

**PERIODIC SOLUTIONS OF SECOND-ORDER
DIFFERENTIAL INCLUSIONS SYSTEMS WITH
 p -LAPLACIAN**

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ABSTRACT. Some existence results are obtained for periodic solutions of nonautonomous second-order differential inclusions systems with p -Laplacian.

1. INTRODUCTION

Consider the second order system

$$(1) \quad \begin{aligned} \ddot{u}(t) &= \nabla F(t, u(t)) \text{ a.e. } t \in [0, T] \\ u(0) - u(T) &= \dot{u}(0) - \dot{u}(T) = 0 \end{aligned}$$

where $T > 0$ and $F : [0, T] \times \mathbb{R}^n \rightarrow \mathbb{R}$ satisfies the following assumption:

(A) $F(t, x)$ is measurable in t for each $x \in \mathbb{R}^n$ and continuously differentiable in x for a.e. $t \in [0, T]$, and there exist $a \in C(\mathbb{R}_+, \mathbb{R}_+)$, $b \in L^1(0, T; \mathbb{R}_+)$ such that

$$|F(t, x)| \leq a(\|x\|)b(t), \quad \|\nabla F(t, x)\| \leq a(\|x\|)b(t)$$

for all $x \in \mathbb{R}^n$ and a.e. $t \in [0, T]$.

In the last years many authors starting with Mawhin and Willem (see [2]) proved the existence of solutions for problem (1) under suitable conditions on the potential F (see [6]-[17]). Also in a series of papers (see [3]-[5]) we have generalized some of these results for the case when the potential F is just locally Lipschitz in the second variable x not continuously differentiable.

The aim of this paper is to consider the problem (1) in a more general sense. More exactly our results represent the extensions to systems with p -Laplacian and also with discontinuity (we consider the generalized gradients unlike continuously gradient in classical results).

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Consider the second order differential inclusions system

$$(2) \quad \begin{aligned} \frac{d}{dt}(\|\dot{u}(t)\|^{p-2}\dot{u}(t)) &\in \partial F(t, u(t)) \text{ a.e. } t \in [0, T], \\ u(0) &= u(T), \dot{u}(0) = \dot{u}(T), \end{aligned}$$

where $p > 1$, $T > 0$, $F : [0, T] \times \mathbb{R}^n \rightarrow \mathbb{R}$ and ∂ denotes the Clarke subdifferential.

We suppose that $F = F_1 + F_2$ and F_1, F_2 satisfy the following assumption:

(A') F_1, F_2 are measurable in t for each $x \in \mathbb{R}^n$, at least F_1 or F_2 are strictly differentiable in x and there exist $k_1, k_2 \in L^q(0, T; \mathbb{R})$ such that

$$\begin{aligned} |F_1(t, x_1) - F_1(t, x_2)| &\leq k_1(t)\|x_1 - x_2\|, \\ |F_2(t, x_1) - F_2(t, x_2)| &\leq k_2(t)\|x_1 - x_2\|, \end{aligned}$$

for all $x_1, x_2 \in \mathbb{R}^n$ and all $t \in [0, T]$.

The corresponding functional $\varphi : W_T^{1,p} \rightarrow \mathbb{R}$ is given by

$$\varphi(u) = \frac{1}{p} \int_0^T \|\dot{u}(t)\|^p dt + \int_0^T F(t, u(t)) dt.$$

Definition 1. A function $G : \mathbb{R}^n \rightarrow \mathbb{R}$ is called to be (λ, μ) -subconvex if

$$G(\lambda(x+y)) \leq \mu(G(x) + G(y))$$

for some $\lambda, \mu > 0$ and all $x, y \in \mathbb{R}^n$.

Remark 1. When $\lambda = \mu = \frac{1}{2}$, a function $(\frac{1}{2}, \frac{1}{2})$ -subconvex is called convex.

When $\lambda = \mu = 1$, a function $(1, 1)$ -subconvex is called subadditive.

When $\lambda = 1, \mu > 0$, a function $(1, \mu)$ -subconvex is called μ -subadditive.

2. MAIN RESULTS

Theorem 1. Assume that $F = F_1 + F_2$, where F_1, F_2 satisfy assumption (A') and the following conditions:

- (i) $F_1(t, \cdot)$ is (λ, μ) -subconvex with $\lambda > 1/2$ and $0 < \mu < 2^{p-1}\lambda^p$ for a.e. $t \in [0, T]$;
- (ii) there exist $c_1, c_2 > 0$ and $\alpha \in [0, p-1)$ such that

$$\zeta \in \partial F_2(t, x) \Rightarrow \|\zeta\| \leq c_1\|x\|^\alpha + c_2$$

for all $x \in \mathbb{R}^n$ and a.e. $t \in [0, T]$;

- (iii) for $q = \frac{p}{p-1}$,

$$\frac{1}{\|x\|^{q\alpha}} \left[\frac{1}{\mu} \int_0^T F_1(t, \lambda x) dt + \int_0^T F_2(t, x) dt \right] \rightarrow \infty, \text{ as } \|x\| \rightarrow \infty.$$

Then the problem (2) has at least one solution which minimizes φ on $W_T^{1,p}$.

Theorem 2. Assume that $F = F_1 + F_2$, where F_1, F_2 satisfy assumption (A') and the following conditions:

- (iv) $F_1(t, \cdot)$ is (λ, μ) -subconvex for a.e. $t \in [0, T]$, and there exists $\gamma \in L^1(0, T; \mathbb{R})$, $h \in L^1(0, T; \mathbb{R}^n)$ with $\int_0^T h(t)dt = 0$ such that

$$F_1(t, x) \geq \langle h(t), x \rangle + \gamma(t)$$

for all $x \in \mathbb{R}^n$ and a.e. $t \in [0, T]$;

- (v) there exist $c_1 > 0$, $c_0 \in \mathbb{R}$ such that

$$\zeta \in \partial F_2(t, x) \Rightarrow \|\zeta\| \leq c_1$$

for all $x \in \mathbb{R}^n$ and all $t \in [0, T]$, and

$$\int_0^T F_2(t, x)dt \geq c_0$$

for all $x \in \mathbb{R}^n$;

- (vi)

$$\frac{1}{\mu} \int_0^T F_1(t, \lambda x)dt + \int_0^T F_2(t, x)dt \rightarrow \infty, \text{ as } \|x\| \rightarrow \infty.$$

Then the problem (2) has at least one solution which minimizes φ on $W_T^{1,p}$.

Theorem 3. Assume that $F = F_1 + F_2$, where F_1, F_2 satisfy assumption (A') and the following conditions:

- (vii) $F_1(t, \cdot)$ is (λ, μ) -subconvex for a.e. $t \in [0, T]$, and there exists $\gamma \in L^1(0, T; \mathbb{R})$, $h \in L^1(0, T; \mathbb{R}^n)$ with $\int_0^T h(t)dt = 0$ such that

$$F_1(t, x) \geq \langle h(t), x \rangle + \gamma(t)$$

for all $x \in \mathbb{R}^n$ and a.e. $t \in [0, T]$;

- (viii) there exist $c_1, c_2 > 0$ and $\alpha \in [0, p-1)$ such that

$$\zeta \in \partial F_2(t, x) \Rightarrow \|\zeta\| \leq c_1 \|x\|^\alpha + c_2$$

for all $x \in \mathbb{R}^n$ and a.e. $t \in [0, T]$;

- (ix) for $q = \frac{p}{p-1}$,

$$\frac{1}{\|x\|^{q\alpha}} \int_0^T F_2(t, x)dt \rightarrow \infty, \text{ as } \|x\| \rightarrow \infty.$$

Then the problem (2) has at least one solution which minimizes φ on $W_T^{1,p}$.

Remark 2. Theorems 1, 2 and 3, generalizes the corresponding Theorems 2.1, 2.3 and 2.4 of [5]. In fact, it follows from these theorems letting $p = 2$.

3. THE PRELIMINARY RESULTS

We introduce some functional spaces. Let $[0, T]$ be a fixed real interval ($0 < T < \infty$) and $1 < p < \infty$. We denote by $W_T^{1,p}$ the Sobolev space of functions $u \in L^p(0, T; \mathbb{R}^n)$ having a weak derivative $\dot{u} \in L^p(0, T; \mathbb{R}^n)$. The norm over $W_T^{1,p}$ is defined by

$$\|u\|_{W_T^{1,p}} = \left(\int_0^T \|u(t)\|^p dt + \int_0^T \|\dot{u}(t)\|^p dt \right)^{\frac{1}{p}}.$$

We recall that

$$\|u\|_{L^p} = \left(\int_0^T \|u(t)\|^p dt \right)^{\frac{1}{p}} \text{ and } \|u\|_{\infty} = \max_{t \in [0, T]} \|u(t)\|.$$

For our aims it is necessary to recall some very well know results (for proof and details see [2]).

Proposition 4. *If $u \in W_T^{1,p}$ then*

$$\|u\|_{\infty} \leq c \|u\|_{W_T^{1,p}}.$$

If $u \in W_T^{1,p}$ and $\int_0^T u(t) dt = 0$ then

$$\|u\|_{\infty} \leq c \|\dot{u}\|_{L^p}.$$

Proposition 5. *If the sequence $(u_k)_k$ converges weakly to u in $W_T^{1,p}$, then $(u_k)_k$ converges uniformly to u on $[0, T]$.*

Let X be a Banach space. Now follows [1], for each $x, v \in X$, we define the *generalized directional derivative* at x in the direction v of a given $f \in Lip_{loc}(X, \mathbb{R})$ as

$$f^0(x; v) = \limsup_{y \rightarrow x, \lambda \searrow 0} \frac{f(y + \lambda v) - f(y)}{\lambda}$$

and we denote by

$$\partial f(x) = \{x^* \in X^* : f^0(x; v) \geq \langle x^*, v \rangle, \text{ for all } v \in X\}$$

the *generalized gradient* of f at x (the Clarke subdifferential).

We recall the *Lebourg's mean value theorem* (see [1], Theorem 2.3.7).

Theorem 6. *Let x and y be points in X , and suppose that f is Lipschitz on open set containing the line segment $[x, y]$. Then there exists a point u in (x, y) such that*

$$f(y) - f(x) \in \langle \partial f(u), y - x \rangle.$$

Clarke consider in [1] the following abstract framework:

- let (T, \mathcal{T}, μ) be a positive complete measure space with $\mu(T) < \infty$, and let Y be a separable Banach space;
- let Z be a closed subspace of $L^p(T; Y)$ (for some p in $[1, \infty)$), where $L^p(T; Y)$ is the space of p -integrable functions from T to Y ;
- define a functional f on Z via

$$f(x) = \int_T f_t(x(t))\mu(dt),$$

where $f_t : Y \rightarrow \mathbb{R}$, $(t \in T)$ is a given family of functions;

- suppose that for each y in Y the function $t \rightarrow f_t(y)$ is measurable, and that x is a point at which $f(x)$ is defined (finitely).

Hypothesis 1: There is a function k in $L^q(T, \mathbb{R})$, $\left(\frac{1}{p} + \frac{1}{q} = 1\right)$ such that, for all $t \in T$,

$$|f_t(y_1) - f_t(y_2)| \leq k(t)\|y_1 - y_2\|_Y \text{ for all } y_1, y_2 \in Y$$

Hypothesis 2: Each function f_t is Lipschitz (of some rank) near each point of Y , and for some constant c , for all $t \in T$, $y \in Y$, one has

$$\zeta \in \partial f_t(y) \Rightarrow \|\zeta\|_{Y^*} \leq c\{1 + \|y\|_Y^{p-1}\}.$$

Under this conditions described above Clarke prove (see [1], Theorem 2.7.5):

Theorem 7. *Under the conditions described above, under either of Hypothesis 1 or 2, f is uniformly Lipschitz on bounded subsets of Z , and one has*

$$\partial f(x) \subset \int_T \partial f_t(x(t))\mu(dt).$$

Further, if each f_t is regular at $x(t)$ then f is regular at x and equality holds.

Remark 3. *f is globally Lipschitz on Z when Hypothesis 1 hold.*

Now we can prove the following result.

Theorem 8. *Let $F : [0, T] \times \mathbb{R}^n \rightarrow \mathbb{R}$ such that $F = F_1 + F_2$ where F_1, F_2 are measurable in t for each $x \in \mathbb{R}^n$, and there exist $k_1 \in L^q(0, T; \mathbb{R})$, $a \in C(\mathbb{R}^+, \mathbb{R}^+)$, $b \in L^1(0, T; \mathbb{R}^+)$, $c_1, c_2 > 0$ and $\alpha \in [0, p - 1)$ such that*

$$|F_1(t, x_1) - F_1(t, x_2)| \leq k_1(t)\|x_1 - x_2\|$$

$$|F_2(t, x)| \leq a(\|x\|)b(t)$$

$$(3) \quad \zeta \in \partial F_2(t, x) \Rightarrow \|\zeta\| \leq c_1\|x\|^\alpha + c_2$$

for all $t \in [0, T]$ and all $x, x_1, x_2 \in \mathbb{R}^n$. We suppose that $L : [0, T] \times \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$, is given by $L(t, x, y) = \frac{1}{p}\|y\|^p + F(t, x)$.

Then, the functional $f : Z \in \mathbb{R}$, where

$$Z = \left\{ (u, v) \in L^p(0, T; Y) : u(t) = \int_0^t v(s)ds + c, c \in \mathbb{R}^n \right\}$$

given by $f(u, v) = \int_0^T L(t, u(t), v(t))dt$, is uniformly Lipschitz on bounded subsets of Z and one has

$$\partial f(u, v) \subset \int_0^T \{ \partial F_1(t, u(t)) + \partial F_2(t, u(t)) \} \times \{ \|v(t)\|^{p-2}v(t) \} dt.$$

Proof. Let $L_1(t, x, y) = F_1(t, x)$, $L_2(t, x, y) = \frac{1}{p}\|y\|^p + F_2(t, x)$ and $f_1, f_2 : Z \rightarrow \mathbb{R}$ given by $f_1(u, v) = \int_0^T L_1(t, u(t), v(t))dt$, $f_2(u, v) = \int_0^T L_2(t, u(t), v(t))dt$. For f_1 we can apply Theorem 7 under Hypothesis 1, with the following cast of characters:

- $(T, \mathcal{T}, \mu) = [0, T]$ with Lebesgue measure, $Y = \mathbb{R}^n \times \mathbb{R}^n$ be the Hilbert product space (hence is separable);
- $p > 1$ and

$$Z = \left\{ (u, v) \in L^p(0, T; Y) : u(t) = \int_0^t v(s)ds + c, c \in \mathbb{R}^n \right\}$$

be a closed subspace of $L^p(0, T; Y)$;

- $f_t(x, y) = L_1(t, x, y) = F_1(t, x)$; in our assumptions it results that the integrand $L_1(t, x, y)$ is measurable in t for a given element (x, y) of Y and there exists $k \in L^q(0, T; \mathbb{R})$ such that

$$\begin{aligned} & |L_1(t, x_1, y_1) - L_1(t, x_2, y_2)| = |F_1(t, x_1) - F_1(t, x_2)| \leq \\ (4) \quad & \leq k_1(t)\|x_1 - x_2\| \leq k_1(t)(\|x_1 - x_2\| + \|y_1 - y_2\|) = \\ & = k_1(t)\|(x_1, y_1) - (x_2, y_2)\|_Y \end{aligned}$$

for all $t \in [0, T]$ and all $(x_1, y_1), (x_2, y_2) \in Y$. Hence f_1 is uniformly Lipschitz on bounded subsets of Z and one has

$$\partial f_1(u, v) \subset \int_0^T \partial L_1(t, u(t), v(t))dt.$$

For f_2 we can apply Theorem 7 under Hypothesis 2 with the same cast of characters, but now $f_t(x, y) = L_2(t, x, y) = \frac{1}{p}\|y\|^p + F_2(t, x)$. In our assumptions it results that the integrand $L_2(t, x, y)$ is measurable in t for a given element (x, y) of Y and locally Lipschitz in (x, y) for each $t \in [0, T]$.

Proposition 2.3.15 from [1] implies

$$\partial L_2(t, x, y) \subset \partial_x L_2(t, x, y) \times \partial_y L_2(t, x, y) = \partial F_2(t, x) \times \{ \|y\|^{p-2}y \}.$$

Using (3) and (4), if $\zeta = (\zeta_1, \zeta_2) \in \partial L_2(t, x, y)$ it results $\zeta_1 \in \partial F_2(t, x)$ and $\zeta_2 = \|y\|^{p-2}y$, and hence

$$\|\zeta\| = \|\zeta_1\| + \|\zeta_2\| \leq c_1\|x\|^\alpha + c_2 + \|y\|^{p-1} \leq \tilde{c}\{1 + \|(x, y)\|^{p-1}\}$$

for each $t \in [0, T]$, since $\alpha < p-1$ and $p > 1$. Hence f_2 is uniformly Lipschitz on bounded subsets of Z and one has

$$\partial f_2(u, v) \subset \int_0^T \partial L_2(t, u(t), v(t)) dt.$$

It follows that $f = f_1 + f_2$ is uniformly Lipschitz on the bounded subsets of Z .

Proposition 2.3.3 and Proposition 2.3.15 from [1] implies

$$\begin{aligned} \partial f(u, v) &\subset \partial f_1(u, v) + \partial f_2(u, v) \subset \\ &\subset \int_0^T \left[\partial L_1(t, u(t), v(t)) + \partial L_2(t, u(t), v(t)) \right] dt \subset \\ &\subset \int_0^T \left[\left(\partial_x L_1(t, u(t), v(t)) \times \partial_y L_1(t, u(t), v(t)) \right) + \right. \\ &\quad \left. + \left(\partial_x L_2(t, u(t), v(t)) \times \partial_y L_2(t, u(t), v(t)) \right) \right] dt \subset \\ &\subset \int_0^T \left[\left(\partial_x L_1(t, u(t), v(t)) + \partial_x L_2(t, u(t), v(t)) \right) \times \right. \\ &\quad \left. \times \left(\partial_y L_1(t, u(t), v(t)) + \partial_y L_2(t, u(t), v(t)) \right) \right] dt = \\ &= \int_0^T \left(\partial F_1(t, u(t)) + \partial F_2(t, u(t)) \right) \times \{ \|v(t)\|^{p-2} v(t) \} dt. \end{aligned}$$

Moreover, Corollary 1 of Proposition 2.3.3 from [1] imply that, if at least of the functions F_1, F_2 is strictly differentiable in x for all $t \in [0, T]$ then

$$(5) \quad \partial f(u, v) \subset \int_0^T \partial F(t, u(t)) \times \{ \|v(t)\|^{p-2} v(t) \} dt.$$

□

Remark 4. *The interpretation of expression (5) is as follows: if (u_0, v_0) is an element of Z (so that $v_0 = \dot{u}_0$) and if $\zeta \in \partial f(u_0, v_0)$, we deduce the existence of a measurable function $(q(t), p(t))$ such that*

$$(6) \quad q(t) \in \partial F(t, u_0(t)) \text{ and } p(t) = \|v_0(t)\|^{p-2} v_0(t) \text{ a.e. on } [0, T]$$

and for any (u, v) in Z , one has

$$\langle \zeta, (u, v) \rangle = \int_0^T \{ \langle q(t), u(t) \rangle + \langle p(t), v(t) \rangle \} dt.$$

In particular, if $\zeta = 0$ (so that u_0 is critical point for $\varphi(u) = \int_0^T \left[\frac{1}{p} \|\dot{u}(t)\|^p + F(t, u(t)) \right] dt$), it then follows easily that $q(t) = \dot{p}(t)$ a.e., or taking into account (6)

$$\frac{d}{dt} (\|i_0(t)\|^{p-2} i_0(t)) \in \partial F(t, u_0(t)) \text{ a.e. on } [0, T],$$

so that u_0 satisfies the inclusions system (2).

Remark 5. Of course if $p = 2$ and F is continuously differentiable in x , then the system (2) becomes system (1).

4. PROOFS OF THE THEOREMS

Proof of Theorem 1. From (A') it follows immediately there exist $a \in C(\mathbb{R}_+, \mathbb{R}_+)$, $b \in L^1(0, T; \mathbb{R}_+)$ such that

$$|F_1(t, x)| \leq a(\|x\|)b(t),$$

for all $x \in \mathbb{R}^n$ and all $t \in [0, T]$. Like in [11] we obtain

$$F_1(t, x) \leq (2\mu\|x\|^\beta + 1)a_0b(t)$$

for all $x \in \mathbb{R}^n$ and all $t \in [0, T]$, where $\beta < p$ and $a_0 = \max_{0 \leq s \leq 1} a(s)$.

For $u \in W_T^{1,p}$, let $\bar{u} = \frac{1}{T} \int_0^T u(t) dt$ and $\tilde{u} = u - \bar{u}$. From Lebourg's mean value theorem it follows that for each $t \in [0, T]$ there exist $z(t)$ in $(\bar{u}, u(t))$ and $\zeta \in \partial F_2(t, z(t))$ such that $F_2(t, u(t)) - F_2(t, \bar{u}) = \langle \zeta, \tilde{u}(t) \rangle$. It follows from (ii) and Hölder's inequality that

$$\begin{aligned} \left| \int_0^T [F_2(t, u(t)) - F_2(t, \bar{u})] dt \right| &\leq \int_0^T |F_2(t, u(t)) - F_2(t, \bar{u})| dt \leq \\ &\leq \int_0^T \|\zeta\| \|\tilde{u}(t)\| dt \leq \int_0^T \left[2c_1(\|\bar{u}\|^\alpha + \|\tilde{u}(t)\|^\alpha) + c_2 \right] \|\tilde{u}(t)\| dt \leq \\ &\leq C_1 \|\tilde{u}\|_\infty^{\alpha+1} + C_2 \|\tilde{u}\|_\infty \|\bar{u}\|^\alpha + C_3 \|\tilde{u}\|_\infty \leq \\ &\leq C_4 \|\dot{u}\|_{L^p}^{\alpha+1} + \frac{1}{2p} \|\dot{u}\|_{L^p}^p + C_5 \|\dot{u}\|_{L^p} + C_6 \|\bar{u}\|^{q\alpha} \end{aligned}$$

for all $u \in W_T^{1,p}$ and some positive constants C_4 , C_5 and C_6 . Hence we have

$$\varphi(u) \geq \frac{1}{p} \int_0^T \|\dot{u}(t)\|^p dt + \frac{1}{\mu} \int_0^T F_1(t, \lambda \bar{u}) dt - \int_0^T F_1(t, -\tilde{u}(t)) dt +$$

$$\begin{aligned}
 & + \int_0^T F_2(t, \bar{u}) dt + \int_0^T [F_2(t, u(t)) - F_2(t, \bar{u})] dt \geq \\
 \geq & \frac{1}{2p} \|\dot{u}\|_{L^p}^p - C_4 \|\dot{u}\|_{L^p}^{\alpha+1} - C_5 \|\dot{u}\|_{L^p} - C_6 \|\bar{u}\|^{q\alpha} - (2\mu \|\tilde{u}\|_{\infty}^{\beta} + 1) \int_0^T a_0 b(t) dt + \\
 & + \frac{1}{\mu} \int_0^T F_1(t, \lambda \bar{u}) dt + \int_0^T F_2(t, \bar{u}) dt \geq \frac{1}{2p} \|\dot{u}\|_{L^p}^p - C_4 \|\dot{u}\|_{L^p}^{\alpha+1} - C_5 \|\dot{u}\|_{L^p} - \\
 & - C_7 \|\dot{u}\|_{L^p}^{\beta} - C_8 + \|\bar{u}\|^{q\alpha} \left\{ \frac{1}{\|\bar{u}\|^{q\alpha}} \left[\frac{1}{\mu} \int_0^T F_1(t, \lambda \bar{u}) dt + \int_0^T F_2(t, \bar{u}) dt \right] - C_6 \right\}
 \end{aligned}$$

for all $u \in W_T^{1,p}$, which implies that $\varphi(u) \rightarrow \infty$ as $\|u\| \rightarrow \infty$ by (iii) because $\alpha < p - 1$, $\beta < p$, and the norm $\|u\| = (\|\bar{u}\|^p + \|\dot{u}\|_{L^p}^p)^{\frac{1}{p}}$ is an equivalent norm on $W_T^{1,p}$. Now we write $\varphi(u) = \varphi_1(u) + \varphi_2(u)$ where

$$\varphi_1(u) = \frac{1}{p} \int_0^T \|\dot{u}(t)\|^p dt \text{ and } \varphi_2(u) = \int_0^T F(t, u(t)) dt.$$

The function φ_1 is weakly lower semi-continuous (w.l.s.c.) on $W_T^{1,p}$. From (i), (ii) and Theorem 7, taking to account Remark 3 and Proposition 5, it follows that φ_2 is w.l.s.c. on $W_T^{1,p}$. By Theorem 1.1 in [2] it follows that φ has a minimum u_0 on $W_T^{1,p}$. Evidently $Z \simeq W_T^{1,p}$ and $\varphi(u) = f(u, v)$ for all $(u, v) \in Z$. From Theorem 8, it results that f is uniformly Lipschitz on bounded subsets of Z , and therefore φ possesses the same properties relative to $W_T^{1,p}$. Proposition 2.3.2 in [1] implies that $0 \in \partial\varphi(u_0)$ (so that u_0 is critical point for φ). Now from Theorem 8 and Remark 4 it follows that the problem (2) has at least one solution $u \in W_T^{1,p}$. \blacksquare

Proof of Theorem 2. Let (u_k) be a minimizing sequence of φ . It follows from (iv), (v), Lebourg's mean value theorem and Proposition 4 that

$$\begin{aligned}
 \varphi(u_k) & \geq \frac{1}{p} \|\dot{u}_k\|_{L^p}^p + \int_0^T \langle h(t), u_k(t) \rangle dt + \int_0^T \gamma(t) dt + \\
 & + \int_0^T F_2(t, \bar{u}_k) dt - \int_0^T \|\zeta\| \|\tilde{u}_k(t)\| dt \geq \frac{1}{p} \|\dot{u}_k\|_{L^p}^p - \\
 & - \|\tilde{u}_k\|_{\infty} \int_0^T \|h(t)\| dt + \int_0^T \gamma(t) dt - c_1 \|\tilde{u}_k\|_{\infty} + c_0 \geq \\
 & \geq \frac{1}{p} \|\dot{u}_k\|_{L^p}^p - c_2 \|\dot{u}_k\|_{L^p} - c_3
 \end{aligned}$$

for all k and some constants c_2, c_3 , which implies that (\tilde{u}_k) is bounded. On the other hand, in a way similar to the proof of Theorem 1, one has

$$\left| \int_0^T [F_2(t, u(t)) - F_2(t, \bar{u})] dt \right| \leq \frac{1}{2p} \|\dot{u}\|_{L^p}^p + C_1 \|\dot{u}\|_{L^p}$$

for all k and some positive constant C_1 , which implies that

$$\begin{aligned} \varphi(u_k) &\geq \frac{1}{p} \|\dot{u}_k\|_{L^p}^p + \frac{1}{\mu} \int_0^T F_1(t, \lambda \bar{u}_k) dt - \int_0^T F_1(t, -\tilde{u}_k(t)) dt + \\ &+ \int_0^T F_2(t, \bar{u}_k) dt + \int_0^T [F_2(t, u(t)) - F_2(t, \bar{u}_k)] dt \geq \\ &\geq \frac{1}{2p} \|\dot{u}_k\|_{L^p}^p - a(\|\tilde{u}_k\|_\infty) \int_0^T b(t) dt - C_1 \|\dot{u}_k\|_{L^p} + \\ &+ \frac{1}{\mu} \int_0^T F_1(t, \lambda \bar{u}_k) dt + \int_0^T F_2(t, \bar{u}_k) dt \end{aligned}$$

for all k and some positive constant C_1 . It follows from (vi) and the boundedness of (\tilde{u}_k) that (\bar{u}_k) is bounded. Hence φ has a bounded minimizing sequence (u_k) . Now Theorem 2 follows like Theorem 1. \blacksquare

Proof of Theorem 3. From (vii), (viii) and Proposition 4 it follows that

$$\begin{aligned} \varphi(u) &\geq \frac{1}{p} \|\dot{u}\|_{L^p}^p + \int_0^T \langle h(t), u(t) \rangle dt + \\ &+ \int_0^T \gamma(t) dt + \int_0^T F_2(t, \bar{u}) dt + \int_0^T [F_2(t, u(t)) - F_2(t, \bar{u})] dt \geq \\ &\geq \frac{1}{2p} \|\dot{u}\|_{L^p}^p - \|\tilde{u}\|_\infty \int_0^T \|h(t)\| dt + \\ &+ \int_0^T \gamma(t) dt - C_1 \|\dot{u}\|_{L^p}^{\alpha+1} - C_2 \|\dot{u}\|_{L^p} + \int_0^T F_2(t, \bar{u}) dt - C_3 \|\bar{u}\|^{q\alpha} \geq \\ &\geq \frac{1}{2p} \|\dot{u}\|_{L^p}^p - C_1 \|\dot{u}\|_{L^p}^{\alpha+1} - C_4 (\|\dot{u}\|_{L^p} + 1) + \|\bar{u}\|^{q\alpha} \left[\frac{1}{\|\bar{u}\|^{q\alpha}} \int_0^T F_2(t, \bar{u}) dt - C_3 \right] \end{aligned}$$

for all $u \in W_T^{1,p}$ and some positive constants C_1, C_3 and C_4 . Now follows like in the proof of Theorem 1 that φ is coercive by (ix), which completes the proof. \blacksquare

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