# HOMOGENIZATION OF A 

CAPILLARY PHENOMENA

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#### Abstract

We study the height of a liquid in a tube when it contains a great number of thin vertical bars and when its border is finely strained. For this, one uses an epi-convergence method.


## 1. Introduction

Let $T$ be a cylindrical tube of height infinity, containing a compressible liquid and a great number of thin cyclindrical bars of radius $r$ which are distributed periodically with a period $\epsilon$ such that $r<\epsilon$ (see Figure 1). One supposes the bars are of the same material which is specified by the coefficient $\lambda$ (see (1) below). In section 2 we show that (see Proposition 2 and Theorem 1 ) when $(\epsilon, r \lambda)$ tends to $(0,0,0)$ the height of the liquid grows indefinitely, does not grow or take a certain height according to the rate $\frac{r \lambda}{\epsilon^{2}}$ being $+\infty, 0$ or finite (see Proposition 2 and Theorem 1).
Suppose now that the border of the tube is made of two alternate periodic bands with a period $\epsilon$. The band 1 of length $r$ is encrusted in the other of length $\epsilon-r(r<\epsilon)$ (see Figure 3). The different materials that constitute the bands are specified by the coefficients $k_{1}$ and $k_{2}$.

[^0]One shows that (see Theorem 2) when $(\epsilon, r)$ tends to $(0,0)$ the tube behaves like an intermediate and homogeneous one of coefficient $k_{1} a+$ $k_{2}(1-a)$, where $a=\lim _{(\epsilon, r) \rightarrow(0,0)} \frac{r}{\epsilon}$.


Figure 1. The tube with the bars.

## 2. Tube containing a great number of thin bars

### 2.1. Problem.

Let $T$ be a cylindrical tube of base $\Omega$ with radius $R$ and of height infinity, containing a compressible liquid of a finite volume. Let us divide $\Omega$ by a net of side $\epsilon$ and let us set in the center $x_{\epsilon, j}$ of the net $Y_{\epsilon, j}(j \in I$ the integer part of the real $\frac{|\Omega|}{\epsilon^{2}}$ ) an homogeneous vertical cylindrical bar $T_{h, j}$ of radius $r(r<\epsilon)$ where $h=(\epsilon, r, \lambda)$ (see Figures 1 and 2).

Let us denote the union of the bars $T_{h, j}$ by $T_{h}$ and let $\Omega_{h}=\Omega \backslash T_{h}$.


Figure 2
The height of the liquid is stabilizing when it satisfies the following minimization problem (see [3], [4]):

$$
\begin{equation*}
\operatorname{Min}\left\{J_{h}(v), v \in B V\left(\Omega_{h}\right)\right\} \tag{1}
\end{equation*}
$$

where

$$
J_{h}(v)=\int_{\Omega_{h}} \sqrt{1+|D v|^{2}}+c \int_{\Omega_{h}} v^{2}-\lambda \int_{\partial T_{h}} v-k \int_{\partial \Omega} v
$$

for $v \in B V\left(\Omega_{h}\right)$ the space of functions of bounded variation defined in $\Omega$ (see [5] for the definition and the properties of $B V(\Omega)$ ):

$$
B V(\Omega)=\left\{v \in L^{1}(\Omega), \int_{\Omega}|D v|<+\infty\right\}
$$

where
$\int_{\Omega}|D v|=\sup \left\{\sum_{k=1}^{n} \int_{\Omega} v(x) \frac{\partial \phi_{k}}{\partial x_{k}}(x) d x, \sum_{k=1}^{n} \phi_{k}^{2}(x) \leq 1, \phi_{k} \in C_{0}^{1}(\Omega) \forall k\right\}$.
$C_{0}^{1}(\Omega)$ is the space of functions defined in $\Omega$, of class $C^{1}$ with a compact support included in $\Omega$,

$$
\begin{aligned}
\int_{\Omega} \sqrt{1+|D v|^{2}} & =\sup \left\{\int_{\Omega} v(x) \phi_{0}(x) d x\right. \\
- & \left.\sum_{k=1}^{n} \int_{\Omega} v(x) \frac{\partial \phi_{k}}{\partial x_{k}}(x) d x, \sum_{k=0}^{n} \phi_{k}^{2}(x) \leq 1, \phi_{k} \in C_{0}^{1}(\Omega) \forall k\right\}
\end{aligned}
$$

The capillary constant $c$ is related to the pressure term of the liquid, $\lambda$ and $k$ are respectively the cosine of the contact angles (liquid, bar), (liquid, border) and which specify respectively the bars material and the tube border. The constants $c, \lambda$ and $k$ are supposed real positive numbers.

Problem. We look for the limit behavior of the height of the liquid when $h=(\epsilon, r, \lambda)$ tends to $(0,0,0)$.

### 2.2. Existence and extension of the solution.

Proposition 1. (See [3], [4]). The problem (1) has a unique positive solution in $B V\left(\Omega_{h}\right)$. Furthermore $u_{h} \in C^{2}\left(\overline{\Omega_{h}}\right)$ and is constant on the boundary $\partial T_{h, j}$ of the bar $T_{h, j}$ for all $j \in I$.

Let us cite a trace lemma in the space $B V(\Omega)$ which will be useful:
Lemma 1. (See [4]). Suppose that $\Omega$ is of class $C^{2}$ and satisfying an internal sphere condition of radius $r$ (i.e. for any boundary point $x \in \partial \Omega$, there is a ball $B$ of radius $r$ such that $B \subset \Omega$ and $x \in \partial B)$. Then there exists a positive constant ct such that for any $v \in B V(\Omega)$,

$$
\int_{\partial \Omega}|v| \leq \int_{\Omega}|D v|+\frac{c t}{r} \int_{\Omega}|v|
$$

Let us now state some estimates of $u_{h}$ :
Proposition 2. Let $a=\lim _{h \rightarrow 0} \frac{r \lambda}{\epsilon^{2}}$. Then,
i) If $a=+\infty$, then $\lim _{h \rightarrow 0} \int_{\Omega_{h}} u_{h}=+\infty$ and if $a$ is finite, then

$$
\lim _{h \rightarrow 0} \int_{\Omega_{h}} u_{h}=\frac{k|\partial \Omega|}{2 c}+\frac{\pi a|\Omega|}{c} .
$$

ii) If $a$ is finite, then $\int_{\Omega_{h}} u_{h}$ and $\int_{\Omega_{h}}\left|D u_{h}\right|$ are uniformly bounded for $\frac{\lambda}{\epsilon}$ bounded.

Proof: i) The problem (1) is equivalent to the Euler equation (see [4])

$$
\begin{array}{rlll}
-\operatorname{Div} T u_{h}+2 c u_{h} & =0 & \text { in } & \Omega_{h} \\
T u_{h} \cdot n=\lambda & \text { on } & \partial T_{h} \\
T u_{h} \cdot n=k & \text { on } & \partial \Omega, \tag{4}
\end{array}
$$

where $T v=\frac{D v}{\sqrt{1+|D v|^{2}}}$ and $n$ the outer normal.

Multiplying (2) by the characteristic function $\chi_{\Omega_{h}}$ and using the Green formula, (3) and (4),

$$
\begin{equation*}
\int_{\Omega_{h}} u_{h}=\frac{k|\partial \Omega|}{2 c}+\frac{\pi|\Omega|}{c} \frac{\lambda r}{\epsilon^{2}}, \tag{5}
\end{equation*}
$$

hence passing to the limit in (5), one obtains i).
ii) According to Lemma 1

$$
\begin{equation*}
\int_{\partial T_{h}} u_{h} \leq \int_{\Omega_{h}}\left|D u_{h}\right|+\frac{c t}{\epsilon} \int_{\Omega_{h}} u_{h} . \tag{6}
\end{equation*}
$$

Let $\tilde{u}_{h}$ be the extension of $u_{h}$ in $\Omega$ defined by

$$
\begin{align*}
& \tilde{u}_{h}=u_{h} \quad \text { in } \quad \Omega_{h}  \tag{7}\\
& \tilde{u}_{h}=u_{h, j} \quad \text { in } \quad T_{h, j} ; j \in I,
\end{align*}
$$

where $u_{h, j}$ is the value of $u_{h}$ on $\partial T_{h, j}$.
Using again Lemma 1, one has

$$
\begin{aligned}
\int_{\partial h} u_{h} & =\int_{\partial h} \tilde{u}_{h} \leq \int_{\Omega}\left|D \tilde{u}_{h}\right|+\frac{c t}{R} \int_{\Omega} \tilde{u}_{h} \\
& =\int_{\Omega}\left|D u_{h}\right|+\frac{c t}{R} \int_{\Omega_{h}} u_{h}+\frac{c t}{R} \int_{T_{h}} u_{h}
\end{aligned}
$$

$$
=\int_{\Omega}\left|D u_{h}\right|+\frac{c t}{R} \int_{\Omega_{h}} u_{h}+c t \frac{r}{R} \int_{\partial T_{h}} u_{h}
$$

$$
\leq(1+c t . r) \int_{\Omega_{h}}\left|D u_{h}\right|+c t \int_{\Omega_{h}} u_{h}
$$

where the last inequality of (9) is due to (6).
The inequality

$$
J_{h}\left(u_{h}\right) \leq J_{h}(0)=|\Omega|
$$

(6) and (9) yield

$$
(1-k-\lambda-k r) \int_{\Omega_{h}}\left|D u_{h}\right|+c \int_{\Omega} u_{h}^{2} \leq c t\left(1+\frac{\lambda}{\epsilon}\right) .
$$

Hence the assertion ii) holds.
The following proposition yields an extension of $u_{h}$ and of $J_{h}$ in $\Omega$ which will be useful afterwards.

Proposition 3. Suppose that $\lim _{h \rightarrow 0} \frac{\lambda}{\epsilon}$ is finite. Let $\tilde{u}_{h}$ be the extension of $u_{h}$ in $\Omega$ which is defined by (7), (8) and $\tilde{J}_{h}$ the extension of $J_{h}$ in $B V(\Omega)$ defined by

$$
\tilde{J}_{h}(v)=\int_{\Omega} \sqrt{1+|D v|^{2}}+c \int_{\Omega_{h}} v^{2}-\lambda \int_{\partial T_{h}} v_{i}-k \int_{\partial \Omega} v
$$

where $v_{i}$ is the trace of the restriction of $v$ in $\Omega_{h}$. Then
i) $\tilde{J}_{h}$ attains its minimum at the point $\tilde{u}_{h}$.
ii) The sequence $\tilde{u}_{h}$ is uniformly bounded in $B V(\Omega)$. In particular a subsequence of $\tilde{u}_{h}$, noted by $\tilde{u}_{h}$, converges to an element $u(u \in$ $B V(\Omega))$ in $L^{1}(\Omega)$.

Proof: i) For the existence and the regularity of the minimum of $\tilde{J}_{h}$ in $B V(\Omega)$ see [3], [4]. The minimum value of $\tilde{J}_{h}$ is attained at $\tilde{u}_{h}$ since $\tilde{J}_{h}\left(\tilde{u}_{h}\right)=J_{h}\left(u_{h}\right)$.
ii) From the definition of $\tilde{u}_{h}$,

$$
\begin{equation*}
\int_{\Omega}\left|D \tilde{u}_{h}\right|=\int_{\Omega_{h}}\left|D u_{h}\right| . \tag{10}
\end{equation*}
$$

On the other hand, using (6), one has

$$
\begin{equation*}
\int_{\Omega} \tilde{u}_{h}=\int_{\Omega_{h}} u_{h}+\frac{r}{2} \int_{\partial T_{h}} u_{h} \leq\left(1+c t \frac{r}{\epsilon}\right) \int_{\Omega_{h}} u_{h}+\frac{r}{2} \int_{\Omega_{h}}\left|D u_{h}\right| . \tag{11}
\end{equation*}
$$

Then, using Proposition 2, (10) and (11), one deduces that $\tilde{u}_{h}$ is uniformly bounded in $B V(\Omega)$ if $\lim _{(\lambda, \epsilon) \rightarrow(0,0)} \frac{\lambda}{\epsilon}$ is finite.

### 2.3. Epi-limit of the functional $\tilde{J}_{h}$.

The following proposition characterizes the epi-limit of the sequence $\tilde{J}_{h}$ (see [1], [2] for the definition and the properties of the epi-limit) when $h \rightarrow(0,0,0)$ :

Proposition 4. Suppose that $a=\lim _{h \rightarrow 0} \frac{\lambda r}{\epsilon^{2}}$ is finite. Then the sequence of the functionals $\tilde{J}_{h}$ epi-converges to the functional $J$ in $B V(\Omega)$ endowed with the topology of $L^{1}(\Omega)$ where

$$
J(v)=\int_{\Omega} \sqrt{1+|D v|^{2}}+c \int_{\Omega} v^{2}-2 \pi a \int_{\Omega} v-k \int_{\partial \Omega} v
$$

for $v \in B V(\Omega)$.

Proof: 1) Let $v \in B V(\Omega)$ and $v_{h}=v$. Since

$$
\lambda \int_{\partial T_{h}} v=\frac{r \lambda}{\epsilon^{2}} \sum_{j \in I} \epsilon^{2}\left(\frac{1}{\left|\partial T_{h, j}\right|} \int_{\partial T_{h, j}} v\right)
$$

then

$$
\lim _{h \rightarrow 0} \tilde{J}_{h}\left(v_{h}\right)=J(v)
$$

2) Let $v$ and $v_{h} \in B V(\Omega)$ such that $v_{h}$ converges to $v$ in $L^{1}(\Omega)$ when $h$ tends to $(0,0,0)$. Let $J_{h}^{\prime}$ the functional defined in $B V(\Omega)$ by

$$
J_{h}^{\prime}(v)=\int_{\Omega} \sqrt{1+|D v|^{2}}+c \int_{\Omega_{h}} v^{2}-\lambda \int_{\partial T_{h}} v_{i}-k \int_{\partial \Omega} v
$$

where $v_{i}$ is the trace, on $\partial T_{h}$, of the restriction of $v$ to $\Omega_{h}$.
Using the inequality (6),

$$
\begin{aligned}
J_{h}^{\prime}(v)-\tilde{J}_{h}\left(v_{h}\right) \leq & \left(\int_{\Omega} \sqrt{1+|D v|^{2}}-k \int_{\partial \Omega} v\right) \\
& -\left(\int_{\Omega} \sqrt{1+\left|D v_{h}\right|^{2}}-k \int_{\partial \Omega} v_{h}\right) \\
& +\int_{\partial T_{h}}\left|v_{h}-v\right|+c\left(\int_{\Omega} v^{2}-\int_{\Omega_{h}} v_{h}^{2}\right) \\
\leq & \left(\int_{\Omega} \sqrt{1+|D v|^{2}}-k \int_{\partial \Omega} v\right) \\
& -\left((1-\lambda) \int_{\Omega} \sqrt{1+\left|D v_{h}\right|^{2}}-k \int_{\partial \Omega} v_{h}\right) \\
& +c t \frac{\lambda}{\epsilon} \int_{\Omega}\left|v_{h}-h\right|+\lambda \int_{\Omega}|D v| \\
& +c\left(\int_{\Omega} v^{2}-\int_{\Omega_{h}} v_{h}^{2}\right) .
\end{aligned}
$$

Now, passing to the limitinf in (12), using the lower semi continuity of the functionsl $v \rightarrow \int_{\Omega} \sqrt{1+|D v|^{2}}-k \int_{\partial \Omega} v$ in $B V(\Omega)$ according to the topology of $L^{1}(\Omega)$ (see $[\mathbf{6}]$ ), Fatou Lemma, the fact that $v_{h}$ converges to $v$ in $L^{1}(\Omega)$ and that $\lim _{h \rightarrow 0} \frac{\lambda}{\epsilon}$ is finite, one deduces that

$$
J(v)=\liminf _{h \rightarrow 0} J_{h}^{\prime}(v) \leq \liminf _{h \rightarrow 0} \tilde{J}_{h}\left(v_{h}\right)
$$

### 2.4. Limit behavior.

According to the properties of the epi-convergence (see [1], [2]), one deduces the limit behavior of the problem (1) from Propositions 2 and 3.

Theorem 1. If $\lim _{h \rightarrow 0} \frac{\lambda r}{\epsilon^{2}}$ is finite, then the minimum $\tilde{J}_{h}\left(\tilde{u}_{h}\right)$ of $\tilde{J}$ converges to the minimum $J(u)$ and $\tilde{u}_{h}$ converges to $u$ in $L^{1}(\Omega)$ when $h$ tends to $(0,0,0)$.

Physic interpretation. When the section, of radius $r$, of the bars $T_{h, j}$ satisfies $r \gg \frac{\epsilon^{2}}{\lambda}$, the liquid rises indefinitely; when $r \ll \frac{\epsilon^{2}}{\lambda}$, it does not rise and when $r \simeq a \frac{\epsilon^{2}}{\lambda}, a \in(0,+\infty)$, the capillary problem in the tube with the bars is approximated by a capillary problem in the tube without bars with the same capillary constant $2 c$ but with $-2 \pi a$ as Lagrange parameter.

## 3. Tube with a strained border

Let $n \in N^{*}$ and $\epsilon=\frac{|\Omega|}{n}$. Suppose now that the border of the tube is formed by two bands which are distributed alternately and periodically with the period $\epsilon$ (see Figures 3 and 4$)$ : the boundary $\partial \Omega$ is formed by $n \operatorname{arcs} Y_{\epsilon, j}, j \in\{1, \ldots, n\}$ of length $\epsilon$. In the center of any arc $Y_{\epsilon, j}$ is encrusted an arc $T_{h, j}$ (band 1), $h=(\epsilon, r)$, of length $r(r<\epsilon)$. Suppose that the arcs $T_{h, j}$ are of the same material specified by the coefficient $k_{1}$ and the union of $Y_{\epsilon, j} \backslash T_{h, j}$ (band 2) is of another material specified by the coefficient $k_{2}$ (see (13)). Let us denote $T_{h}=\cup T_{h, j}$ and $(\partial \Omega)_{h}=\cup\left(Y_{\epsilon, j} \backslash T_{h, j}\right)$.

The height of the liquid is stabilizing when it satisfies the minimization problem (see [3], [4]):

$$
\begin{equation*}
\operatorname{Min}\left\{F_{h}(v), v \in B V(\Omega)\right\} \tag{13}
\end{equation*}
$$

where

$$
F_{h}(v)=\int_{\Omega_{h}} \sqrt{1+|D v|^{2}}+c \int_{\Omega} v^{2}-k_{1} \int_{T_{h}} v-k_{2} \int_{(\partial \Omega)_{h}} v
$$

for $v \in B V(\Omega) ; c$ is the capillary constant, $k_{1}, k_{2}$ are respectively the cosine of the contact angles (liquid, band 1) and (liquid, band 2). $c, k_{1}$, $k_{2}$ are supposed to be positive constants.


Figure 3. The tube with a strained border.

### 3.1. Existence.

Proposition 5. The problem (13) has a unique positive solution in $B V(\Omega), u_{h} \in C^{2}\left(\overline{\Omega_{h}}\right)$ and $u_{h}$ is bounded in $B V(\Omega)$. In particular a subsequence, noted $u_{h}$ converges to an element $u(u \in B V(\Omega))$ in $L^{1}(\Omega)$.

Proof: The proof of the existence is similar than the one of Proposition 1.

The problem (13) is equivalent to the equation

$$
\begin{align*}
& -\operatorname{Div} T u_{h}+2 c u_{h}=0 \quad \text { in } \quad \Omega  \tag{14}\\
& T_{u_{h} . n}=k_{1} \quad \text { on } \quad T_{h}  \tag{15}\\
& T u_{h} . n=k_{2} \quad \text { on } \quad \partial \Omega \backslash T_{h}, \tag{16}
\end{align*}
$$

where $T v=\frac{D v}{\sqrt{1+|D v|^{2}}}$ and $n$ the outer normal.

Multiplying (14) by the characteristic function $\chi_{\Omega_{h}}$ and using the Green formula, (15) and (16)

$$
\begin{equation*}
\int_{\Omega} u_{h}=\frac{1}{2 c}\left(k_{1}\left|T_{h}\right|+k_{2}\left|\partial \Omega \backslash T_{h}\right|\right)=\frac{|\Omega|}{2 c}\left(k_{1} \frac{r}{\epsilon}+k_{2} \frac{\epsilon-r}{\epsilon}\right) . \tag{17}
\end{equation*}
$$

The inequality

$$
J_{h}\left(u_{h}\right) \leq J_{h}(0)=|\Omega|
$$

and (see Lemma 1)

$$
\int_{\partial \Omega} u_{h} \leq \int_{\Omega}\left|D u_{h}\right|+\frac{c t}{R} \int_{\Omega} u_{h}
$$

yield

$$
\begin{equation*}
\left(1-k_{3}\right) \int_{\Omega}\left|D u_{h}\right|+c \int_{\Omega} u_{h}^{2} \leq \frac{c t . k_{3}}{R} \int_{\Omega} u_{h}+|\Omega| \tag{18}
\end{equation*}
$$

where $k_{3}=\max \left(k_{1}, k_{2}\right)$. The boundedness of $u_{h}$ in $B V(\Omega)$ is then a consequence of (17) and (18).


Figure 4

### 3.2. Epi-limit of the functional $F_{h}$.

The following proposition characterizes the epi-limit of the sequence $F_{h}$ when $h \rightarrow(0,0)$ :

Proposition 6. The sequence of the functionals $F_{h}$ epi-converges to the functional $F$ in $B V(\Omega)$ endowed within the topology of $L^{1}(\Omega)$ where

$$
F(v)=\int_{\Omega} \sqrt{1+|D v|^{2}}+c \int_{\Omega} v^{2}-\left[k_{1} a+k_{2}(1-a)\right] \int_{\partial \Omega} v
$$

for $v \in B V(\Omega) ; a=\lim _{h \rightarrow(0,0)} \frac{r}{\epsilon} \in[0,1]$.

Proof: 1) Let $v \in B V(\Omega)$ and $v_{h}=v$. Since

$$
\left.\int_{T_{h}} v=\frac{r}{\epsilon} \sum_{j \in I} \epsilon\left(\frac{1}{\left|T_{h, j}\right|}\right) \int_{\partial T_{h, j}} v\right)
$$

and

$$
\left.\int_{\partial \Omega \backslash T_{h}} v=\frac{\epsilon-r}{\epsilon} \sum_{j \in I} \epsilon\left(\frac{1}{\left|Y_{j} \backslash T_{h, j}\right|}\right) \int_{Y_{j} \backslash T_{h, j}} v\right)
$$

then

$$
\lim _{h \rightarrow 0} F_{h}\left(v_{h}\right)=F(v)
$$

2) Let $v$ and $v_{h} \in B V(\Omega)$ such that $v_{h}$ converges to $v$ in $L^{1}(\Omega)$ when $h$ tends to $(0,0)$.

Using Lemma 1

$$
\begin{align*}
F_{h}(v)-F_{h}\left(v_{h}\right) \leq & \left(\int_{\Omega} \sqrt{1+|D v|^{2}}-\int_{\Omega} \sqrt{1+\left|D v_{h}\right|^{2}}\right) \\
& +\int_{\partial \Omega}\left|v_{h}-v\right|+c\left(\int_{\Omega} v^{2}-\int_{\Omega_{h}} v_{h}^{2}\right)  \tag{19}\\
\leq & \left(\int_{\Omega} \sqrt{1+|D v|^{2}}-\int_{\Omega} \sqrt{1+\left|D v_{h}\right|^{2}}\right) \\
& +c t \frac{1}{R} \int_{\Omega}\left|v_{h}-v\right|+c\left(\int_{\Omega} v^{2}-\int_{\Omega} v_{h}^{2}\right)
\end{align*}
$$

Now, passing to the limitinf in (19), using the lower semi continuity of the functional $v \rightarrow \int_{\Omega} \sqrt{1+|D v|^{2}}$ in $B V(\Omega)$ according to the topology of $L^{1}(\Omega)$ (see [5]), Fatou Lemma and the fact that $v_{h}$ converges to $v$ in $L^{1}(\Omega)$, one deduces that

$$
F(v)=\liminf _{h \rightarrow 0} F_{h}(v) \leq \liminf _{h \rightarrow 0} F_{h}\left(v_{h}\right)
$$

### 3.3. Limit behavior.

From Proposition 6, one deduces the limit behavior of the problem (13).
Theorem 2. i) The minimum of $F_{h}$ converges, when $h$ tends to $(0,0)$, to the minimum of $F$ in $B V(\Omega)$ where

$$
F(v) \int_{\Omega} \sqrt{1+|D v|^{2}}+c \int_{\Omega} v^{2}-\left[k_{1} a+k_{2}(1-a)\right] \int_{\partial \Omega} v
$$

for $v \in B V(\Omega)$ and $a=\lim _{h \rightarrow 0} \frac{r}{\epsilon} \in[0,1]$.
ii) The functional $F$ attains its minimum at the point $u$ and $u_{h}$ converges to $u$ in $L^{1}(\Omega)$ when $h$ tends to $(0,0)$.

Physic interpretation. When the thickness $r$ of the band 1 satisfies $r \ll \epsilon(a=0)$, the tube behaves like an homogeneous one whose border is made only of the band 2 ; when $r \simeq \epsilon$, it behaves like an homogeneous one whose border is made only of the band 1 , and when $r \simeq a \epsilon, a \in(0,1)$, it behaves like an intermediate homogeneous one made only of a third material specified by its contact angle (liquid, border) whose cosine is $k_{1} a+k_{2}(1-a)$.

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