanowire has been fully

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<sup>1</sup>Work done in UCLA by Prof. Chui's group, included for completeness



**Figure 4.2.** Three xnwFET devices simulated (a) Si gate xnwFET (b) NiSi gate xnwFET (c) Omega-gated xnwFET.

silicided. This eliminates some undesired effects such as gate depletion, and reduces the resistance of the gate nanowire needed for fast evaluation of the previous logic stage. Also NiSi gives a smaller gate-substrate workfunction difference and therefore, there is no need of applying large substrate biases or using large source/drain underlaps to achieve the desired threshold voltage.

The third structure considered is the Omega-gated xnwFET structure with a metal gate. This structure was chosen because it has a better gate to channel coupling than the two previous structures. Therefore it should have a better ON current ( $I_{ON}$ ) as well as a higher on-to-off current ratio ( $I_{ON}/I_{OFF}$ ).

#### 4.2.2 Methodology

Due to the complex structure of xnwFETs, a 3D simulation is mandated. To study the behavior of xnwFETs, Synopsys Sentaurus Device simulator was used. Before any relevant simulation can be done, the simulation models have to be calibrated. To do this, experimental data from well characterized nanowire channel FETs with similar dimensions was employed [50, 47]. The calibrated models and parameters include the

**Table 4.1.** Parameters used for xnwFET device simulations

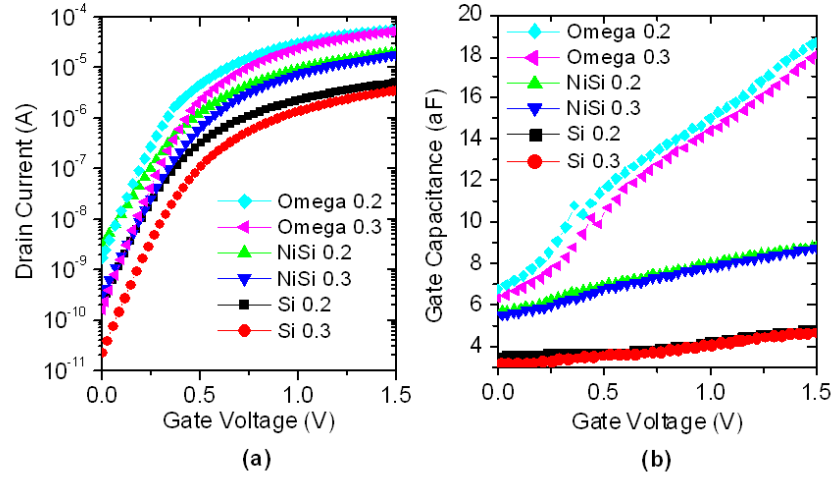
Device	Si 0.2	Si 0.3	NiSi 0.2	NiSi 0.3	Omega 0.2	Omega 0.3
Gate Material	Si	Si	NiSi	NiSi	Metal	Metal
Gate Workfunction (eV)	n+ Si	n+ Si	4.5	4.5	4.5	4.6
Gate NW diameter (nm)	10	10	10	10	-	-
Channel NW diameter (nm)	10	10	10	10	10	10
Channel doping ( $\text{cm}^{-3}$ )	$10^{18}$	$10^{18}$	$10^{18}$	$10^{18}$	$10^{18}$	$10^{18}$
Gate oxide material	HfO <sub>2</sub>	HfO <sub>2</sub>	HfO <sub>2</sub>	HfO <sub>2</sub>	HfO <sub>2</sub>	HfO <sub>2</sub>
Gate Oxide thickness (nm)	3	3	3	3	3	3
Bottom oxide material	SiO <sub>2</sub>	SiO <sub>2</sub>	SiO <sub>2</sub>	SiO <sub>2</sub>	SiO <sub>2</sub>	SiO <sub>2</sub>
Bottom oxide thickness (nm)	10	10	10	10	10	10
Source/Drain underlap (nm)	3	3	0	0	0	0
Back Gate Bias (V)	-4	-5	-3	-4	-3	-3

drift-diffusion transport models, to include effects such as carrier scattering due to surface roughness, and dielectric/channel interface trapped charges.

### 4.2.3 Simulation Results

For this study, six different devices have been simulated. For each of the structures mentioned before, we simulated a device with a threshold voltage of around 0.2 V and another device with a threshold voltage of around 0.3 V. The 0.2 V and 0.3 V values for  $V_{TH}$  were chosen for the noise resilience study purposes. A lower value for  $V_{TH}$  is expected to improve logic ‘1’ noise resilience, but lower the logic ‘0’ noise resilience, whereas a higher value for  $V_{TH}$  will do the opposite. To achieve the desired  $V_{TH}$  values, a source/drain underlap, as well as a back gate bias can be applied. Table 4.1 summarizes the basic device parameters used to achieve the desired  $V_{TH}$  values.

Drain current vs. gate voltage ( $I_{DS}$ - $V_{GS}$ ), drain current vs. drain voltage ( $I_{DS}$ - $V_{DS}$ ) and capacitance vs. gate voltage characteristics were simulated and important electrical parameters such as on current ( $I_{ON}$ ) and on-to-off current ratio ( $I_{ON}/I_{OFF}$ ) were extracted. Fig. 4.3(a) shows  $I_{DS}$ - $V_{GS}$  curves for the 6 devices simulated and



**Figure 4.3.** Device simulation outputs: (a)  $I_D - V_{GS}$  curves (b)  $C_G - V_{GS}$  curves

**Table 4.2.** xnwFET Device simulation results

	Si Gate xn-wFET		NiSi Gate xn-wFET		Omega-Gated xnwFET	
$V_{TH}$ (V)	0.21	0.32	0.22	0.31	0.21	0.31
$I_{ON}$ (A)	1.31	0.69	5.37	3.95	18.5	12.9
$I_{ON}/I_{OFF}$	6798	29831	1773	12046	10782	77875
Intrinsic delay (ps)	2.38	4.43	1.13	1.49	0.59	0.81



Fig. 4.3(b) shows capacitance vs.  $V_{GS}$  curves for the 6 devices simulated at  $V_{DS} = 0.8$  V ( $V_{DD}$ ). Similarly, data was obtained for other values of  $V_{DS}$  and  $V_{GS}$  to cover the operating regions of the devices. Table 4.2 summarizes key parameters such as  $I_{ON}$ ,  $I_{ON}/I_{OFF}$  and intrinsic delay for the different devices.

$I_{ON}$  is defined as the current level when the gate to source voltage ( $V_{GS}$ ) and the drain to source voltage ( $V_{DS}$ ) are both equal to 0.8 V ( $V_{DD}$ ). The off-state-current is defined as the current level when  $V_{GS}$  is equal to 0 V and  $V_{DS}$  is equal to 0.8 V. Various techniques is available for  $V_{TH}$  extraction. We have chosen the square-root  $I_{DS}$  extrapolation method. To calculate the intrinsic delay, we computed the  $CV/I$  ratio, where C is the total capacitance seen from the gate and  $I_{DS}$  is the current value at  $V_{GS} = V_{DS} = V_{DD}$ .

#### 4.2.4 Device Comparisons

The characteristics of the three nanowire transistor structures are compared as follows. For a given threshold voltage, the silicon gate xnwFET has the smallest  $I_{ON}$ , followed by the NiSi gate xnwFET and the Omega-gated xnwFET has the highest  $I_{ON}$  as expected. First the NiSi structure has a higher  $I_{ON}$  than the Si gate structure because the  $\Phi_{MS}$  value is lower in the NiSi case. Therefore a smaller source/drain underlap is needed to achieve the same  $V_{TH}$ , which in turn reduces the effective channel length, raising the drain current level. For the Omega-gated xnwFET, the higher current level is due to the increased ability of the gate to modulate the channel conductivity. In the Si gate or NiSi gate xnwFET structure, the inversion layer needed to turn on the device is formed mostly on the top part of the channel nanowire, near the gate nanowire, whereas in the Omega-gated xnwFET, the inversion layer can be formed almost all around the channel nanowire and therefore, this can be thought as increasing the effective channel width at the same gate voltage.

Another figure of merit for these three devices is the on-to-off current ratio. For a given threshold voltage, the Si gate xnwFET and the NiSi gate xnwFET devices have similar  $I_{ON}/I_{OFF}$  but the Omega-gated xnwFET has a higher  $I_{ON}/I_{OFF}$  value as expected. This is because the Omega-gated xnwFET has better gate to channel electrostatic control than any of the other two structures. In other words, the Omega-gated xnwFET is more effective at turning the device on and off than any of the other xnwFET structures. The Omega-gated xnwFET, therefore, should have better subthreshold slope than any of the other two devices leading to a higher  $I_{ON}/I_{OFF}$ .

Also we can compare the capacitances for these three devices. For a given  $V_{TH}$  specification, it can be seen that the capacitance values are usually higher for the Omega-gated xnwFET, followed by the NiSi gate device, and the Si gate xnwFET has the lowest values. For example, the NiSi gate device has a higher gate-to-source and gate-to-drain capacitance value than the Si gate device because the former has a smaller junction underlap, which will thus increase the gate coupling to the source and drain. In addition, the NiSi gate device does not have the gate semiconductor depletion issue near the oxide interface further increasing its capacitance values. For the Omega-gated xnwFET, since the gate is wrapped around the channel, it can be easily seen that the gate is located closer to the source and the drain regions than in the other two xnwFET devices. It will in turn increase the gate-to-source and gate-to-drain coupling and thus the respective capacitances.

### 4.3 Circuit level simulation and noise evaluation in-fabric

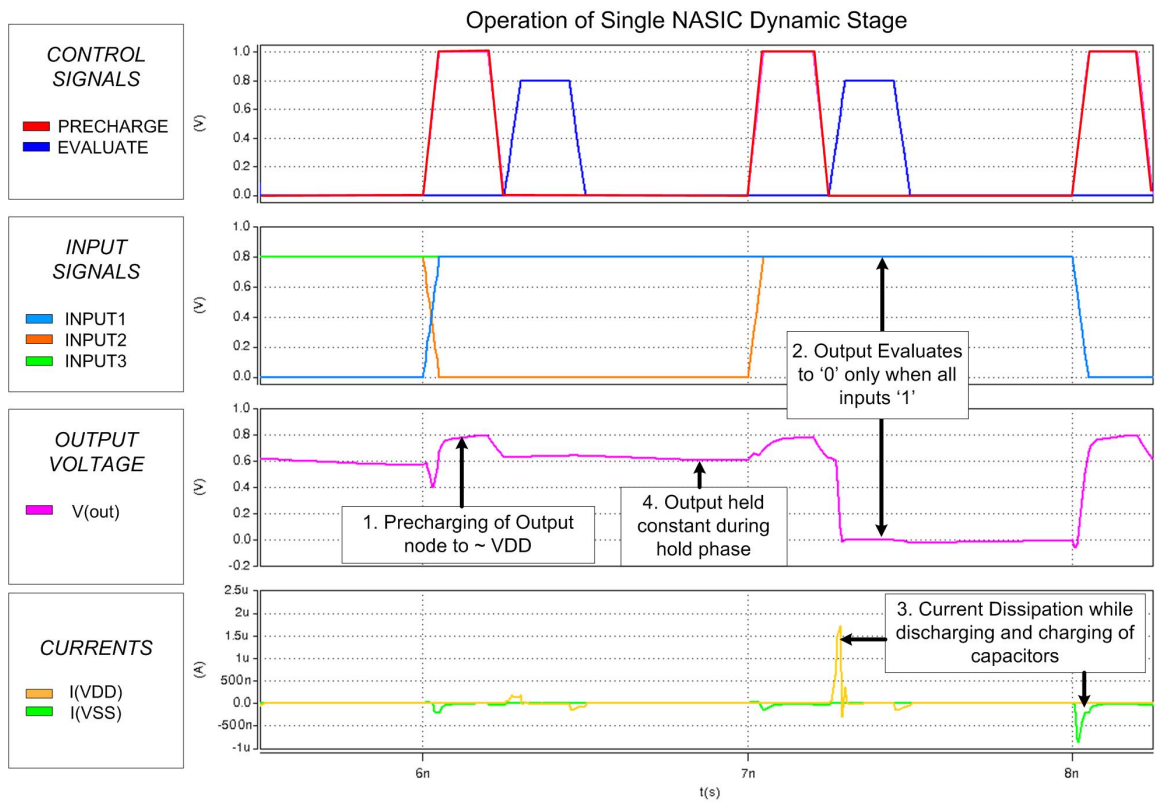
Behavioral models for the devices examined in the previous section were created using the methodology described in Fig. 4.1. This section describes a variety of circuit level simulations carried out to identify and fully evaluate the impact of internal noise and validate cascaded nanowire fabrics utilizing xnwFETs.

DC Sweep analysis was done to verify that behavioral models accurately abstract device data. For all devices, it was found that behavioral models accurately track Sentaurus<sup>TM</sup> current data within 5% error for the voltage ranges considered.

A single NASIC NAND stage was simulated using HSPICE to verify expected functionality. Representative results are shown in Fig. 4.4 for the Omega 0.2 device. Other devices exhibit similar behavior. From the signal waveforms we make the following key observations: 1) the output precharges to logic ‘1’ when the *pre* signal is asserted. Typically a value greater than  $V_{DD}$  is used for *pre* to achieve rail-to-rail voltage swing at the output node . 2) The output goes to ‘0’ only when all inputs are ‘1’, achieving the required NAND logic. 3) Current dissipation occurs only when the capacitances are charged or discharged, and there is no static current in NASIC designs as one of *pre* or *eva* is always off. 4) During the hold phase, the output does not change. However during this time, the output node has high output impedance which makes it susceptible to switching events in its neighborhood while considering cascaded NASIC designs. In the next set of circuit simulation experiments these internal noise sources and switching events will be investigated in detail for the different xnwFETs and two baseline control schemes.

#### 4.3.1 Sequencing schemes for the NASIC fabric

Fig. 3.2 showed one possible sequencing scheme for cascaded NASIC designs. In this baseline scheme, one stage is precharged and evaluated before the next stage with signals repeating every two stages, i.e. stages 1, 3 and 5 may use the same control signals (say *pre1* and *eva1*) whereas stages 2, 4 would use *pre2* and *eva2*. While any one stage is being precharged or evaluated, its neighbors are in the hold phase, with outputs implicitly latched on the nanowire for correct cascading and pipelining of datapaths.



**Figure 4.4.** Circuit simulations of single NASIC dynamic stage

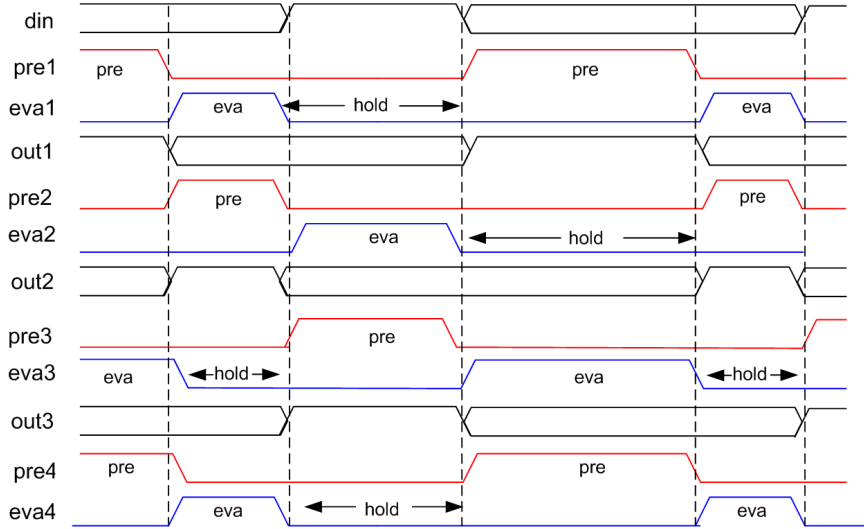
In general, since control signals are not driven from logic but from reliable external circuitry, they may be optimized to achieve specific targets. One example of this is driving precharge signals to voltages greater than  $V_{DD}$ , thereby achieving a full  $V_{DD}$  voltage swing at the output node of a nanowire for maximum logic ‘1’ noise margin. In keeping with the fabric-centric mindset, modifying the control schemes does not impose any new challenges at the physical layer or in terms of manufacturing requirements, since there is no additional customization requirement at the nanoscale. Furthermore, noise implications and signal integrity considerations may be very different depending on the sequencing scheme used, since the scheme decides how logic nodes are switching relative to one another.

Another sequencing scheme used for the NASIC fabric is shown in Fig. 4.5. This is a 3-phase sequencing scheme where signals are repeating every 3 stages. In a large scale design, this would imply that stages 1,4,7 etc would use identical control signals. In this scheme, evaluate of one stage is overlapped with the precharge phase of the next. This scheme carries performance benefits in a pipelined design as compared to the scheme described in Fig. 3.2, since output evaluation events occur at a higher frequency.

### 4.3.2 Circuit Simulation and Analysis

The six devices described in Section 4.2 were evaluated for a worst-case circuit to evaluate noise implications and functionality. Both baseline timing schemes described in the previous sub-section were considered in this analysis.

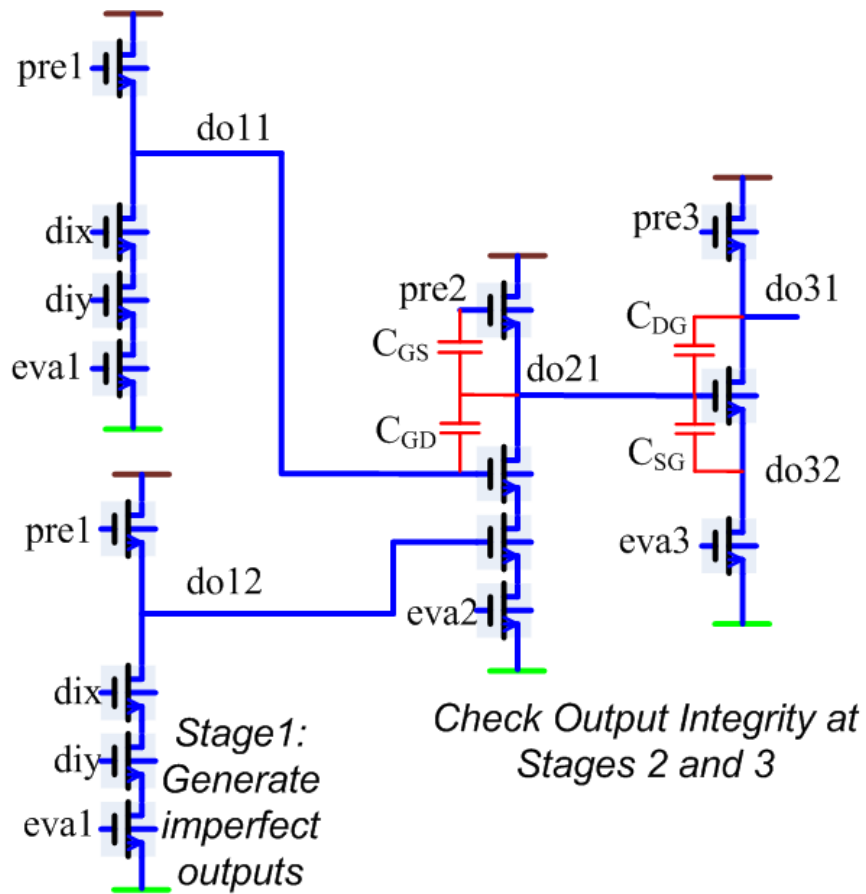
The three-stage cascaded test circuit used in these noise evaluations is shown in Fig. 4.6. Stage 1 generates imperfect outputs that drive input xnwFETs of stage 2. Output integrity is checked at output nodes *do21* and *do31*. Due to high output impedance during the hold phase, the output nodes at various stages may be susceptible to noise effects across device parasitic capacitances.



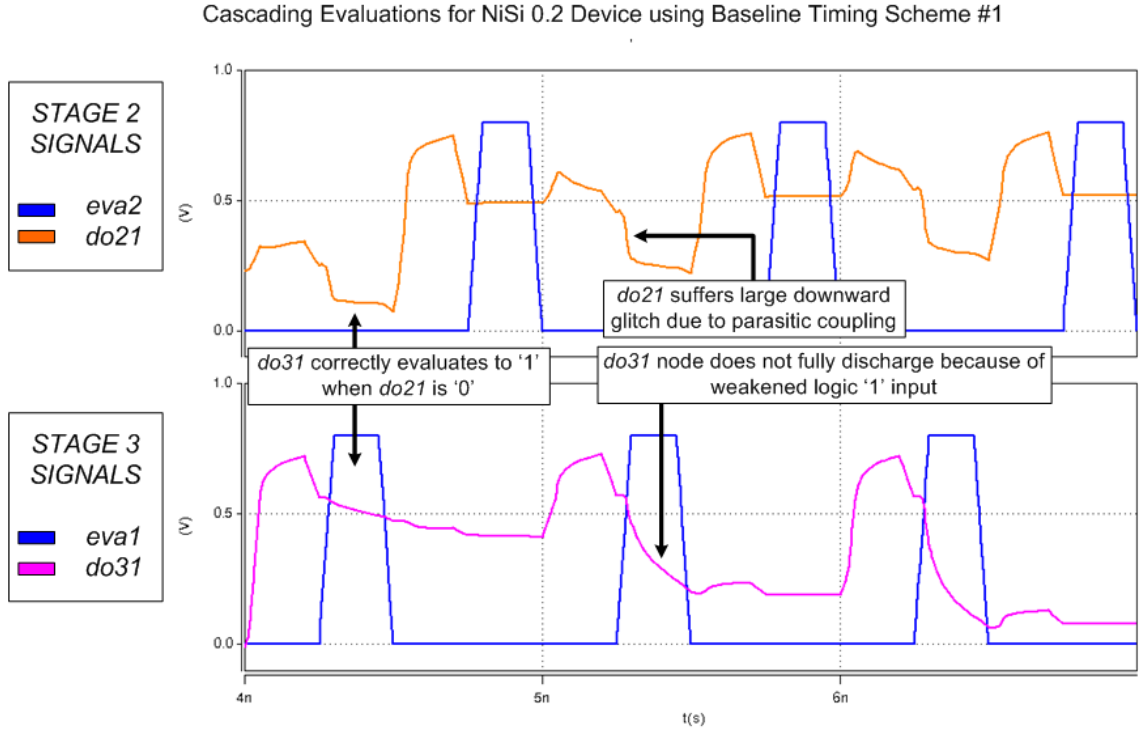
**Figure 4.5.** Three-phase timing scheme for the NASIC fabric. Note that signals repeat every three stages, with *pre4* and *eva4* identical to *pre1* and *eva1* respectively.

For example, key sources of noise for the *do21* node include the Miller capacitances between this node and *do11* and *do31* nodes. If *do11* evaluates to ‘0’ it might cause a downward glitch (degradation of logic ‘1’) at *do21* due to the  $C_{GD}$  capacitance between *do11* and *do21*. Similarly, if *eva3* is asserted, a downward glitch may occur at *do21* due to the  $C_{SG}$  parasitic capacitance. Precharging of *do31* could cause an upward glitch at the *do21* node. Other similar parasitic effects exist between outputs and intermediate nodes in the design, leading to glitching and internal noise events.

Fig. 4.7 and Fig. 4.8 show the output waveforms for the NiSi 0.2 and Omega 0.2 devices for the basic sequencing scheme describe in Fig. 3.2. Logic ‘1’ glitching is a very serious problem in this timing scheme. Due to parasitic coupling between the *pre2* signal and *do21* through the  $C_{GS}$  capacitor (see Fig. 4.6), there is a drop in the *do21* output when *pre2* is deasserted. Furthermore, while *do21* is holding logic ‘1’, it may be severely affected by two sources of noise: the  $C_{GD}$  capacitance between *do11* and *do21* as well as the  $C_{SG}$  capacitance of the input transistor of stage 3. If *eva1* is asserted and *do11* simultaneously discharges, a severe downward glitch may be experienced at the *do21* node due to these capacitances. This implies that when



**Figure 4.6.** Test circuit used for cascading evaluations - output integrity of stages 2 and 3 are affected by switching events in their neighborhood. The circuit represents a worst-case scenario for noise since stage 3 has a single input, corresponding to the least effective resistance and capacitance between its output node and VSS.

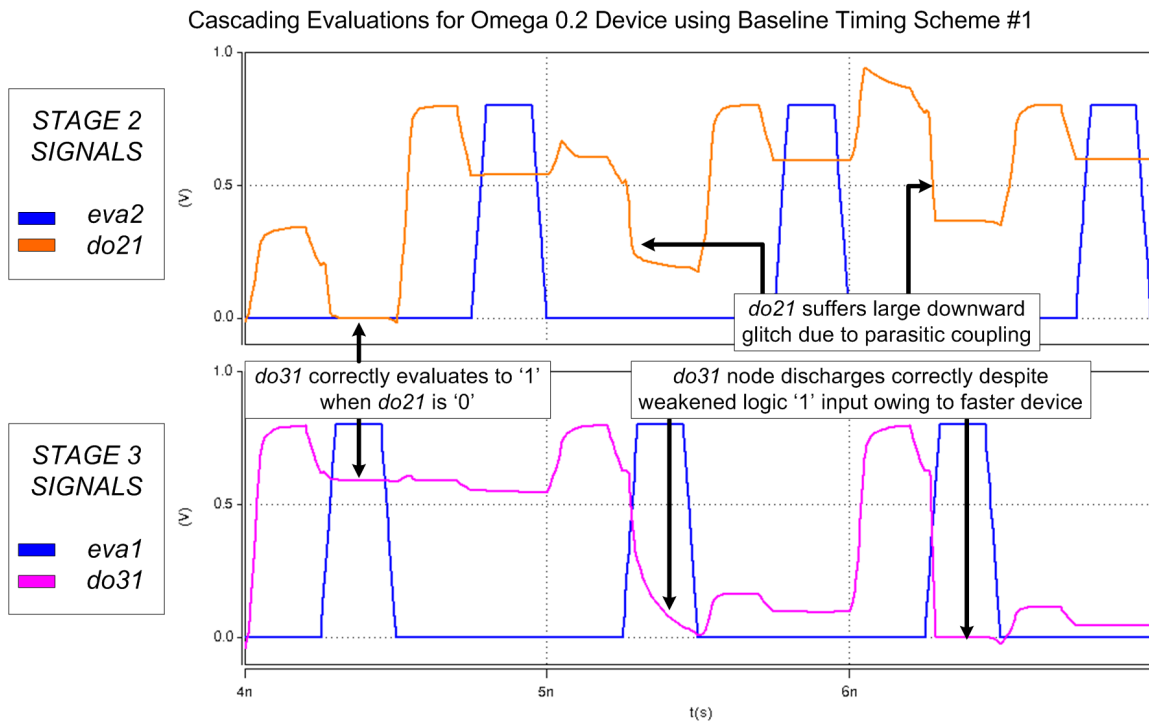


**Figure 4.7.** Cascading evaluations for NiSi 0.2 Device - Due to poor driving voltage at the input transistor and slow device, output node  $do31$  does not properly discharge leading to loss of signal integrity.

stage 3 is evaluated, the driving voltage at the  $do21$  node could be significantly below  $V_{DD}$ .

Two scenarios may then be considered: the voltage of  $do21$  may be below or above  $V_{TH}$ . In the former case the signal integrity test fails at  $do21$ , since it is effectively at a logic ‘0’ voltage level. In the latter case, the circuit functionality depends on the characteristics of the device. A fast device may be able to effectively switch even with a low driving voltage, leading to a correct logic ‘0’ evaluation of node  $do31$ , whereas a slower device may not be able to effectively discharge  $do31$ , leading to an erroneous logic ‘1’ value on the node. As seen in Fig. 4.7, circuits with the slower NiSi gated devices fail in this scenario despite the input voltage being within the logic ‘1’ noise margin (i.e.  $> V_{TH}$ ). However, the circuit with Omega 0.2 devices, which is the fastest of the 6 devices considered in terms of intrinsic delay, is able to effectively



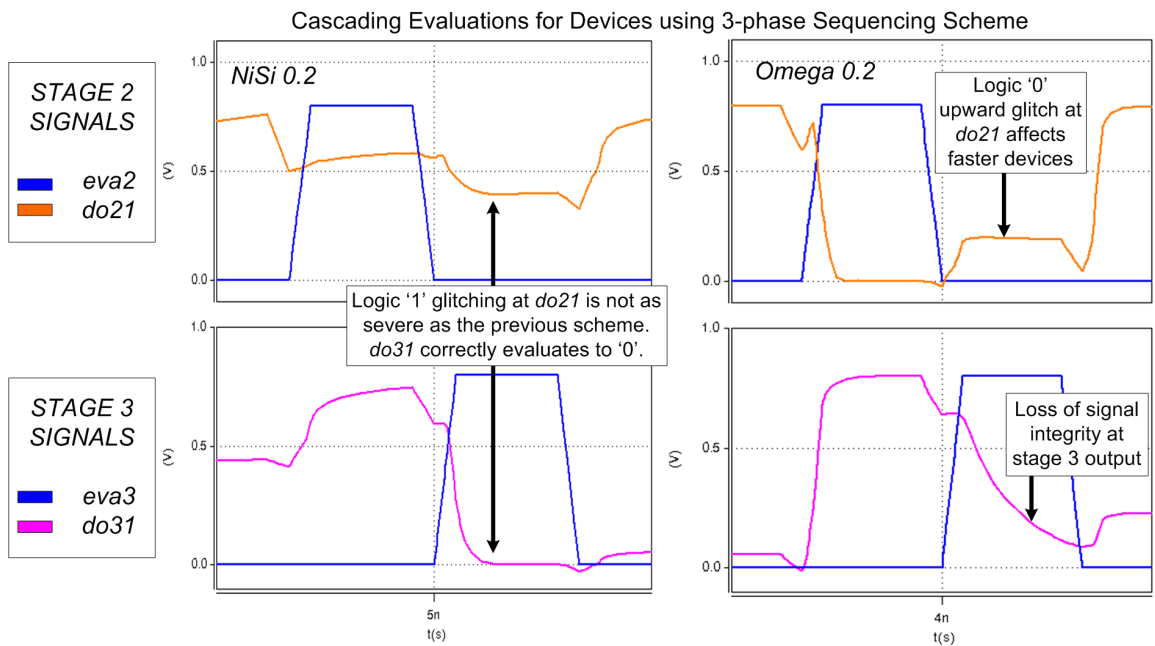


**Figure 4.8.** Cascading evaluations for Omega 0.2 Device - Despite poor driving voltage, signal integrity is preserved owing to faster device.

discharge the output node even with a significantly degraded input voltage. In other words, faster devices are more resilient to logic ‘1’ glitching effects. Of the 6 devices considered for these simulations, only the fastest Omega 0.2 device achieves expected behavior, the 5 slower devices do not work.

Fig. 4.9 shows output waveforms for the NiSi 0.2 (left) and Omega 0.2 (right) devices for the 3-phase control scheme described in Fig. 4.5. In this control scheme, logic ‘1’ glitching effects are not as severe as in the previous scheme. This is because both neighboring stages are not simultaneously discharging during the stage 2 hold phase. While there can be some downward glitching due to  $C_{SG}$  between *do21* and *do32*, in this scheme the parasitic capacitance  $C_{GD}$  to *do11* does not hurt logic ‘1’ integrity, since *do11* is actually precharging during the stage 2 hold phase. Therefore the NiSi 0.2 device (Fig. 4.9 - left) is able to effectively discharge the *do31* output node, leading to correct functionality. As expected, the Omega 0.2 device works correctly in the presence of logic ‘1’ glitches.

However, in this sequencing scheme, logic ‘0’ glitching is an important consideration. Due to precharging of node *do11*, the output node *do21* might have an upward glitch from logic ‘0’ during its hold phase. For the Omega 0.2 device this upward glitch might cause a logic ‘0’ value to reach above the threshold voltage of the device. Given that this device has the lowest intrinsic delay of all devices considered, the glitch may be sufficient to cause the stage 3 input xnwFET to operate in the linear region, leading to loss of signal integrity (Fig. 4.9 – right). In other words, faster devices are less resilient to logic ‘0’ glitching effects. Of the 6 devices considered, the slowest NiSi 0.3 and Si 0.3 devices fail due to logic ‘1’ glitching effects, whereas the Omega 0.2 fails due to the logic ‘0’ glitching. NiSi 0.2, Si 0.2 and Omega 0.3, which are middle-of-the-road devices in terms of intrinsic delay, pass all signal integrity tests and are correctly evaluated.



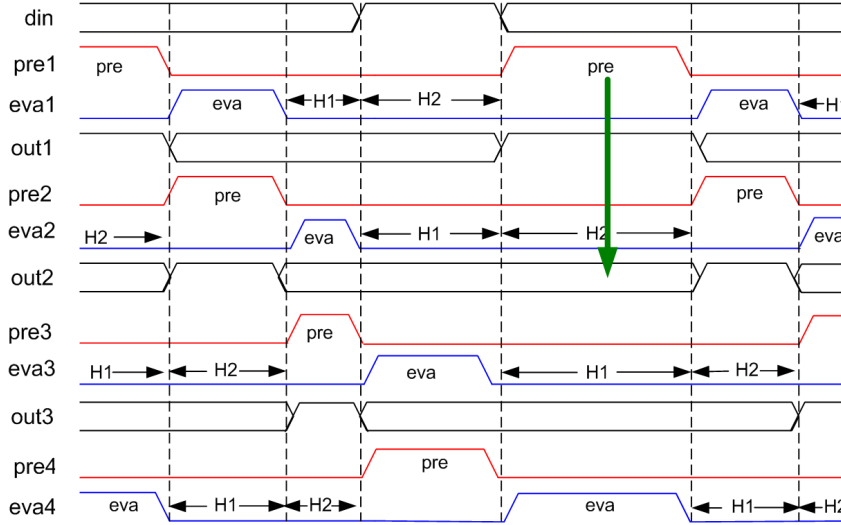
**Figure 4.9.** Cascading evaluations for NiSi 0.2 and Omega 0.2 devices using 3-phase sequencing scheme - Logic '1' glitching effects are reduced in this scheme, and NiSi 0.2 device shows expected behavior. However, logic '0' glitching is critical for faster devices. Upward glitch on *do21* during *eva3* causes loss of signal integrity at *do31* node.

As seen from these results, both sequencing schemes and device properties have strong implications on noise. Glitching occurs due to switching events in the neighborhood, which are influenced by the external control sequence. Therefore, while device parameters such as  $V_{TH}$  and intrinsic delay need to be adjusted for noise resilience, additional noise optimizations could be done at the fabric level by altering the sequencing schemes and eliminating or isolating glitching events. For example, the 3-phase scheme is resilient to logic ‘1’ glitching for 4 out of 6 devices owing to the higher driving voltage at the input nodes, whereas the other baseline scheme works only for 1 of 6 devices. We could then potentially design a new noise resilient timing scheme that preserves the logic ‘1’ advantages of the 3-phase timing scheme while providing tolerance against logic ‘0’ glitching such that the fastest devices may be leveraged in NASIC designs.

#### 4.4 Noise Resilient Sequencing Scheme for the NASIC Fabric

In this section, we present and evaluate a new noise-resilient dynamic control scheme that provides resilience against both logic ‘1’ and logic ‘0’ glitches across a variety of devices. The scheme is described and all devices are evaluated against it for the test circuit (Fig. 4.6).

Fig. 4.10 shows the new noise resilient sequencing scheme. Similar to the 3-phase scheme, *eva* phase of any stage overlaps with *pre* of the next stage. Also, since both neighboring stages do not simultaneously discharge, logic ‘1’ glitching is less severe than in the first scheme. However, the key difference for the noise resilient scheme is the introduction of a second hold stage (labeled *H2* in Fig. 4.10) to separate evaluation events from noise events. For example, in the 3-phase scheme (Fig. 4.5), *do11* precharging can cause an upward glitch at *do21*, which affects logic ‘0’ integrity. However, with the new scheme *do21* has already been ‘used’ as input for the next stage, i.e. *eva3* has completed before the noise event (i.e. *pre1*) occurs (shown by



**Figure 4.10.** Noise resilient 4-phase sequencing scheme for the NASIC fabric - Additional hold phase (H2) inserted to separate evaluation from noise event. Green arrow shows *do21* glitches only after *eva3* has completed. Signals repeat every four stages.

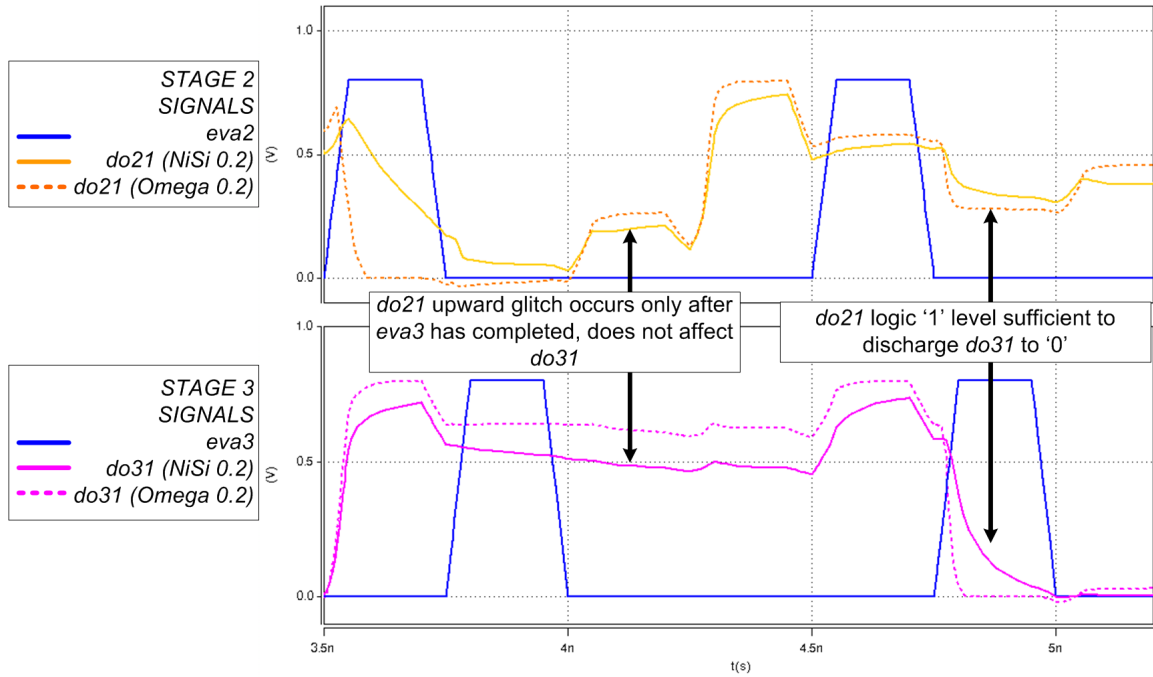
the green arrow in Fig. 4.10). In this new control scheme, signals repeat every four stages.

Fig. 4.11 shows the output waveforms for the Omega 0.2 device with the new noise resilient scheme. As expected, the logic ‘0’ at *do21* is already consumed before the glitching event occurs and does not affect *do31*. During *eva3*, stage 1 is in the new *H2* phase, which essentially isolates the noise event from the propagation event preserving signal integrity. Thus, using the new noise resilient timing schemes, devices with lower intrinsic delays may be made functional in the NASIC fabric.

## 4.5 Discussion

This section discusses implications of the 4-phase noise resilient timing scheme on fabric performance, the effect of external noise sources (e.g. power supply droops) and manufacturing implications.

Cascading Evaluations for Devices using 4-phase Noise Resilient Scheme



**Figure 4.11.** Cascading evaluations for NiSi (solid) and Omega (Dotted) devices using the noise resilient 4-phase control scheme - Results show signal integrity and sufficient noise margins for logic '1' glitches for both devices. Logic '0' glitches have been isolated from evaluation events and are therefore not propagated. The new sequencing scheme achieves noise resilience and correct functionality for 4 out of 6 devices.

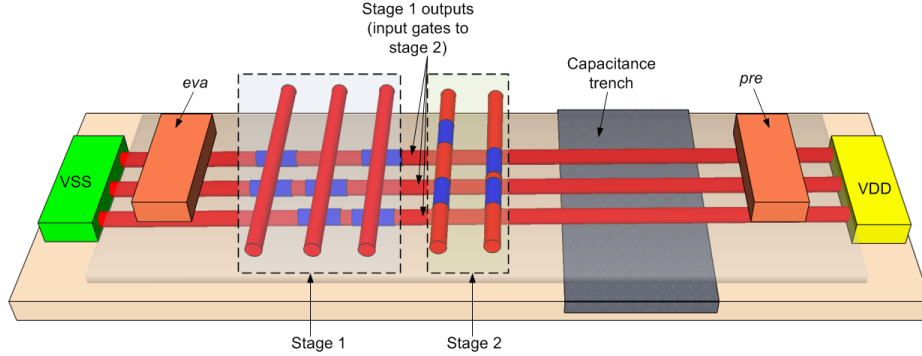
### 4.5.1 Performance Optimization and Evaluation

In general, it may be expected that the noise resilient 4-phase sequencing scheme would run at slower frequencies than the 3-phase and basic schemes since additional hold phases are inserted for noise resilience. However, since the 4-phase scheme provides better logic ‘1’ values and isolates logic ‘0’ glitches, faster devices could be leveraged with this scheme leading to significant performance improvements at the system level.

However, even with faster devices, NASIC dynamic circuits need to be optimized for performance. Specifically, due to noise cascading effects and high output impedance, charge at driving nodes and the associated gate-drive voltages are typically expected to be lower than  $V_{DD}$ . Since  $I_{ON}$  is strongly dependent on  $V_{GS}$ , this implies that even devices with low intrinsic delays (e.g. Omega 0.2) may be operating at sub-optimal points, leading to large evaluation delays and poor circuit performance. Therefore, circuits need to be optimized ‘in-fabric’ to improve  $V_{GS}$  and performance.

CMOS dynamic circuits typically use keeper devices or domino logic [45] for achieving low output impedance. A keeper device is part of a feedback network, which is turned ON when the output node is ‘1’, and OFF when it is ‘0’. Keeper configurations are typically achieved with an inverter and a PMOSFET. However, this may be hard to achieve on a regular NW based fabric without a large density impact, since it requires nanoscale customization and feedback, in addition to  $p$ -type FETs and static inverters for every NASIC dynamic gate. Similarly, domino logic would need insertion of static CMOS stages between tiles. These approaches cannot be directly integrated into the NASIC fabric.

One promising technique for increasing charge at the driving nodes is capacitance engineering. The key idea is to increase the overall capacitance (and consequently the charge stored) at input nodes, thereby reducing the magnitude of noise glitching, thereby leading to higher gate voltages. While increased load capacitance at a



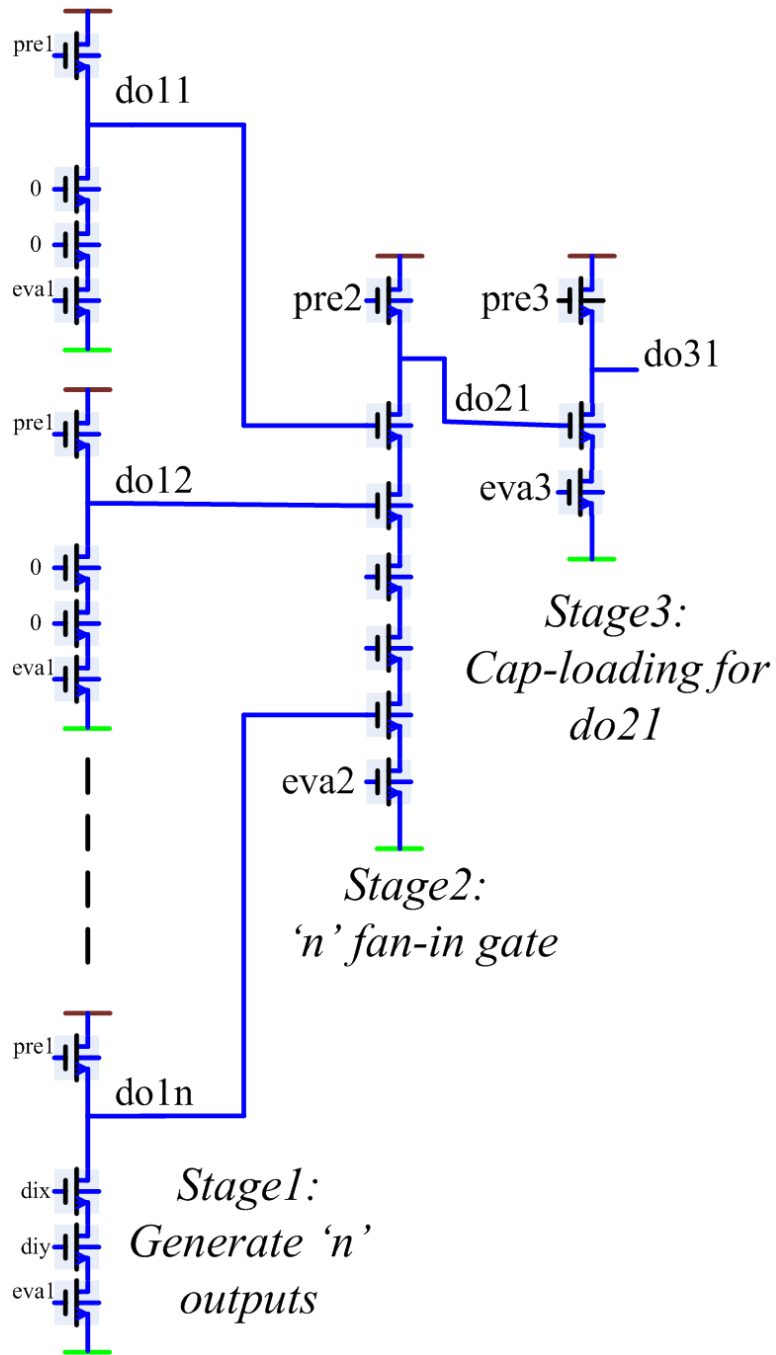
**Figure 4.12.** Capacitance engineering of input gates: adding gate capacitance at outputs of Stage 1 increases gate-drive voltages of Stage 2 xnwFETs.

node will have a linear impact on performance; the expectation is that a net benefit will be achieved due to the better-than-linear relationship between  $I_{ON}$  and  $V_{GS}$ . Importantly, this technique does not impose new manufacturing challenges. A capacitance trench may be created at an input stage, increasing the net capacitance of all input nodes in that stage (Fig. 4.12). This would be done at the granularity of a NASIC stage (typically 10s – 100s of nm) using conventional photolithography steps and would be easier to achieve than in a conventional DRAM process, which requires isolated capacitors for every memory bit.

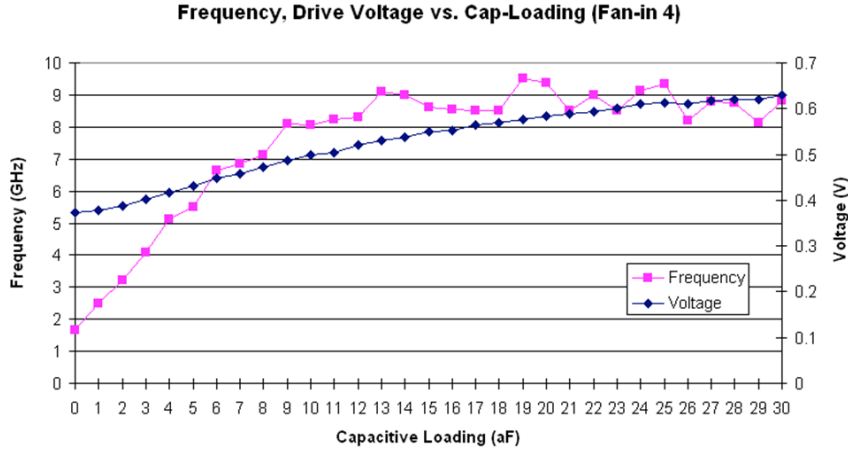
The test circuit used for performance evaluation with capacitance engineering is shown in Fig. 4.13. Stage 1 generates imperfect outputs and is subject to noise effects previously discussed. The time taken to fully discharge the output node of stage 2 is measured as a function of fan-in. Stage 3 loads stage 2. Capacitors shown in green are inserted at output nodes and improve drive voltages. It must be noted that these capacitances improve logic ‘1’ noise margins, since more charge is stored on the nodes and magnitude of downward glitching is reduced.

Experiments were done to characterize the evaluation delay of NASIC dynamic circuits as a function of fan-in. Maximum operating frequency is defined as  $1/N * delay$ , where  $N$  is the number of distinct evaluate phases in the control scheme (explicitly,  $N$





**Figure 4.13.** Test circuit for performance evaluation as a function of fan-in - The time taken to discharge *do21* through a xnwFET stack consisting of  $N$  inputs is measured. Stage 3 provides constant capacitive loading.

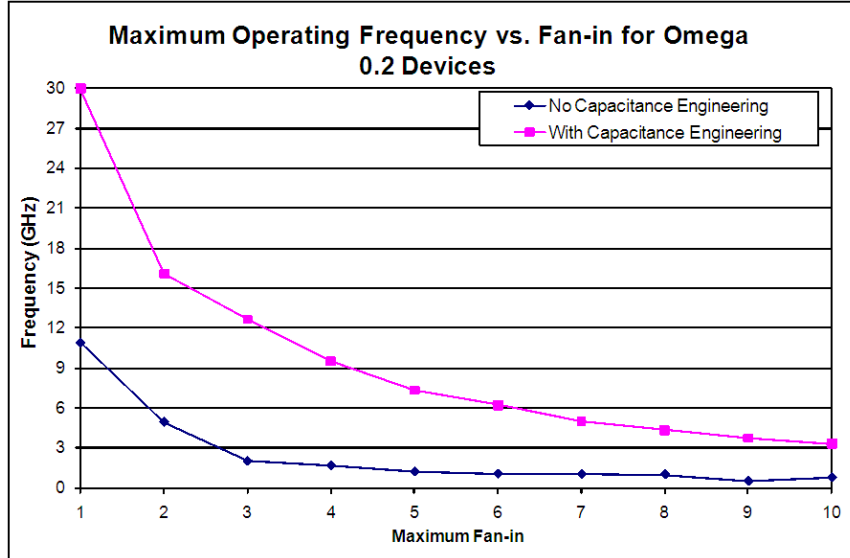


**Figure 4.14.** Graph showing frequency and drive voltage improvements against capacitive loading for fan-in 4 NASIC dynamic circuits - 5X improvement in operating frequency compared to no cap-loading is demonstrated.

is 4 for 4-phase). The reasoning is that the minimum duration of any single evaluate phase has to be at least equal to the delay for completely discharging the output node through the pull-down network.

Fig. 4.14 shows drive voltage and maximum operating frequency vs. capacitance for fan-in 4 NASIC dynamic gates. Without any capacitive loading, a maximum frequency of 1.68 GHz is obtained. However, increasing the capacitance leads to a 5X improvement performance. A key observation is that for smaller drive voltages, significant improvements in performance are seen. However, at higher drive voltages, the  $I_{ON}$  vs.  $V_{GS}$  relationship becomes more linear, and the effect of better driving voltages due to capacitance at the input node is negated by the linear impact of the output load capacitance.

For capacitance loading between 9 aF and 30 aF, only a 5% standard deviation is observed, implying that performance is not very sensitive to variations in the capacitance values. Also, new techniques to mitigate the impact of variability in nanoscale fabrics [39] may be leveraged to improve the performance further. Similar trends are seen at other fan-ins.



**Figure 4.15.** Maximum operating frequency with and without capacitance loading vs. fan-in: a consistent 4.5X to 6X improvement in performance is seen for all fan-ins.

Fig. 4.15 shows the maximum operating frequency vs. maximum fan-in for the Omega 0.2 device with and without capacitance engineering. A consistent 4.5-6X performance improvement is seen for all fan-ins with capacitance engineering (e.g. for fan-in 10, maximum operating frequency increases from 798 MHz to 3.34 GHz). These results attest to the importance of achieving high drive voltages at input nodes.

#### 4.5.2 Impact of Power Supply Droop on NASIC Fabric Functionality

The previous sections dealt exclusively with internal noise sources such as arising from parasitic capacitances. Fundamentally, fabric design and optimizations have to be validated for functionality by mitigating internal noise. However, external effects such as power supply variation, clock skew, thermal vibrations and soft errors can also be detrimental to nanoscale fabric functionality. The latter two effects may partially be dealt with through built-in fault tolerance techniques incorporated in the NASIC fabric [35, 57]. With regard to clock skew, NASIC designs employ local interconnections between neighboring dynamic stages. The control signals that 'clock' NASIC

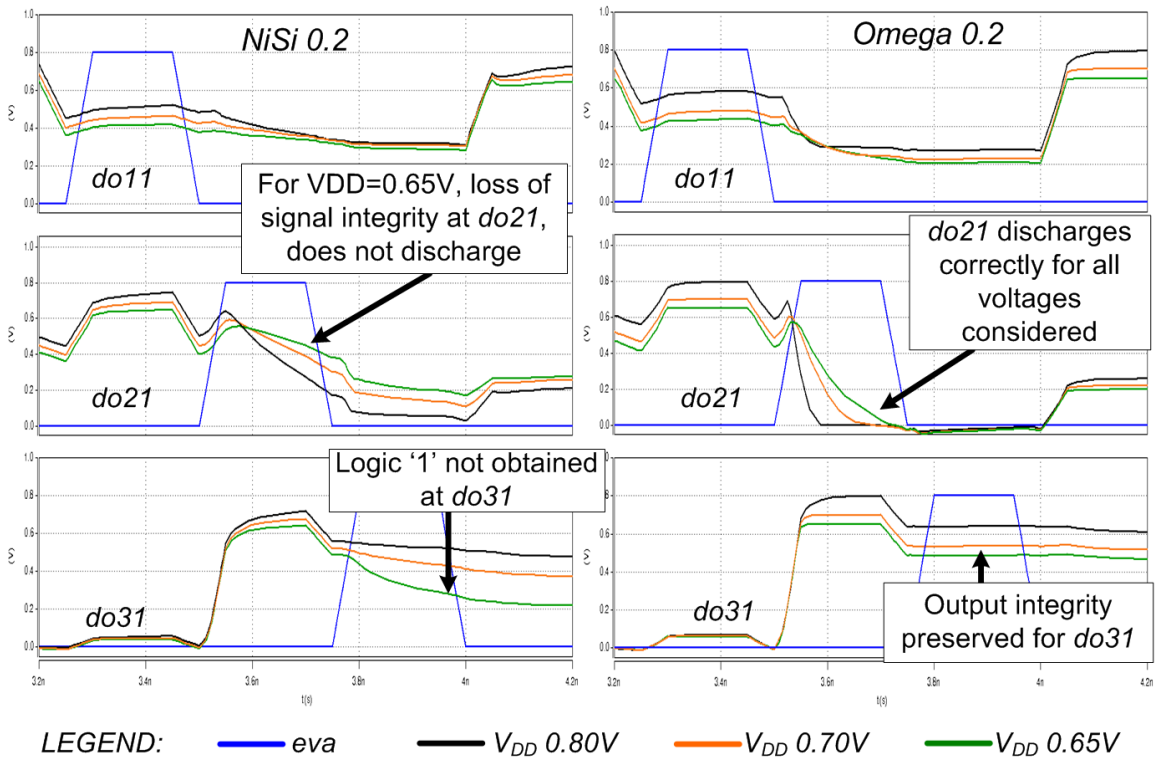
stages are expected to be propagated on common rails from a Phase-Locked-Loop with local phase shifters generating the four-phase clock. Given the local interactions and the prescribed clocking structure, appreciable skew is not expected on control signals. However, systematic effects such as fluctuations in  $V_{DD}$  could still disrupt functionality, especially when considered in conjunction with internal noise sources.

In this section, we examine how  $V_{DD}$  changes may affect fabric functionality. The test circuit in Fig. 4.6 was used and the four devices examined were: Si 0.2, NiSi 0.2, Omega 0.3 and Omega 0.2. These devices were found to work correctly under nominal  $V_{DD}$  with the 4-phase noise resilient control scheme.  $V_{DD}$  was varied systematically for all the stages in the test design, because while across chip variation in  $V_{DD}$  could be large, little local variation is expected for smaller circuits using the same supply rails. Up to 20% variation on either side of nominal (0.8 V) was considered.

Supply voltage spiking can be detrimental to logic ‘0’ outputs. However, these upward glitches can be isolated using the 4-phase noise resilient scheme and our simulations showed circuits with all four devices working correctly for up to a 20% spike in  $V_{DD}$ . Droops in supply voltage on the other hand affect logic ‘1’s. The following results highlight the impact of power supply drooping.

The results are shown in Fig. 4.16 for the NiSi 0.2 (left) and Omega 0.2 (right) devices. The trends for Si 0.2 and Omega 0.3 are very similar to NiSi 0.2. Omega 0.2 is extremely resilient to  $V_{DD}$  noise (Fig. 4.16 - right) due to its smaller intrinsic delay. Even when  $V_{DD}$  drops to 0.65 V ( $\sim 20\%$  droop), the logic ‘1’ values are evaluated correctly and a strong ‘0’ is obtained at the *do21* node. For NiSi 0.2, we see for  $V_{DD} = 0.65$  V, the stage 2 input devices are not fully turned on and *do21* is not fully discharged. An ambiguous signal  $\approx V_{TH}$  is obtained and loss of signal integrity occurs at *do31*. While the voltage at *do21* for  $V_{DD} = 0.65$  V is only slightly higher than for  $V_{DD} = 0.7$  V, the stage 3 xnwFET is much more strongly turned on, leading to incorrect discharge at the *do31* node.

### Impact of Supply Droops on Fabric Functionality



**Figure 4.16.** Impact of VDD drooping in conjunction with internal noise on cascaded NASIC fabrics - Slower NiSi devices (left) do not discharge effectively and signal integrity is lost for a 20% droop in VDD. Circuits using faster Omega 0.2 devices (right) are resilient to VDD drooping.

These results highlight that devices with smaller intrinsic delays are resilient to logic ‘1’ glitching caused by both internal and external noise sources. In conjunction with fabric level noise resilient sequencing schemes and capacitance engineering, faster devices may be leveraged for noise tolerant, high performance computational fabrics and systems.

### 4.5.3 Manufacturing Considerations

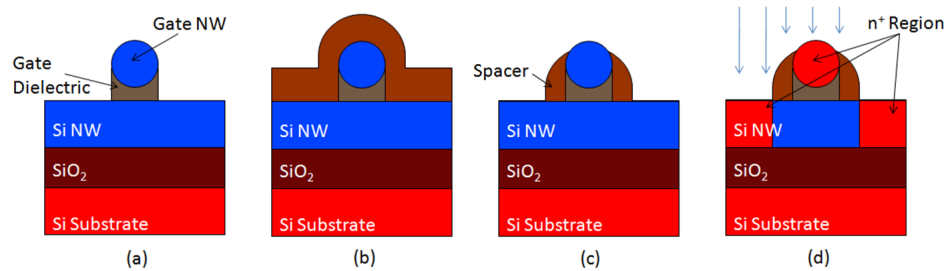
Reliable and scalable assembly of nanostructures and manufacturing pathways towards integrated systems continue to pose significant challenges. Therefore two objectives must be concurrently achieved: i) Device design and optimizations at device/circuit levels must target circuit functionality and fabric noise mitigation, and ii) In keeping with the fabric-centric mindset physical layer assumptions targeting device structures must not pose insurmountable challenges to the manufacturing sequence.

Silicidation of VLS grown nanowires with nickel for improved conductivity has been shown in [60]. A similar silicidation process may be used to achieve NiSi gate material as well as interconnect regions between xnwFETs. Since a final nickel silicidation step can be carried out after all ion implantation steps, thermal stability issues for NiSi material do not arise.

Omega-gated structures could be achieved by nanolithography or other pattern and etch techniques. For example, Superlattice Nanowire Pattern Transfer [34, 55] has shown metal nanowires at sub-15nm pitches. Snider *et al.* [48] have shown nanoimprint lithography based copper nanowires.

Two device engineering techniques discussed include the back-gate bias and the underlap. The substrate bias is applied to all devices in the fabric and therefore does not impose new manufacturing constraints. The underlap is envisioned to be created using a self-aligned process without any masking and is described below.

*Self-aligned Underlap Formation:* Source and drain junction underlap regions self-aligned to the gate nanowire are formed using spacer technology (Fig. 4.17). This process is similar to what is used to form highly doped drain and source (HDD) in CMOS devices and does not need any extra lithographic masking or overlay. During the anisotropic etch step (Fig. 4.17c), deposited material on nanowire sidewalls is not completely etched owing to higher thickness (Fig. 4.17b).



**Figure 4.17.** Front view of the xnwFET during the formation of the source and drain underlap. (a) Initial structure right after channel nanowire, gate dielectric and gate nanowire have been placed into position. (b) A thin layer the spacer material (oxide or nitride) is conformally deposited. (c) The spacer material is anisotropically etched. (d) Ion implantation is performed to dope the source, drain and gate regions.

We believe that these physical layer choices carefully addressing manufacturing considerations, in conjunction with manufacturing-friendly device and fabric optimizations for noise and functionality may pave the way for future nanowire-based integrated nano-fabrics.

## 4.6 Chapter Summary

A methodology for integrated device-circuit explorations of nanodevice based systems was presented. This methodology provides a fast and accurate way to create behavioral models for circuit simulations from device data using regression analysis. Furthermore, this approach is very generic, and can be applied to any nanodevice based computing system.

Cascaded crossbar dynamic circuits were validated using this integrated approach that combines circuit simulations, regression analysis, and accurate 3-D physics based device models. Three different xnwFETs were investigated; a xnwFET with 10 nm gate, 10 nm channel, underlap of 7 nm and a substrate bias of -1 V was found to meet circuit requirements including sufficiently high on/off ratios and a  $V_{TH}$  of +0.23 V. Circuit simulations show that this device combined with NASIC circuit and logic styles can achieve correct cascading with adequate noise margins. Future work will address implications for optimized devices such as based on cylindrical nanowires, fully-silicided gates, omega-gated structures etc. as well as new noise mitigation and performance enhancement techniques.



## CHAPTER 5

# PARAMETER VARIATION IN NANOSCALE COMPUTING FABRICS: BOTTOM-UP INTEGRATED EXPLORATION

Reliable and deterministic manufacturing of integrated nanosystems continues to be challenging. Self-assembly based approaches as well as photolithography at features sizes of few tens of nanometers and below are expected to introduce significant levels of permanent defects as well as large variations in physical parameters. While permanent defects have been extensively analyzed at circuit and system levels through approaches such as built-in defect tolerance [57, 35] and reconfiguration [49, 48], there is little understanding of the impact of parameter variability for emerging nanoscale fabrics.

Parameter variations arise due to imprecision in the manufacturing process as well as fundamental atomic scale randomness. At nanometer dimensions where structures typically consist of tens of atoms/molecules, even a small absolute variation in the number of atoms causes a large shift in the electrical characteristics (e.g., random dopant fluctuation and  $V_{TH}$  [59]). This could potentially lead to performance deterioration and/or yield loss.

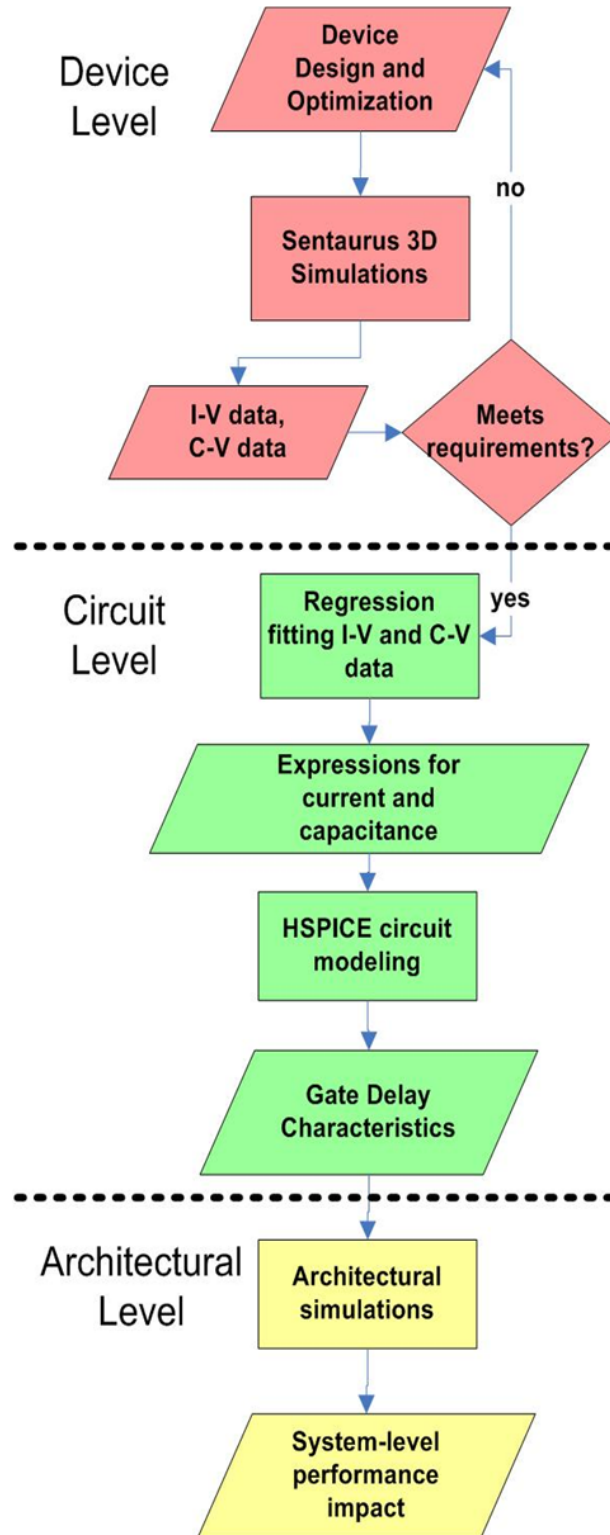
In this chapter, we explore a methodology for evaluating the impact of variability on a nanoscale fabric. This methodology is integrative across device, circuit and architectural layers. It builds on the core concepts of the device-circuit exploration methodology described in the previous chapter including physics-based simulation of device structures and regression-based behavioral models, but incorporates sources of variation for xnwFETs as well as architectural-level evaluations using a custom simu-

lator. We identify key sources of variability at the physical layer, such as channel and gate dimensions of transistors and incorporate them into unified behavioral models for circuit simulation. Extensive HSPICE based characterization of circuits may be done and a library of gate delays incorporated into a high-level architectural simulator to evaluate system-level variability impact. While there has been some previous work in characterizing properties of nanomaterials (e.g., distributions of nanowire diameters for a particular manufacturing setup [31, 12]), devices (e.g. on-current variation [33]) or architecture, this is the first time that an integrated bottom-up approach evaluating implications of variability across multiple fabric levels is presented. The variability framework, while discussed in the context of NASICs, is fully generic and can be adapted to other nanofabrics as well.

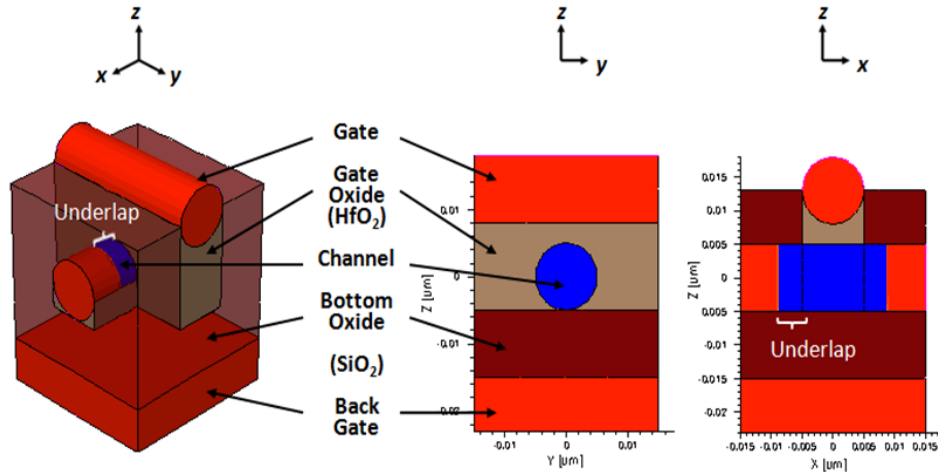
## 5.1 Methodology for Addressing Variability in Nanoscale Systems

In this section we present the methodology for achieving integrated device-circuit-architectural explorations considering parameter variability. This methodology, while discussed in the context of the NASIC fabric, is fully generic and can be applied to other emerging nanoscale computational fabrics for which analytical models of device behavior considering variations are not available. This integrated approach ties physical layer variability to circuit and system level metrics such as delay and performance.

The overall methodology for integrated exploration is presented in the flowchart on Fig. 5.1. The methodology for parameter variation builds on the integrated device-fabric exploration methodology presented in the previous chapter but includes sources of physical parameter variation (e.g. channel diameter, oxide thickness) as independent variables in addition to gate-source and gate-drain voltages. Devices are characterized extensively using Synopsys Sentaurus to extract current-voltage



**Figure 5.1.** Methodology for evaluation of parameter variation integrating device, circuit and architectural levels



**Figure 5.2.** Crossed Nanowire Field Effect Transistor (xnwFET) structure

and capacitance-voltage information. Different device configurations are investigated based on values of physical parameters and their behavior quantified. If the device does not meet circuit requirements for correct functionality, device design may be iteratively carried out. Otherwise, the current and capacitance data are fitted using a standard curve-fit tool to obtain mathematical expressions for the data. Using these, a unified behavioral model is created for a circuit simulator such as HSPICE. The unified behavioral model accurately describes the behavior of a single device across a range of input voltages and physical parameter values. Circuit level simulations incorporating Monte Carlo sampling of individual parameters may then be carried out to obtain distributions of circuit delays with parameter variation. This information is then used to create a library of delays and incorporated into a custom nano-architectural simulator to quantify the critical path delays and performance of large-scale designs. To our best knowledge, this framework is a first of its kind. Subsequent sections describe each phase in more detail.

## 5.2 Device Parameter Variability

Key sources of variability for a single xnwFET device were identified based on device structure (Fig. 5.2) and manufacturing sequence. These include channel diameter and doping, gate oxide thickness, gate diameter as well as source-drain doping. Table 5.1 summarizes all parameters and their extent of variability. Variations in these parameters are dependent on the specific fabrication process used. For example, if a Vapor-Liquid-Solid (VLS) growth method [31] is assumed for nanowire growth, the gate and channel diameter parameters would be very strongly correlated to variations in the catalyst nanoparticles used as seeds. The standard deviation in wire diameter has been shown to be less than 10% in [31, 12]. Similar deviation is seen for Silicon nanowires with SNAP [18]. Atomic Layer Deposition for gate oxide formation has been shown to have spatial variability as low as  $\sigma=1\%$  [32].

xnwFETs need to be engineered to meet NASIC circuit requirements (e.g., threshold voltage, on-off current ratios [40]). Device level techniques such as gate underlap and substrate bias were applied in conjunction to achieve these targets. However, these techniques can be sources of additional variability. For example, variation in the length of the underlap can significantly affect  $I-V$  characteristics. Since this process step is identical to conventional spacer technology, the ITRS spacer requirements table [25] defines the extent of variability allowed for underlap. For a 16nm CMOS technology node this value is  $3\sigma=\pm 0.6\text{nm}$  which is 50% of the extent of variability assumed in our work.

Large-scale integrated manufacturing of nanoscale computing systems is still in its infancy, and for NASIC system fabrication, different approaches are currently being investigated. Therefore, for our initial variability modeling, we conservatively model 10% standard deviation ( $3\sigma=\pm 30\%$ ) for all parameters<sup>1</sup>. Random variation

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<sup>1</sup>For doping levels, each device simulation assumes a discrete number of dopants. 10% standard deviation represents the average deviation over multiple device simulations

**Table 5.1.** xnwFET Device parameters and extent of variation

Parameter	Nominal Value	Standard Deviation
Channel diameter (Cdiam)	10nm	10%
Gate diameter (Gdiam)	10nm	10%
Underlap (Ulap)	4nm	10%
Gate oxide thickness (Gox)	3nm	10%
Bottom oxide (Box)	10nm	10%
Channel doping (Cdop)	$10^{18} \text{dopants}/\text{cm}^3$	10%
Source-drain doping (Sddop)	$10^{20} \text{dopants}/\text{cm}^3$	10%

in all parameters is assumed. Furthermore, physical parameters are expected to be uncorrelated since they would be influenced by separate process steps. For example, the gate oxide may be created using Atomic Layer Deposition (ALD) [46, 32]. There is no dependence of this parameter on any other process step. Similarly, variation in the underlap is purely dependent on the spacers used, and not on any other step.

As more experimental data on device characterization becomes available and detailed process models developed, the modes and extent of variation can be suitably altered.

Accurate 3D-physics-based simulations using Synopsys Sentaurus were carried out to characterize the electrical behavior of the xnwFET device structures. Depending on extent of variability in individual parameters, multiple device configurations were explored. Simulations were calibrated against published experimental data for nanowire FETs at similar dimensions to account for effects such as carrier scattering due to surface roughness and dielectric/channel interface trapped charges. Since parameters are assumed to be uncorrelated, in these simulations, each parameter was varied one at a time for  $\pm 3\sigma$  and the I-V and C-V data were obtained for all device configurations. This data was then used to construct unified behavioral models for circuit simulations.

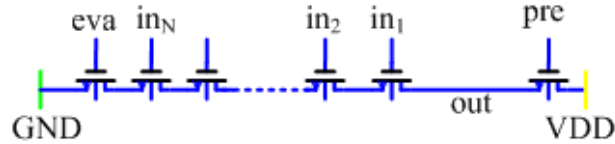
### 5.3 Circuit-level Simulations

In order to represent the behavior of the device accurately in a circuit simulator such as HSPICE [2], curve-fitting of the raw data obtained from device simulations needs to be done. In this step, the current (and various parasitic capacitances) are fitted as a function of independent variables, i.e., input voltages (drain-source ( $V_{DS}$ ) and gate-source voltages ( $V_{GS}$ )) as well as the physical parameters described in Table 5.1. This step was accomplished using the statistical computing tool R [1]. Mathematical expressions describing the current (and capacitances) as functions of the independent variables are then obtained for various regions (see Fig. 5.1 for flow).

An equivalent circuit for the xnwFET was then built into HSPICE incorporating the current source and the parasitic capacitances using sub-circuit definitions. The current and capacitance are calculated on-the-fly during simulations using the fitted mathematical expressions. The subcircuit definition in conjunction with the expressions for individual elements forms the unified behavioral model for the xnwFET device.

NASIC dynamic circuits were extensively characterized for delay using these models. A typical NASIC dynamic circuit is shown in Fig. 5.3. It has  $N$  inputs, as well as control xnwFET devices for precharge and evaluate. The output node is first precharged to logic ‘1’, and then the *pre* signal is switched off and *eva* is enabled. If all inputs are logic ‘1’, the output node will discharge to logic ‘0’ accomplishing NAND gate functionality. The NAND gate is the universal building block for large scale designs, and its delay behavior needs to be extensively characterized and a library of delay distributions constructed for use in an architectural level simulator.

Delay characterization was done using NASIC dynamic NAND gates with number of inputs varying from 1 to 30. The Monte Carlo simulation framework available with HSPICE was used to vary parameter values and the delay to precharge and evaluate the output node was obtained. Parameters are assumed to follow a Gaussian



**Figure 5.3.** N-input dynamic NAND circuits characterized for delay distribution

distribution, with the mean and standard deviation values specified in Table 5.1. They are varied independently for each device, except for the channel diameter which is assumed to be the same across all devices, since all devices are along the same nanowire. Since it may be very hard to do detailed circuit-level simulations on a larger design such as the WISP-0 processor, the delay information is abstracted and used in a higher level architectural simulator.

## 5.4 Architectural Simulations

The architectural simulations take as input the gate delay characterizations as shown in Fig. 5.1. We use a custom-written simulator called FTSIM. FTSIM takes as input a NASIC circuit definition, gate timing characterizations, and parameters for defects and simulates the operation of the circuit on a cycle-by-cycle basis, tracking values within the circuit logically.

FTSIM handles both parameter variations and permanent defects. For permanent defects, the user specifies the type of defects (e.g. stuck-on, stuck-off devices, broken nanowires) and individual defect rates. A Monte Carlo system is used for defect injection and multiple trials carried out. Clustered defects may also be handled. Additional information on defect tolerance can be found in [35, 57].

For parameter variations, timing characterization information for NAND gates from HSPICE are used. Gate delay for any one stage is sampled from the distribution of delays obtained from circuit simulation for each trial and the maximum frequency at which correct outputs are obtained may be found.



In this work, we ran 1,000 trials which produces sufficient working circuits to give a sound idea of the performance distributions. The output of this stage is the performance distributions for the test architectures considered.

## 5.5 Variability Impact on xnwFET Devices<sup>2</sup>

At the device level, variation in physical parameters affects the on-current ( $I_{ON}$ ) of the device<sup>3</sup> and capacitances of xnwFETs. This implies variation in the on-resistance leading to variations in delay and performance at higher levels.

In this study, physical parameters from Table 5.1 are varied one at a time, and the sensitivity of  $I_{ON}$  to parameter variation is measured. Parameters are varied across a  $\pm 3\sigma$  range, assuming 10% standard deviation (i.e., parameters are varied from 70% to 130% of their nominal value).

Not all parameters have equal impact on  $I_{ON}$ . The percentage change in on-current between the lowest and highest sampled value for each physical parameter is shown in Table 5.2. Channel diameter has the largest impact, with  $I_{ON}$  varying by 3.5X over a 7nm to 13nm range.

For four parameters, positive correlation exists between the parameter value and  $I_{ON}$ . For example, as bottom oxide thickness increases,  $I_{ON}$  increases. The substrate bias is used to deplete carriers in the channel for reducing leakage and improving threshold voltage. However, the substrate bias also reduces  $I_{ON}$  due to a shift in the threshold voltage. As the bottom oxide is made thicker, the electrostatic control exerted by the back gate bias is reduced, producing a smaller positive  $V_{TH}$  shift than expected, leading to larger  $I_{ON}$ . As channel diameter increases, the channel resistance

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<sup>2</sup>Work done in UCLA by Prof. Chui's group, included for completeness

<sup>3</sup>Off-currents are also affected, but this is primarily a leakage issue. While variation in the off-currents is captured in device simulations and in the circuit level model, it is not expected to affect the delay and performance of NASIC designs that is the focus of this chapter.

**Table 5.2.** Impact of physical parameter variation ( $3\sigma = \pm 30\%$ ) on device on-current

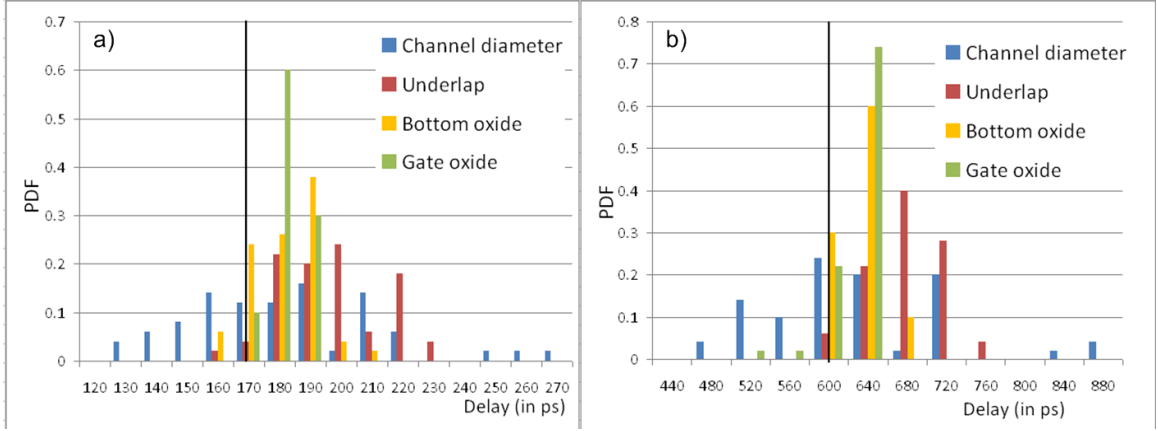
Parameter	% Change in $I_{ON}$	Correlation
Channel diameter	352.0	Positive
Underlap	181.2	Negative
Bottom oxide thickness	147.2	Positive
Gate oxide thickness	58.2	Negative
Source/drain doping	23.8	Positive
Gate diameter	16.2	Negative
Channel doping	11.7	Positive

decreases due to an increase in the cross-sectional area, leading to an increase in  $I_{ON}$ . Increasing the source and drain doping reduces the series resistance. Lastly, as channel doping increases, the short channel effects (SCE) are somewhat alleviated leading to larger  $I_{ON}$ . The other parameters all correlate negatively with on current. Increasing the underlap increases the effective channel length, resulting in a decrease in  $I_{ON}$ . Similarly, increasing the gate oxide thickness decreases the gate capacitance and how well the gate can turn on the channel. Increasing gate diameter increases the length of the channel underneath, decreasing  $I_{ON}$ .

## 5.6 Variability Impact on Circuit Level Delay and System Performance

### 5.6.1 Circuit Level Delay Characterization

NASIC N-input dynamic NAND gates (Fig. 5.3) were simulated in HSPICE using unified behavioral models derived from device data. Delay characterization was done for fan-in varying between 1 and 30, which is the maximum fan-in for the NASIC WISP-0 processor, using the HSPICE Monte Carlo framework and Gaussian sampling of individual parameters. A single channel diameter value was sampled per Monte Carlo simulation for all devices, since all xnwFETs are on the same nanowire. Length-wise variation has been shown to be negligible for the nanowire lengths considered [43]



**Figure 5.4.** Delay distributions for physical parameters with maximum impact on on-current for (a) 15 input and (b) 30 input NASIC dynamic NAND gates. Black line represents nominal.

for a process such as VLS growth. All other parameters were varied independently for each device.

The delay sensitivity of NASIC N-input dynamic gates to individual parameters was studied. We show the impact on delay for the four parameters that have maximum impact on  $I_{ON}$  at the device level. Representative results for fan-in of 15 and 30 are shown. Other fan-in gates were investigated and found to show similar trends.

Fig. 5.4(a) and (b) show the delay distributions for 15 input and 30 input NASIC dynamic NAND gates. The delay distribution due to channel diameter, underlap, bottom oxide and gate oxide thickness is studied. The following key observations are made -

**Channel diameter** has the maximum impact on delay distribution - 81% (71%) change in delay with respect to nominal for 15 (30) input gate. This is due to the high sensitivity of  $I_{ON}$  at the device level, and also due to the correlation of channel diameter across all devices for a single NASIC dynamic NAND circuit. These effects also imply a large percentage standard deviation - 18% (15%) for 15 (30) input gates - leading to a wide spread of delay values.

**Underlap** is negatively correlated with  $I_{ON}$ . This implies that delays will be less than nominal for shorter underlaps. Furthermore, from device level sensitivity analysis  $I_{ON}$  variation is asymmetrical with underlap. 30% negative (positive) deviation causes +74% (-43%) change in the  $I_{ON}$ . This would imply that in a circuit simulation, where underlap values for individual devices are independently sampled, the delay distribution should be left-shifted (majority of devices operating better than nominal). However, the opposite trend is noticed. This is because increasing trend in the  $I_{ON}$  with decreasing underlap is dominated by an increasing trend in the various capacitances as distances between terminals shrink.

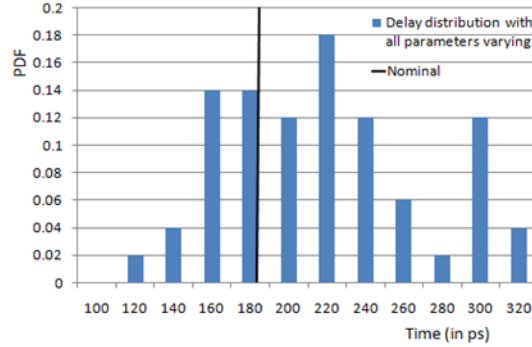
The evaluation delays for **gate oxide** and **bottom oxide** are tightly distributed along the nominal, with mean values within 2% of nominal and standard deviation of 3% for the 30 input gate. Since these parameters are sampled independently, and there exist no appreciable asymmetries as compared to the underlap, variation in delays of individual devices tend to cancel out especially in higher fan-in designs.

Fig. 5.5 shows delay distributions for the 15 input NASIC dynamic NAND gate with all parameters varied simultaneously with  $3\sigma = \pm 30\%$ . The mean is 20% higher than the nominal due to the underlap asymmetry effect that skews the distribution to the right. The same trend is observed in other fan-in gates as well. A 118% spread with respect to the nominal is observed for 15 input gates. The relative spread was found to be decreasing with increasing fan-in, as expected.

The gate delay distributions with all parameters varying for different fan-ins were modeled as gamma distributions and used in an architectural simulator to evaluate the process variation impact on a larger design.

### 5.6.2 System Level Performance

Architectural simulations of the NASIC WISP-0 processor [56, 58] were carried out using the architectural simulation framework described in Fig. 5.1 and Section 5.4.

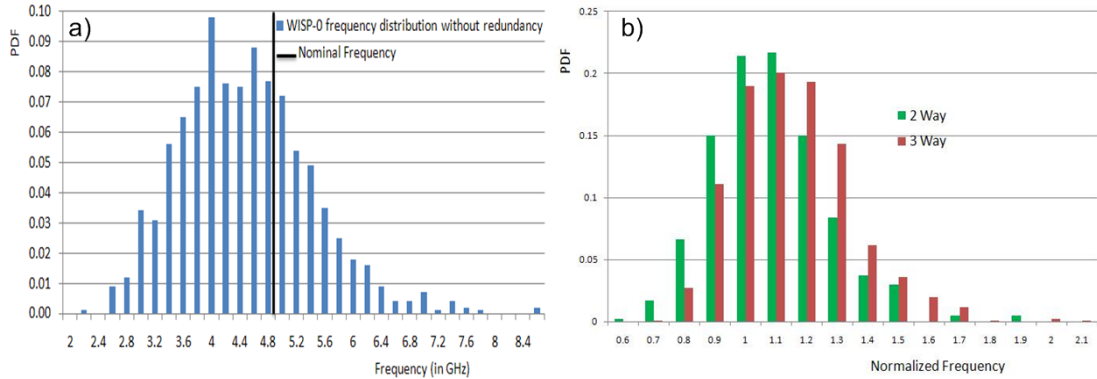


**Figure 5.5.** Delay distribution for 15 input gate with all parameters simultaneously varied: Nominal value is 174ps. Distribution is right-shifted due to asymmetric underlap effect

Gate delay distributions obtained from Monte Carlo simulations of NASIC dynamic NAND gates were sampled for each gate in the design and the maximum operating frequency at which the processor functioned without missed deadlines was estimated.

The probability density function of operating frequencies obtained is plotted in Fig. 5.6(a). Also shown in the diagram is the nominal frequency for WISP-0 without any process variation. From the diagram, parameter variation causes performance deterioration in 67% of the samples investigated.

WISP-0 is not fully balanced with respect to timing and delay. The frequency is therefore determined entirely by a small number of high fan-in data-paths. If the delays sampled from these paths are lower than nominal then the performance of the entire design is not affected or may even improve. However, in designs balanced for timing, such as commercial processors where a lot of emphasis is typically put on timing path optimizations, there will be a large number of paths with similar nominal delay. The slowest path among these would determine the operating frequency. This implies that for balanced designs with process variation, a much larger fraction of chips will be slower than nominal, since data speed-up along some high fan-in paths will be entirely offset by others.



**Figure 5.6.** Distribution of WISP-0 operating frequencies showing impact of parameter variations: (a) With no built-in fault tolerance incorporated, 67% of chips operate at frequency below nominal due to variations in device parameters (b) PDF for 2-way and 3-way redundancy schemes, showing a majority of samples operating at better-than-nominal frequencies (normalized frequency  $> 1$ ).

Results in Fig. 5.6(a) are for designs with no built-in fault tolerance. However, nanoscale fabrics based on self-assembly manufacturing processes tend to have very high defect rates (in NASICs we assume 10 orders of magnitude higher than CMOS or 100s of millions to billions of defective devices per  $\text{cm}^2$ ) that necessitates the use of built-in fault tolerance for achieving acceptable effective yield. These techniques may also provide resilience against parameter variation related timing faults, since the fault-tolerance is agnostic to the source of the fault (permanent defects or parameter variation) and may be leveraged for parameter variation resilience.

Fig. 5.6(b) plots a distribution of maximum operating frequencies obtained for 2-way and 3-way redundant WISP-0 designs for 6% device level defect rate. The x-axis is normalized to the respective nominal frequencies (no parameter variation). In these cases, timing faults due to slower data-paths are masked by redundant fast data-paths which implies that a majority of samples (75% for 2-way redundancy) operate at frequencies better than nominal, proving that built-in fault tolerance can provide resilience against parameter variations in conjunction with manufacturing defects. A variety of new techniques based on FastTrack and biased voting schemes that carefully

manage yield and performance tradeoffs and are optimized for parameter variation as opposed to permanent defects have been developed for nanoscale fabrics [39].

## 5.7 Chapter Summary

A novel methodology for bottom-up integrated device-circuit-architectural explorations for analyzing the impact of parameter variability in nano-device based computing systems was developed. The methodology builds on accurate 3D physics based simulations of device structure to capture variations in on-current as a function of physical parameters. Circuit and architectural simulations can then be done to evaluate the impact of this variability on gate delay and system level performance respectively.

The methodology was evaluated on the NASIC computational fabric with xn-wFETs, NASIC dynamic NAND gates and a processor design. Key sources of variation at the device level such as channel diameter were identified and sensitivity of  $I_{ON}$  was evaluated.  $I_{ON}$  may vary by up to 3.5X with variations in the channel diameter and by up to 1.5X with gate underlap. Circuit level simulations identified the evaluate time in NASIC designs as the dominant component of the gate delay with parameter variation incorporated. Gate delay simulations varying a single parameter show up to  $\pm 40\%$  variation from nominal gate delay.

For a processor with no fault tolerance, 67% of chips were found to operate at frequencies below nominal due to parameter variation. However given high defect rate for nanomanufacturing, nanoscale computing fabrics would incorporate built-in fault tolerance that could also provide resilience against timing faults.

## CHAPTER 6

# MANUFACTURING PATHWAYS AND ASSOCIATED CHALLENGES FOR NASICS

Reliable manufacturing of large-scale nanodevice-based systems continues to be challenging. Self-assembly based approaches, while essential for the synthesis and scalable assembly of nano-materials and structures at very small dimensions, lack the specificity and long-range control shown by conventional photolithography. Other non-conventional approaches such as electron-beam lithography (EBL) provide the necessary precision and control and are pivotal in characterization studies; but these are not scalable to large scale systems. Examples of small nanoscale prototypes include a carbon nanotube FET based ring oscillator [8] and an XOR gate using SNAP assembled semiconductor nanowires and electron-beam lithography [54]. In all these cases, the focus has been on creation of devices followed by arbitrary interconnections to build logic gates, an approach that is not scalable to large-scale systems.

In general, a manufacturing pathway for integrated nanosystems needs to achieve three important criteria:

- Scalability: Large scale simultaneous assembly of nanostructures/devices on a substrate must be possible.
- Interconnect: Nanodevices must be interconnected in a prescribed fashion for signal propagation and achieving requisite circuit functionality. While it may be possible to integrate individual devices together after assembly, an approach that simultaneously creates nanodevices and interconnections poses fewer challenges and is expected to achieve better density.



- Interfacing: The nanosystem must be effectively interfaced with the external world.

In this chapter we explore a manufacturing pathway for NASICs that realizes the fabric as a whole including devices, interconnect and interfacing. This pathway employs self-assembly/ unconventional patterning-based approaches for scalable assembly of semiconductor nanowires, and conventional lithography based techniques for parallel and specific functionalization of nanodevices and interconnects. While individual steps have been demonstrated in laboratory settings, challenges exist in terms of meeting specific fabric requirements and integration of disparate process steps.

## 6.1 Fabric Choices Targeting Manufacturability

Before delving into the details of the manufacturing pathway, it is instructive to look at certain aspects of the NASIC fabric that significantly mitigate requirements on manufacturing. Design choices have been made at the device, circuit, and architectural levels targeting feasible manufacturability while carefully managing constraints. This is in direct contrast to other technologies such as CMOS which optimize designs for performance and area, but place stringent requirements on the manufacturing process.

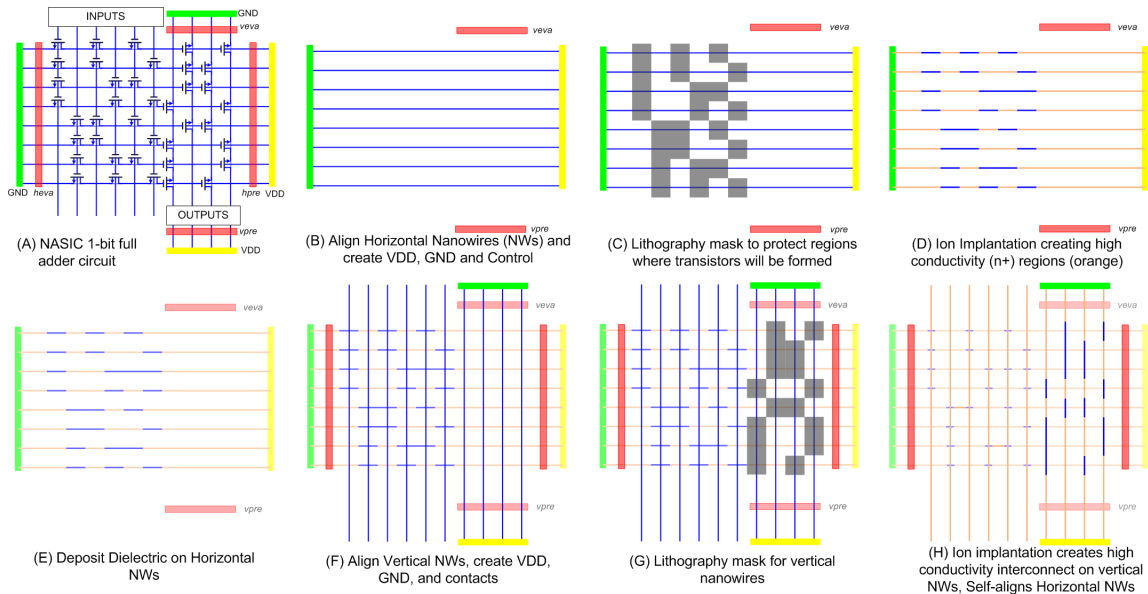
- NASIC designs use regular semiconductor nanowire crossbars without any requirement for arbitrary sizing, placement or doping. Regular nanostructures with limited customization are more easily realizable with unconventional nanofabrication approaches.
- NASIC circuits require only one type of xnwFET in logic portions of the design.

- Local interconnection between individual devices as well as between adjacent crossbars is achieved entirely on nanowires; interconnection of devices does not introduce new manufacturing requirements.
- NASICs use dynamic circuit styles with implicit latching on nanowires. Implicit latching reduces the need for complex latch/flip-flop components that require local feedback.
- Tuning xnwFET devices to meet circuit requirements is done in a fabric-friendly fashion; techniques such as gate underlap and substrate biasing do not impose new manufacturing constraints.
- NASICs use built-in fault tolerance techniques to protect against manufacturing defects and timing faults caused by process variation. Built-in fault tolerance techniques do not need reconfigurable devices, extraction of defect maps, or complex micro-nano interfacing as required by reconfiguration based fabrics. All fault tolerance is added at nanoscale and made part of the design.

These fabric choices reduce manufacturing requirements down to two key issues: assembling nanowire grids on to a substrate and defining the positions of xnwFET transistors and interconnect. The latter step, also called functionalization, is a price paid for a manufacturing-time customization. The manufacturing pathway and associated challenges are discussed in the next sub-section. Note that by adjusting the nanowire pitch any manufacturing issue can be managed but the goal is to achieve the smallest possible pitch.

## 6.2 Manufacturing Pathway

Key steps in the NASIC manufacturing pathway are shown in Fig. 6.1. Fig. 6.1(A) shows a NASIC 1-bit full adder circuit. Horizontal nanowires are grown and aligned



**Figure 6.1.** Scalable manufacturing pathway for NASICs

on a substrate (B). In general, nanowire alignment can be *in-situ*, *ex-situ*, or direct-patterned. *In-situ* refers to techniques where nanowires are aligned in parallel arrays during the synthesis phase itself. On the other hand, *ex-situ* refers to techniques where nanowire synthesis and alignment are carried out separately. Lithographic contacts for  $V_{DD}$  and  $V_{SS}$  as well as some control signals are created (B). A photolithography step is used to protect regions where transistors will be formed while creating high conductivity regions using ion implantation- elsewhere (C, D). Ion implantation creates  $n + /p/n+$  regions along the nanowires which under suitable electrical fields act as inversion mode source/channel/drain regions.

Gate dielectric layer is then deposited (or oxide is grown) (E) followed by alignment of vertical nanowires. The above steps are now repeated for the vertical nanowire layer (F-H). During ion implantation on vertical nanowires (H), channels along horizontal nanowires are self-aligned against the vertical gates.

Key individual steps and challenges are discussed in detail in the following subsections.

### 6.2.1 Nanowire Growth and Alignment

The ideal technique to form aligned nanowire arrays should guarantee an intrinsic and concurrent control over three key parameters:

- the number of nanowires,
- the inter-nanowire pitch, and
- the nanowire diameter within the array.

State-of-the-art semiconductor nanowire array formation with alignment techniques can be broadly classified into three categories:

- *In-situ* nanowire growth and alignment: In *in-situ* nanowire growth and alignment nanowires are directly synthesized in an aligned fashion on a substrate. For example, [28] has shown MOCVD growth of InSb nanowires from gold precursors in-plane using a InSb (111) substrate. Other representative techniques for *in-situ* growth include gas-flow guiding [30] and electrical field guiding [52, 14]. This family of techniques is dependent on catalyst engineering and patterning as well as compatibility of nanowires with the substrate. One approach to pattern gold catalysts at sub-lithographic features is using oriented block-copolymer films [51] as templates. The key advantage is that a separate transfer step for nanowires is not required.
- *Ex-situ* nanowire alignment: In *ex-situ* nanowire alignment, nanowires are grown separately and then transferred to substrate. Representative techniques include fluidic alignment [62] and organic self-assembly etch [19, 27]. The key advantages of *ex-situ* techniques are wide variety of material choice and nanowire synthesis processes that are available. It is also possible to achieve a tighter distribution of nanowire diameters since the growth process can be separately controlled. However, an effective transfer step is required to attach each nanowire to pre-defined locations as well as control of orientation of transferred nanowires.

- Nanolithography-based pattern and etch techniques: In these approaches, a semiconductor material layer pre-formed on the target substrate surface is first patterned by nanolithography and then anisotropically etched to create a periodic nanowire array. While the etching process is rather standard, there are two very promising nanoscale patterning techniques including the nanoimprint lithography (NIL) [9] and superlattice nanowire pattern transfer (SNAP) [54, 18]. These approaches in principle meet the aforementioned criteria in terms of numbers, diameter and pitch of nanowires (e.g. since the reusable transfer pattern can be precisely controlled) but possess some subtle practicality concerns. Since the surfaces of these nanowires are usually damaged during the etching process, caution should be exercised to prevent significant degradation in the resultant device performance. Also the choice of semiconductor nanowire material is more limited compared to either the *in-situ* or *ex-situ* approach.

The construction of the 2D nanowire fabric for NASIC circuit applications consists of two aligned nanowire array formation steps. The first (and bottom) semiconductor nanowire array can be formed by either the nanolithography-based patterning-and-etching technique or the *ex-situ* aligned assembly method. The former selection is primarily driven by the material choice silicon. Since silicon-on-insulator (SOI) substrates are readily available, the patterning-and-etching technique could be considered due to its capability of achieving aligned parallel nanowires with long-range order as long as the nanowire surface damage could be minimized. Alternatively, the *ex-situ* method remains an attractive solution with the advantages and challenges discussed above.

The second (and top) array is preferentially formed by the transferring of a pre-aligned nanowire array assembled using either the *ex-situ* or *in-situ* approach. The choice of a particular technique would depend on its ability to accomplish the key specifications outlined above. Since the same material (silicon) with roughly the same

nanowire diameter and pitch is required in both arrays, it is therefore beneficial to employ the same method and repeat it.

### 6.2.2 Functionalization

In an  $n$ -type xnwFET, the gate, drain and source terminals are doped  $n+$ , whereas the channel used  $p$ -type doping for inversion mode operation. Similar to conventional FET devices, the potential applied at the gate controls the flow of electrons between the source and drain terminals. Customization of nanowire arrays is required to define the positions of transistors on the grid for achieving arbitrary logic functions, and create high conductivity interconnects elsewhere.

Nanowires assembled on the substrate are initially doped uniformly along their lengths. The doping type corresponds to the channel doping of the inversion mode FET devices (for example, if  $n$ -type FETs are needed, the nanowires transferred to the substrate will originally contain  $p$ -type dopants).

We propose to use ion implantation, a well controlled technique used in the semiconductor industry, to create: a) high conductivity regions on nanowires where transistors do not exist, b) gate material of NWs, and c) gate self-aligned FET channels. The minimum feature size is calculated to be  $(2 \times \text{pitch} - \text{width})$  squares (Fig. 6.1(C) and 6.1(G)). Simulations of overlay requirements for NASICs was carried out sampling overlay imprecision for successive lithographic masks as Gaussian random variables. Results of overlay simulations show that 100% overlay-limited yield can be obtained for a mask misalignment of  $3\sigma = \pm 5.7nm$  [53], which is a considerable improvement over 16nm CMOS ( $3\sigma = \pm 3nm$ )

Ion implantation of horizontal nanowires is shown in Fig. 6.1(C), (D). These steps create high conductivity regions along the assembled horizontal nanowires.  $n+/p/n+$  regions are formed on the left side of Fig. 6.1(D); these act as source/channel/drain regions. The  $n+$  regions on the right of Fig. 6.1(D) are gates for vertical nanowires

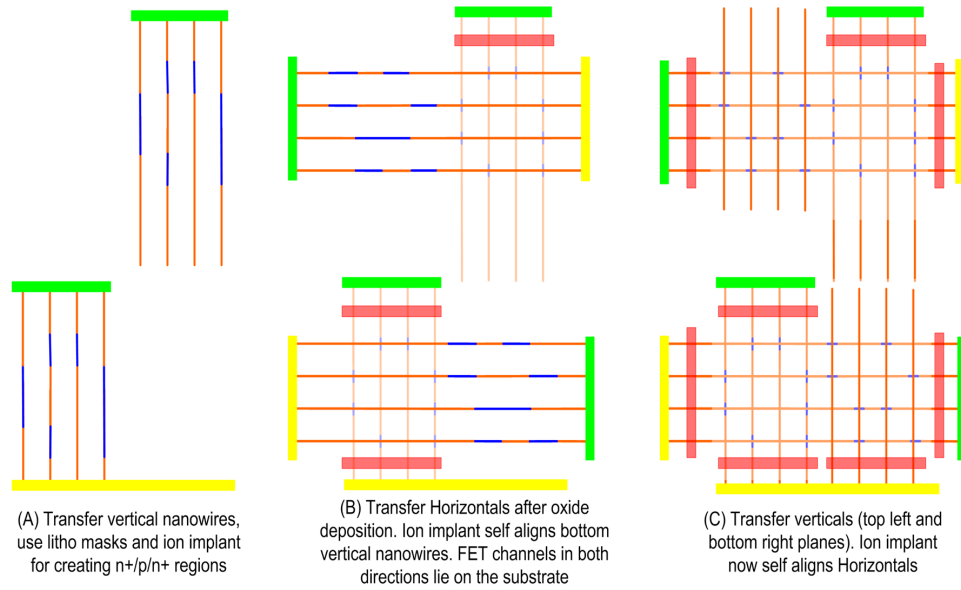
that will be assembled in subsequent steps. An additional optional silicidation step could be done to further improve the conductivity of the  $n+$  regions defined in this step.

Fig. 6.1(G), (H) show ion implantation steps applied to vertical nanowires. The six vertical nanowires on the left are doped  $n+$  and act as gates for underlying horizontal nanowire channels. The four vertical nanowires to the right contain  $n+/p/n+$  source/channel/drain regions and are gated by underlying horizontal nanowires. Furthermore, this ion implantation step self-aligns the horizontal channels on the left side of the figure against the vertical nanowire gates.

It must be noted that lithography is used to protect regions where FETs will be formed, and not for complex patterning. In conjunction with self-alignment, this implies that precise shapes with sharp edges are not needed. NASIC built-in defect tolerance techniques [35, 57] further ameliorate requirements on lithography. Fewer masks and NASICs built-in fault tolerance imply that it may be possible to build NASICs at a much lower manufacturing cost and finer resolution than scaled CMOS.

The manufacturing pathway in Fig. 6.1 needs nanowires to be transferred on to the substrate twice, once each for horizontal and vertical nanowires. This implies that vertical xnwFET channels are not on the substrate, but placed above layers of horizontal nanowires and oxide; this poses some challenges in terms of self-alignment of these channels against horizontal nanowire gates.

This concern may be overcome by using an approach that uses 3 separate nanowire transfers as shown in Fig. 6.2 A) vertical NWs in the output plane are first transferred, and ion implantation with lithographic masks is carried out; B) horizontal NWs are transferred after gate dielectric deposition, these NWs are self-aligned with the previously transferred verticals; and C) input plane verticals are transferred and ion implantation self-aligns these with the underlying horizontals. This approach, however, poses challenges in terms of alignment of input vertical nanowires in one



**Figure 6.2.** Manufacturing pathway for NASICs with 3-step nanowire transfer

NASIC tile against output nanowires of the previous tile, as well as the requirement of physical interconnections between nanowires assembled in separate steps.

### 6.3 Chapter Summary

One manufacturing pathway for the NASIC fabrics was discussed. The pathway realizes the fabric as a whole with devices and interconnect formed as part of a regular grid, as opposed to approaches focused on arbitrary interconnection of individual nano-devices. Key challenges including nanowire alignment and functionalization requirements were discussed.



## CHAPTER 7

### **N<sup>3</sup>ASICS: DESIGNING NANOFABRICS WITH REDUCED MANUFACTURING REQUIREMENTS**

In this chapter, we present N<sup>3</sup>ASICs, a new nanoscale computing fabric that eliminates the remaining manufacturing challenges for NASICs and can be built with manufacturing solutions that are known today. In keeping with the fabric-centric mindset, this reduction in manufacturing complexity is enabled by design choices at multiple levels. While this new fabric trades-off some of the density advantages of NASICs, it still achieves considerable improvements in area/power/performance over scaled CMOS with reduced manufacturing requirements.

As discussed in the previous chapter, unconventional direct-patterning based manufacturing techniques such as Nano Imprint Lithography (NIL) [38] and Superlattice Nanowire Pattern transfer (SNAP) [55] [58], are able to produce ultra-high density nanostructures. For e.g., it has been shown that 7nm width with 13nm pitch nanowires can be patterned with SNAP [18] on an SOI substrate. However these and other unconventional techniques have poor overlay with respect to previously formed patterns. Overlay imprecision reported for NIL was  $3\sigma = \pm 105\text{nm}$  [44].

On the other hand photolithography has an excellent overlay and alignment precision. According to International Technology Roadmap for Semiconductors (ITRS) [26] state-of-the-art photolithography has an overlay imprecision of  $3\sigma = \pm 6.4\text{nm}$ . However, overlay alignment is expected to become much more challenging with further CMOS scaling (e.g. 16nm CMOS would require  $3\sigma = \pm 3\text{nm}$ , manufacturing solutions unknown).

Our goal in this chapter is to develop an approach by which we can combine unconventional and conventional manufacturing approaches while retaining the benefits of both. Unconventional nanomanufacturing is used in conjunction with conventional CMOS lithography and design rules to build a new class of 3-D integrated nanofabrics (N<sup>3</sup>ASICs: Nanoscale 3D Application Specific Integrated Circuits) with careful consideration to manufacturing and overlay requirements. We present the overall fabric design and show a layer-by-layer assembly sequence for N<sup>3</sup>ASICs depicting how the complete fabric (including devices, interconnect and interfacing) may be realized on a single Silicon-on-Insulator (SOI) wafer. We show how fine-grained integration between nanoscale and CMOS features can be achieved using standard area distributed pins/vias and design rules. We also evaluate key system-level metrics such as density, performance and power for N<sup>3</sup>ASICs and compare it against both NASICs and an equivalent 16nm CMOS design.

## 7.1 Physical Fabric Vision

We propose a new physical fabric that consists of nanowire arrays at the bottom (built using unconventional manufacturing) with a conventional CMOS metal stack for interconnect (built using photolithography) on top. All active devices and logic implementation is achieved on the ultra-dense nanowire arrays which can be direct-patterned on an ultra-thin Silicon-On-Insulator (SOI) wafer. The patterning can be achieved using techniques like NIL or SNAP that provide excellent control over the number of nanowires, width and spacing. There is no second nanowire transfer step.

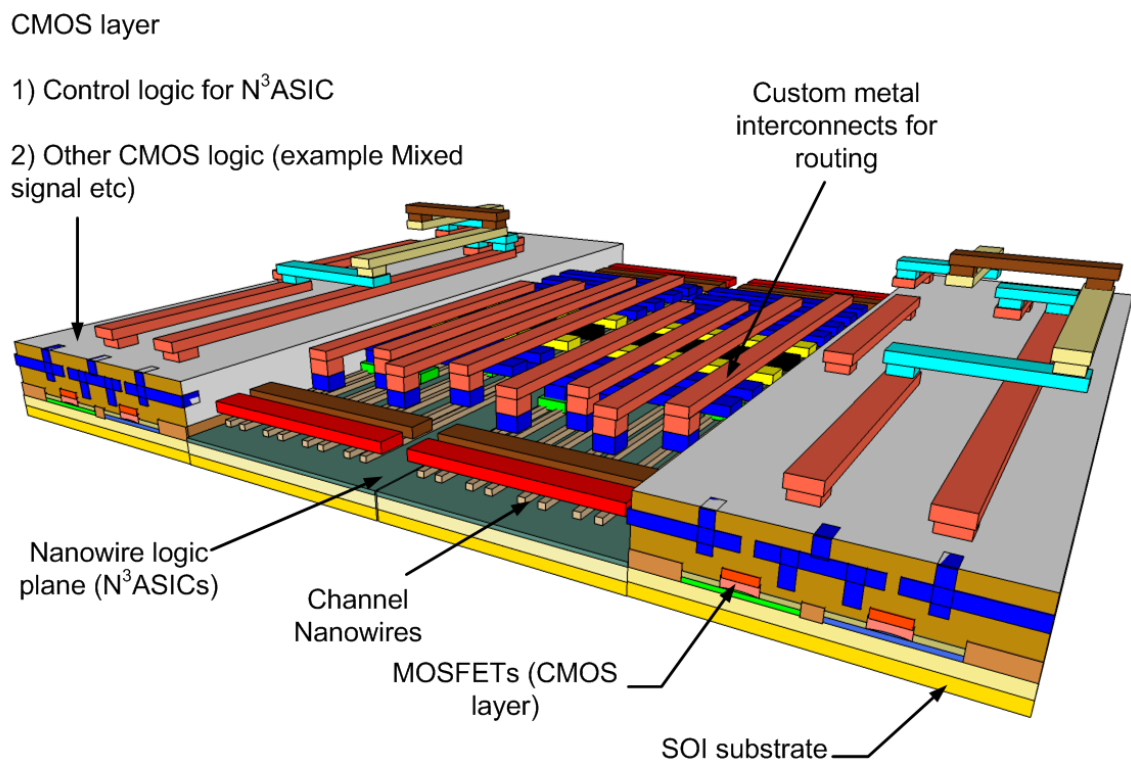
In this approach, patterning of high-density nanostructures is carried out *prior* to all lithography steps without any overlay requirement. Furthermore if the defined nanostructure pattern is regular (e.g. parallel arrays), the first lithographic mask has overlay tolerance, i.e. it may be offset over the array without yield loss. Subsequent steps make use of conventional photolithography. The *a priori* assembly/direct-

patterning of sub-lithographic features on the densest NW layer before any conventional lithographic step (e.g., for contacts/vias) means 3D overlay alignment requirements exist only between subsequent lithographic masks.

Fig. 7.1 shows the envisioned N<sup>3</sup>ASICs fabric built on a standard Silicon-on-Insulator (SOI) wafer. It consists of uniform parallel semiconductor nanowire arrays on which logic/memory is implemented. Active devices in N<sup>3</sup>ASICs are single type, doped dual channel crossed nanowire transistors (2C-xnwFETs). Area-distributed interfaces or vias are used to connect outputs of nanowire stages to a standard CMOS metal stack. Metal interconnections between vias achieve arbitrary routing. The nanowire logic plane is surrounded by CMOS circuitry. The peripheral CMOS circuitry can be used for control logic, dynamic clocking, mixed signal etc. N<sup>3</sup>ASICs use the same circuit styles as NASICs and previous explorations on device requirements, cascading/noise issues and parameter variation are equally relevant.

To enable full and fine-grained integration with CMOS metal stack without new manufacturing or functionalization requirements, lithographic design rules need to be followed. Standard lithography design rules are used for lithographic functionalization steps including defining positions of transistors, power and control rails, vias, interconnect etc. Lithographically defined vias or area-distributed interfaces connect the nanowire arrays through a CMOS metal stack. Metal interconnects are used for routing the signals in 3D. Adherence to design rules imply functionalization requirements are mitigated.

Fig. 7.2 shows representative  $\lambda$  design rules applied to the N<sup>3</sup>ASICs fabric. All design rule requirements like Metal-Metal spacing, Metal-via spacing and Via-overhang are followed. C. Bencher et. al. [5] project that the metal 1(M1) pitch for the 16nm technology node is 40nm. This is equal to  $5\lambda$  where  $\lambda=8\text{nm}$  for 16nm technology node.



**Figure 7.1.** Nano-CMOS integrated N<sup>3</sup>ASICs fabric

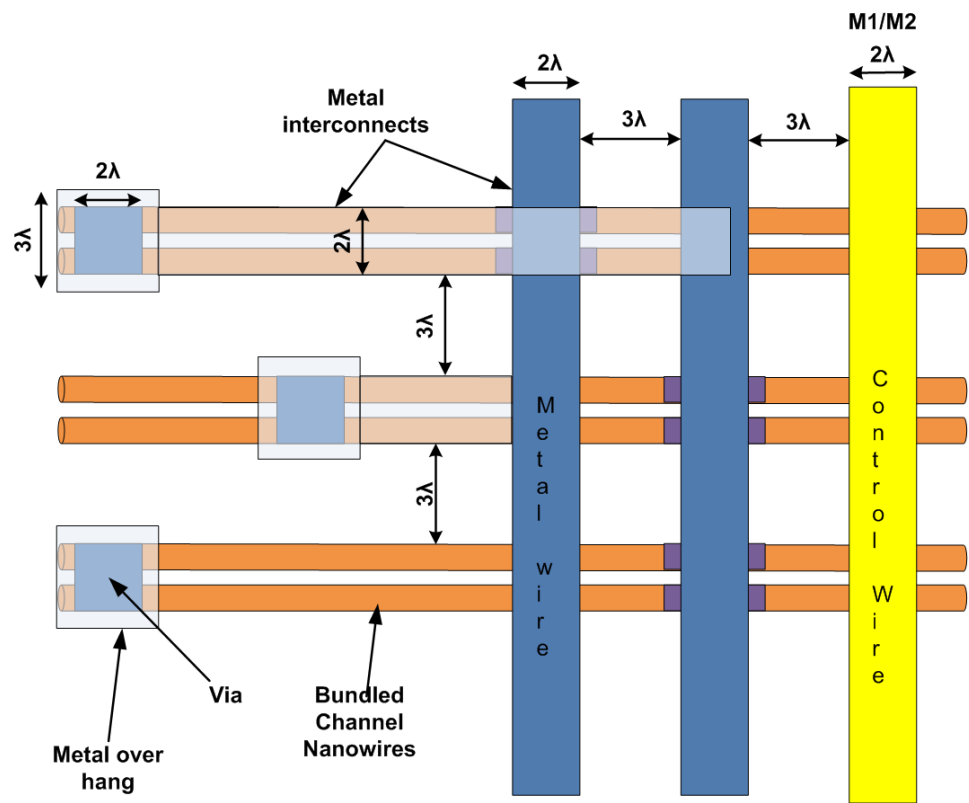


Figure 7.2. CMOS Design rules applied to N³ASICs

Since metal vias are used to contact nanowires, the nanowire spacing should adhere to CMOS design rules. Given that nanowires can have much smaller dimensions than vias, more sub-lithographically patterned nanowires may be bundled within the same via dimension without any density impact. Having more than one nanowire per via allows for better contact, performance and inherent defect resilience (e.g against stuck-open channels).

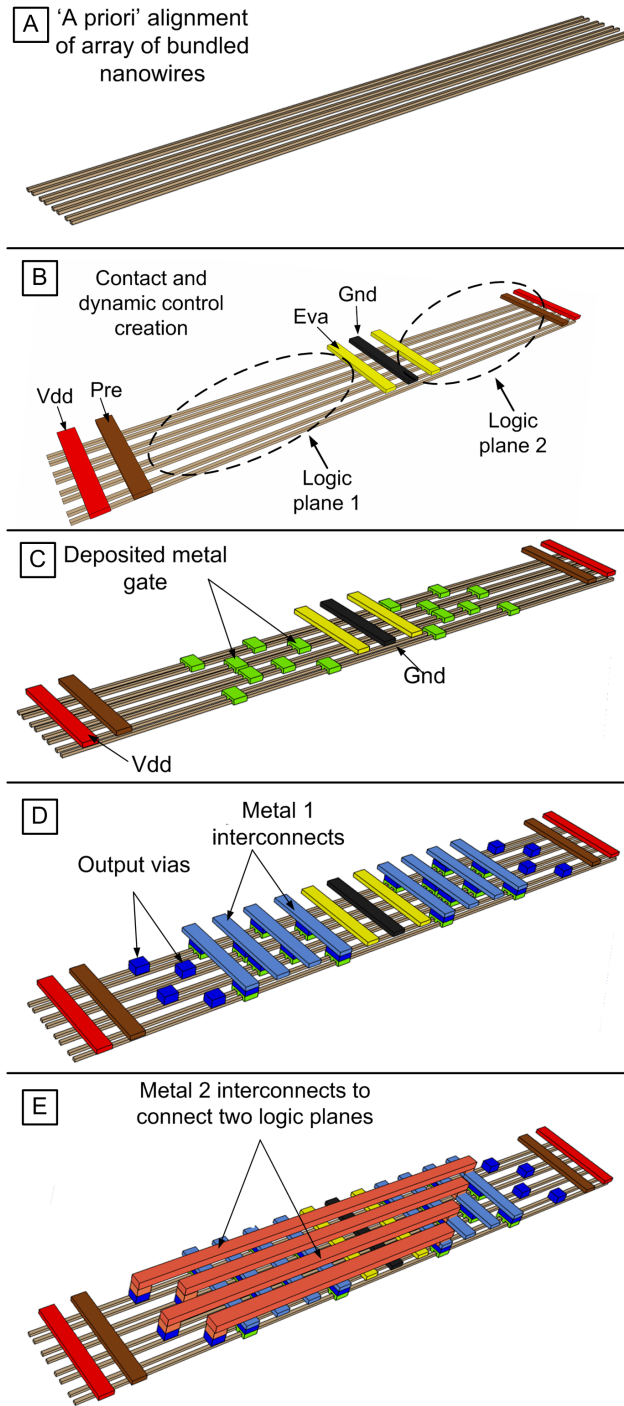
Fig. 7.2 shows how bundled pair of nanowires are contacted using a via. Metal 1 interconnects is used to connect the inputs of the transistors. Metal 2 interconnects are used to connect the output on the nanowires to the subsequent stages.

## 7.2 Assembly Sequence

We present a simplified assembly sequence followed in building the N<sup>3</sup>ASICs fabric. At the bottom of the fabric is a uniform semiconductor nanowire array. This can be direct patterned on ultra-thin Silicon-On-Insulator. Nanowires can be bundled in pairs in order to achieve better contact with the vias. Fig. 7.3A shows the uniform dense nanowire array created *a priori* to any lithographic step.

Fig. 7.3B shows the contact creation for VDD and GND, precharge and evaluate. This diagram depicts the scenario of two stages cascaded next to each other. This can be treated as two logic planes as shown in the figure. We can use interconnects to route signals across the logic planes. Logic plane 1 is on the left and logic plane 2 is on the right

Fig. 7.3C shows the metal gate deposition step. Metal gates (shown in green) are deposited at certain positions to define 2C-xnwFETs using conventional lithography and masks. Initially the nanowires are doped *p*-type. A self-aligning ion implantation is then used to create *n* + /*p*/*n*+ source/channel/drain structures. This creates enhancement mode 2C-xnwFETs similar to conventional MOSFETs in CMOS. All device channels are oriented along the same direction and lie on the substrate itself.



**Figure 7.3.** Assembly Sequence for N<sup>3</sup>ASICs fabric: A) Patterned Nanowires B) Creation of Lithographic contacts and dynamic control rails C) Metal gate deposition followed by self-aligned ion-implantation to define high-conductivity interconnect D) Metal 1 vias and interconnects, and E) Creation of Lithographic contacts and dynamic control rails.

Fig. 7.3D shows the Metal 1 vias and interconnects. Metal lines and vias are laid down for interconnection. Inputs are received through an M1 array (light blue lines) and vias are dropped on to the nanowires to tap the outputs (blue dots).

As shown in Fig. 7.3E, outputs from the left logic plane are cascaded to the inputs of the right plane using M2 (orange lines). The output of the second logic plane can be routed to other tiles using higher metal layers in the metal stack. This allows us to achieve arbitrary routing between two different tiles. All local routing within a single stage is achieved on the nanowires themselves. This helps in reducing the routing overhead of the design.

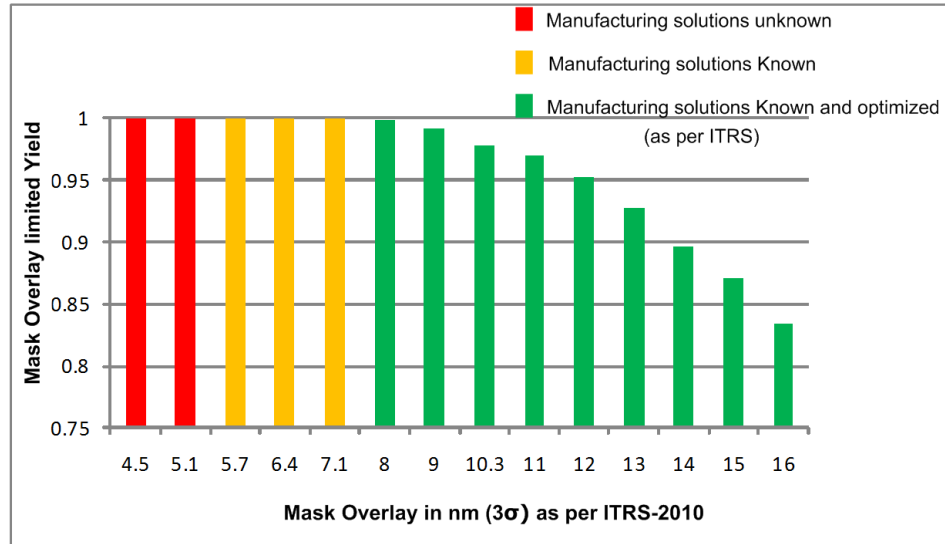
### 7.3 Overlay Requirement

As discussed previously, the initial nanowire patterning step with unconventional manufacturing does not have any overlay requirement. In this section, the impact of mask overlay misalignment for subsequent lithographic masks is addressed. The WISP-0 [56] nanoscale processor design was mapped onto the N<sup>3</sup>ASIC fabric. Overlay misalignment between successive masks were modelled as Gaussian random variables, and Monte Carlo simulations were carried out in a custom simulator to determine the number of functioning chips. The simulations were carried out for several  $3\sigma$  overlay misalignment values projected by ITRS 2011.

The contact creation and metal gate deposition steps involve alignment to the smallest features, and hence they are most critical to mask overlay and contribute significantly to the yield loss. Yield loss due to mask overlay during metal stack creation is minimal (identical to conventional CMOS). Hence metal stacks higher than M2 layer have not been considered in these simulations.

The results in Fig. 7.4 show that 100% mask overlay limited yield may be obtained for  $3\sigma = \pm 8\text{nm}$  overlay (manufacturing solutions known as per ITRS 2011) when constructing a uniform nanowire bundle with  $\lambda=8\text{nm}$  (16nm technology node) in the





**Figure 7.4.** Mask overlay limited Yield vs. Overlay for 3D integrated fabric

3D integrated fabric. Within a bundle the width of nanowires is 5nm each, with 6nm spacing to accommodate 16nm vias. Fig. 7.4 shows that even with a pessimistic mask overlay projection of  $3\sigma = \pm 16\text{nm}$  a mask overlay limited yield of 83% can be observed. These numbers are a significant improvement over overlay precision requirement for NASICs, where the equivalent number is  $3\sigma = \pm 5.7\text{nm}$  for 100% overlay-limited yield.

It is evident from the results that the use of regular structure (like the nanowire arrays in  $N^3$ ASICs) does not impose stringent constraints on overlay precision requirement. Further, fewer masks are required to manufacture this fabric compared to a CMOS design which is beneficial from both yield and cost perspective. By contrast, irregular structures would have more stringent mask overlay requirements. For example, the proposed approach also has considerably greater tolerance to overlay imprecision than 16nm CMOS that requires a 3nm precision at 16nm node as per ITRS 2011.

## 7.4 N<sup>3</sup>ASICs Device, Circuits and Architectural Exploration

N<sup>3</sup>ASICs evaluations were carried out at device, circuit and architecture level. The integrated device-fabric exploration methodology proposed for NASIC was adopted.

Physical fabric choices impact the structure and properties of N<sup>3</sup>ASICs devices. For e.g. if SNAP is used to pattern the bottom most ultra-dense nanowire layer, nanowires with square cross section will be obtained. Further, use of CMOS design rules facilitates bundling of nanowires because of the larger via dimension compared to nanowires. Hence, dual-channel devices can be used in N<sup>3</sup>ASICs. For this device structure the electrical properties are obtained from Synopsys Sentaurus Device [3]. Using this data, behavioral model compatible with HSPICE [2] is created. This behavioral model is used to carry out circuit and system level evaluations.

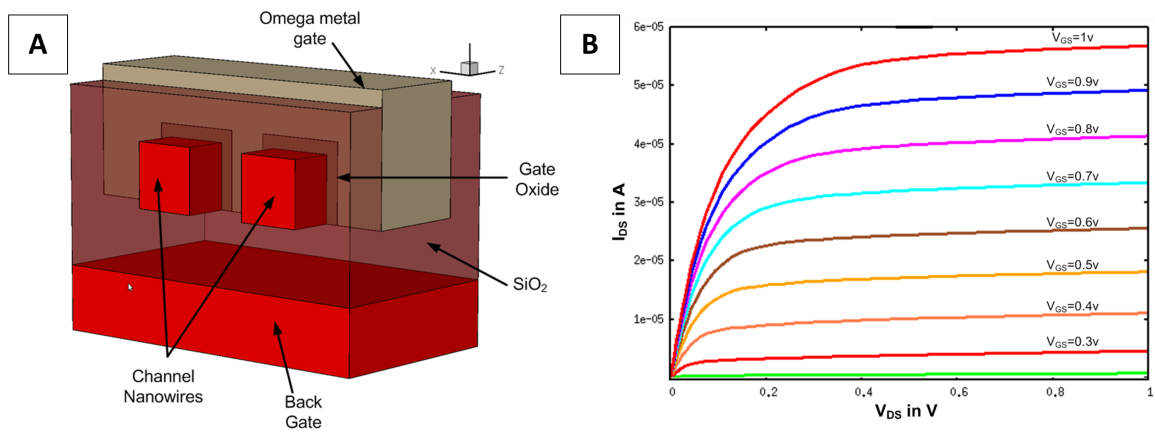
### 7.4.1 Device Simulations<sup>1</sup>

Dual-Channel Crossed Nanowire FETs (2C-xnwFETs, Fig. 7.5A) employ metal Omega gate structures for tighter electrostatic control. Gate material work function is 4.6 eV. 16nm channel devices were simulated given that it is the minimum feature size for lithographically defined gates. The notation N<sup>3</sup>ASICs-16 represents N<sup>3</sup>ASICs constructed with 16nm CMOS design rules, which implies  $\lambda$  the scale length, is equal to 8nm. The channels are doped p-type of the order of  $10^{18}$  cm<sup>-3</sup> and the source/drain regions were doped n-type of the order of  $10^{20}$  cm<sup>-3</sup>. A substrate bias of -3V was assumed to deplete the channel and adjust device parameters such as threshold voltage and on/off current ratios for correct cascading. A high- $\kappa$  HfO<sub>2</sub> material is used for gate oxide. The gate oxide thickness was 3nm. Table 7.1 summarizes the parameters used for Device simulations.

Drain current vs. drain voltage ( $I_{DS}$ - $V_{DS}$ ), drain current vs. gate voltage ( $I_{DS}$ - $V_{GS}$ ), and different parasitic capacitances vs. gate voltage ( $C$  vs  $V_{GS}$ ) were simulated.

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<sup>1</sup>Device Simulations were done by other students in the group, but are included for completeness



**Figure 7.5.** 3D structure of N<sup>3</sup>ASICs device (2C-xnwFET)

**Table 7.1.** Device simulation parameters for 2C-xnwFET

Parameter	Value
Gate Material	Metal
Gate Workfunction(eV)	4.6
Channel Doping (cm <sup>-3</sup> )	10 <sup>18</sup>
Gate Oxide Material	HfO <sub>2</sub>
Gate oxide thickness (nm)	3
Bottom oxide material	SiO <sub>2</sub>
Bottom oxide thickness (nm)	10
Back Gate bias (V)	-3
Source/Drain doping (cm <sup>-3</sup> )	10 <sup>20</sup>

**Table 7.2.** 2C-xnwFET Device simulation results

Parameter	N <sup>3</sup> ASICs-16 2C-xnwFET
$V_{TH}$	0.27
$I_{ON}$	39.6 $\mu$ A
$I_{ON}/I_{OFF}$	26218

On-current ( $I_{ON}$ ) and on/off ( $I_{ON}/I_{OFF}$ ) current ratio were extracted. Fig. 7.5B shows the  $I_{DS}$ - $V_{DS}$  curve for different  $V_{GS}$  values. These simulations verify inversion mode behavior for 2C-xnwFETs with a positive threshold voltage.

Table 7.2 shows key device simulation results for N<sup>3</sup>ASICs-16 2C-xnwFET. With a high on current,  $V_{TH} > 0.2$ , and  $I_{ON}/I_{OFF} > 10^4$  the devices meet circuit requirements for correct functionality and noise.

#### 7.4.2 Circuit and System Evaluation

Detailed system level evaluations were carried out using WISP-0 nanoprocessor as the test case. 16nm CMOS equivalent of WISP-0 was developed in order to compare the area, power and performance. NASICs are 22 $\times$  and N<sup>3</sup>ASICs are 3 $\times$  denser than 16nm CMOS equivalent design. It was seen that both fabrics are able to achieve comparable performance at 30 $\times$  and 5 $\times$  lower power consumption. The density advantage is due to the dense nanowire array at the bottom (implying the use of devices with smaller dimensions when compared to conventional CMOS FETs), use of single type FET to realize logic, implicit latching on the nanowires (which ensures that there is no need for area expensive latches and flip-flops) and finally reduced transistor count compared to CMOS.

N<sup>3</sup>ASICs trades-off some density benefits, since CMOS design rules are used for pitch and spacing, but achieves ease-of-manufacturability. As the nanowire layer conforms to CMOS design rules, the spacing between the nanowires is greater compared to a 2-D grid based NASIC fabric. The use of design rules, while alleviating manufac-

**Table 7.3.** Comparison of key system-level metrics for WISP-0

	Area( $\mu\text{m}^2$ )	Performance(GHz)	Power( $\mu\text{W}$ )
CMOS Baseline(16nm)	66.24	6.25	77.90
NASICs	2.90	4.66	2.60
N <sup>3</sup> ASICs-16	22	6.32	14.36
Relative Improvement	22x,3x	0.75x,1x	30x,5.42x

turing requirements, reduces the density advantage of N<sup>3</sup>ASICs to 3X. The evaluation results are summarized in the table.

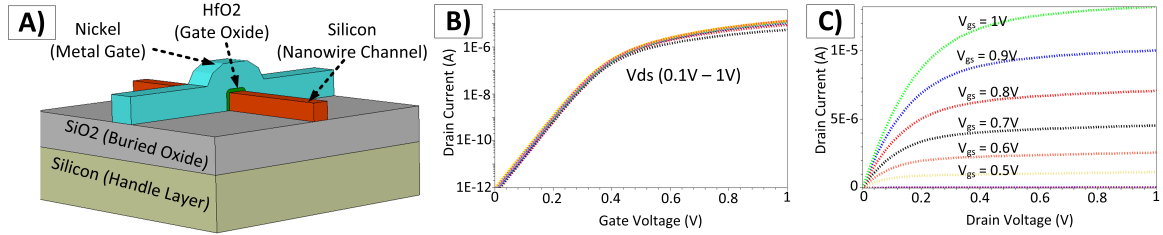
Power and performance comparisons are shown in Table 7.3. We notice that the performance of N<sup>3</sup>ASICs-16 is comparable to that of 16nm CMOS equivalent WISP-0. These simulations do not consider key optimizations for xnwFETs and 2C-xnwFETs making comparisons pessimistic. For example, while the PTM models employ strained silicon, no straining was assumed for nanowire FETs. It is expected that a better mobility and hence better performance could be obtained when straining techniques are employed in NASICs and N<sup>3</sup>ASICs.

## 7.5 Reducing Doping Requirements with Metal-Gated Junctionless xnwFETs

Both conventional inversion-mode CMOS devices and 2C-xnwFETs for N<sup>3</sup>ASICs require ultra-sharp source-channel and drain-channel junction with dopant concentrations changing several orders of magnitude within a span of 1nm-2nm. Achieving this requires extremely precise control of spacer techniques and high temperature annealing processes. Design choices can further be optimized to eliminate this requirement in N<sup>3</sup>ASICs. In this section, we propose and describe Metal-gated Junctionless Nanowire FETs (MJNFETs) that are fully compatible with the N<sup>3</sup>ASICs fabric and provide significantly reduced manufacturing complexity.

The device structure is shown in Fig. 7.6A. It consists of a uniformly doped channel nanowire without drain- or source- junctions, a high- $\kappa$  dielectric material, and an orthogonal metal gate. This junctionless channel scheme considerably simplifies manufacturing by eliminating complex fabrication steps such as ultra-low energy impurity implantation, and high thermal budget defect annihilation/dopant incorporation for achieving extremely sharp lateral doping abruptness both of which are increasingly prohibitive especially for non-planar semiconductor nanostructures. The principle of operation is not based on inversion but on accumulation/depletion. Channel depletion is induced by work-function difference between the metal gate and the doped channel.  $n+$  Silicon channels can be depleted by metals with higher work-function than the Si-channel (e.g. Nickel), whereas  $p+$  channels are depleted by materials with lower workfunction (e.g. Titanium). Given the nanoscale dimensions of the channel cross-section, the channel region can be completely depleted of carriers at zero gate voltage, leading to normally OFF devices (necessary for cascading in NASICs and N<sup>3</sup>ASICs). Applying a voltage bias on the metal gate eliminates the work-function difference, turning ON the device.

MJNFET device behavior was validated through detailed 3-D Synopsys Sentaurus process and device simulations (Fig. 7.6B, C). For an  $n+$  device with 16nm (gate length)  $\times$  10nm (channel width)  $\times$  10nm (channel thickness) dimensions, HfO<sub>2</sub> gate dielectric with 2nm thickness, and channel doping of  $2 \times 10^{19}$  dopants/cm<sup>3</sup>) a threshold voltage of  $\sim 0.3$ V is achieved. Above the threshold voltage a conducting path is established and the device is considered ON. Accumulation increases up to the flat-band condition, when the channel concentration reaches the initial doping concentration. ON-current for this device was found to be  $14\mu\text{A}$ .



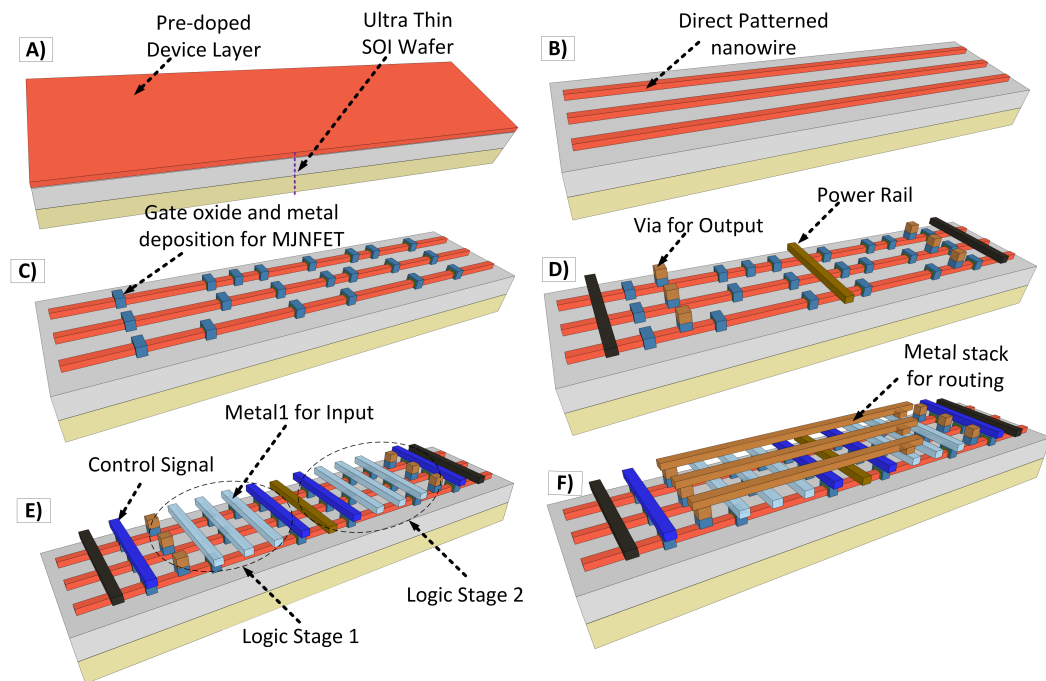
**Figure 7.6.** Metal-gated Junctionless Nanowire FET (MJNFET) A) Structure, B) Simulated  $I_{DS} - V_{GS}$  (log) plot C) Simulated  $I_{DS} - V_{DS}$  curve for different  $V_{GS}$  showing linear and saturation regimes of operation

## 7.6 Assembly Sequence for N<sup>3</sup>ASICs with MJNFETs

Fig. 7.7 shows the layer-by-layer assembly sequence for N<sup>3</sup>ASICs with MJNFETs. Similar to the enhancement-mode device, the unconventional patterning step is carried out *a priori* to all lithographic steps. However, a key distinction is the doping requirement mitigation. Given that the circuit-style uses single-type FETs, and that individual devices do not have complex or dissimilar doping profiles the only doping step required is a single initial wafer-wide doping before any patterning. Functionalization of MJNFET crosspoints is achieved by depositing metal gates with the appropriate workfunction to achieve channel depletion in the required channel segments without additional alignment/processing. Self-aligned ion-implantation or lateral doping abruptness across the nanowire length are not needed.

## 7.7 Chapter Summary

A 3-D integrated nanofabric N<sup>3</sup>ASICs was presented. A physical fabric vision was developed to enable the self-assembly/unconventional manufacturing approach and conventional photolithography, to be employed in conjunction while retaining the benefits of both the approaches. To facilitate the use of photolithography CMOS design rules were followed at all levels. No special manufacturing constraints were introduced. A detailed layer-by-layer assembly sequence of the fabric was presented.



**Figure 7.7.** Assembly Sequence for  $N^3$ ASICs fabric with MJNFETs: A) SOI wafer with wafer-wide top Silicon doping, B) Direct patterning of nanowires, C) MJNFET creation by gate oxide + gate metal deposition, D) Power rail and via placement, E) Metal1 for gate inputs and control signals, F) M2 for routing.



Fabric evaluations were carried out at device, circuit and system levels. A nanoprocessor implemented using the proposed N<sup>3</sup>ASIC fabric was shown to be 3X denser than equivalent CMOS design and 5X power efficient for a comparable performance. Systematic yield implications due to mask overlay misalignment were analyzed. Results show that a yield of 100% was obtained with an overlay misalignment of  $3\sigma = \pm 8\text{nm}$  (manufacturing solutions known and optimized). A yield of 83% was obtained even for a pessimistic overlay misalignment of  $3\sigma = \pm 16\text{nm}$ .

Junctionless xnwFETs with Metal-gates were discussed to further reduce manufacturing requirements by eliminating complex doping profiles and high thermal budgets. Sentaurus simulations show these devices to have the requisite I-V characteristics to be made functional in NASIC and N<sup>3</sup>ASICs circuits. An assembly sequence for N<sup>3</sup>ASICs was developed with these MJNFETs, where the only doping requirements is an initial wafer-wide doping step of the top silicon.

## CHAPTER 8

### EXPERIMENTAL PROTOTYPE DEVELOPMENT

A comprehensive theoretical framework for nanowire fabrics spanning device characteristics, circuit behavior, architecture, fault-tolerance and assembly sequences was explored. Through careful design choices at multiple levels, manufacturability requirements were mitigated. Building on these fabric-centric explorations, a new research effort was undertaken with the goal being to experimentally validate core fabric concepts and demonstrate MJNSET devices and N<sup>3</sup>ASICs prototype at sub-35nm dimensions in Cleanroom settings.

#### 8.1 Fabrication - Preliminaries

The starting material for prototyping is a Silicon Implanted Oxide (SIMOX) Silicon-on-Insulator (SOI) wafer. The SOI has a 100nm top Silicon and 378nm buried oxide layer. The initial doping is p-type  $10^{15}$  *dopants/cm*<sup>3</sup>. A wafer-wide ion implantation step is used to increase the doping to achieve conducting channels with sufficient on-currents. For the purpose of prototyping, all patterning steps are done with Electron-Beam Lithography (EBL), which can achieve the requisite nanowire channel and gate dimensions. EBL steps can be replaced by unconventional patterning or photolithography steps to achieve scalable manufacturing of the fabric with assembly sequences shown in previous chapters. Standard processing steps such as Evaporation, Reactive Ion Etch (RIE), Wet Chemical Etches, Atomic Layer Deposition (ALD), Sputtering etc. are used. Where appropriate, process simulations are used to determine critical process parameters for experiments.

The key milestones for this effort are:

- Demonstrate successful ion implantation of top SOI substrate
- Develop end-to-end process flow for the N<sup>3</sup>ASIC fabric and optimize individual process steps
- Demonstrate individual conducting nanowires after EBL patterning and RIE pattern transfer
- Show MJN<sup>3</sup>FET devices that are normally OFF (fully depleted at zero gate bias - required for cascading) with appropriate choice of gate material, gate oxide and device dimensions
- Demonstrate small-scale N<sup>3</sup>ASICs tile

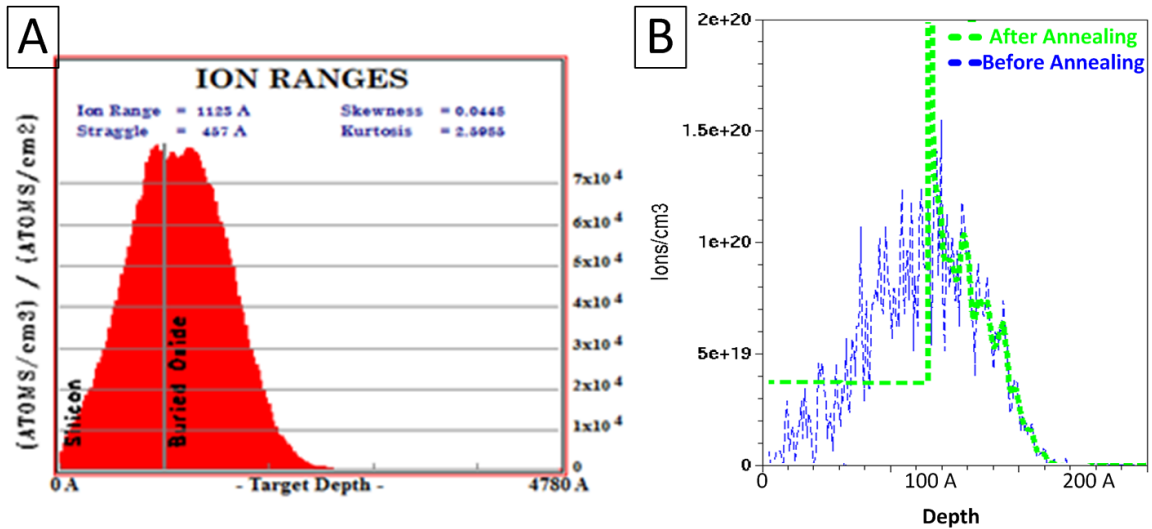
## 8.2 Ion Implantation of SOI Wafers

Ion implantation is required to achieve sufficiently high doping concentration that can ensure high on-currents as well as high conductivity drain and source regions in junctionless xnwFET devices. This is a two step process: the first step is the dopant implant, which is followed by thermal annealing to diffuse and activate the dopants in the lattice.

A combination of two simulation tools (SRIM and Sentaurus Process) is used to simulate process characteristics and extract process parameters. SRIM (Stopping Range of Ions in Matter) [63] simulations are used to extract ion implantation parameters such as acceleration voltage and implant dosage. Sentaurus Process [4] is used to determine annealing temperature and annealing time.

SRIM Simulations are carried out for an SOI wafer with 100nm thick top device layer (Si), 378nm middle buried oxide(SiO<sub>2</sub>) layer and and 500um bottom handle layer (Si). The acceleartion voltage (28 keV) used in SRIM simulations is obtained

from stopping range table for Boron dopants and silicon substrate. Ion implantation process is modeled using Monte Carlo (TRIM) simulation model. Fig. 8.1A shows Ion ( $B^+$ ) distribution plot obtained. Ion implantation parameters (acceleration voltage 28 keV, implant dosage  $10^{14} atoms/cm^2$ ) obtained from SRIM are used in Sentaurus Process [4] simulations to implant the SOI substrate. Diffusion and activation processes are modeled using Charged Cluster model. Simulations show that Ion-implanted substrates, if annealed at  $1000^\circ C$ , for 60 minutes in  $N_2$  ambient will diffuse and activate dopants. Fig. 8.1B shows process simulation with uniform dopant distribution in the top silicon layer after annealing.



**Figure 8.1.** Simulations for Ion Implantation A) SRIM simulation plot showing ion distribution in SOI wafer for 28keV implant B) Sentaurus process simulation plot showing ion distribution in SOI wafer before and after thermal annealing at  $1000^\circ C$ .

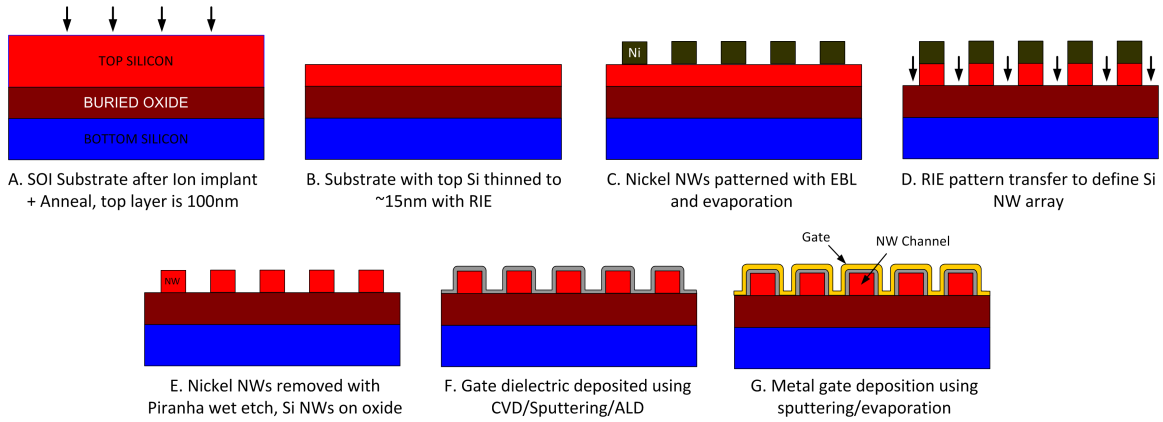
Process simulations were also used to construct the targeted junctionless xnwFET structure. Combined with device-level simulations of charge transport, this approach helps identify several key parameters including gate oxide thickness, impact of different gate oxide materials, metal gate workfunction to achieve normally OFF devices, impact of channel/gate geometry on device characteristics etc.

### 8.3 Experimental Process Flow

An end-to-end process flow for small-scale fabric prototype was developed and individual steps optimized. This pathway is based on direct patterning of silicon nanowires from Silicon-on-Insulator (SOI) substrates with thin top silicon layers using Electron-Beam Lithography (EBL). As previously mentioned, a key feature of the fabric is that given an initial SOI wafer with the correct doping concentration, no additional doping steps are necessary for realizing individual devices and functional blocks. A scalable pathway for integrated systems can be envisioned along the same lines as this prototyping approach, but using parallel processes for assembly and functionalization.

The prototyping approach is shown schematically in Fig. 8.2. The starting material is an SOI wafer where the top device layer is uniformly doped with  $p+$  dopants. The ion implantation and annealing steps for uniform doping of Si device layer were carried out using simulated process parameters (Acceleration voltage: 28keV, Area dosage:  $10^{14}$  dopants/cm<sup>2</sup>, Implant tilt: 7 degrees, Annealing Temperature: 1000°C, Annealing Duration: 60min, Annealing Ambient: N<sub>2</sub>). The substrate was thinned down to 15nm with anisotropic RIE using SF<sub>6</sub> + CHF<sub>3</sub> etch recipe (Fig. 8.2B). Using EBL and PMMA resist, sub-30nm features are patterned and a Nickel evaporation and liftoff step is used to define Ni features on top of the substrate (Fig. 8.2C). The Ni features act as an etch mask for defining nanowires on the SOI. Anisotropic RIE using SF<sub>6</sub> + CHF<sub>3</sub> mixture is used to etch the surrounding Si, followed by Piranha (3:1 H<sub>2</sub>SO<sub>4</sub>:H<sub>2</sub>O<sub>2</sub>) treatment to remove Ni etch mask. This leaves Silicon nanowires directly patterned on the SOI substrate (Fig. 8.2D and E). Nanowires at widths as small as 30nm, 20nm and 15nm have been successfully demonstrated using this approach. Smaller dimensions imply better depletion, leading to normally off devices with higher on/off current ratios. Atomic layer deposition technique is used for Hafnium oxide (HfO<sub>2</sub>) deposition (Fig. 8.2F), followed by alignment, patterning, evaporation and

liftoff to define metal gate nanowires (Fig. 8.2G). Additional details are presented below.



**Figure 8.2.** End-to-end prototyping process flow for N<sup>3</sup>ASICs fabric

### 8.3.1 Electron Beam Lithography

EBL is used for all patterning steps including defining contacts and alignment markers, patterning nanowires and orthogonal gates. For all steps a positive resist process is used with Poly-Methyl-MethAcrylate (PMMA), with a commercially available formulation in Anisole designated A2. The resist has excellent adhesion to Silicon and fairly low thicknesses (less than 60nm) are achievable for small feature sizes. Exposure to an electron-beam causes breakdown of polymer chains in PMMA, which can be dissolved in a ketone developer solution (Methyl Iso-Butyl Ketone, MIBK). Alignment routines available as part of the patterning system are used for locating previously defined features (e.g. in the creation of metal gates over previously defined channels).

### 8.3.2 Reactive Ion Etch

RIE steps are used in two steps of the process flow: i) to thin down the top silicon layer from 100nm to ~20nm and ii) to transfer EBL-defined nanowire patterns to the

substrate to achieve Silicon nanowires. The recipe used to etch Silicon is adapted from [6]. A combination of  $\text{SF}_6$  and  $\text{CHF}_3$  gases is used.  $\text{SF}_6$  achieves the actual etching of Silicon; however the process is isotropic. To improve the anisotropy,  $\text{CHF}_3$  is used. Radicals from this gas ensure passivation of any exposed Silicon sidewalls, ensuring that the process is entirely top-down from any exposed Silicon surfaces. This ensures smooth thinning of the Silicon substrate in Fig. 8.2B as well as successful pattern transfer in Fig. 8.2D. Nickel is used as a metal etch mask since it is completely unreactive to this gas mixture, and can be easily removed using a piranha wet-etch process that does not affect the substrate, channel or contacts/markers.

### 8.3.3 Oxide Deposition

Silicon dioxide, Aluminum oxide and Hafnium dioxide were considered as possible gate oxide materials. Silicon oxide was deposited using a standard PECVD process with Silane gas and Oxygen, Aluminum oxide was sputtered, and Hafnium oxide was deposited using ALD. The former two approaches were found to be unsuitable for MJNFETs: Dielectric constants were lower than  $\text{HfO}_2$  to begin with, and oxide thicknesses could not be controlled to atomic precision. Characterization of FET structures showed poor gate control, with dielectric breakdown occurring well before full channel depletion. ALD  $\text{HfO}_2$  process at  $150^\circ\text{C}$  was optimized to achieve thicknesses between 1nm to 2nm. Characterization of oxide thickness was done using ellipsometry.

### 8.3.4 I-V Measurements

I-V Measurements are done at various stages of the process flow. 4-pt probe measurements of the substrate are used for determining if it has been successfully doped and dopants activated. 2-pt probe measurements are done after nanowire patterning to determine if patterned nanowires conduct. 3-pt FET characterization is done after creating MJNFET structures to determine  $I_D - V_{GS}$  and  $I_D - V_{DS}$

characteristics. A Keithley 4200 Semiconductor Parametric Analyzer was used for these experiments.

## 8.4 Experimental Results

The aforementioned process steps and process simulations were used in fabricating xnwFET structures and logic stage of the nanowire fabric. Extensive metrology was done after each process step to verify expected results. Four point probe measurements were carried out to determine doping concentration in Silicon substrate after ion implantation. This was found to be  $\sim 8 \times 10^{18} \text{dopants/cm}^3$  which is almost equal to targeted concentration from simulations ( $10^{19} \text{dopants/cm}^3$ ).

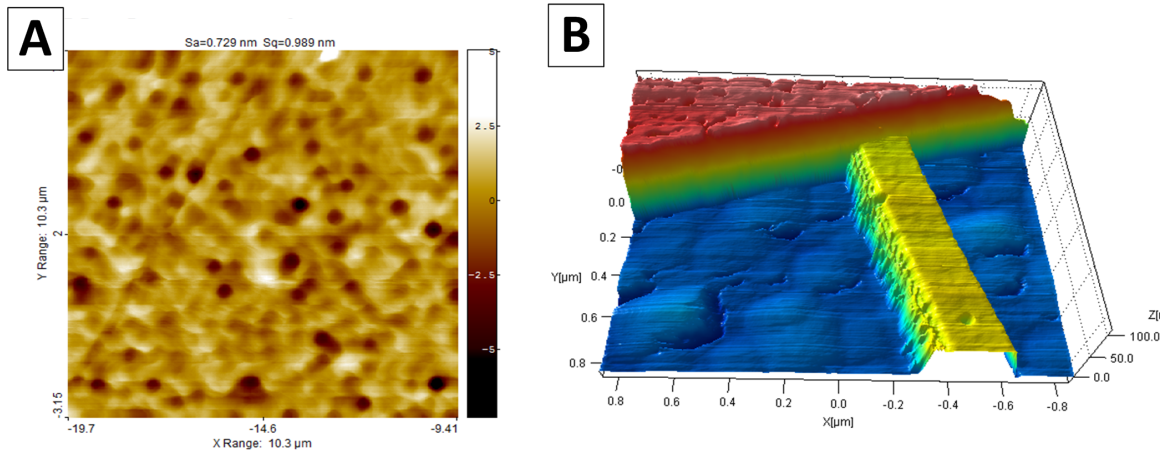
Atomic Force Microscopy (AFM) measurements were done to determine surface roughness and Silicon thickness after RIE substrate thinning and pattern transfer steps. As shown in Fig.4A (left), a thinned Silicon substrate has less than 1nm root-sum-squared variation in surface roughness after anisotropic etching of top SOI layer from 100nm to 15nm. Fig.4A (right) shows AFM image of 15nm thick patterned Silicon nanowire on top of SiO<sub>2</sub> buried oxide.

I-V measurements were carried out on individual junctionless xnwFETs to characterize electrical properties. In order to determine on current and contact resistivity in junctionless xnwFETs, two point probe I-V measurements were done on nanowire channels, which were patterned in between source and drain contacts. Excellent Ohmic behavior was achieved through these nanowires (contact metal stack: 5nm Ti + 30nm Au) since the substrate from which they are patterned was heavily doped.

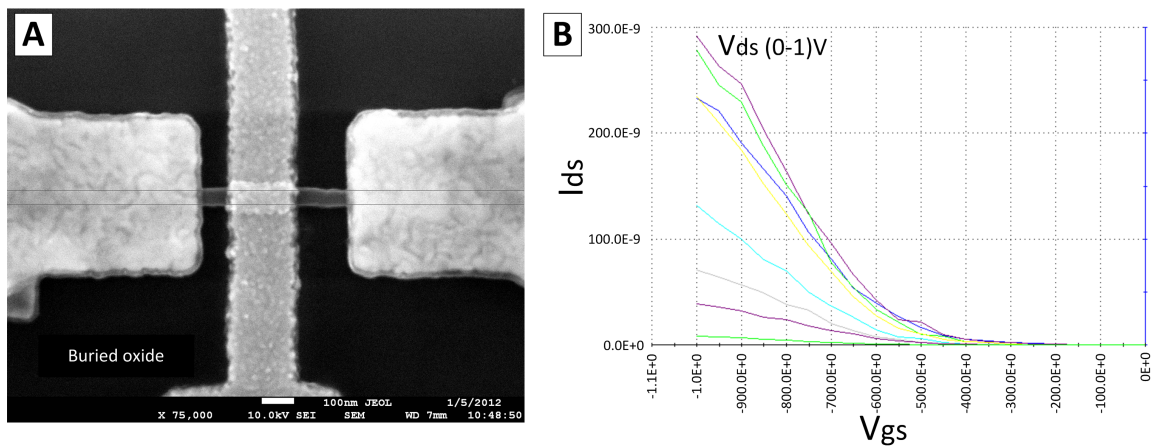
Ellipsiometry measurements were done to determine HfO<sub>2</sub> thickness after atomic layer deposition at 150° C. We were able to deposit and measure HfO<sub>2</sub> films down to 1nm, and the thickness was found to be uniform across the die.

Three point probe measurements were done on junctionless xnwFETs. Dimensions for fabricated devices were 30nm wide and 15nm thick nanowire channel, 1.2nm





**Figure 8.3.** AFM Images post-RIE A) Successful thinning of top Silicon to  $\sim 15\text{nm}$  with less than 1nm RMS deviation in surface roughness B) Successful pattern transfer to Si followed by Nickel removal, showing anisotropic profile and smooth top surface.



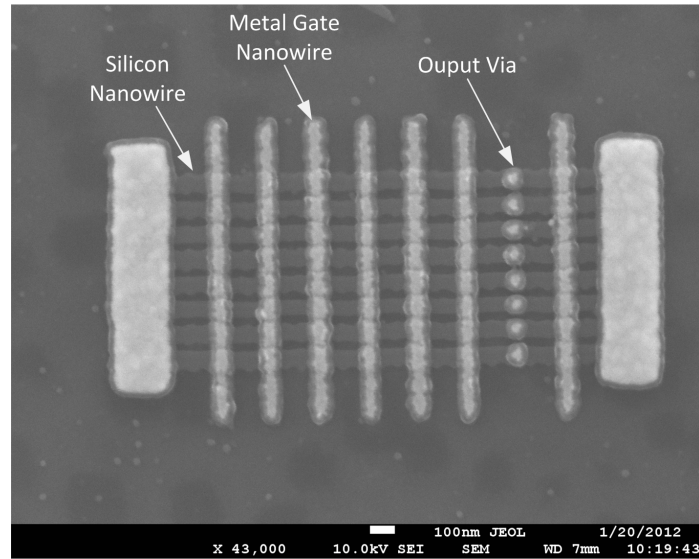
**Figure 8.4.** Experimental MJNFET Device Characterization: A) Fabricated Device Structure and B)  $I_{DS} - V_{GS}$  characteristics for normally off MJNFETs.

thick  $\text{HfO}_2$  gate dielectric, 200nm long gate and 50nm thick gate metal stack. A stack of 35nm Titanium layer and 15nm thick Gold layer served as gate metal stack; Titanium provides the necessary work-function difference for depleting  $p+$  doped Silicon channel, and Gold is used for reducing the series resistance of the gate. Fig. 8.4 shows  $I_{DS} - V_{GS}$  characteristics of  $p$ -type junctionless xnwFETs when a metal gate stack was put on top of silicon nanowire channel. The  $I_{DS} - V_{GS}$  characteristics in Fig. 8.4 accurately depicts junctionless device characteristics, where the workfunction difference between Titanium/Au gate and  $p+$  doped Silicon nanowire channel depletes the channel and the device is normally OFF at 0V  $V_{gs}$ . As the negative gate voltages ( $V_{GS} < 0$ ) are applied, the carriers are accumulated and the channel conducts. These devices have an  $I_{ON}/I_{OFF} > 10^3$  and threshold voltage  $\sim -0.3V$ . These characteristics imply that MJNFET devices can be made functional in NASIC and  $N^3$ ASICs circuits, with sufficient noise margins and cascading capability.

We have also demonstrated a single logic stage of the nanowire fabric. As shown in Fig. 8.5, nanowire grid with functional cross-points was fabricated using the process flow described before. The bottom (horizontal) Si nanowires in the grid were 30nm wide, 15nm thick and 100nm apart from each other; the top metal nanowires (vertical) were 30nm wide, 50nm thick and 200nm spaced; Vias were placed at output of each horizontal nanowires. While demonstration of a fully functional  $N^3$ ASICs fabric will require further effort, this work shows feasibility of the approach and validates the process flow.

## 8.5 Chapter Summary

A prototyping process flow for demonstration of  $N^3$ ASICs was presented. This process flow uses EBL steps for patterning in conjunction with standard semiconductor processing steps including ion implant, RIE, evaporation etc. No special manufacturing requirements exist. The experimental approach was supported by process



**Figure 8.5.** Fabricated N<sup>3</sup>ASiCs Tile

simulations to determine key parameters for fabrication (e.g. ion implant dosage, annealing time/temperature etc). Key milestones such as successful ion implantation, optimization of individual process steps, successful nanowire pattern transfer, and demonstration of requisite MJNFET behavior with normally OFF *p*-type devices ( $V_{TH} \sim -0.3V$ ) and three orders of magnitude ON/OFF current ratios were achieved. An N<sup>3</sup>ASiCs tile was also demonstrated. Further optimization of process and devices will enable a fully functional prototype.

## CHAPTER 9

### CONCLUSIONS

A fabric-centric approach towards building integrated nanosystems was presented. Through careful design choices across device, circuit and architecture levels manufacturing requirements are reduced - regular arrays with limited customization imply mitigated overlay precision requirements, novel circuit styles eliminate the need for arbitrary fine-grain sizing and complementary doping, simple device structures are used and device optimizations are done in a fabric-friendly manner. The fabric is validated through an integrated bottom-up methodology with careful consideration to physical layer assumptions and their implications for noise and parameter variation at circuit and system levels. It is shown to have  $22\times$  density benefit and  $30\times$  power benefit vs. CMOS for improved overlay imprecision tolerance ( $3\sigma = \pm 5.7nm$ ).

A new 3D integrated fabric, N<sup>3</sup>ASICs, was proposed that combines unconventional manufacturing with lithography and design rules for reduced manufacturing requirements vs. scaled CMOS. This fabric achieves 3X area, 5X power at comparable performance vs. 16nm CMOS for a processor design. Furthermore, these benefits may be achieved with overlay imprecision of  $\pm 8nm$ , for which manufacturing solutions are known today (vs.  $\pm 3nm$  for 16nm CMOS, manufacturing solutions unknown).

Experimental efforts towards building an N<sup>3</sup>ASICs prototype were discussed. An end-to-end process flow was developed and individual steps optimized. Successful doping of SOI substrates, pattern transfer to create nanowires at dimensions between 15nm to 30nm, and metal-gated junctionless nanowire FET structures were demonstrated. I-V characterization of MJNFET devices show normally OFF behav-

ior (through gate channel workfunction difference) and three orders of magnitude on/off current ratios, implying that these devices meet circuit requirements for cascading and noise, as per circuit evaluations. N<sup>3</sup>ASICs tiles with MJNFETs at the crosspoints were also demonstrated. Thus through a combination of fabric design, theoretical exploration and cleanroom fabrication, new nano-fabrics were developed and shown to achieve the concurrent objectives of improved system-level benefits and improved manufacturability.

## APPENDIX

### LIST OF PUBLICATIONS

C. A. Moritz, **P. Narayanan** and C. O. Chui, “Nanoscale Application Specific Integrated Circuits,” *Book chapter for Nanoelectronic Circuit Design (Eds. Niraj Jha and Deming Chen)*, Springer 2011.

**P. Narayanan**, J. Kina, P. Panchapakeshan, C. O. Chui and C. A. Moritz, “Integrated Device-Fabric Explorations and Noise Mitigation in Nanoscale Fabrics,” *IEEE Transactions on Nanotechnology*, vol. 11, no. 4, pp. 687-700, 2012.

**P. Narayanan**, M. Leuchtenburg, J. Kina, P. Joshi, P. Panchapakeshan, C. O. Chui and C. A. Moritz, “Variability in Nanoscale Fabrics: Bottom-up Integrated Analysis and Mitigation,” *Accepted for publication by ACM Journal on Emerging Technologies in Computing Systems, 2013*.

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Y. Guo, **P. Narayanan**, M. A. Bennisser, S. Chheda and C. A. Moritz, “Energy-Efficient Hardware Data Prefetching,” *IEEE Trans. on VLSI*, vol. 19, no. 2, pp. 250-263, 2011.

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**P. Narayanan**, P. Panchapakeshan, J. Kina, C. O. Chui and C. A. Moritz, ”Integrated Nanosystems with Junctionless Crossed Nanowire Transistors”, *IEEE International Conference on Nanotechnology (IEEE NANO 2011)*, pp.845-848, 2011.

P. Panchapakeshan, P. Vijayakumar, **P. Narayanan**, C. O. Chui and C. A. Moritz, 3-D Integration Requirements for Hybrid Nanoscale-CMOS Fabrics, *IEEE International Conference on Nanotechnology (IEEE NANO 2011)*, pp.849-853, 2011.

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