

WHY ARE SLIP LENGTHS SO LARGE IN CARBON NANOTUBES?

TIM G. MYERS

ABSTRACT. The enhanced flow in carbon nanotubes is explained using a mathematical model that includes a depletion layer with reduced viscosity near the wall. In the limit of large tubes the model predicts no noticeable enhancement. For smaller tubes the model predicts enhancement that increases as the radius decreases. An analogy between the reduced viscosity and slip-length models shows that the term slip-length is misleading and that on surfaces which are smooth at the nanoscale it may be thought of as a length-scale associated with the size of the depletion region and viscosity ratio. The model therefore provides a physical interpretation of the classical Navier slip condition and explains why ‘slip-lengths’ may be greater than the tube radius.

1. INTRODUCTION

The classical model for flow in a circular cylindrical pipe is described by the Hagen-Poiseuille equation

$$(1) \quad u_{HP} = -\frac{p_z R^4}{4\mu} \left(1 - \frac{r^2}{R^2}\right)$$

where $u_{HP}(r)$ is the velocity in the z direction, p_z is the pressure gradient along the pipe, R is the radius and μ the fluid viscosity. The corresponding flux is given by

$$(2) \quad Q_{HP} = 2\pi \int_0^R r u_{HP} dr = -\frac{\pi R^4 p_z}{8\mu}.$$

In carbon nano-tubes (CNT) it is well documented that the flow is enhanced and the true value of the flux is significantly higher than this classical value. A popular approach to explain this enhancement is to introduce a slip-length into the mathematical model, that is, the no-slip boundary condition $u(R) = 0$ is replaced by

$$(3) \quad u(R) = -L_s \left. \frac{\partial u}{\partial r} \right|_{r=R}$$

where L_s is the slip-length. This leads to modified velocity and flux expressions

$$(4) \quad u_{slip} = -\frac{R^2 p_z}{4\mu_1} \left[1 - \frac{r^2}{R^2} + \frac{2L_s}{R}\right], \quad Q_{slip} = Q_{HP} \left(1 + \frac{4L_s}{R}\right),$$

hence any magnitude of enhancement can be accounted for by using an appropriate value for L_s .

The concept of slip is an old one, attributed to Navier [1, 2, 3], and has many practical uses. When dealing with flow over a rough surface it permits a boundary condition to be applied on a flat surface, then the slip-length is related to the roughness height. In thin film theory it removes the stress singularity at the moving contact line, where the fluid front moves over a dry surface. It is also frequently invoked in studies of non-Newtonian fluids [2, 3, 4, 5, 6, 7]. In all cases the slip length is significantly smaller than the thickness of the bulk flow [1]. For example, Trethaway and Meinhart [8] carry out experiments on water flow in a coated microchannel of width $30\ \mu\text{m}$. Using particle imaging velocimetry they determine a slip length of $1\ \mu\text{m}$. In $1\text{-}2\ \mu\text{m}$ channels Choi *et al* [9] determine values of the order $30\ \text{nm}$. Molecular dynamics (MD) simulations indicate lengths of “1 to a few nm” [10]. Whilst there is no theory to predict the slip length for a liquid flowing past a solid, there is one for gases. In this case the slip length is the mean free path of the gas [2] (for water this is $0.3\ \text{nm}$ [11]). Yet, when analysing flow in CNTs, in order to sufficiently enhance the flow, the slip length must be set significantly higher than the bulk flow thickness. For example Whitby *et al* [12] quote lengths of $30\text{-}40\ \text{nm}$ for experiments in pipes of $20\ \text{nm}$ radius. Holt *et al* [11] and Majumder *et al* [13] quote slip lengths on the order of microns for their experiments with nanometer size pores.

Of course the high values of slip-length have led some authors to question the validity of the slip modified Hagen-Poiseuille model [14, 15]. Cottin-Bizonne *et al* [16] state that the slip-length should have a single value independent of the tube radius and much less than those quoted in the literature. They attribute some of the high experimental values to contamination by hydrophobic particles. It has been proposed that the apparent slip is probably due to a decrease in the fluid viscosity near the wall caused, for example, by enhanced nucleation of dissolved gas or the formation of vapour [1, 17, 16]. Experiments have conclusively shown the existence of depletion layers between water and hydrophobic surfaces and this motivated the MD simulations of Joseph *et al* [18]. In keeping with this mechanism for apparent slip, Majumder *et al* [13] suggested that their observed flow enhancement could be attributed to an essentially frictionless interface at the CNT wall. Ruckenstein and Rajora [19] propose a gas gap at the interface between the solid and the liquid. Clearly this gap or depletion layer must be small. Experiments and simulations have shown that the fluid viscosity is in close agreement with its bulk value down to separations of about 10 molecular diameters [1]. MD simulations indicate that the fluid viscosity close to a solid boundary is position dependent [20]. For CNTs the fluid properties typically vary within an annular region approximately $0.7\ \text{nm}$ from the CNT wall [18, 14, 21].

Consequently, in the following work we will investigate a mathematical model for flow including a region of low viscosity near the tube wall. In their review

paper Mattia and Gogotsi [22] state that the *question whether the nonslip boundary condition is applicable at very small scales remains open*. We will provide a possible answer to this question by showing that the reduced viscosity model is analogous to a slip model, although perhaps the term ‘slip length’ is misleading. The slip length is typically considered to be the length-scale over which the fluid layer slips over the boundary. If instead it is interpreted as a length-scale associated with the reduced viscosity then the required high values have a more physically sensible interpretation.

2. MATHEMATICAL MODEL

Consider a pipe of cross-section R , occupied by two fluids. In the bulk flow region, defined by $0 \leq r \leq \alpha$, we impose a viscosity μ_1 . In the annular region near the wall, defined by $\alpha \leq r \leq R$, we impose a viscosity $\mu_2 < \mu_1$. Of course there is uncertainty about the values to choose for viscosity and α . If we define the position of the transition $\alpha = R - \delta$ then, based on previous studies of water in CNTs [14, 18, 21] in all calculations we will set $\delta = 0.7$ nm. However, experiments show that the slip length increases with hydrophobicity [9, 16] and so for other fluids and tubes the value of δ may differ. MD simulations indicate μ_2 varies with position [20], however, for simplicity we will take it as constant and so use an average value in the annulus. Again the constant will be system dependent.

For unidirectional pressure driven flow the appropriate mathematical model is

$$(5) \quad \frac{\mu_1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u_1}{\partial r} \right) = \frac{\partial p}{\partial z} \quad 0 \leq r \leq \alpha, \quad \frac{\mu_2}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u_2}{\partial r} \right) = \frac{\partial p}{\partial z} \quad \alpha \leq r \leq R.$$

Appropriate boundary conditions are

$$(6) \quad \left. \frac{\partial u_1}{\partial r} \right|_{r=0} = 0 \quad u_2(R, z) = 0,$$

which represent symmetry at the centreline and no-slip at the solid boundary. At the interface between the fluids, $r = \alpha$, there is continuity of velocity and shear stress

$$(7) \quad u_1 = u_2 \quad \mu_1 \frac{\partial u_1}{\partial r} = \mu_2 \frac{\partial u_2}{\partial r}.$$

The appropriate velocity expressions are then

$$(8) \quad u_1 = \frac{p_z}{4\mu_1}(r^2 - \alpha^2) - \frac{p_z}{4\mu_2}(R^2 - \alpha^2) \quad u_2 = \frac{p_z}{4\mu_2}(r^2 - R^2).$$

The flux Q_μ is defined as the sum of fluxes in the two regions

$$(9) \quad Q_\mu = 2\pi \left(\int_0^\alpha r u_1 dr + \int_\alpha^R r u_2 dr \right)$$

$$(10) \quad = -\frac{\pi\alpha^4 p_z}{8\mu_1} \left[1 - \frac{2\mu_1}{\mu_2} \left(1 - \frac{R^2}{\alpha^2} \right) \right] - \frac{\pi\alpha^4 p_z}{8\mu_2} \left(1 - \frac{R^2}{\alpha^2} \right)^2.$$

This may be related to the standard expression by

$$(11) \quad Q_\mu = Q_{HP} \frac{\alpha^4}{R^4} \left[1 + \frac{\mu_1}{\mu_2} \left(\frac{R^4}{\alpha^4} - 1 \right) \right].$$

The flow rate enhancement is defined as

$$(12) \quad \epsilon_\mu = \frac{Q_\mu}{Q_{HP}} = \frac{\alpha^4}{R^4} + \frac{\mu_1}{\mu_2} \left(1 - \frac{\alpha^4}{R^4} \right).$$

For the slip model the corresponding enhancement is

$$(13) \quad \epsilon_{slip} = 1 + \frac{4L_s}{R}.$$

In the limits $\alpha \rightarrow R$ and $L_s \rightarrow 0$ the expressions for Q_μ, Q_{slip} reduce to Q_{HP} and so $\epsilon_\mu, \epsilon_{slip} \rightarrow 1$. If the flow rate is to be increased then $\epsilon > 1$. The above expressions indicate that this requires $\mu_1 > \mu_2$ or $L_s > 0$.

To verify whether this model gives reasonable results we consider the experiments of Whitby *et al* [12]. Their flow enhancement indicates a slip length of 30-40 nm for pipes of radius 20 nm. Setting $L_s = 35$ nm, $R = 20$ nm determines their enhancement factor as $\epsilon_{slip} = 8$. Rearranging the expression for ϵ_μ gives

$$(14) \quad \mu_2 = \mu_1 \left[\frac{R^4 - \alpha^4}{\epsilon_\mu R^4 - \alpha^4} \right].$$

To obtain the same enhancement we set $\epsilon_\mu = 8$ and also take $\alpha = R - \delta = 19.3$ nm to find $\mu_2 = 0.018\mu_1$. So, the current model will provide an enhancement factor of 8 with an average viscosity in the depletion layer approximately 0.02 times that of the bulk flow. It is interesting to note that the viscosity of oxygen is also approximately 0.02 that of water, so this value supports the depletion layer theory.

To clarify the behaviour of the current model we set $\alpha = R - \delta$. Noting that ϵ_μ is simply a quartic in α we may expand and rearrange the expression to find

$$(15) \quad \epsilon_\mu = 1 + \frac{4\delta}{R} \left(\frac{\mu_1}{\mu_2} - 1 \right) \left[1 - \frac{3\delta}{2R} + \left(\frac{\delta}{R} \right)^2 - \frac{1}{4} \left(\frac{\delta}{R} \right)^3 \right],$$

which is a monotonically decreasing function of R . This is in accordance with the findings of Thomas & McGaughey [14] that the enhancement factor decreases with increasing tube radius. Noting that the reduced viscosity model requires two distinct regions, hence $R \geq \delta$, the limit to the enhancement predicted by the current theory is determined by setting $R = \delta$, $\mu_2/\mu_1 = 0.018$ and $\delta = 0.7$ nm to give $\epsilon_\mu \approx 50$ (Whitby *et al* predict an enhancement of up to 45 times theoretical predictions).

Equation (15) also allows us to make further inference about the model behaviour and its relation to the slip model. If we compare the above expression

with that for ϵ_{slip} we may define the slip length in terms of the thickness of the depletion layer and the viscosity ratio

$$(16) \quad L_s = \delta \left(\frac{\mu_1}{\mu_2} - 1 \right) \left[1 - \frac{3}{2} \frac{\delta}{R} + \left(\frac{\delta}{R} \right)^2 - \frac{1}{4} \left(\frac{\delta}{R} \right)^3 \right]$$

Further, noting that $\mu_1/\mu_2 \gg 1$, we can identify three distinct regimes:

- (1) For sufficiently wide tubes, such that $\delta/R \ll \mu_2/\mu_1$, then $\epsilon_\mu \approx 1$. There is no noticeable flow enhancement and the no-slip boundary condition will be sufficient.
- (2) For moderate tubes, such that $(\delta/R)(\mu_1/\mu_2)$ is order 1 but $\delta/R \ll 1$ then only the leading order term of L_s applies and

$$(17) \quad \epsilon_\mu \approx 1 + \frac{4\delta}{R} \left(\frac{\mu_1}{\mu_2} - 1 \right).$$

- (3) For very small tubes where δ/R is order 1 then the full expression for ϵ_μ is required.

To be specific, the no-slip Hagen-Poiseuille model is only appropriate when $\delta/R \ll \mu_2/\mu_1$. If we neglect the viscosity terms in the first regime, the error in the enhancement factor would be below 5% when $4\delta\mu_1/(R\mu_2) < 0.05$. With $\mu_2/\mu_1 = 0.018$ and $\delta = 0.7$ nm this requires $R > 3\mu\text{m}$. In the second regime the error would be below 5% for $3\delta/(2R) < 0.05$ or $R > 21$ nm. In this regime the apparent slip length $L_s \approx 39$ nm is approximately constant, as suggested by Cottin-Bizonne *et al* [16] and in keeping with a number of research groups who find slip-lengths in the range 20-40 nm for a wide range of length-scales [9, 12, 14, 16]. For $R < 21$ nm the slip length will decrease as the radius decreases.

3. CONCLUSIONS

The motivation behind this paper was to explain the unrealistically large slip-lengths reported in nanotubes. The mathematical model developed shows that the flow enhancement can be plausibly related to a reduced viscosity model, where the viscosity in the depletion region is always much lower than in the bulk. Theoretically, in pipes with a radius greater than the depletion layer thickness, it appears that the flow enhancement can only be enhanced by an order of magnitude (not orders as reported in some papers).

In answer to the question posed in the title “why are slip-lengths so large in carbon nanotubes?” we note that there is a clear analogy between the enhancement factor for the reduced viscosity model developed in this paper and that using a slip length. This indicates that the term ‘slip length’ is rather misleading. The usual physical interpretation is that the slip length represents a length-scale over which the fluid slips and consequently when this exceeds the dimension of the fluid it appears physically unrealistic. In fact it appears to be a length-scale proportional to the product of the viscosity ratio and the width of the depletion

region. This length-scale is a property of the fluid-solid system and remains approximately constant, down to very small radius tubes, and so can easily exceed the tube radius.

In a wider context the reduced viscosity model provides one possible explanation for the Navier slip boundary condition when the solid is smooth down to the nanoscale (and hence an explanation for flow enhancement). In other systems there may well be different mechanisms to explain the slip boundary condition, for example on rough surfaces one would expect the slip length to be determined by the roughness height-scale. A number of other factors will affect the flow, such as surface composition and hydrophobicity, shear rate, fluid composition *etc.* To a certain extent these could be incorporated into the definition of the depletion layer and average viscosity but clearly this must be linked to detailed experimental work which is beyond the scope of this theoretical study.

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TIM G. MYERS
CENTRE DE RECERCA MATEMÀTICA
CAMPUS DE BELLATERRA, EDIFICI C,
08193 BELLATERRA
BARCELONA, SPAIN
E-mail address: tmyers@crm.cat