patternize: An R package for quantifying color pattern variation

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1 Summary

The use of image data to quantify, study and compare variation in the colors and patterns of
 organisms requires the alignment of images to establish homology, followed by color-based
 segmentation of images. Here we describe an R package for image alignment and segmentation
 that has applications to quantify color patterns in a wide range of organisms.

2. patternize is an R package that quantifies variation in color patterns obtained from image
data. patternize first defines homology between pattern positions across specimens either
through manually placed homologous landmarks or automated image registration. Pattern
identification is performed by categorizing the distribution of colors using an RGB threshold, *k*means clustering or watershed transformation.

3. We demonstrate that patternize can be used for quantification of the color patterns in a
 variety of organisms by analyzing image data for butterflies, guppies, spiders and salamanders.
 Image data can be compared between sets of specimens, visualized as heatmaps and analyzed using
 principal component analysis (PCA).

4. patternize has potential applications for fine scale quantification of color pattern phenotypes
in population comparisons, genetic association studies and investigating the basis of color pattern
variation across a wide range of organisms.

18 Introduction

19 Natural populations often harbor great phenotypic diversity. Variation in color and pattern are of the more vivid examples of morphological variability in nature. Taxa as diverse as spiders (De 20 21 Busschere et al. 2012; Cotoras et al. 2016), insects (Katakura et al. 1994; Williams 2007), fish 22 (Endler 1983; Houde 1987), amphibians and reptiles (Calsbeek et al. 2008; Allen et al. 2013; 23 Balogová & Uhrin 2015; Rabbani et al. 2015), mammals (Hoekstra et al. 2006; Nekaris & Jaffe 2007) and plants (Clegg & Durbin 2000; Mascó et al. 2004) display natural variation in pigment 24 25 or structural colorations. The distribution of colors in specific patterns play an important role in 26 mate preference (Endler 1983; Kronforst et al. 2006), thermal regulation (Forsman et al. 2002), aposematism (Rojas et al. 2015) and crypsis (Nosil & Crespi 2006) and represent evolutionary 27 28 adaptations that in many cases have promoted diversification within lineages.

29 Measuring phenotypic variation in organismal color patterns can provide insights into their 30 underlying developmental and genetic architecture (Klingenberg 2010). However, precisely quantifying color pattern variation is challenging. Consistent comparisons of color patterns from 31 32 images requires the (1) homologous alignment and (2) color-based segmentation of the images. Homologous alignment can be performed by transforming one image onto another. This 33 34 transformation can be obtained from manually placed homologous landmarks or advanced image registration techniques, which can be stored and utilized to align color patterns extracted from the 35 images. Image segmentation concerns the categorization of pixels by color. Previously, examples 36 of color pattern quantification have been extensively developed for Heliconius butterflies (Color 37 38 Pattern Modelling (CPM) in Le Poul et al. 2014) and primates (Allen et al. 2015). However, these 39 applications are currently not easily accessible for use in other organisms. Similarly, advanced 40 solutions are available for biomedical image analysis (Modat et al. 2010a; Schindelin et al. 2012, 41 2015), but are not tailored towards quantifying color pattern variation.

Here, we present patternize, an approach to quantification of color pattern variation from 2D images using the R statistical computing environment (R Development Core Team 2013). The package provides utilities to extract, transform and superimpose color patterns as well as downstream analysis (Fig. 1). The provided R functions combine single transformation and color extraction approaches. While transformations are obtained from manually placed homologous landmarks (patLanRGB(), patLanK() or patLanW()) or automated image registration

(patRegRGB(), patRegK() or patRegW()), color-based segmentation of the patterns is 48 performed by using threshold RGB (Red, Blue and Green) values (patLanRGB() or 49 patRegRGB()), unsupervised classification of pixels into a set of clusters (patLanK() or 50 patReqK()) or watershed transformation (patLanW() or patReqW()). By extracting and 51 aligning color patterns from image data of large numbers of samples, patternize provides 52 quantitative measures of variation in color patterns that can be used for population comparisons, 53 54 genetic association studies and investigating dominance and epigenetic interactions of color pattern variation in a wide range of organisms. We demonstrate the utility of the package with Heliconius 55 56 butterflies and more challenging examples from guppy fish, Galápagos wolf spiders and 57 salamanders.

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59 Alignment

Superimposing color patterns to quantify variation in their expression requires the homologous
alignment of the anatomical structures they occur in. Image transformations for this alignment can
be obtained from landmark based transformations or image registration techniques.

Landmark based transformations: Landmark based transformations use discrete anatomical points 63 that are homologous among individuals in the analysis. Non-rigid, but uniform transformations 64 from one set of 'source' landmarks to a set of 'target' landmarks such as affine transformations 65 66 include translation, rotation, scaling and skewing (Hazewinkel 2001). Additionally, non-uniform changes in shape between the source and target landmarks can be accounted for by storing the 67 68 transformation as if it were 'the bending of a thin sheet of metal', the so-called *thin plate spline* 69 (TPS) transformation (Duchon 1976). Both the affine and TPS transformation can be calculated 70 from sets of landmarks (Fig. 2A). We implemented these landmark transformations using utilities 71 provided by the R package Morpho (Schlager 2016). Landmarks can be transformed using an 72 arbitrarily chosen reference sample or an average landmark shape obtained from a set of samples. 73 The average landmark shape is obtained by means of Procrustes superimposition of the samples 74 (Goodall 1991).

Image registration: Alternative to landmark based methods, fast and accurate image registration techniques are available for calculating a transformation from a source to target image based on

77 either intensity patterns or features such as points, lines or contours present in the images 78 (Goshtasby 2005) (Fig. 2A). We use a computation efficient intensity-based image registration technique implemented in the NiftyReg image registration library (Translational Imaging Group 79 (TIG) 2016) and made available in R through the RNiftyReq package (Clayden et al. 2017). This 80 81 methodology calculates the global transformation of an image by finding correspondences between 82 sub-volumes of the two images (Modat et al. 2010a,b). Correspondence is assessed using intensity-83 based similarity measures and used to calculate the transformation parameters through a least trimmed square (LTS) regression method (Modat et al. 2010a,b). The number of corresponding 84 85 sub-volumes to be included or considered as outliers in the calculation of the transformation can 86 be varied by the user. The global transform calculated by NiftyReg can be rigid (i.e. including 87 translation, rotation and scaling) or affine (i.e. translation, rotation, scaling and skewing).

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89 Color pattern extraction

Studying variation in color patterns requires the correct identification of the color boundaries.
 patternize provides functionality to categorize the distribution of colors using either an RGB
 threshold, *k*-means clustering or watershed transformation.

RGB threshold: Color boundaries can be extracted from images or the trait of interest using an RGB threshold (Fig. 2 and Fig. 3). By selecting pixels within a specified color range (specified as RGB value and offset) we provide a basic image segmentation approach that works well for extracting distinct color patterns. Additionally, for distinct color patterns, the RGB value can be iteratively recalculated as the average for the extracted color pixels. This latter approach permits patterns to be easily combined when extracted from sets of images that may have been taken under different light conditions resulting in differences in intensity and contrast.

100 k-means clustering: We implemented an unsupervised approach for color-based image 101 segmentation by using k-means clustering (Fig. 4 and Fig. 5) (Hartigan & Wong 1979). This 102 algorithm assigns pixel RGB values to k clusters by iteratively assigning each pixel in the image to 103 the RGB cluster that minimizes the distance between the pixel and the cluster centers. Cluster 104 centers are recalculated each iteration by averaging all pixels in the cluster until convergence. We 105 implemented k-means clustering using the R package stats (R Development Core Team 2013). 106 Clusters are first obtained from a reference image and then used as initial cluster centers for the k-107 means clustering of the subsequently analyzed images. This allows the program to match clusters 108 that represent the same color pattern in different images. For k-means clustering, the number of 109 clusters must be defined manually. For organisms with less distinct pattern boundaries, this is best 110 done by testing different numbers of clusters and choosing a number that best assigns pixels to 111 color patterns.

112 Watershed transformation: The watershed transformation is a powerful tool for image 113 segmentation (Fig. 6) (Beucher 1991). The concept of watershed treats the image as a topographic 114 map by calculating a gradient map with high values in parts of the image where pixel values change 115 abruptly (Fig. 6B). Subsequently, a flooding process propagates pattern and background labels 116 guided by the gradient map. Continuing the flooding until pattern and background labels meet, 117 determines the watershed lines (ridges in the topography) that are used to segment the image (Fig. 118 6C). We implemented the watershed algorithm with utilities from the R package imager 119 (Barthelme 2017) that is based on the image processing library CImg (Tschumperle 2004). In our 120 implementation, the pattern and background labels are chosen by manually identifying at least one 121 pattern and one background pixel (at least one for each separate pattern and background element). 122 This manual assignment helps the user to overcome potential differences in image lightning, glare 123 or overlap between pattern and background RGB values.

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125 Output

126 The main patternize functions generate a list of extracted color patterns from each image stored as a raster object (Hijmans 2016). These extracted patterns can be summed and visualized 127 as heatmaps or used to calculate the relative area of the color patterns. To better characterize 128 129 variation in color patterns among samples, we implemented linear principal component analysis 130 (PCA). For an extracted color pattern, PCA can be performed on the binary representation of the 131 aligned color pattern rasters obtained from each sample (Fig. 3-5). In this matrix, pixel coordinates 132 that have the color of interest in a sample have a value of one, whereas pixel coordinates without 133 the color have the value zero assigned. The variance-covariance matrix obtained from the binary 134 matrix for a color is suitable for PCA, which allows visualizing the main variations in color pattern 135 boundaries among or between groups of samples, as well as the predicted color pattern changes along the principal component (PC) axis (Johnson & Wichern 2007). In the visualization of the predicted color pattern changes, positive values present a higher predicted expression of the pattern, whereas negative values present the absence of the pattern. Note that parts of the color patterns that are expressed in all considered samples have a predicted value of zero, as these pixels do not contribute variance for the PCA analysis.

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142 Examples

143 RGB threshold pattern extraction in Heliconius butterflies: We demonstrate the utility of image 144 alignment and RGB threshold extraction in the forewing band area of *Heliconius erato* populations 145 (Fig. 2). *Heliconius* butterflies from the Neotropics display great diversity in forewing band shape, which is mainly defined by expression of the *wntA* gene (Van Belleghem *et al.*; Martin *et al.* 2012). 146 147 Expression of red pigments in the wing scales is on its turn defined by expression of the *optix* gene (Reed et al. 2011). Comparison of the landmark and image registration approach applied to the red 148 149 forewing band variation in *H. erato hydara* shows that both methods perform well (Fig. 2B). The 150 TPS transformation used in the landmark approach resulted in a better fit to the internal structures 151 of the wing (i.e. wing veins). The slight offset between the color pattern and vein position in the 152 image registration approach likely resulted from a bias in the linear transformation towards aligning 153 the outline of the wing and not including non-uniform changes in shape within the wing.

Next, we performed automated image registration and RGB threshold color extraction on the same forewing band area of *H. erato erato*. In this region of the wing, *H. e. erato* lacks *optix* expression and, thus, red scales. However, naturally occurring hybrids between *H. e. erato* and *H. e. hydara* show *optix* expression in the forewing band area (Fig. 3). With this example, we demonstrate the ability to compare homologous, but differing colored pattern elements (i.e. yellow versus red). The PCA analysis and relative area of the extracted patterns allow to differentiate the two groups of butterflies and indicate overexpression of the color pattern in hybrids.

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Automated registration and k-means clustering in guppies and spiders: To assess the general utility of our application across taxa, we applied the automated registration and k-means clustering approach to groups with more complex body shape and color pattern variation; guppy fish and Galápagos wolf spiders. Males of the guppy (*Poecilia reticulata*) vary greatly in their ornamental

patterns that have evolved in response to both natural and sexual selection. Several mutants have 166 167 been described among male guppies that affect color pattern expression. Manually quantifying the differences in color pattern expression among these mutations has provided valuable insights into 168 the developmental basis and interactions of the involved genes (Kottler et al. 2013). Here, we 169 170 summarized and compared the black and orange color patterns expressed in wild type (WT) versus 171 golden mutants of P. reticulata males using images obtained from Kottler et al. 2013 (images were used from backcrosses obtained from golden blue mutant females with heterozygous males from 172 173 crossing golden blue with inbred wild-derived Cumána populations) (Fig. 4). All images were 174 aligned to a target image using image registration and colors were k-means clustered into seven 175 groups. Before k-means color clustering, the background was masked using the outline of the guppy 176 in the target image. Our analysis of the black and orange color cluster strongly matched the 177 description presented in Kottler et al. 2013, demonstrating the absence of a posterior orange spot in golden mutants backcrossed into a Cumána population genetic background and more diffuse and 178 179 shifted black ornaments in the golden mutants.

180 Wolf spiders of the genus *Hogna* inhabit high elevation and coastal habitats on the Galápagos 181 islands Santa Cruz and San Cristobal (De Busschere et al. 2010). Despite the phylogenetically close 182 relationship of the high elevation and coastal populations within both islands, morphometric 183 analysis, including measurements of color intensity, have highlighted striking parallel phenotypic 184 divergence between the high elevation and coastal species between the islands (De Busschere *et al.* 2012). Coastal species appear to be paler with a more conspicuous median band on the carapace 185 186 compared to high elevation species. Here, we demonstrate the robustness of automated image registration by aligning the highly variable images of the wolf spiders (Fig. 5). By focusing on 187 188 correspondence between the images, the automated image registration technique manages to align 189 the spider's carapace, which is morphologically the most consistent part in the images. By assigning 190 colors in the spiders to only two clusters, we show a similar pattern as described in De Busschere 191 et al. (2012) in which the coastal species show a consistently broader and more conspicuous median 192 band on the carapace and pale lateral bands compared to the high elevation species.

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Watershed pattern extraction in fire salamanders: The glare that is usually present in images of amphibians can make it challenging to correctly extract the color patterns. Additionally, some pattern elements may be difficult to identify based on color alone. To overcome these difficulties, we illustrate the watershed segmentation using images of fire salamanders obtained from Balogová & Uhrin (2015) (Fig. 6). The fire salamander (*Salamandra salamandra*) is common to Europe and is black with yellow, orange or red spots or stripes. The watershed approach confidently identifies the orange pattern boundaries in the analyzed images. Combining this color pattern extraction approach with aligning the images allows users to identify regions in the salamander's body where spots or stripes are more consistently expressed.

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204 Concluding remarks and recommendations

Alignment: patternize provides an unbiased, fast and user-friendly approach for color pattern 205 206 analysis that is applicable to a wide variety of organisms. patternize takes jpeg images as input, 207 which can be downsampled to decrease computation times. While the landmark based approach is 208 computationally slightly faster, automated image registration removes the need for labor-intensive 209 landmark setting. Moreover, image registration reduces any variation introduced by differences in 210 how users manually place image landmarks. However, because automated registration uses 211 intensity patterns in the images, it can be highly sensitive to artifacts in the background and care should be taken by standardizing the experimental setup. For cases in which the background differs 212 213 starkly from the studied object, functionality is included that allows users to remove the background by providing RGB cutoff values. The package also allows users to review the image registration 214 progress to assess the quality of the automatic registration. 215

216 Color pattern extraction: Variation in photographic conditions complicates color pattern 217 extraction. The option for iteratively recalculating the RGB value and defining the start clusters for 218 k-means clustering from a reference image can improve color pattern extraction under these 219 conditions. However, setting correct RGB or cluster parameters may impact results and should be 220 optimized for each analysis. Appropriate RGB and offset values can be obtained, for instance, by 221 extracting RGB values from image pixels or areas of interest (e.g. use sampleRGB()). Using few 222 or many k-means clusters may, respectively, result in grouping colors of interest or assigning 223 multiple clusters to a single pattern of interest. Finally, in contrast to RGB threshold color extraction and k-means clustering, watershed transformation takes into account the spatial 224 225 proximity of pixels. Doing so, the interactive identification of pattern versus background in the watershed transformation provides a way to extract color patterns that is robust to variation inphotographic conditions.

Output: The output of the main patternize functions are raster objects (Hijmans 2016) that provide for a wide range of downstream analyses. As demonstrated by the examples, we provide functions to intersect (mask) the extracted patterns with defined outlines, sum or subtract the patterns to plot heatmaps, calculate the relative area in which the pattern is expressed and carry out principal component analysis (PCA). Overall, we hope this R package provides a useful tool for the community of researchers working on color and pattern variation in animals.

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244 Data accessibility

245 The package and descriptions of the functions and parameters are available as library("patternize") on CRAN (cran.r-project.org/web/packages/patternize). The code, ongoing developments and data 246 247 and code used for the examples be accessed through GitHub can (github.com/StevenVB12/patternize; github.com/StevenVB12/patternize-examples). Bug reports 248 249 and feature requests can be sent using the GitHub issue tracker.

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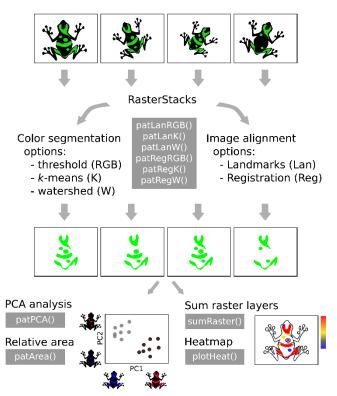
251 Author contributions

SMVB and BAC conceived the development of the package. SMVB wrote the code. SMVB, RP and BAC wrote the manuscript. HOZ helped improving the code. SMVB, BAC, FH and RP conceived data acquisition. HOZ, FH, CDJ and WOM contributed helpful comments for building the package and writing the manuscript. All authors contributed critically to the drafts and gave final approval for publication.

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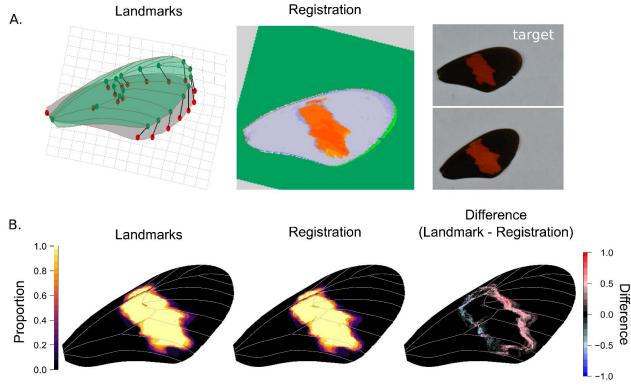
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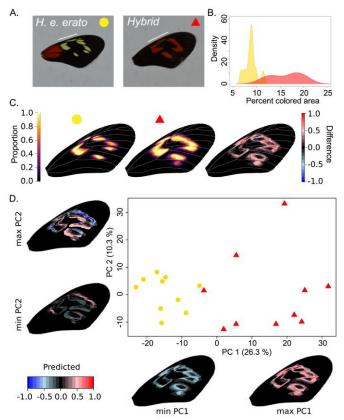
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Fig. 1. Overview of main patternize functions and functionality. Images can be aligned using homologous landmarks (Lan) or automatic registration (Reg), which aligns images using common intensity patterns. Colors can be extracted using an RGB threshold (RGB), *k*-means clustering (K) or by identifying watershed lines (W). The resulting extracted patterns can be summed and visualized as heatmaps or used for PCA analysis and calculating the relative area of the color patterns.





360 Fig. 2. Comparison of image transformation using landmarks or automated registration for quantification of color 361 pattern variation. (A.) Illustration of transformation strategies of a source (green) image to a target (gray) image. The 362 thin plate spline (TPS) transformation from the source to target landmarks is illustrated by the deformed grid and can be used to transform the image or extracted color pattern. Image registration attempts to find common patterns in 363 364 images and align the source (green) image to the pixel coordinate system of the target (gray) image. Note the extracted 365 color pattern in red. (B.) Example comparison between landmark approach for color pattern alignment for ten butterfly 366 wings of male Heliconius erato hydara. For the landmark approach, we used TPS transformation. For the image 367 registration approach, we used affine transformation and 75% of sub-volumes included as inliers.



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369 Fig. 3. Example of image registration and threshold color extraction in the forewing band area of Heliconius erato 370 *erato* (n = 10) and hybrid (n = 10) butterflies (French Guiana). (A.) Example of original images with a white line 371 indicating the forewing band area. The hybrid represents a naturally occurring backcross in a hybrid zone with H. e. 372 hydara (see Fig. 1) that results in red color expression in the forewing band. (B.) Density plot showing the probability 373 to find a sample with a certain percentage of colored area in the wing expressing yellow in H. e. erato and red in the 374 hybrid. (C.) Visualizing the variation in color pattern expression in a heatmap shows a consistently larger pattern in 375 the hybrid phenotypes (H. e. erato: left, hybrid: middle, hybrid minus H. e. erato: right). (D.) Principal component 376 analysis (PCA) confirms that the main axis of variation (PC1) is related to size of the pattern (yellow or red in H. e. 377 erato and hybrids, respectively) and separates the H. e. erato and hybrid samples. The second principal component 378 (PC2) axis highlights more complex shape differences in the forewing band among the samples as demonstrated by 379 the shape changes of the color patterns along the principal component axis.

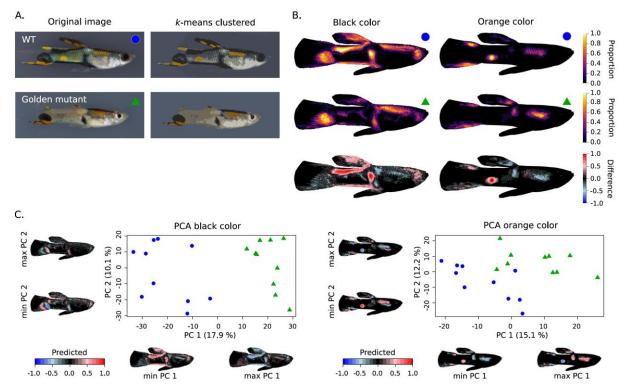
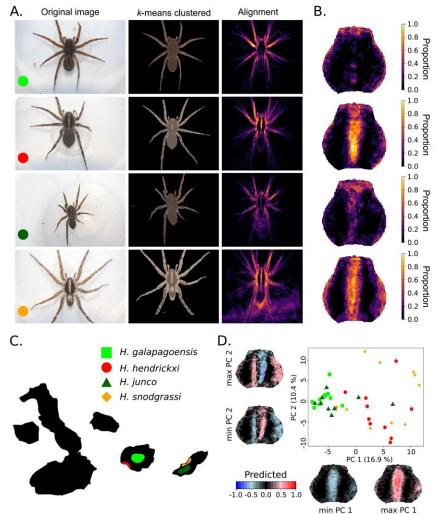
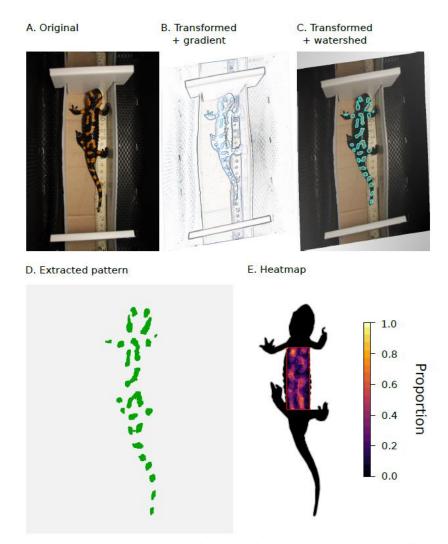


Fig. 4. Example of image registration and *k*-means clustering of colors in guppies (*Poecilia reticulata*). (A.) Original image of a wild type (WT) and *golden* mutant guppy and their *k*-means clustered representation (clusters = 7). (B.) Heatmaps and difference between WT (n=10) and golden mutant (n=10) for black and orange color clusters. (D.) PCA analysis of the pixel matrices obtained for the black (left) and orange (right) color clusters. Images were obtained with permission from Kottler *et al.* (2013).

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386 387 Fig. 5. Example of image registration and k-means clustering of the color pattern of Galápagos wolf spiders (Hogna). 388 (A.) From left to right: example of original image (10 images were used for each species), k-means clustered image (k 389 = 3) with removed background, and alignment of the lightest color. (B.) Heatmap corresponding to the lightest color 390 cluster focused on the carapace. (C.) Map of the Galápagos islands with colors indicating the distribution of four Hogna 391 species, two high elevation species (light and dark green) and two coastal species (red and orange). (D.) PCA analysis 392 of the pixel matrices obtained for the lightest color cluster demonstrates that the coastal (H. hendrickxi and H. 393 snodgrassi) and high-elevation (H. galapagoensis and H. junco) species cluster phenotypically together and share, 394 respectively, the presence and absence of a pale median band on their carapace. Images were obtained with permission 395 from De Busschere et al. (2012).



396 397 Fig. 6. Example of watershed transformation for color pattern extraction in fire salamanders (Salamandra salamandra). 398 (A.) Original image. (B.) Image gradient transformed to a reference shape using landmarks. (C.) Transformed image 399 with watershed lines highlighted. (D.) Extracted patterns using the watershed lines. (E.) Heatmap of orange patterns

400 extracted from ten male fire salamanders. Areas outside the red box were masked. Images were obtained with permission from Balogová & Uhrin (2015). 401