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EXISTENCE AND NONEXISTENCE OF RADIAL POSITIVE SOLUTIONS OF SUPERLINEAR ELLIPTIC SYSTEMS

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Abstract

The main goal in this paper is to prove the existence of radial positive solutions of the quasilinear elliptic system

$$(S^+) \begin{cases} -\Delta_p u = f(x, u, v) & \text{in } \Omega, \\ -\Delta_q v = g(x, u, v) & \text{in } \Omega, \\ u = v = 0 & \text{on } \partial\Omega, \end{cases}$$

where Ω is a ball in \mathbf{R}^N and f, g are positive continuous functions satisfying $f(x, 0, 0) = g(x, 0, 0) = 0$ and some growth conditions which correspond, roughly speaking, to superlinear problems. Two different sets of conditions, called strongly and weakly coupled, are given in order to obtain existence. We use the topological degree theory combined with the blow up method of Gidas and Spruck. When $\Omega = \mathbf{R}^N$, we give some sufficient conditions of nonexistence of radial positive solutions for Liouville systems.

1. Introduction and main results

We are concerned with the existence of radial positive solutions of the problem

$$(S^+) \begin{cases} -\Delta_p u = a(x)u|u|^{\alpha-1} + b(x)v|v|^{\beta-1} & \text{in } \Omega, \\ -\Delta_q v = c(x)u|u|^{\gamma-1} + d(x)v|v|^{\delta-1} & \text{in } \Omega, \\ u = v = 0 & \text{on } \partial\Omega, \end{cases}$$

where $\Omega := B_R$ is the ball in \mathbf{R}^N centered at zero and radius $R > 0$. Here as usual for $m > 1$ ($m = p, q$), Δ_m denotes the m -Laplacian operator.

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During the last years the problem of existence for (S^+) has been studied by many authors, see for example, [1], [2], [7], [8], [13], [14], [15], [17]. In particular in [16], Souto proved the existence of a positive solution taking Ω a smooth general bounded domain in \mathbf{R}^N and $p = q = 2$. In the case $p \neq q$, we mention the recent results of Boccardo, Fleckinger and de Thélin [2] where the authors prove the existence of solutions of the following problem:

$$\begin{cases} -\Delta_p u = a(x)u|u|^{\alpha-1} + b(x)v|v|^{\beta-1} + h_1(x) & \text{in } \Omega, \\ -\Delta_q v = c(x)u|u|^{\gamma-1} + d(x)v|v|^{\delta-1} + h_2(x) & \text{in } \Omega, \\ u = v = 0 & \text{on } \partial\Omega, \end{cases}$$

when

$$p - 1 \geq \alpha, \quad q - 1 \geq \delta$$

and

$$(p - 1)(q - 1) > \beta\gamma$$

with Ω a smooth general bounded domain in \mathbf{R}^N , and $h_1 \in L^{p'}(\Omega)$, $h_2 \in L^{q'}(\Omega)$. We remark that if h_1 and h_2 are identically zero, the solution (u, v) can be a trivial solution. Our goal is to find sufficient conditions on exponents α, β, γ , and δ in order to have a radial positive solution of (S^+) when Ω is a ball.

At this point, we introduce two subclasses of systems (S^+) :

1) System (S^+) is strongly coupled if

$$\text{i) } \beta \geq \frac{q\beta + p(q-1)}{p\gamma + q(p-1)}\alpha \quad \text{and} \quad \text{ii) } \gamma \geq \frac{p\gamma + q(p-1)}{q\beta + p(q-1)}\delta.$$

2) System (S^+) is weakly coupled if

$$\text{j) } \beta < \frac{q\beta + p(q-1)}{p\gamma + q(p-1)}\alpha \quad \text{or} \quad \text{jj) } \gamma < \frac{p\gamma + q(p-1)}{q\beta + p(q-1)}\delta.$$

Similarly, the weakly coupled definition has been introduced in De Figueiredo [6] when j) and jj) are both satisfied. It is interesting to note that our definition includes clearly this case.

The existence and nonexistence for quasilinear systems have been studied by several authors by using different approaches; recent results can be seen in [4], [5], [16]. For the scalar case see [3], [9] and [10].

Now, let us make the following assumptions

$$(H_1) \quad \max(p, q) < N,$$

$$(H_2) \quad a, b, c, d \in C^0([0, +\infty[)$$

and satisfy

$$\inf_{r \in [0, +\infty[} (a(r), b(r), c(r), d(r)) > 0,$$

$$(H_3) \quad (p - 1)(q - 1) < \beta\gamma.$$

We suppose that (S^+) is a superlinear system, i.e.,

$$(H_4) \quad p - 1 < \alpha \quad \text{and} \quad q - 1 < \delta.$$

The main results are the following.

Theorem 1.1. *We assume that the system S^+ is strongly coupled and that the hypotheses (H_1) , (H_2) , (H_3) and (H_4) hold. We suppose furthermore that*

$$(H_s) \quad \max \left\{ \frac{q\beta + p(q-1)}{\gamma\beta - (p-1)(q-1)} - \frac{N-p}{p-1}; \frac{p\gamma + q(p-1)}{\gamma\beta - (p-1)(q-1)} - \frac{N-q}{q-1} \right\} \geq 0,$$

is satisfied. Then, the problem (S^+) has a solution (u, v) in $C^1(B_R) \cap C^2(B_R \setminus \{0\})$, such that $u > 0$ and $v > 0$ in B_R .

Theorem 1.2. *We assume that the system (S^+) is weakly coupled and that the hypotheses (H_1) , (H_2) , (H_3) , and (H_4) hold. We suppose furthermore that*

$$(H_w) \quad \frac{N(p-1)}{N-p} > \alpha \quad \text{and} \quad \frac{N(q-1)}{N-q} > \delta,$$

is satisfied. Then the problem (S^+) has a solution (u, v) in $C^1(B_R) \cap C^2(B_R \setminus \{0\})$, such that $u > 0$ and $v > 0$ in B_R .

We will adapt rather classical techniques of the mapping degree: we will consider the solution operator S_1 associated to a problem (S^+) acting in a suitable functional space. Then, we will look for solutions of the problem as fixed points of S_1 . As it is usual in this setting, the main difficulty will be to obtain existence of a priori bounds of positive solutions.

This paper is organized as follows. Section 2 contains notations and some definitions of functional spaces and of operators S_λ and T_τ associated to the problem (S^+) . In Section 3 we treat the nonexistence of radial positive solution for the Liouville problem (S_∞^+) associated to (S^+) . This is the goal of Theorem 3.1. In Section 4 we get a priori estimates for the solutions of the system in the strongly coupled case and weakly coupled case. Finally in Section 5 we apply our results to obtain the proof of Theorems 1.1 and 1.2.

2. Notations

Besides fixing notations, in this section we recall the results that we use throughout the paper. Let R be a positive number; we consider the following space:

$$\chi := \{(u, v) \in C^0([0, R]) \times C^0([0, R]) \text{ such that } u(R) = v(R) = 0\}$$

endowed with the norm $\|(u, v)\| = \|u\|_\infty + \|v\|_\infty$, which makes it a Banach space. Let S_λ and $T_\tau: \chi \rightarrow \chi$ be the operators defined by $S_\lambda(u, v) = (S^1(u, v); S^2(u, v))$ and $T_\tau(u, v) = (T^1(u, v); T^2(u, v))$ such that

$$S^1(u, v)(r) := \lambda^{\frac{1}{p-1}} \int_r^R \left[t^{1-N} \int_0^t s^{N-1} (a(s)|u(s)|^\alpha + b(s)|v(s)|^\beta) ds \right]^{\frac{1}{p-1}} dt,$$

$$S^2(u, v)(r) := \lambda^{\frac{1}{q-1}} \int_r^R \left[t^{1-N} \int_0^t s^{N-1} (c(s)|u(s)|^\gamma + d(s)|v(s)|^\delta) ds \right]^{\frac{1}{q-1}} dt$$

and

$$T^1(u, v)(r) := \int_r^R \left[t^{1-N} \int_0^t s^{N-1} (a(s)|u(s)|^\alpha + b(s)|v(s) + \tau|^\beta) ds \right]^{\frac{1}{p-1}} dt,$$

$$T^2(u, v)(r) := \int_r^R \left[t^{1-N} \int_0^t s^{N-1} (c(s)|u(s)|^\gamma + d(s)|v(s)|^\delta) ds \right]^{\frac{1}{q-1}} dt.$$

It is well known that, for all $\lambda \in [0, 1]$ and for all $\tau \in [0, \infty[$, S_λ and T_τ are completely continuous operators on χ . From the Maximum Principle this implies that $S_\lambda(\chi) \subset \chi$ and that the problem (S^+) is equivalent to find some non trivial positive fixed point $(u, v) \in \chi$ of the operator (S_1) (by taking $\lambda = 1$) such that $u'(0) = v'(0) = 0$. The main difficulty will be to obtain suitable a priori estimates to guarantee that we are in the conditions of the fixed point theorem. To study this question, we use a Blow up argument like in Gidas-Spruck paper [9]. This technique transforms the problem (S^+) into a problem

$$(S_\infty^+) \begin{cases} -\Delta_p u = A_\infty(\|y\|)u|u|^{\alpha-1} + B_\infty(\|y\|)v|v|^{\beta-1} & \text{in } \mathbf{R}^N, \\ -\Delta_q v = C_\infty(\|y\|)u|u|^{\gamma-1} + D_\infty(\|y\|)v|v|^{\delta-1} & \text{in } \mathbf{R}^N, \\ u > 0 \text{ and } v > 0 & \text{in } \mathbf{R}^N, \end{cases}$$

where $A_\infty, B_\infty, C_\infty$ and D_∞ are positive continuous functions on $[0, +\infty[$.

A Liouville type Theorem proves that (S_∞^+) has no radial positive solutions. For the case $A_\infty = D_\infty = 0$, $p = q = 2$, $\beta > 1$ and $\gamma > 1$ this kind of theorems are obtained in [12] under the hypothesis

$$\frac{1}{\beta + 1} + \frac{1}{\gamma + 1} > \frac{N - 2}{2}.$$

3. Liouville’s Theorem

In this section we prove the nonexistence of radial positive solutions of the following Liouville’s system (S_∞^+) :

$$(3.1) \quad -\Delta_p u \geq a(x)u|u|^{\alpha-1} + b(x)v|v|^{\beta-1} \quad \text{in } \mathbf{R}^N,$$

$$(3.2) \quad -\Delta_q v \geq c(x)u|u|^{\gamma-1} + d(x)v|v|^{\delta-1} \quad \text{in } \mathbf{R}^N.$$

We will need the following fundamental lemmas given in [5].

Lemma 3.1. *Let $w \in C^1([0, R]) \cap C^2(]0, R])$, $w \geq 0$, satisfying*

$$(3.3) \quad -\frac{d}{dr} \left(r^{N-1} \left| \frac{dw}{dr}(r) \right|^{m-2} \frac{dw}{dr}(r) \right) \geq 0 \quad \text{on } [0, R],$$

with $N > m > 1$. Then, for any $r \in]0, \frac{R}{2}[$ we have:

$$(3.4) \quad w(r) \geq C_{N,m} r \left| \frac{dw}{dr}(r) \right|$$

where

$$(3.5) \quad C_{N,m} = \frac{m-1}{N-m} \left(1 - 2^{\frac{m-N}{m-1}} \right).$$

Lemma 3.2. *Let be a positive function $w \in C^0([0, +\infty[) \cap C^2(]0, +\infty[)$ satisfying*

$$(3.6) \quad -\frac{d}{dr} \left(r^{N-1} \left| \frac{dw}{dr}(r) \right|^{m-2} \frac{dw}{dr}(r) \right) \geq 0 \quad \text{in }]0, +\infty[$$

with $N > m > 1$. We suppose that for some real $r_0 \geq 0$ we have $w(r_0) > 0$. Then we obtain, $w(r) > 0$ for all $r \geq r_0$ and there exists $C_{N,m} > 0$ such that

$$(3.7) \quad r^{\frac{N-m}{m-1}} w(r) \geq C_{N,m} \quad \text{for any } r \geq r_0.$$

Theorem 3.1. *We assume (H_1) , (H_3) , (H_4) and one of the following assumptions:*

$$(H_s) \quad \max \left\{ \frac{q\beta + p(q-1)}{\beta\gamma - (p-1)(q-1)} - \frac{N-p}{p-1}; \frac{p\gamma + q(p-1)}{\beta\gamma - (p-1)(q-1)} - \frac{N-q}{q-1} \right\} \geq 0$$

$$(H_w) \quad \frac{N(p-1)}{N-p} > \alpha \quad \text{or} \quad \frac{N(q-1)}{N-q} > \delta.$$

Then the only radial positive solution of (S_∞^+) is $(0, 0)$.

Proof: We assume that the hypotheses (H_1) , (H_3) and (H_4) hold:

1st case: If (H_s) is satisfied, in [5] and [11] the authors prove the nonexistence of radial positive solutions of

$$(3.8) \quad -\Delta_p u \geq b(x)v|v|^{\beta-1} \quad \text{in } \mathbf{R}^N,$$

$$(3.9) \quad -\Delta_q v \geq c(x)u|u|^{\gamma-1} \quad \text{in } \mathbf{R}^N.$$

Applying this result, we deduce the nonexistence of radial positive solutions of (S_∞^+) .

2nd case: Let u, v be a radial positive solution of the system (S_∞^+) . We can rewrite it as

$$(3.10) \quad -(r^{N-1}|u'(r)|^{p-2}u'(r))' = r^{N-1} [a(r)|u(r)|^\alpha + b(r)|v(r)|^\beta],$$

$$(3.11) \quad -(r^{N-1}|v'(r)|^{q-2}v'(r))' = r^{N-1} [c(r)|u(r)|^\gamma + d(r)|v(r)|^\delta]$$

$$(3.12) \quad u'(0) = v'(0) = 0.$$

Integrating (3.10) and (3.11) on $(0, r)$ and taking into account that $u'(r), v'(r) < 0$, for $r > 0$, we find

$$(3.13) \quad -u'(r) \geq \left(\frac{a(0)}{N} \right)^{\frac{1}{p-1}} r^{\frac{1}{p-1}} (u(r))^{\frac{\alpha}{p-1}}$$

$$(3.14) \quad -v'(r) \geq \left(\frac{d(0)}{N} \right)^{\frac{1}{q-1}} r^{\frac{1}{q-1}} (v(r))^{\frac{\delta}{q-1}}.$$

Thus, from Lemma 3.1 we deduce that there exists some constant $C > 0$ depending only of (N, p, q, a, d) such that

$$(3.15) \quad u(r) \geq -C_{N,p} r u'(r) \geq C r^{\frac{p}{p-1}} (u(r))^{\frac{\alpha}{p-1}}$$

$$(3.16) \quad v(r) \geq -C_{N,q} r v'(r) \geq C r^{\frac{q}{q-1}} (v(r))^{\frac{\delta}{q-1}}$$

for all $r \in]0, +\infty[$.

Thus, by Lemma 3.2, there exists some constant $C > 0$ depending only of (N, p, q, a, d) and $r_0 > 0$ such that for all $r \geq r_0$, we have

$$(3.17) \quad 1 \geq Cr^{\frac{p}{p-1} - \frac{N-p}{p-1} \frac{\alpha-p+1}{p-1}}$$

and

$$(3.18) \quad 1 \geq Cr^{\frac{q}{q-1} - \frac{N-q}{q-1} \frac{\delta-q+1}{q-1}}.$$

Consequently if (H_w) is satisfied, we get

$$(3.19) \quad \frac{p}{p-1} - \frac{N-p}{p-1} \frac{\alpha-p+1}{p-1} > 0,$$

or

$$(3.20) \quad \frac{q}{q-1} - \frac{N-q}{q-1} \frac{\delta-q+1}{q-1} > 0.$$

Hence a contradiction. □

4. A priori bounds for positive solutions of (S^+)

In this section we will study a priori bounds for radial positive solutions of the system (S^+) , in the strongly coupled and weakly coupled cases. For that, we need the following lemma:

Lemma 4.1. *We assume that there is a sequence $\{(\tilde{u}_n, \tilde{v}_n)\}$ in $(C^1([0, R_n]) \cap C^2(]0, R_n]))^2$ of positive solutions of the following system (\tilde{S}_n) :*

$$(4.1) \quad -\frac{d}{dy} \left(y^{N-1} \left| \frac{d\tilde{u}_n}{dy}(y) \right|^{p-2} \frac{d\tilde{u}_n}{dy}(y) \right) = y^{N-1} F_n(\tilde{u}_n(y), \tilde{v}_n(y)),$$

$$(4.2) \quad -\frac{d}{dy} \left(y^{N-1} \left| \frac{d\tilde{v}_n}{dy}(y) \right|^{q-2} \frac{d\tilde{v}_n}{dy}(y) \right) = y^{N-1} G_n(\tilde{u}_n(y), \tilde{v}_n(y)),$$

$$(4.3) \quad \frac{d\tilde{u}_n}{dy}(0) = \frac{d\tilde{v}_n}{dy}(0) = \tilde{u}_n(R_n) = \tilde{v}_n(R_n) = 0$$

where

$$\begin{cases} F_n(\tilde{u}_n(y), \tilde{v}_n(y)) = [A_n(|y|)|\tilde{u}_n(y)|^\alpha + B_n(|y|)|\tilde{v}_n(y) + \tau_n'^{\beta}], \\ G_n(\tilde{u}_n(y), \tilde{v}_n(y)) = [C_n(|y|)|\tilde{u}_n(y)|^\gamma + D_n(|y|)|\tilde{v}_n(y)|^\delta], \end{cases}$$

where $\{(A_n, B_n, C_n, D_n)\}$ are sequences of positive functions in $(C^0_{\text{loc}}([0, +\infty[))^4$ which converge to $(A_\infty, B_\infty, C_\infty, D_\infty)$ in $(C^0_{\text{loc}}([0, +\infty[))^4$.
 If,

$$(4.4) \quad \lim_{n \rightarrow \infty} \tau'_n = 0, \quad \lim_{n \rightarrow \infty} R_n = +\infty,$$

and $0 < \|(\tilde{u}_n(0), \tilde{v}_n(0))\| \leq 1$ for all $n \in \mathbf{N}$, then there exists a subsequence $\{(\tilde{u}_{n_k}, \tilde{v}_{n_k})\}$ of $\{(\tilde{u}_n, \tilde{v}_n)\}$ converging in $(C^0_{\text{loc}}([0, +\infty[))^2$ and whose limit (\tilde{u}, \tilde{v}) is a positive radially symmetric solution of the following Liouville's system

$$(S^+_\infty) \begin{cases} -\Delta_p u = A_\infty(|y|)u|u|^{\alpha-1} + B_\infty(|y|)v|v|^{\beta-1} & \text{in } \mathbf{R}^N, \\ -\Delta_q v = C_\infty(|y|)u|u|^{\gamma-1} + D_\infty(|y|)v|v|^{\delta-1} & \text{in } \mathbf{R}^N. \end{cases}$$

Proof: We argue as in [5]. We first note that, since $\|(\tilde{u}_n(0), \tilde{v}_n(0))\| \leq 1$ there exists a subsequence $\{(\tilde{u}_{n_k}(0), \tilde{v}_{n_k}(0))\}$ which converges in \mathbf{R}^2 to $(\tilde{u}_0, \tilde{v}_0)$ such that $\|(\tilde{u}_0, \tilde{v}_0)\| \leq 1$.

Next we will prove that the restriction of $\{(\tilde{u}_n, \tilde{v}_n)\}$ to $[0, R']$ is equicontinuous in $(C^0([0, R']))^2$.

In fact, multiplying (4.1) by $\frac{d\tilde{u}_n}{dy}$ and (4.2) by $\frac{d\tilde{v}_n}{dy}$ we obtain the following equations:

$$(4.5) \quad \frac{p-1}{p} \frac{d}{dy} \left(\left| \frac{d\tilde{u}_n}{dy}(y) \right|^p \right) + \frac{N-1}{y} \left| \frac{d\tilde{u}_n}{dy}(y) \right|^p + F_n(\tilde{u}_n(y), \tilde{v}_n(y)) \frac{d\tilde{u}_n}{dy}(y) = 0$$

$$(4.6) \quad \frac{q-1}{q} \frac{d}{dy} \left(\left| \frac{d\tilde{v}_n}{dy}(y) \right|^q \right) + \frac{N-1}{y} \left| \frac{d\tilde{v}_n}{dy}(y) \right|^q + G_n(\tilde{u}_n(y), \tilde{v}_n(y)) \frac{d\tilde{v}_n}{dy}(y) = 0.$$

From (4.5) and (4.6) it follows that

$$(4.7) \quad \frac{p-1}{p} \frac{d}{dy} \left(\left| \frac{d\tilde{u}_n}{dy}(y) \right|^p \right) + a_n \frac{d\tilde{u}_n}{dy}(y) \leq 0$$

$$(4.8) \quad \frac{q-1}{q} \frac{d}{dy} \left(\left| \frac{d\tilde{v}_n}{dy}(y) \right|^q \right) + b_n \frac{d\tilde{v}_n}{dy}(y) \leq 0$$

where

$$(4.9) \quad a_n = 2 \max_{s \in [0, R']} \{A_n; B_n\} \quad \text{and} \quad b_n = 2 \max_{s \in [0, R']} \{C_n; D_n\}.$$

Since the sequence $\{(A_n, B_n, C_n, D_n)\}$ converges to $(A_\infty, B_\infty, C_\infty, D_\infty)$ in $(C^0([0, R']))^4$, then there exist $a_1 > 0$ and $b_1 > 0$ such that $\|a_n\| < a_1$ and $\|b_n\| < b_1$ for all $n \in \mathbf{N}$. Hence, from (4.7), (4.8) and by integrating from 0 to $y \in [0, R']$ we find that

$$(4.10) \quad \frac{p-1}{p} \left| \frac{d\tilde{u}_n}{dy}(y) \right|^p + a_1 \int_0^y \frac{d\tilde{u}_n}{dy}(s) ds \leq 0$$

$$(4.11) \quad \frac{q-1}{q} \left| \frac{d\tilde{v}_n}{dy}(y) \right|^q + b_1 \int_0^y \frac{d\tilde{v}_n}{dy}(s) ds \leq 0$$

and hence that

$$(4.12) \quad \left| \frac{d\tilde{u}_n}{dy}(y) \right| \leq C_1$$

$$(4.13) \quad \left| \frac{d\tilde{v}_n}{dy}(y) \right| \leq C_2$$

uniformly in n , which imply the equicontinuity of the sequence $\{(\tilde{u}_n, \tilde{v}_n)\}$. Thus, by the Ascoli-Arzelà Theorem, there exists a subsequence $\{(\tilde{u}_{n_k}, \tilde{v}_{n_k})\}$, such that $\{(\tilde{u}_{n_k}, \tilde{v}_{n_k})\}$ converges to (\tilde{u}, \tilde{v}) when $k \rightarrow \infty$, in $(C^0([0, R']))^2$. Now from (4.1) and (4.2) we have that $\{(\tilde{u}_{n_k}, \tilde{v}_{n_k})\}$ satisfy

$$(4.14) \quad \tilde{u}_{n_k}(0) - \tilde{u}_{n_k}(y) = \int_0^y \left(\frac{1}{t^{N-1}} \int_0^t s^{N-1} F_{n_k}(\tilde{u}_{n_k}(s), \tilde{v}_{n_k}(s)) ds \right)^{\frac{1}{p-1}} dt$$

$$(4.15) \quad \tilde{v}_{n_k}(0) - \tilde{v}_{n_k}(y) = \int_0^y \left(\frac{1}{t^{N-1}} \int_0^t s^{N-1} G_{n_k}(\tilde{u}_{n_k}(s), \tilde{v}_{n_k}(s)) ds \right)^{\frac{1}{q-1}} dt.$$

By the Dominated Convergence Theorem we obtain that (\tilde{u}, \tilde{v}) satisfy

$$(4.16) \quad \tilde{u}_0 - \tilde{u}(y) = \int_0^y \left(\frac{1}{t^{N-1}} \int_0^t s^{N-1} F_\infty(\tilde{u}(s), \tilde{v}(s)) ds \right)^{\frac{1}{p-1}} dt$$

$$(4.17) \quad \tilde{v}_0 - \tilde{v}(y) = \int_0^y \left(\frac{1}{t^{N-1}} \int_0^t s^{N-1} G_\infty(\tilde{u}(s), \tilde{v}(s)) ds \right)^{\frac{1}{q-1}} dt$$

where

$$F_\infty(\tilde{u}(s), \tilde{v}(s)) = [A_\infty(s)|\tilde{u}(s)|^\alpha + B_\infty(s)|\tilde{v}(s)|^\beta],$$

$$G_\infty(\tilde{u}(s), \tilde{v}(s)) = [C_\infty(s)|\tilde{u}(s)|^\gamma + D_\infty(s)|\tilde{v}(s)|^\delta],$$

which imply that $\tilde{u} \geq 0$ and $\tilde{v} \geq 0$ belong to $(C^1([0, R']) \cap C^2([0, R']))^2$ and satisfy

$$(4.18) \quad -\frac{d}{dy} \left(y^{N-1} \left| \frac{d\tilde{u}}{dy}(y) \right|^{p-2} \frac{d\tilde{u}}{dy}(y) \right) = y^{N-1} F_\infty(\tilde{u}(y), \tilde{v}(y)),$$

$$(4.19) \quad -\frac{d}{dy} \left(y^{N-1} \left| \frac{d\tilde{v}}{dy}(y) \right|^{q-2} \frac{d\tilde{v}}{dy}(y) \right) = y^{N-1} G_\infty(\tilde{u}(y), \tilde{v}(y)),$$

for all $y \in [0, R']$ and

$$(4.20) \quad \frac{d\tilde{u}}{dy}(0) = \frac{d\tilde{v}}{dy}(0) = 0.$$

We claim that \tilde{u} and \tilde{v} can be extended to $[0, +\infty[$. It is sufficient to note that we can repeat the above argument on an interval $[0, \bar{R}]$, $\bar{R} > R'$, for the convergent sequence $\{(\tilde{u}_{n_k}, \tilde{v}_{n_k})\}$ on $[0, R']$. We obtain in this manner (\bar{u}, \bar{v}) as solution of (4.18), (4.19) and (4.20) on $[0, \bar{R}]$ and which \bar{u}, \bar{v} satisfy

$$(4.21) \quad \bar{u}(y) = \tilde{u}(y) \quad \text{and} \quad \bar{v}(y) = \tilde{v}(y) \quad \text{on} \quad [0, \bar{R}].$$

It is now clear that \bar{u}, \bar{v} can be extended to $[0, +\infty[$ as a solution of (S_∞^+) which is such that $\bar{u} \geq 0, \bar{v} \geq 0$ for all $y \in [0, \infty[$ and Lemma 4.1 follows. \square

4.1. The strongly coupled case.

Proposition 4.1. *We assume that the system (S^+) is strongly coupled.*

Under the assumptions $(H_1), (H_2), (H_3), (H_4)$ and (H_s) , there exists some $C_0 > 0$ such that for all $\tau \in [0, \infty[$ and for all fixed points $(u, v) \in \chi$ of T_τ we have

$$(4.22) \quad \|(u, v)\| < C_0.$$

Proof: We suppose that there exist sequences $\{(\tau_n)\}$ and $\{(u_n, v_n)\}$ satisfying

$$(4.23) \quad (u_n, v_n) = T_{\tau_n}(u_n, v_n) \quad \forall n \in \mathbf{N}$$

and such that, at least for a subsequence; $\|(u_n, v_n)\| \rightarrow +\infty$ as $n \rightarrow +\infty$.

From the Maximum Principle (4.23) is equivalent that (u_n, v_n) satisfies in $[0, R]$

$$(4.24) \quad -(r^{N-1}|u'_n(r)|^{p-2}u'_n(r))' = r^{N-1} [a(r)|u_n(r)|^\alpha + b(r)|v_n(r) + \tau_n|^\beta],$$

$$(4.25) \quad -(r^{N-1}|v'_n(r)|^{q-2}v'_n(r))' = r^{N-1} [c(r)|u_n(r)|^\gamma + d(r)|v_n(r)|^\delta],$$

$$(4.26) \quad u'_n(0) = v'_n(0) = u_n(R) = v_n(R) = 0.$$

We introduce new functions \tilde{u}_n and \tilde{v}_n in the following way:

$$(4.27) \quad \tilde{u}_n(y) = \frac{u_n(r)}{\sigma_n^l},$$

$$(4.28) \quad \tilde{v}_n(y) = \frac{v_n(r)}{\sigma_n^k},$$

and we make the change of variables

$$(4.29) \quad y = \sigma_n r \quad \text{on} \quad [0, R],$$

where

$$(4.30) \quad \sigma_n = (u_n(0))^{\frac{1}{l}} + (v_n(0))^{\frac{1}{k}}$$

and l, k are positive numbers to be chosen below.

In this way we obtain that \tilde{u}_n and \tilde{v}_n are defined on the interval $[0, R\sigma_n]$ and satisfy the following system (\tilde{S}_n^+)

$$(4.31) \quad -\frac{d}{dy} \left(y^{N-1} \left| \frac{d\tilde{u}_n}{dy}(y) \right|^{p-2} \frac{d\tilde{u}_n}{dy}(y) \right) = y^{N-1} F_n(\tilde{u}_n(y), \tilde{v}_n(y)),$$

$$(4.32) \quad -\frac{d}{dy} \left(y^{N-1} \left| \frac{d\tilde{v}_n}{dy}(y) \right|^{q-2} \frac{d\tilde{v}_n}{dy}(y) \right) = y^{N-1} G_n(\tilde{u}_n(y), \tilde{v}_n(y)),$$

$$(4.33) \quad \frac{d\tilde{u}_n}{dy}(0) = \frac{d\tilde{v}_n}{dy}(0) = \tilde{u}_n(R_n) = \tilde{v}_n(R_n) = 0,$$

where

$$F_n(\tilde{u}_n(y), \tilde{v}_n(y)) = \left[A_n(y)|\tilde{u}_n(y)|^\alpha + B_n(y) \left| \tilde{v}_n(y) + \frac{\tau_n}{\sigma_n^k} \right|^\beta \right],$$

$$G_n(\tilde{u}_n(y), \tilde{v}_n(y)) = \left[C_n(y)|\tilde{u}_n(y)|^\gamma + D_n(y)|\tilde{v}_n(y)|^\delta \right]$$

and

$$(4.34) \quad A_n(y) = a \left(\frac{y}{\sigma_n} \right) \sigma_n^{-p+l(\alpha-p+1)} \quad B_n(y) = b \left(\frac{y}{\sigma_n} \right) \sigma_n^{-p-l(p-1)+k\beta},$$

$$(4.35) \quad C_n(y) = c \left(\frac{y}{\sigma_n} \right) \sigma_n^{-q+k(q-1)+l\gamma} \quad D_n(y) = d \left(\frac{y}{\sigma_n} \right) \sigma_n^{-q+k(\delta-q+1)},$$

$$(4.36) \quad R_n = R\sigma_n.$$

By choosing

$$(4.37) \quad l = \frac{p(q-1) + \beta q}{\beta\gamma - (p-1)(q-1)} \quad \text{and} \quad k = \frac{q(p-1) + p\gamma}{\beta\gamma - (p-1)(q-1)},$$

we obtain

$$(4.38) \quad A_n(y) = a \left(\frac{y}{\sigma_n} \right) \sigma_n^{l\alpha-k\beta}, \quad B_n(y) = b \left(\frac{y}{\sigma_n} \right),$$

$$(4.39) \quad C_n(y) = c \left(\frac{y}{\sigma_n} \right), \quad D_n(y) = d \left(\frac{y}{\sigma_n} \right) \sigma_n^{k\delta-l\gamma}.$$

Recall that \tilde{u}_n, \tilde{v}_n satisfy

$$(4.40) \quad \frac{d\tilde{u}_n}{dy}(y) \leq 0, \quad \tilde{u}_n(y) \leq 1 \quad \forall y \in [0, R_n],$$

$$(4.41) \quad \frac{d\tilde{v}_n}{dy}(y) \leq 0, \quad \tilde{v}_n(y) \leq 1 \quad \forall y \in [0, R_n]$$

and

$$(4.42) \quad (\tilde{u}_n(0))^{\frac{1}{l}} + (\tilde{v}_n(0))^{\frac{1}{k}} = 1.$$

Thus in order to apply Lemma 4.1, it remains to estimate $\tau'_n = \frac{\tau_n}{\sigma_n^k}$.

By integrating (4.24) from 0 to $r \in [0, R]$

$$(4.43) \quad -u'_n(r) \geq C r^{\frac{1}{p-1}} (v_n(r) + \tau_n)^{\frac{\beta}{p-1}},$$

thus from (4.43)

$$(4.44) \quad -u'_n(r) \geq C r^{\frac{1}{p-1}} \tau_n^{\frac{\beta}{p-1}},$$

integrating this inequality from 0 to R , we obtain that

$$(4.45) \quad u_n(0) \geq C R^{\frac{p}{p-1}} \tau_n^{\frac{\beta}{p-1}}.$$

Then, from (4.45), we have

$$(4.46) \quad \tau_n \leq C(u_n(0))^{\frac{p-1}{\beta}}$$

and hence,

$$\frac{\tau_n}{\sigma_n^k} \leq C \frac{(u_n(0))^{\frac{p-1}{\beta}}}{\sigma_n^k}.$$

By definition of σ_n , $0 \leq u_n(0) \leq \sigma_n^l$. Hence,

$$(4.47) \quad \frac{\tau_n}{\sigma_n^k} \leq C \sigma_n^{\frac{l(p-1)-k\beta}{\beta}}.$$

Thus, by the definition (4.37) of l and k , we have

$$l(p-1) - k\beta = -p.$$

Then

$$(4.48) \quad \frac{\tau_n}{\sigma_n^k} \leq C \sigma_n^{-\frac{p}{\beta}}$$

and hence $\tau'_n = \frac{\tau_n}{\sigma_n^k} \rightarrow 0$ as $n \rightarrow +\infty$. Moreover, we have that $\{(A_n, B_n, C_n, D_n)\}$ converges to $(A_\infty, b(0), c(0), D_\infty)$ in $C^0_{loc}([0, +\infty[)$, where $A_\infty = 0$ or $a(0)$ and $D_\infty = 0$ or $d(0)$. Consequently, in the sense of Lemma 4.1, the sequence $\{(\tilde{u}_n, \tilde{v}_n)\}$ converges to (\tilde{u}, \tilde{v}) , such that (\tilde{u}, \tilde{v}) satisfies

$$(S_\infty) \begin{cases} -\Delta_p \tilde{u} = A_\infty \tilde{u} |\tilde{u}|^{\alpha-1} + b(0) \tilde{v} |\tilde{v}|^{\beta-1} & \text{in } \mathbf{R}^N, \\ -\Delta_q \tilde{v} = c(0) \tilde{u} |\tilde{u}|^{\gamma-1} + D_\infty \tilde{v} |\tilde{v}|^{\delta-1} & \text{in } \mathbf{R}^N. \end{cases}$$

Thus, from Lemma 3.2, we have $\tilde{u} > 0$ and $\tilde{v} > 0$. But, since (H_s) is satisfied then, from Liouville's Theorem 3.1, the problem (S_∞) has no radial positive solution. Hence we obtain a contradiction and Proposition 4.1 is proved. \square

4.2. The weakly coupled case.

Before studying this case, we make some remarks on the sequence $\{(\tilde{u}_n, \tilde{v}_n)\}$ defined in the proof of Proposition 4.1, that is:

Claim 1. *If*

$$\lim_{n \rightarrow +\infty} \tilde{u}_n(0) = 0,$$

then we have

$$\lim_{n \rightarrow +\infty} \tilde{v}_n(0) > 0 \quad \text{and} \quad \gamma < \frac{p\gamma + q(p-1)}{q\beta + p(q-1)} \delta.$$

Proof: Before proving that, we will denote by C any positive constant depending only on the data. Now, let t_n be such that $\tilde{v}_n(t_n) = \frac{\tilde{v}_n(0)}{2}$. Since $\tilde{u}'_n \leq 0$ and $\tilde{v}'_n \leq 0$, by integrating the equation (4.32) on $[0, y]$ and later on $[0, t_n]$, we obtain

$$(4.49) \quad 0 < \frac{\tilde{v}_n(0)}{2} = \tilde{v}_n(0) - \tilde{v}_n(t_n) \leq C[t_n^q |\tilde{u}_n(0)|^\gamma + t_n^q \sigma_n^{k\delta - l\gamma} |\tilde{v}_n(0)|^\delta]^{\frac{1}{q-1}}.$$

Moreover, by integrating (4.31) and (4.32) from 0 to t_n , we get

$$(4.50) \quad -\tilde{u}'_n(t_n) \geq C t_n^{\frac{1}{p-1}} (\tilde{v}_n(t_n))^{\frac{\beta}{p-1}},$$

$$(4.51) \quad -\tilde{v}'_n(t_n) \geq C t_n^{\frac{1}{q-1}} \sigma_n^{k\delta - l\gamma} (\tilde{v}_n(t_n))^{\frac{\delta}{q-1}}.$$

On the other hand, from Lemma 3.1 and (4.50)–(4.51) we have

$$(4.52) \quad |\tilde{u}_n(0)|^{p-1} \geq |\tilde{u}_n(t_n)|^{p-1} \geq C t_n^p |\tilde{v}_n(t_n)|^\beta \geq C_{N,p} t_n^p \left| \frac{\tilde{v}_n(0)}{2} \right|^\beta$$

and

$$(4.53) \quad |\tilde{v}_n(0)|^{q-1} \geq |\tilde{v}_n(t_n)|^{q-1} \geq C t_n^q \sigma_n^{k\delta - l\gamma} |\tilde{v}_n(0)|^\delta.$$

Then, since $(\tilde{u}_n(0))^l + (\tilde{v}_n(0))^k = 1$ and

$$(4.54) \quad \lim_{n \rightarrow +\infty} \tilde{u}_n(0) = 0,$$

we obtain

$$(4.55) \quad \lim_{n \rightarrow +\infty} \tilde{v}_n(0) > 0.$$

Thus, from (4.52), (4.54) and (4.55) we have

$$(4.56) \quad \lim_{n \rightarrow +\infty} t_n = 0.$$

Hence, from (4.49), (4.55), (4.56) and (4.57) we deduce that

$$(4.57) \quad 0 < \limsup t_n^q \sigma_n^{k\delta - l\gamma} < +\infty.$$

Consequently, from (4.56), (4.57) and since we assume that

$$\lim_{n \rightarrow +\infty} \sigma_n = +\infty,$$

then we have $k\delta - l\gamma > 0$. By definition of numbers k, l Claim 1 follows. □

Proposition 4.2. *We assume that the system (S^+) is weakly coupled.*

Under the assumptions (H_1) , (H_2) , (H_3) , (H_4) , and (H_w) , there exists some $C_0 > 0$ such that for all $\tau \in [0, \infty[$ and for all fixed points $(u, v) \in \chi$ of T_τ we have

$$\|(u, v)\| < C_0.$$

Proof: We assume (H_1) , (H_2) , (H_3) , (H_4) , and (H_w) . Suppose that

$$j) \quad \beta < \frac{q\beta + p(q-1)}{p\gamma + q(p-1)}\alpha$$

is satisfied. Then as in the proof of Proposition 4.1, we suppose that there exist the sequences $\{(\tau_n)\}$ and $\{(u_n, v_n)\}$ which, at least for a subsequence, $\|(u_n, v_n)\| \rightarrow +\infty$ as $n \rightarrow +\infty$, satisfy $(u_n, v_n) = T_{\tau_n}(u_n, v_n)$. It is equivalent that (u_n, v_n) satisfies in $[0, R]$

$$(4.58) \quad \begin{aligned} -(r^{N-1}|u'_n(r)|^{p-2}u'_n(r))' &= r^{N-1} [a(r)|u_n(r)|^\alpha \\ &\quad + b(r)|v_n(r) + \tau_n|^\beta], \end{aligned}$$

$$(4.59) \quad \begin{aligned} -(r^{N-1}|v'_n(r)|^{q-2}v'_n(r))' &= r^{N-1} [c(r)|u_n(r)|^\gamma \\ &\quad + d(r)|v_n(r)|^\delta], \end{aligned}$$

$$(4.60) \quad u'_n(0) = v'_n(0) = u_n(R) = v_n(R) = 0.$$

We introduce new functions \tilde{u}_n and \tilde{v}_n in the following way:

$$(4.61) \quad \bar{u}_n(y) = \frac{u_n(r)}{\sigma_n^l},$$

$$(4.62) \quad \bar{v}_n(y) = \frac{v_n(r)}{\sigma_n^k}.$$

We make the change of variables

$$(4.63) \quad y = \frac{\sigma_n}{t_n}r \quad \text{on} \quad [0, R],$$

where

$$(4.64) \quad \sigma_n = (u_n(0))^{\frac{1}{l}} + (v_n(0))^{\frac{1}{k}}$$

and where $(t_n)_{n \in N}$ is some sequence to be chosen below.

In this way we obtain the following equations for \bar{u}_n and \bar{v}_n defined on the interval $[0, \frac{\sigma_n}{t_n}R]$ and

$$\begin{cases} -\frac{d}{dy} \left(y^{N-1} \left| \frac{d\bar{u}_n}{dy}(y) \right|^{p-2} \frac{d\bar{u}_n}{dy}(y) \right) = y^{N-1} F_n(\bar{u}_n(y), \bar{v}_n(y)), \\ -\frac{d}{dy} \left(y^{N-1} \left| \frac{d\bar{v}_n}{dy}(y) \right|^{q-2} \frac{d\bar{v}_n}{dy}(y) \right) = y^{N-1} G_n(\bar{u}_n(y), \bar{v}_n(y)), \\ \frac{d\bar{u}_n}{dy}(0) = \frac{d\bar{v}_n}{dy}(0) = \bar{u}_n(R_n) = \bar{v}_n(R_n) = 0, \end{cases}$$

where

$$(4.65) \quad F_n(\bar{u}_n(y), \bar{v}_n(y)) = \left[A_n(y) |\bar{u}_n(y)|^\alpha + B_n(y) \left| \bar{v}_n(y) + \frac{\tau_n}{\sigma_n^k} \right|^\beta \right],$$

$$(4.66) \quad G_n(\bar{u}_n(y), \bar{v}_n(y)) = \left[C_n(y) |\bar{u}_n(y)|^\gamma + D_n(y) |\bar{v}_n(y)|^\delta \right]$$

and

$$(4.67) \quad \begin{aligned} A_n(y) &= a \left(\frac{yt_n}{\sigma_n} \right) t_n^p \sigma_n^{-p+l(\alpha-p+1)} \\ B_n(y) &= b \left(\frac{yt_n}{\sigma_n} \right) t_n^p \sigma_n^{-p-l(p-1)+k\beta}, \end{aligned}$$

$$(4.68) \quad \begin{aligned} C_n(y) &= c \left(\frac{yt_n}{\sigma_n} \right) t_n^q \sigma_n^{-q+k(q-1)+l\gamma} \\ D_n(y) &= d \left(\frac{yt_n}{\sigma_n} \right) t_n^q \sigma_n^{-q+k(\delta-q+1)}, \end{aligned}$$

$$(4.69) \quad R_n = \frac{\sigma_n}{t_n} R.$$

By choosing the positive numbers l and k as in (4.37) we obtain

$$(4.70) \quad A_n(y) = a \left(\frac{yt_n}{\sigma_n} \right) t_n^p \sigma_n^{l\alpha-k\beta}, \quad B_n(y) = b \left(\frac{yt_n}{\sigma_n} \right) t_n^p,$$

$$(4.71) \quad C_n(y) = c \left(\frac{yt_n}{\sigma_n} \right) t_n^q, \quad D_n(y) = d \left(\frac{yt_n}{\sigma_n} \right) t_n^q \sigma_n^{k\delta-l\gamma}.$$

1st case: $\lim_{n \rightarrow +\infty} \bar{u}_n(0) > 0$.

By choosing $t_n = \sigma_n^{\frac{-l\alpha+k\beta}{p}}$, as in Lemma 4.1, we obtain that the first equation of the system (S_n^+) converges to the equation

$$(4.72) \quad -\Delta_p \bar{u} = a(0) \bar{u} |\bar{u}|^{\beta-1} \quad \text{in } R^N,$$

where $\bar{u} > 0$ is the limit of \bar{u}_n .

Thus, from (H_w) and Liouville's Theorem 3.1, the equation (4.72) has no radial positive solution. Hence the contradiction follows.

2nd case: $\lim_{n \rightarrow +\infty} \bar{u}_n(0) = 0$.

We recall that $\bar{u}_n(0) = \tilde{u}_n(0)$ and $\bar{v}_n(0) = \tilde{v}_n(0)$ where $(\tilde{u}_n, \tilde{v}_n)$ are the functions defined in the proof of Proposition 4.2. Then from our claim, we deduce that

$$\lim_{n \rightarrow +\infty} \bar{v}_n(0) > 0 \quad \text{and} \quad \gamma < \frac{p\gamma + q(p-1)}{q\beta + p(q-1)} \delta.$$

Consequently, in this case it suffices to choose $t_n = \sigma_n^{\frac{-k\delta + l\gamma}{q}}$. Then, we obtain that $\{\bar{v}_n\}$ converges to \bar{v} and \bar{v} satisfies

$$-\Delta_q \bar{v} = d(0)\bar{v}|\bar{v}|^{\delta-1} \quad \text{in } R^N.$$

Hence, as in the 1st case, we get a contradiction. □

Proposition 4.3. *Assume that (H_1) , (H_2) , (H_3) , and (H_4) hold. Moreover, assume that one of the assumptions (H_s) or (H_w) holds. Then, the family of operators $(T_\tau)_{\tau \geq 0}$ satisfies the following properties:*

- (P_1) $\exists \tau_0 > 0$ such that, if T_τ has a fixed point $(u, v)_\tau$ for some $\tau \geq 0$ then $\tau \leq \tau_0$.
- (P_2) $\exists C_0 > 0$ such that, if $(u, v)_\tau$ is a fixed point of T_τ with $\tau \leq \tau_0 + 1$, then $\|(u, v)_\tau\| \leq C_0$.

Proof: First, from the Maximum Principle, it follows that the problem

$$(4.73) \quad (u, v) = T_\tau((u, v))$$

is equivalent to find positive solutions u, v of the following system

$$(4.74) \quad -(r^{N-1}|u'(r)|^{p-2}u'(r))' = r^{N-1} [a(r)|u(r)|^\alpha + b(r)|v(r) + \tau|^\beta],$$

$$(4.75) \quad -(r^{N-1}|v'(r)|^{q-2}v'(r))' = r^{N-1} [c(r)|u(r)|^\gamma + d(r)|v(r)|^\delta],$$

$$(4.76) \quad u'(0) = v'(0) = u(R) = v(R) = 0.$$

It follows that $0 \leq u(r)$, $0 \leq v(r)$ and by integrating on $[0, r]$ we obtain

$$(4.77) \quad -u'(r) \geq C r^{\frac{1}{p-1}}(v(r) + \tau)^{\frac{\beta}{p-1}},$$

$$(4.78) \quad -v'(r) \geq C r^{\frac{1}{q-1}}(u(r))^{\frac{\delta}{q-1}}.$$

Thus from (4.77)

$$(4.79) \quad -u'(r) \geq C r^{\frac{1}{p-1}} \tau^{\frac{\beta}{p-1}}.$$

By integrating (4.79) from 0 to R , we obtain that

$$(4.80) \quad u(0) \geq C R^{\frac{p}{p-1}} \tau^{\frac{\beta}{p-1}}.$$

Now we suppose that (P_1) is not true. Then there is a sequence $\{\tau_n\}$ such that

$$(4.81) \quad \lim_{n \rightarrow +\infty} \tau_n = +\infty$$

and such that for each τ_n there exists a solution (u_n, v_n) of (4.74)–(4.76).

Then from (4.80) and (4.81), we have

$$(4.82) \quad \lim_{n \rightarrow +\infty} \|(u_n, v_n)\| = +\infty.$$

Hence, respectively if (H_s) [or (H_w)] holds then from Proposition 4.1 [Proposition 4.2] we obtain a contradiction.

We argue similarly if (P_2) is not true.

Then for all $n \in \mathbf{N}$ there exists $\tau_n \leq \tau_0$ and a solution (u_n, v_n) of (4.74)–(4.76) such that $\|(u_n, v_n)\| > n$, this implies that

$$\lim_{n \rightarrow +\infty} \|(u_n, v_n)\| = +\infty.$$

Hence, from Proposition 4.1, and Proposition 4.2 we deduce a contradiction and Proposition 4.3 is proved. \square

5. Proof of the theorems

Proposition 5.1. *We assume (H_1) , (H_2) and (H_3) . Then there exists a $\rho_1 > 0$ such that:*

$\forall \rho \in [0, \rho_1[$ and $\forall \lambda \in [0, 1]$, we have that $(0, 0)$ is the only fixed point of S_λ , in $B(0, \rho)$.

Proof: Let us take $\lambda \in [0, 1]$ and $(u, v) \in \chi$ such that

$$(5.1) \quad (u, v) = S_\lambda(u, v)$$

with $\|(u, v)\| = \rho > 0$. Notice that by the definition of S_λ we get $u' \leq 0$, $v' \leq 0$ in $[0, R]$. By integrating on $[0, R]$ we have

$$(5.2) \quad u(0) = \lambda^{\frac{1}{p-1}} \int_0^R \left[t^{1-N} \int_0^t s^{N-1} (a(s)|u(s)|^\alpha + b(s)|v(s)|^\beta) ds \right]^{\frac{1}{p-1}} dt,$$

$$(5.3) \quad v(0) = \lambda^{\frac{1}{q-1}} \int_0^R \left[t^{1-N} \int_0^t s^{N-1} (c(s)|u(s)|^\gamma + d(s)|v(s)|^\delta) ds \right]^{\frac{1}{q-1}} dt.$$

Hence $\|(u, v)\| = u(0) + v(0)$. Thus, from (H_3) there exist two numbers $l > 0$ and $k > 0$ such that

$$(5.4) \quad \frac{\beta}{p-1} > \frac{l}{k} > \frac{q-1}{\gamma}.$$

Denote

$$(5.5) \quad \sigma = (u(0))^{\frac{1}{l}} + (v(0))^{\frac{1}{k}},$$

then $\|(u, v)\| < \sigma^l + \sigma^k$ and from (5.2) and (5.3) we deduce,

$$(5.6) \quad (u(0))^{\frac{1}{l}} \leq C\lambda^{\frac{1}{l(p-1)}} [\sigma^{l\alpha} + \sigma^{k\beta}]^{\frac{1}{l(p-1)}},$$

$$(5.7) \quad (v(0))^{\frac{1}{k}} \leq C\lambda^{\frac{1}{k(q-1)}} [\sigma^{l\gamma} + \sigma^{k\delta}]^{\frac{1}{k(q-1)}}.$$

Summing up (5.6) and (5.7), we deduce that σ satisfies

$$(5.8) \quad 1 \leq C\lambda^{\frac{1}{l(p-1)}} [\sigma^{l(\alpha-p+1)} + \sigma^{k\beta-l(p-1)}]^{\frac{1}{l(p-1)}} \\ + C\lambda^{\frac{1}{k(q-1)}} [\sigma^{l\gamma-k(q-1)} + \sigma^{k(\delta-q+1)}]^{\frac{1}{k(q-1)}}.$$

Hence, there exist $m_1 > 0$, $m_2 > 0$ and $C > 0$ such that

$$(5.9) \quad C < \lambda^{m_1} \sigma^{m_2} \leq \sigma^{m_2}.$$

On the other hand, by definition of σ , there exists $m_3 > 0$ such that

$$(5.10) \quad \sigma \leq 2\rho^{m_3}.$$

Then, from (5.9) and (5.10) it suffices to choose ρ_1 such that $2^{1+\frac{1}{m_3}} \rho_1 = C^{\frac{1}{m_2 m_3}}$, to complete the proof of Proposition 5.1. \square

Proof of Theorem 1.1: From Proposition 4.3, it follows that for $\rho_2 = C_0 + 1$, the equation $(u, v) = T_\tau((u, v))$ with $(u, v) \in \partial B(0, \rho_2)$ has no solution for $\tau \in [0, \tau_0 + 1]$. Then, $\deg(I - T_\tau, B(0, \rho_2), 0)$ is well defined and by the property of topological degree we get that

$$(5.11) \quad \deg(I - T_\tau, B(0, \rho_2), 0) = \text{constant}, \quad \forall \tau \in [0, \tau_0 + 1].$$

Moreover, since for $\tau_1 = \tau_0 + 1$, the operator T_{τ_1} has no a fixed point in $B(0, \rho_2)$, we have

$$(5.12) \quad \deg(I - T_{\tau_1}, B(0, \rho_2), 0) = 0.$$

Then, it follows from (5.11), that

$$(5.13) \quad \deg(I - T_0, B(0, \rho_2), 0) = \deg(I - T_{\tau_1}, B(0, \rho_2), 0) = 0.$$

Moreover, from Proposition 5.1, for $\rho_1 > 0$ sufficiently small we have

$$(5.14) \quad \deg(I - S_\lambda, B(0, \rho_1), 0) = \text{constant} \quad \forall \lambda \in [0, 1].$$

Hence

$$(5.15) \quad \deg(I - S_1, B(0, \rho_1), 0) = \deg(I - S_0, B(0, \rho_1), 0) = +1.$$

Then, since $S_1 = T_0$ and from (5.13) and (5.15), by the excision property we obtain

$$(5.16) \quad \deg(I - S_1, B(0, \rho_2) \setminus B(0, \rho_1), 0) \neq 0.$$

So, there is a fixed point (u, v) of S_1 . Hence we obtain the conclusions in Theorem 1.1. \square

Proof of Theorem 1.2: Using Proposition 4.3, the proof of Theorem 1.2 is similar as the proof of Theorem 1.1. \square

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