

# ON SLICEWISE MONOTONE PARAMETERIZED PROBLEMS AND OPTIMAL PROOF SYSTEMS FOR TAUT

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**ABSTRACT.** For a reasonable sound and complete proof calculus for first-order logic consider the problem to decide, given a sentence  $\varphi$  of first-order logic and a natural number  $n$ , whether  $\varphi$  has no proof of length  $\leq n$ . We show that there is a nondeterministic algorithm accepting this problem which, for fixed  $\varphi$ , has running time bounded by a polynomial in  $n$  if and only if there is an optimal proof system for the set TAUT of tautologies of propositional logic. This equivalence is an instance of a general result linking the complexity of so-called slice-wise monotone parameterized problems with the existence of an optimal proof system for TAUT.

## 1. Introduction

In this paper we relate the existence of optimal proof systems for the class TAUT of tautologies of propositional logic with the complexity of slice-wise monotone parameterized problems. A *proof system* in the sense of Cook and Reckhow [4], say for the class TAUT, is a polynomial time computable function defined on  $\{0, 1\}^*$  and with TAUT as range. A proof system  $P$  is *optimal* if for any other proof system  $P'$  for TAUT there is a polynomial  $p \in \mathbb{N}[X]$  such that for every tautology  $\alpha$ , if  $\alpha$  has a proof of length  $n$  in  $P'$ , then  $\alpha$  has a proof of length  $\leq p(n)$  in  $P$ .<sup>1</sup> In their fundamental paper [9] Krajíček and Pudlák showed that an optimal proof system for TAUT exists if  $\text{NE} = \text{co-NE}$  and they derived a series of statements equivalent to the existence of such an optimal proof system; however they conjectured that there is no optimal proof system for TAUT.

On the other hand, Gödel in a letter to von Neumann of 1956 (see [6]) asked for the complexity of the problem to decide, given a sentence  $\varphi$  of first-order logic and a natural number  $n$ , whether  $\varphi$  has a proof of length  $\leq n$ . In our study [2] of this problem we introduced the parameterized problem

*p*-GÖDEL

*Instance:* A first-order sentence  $\varphi$  and  $n \in \mathbb{N}$  in unary.

*Parameter:*  $|\varphi|$ .

*Problem:* Does  $\varphi$  have a proof of length  $\leq n$ ?

<sup>1</sup>All notions will be defined in a precise manner in later sections.

Here we refer to any reasonable sound and complete proof calculus for first-order logic. We do not allow proof calculi, which, for example, admit all first-order instances of propositional tautologies as axioms (as then it would be difficult to recognize correct proofs if  $P \neq NP$ ).

In a different context, namely when trying to show that a certain logic  $L_{\leq}$  for PTIME (introduced in [7]) does not satisfy some effectivity condition, Nash et al. introduced implicitly [12] (and this was done explicitly in [1]) the *parameterized acceptance problem*  $p\text{-ACC}_{\leq}$  for nondeterministic Turing machines:

$p\text{-ACC}_{\leq}$ <i>Instance:</i> A nondeterministic Turing machine $M$ and $n \in \mathbb{N}$ in unary. <i>Parameter:</i> $\ M\ $ , the size of $M$ . <i>Problem:</i> Does $M$ accept the empty input tape in $\leq n$ steps?
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Both problems,  $p\text{-GÖDEL}$  and  $p\text{-ACC}_{\leq}$ , are *slicewise monotone*, that is, their instances have the form  $(x, n)$ , where  $x \in \{0, 1\}^*$  and  $n \in \mathbb{N}$  is given in unary,<sup>2</sup> the parameter is  $|x|$ , and finally for all  $x \in \{0, 1\}^*$  and  $n, n' \in \mathbb{N}$  we have

if  $(x, n)$  is a positive instance and  $n < n'$ , then  $(x, n')$  is a positive instance.

A slicewise monotone problem is in the complexity class  $\text{XNP}_{\text{uni}}$  if there is a nondeterministic algorithm that accepts it in time  $n^{f(|x|)}$  for some function  $f: \mathbb{N} \rightarrow \mathbb{N}$ . And  $\text{co-XNP}_{\text{uni}}$  contains the complements of problems in  $\text{XNP}_{\text{uni}}$ . We show:

**Theorem 1.** *TAUT has an optimal proof system if and only if every slicewise monotone problem in NP is in  $\text{co-XNP}_{\text{uni}}$ .*

There are trivial slicewise monotone problems which are fixed-parameter tractable. However, for the slicewise monotone problems mentioned above we can show:

**Theorem 2.**  $\text{TAUT has an optimal proof system} \iff p\text{-ACC}_{\leq} \in \text{co-XNP}_{\text{uni}}$   
 $\iff p\text{-GÖDEL} \in \text{co-XNP}_{\text{uni}}$ .

In [3] we showed that TAUT has a *p-optimal* proof system if and only if a certain logic  $L_{\leq}$  is a P-bounded logic for P (=PTIME). The equivalence in the first line of Theorem 2 is the nondeterministic version of this result; in fact, an immediate consequence of it states that TAUT has an optimal proof system if and only if  $L_{\leq}$  is an NP-bounded logic for P (a concept that we will introduce in Section 6). It turns out that a slight variant of  $L_{\leq}$  is an NP-bounded logic for P (without any assumption).

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<sup>2</sup>The requirement that  $n$  is given in unary notation ensures that the classical complexity of most slicewise monotone problems we consider is in NP.

The content of the different sections is the following. In Section 2 and Section 3 we recall the concepts and results of parameterized complexity and on optimal proof systems, respectively, we need in Section 4 to derive the equivalence in the first line of Theorem 2. Furthermore, in Section 3 we claim that every problem hard for EEXP under polynomial time reductions has no optimal proof system. In Section 5 we derive some basic properties of slicewise monotone problems, show that  $p\text{-ACC}_{\leq}$  is of highest parameterized complexity among the slicewise monotone problems with classical complexity in NP, and finally show that all the slicewise monotone problems we consider in a certain sense have the same complexity (see Proposition 14 for the precise statement). This yields Theorem 1 and the remaining equivalence of Theorem 2. As already mentioned, in Section 6 we analyze the relationship of the existence of an optimal proof system for TAUT and the properties of the logic  $L_{\leq}$ .

## 2. Some preliminaries

In this section we recall some basic definitions and concepts from parameterized complexity and introduce the concept of slicewise monotone parameterized problem.

We denote the alphabet  $\{0, 1\}$  by  $\Sigma$ . The length of a string  $x \in \Sigma^*$  is denoted by  $|x|$ . We identify problems with subsets  $Q$  of  $\Sigma^*$ . Clearly, as done mostly, we present concrete problems in a verbal, hence uncodified form or by using other alphabets. We denote by  $P$  the class of problems  $Q$  such that  $x \in Q$  is solvable in time polynomial in  $|x|$ .

All deterministic and nondeterministic Turing machines have  $\Sigma$  as their alphabet. If necessary we will not distinguish between a Turing machine and its code, a string in  $\Sigma^*$ . If  $M$  is a Turing machine we denote by  $\|M\|$  the length of its code.

Sometimes statements containing a formulation like “there is a  $d \in \mathbb{N}$  such that for all  $x \in \Sigma^*$ :  $\dots \leq |x|^d$ ” can be wrong for  $x \in \Sigma^*$  with  $|x| \leq 1$ . We trust the reader’s common sense to interpret such statements reasonably.

If  $A$  is any (deterministic or nondeterministic) algorithm and  $A$  accepts  $x$ , then we denote by  $t_A(x)$  the number of steps of a shortest accepting run of  $A$  on  $x$ ; if  $A$  does not accept  $x$ , then  $t_A(x)$  is not defined.

**2.1. Parameterized complexity.** We view *parameterized problems* as pairs  $(Q, \kappa)$  consisting of a classical problem  $Q \subseteq \Sigma^*$  and a *parameterization*  $\kappa: \Sigma^* \rightarrow \mathbb{N}$ , which is required to be polynomial time computable. We will present parameterized problems in the form we did it for  $p\text{-GÖDEL}$  and  $p\text{-ACC}_{\leq}$  in the Introduction.

A parameterized problem  $(Q, \kappa)$  is *fixed-parameter tractable* (or, in FPT) if  $x \in Q$  is solvable by an *fpt-algorithm*, that is, by a deterministic algorithm running in time  $f(\kappa(x)) \cdot |x|^{O(1)}$  for some computable  $f: \mathbb{N} \rightarrow \mathbb{N}$ .

Let  $C$  be a complexity class of classical complexity theory defined in terms of deterministic (nondeterministic) algorithms. A parameterized problem  $(Q, \kappa)$  is in the class  $\text{XC}_{\text{uni}}$  if there is a deterministic (nondeterministic) algorithm deciding (accepting)  $Q$  and witnessing for every  $k \in \mathbb{N}$  that the classical problem

$$(Q, \kappa)_k := \{x \in Q \mid \kappa(x) = k\},$$

the  $k$ th *slice* of  $(Q, \kappa)$ , is in  $C$ . For example,  $(Q, \kappa)$  is in the class  $\text{XP}_{\text{uni}}$  if there is a deterministic algorithm  $\mathbb{A}$  deciding  $x \in Q$  in time  $|x|^{f(\kappa(x))}$  for some function  $f: \mathbb{N} \rightarrow \mathbb{N}$ . And  $(Q, \kappa)$  is in the class  $\text{XNP}_{\text{uni}}$  if there is a nondeterministic algorithm  $\mathbb{A}$  accepting  $Q$  such that for some function  $f: \mathbb{N} \rightarrow \mathbb{N}$  we have  $t_{\mathbb{A}}(x) \leq |x|^{f(\kappa(x))}$  for all  $x \in Q$ . Finally, a parameterized problem  $(Q, \kappa)$  is in the class  $\text{co-XC}_{\text{uni}}$  if its complement  $(\Sigma^* \setminus Q, \kappa)$  is in  $\text{XC}_{\text{uni}}$ .

We have added the subscript “uni” to the names of these classes to emphasize that they are classes of the so-called uniform parameterized complexity theory. If in the definition of  $\text{XP}_{\text{uni}}$  and  $\text{XNP}_{\text{uni}}$  we require the function  $f$  to be computable, then we get the corresponding classes of the strongly uniform theory. For example,  $\text{FPT}$  is a class of this theory.

A parameterized problem  $(Q, \kappa)$  is *slicewise monotone* if its instances have the form  $(x, n)$ , where  $x \in \Sigma^*$  and  $n \in \mathbb{N}$  is given in unary, if  $\kappa((x, n)) = |x|$ , and finally if the slices are monotone, that is, for all  $x \in \Sigma^*$  and  $n, n' \in \mathbb{N}$

$$(x, n) \in Q \text{ and } n < n' \text{ imply } (x, n') \in Q.$$

We already remarked that the problems  $p$ -GÖDEL and  $p$ -ACC $_{\leq}$  are slicewise monotone.

Clearly, every parameterized problem  $(Q, \kappa)$  with  $Q \in \text{NP}$  is in  $\text{XNP}_{\text{uni}}$ ; thus we can replace  $\text{co-XNP}_{\text{uni}}$  by  $\text{XNP}_{\text{uni}} \cap \text{co-XNP}_{\text{uni}}$  everywhere in Theorem 1 and Theorem 2.

### 3. Optimal proof systems

Let  $Q \subseteq \Sigma^*$  be a problem. A *proof system for  $Q$*  is a surjective function  $P: \Sigma^* \rightarrow Q$  computable in polynomial time. Then, if  $P(w) = x$ , we say that  $w$  is a  *$P$ -proof* of  $x$ . A proof system  $P$  for  $Q$  is *optimal* if for any other proof system  $P'$  for  $Q$  there is a polynomial  $p \in \mathbb{N}[X]$  such that for every  $x \in Q$ , if  $x$  has a  $P'$ -proof of length  $n$ , then  $x$  has a  $P$ -proof of length  $\leq p(n)$ . Hence, any  $P'$ -proof can be translated into a  $P$ -proof by a nondeterministic polynomial time algorithm.

The corresponding deterministic concept is the notion of  $p$ -optimality. The proof system  $P$  for  $Q$  is *polynomially optimal* or  *$p$ -optimal* if for every proof system  $P'$  for  $Q$  there is a polynomial time computable  $T: \Sigma^* \rightarrow \Sigma^*$  such that for all  $w' \in \Sigma^*$

$$P(T(w')) = P'(w').$$

We list some known results. Part (1) and (2) are immediate from the definitions.

- (1) Every  $p$ -optimal proof system is optimal.
- (2) Every nonempty  $Q \in \text{PTIME}$  has a  $p$ -optimal proof system, every nonempty  $Q \in \text{NP}$  has an optimal proof system.
- (3) ([8]) If  $Q$  is nonempty and  $Q \leq^p Q'$  (that is, if  $Q$  is polynomial time reducible to  $Q'$ ) and  $Q'$  has a (p-)optimal proof system, then  $Q$  has a (p-)optimal proof system too.
- (4) ([10]) Every  $Q$  hard for  $\text{EXP} = \text{DTIME}\left(2^{n^{O(1)}}\right)$  under polynomial time reductions has no p-optimal proof system.

It is not known whether there is a problem  $Q \notin \text{P}$  ( $Q \notin \text{NP}$ ) with a p-optimal (an optimal) proof system. As mentioned in the Introduction, Krajíček and Pudlák [9] conjectured that there is no optimal proof system for the set  $\text{TAUT}$  of tautologies.

Concerning (4) we did not find a corresponding result for optimal proof systems in the literature. We can show:

**Proposition 3.** *Every  $Q$  hard for  $\text{EEXP} = \text{DTIME}\left(2^{2^{n^{O(1)}}}\right)$  under polynomial time reductions has no optimal proof system.*

We do not need this result (and will prove it in the full version of the paper). However we state a consequence:

**Corollary 4.** *There is no optimal proof system for the set of valid sentences of first-order logic.*

### 3.1. Almost optimal algorithms and enumerations of P-easy subsets.

Let  $Q \subseteq \Sigma^*$  be a problem. A deterministic (nondeterministic) algorithm  $\mathbb{A}$  accepting  $Q$  is *almost optimal* or *optimal on positive instances of  $Q$*  if for every deterministic (nondeterministic) algorithm  $\mathbb{B}$  accepting  $Q$  there is a polynomial  $p \in \mathbb{N}[X]$  such that for all  $x \in Q$

$$t_{\mathbb{A}}(x) \leq p(t_{\mathbb{B}}(x) + |x|).$$

By definition a subset  $Q'$  of  $Q$  is *P-easy* if  $Q' \in \text{P}$ . An *enumeration of the P-easy subsets of  $Q$  by P-machines (by NP-machines)* is a computable function  $M: \mathbb{N} \rightarrow \Sigma^*$  such that

- (i) for every  $i \in \mathbb{N}$  the string  $M(i)$  is a deterministic (nondeterministic) Turing machine deciding (accepting) a P-easy subset of  $Q$  in polynomial time;
- (ii) for every P-easy subset  $Q'$  of  $Q$  there is an  $i \in \mathbb{N}$  such that  $M(i)$  decides (accepts)  $Q'$ .

If in the nondeterministic case instead of (i) we only require

- (i') for every  $i \in \mathbb{N}$  the string  $M(i)$  is a nondeterministic Turing machine accepting a subset of  $Q$  in polynomial time,

we obtain the notion of a *weak enumeration of P-easy subsets of  $Q$  by NP-machines*.

We denote by TAUT the class of all tautologies of propositional logic. We need the following theorem:

**Theorem 5.** (1) *The following statements are equivalent:*

- (a) TAUT has a  $p$ -optimal proof system.
- (b) TAUT has an almost optimal deterministic algorithm.
- (c) TAUT has an enumeration of the P-easy subsets by P-machines.

(2) *The following statements are equivalent:*

- (a) TAUT has an optimal proof system.
- (b) TAUT has an almost optimal nondeterministic algorithm.
- (c) TAUT has a weak enumeration of the P-easy subsets by NP-machines.
- (d) TAUT has an enumeration of the P-easy subsets by NP-machines.

The equivalence of (a) and (b) in (1) and (2) is due to [9], the equivalence to (c) to [13]. The equivalence in (2) to (d) will be a by-product of the proof of Theorem 8; the equivalence was already claimed in [13] but its author was so kind to point out to us that he did not realize the difference between (c) and (d): some machines  $M(i)$  of a weak enumeration might accept subsets of  $Q$  which are not P-easy (but only in NP).

#### 4. Linking slicewise monotone problems and optimal proof systems

The following result yields a uniform bound on the complexity of slicewise monotone problems whose complements have optimal proof systems.

**Theorem 6.** *Let  $(Q, \kappa)$  be a slicewise monotone parameterized problem with decidable  $Q$ .*

- (1) *If  $\Sigma^* \setminus Q$  has a  $p$ -optimal proof system, then  $(Q, \kappa) \in \text{XP}_{\text{uni}}$ .*
- (2) *If  $\Sigma^* \setminus Q$  has an optimal proof system, then  $(Q, \kappa) \in \text{co-XNP}_{\text{uni}}$ .*

As by (3) on page 5 every nonempty problem in co-NP has a (p-)optimal proof system if TAUT has one, we immediately get:

**Corollary 7.** *Let  $(Q, \kappa)$  be a slicewise monotone parameterized problem with  $Q$  in NP.*

- (1) *If TAUT has a  $p$ -optimal proof system, then  $(Q, \kappa) \in \text{XP}_{\text{uni}}$ .*
- (2) *If TAUT has an optimal proof system, then  $(Q, \kappa) \in \text{co-XNP}_{\text{uni}}$ .*

Concerning Theorem 6 (1) we should mention that Monroe [11] has shown that if the complement of (the classical problem underlying)  $p\text{-ACC}_{\leq}$  has an almost optimal algorithm (which by [9] holds if it has a  $p$ -optimal proof system), then  $p\text{-ACC}_{\leq} \in \text{XP}_{\text{uni}}$ .

*Proof of Theorem 6:* We present the proof for (2), the proof for (1) is obtained by the obvious modifications. Let  $(Q, \kappa)$  be slicewise monotone and let  $\mathbb{Q}$  be a deterministic algorithm deciding  $Q$ . Assume that  $\Sigma^* \setminus Q$  has an optimal proof system. It is well-known [9] that then  $\Sigma^* \setminus Q$  has an almost optimal nondeterministic algorithm  $\mathbb{O}$ . We have to show that  $(Q, \kappa) \in \text{co-XNP}_{\text{uni}}$ .

Let  $\mathbb{S}$  be the algorithm that, on  $x \in \Sigma^*$ , by systematically applying  $\mathbb{Q}$  to the inputs  $(x, 0), (x, 1), \dots$  computes

$$n(x) := \text{the least } n \text{ such that } (x, n) \in Q.$$

If  $(x, n) \notin Q$  for all  $n \in \mathbb{N}$ , then  $n(x)$  is not defined and  $\mathbb{S}$  does not stop. We show that the following algorithm  $\mathbb{A}$  witnesses that  $(\Sigma^* \setminus Q, \kappa) \in \text{XNP}_{\text{uni}}$ .

$\mathbb{A}(x, n)$ // $x \in \Sigma^*, n \in \mathbb{N}$ in unary 1. In parallel simulate $\mathbb{S}$ on input $x$ and $\mathbb{O}$ on input $(x, n)$ 2. <b>if</b> $\mathbb{O}$ accepts <b>then</b> accept 3. <b>if</b> $\mathbb{S}$ stops, <b>then</b> 4. <b>if</b> $n < n(x)$ <b>then</b> accept <b>else</b> reject.
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By our assumptions on  $\mathbb{O}$  and  $\mathbb{S}$  and the slicewise monotonicity of  $Q$ , it should be clear that  $\mathbb{A}$  accepts  $\Sigma^* \setminus Q$ . We have to show that  $\mathbb{A}$  does it in the time required by  $\text{XNP}_{\text{uni}}$ . Hence, we have to determine the running time of  $\mathbb{A}$  on inputs  $(x, n) \notin Q$ .

*Case “ $(x, \ell) \notin Q$  for all  $\ell \in \mathbb{N}$ ”:* In this case  $\mathbb{S}$  on input  $x$  does not stop. Hence, the running time of  $\mathbb{A}$  on input  $(x, n)$  is determined by  $\mathbb{O}$ . The following algorithm  $\mathbb{O}_x$  accepts  $\Sigma^* \setminus Q$ : on input  $(y, \ell)$  the algorithm  $\mathbb{O}_x$  checks whether  $y = x$ . If so, it accepts and otherwise it runs  $\mathbb{O}$  on input  $(y, \ell)$  and answers accordingly. Clearly, for all  $\ell \in \mathbb{N}$

$$t_{\mathbb{O}_x}((x, \ell)) \leq O(|x|).$$

As  $\mathbb{O}$  is almost optimal, we know that there is a constant  $d_x \in \mathbb{N}$  (depending on  $x$ ) such that for all  $(y, \ell) \in \Sigma^* \setminus Q$

$$t_{\mathbb{O}}((y, \ell)) \leq (|(y, \ell)| + t_{\mathbb{O}_x}((y, \ell)))^{d_x}.$$

In particular, we have

$$t_{\mathbb{A}}((x, n)) = O(t_{\mathbb{O}}((x, n))) \leq O\left(|(x, n)| + O(|x|)^{d_x}\right) \leq n^{d'_x}$$

for some constant  $d'_x \in \mathbb{N}$  (depending on  $x$ ).

*Case “ $(x, \ell) \in Q$  for some  $\ell \in \mathbb{N}$ ”:* Then  $\mathbb{S}$  will stop on input  $x$ . Thus, in the worst case,  $\mathbb{A}$  on input  $(x, n)$  has to wait till the simulation of  $\mathbb{S}$  on  $x$  stops and then  $\mathbb{A}$  must check whether the result  $n(x)$  of the computation of  $\mathbb{S}$  is bigger than  $n$  or not and answer according to Line 4. So in the worst case  $\mathbb{A}$  takes time  $O(t_{\mathbb{S}}(x) + O(n)) \leq n^{O(t_{\mathbb{S}}(x))}$ .  $\square$

We show the equivalence in the first line of Theorem 2:

**Theorem 8.** (1) TAUT has a  $p$ -optimal proof system iff  $p\text{-ACC}_{\leq} \in \text{XP}_{\text{uni}}$ .  
(2) TAUT has an optimal proof system iff  $p\text{-ACC}_{\leq} \in \text{co-XNP}_{\text{uni}}$ .

*Proof.* Again we only prove (2) and by the previous corollary it suffices to show the corresponding implication from “right to left.”

So assume that the complement of  $p\text{-ACC}_{\leq}$  is in  $\text{XNP}_{\text{uni}}$  and let  $\mathbb{A}$  be a non-deterministic algorithm witnessing it; in particular,  $t_{\mathbb{A}}((\mathbb{M}, n)) \leq n^{f(\|\mathbb{M}\|)}$  for some function  $f$  and all  $(\mathbb{M}, n) \notin p\text{-ACC}_{\leq}$ . We show that TAUT has an enumeration of the P-easy subsets by NP-machines (and this suffices by Theorem 5).

We fix a deterministic Turing machine  $\mathbb{M}_0$  that given a propositional formula  $\alpha$  and an assignment checks if this assignment satisfies  $\alpha$  in time  $|\alpha|^2$ .

For a deterministic Turing machine  $\mathbb{M}$  let  $\mathbb{M}^*$  be the nondeterministic machine that on empty input tape

- first guesses a propositional formula  $\alpha$ ;
- then checks (by simulating  $\mathbb{M}$ ) whether  $\mathbb{M}$  accepts  $\alpha$  and rejects if this is not the case;
- finally guesses an assignment and accepts if this assignment does not satisfy  $\alpha$  (this is checked by simulating  $\mathbb{M}_0$ ).

A deterministic Turing machine  $\mathbb{M}$  is *clocked* if (the code of)  $\mathbb{M}$  contains a natural number  $\text{time}(\mathbb{M})$  such that  $n^{\text{time}(\mathbb{M})}$  is a bound for the running time of  $\mathbb{M}$  on inputs of length  $n$  (in particular, a clocked machine is a polynomial time one).

Finally, for a clocked Turing machine  $\mathbb{M}$  let  $\mathbb{M}^+$  be the nondeterministic Turing machine that on input  $\alpha$  accepts if and only if (i) and (ii) hold:

- (i)  $\mathbb{M}$  accepts  $\alpha$ ;
- (ii)  $(\mathbb{M}^*, |\alpha|^{\text{time}(\mathbb{M})+4}) \notin p\text{-ACC}_{\leq}$ .

The machine  $\mathbb{M}^+$  checks (i) by simulating  $\mathbb{M}$  and (ii) by simulating  $\mathbb{A}$ . Hence, if  $\mathbb{M}^+$  accepts  $\alpha$ , then

$$t_{\mathbb{M}^+}(\alpha) \leq O(|\alpha|^{\text{time}(\mathbb{M})} + t_{\mathbb{A}}((\mathbb{M}^*, |\alpha|^{\text{time}(\mathbb{M})+4}))),$$

and as  $t_{\mathbb{A}}((\mathbb{M}^*, |\alpha|^{\text{time}(\mathbb{M})+4})) \leq |\alpha|^{(\text{time}(\mathbb{M})+4) \cdot f(\|\mathbb{M}^*\|)}$ , the Turing machine  $\mathbb{M}^+$  accepts in time polynomial in  $|\alpha|$ .

We show that  $\mathbb{M}^+$ , where  $\mathbb{M}$  ranges over all clocked machines, yields an enumeration of all P-easy subsets of TAUT by NP-machines. First let  $\mathbb{M}$  be a clocked machine. We prove that  $\mathbb{M}^+$  accepts a P-easy subset of TAUT.

*$\mathbb{M}^+$  accepts a subset of TAUT:* If  $\mathbb{M}^+$  accepts  $\alpha$ , then, by (i),  $\mathbb{M}$  accepts  $\alpha$  and by (ii),  $(\mathbb{M}^*, |\alpha|^{\text{time}(\mathbb{M})+4}) \notin p\text{-ACC}_{\leq}$ . Therefore, by definition of  $\mathbb{M}^*$ , every assignment satisfies  $\alpha$  and hence  $\alpha \in \text{TAUT}$ .

*$\mathbb{M}^+$  accepts a P-easy set:* If  $(\mathbb{M}^*, m) \in p\text{-ACC}_{\leq}$  for some  $m$ , then, by slicewise monotonicity of  $p\text{-ACC}_{\leq}$ , the machine  $\mathbb{M}^+$  accepts a finite set and hence a P-easy set. If  $(\mathbb{M}^*, m) \notin p\text{-ACC}_{\leq}$  for all  $m$ , then  $\mathbb{M}^+$  accepts exactly those  $\alpha$  accepted by  $\mathbb{M}$ ; as  $\mathbb{M}$  is clocked, this is a set in P.

Now let  $Q \subseteq \text{TAUT}$  be a P-easy subset of TAUT and let  $\mathbb{M}$  be a clocked machine deciding  $Q$ . Then  $\mathbb{M}^+$  accepts  $Q$ .  $\square$



## 5. Slicewise monotone parameterized problems

In this section we observe that  $p\text{-ACC}_{\leq}$  is a complete problem in the class of slicewise monotone parameterized problems with underlying classical problem in NP. Furthermore, we shall see that in Theorem 8 we can replace the problem  $p\text{-ACC}_{\leq}$  by other slicewise monotone parameterized problems (among them  $p\text{-GÖDEL}$ ) by showing for them that they are in the class  $\text{XP}_{\text{uni}}$  ( $\text{co-XNP}_{\text{uni}}$ ) if and only if  $p\text{-ACC}_{\leq}$  is.

**5.1. The complexity of slicewise monotone problems.** We start with some remarks on the complexity of slicewise monotone problems. In [1, 2] we have shown that  $p\text{-ACC}_{\leq}$  and  $p\text{-GÖDEL}$  are not fixed-parameter tractable if “ $\text{P} \neq \text{NP}$  holds for all time constructible and increasing functions,” that is, if  $\text{DTIME}(h^{O(1)}) \neq \text{NTIME}(h^{O(1)})$  for all time constructible and increasing functions  $h: \mathbb{N} \rightarrow \mathbb{N}$ . However:

**Proposition 9.** (1) [2] *Let  $(Q, \kappa)$  be slicewise monotone. Then  $(Q, \kappa)$  is non-uniformly fixed-parameter tractable, that is, there is a  $c \in \mathbb{N}$ , a function  $f: \mathbb{N} \rightarrow \mathbb{N}$ , and for every  $k$  an algorithm deciding the slice  $(Q, \kappa)_k$  in time  $f(k) \cdot n^c$ .*

(2) *Let  $(Q, \kappa)$  be slicewise monotone with enumerable  $Q$ . Then  $(Q, \kappa) \in \text{XNP}_{\text{uni}}$ .*

*Proof.* (2) Let  $\mathbb{Q}$  be an algorithm enumerating  $Q$ . The following algorithm shows that  $(Q, \kappa) \in \text{XNP}_{\text{uni}}$ : On input  $(x, n)$  it guesses  $m \in \mathbb{N}$  and a string  $c$ . If  $c$  is the code of an initial segment of the run of  $\mathbb{Q}$  enumerating  $(x, m)$ , then it accepts if  $m \leq n$ .  $\square$

We remark that there are slicewise monotone problems with underlying classical problem of arbitrarily high complexity that are fixed-parameter tractable. In fact, let  $Q_0 \subseteq \Sigma^*$  be decidable. Then the slicewise monotone  $(Q, \kappa)$  with

$$Q := \{(x, n) \mid x \in Q_0, n \in \mathbb{N}, \text{ and } |x| \leq n\}$$

(and  $\kappa((x, n)) := |x|$ ) is in FPT.

To compare the complexity of parameterized problems we use the standard notions of reduction that we recall first. Let  $(Q, \kappa)$  and  $(Q', \kappa')$  be parameterized problems. We write  $(Q, \kappa) \leq^{\text{fpt}} (Q', \kappa')$  if there is an *fpt-reduction* from  $(Q, \kappa)$  to  $(Q', \kappa')$ , that is, a mapping  $R: \Sigma^* \rightarrow \Sigma^*$  with:

- (1) For all  $x \in \Sigma^*$  we have  $(x \in Q \iff R(x) \in Q')$ .
- (2)  $R(x)$  is computable in time  $f(\kappa(x)) \cdot |x|^{O(1)}$  for some computable  $f: \mathbb{N} \rightarrow \mathbb{N}$ .
- (3) There is a computable function  $g: \mathbb{N} \rightarrow \mathbb{N}$  such that  $\kappa'(R(x)) \leq g(\kappa(x))$  for all  $x \in \Sigma^*$ .

We write  $(Q, \kappa) \leq^{\text{xp}} (Q', \kappa')$  if there is an *xp-reduction* from  $(Q, \kappa)$  to  $(Q', \kappa')$ , which is defined as  $(Q, \kappa) \leq^{\text{fpt}} (Q', \kappa')$  except that instead of (2) it is only required that  $R(x)$  is computable in time  $|x|^{f(\kappa(x))}$  for some computable  $f: \mathbb{N} \rightarrow \mathbb{N}$ .

These are notions of reductions of the usual (strongly uniform) parameterized complexity theory. We get the corresponding notions  $\leq_{\text{uni}}^{\text{fpt}}$  and  $\leq_{\text{uni}}^{\text{xp}}$  by allowing the functions  $f$  and  $g$  to be arbitrary (and not necessarily computable).

We shall use the following simple observation.

**Lemma 10.** *If  $(Q, \kappa) \leq_{\text{uni}}^{\text{xp}} (Q', \kappa')$  and  $(Q', \kappa') \in \text{XP}_{\text{uni}}$ , then  $(Q, \kappa) \in \text{XP}_{\text{uni}}$ . The same holds for  $\text{XNP}_{\text{uni}}$  instead of  $\text{XP}_{\text{uni}}$ .*

We turn again to slicewise monotone problems. Among these problems with underlying classical problem in NP the problem  $p\text{-ACC}_{\leq}$  is of highest complexity.

**Proposition 11.** *Let  $(Q, \kappa)$  be slicewise monotone and  $Q \in \text{NP}$ . Then*

$$(Q, \kappa) \leq^{\text{fpt}} p\text{-ACC}_{\leq}.$$

Note that this result together with Theorem 8 (2) yields Theorem 1.

*Proof of Proposition 11:* Let  $\mathbb{M}$  be a nondeterministic Turing machine accepting  $Q$ . We may assume that for some  $d \in \mathbb{N}$  the machine  $\mathbb{M}$  on input  $(x, n)$  performs exactly  $|(x, n)|^d$  steps. For  $x \in \Sigma^*$  let  $\mathbb{M}_x$  be the nondeterministic Turing machine that on empty input tape, first writes  $x$  on the tape, then guesses a natural number  $m$ , and finally simulates the computation of  $\mathbb{M}$  on input  $(x, m)$ . We can assume that there is a polynomial time computable function  $h$  such that  $\mathbb{M}_x$  makes exactly  $h(x, m) \in O(|x| + m + |(x, m)|^d)$  steps if it chooses the natural number  $m$ . Furthermore we can assume that  $h(x, m) < h(x, m')$  for  $m < m'$ .

Then  $(x, n) \mapsto (\mathbb{M}_x, h(x, n))$  is an fpt-reduction from  $(Q, \kappa)$  to  $p\text{-ACC}_{\leq}$ : Clearly, if  $(x, n) \in Q$  then  $(\mathbb{M}_x, h(x, n)) \in p\text{-ACC}_{\leq}$  by construction of  $\mathbb{M}_x$ . Conversely, if  $(\mathbb{M}_x, h(x, n)) \in p\text{-ACC}_{\leq}$ , then by the properties of  $h$  we see that  $\mathbb{M}$  accepts  $(x, m)$  for some  $m \leq n$ . Thus,  $(x, m) \in Q$  and therefore  $(x, n) \in Q$  by slicewise monotonicity.  $\square$

Later on we shall use the following related result.

**Proposition 12.** *Let  $(Q, \kappa)$  be slicewise monotone and assume that there is a nondeterministic algorithm  $\mathbb{A}$  accepting  $Q$  such that  $t_{\mathbb{A}}(x, n) \leq n^{f(|x|)}$  for some time constructible  $f$  and all  $(x, n) \in Q$ . Then*

$$(Q, \kappa) \leq^{\text{xp}} p\text{-ACC}_{\leq}.$$

*Proof.* Let  $(Q', \kappa')$  be the problem

*Instance:*  $x \in \Sigma^*$  and  $m \in \mathbb{N}$  in unary.  
*Parameter:*  $|x|$ .  
*Problem:* Is there an  $n \in \mathbb{N}$  such that  $n^{f(|x|)} \leq m$  and  $(x, n) \in Q$ ?

By the previous proposition we get our claim once we have shown:

- (1)  $(Q', \kappa')$  is slicewise monotone and  $Q' \in \text{NP}$ .
- (2)  $(Q, \kappa) \leq^{\text{xp}} (Q', \kappa')$

To see (1) let  $\mathbb{A}$  be as stated above and let  $\mathbb{T}$  an algorithm witnessing the time constructibility of  $f$ ; that is,  $\mathbb{T}$  on input  $k \in \mathbb{N}$  computes  $f(k)$  in exactly  $f(k)$  steps. An algorithm  $\mathbb{B}$  witnessing that  $Q' \in \text{NP}$  runs as follows on input  $(x, m)$ :

- $\mathbb{B}$  guesses  $n \in \mathbb{N}$ ;
- if  $n = 1$ , the algorithm  $\mathbb{B}$  rejects in case  $m = 0$ ;  
if  $n \geq 2$ , the algorithm  $\mathbb{B}$  simulates  $m$  steps of the computation of  $\mathbb{T}$  on input  $|x|$ ; if thereby  $\mathbb{T}$  does not stop,  $\mathbb{B}$  rejects; otherwise, the simulation yields  $f(|x|)$  and  $\mathbb{B}$  checks whether  $n^{f(|x|)} > m$  (this can be detected in time  $O(m)$ ); in the positive case  $\mathbb{B}$  rejects;
- finally  $\mathbb{B}$  simulates the computation of  $\mathbb{A}$  on  $(x, n)$  and answers accordingly.

(2) Note that the mapping  $(x, n) \mapsto (x, n^{f(|x|)})$  is an xp-reduction. □

**5.2. Slicewise monotone problems related to logic.** In the next section we will use some further slicewise monotone problems related to first-order logic and least fixed-point logic that we introduce now.

We assume familiarity with *first-order logic* FO and its extension *least fixed-point logic* LFP (e.g, see [5]). We denote by  $\text{FO}[\tau]$  and  $\text{LFP}[\tau]$  the set of sentences of vocabulary  $\tau$  of FO and of LFP, respectively. In this paper all vocabularies are finite sets of relational symbols.

If the structure  $\mathcal{A}$  is a model of the LFP-sentence  $\varphi$  we write  $\mathcal{A} \models \varphi$ . We only consider structures  $\mathcal{A}$  with finite universe  $A$ . The size  $\|\mathcal{A}\|$  of the structure  $\mathcal{A}$  is the length of a reasonable encoding of  $\mathcal{A}$  as string in  $\Sigma^*$ . An algorithm based on the inductive definition of the satisfaction relation for LFP shows (see [14]):

**Proposition 13.** *The model-checking problem  $\mathcal{A} \models \varphi$  for structures  $\mathcal{A}$  and LFP-sentences  $\varphi$  can be solved in time  $\|\mathcal{A}\|^{O(|\varphi|)}$ .*

Let  $L = \text{FO}$  or  $L = \text{LFP}$ . First we introduce the parameterized problem

<p><i>p-L-MODEL</i></p> <p><i>Instance:</i> An <math>L</math>-sentence <math>\varphi</math> and <math>n \in \mathbb{N}</math> in unary.</p> <p><i>Parameter:</i> <math> \varphi </math>.</p> <p><i>Problem:</i> Is there a structure <math>\mathcal{A}</math> with <math>\mathcal{A} \models \varphi</math> and <math> A  \leq n</math>?</p>
--

Here,  $|A|$  denotes the size of the universe  $A$  of  $\mathcal{A}$ . For every vocabulary  $\tau$  we let  $\tau_{<} := \tau \cup \{<\}$ , where  $<$  is a binary relation symbol not in  $\tau$ . For  $m \geq 1$  we say that an  $L[\tau_{<}]$ -sentence  $\varphi$  is  $\leq m$ -invariant if for all  $\tau$ -structures  $\mathcal{A}$  with  $|A| \leq m$  we have

$$(\mathcal{A}, <_1) \models \varphi \iff (\mathcal{A}, <_2) \models \varphi$$

for all orderings  $<_1$  and  $<_2$  on  $A$ .

Finally we introduce the slicewise monotone parameterized problem

$p$ -L-NOT-INV

*Instance:* A vocabulary  $\tau$ , an  $L[\tau_{<}]$ -sentence  $\varphi$  and  $m \geq 1$  in unary.

*Parameter:*  $|\varphi|$ .

*Problem:* Is  $\varphi$  not  $\leq m$ -invariant?

**5.3. Membership in  $\text{XP}_{\text{uni}}$  and  $\text{co-XNP}_{\text{uni}}$ .** Concerning membership in the classes  $\text{XP}_{\text{uni}}$  and  $\text{co-XNP}_{\text{uni}}$  all the slicewise monotone problems we have introduced behave in the same way:

**Proposition 14.** *Consider the parameterized problems*

$p$ -GÖDEL,  $p$ -FO-MODEL,  $p$ -LFP-MODEL,  $p$ -FO-NOT-INV,  $p$ -LFP-NOT-INV, and  $p$ -ACC $_{\leq}$ .

*If one of the problems is in  $\text{XP}_{\text{uni}}$ , then all are; if one of the problems is in  $\text{co-XNP}_{\text{uni}}$ , then all are.*

By Theorem 8 this result yields Theorem 2. We prove it with Lemmas 15–18.

**Lemma 15.** ([2])  $p$ -GÖDEL  $\leq^{\text{fpt}}$   $p$ -FO-MODEL.

**Lemma 16.** *Let  $L = \text{FO}$  or  $L = \text{LFP}$ . Then  $p$ -L-MODEL  $\leq^{\text{fpt}}$   $p$ -L-NOT-INV.*

*Proof.* Let  $\varphi$  be a sentence of vocabulary  $\tau$ . We set  $\tau' := \tau \cup \{P\}$  with a new unary relation symbol  $P$  and consider the sentence of vocabulary  $\tau'_{<}$

$$\psi(\varphi) := \varphi \wedge \text{“}P \text{ holds for the first element of } < \text{.”}$$

Clearly, for every  $n \geq 2$

$$(\varphi, n) \in p\text{-FO-MODEL} \iff (\psi(\varphi), n) \in p\text{-FO-NOT-INV}$$

and the same equivalence holds for  $p$ -LFP-MODEL and  $p$ -LFP-NOT-INV. Thus  $(\varphi, n) \mapsto (\psi(\varphi), n)$  is the desired reduction in both cases.  $\square$

**Lemma 17.**  $p$ -LFP-NOT-INV  $\leq^{\text{xp}}$   $p$ -ACC $_{\leq}$

*Proof.* Consider the algorithm  $\mathbb{A}$  that on input  $(\varphi, m)$ , where  $\varphi$  is an LFP-sentence and  $m \geq 1$ , guesses a structure  $\mathcal{A}$  and two orderings  $<_1$  and  $<_2$  and accepts if  $|A| \leq m$ ,  $(\mathcal{A}, <_1) \models \varphi$ , and  $(\mathcal{A}, <_2) \models \neg\varphi$ . Then, by Proposition 13, the algorithm  $\mathbb{A}$  witnesses that  $p$ -LFP-NOT-INV satisfies the assumptions on  $(Q, \kappa)$  in Proposition 12. This yields the claim.  $\square$

**Lemma 18.** (1) *If  $p$ -GÖDEL  $\in \text{XP}_{\text{uni}}$ , then  $p$ -ACC $_{\leq} \in \text{XP}_{\text{uni}}$ .*

(2) *If  $p$ -GÖDEL  $\in \text{co-XNP}_{\text{uni}}$ , then  $p$ -ACC $_{\leq} \in \text{co-XNP}_{\text{uni}}$ .*

*Proof.* We give the proof of (2). By standard means we showed in [2, Lemma 7] that there exists a  $d \in \mathbb{N}$  and a polynomial time algorithm that assigns to every nondeterministic Turing machine  $\mathbb{M}$  a first-order sentence  $\varphi_{\mathbb{M}}$  such that for  $n \in \mathbb{N}$

$$(1) \quad (\mathbb{M}, n) \in p\text{-ACC}_{\leq} \implies (\varphi_{\mathbb{M}}, n^d) \in p\text{-GÖDEL.}$$

Moreover,

(2)  $\varphi_{\mathbb{M}}$  has a proof  $\implies \mathbb{M}$  accepts the empty input tape.

Now assume that  $\mathbb{A}$  is an algorithm that witnesses that the complement of  $p$ -GÖDEL is in  $\text{XNP}_{\text{uni}}$ . We may assume that every run of  $\mathbb{A}$  either accepts its input or is infinitely long. Let  $d \in \mathbb{N}$  be as above. We present an algorithm  $\mathbb{B}$  showing that the complement of  $p\text{-ACC}_{\leq}$  is in  $\text{XNP}_{\text{uni}}$ . On input  $(\mathbb{M}, n)$  the algorithm  $\mathbb{B}$  first computes  $\varphi_{\mathbb{M}}$  and then runs two algorithms in parallel:

- a brute force algorithm that on input  $\mathbb{M}$  searches for the least  $n_{\mathbb{M}}$  such that  $\mathbb{M}$  on empty input tape has an accepting run of length  $n_{\mathbb{M}}$ ;
- the algorithm  $\mathbb{A}$  on input  $(\varphi_{\mathbb{M}}, n^d)$ .

If the brute force algorithm halts first and outputs  $n_{\mathbb{M}}$ , then  $\mathbb{B}$  checks whether  $n_{\mathbb{M}} \leq n$  and answers accordingly.

Assume now that  $\mathbb{A}$  halts first. Then  $\mathbb{A}$  accepts  $(\varphi_{\mathbb{M}}, n^d)$  and  $((\varphi_{\mathbb{M}}, n^d) \notin p\text{-GÖDEL}$  and hence  $(\mathbb{M}, n) \notin p\text{-ACC}_{\leq}$  by (1) and therefore)  $\mathbb{B}$  accepts.

The algorithm  $\mathbb{B}$  accepts the complement of  $p\text{-ACC}_{\leq}$ ; note that if no run of  $\mathbb{A}$  accepts  $(\varphi_{\mathbb{M}}, n^d)$ , then  $(\varphi_{\mathbb{M}}, n^d) \in p\text{-GÖDEL}$  and therefore  $\mathbb{M}$  accepts the empty input tape by (2), so that in this case the computation of the brute force algorithm eventually will stop.

It remains to see that  $\mathbb{B}$  accepts the complement of  $p\text{-ACC}_{\leq}$  in the time required by  $\text{XNP}_{\text{uni}}$ . We consider two cases.

*$\mathbb{M}$  halts on empty input tape:* Then an upper bound for the running time is given by the time that the brute force algorithm needs to compute  $n_{\mathbb{M}}$  (and the time for the check whether  $n_{\mathbb{M}} \leq n$ ); hence we have an upper bound of the form  $n^{c_{\mathbb{M}}}$ .

*$\mathbb{M}$  does not halt on empty input tape:* Then, by (2), we have  $(\varphi_{\mathbb{M}}, n^d) \notin p\text{-GÖDEL}$ ; hence an upper bound is given by the running time of  $\mathbb{A}$  on input  $(\varphi_{\mathbb{M}}, n^d)$ .  $\square$

It should be clear that Lemmas 15–18 together with Lemma 10 yield a proof of Proposition 14.

## 6. Optimal algorithms and the logic $L_{\leq}$

In this section we interpret Theorem 2 in terms of the expressive power of a certain logic.

For our purposes a *logic*  $L$  consists

- for every vocabulary  $\tau$  of a set  $L[\tau]$  of strings, the set of  $L$ -sentences of vocabulary  $\tau$  and of an algorithm that for every vocabulary  $\tau$  and every string  $\xi$  decides whether  $\xi \in L[\tau]$  (in particular,  $L[\tau]$  is decidable for every  $\tau$ );
- of a *satisfaction relation*  $\models_L$ ; if  $(\mathcal{A}, \varphi) \in \models_L$ , written  $\mathcal{A} \models_L \varphi$ , then  $\mathcal{A}$  is a  $\tau$ -structure and  $\varphi \in L[\tau]$  for some vocabulary  $\tau$ ; furthermore for each

$\varphi \in L[\tau]$  the class  $\text{Mod}_L(\varphi) := \{\mathcal{A} \mid \mathcal{A} \models_L \varphi\}$  of *models of  $\varphi$*  is closed under isomorphisms.

**Definition 19.** Let  $L$  be a logic.

(a)  $L$  is a logic for  $P$  if for all vocabularies  $\tau$  and all classes  $C$  (of encodings) of  $\tau$ -structures closed under isomorphisms we have

$$C \in P \iff C = \text{Mod}_L(\varphi) \text{ for some } \varphi \in L[\tau].$$

(b)  $L$  is a  $P$ -bounded logic for  $P$  if (a) holds and if there is an algorithm  $\mathbb{A}$  deciding  $\models_L$  (that is, for every structure  $\mathcal{A}$  and  $L$ -sentence  $\varphi$  the algorithm  $\mathbb{A}$  decides whether  $\mathcal{A} \models_L \varphi$ ) and if moreover, for fixed  $\varphi$  the algorithm  $\mathbb{A}$  runs in time polynomial in  $\|\mathcal{A}\|$ .

The relationship of these concepts with topics of this paper is already exemplified by the following simple observation.

**Proposition 20.** Let  $L$  be a logic for  $P$  and define  $p\text{-}\models_L$  by

$p\text{-}\models_L$	<i>Instance:</i> A structure $\mathcal{A}$ and an $L$ -sentence $\varphi$ .
	<i>Parameter:</i> $ \varphi $ .
	<i>Problem:</i> Is $\mathcal{A} \models_L \varphi$

Then  $L$  is a  $P$ -bounded logic for  $P$  if and only if  $p\text{-}\models_L \in \text{XP}_{\text{uni}}$ .

This relationship suggests the following definition.

**Definition 21.**  $L$  is an NP-bounded logic for  $P$  if it is a logic for  $P$  and  $p\text{-}\models_L \in \text{XNP}_{\text{uni}}$ .

We introduce the logic  $L_{\leq}$ , a variant of LFP.<sup>3</sup> For every vocabulary  $\tau$  we set

$$L_{\leq}[\tau] = \text{LFP}[\tau_{<}]$$

(recall that  $\tau_{<} := \tau \cup \{<\}$ , with a new binary  $<$ ) and define the semantics by

$$\mathcal{A} \models_{L_{\leq}} \varphi \iff \left( \varphi \text{ is } \leq |A|\text{-invariant and } (\mathcal{A}, <) \models_{\text{LFP}} \varphi \text{ for some ordering } < \text{ on } A \right).$$

Hence, by the previous proposition and the definition of  $\models_{L_{\leq}}$ , we get:

**Proposition 22.** (1) *The following statements are equivalent:*

- $L_{\leq}$  is a  $P$ -bounded logic for  $P$ .
- $p\text{-}\models_{L_{\leq}} \in \text{XP}_{\text{uni}}$ .
- $p\text{-LFP-NOT-INV} \in \text{XP}_{\text{uni}}$ .

<sup>3</sup>In this section, if the structure  $\mathcal{B}$  is a model of an LFP-sentence  $\varphi$  we write  $\mathcal{A} \models_{\text{LFP}} \varphi$  instead of  $\mathcal{A} \models \varphi$ .

(2) *The following statements are equivalent:*

- $L_{\leq}$  is an NP-bounded logic for P.
- $p \not\models_{L_{\leq}} \in \text{XNP}_{\text{uni}}$ .
- $p\text{-LFP-NOT-INV} \in \text{co-XNP}_{\text{uni}}$ .

By Theorem 2 and Proposition 14 we get:

**Theorem 23.** *TAUT has an optimal proof system if and only if  $L_{\leq}$  is an NP-bounded logic for P.*

Hence, if TAUT has an optimal proof system, then there is an NP-enumeration of P-easy classes of graphs closed under isomorphisms. We do not define the concept of NP-enumeration explicitly, however the enumeration obtained by applying the algorithm in  $\text{XNP}_{\text{uni}}$  for  $p \not\models_{L_{\leq}}$  to the classes  $\text{Mod}_{L_{\leq}}(\varphi(\text{GRAPH}) \wedge \psi)$ , where  $\varphi(\text{GRAPH})$  axiomatizes the class of graphs and  $\psi$  ranges over all sentences of  $L_{\leq}$  in the language of graphs, is such an NP-enumeration. Note that even without the assumption that TAUT has an optimal proof system we know that there is such an NP-enumeration of P-easy classes of graphs closed under isomorphisms, as the following variant  $L_{\leq}(\text{not})$  of  $L_{\leq}$  is an NP-bounded logic for P. The logic  $L_{\leq}(\text{not})$  has the same syntax as  $L_{\leq}$  and the semantics is given by the following clause:

$$\mathcal{A} \models_{L_{\leq}(\text{not})} \varphi \iff \text{not } \mathcal{A} \models_{L_{\leq}} \varphi.$$

As the class P is closed under complements,  $L_{\leq}(\text{not})$  is a logic for P. And  $L_{\leq}(\text{not})$  is an NP-bounded logic for P, as  $p\text{-LFP-NOT-INV} \in \text{XNP}_{\text{uni}}$ .

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