

A mathematical approach to retinal waves

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A mathematical approach to retinal waves

B. Cessac, D. Karvouniari Biovision team, INRIA, Sophia Antipolis



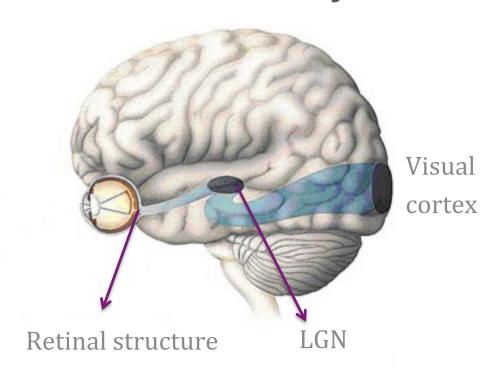


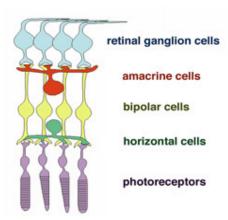
Acknowledgement

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- S. Picaud, Institut de la Vision, Paris

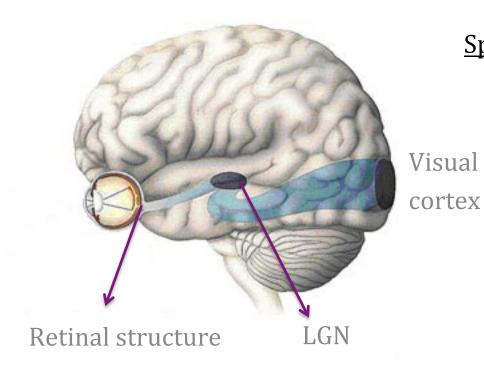
Matthias Hennig, *University of Edinburgh*Evelyne Sernagor, *Newcastle University*

Visual system and retinal waves





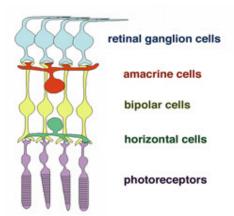
Visual system and retinal waves



Spontaneous spatio-temporal "waves" during development

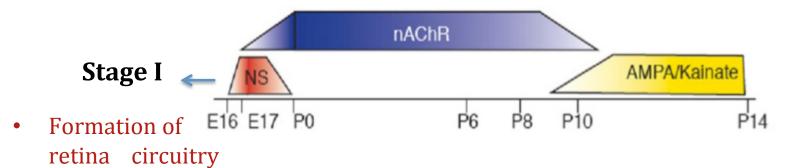
Disappear short after birth





Spatio-Temporal evolution of a retinal wave in mice during development, Maccione et al. 2014

Stages of Retinal Waves During Development

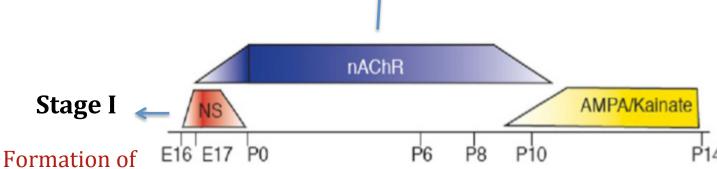


- Chemical synapses <u>not</u> formed yet
- Gap juctionmediated

Stages of Retinal Waves During Development

Stage II

- Retinotopic mapping
- Nicotinic Acetylcholine Receptors (nAChR)



- retina circuitry
- Chemical synapses <u>not</u> formed yet
- Gap juctionmediated

Stages of Retinal Waves During Development

Stage II

nAChR

- Retinotopic mapping
- Nicotinic Acetylcholine Receptors (nAChR)

Stage III Disappear when

vision is functionalGlutamate –

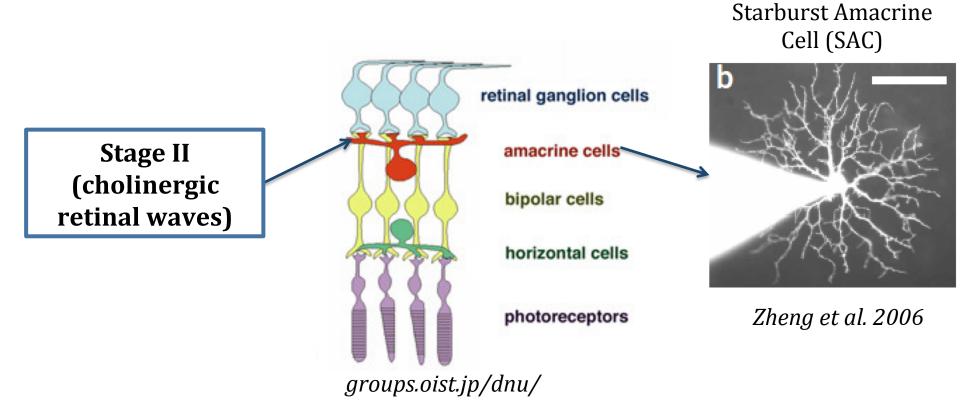
AMPA receptors



- Chemical synapses <u>not</u> formed yet
- Gap juctionmediated

Focus on stage II retinal waves

Stage II retinal waves are well studied experimentally and there is already existing work on their modelling



Goal of this lecture

Idea:

Identify generic mechanisms generating stage II retinal waves and analyze them mathematically.

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Motivation:

Retinal waves instruct the shaping of the visual system

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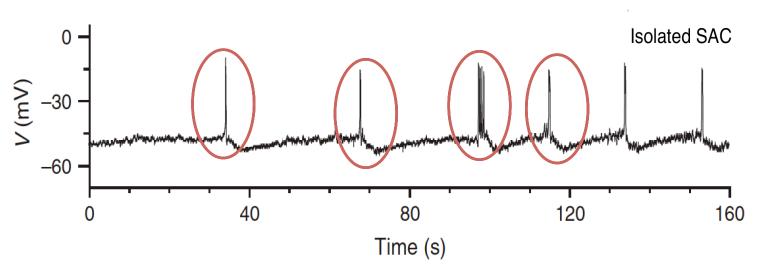
Identify generic mechanisms generating stage II retinal waves and analyze them mathematically.

Motivation:

- Retinal waves instruct the shaping of the visual system
- Understanding the mechanisms that generate them may help to control them
- New mathematical problems and new techniques.

Retinal waves require three components:

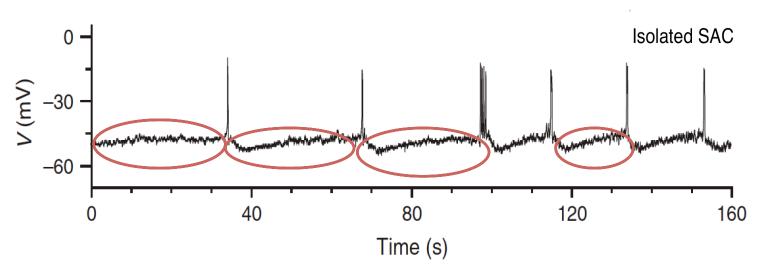
i) Spontaneous bursting activity



Experiment for isolated neurons, Zheng et al., 2006, Nature

Retinal waves require three components:

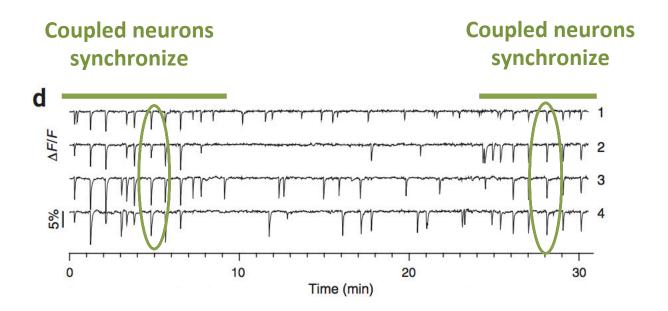
- i) Spontaneous bursting activity
- ii) Refractory mechanism (slow After HyperPolarisation-sAHP)



Experiment for isolated neurons, Zheng et al., 2006, Nature

Retinal waves require three components:

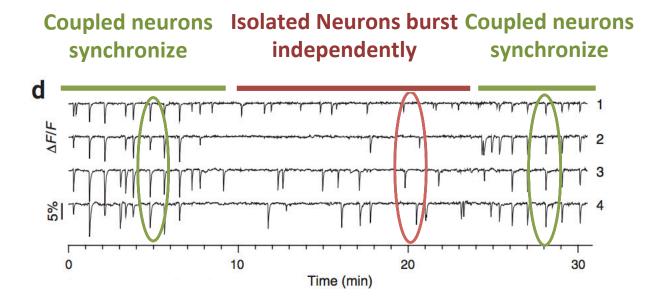
- i) Spontaneous bursting activity
- ii) Refractory mechanism (slow After HyperPolarisation-sAHP)
- iii) Coupling (through Acetylcholine neurotransmitter)



Experiment for coupled and isolated neurons, Zheng et al., 2006, Nature

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From the non linear physics perspective a retinal wave is a spatiotemporal activity which:

 is generated by the conjunction of local (cell level) nonlinear characteristics and network effects

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- is induced by generic mechanisms that can be studied in the context of dynamical systems theory
- can be associated with bifurcations

- Model biophysically the dynamics of isolated neurons (SACs)
 - Carefully model all currents involved
 - Fix parameters from experiments

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 - Carefully model all currents involved
 - Fix parameters from experiments
- Bifurcation analysis of the non-linear dynamical system for isolated neurons
- Extract a generic biophysical mechanism of spontaneous bursting activity for SACs
- Model the network interactions:
 - Study the effects of synaptic coupling to synchrony and wave initiation
 - Search for biophysical parameters which control spatiotemporal patterns

Modelling the bursting of individual Starburst Amacrine Cells

Bruno Cessac and Dora Karvouniari

Biovision Team, INRIA Sophia Antipolis, France.

15-01-2017

From biophysics to modelling

2 Model analysis

3 Conclusions

From biophysics to modelling

Biophysics of bursting SAC

Retinal waves require three components:

- Spontaneous bursting activity
- Refractory mechanism (slow After HyperPolarisation- sAHP)
- Coupling (through Acetylcholine neurotransmitter)

Biophysics of bursting SAC

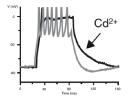


Figure: Zheng et al., Nature, 2006. Grey curve: Fast oscillations due to voltage-gated Ca^{+2} channels and Ca^{+2} dependent K^+ channels. Black curve: Application of Cd^+ blocking Ca^{+2} related channels.

Biophysics of bursting SAC

Morris-Lecar model with fast Potassium.

$$\begin{cases}
C_{m} \frac{dV}{dt} = -g_{L}(V - V_{L}) - g_{C} M_{\infty}(V)(V - V_{C}) - g_{K} N(V - V_{K}) \\
+ I_{ex}(\bullet)
\end{cases}$$

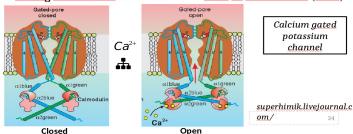
$$\tau_{N} \frac{dN}{dt} = \Lambda(V)(N_{\infty}(V) - N)$$
(1)

Definition

- Slow After Hyperpolarisation Current
- Calcium-dependent slow potassium channels

Mechanism

- Model SK-like channels (Abel et al. 2004)
- Gating Mechanism: Four ions Ca²⁺ bind to Calmodulin (CaM)



- Four Ca²⁺ions bound to calmodulin bind to a terminal
- I_{sAHP} current depends on gating variable R as follows:

$$I_{SAHP} = g_{SAHP}^m R^4 (V - V_K)$$
 (Hennig et al. 2009)



The conductance is proportional to the fourth power of R because four terminals are needed to open the channel.

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$$\tau_R \frac{dR}{dt} = a_R S(1 - R) - R$$

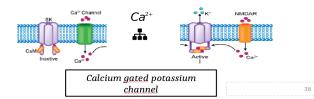
R : Probability that one terminal of the channel is open

$$\tau_s \frac{dS}{dt} = -S + a_s C^4 (1 - S)$$

S : Fraction of saturated calmodulin concentration (CaM)

$$\tau_{Ca} \frac{dC}{dt} = -a_R \frac{C}{H_x} + C_o + \delta_{Ca} I_{Ca}(V)$$

C : Intracellular Calcium concentration



Model analysis

Dynamics

$$\begin{cases}
C_{m} \frac{dV}{dt} &= -g_{L}(V - V_{L}) - g_{C} M_{\infty}(V)(V - V_{C}) - g_{K} N(V - V_{K}) \\
-g_{SAHP} R^{4}(V - V_{K})
\end{cases}$$

$$\tau_{N} \frac{dN}{dt} &= \Lambda(V)(N_{\infty}(V) - N)$$

$$\tau_{C} \frac{dC}{dt} &= -\frac{H_{X}}{\alpha_{C}} C + C_{0} - \delta_{C} g_{C} M_{\infty}(V)(V - V_{C})$$

$$\tau_{S} \frac{dS}{dt} &= \alpha_{S}(1 - S)C^{4} - S$$

$$\tau_{R} \frac{dR}{dt} &= \alpha_{R} S(1 - R) - R
\end{cases}$$
(2)

Dynamics

$$\begin{cases}
C_{m} \frac{dV}{dt} &= -g_{L}(V - V_{L}) - g_{C} M_{\infty}(V)(V - V_{C}) - g_{K} N(V - V_{K}) \\
-g_{SAHP} R^{4} G_{SAHP}(R)(V - V_{K})
\end{cases}$$

$$\tau_{N} \frac{dN}{dt} &= \Lambda(V)(N_{\infty}(V) - N)$$

$$\tau_{C} \frac{dC}{dt} &= -\frac{H_{X}}{\alpha_{C}} C + C_{0} - \delta_{C} g_{C} M_{\infty}(V)(V - V_{C})$$

$$\tau_{S} \frac{dS}{dt} &= \alpha_{S}(1 - S)C^{4} - S$$

$$\tau_{R} \frac{dR}{dt} &= \alpha_{R} S(1 - R) - R
\end{cases}$$
(3)

Dynamics

Leak time scale: $\tau_L = \frac{C}{g_L}$. Conductances rescaling: $\tilde{g}_X = \frac{g_X}{g_I}$.

$$\begin{cases} \tau_L \frac{dV}{dt} &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\ -\tilde{G}_{sAHP}(R)(V - V_K) \end{cases}$$

$$\tau_N \frac{dN}{dt} &= \Lambda(V)(N_\infty(V) - N)$$

$$\tau_C \frac{dC}{dt} &= -\frac{H_X}{\alpha_C} C + C_0 - \delta_C g_C M_\infty(V)(V - V_C)$$

$$\tau_S \frac{dS}{dt} &= \alpha_S (1 - S) C^4 - S$$

$$\tau_R \frac{dR}{dt} &= \alpha_R S(1 - R) - R$$

Multi-scale dynamics

Fast V, N. $\tau_L = 11$ ms, $\tau_N = 5$ ms.

Medium C. $\tau_C = 2$ s.

Slow *S*, *R*. $\tau_R = \tau_S = 44$ s.

Fast-scale

$$t_f = \frac{t}{\tau_I} \Rightarrow dt = \tau_L dt_f$$

$$\begin{cases} \frac{dV}{dt_f} &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_{\infty}(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\ -\tilde{G}_{sAHP}(R)(V - V_K) \end{cases}$$

$$\frac{\tau_N}{\tau_L} \frac{dN}{dt_f} &= \Lambda(V)(N_{\infty}(V) - N)$$

$$\frac{\tau_C}{\tau_L} \frac{dC}{dt_f} &= -\frac{H_X}{\alpha_C} C + C_0 - \delta_C g_C M_{\infty}(V)(V - V_C)$$

$$\frac{\tau_S}{\tau_L} \frac{dS}{dt_f} &= \alpha_S (1 - S) C^4 - S$$

$$\frac{\tau_R}{\tau_L} \frac{dR}{dt_f} &= \alpha_R S(1 - R) - R$$

Fast-scale

Set
$$\epsilon_X = \frac{\tau_L}{\tau_X}$$
, $X = C, R, S$.
 $\epsilon_C = \frac{11}{2} \times 10^{-3} \sim 5.5 \times 10^{-3}$, $\epsilon_S = \epsilon_R = \frac{11}{44} \times 10^{-3} \sim 2.5 \times 10^{-4}$

$$\begin{cases} \frac{dV}{dt_f} &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_{\infty}(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\ -\tilde{G}_{sAHP}(R)(V - V_K) \end{cases}$$

$$\frac{dN}{dt_f} &= \frac{\tau_L}{\tau_N} \Lambda(V)(N_{\infty}(V) - N)$$

$$\frac{dC}{dt_f} &= \epsilon_C \left[-\frac{H_X}{\alpha_C} C + C_0 - \delta_C g_C M_{\infty}(V)(V - V_C) \right]$$

$$\frac{dS}{dt_f} &= \epsilon_S \left[\alpha_S (1 - S) C^4 - S \right]$$

$$\frac{dR}{dt_f} &= \epsilon_R \left[\alpha_R S(1 - R) - R \right]$$

Fast-scale: approximation

$$\begin{cases} \frac{dV}{dt_f} &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_{\infty}(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\ -\tilde{G}_{sAHP}(R)(V - V_K) \end{cases}$$

$$\begin{cases} \frac{dN}{dt_f} &= \frac{\tau_L}{\tau_N} \Lambda(V)(N_{\infty}(V) - N) \\ \frac{dC}{dt_f} &= 0 \end{cases}$$

$$\frac{dS}{dt_f} &= 0$$

$$\frac{dR}{dt_f} &= 0$$

C, R, S are constant at this time scale.



Morris-Lecar model analysis

$$\begin{cases}
\frac{dV}{dt_f} &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_{\infty}(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\
&- \tilde{G}_{sAHP}(R)(V - V_K)
\end{cases}$$

$$\frac{dN}{dt_f} &= \frac{\tau_L}{\tau_N} \Lambda(V)(N_{\infty}(V) - N)$$
(4)

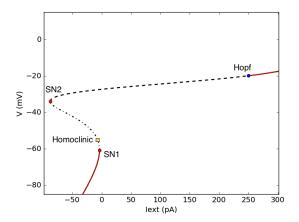
Morris-Lecar model analysis

$$\begin{cases}
\frac{dV}{dt_f} = -\tilde{g}_L(V - V_L) - \tilde{g}_C M_{\infty}(V)(V - V_C) - \tilde{g}_K N(V - V_K) + I_{\text{ext}} \\
\frac{dN}{dt_f} = \frac{\tau_L}{\tau_N} \Lambda(V)(N_{\infty}(V) - N)
\end{cases}$$
(5)

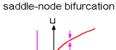
Bifurcation analysis when varying the parameter I_{ext} .

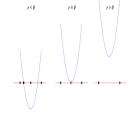
Morris-Lecar model analysis

Karvouniari et al, submitted to Plos Comp. Bio.



The saddle-node bifurcation





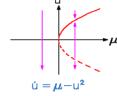


Figure: From https://elmer.unibas.ch/pendulum/bif.htm and https://it.wikipedia.org/wiki/Biforcazione_a_nodo_sella.

The Hopf bifurcation

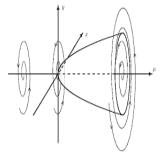


Figure: From Navarro et al, "Control of the Hopf bifurcation in the Takens-Bogdanov bifurcation", CDC2008

The homoclinic bifurcation

Hopf Bifurcation



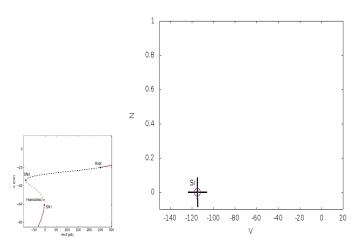
Small amplitude, frequency = $Im(\lambda)$, finite period

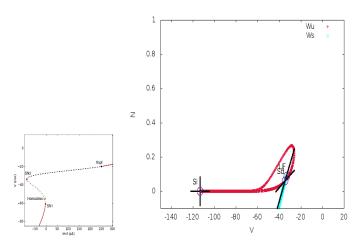
Homoclinic Bifurcation

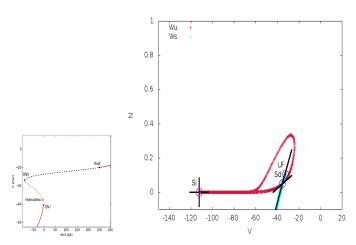


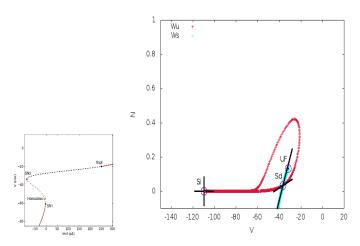
Finite amplitude, small frequency, infinite period

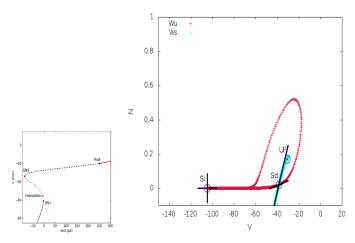
Figure: From J.Tyson, http://slideplayer.com/slide/8870556/

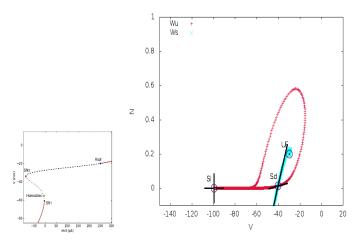




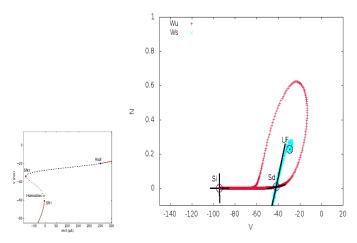


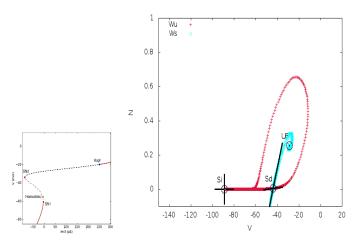






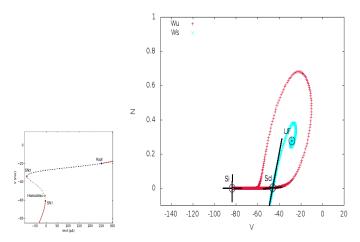
Karvouniari et al, submitted





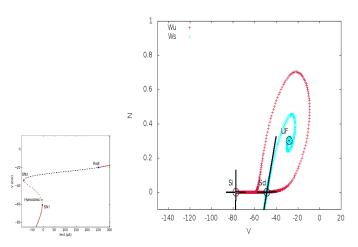
Conclusions

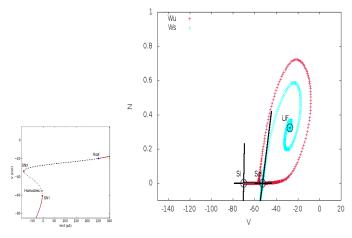
The complete movie

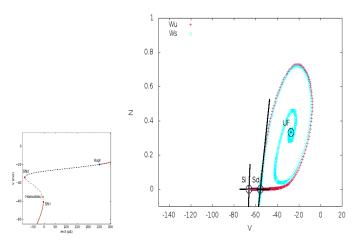


Conclusions

The complete movie

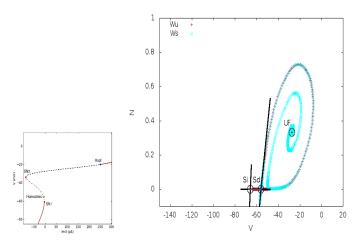


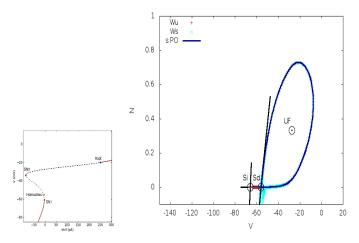


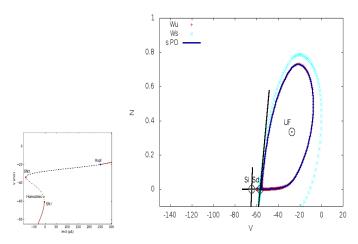


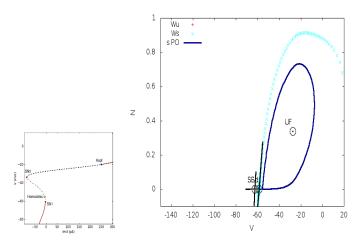
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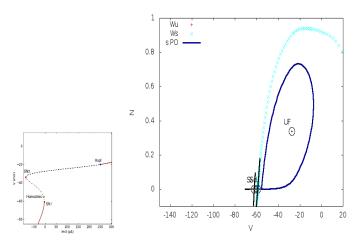
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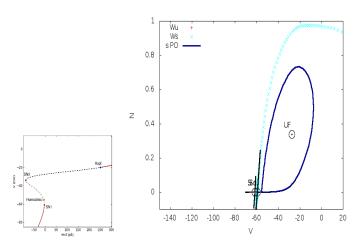


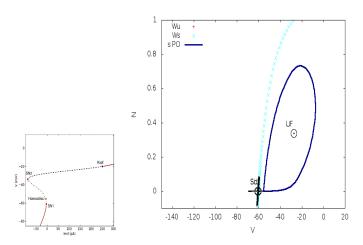


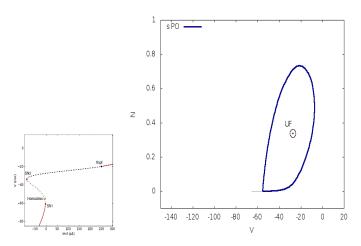


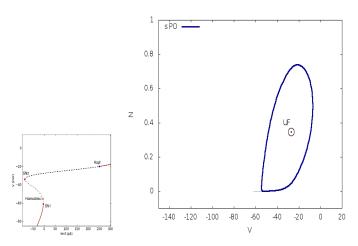


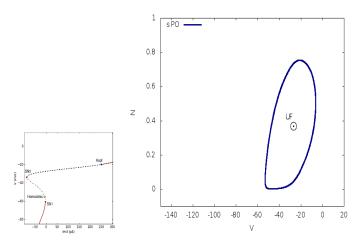


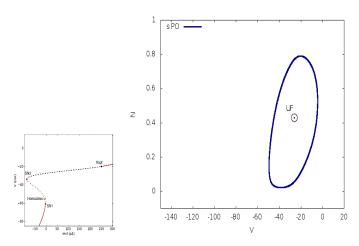


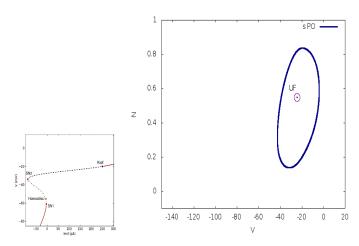


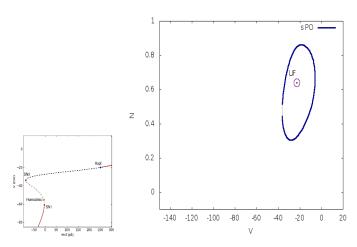


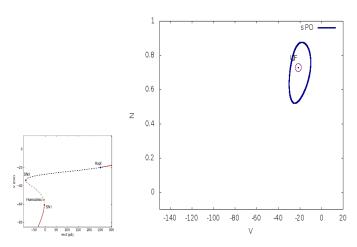


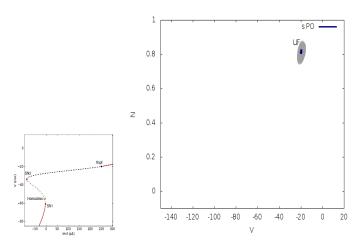






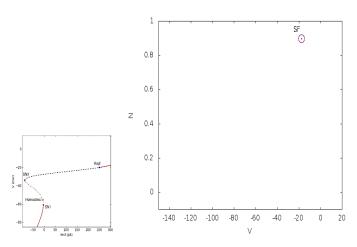


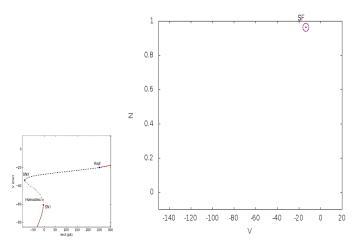


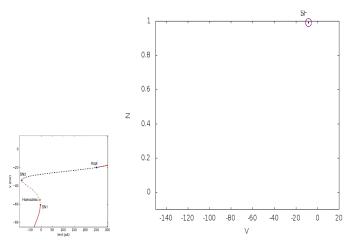


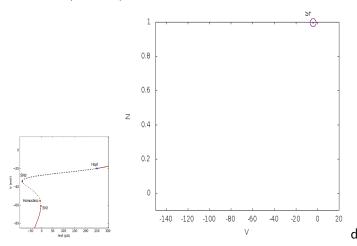
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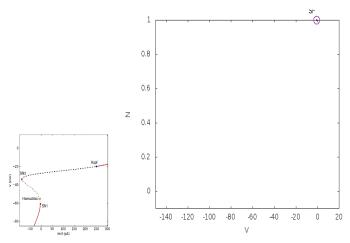
The complete movie

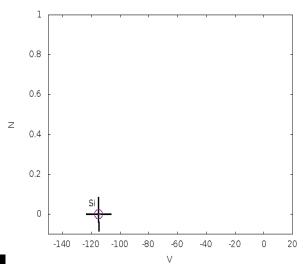












Back to Zhou experiment

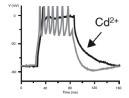
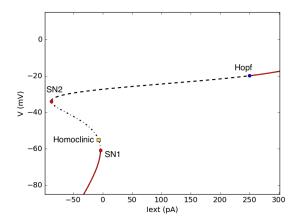


Figure: Zheng et al., Nature, 2006. Grey curve: Fast oscillations due to voltage-gated Ca^{+2} channels and Ca^{+2} dependent K^+ channels. Black curve: Application of Cd^+ blocking Ca^{+2} related channels.

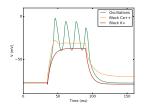
Back to Zhou experiment

Karvouniari et al, submitted to Plos Comp. Bio.



Back to Zhou experiment

Karvouniari et al, submitted to Plos Comp. Bio.



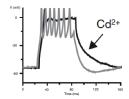


Figure: Left. Green. Application of a current step pulse of 150 pA for 60ms. Orange: Oscillations disappear when Ca^{+2} related conductances are set to zero. Red. Blocking the oscillations upon setting the voltage-gated K+ conductance to zero. Right: Zheng et al. 2006 experimental figure. Grey curve: Fast oscillations due to voltage-gated Ca^{+2} channels and Ca^{+2} dependent K^+ channels. Black curve: Application of Cd^+ blocking Ca^{+2} related channels.

Dynamics of bursting

Dynamics of bursting

$$\begin{cases} \tau_L \frac{dV}{dt} &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\ -\tilde{G}_{sAHP}(R)(V - V_K) \end{cases}$$

$$\tau_N \frac{dN}{dt} &= \Lambda(V)(N_\infty(V) - N)$$

$$\tau_C \frac{dC}{dt} &= -\frac{H_X}{\alpha_C} C + C_0 - \delta_C g_C M_\infty(V)(V - V_C)$$

$$\tau_S \frac{dS}{dt} &= \alpha_S (1 - S) C^4 - S$$

$$\tau_R \frac{dR}{dt} &= \alpha_R S(1 - R) - R$$

Fast V, N. $\tau_L = 11$ ms, $\tau_N = 5$ ms.

Medium C. $\tau_C = 2$ s.

Slow *S*, *R*. $\tau_R = \tau_S = 44$ s.



Slow time-scale

$$t_s = \frac{t}{\tau_S} \Rightarrow dt = \tau_S dt_s$$

$$\begin{cases} \frac{\tau_L}{\tau_S} \frac{dV}{dt_s} &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\ -\tilde{G}_{sAHP}(R)(V - V_K) \end{cases}$$

$$\begin{cases} \frac{\tau_N}{\tau_S} \frac{dN}{dt_s} &= \Lambda(V)(N_\infty(V) - N) \end{cases}$$

$$\frac{\tau_C}{\tau_S} \frac{dC}{dt_s} &= -\frac{H_X}{\alpha_C} C + C_0 - \delta_C g_C M_\infty(V)(V - V_C)$$

$$\frac{dS}{dt_s} &= \alpha_S (1 - S) C^4 - S$$

$$\frac{dR}{dt_s} &= \alpha_R S(1 - R) - R$$

Slow time-scale

$$\begin{array}{l} \epsilon_V = \frac{\tau_L}{\tau_S} \sim 2.5 \times 10^{-4}, \quad \epsilon_N = \frac{\tau_N}{\tau_S} \sim 1 \times 10^{-3} \\ \epsilon_C = \frac{\tau_C}{\tau_S} \sim 4.5 \times 10^{-2} \end{array}$$

$$\begin{cases} \epsilon_{V} \frac{dV}{dt_{s}} &= -\tilde{g}_{L}(V - V_{L}) - \tilde{g}_{C} M_{\infty}(V)(V - V_{C}) - \tilde{g}_{K} N(V - V_{K}) \\ -\tilde{G}_{sAHP}(R)(V - V_{K}) \end{cases}$$

$$\epsilon_{N} \frac{dN}{dt_{s}} &= \Lambda(V)(N_{\infty}(V) - N)$$

$$\epsilon_{C} \frac{dC}{dt_{s}} &= -\frac{H_{X}}{\alpha_{C}} C + C_{0} - \delta_{C} g_{C} M_{\infty}(V)(V - V_{C})$$

$$\frac{dS}{dt_{s}} &= \alpha_{S}(1 - S)C^{4} - S$$

$$\frac{dR}{dt_{s}} &= \alpha_{R} S(1 - R) - R$$

Slow time-scale approximation

$$\begin{cases}
0 &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_{\infty}(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\
&- \tilde{G}_{sAHP}(R)(V - V_K)
\end{cases}$$

$$0 &= \Lambda(V)(N_{\infty}(V) - N)$$

$$0 &= -\frac{H_X}{\alpha_C}C + C_0 - \delta_C g_C M_{\infty}(V)(V - V_C)$$

$$\frac{dS}{dt_s} &= \alpha_S(1 - S)C^4 - S$$

$$\frac{dR}{dt_s} &= \alpha_R S(1 - R) - R$$

Steady state

$$V = rac{V_{ML}(V) + ilde{G}_{sAHP}(R)V_{K}}{ ilde{g}_{ML}(V) + ilde{G}_{sAHP}(R)}$$

where:

$$V_{ML}(V) = V_L + \tilde{g}_C M_{\infty}(V) V_C + \tilde{g}_K N_{\infty}(V) V_K;$$

$$\tilde{g}_{ML}(V) = 1 + \tilde{g}_C M_{\infty}(V) + \tilde{g}_K N_{\infty}(V),$$

Steady state

V follows "adiabatically" R.

$$V \equiv f(V,R) = \frac{V_{ML}(V) + \tilde{G}_{sAHP}(R)V_{K}}{\tilde{g}_{ML}(V) + \tilde{G}_{sAHP}(R)}$$
(6)

Steady state

V follows "adiabatically" R.

$$V \equiv f(V,R) = \frac{V_{ML}(V) + \tilde{G}_{sAHP}(R)V_K}{\tilde{g}_{ML}(V) + \tilde{G}_{sAHP}(R)}$$
(6)

Implicit function theorem.

Wherever $\frac{\partial f}{\partial V} \neq 1$ V follows a unique and differentiable branch $V \equiv V(R)$. At points R where $\frac{\partial f}{\partial V} = 1$ this branch may disappear or several branch may appear simultaneously (bifurcation).

Hint

$$V \equiv f(V,R) = \frac{V_{ML}(V) + \tilde{G}_{sAHP}(R)V_{K}}{\tilde{g}_{ML}(V) + \tilde{G}_{sAHP}(R)}$$
(7)

Taking the differential gives:

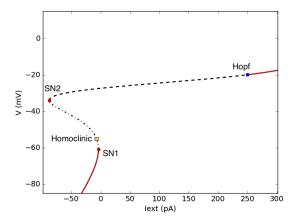
$$dV\left(1 - \frac{\partial f}{\partial V}\right) = \frac{\partial f}{\partial R}dR$$

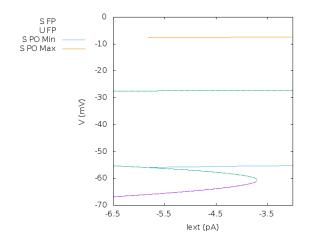
$$\Rightarrow$$

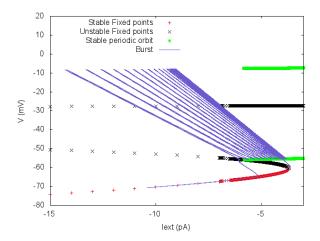
$$\frac{dV}{dR} = \frac{\frac{\partial f}{\partial R}}{1 - \frac{\partial f}{\partial V}}$$

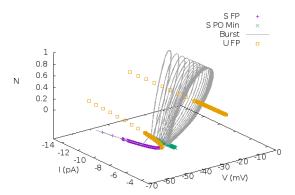


V follows adiabatically $\tilde{G}_{sAHP}(R)$.



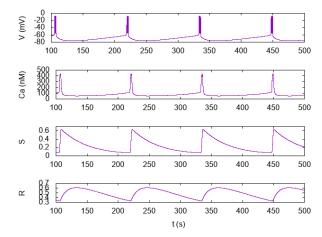




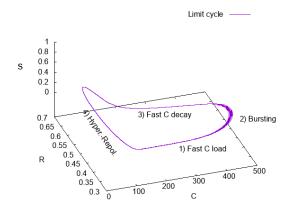


Complete dynamics

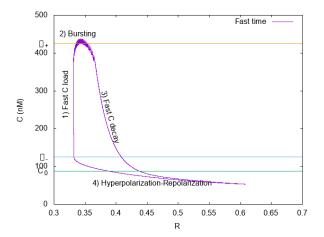
Complete dynamics



Medium and fast dynamics



Medium and fast dynamics



Medium-scale

$$t_m = \frac{t}{\tau_C} \Rightarrow dt = \tau_C dt_m$$

$$\begin{cases} \frac{\tau_L}{\tau_C} \frac{dV}{dt_m} &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\ -\tilde{G}_{sAHP}(R)(V - V_K) \end{cases}$$

$$\begin{cases} \frac{\tau_N}{\tau_C} \frac{dN}{dt_m} &= \Lambda(V)(N_\infty(V) - N) \end{cases}$$

$$\frac{dC}{dt_m} &= -\frac{H_X}{\alpha_C} C + C_0 - \delta_C g_C M_\infty(V)(V - V_C)$$

$$\frac{\tau_S}{\tau_C} \frac{dS}{dt_m} &= \alpha_S (1 - S) C^4 - S$$

$$\frac{\tau_R}{\tau_C} \frac{dR}{dt_m} &= \alpha_R S(1 - R) - R$$

Medium-scale

$$\begin{split} \epsilon_V &= \frac{\tau_L}{\tau_C} \sim 5 \times 10^{-3}, \quad \epsilon_N = \frac{\tau_N}{\tau_C} \sim 2.5 \times 10^{-3} \\ \epsilon_S &= \epsilon_R = \frac{\tau_C}{\tau_S} \sim 4.5 \times 10^{-2} \end{split}$$

$$\begin{cases} \epsilon_{V} \frac{dV}{dt_{m}} &= -\tilde{g}_{L}(V - V_{L}) - \tilde{g}_{C} M_{\infty}(V)(V - V_{C}) - \tilde{g}_{K} N(V - V_{K}) \\ -\tilde{G}_{sAHP}(R)(V - V_{K}) \end{cases}$$

$$\epsilon_{N} \frac{dN}{dt_{m}} &= \Lambda(V)(N_{\infty}(V) - N)$$

$$\frac{dC}{dt} &= -\frac{H_{X}}{\alpha_{C}} C + C_{0} - \delta_{C} g_{C} M_{\infty}(V)(V - V_{C})$$

$$\frac{dS}{dt_{m}} &= \epsilon_{S} \left[\alpha_{S}(1 - S)C^{4} - S \right]$$

$$\frac{dR}{dt_{m}} &= \epsilon_{R} \left[\alpha_{R} S(1 - R) - R \right]$$

Medium-scale approximation

$$\begin{cases}
0 &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\
&- \tilde{G}_{sAHP}(R)(V - V_K)
\end{cases}$$

$$0 &= \Lambda(V)(N_\infty(V) - N)$$

$$\frac{dC}{dt_m} &= -\frac{H_X}{\alpha_C}C + C_0 - \delta_C g_C M_\infty(V)(V - V_C)$$

$$\frac{dS}{dt} &= 0$$

$$\frac{dR}{dt} &= 0$$

Medium-scale approximation

At this time scale:

- R, S are constant;
- V follows the variations of R;

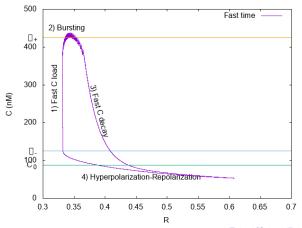
•
$$\frac{dC}{dt_m} = -\frac{H_X}{\alpha_C}C + C_0 - \delta_C g_C M_\infty(V)(V - V_C)$$



Conclusions

Medium-scale approximation

Rapid (medium time scale between upper/lower branch) "Outer dynamics".



Slow time-scale approximation

$$\begin{cases}
0 &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_{\infty}(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\
&- \tilde{G}_{sAHP}(R)(V - V_K)
\end{cases}$$

$$0 &= \Lambda(V)(N_{\infty}(V) - N)$$

$$0 &= -\frac{H_X}{\alpha_C}C + C_0 - \delta_C g_C M_{\infty}(V)(V - V_C)$$

$$\frac{dS}{dt_s} &= \alpha_S(1 - S)C^4 - S$$

$$\frac{dR}{dt_s} &= \alpha_R S(1 - R) - R$$

"Inner dynamics"

- V follows R;
- C follows V;
- Note $P(R) \equiv C^4$, the average value of C^4 for a given value of R.

 \Rightarrow

Dynamics on the slow branches.

$$\begin{cases} \frac{dR}{dt_s} = \alpha_R S(1-R) - R \\ \frac{dS}{dt_s} = \alpha_S (1-S) P(R) - S \end{cases}$$

"Inner dynamics"

Nullclines.

R Nullcline:
$$\frac{dR}{dt_s} = 0 \Rightarrow$$

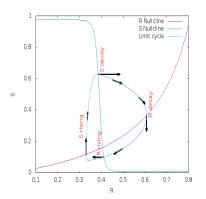
The vector field is vertical on the line $S = \frac{R}{\alpha_R(1-R)}$

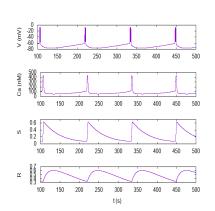
S Nullcline:
$$\frac{dS}{dt_s} = 0 \Rightarrow$$

The vector field is horizontal on the line $S = \frac{\alpha_S P(R)}{1 + \alpha_S P(R)}$

Model analysis

Inner dynamics





• We have now a model reproducing individual SACs bursting.

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- Here SACs burst periodically with a frequency determined by the parameters of the model (mainly τ_R).

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- A small change of parameters make them into a rest state where they burst only upon an external excitation (noise).

- We have now a model reproducing individual SACs bursting.
- Here SACs burst periodically with a frequency determined by the parameters of the model (mainly τ_R).
- A small change of parameters make them into a rest state where they burst only upon an external excitation (noise).
- What happens when they cells are coupled with Acetylcholine?

Modelling stage II retinal waves

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Biovision Team, INRIA Sophia Antipolis, France.

15-01-2017

- 1 Coupling SACs with Acetylcholine
- 2 Dynamical systems analysis
- 3 A simplified setting to mathematically study retinal waves
- 4 Generalisations
- Conclusions

Coupling SACs with Acetylcholine Dynamical systems analysis A simplified setting to mathematically study retinal waves Gene

Coupling SACs with Acetylcholine

Coupling SACs with Acetylcholine

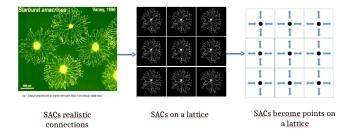


Figure: SACs network.

- Molecular nicotinic receptors (nAchR)
- Two molecules of acetylcholine bind to open a nicotinic channel
- The nicotinic conductance depends on the second power of the acetylcholine neurotransmitter concentration A

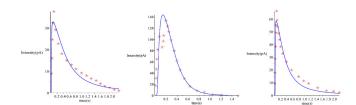
$$g_{Ach} = g_{Ach}^m \frac{A^2}{K_d^2 + A^2}$$

nAChR K+ Ca²⁺ Na+

Figure: Nicotinic receptors and conductance.

$$\frac{\partial A}{\partial t} = \beta_{Ach} T_{Ach} (V) - \frac{A}{\tau_{Ach}}$$

A: Extracellular Acetylcholine concentration



Intensity of Acetylcholine current for three Voltage clamp levels
Experimental fits from Zhou et al. 2004. Neuron

Figure: Ach production.

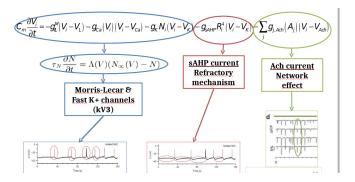


Figure: Equation of membrane potential.

Dynamical systems analysis

Main currents

$$G_{sAHP}(R_i) = g_{sAHP}R_i^4, \tag{1}$$

sAHP conductance,

$$G_A(\{A_k\}_{k\in\mathcal{B}_i}) = g_A \sum_{k\in\mathcal{B}_i} U(A_k), \tag{2}$$

Ach synaptic conductance with:

$$U(A) = \frac{A^2}{\gamma_A + A^2},\tag{3}$$

 \mathcal{B}_i is the set of index of neurons connected to i.



$$\begin{cases}
C_{m} \frac{dV_{i}}{dt} &= -g_{L}(V_{i} - V_{L}) - g_{C}M_{\infty}(V_{i})(V_{i} - V_{C}) - g_{K}N_{i}(V_{i} - V_{K}) \\
-G_{sAHP}(R_{i})(V_{i} - V_{K}) - G_{A}(\{A_{k}\}_{k \in \mathcal{B}_{i}})(V_{i} - V_{A})
\end{cases}$$

$$\tau_{N} \frac{dN_{i}}{dt} &= \Lambda(V_{i})(N_{\infty}(V_{i}) - N_{i})$$

$$\tau_{C} \frac{dC_{i}}{dt} &= -\frac{\alpha_{C}}{H_{X}}C_{i} + C_{0} - \delta_{C}g_{C}M_{\infty}(V_{i})(V_{i} - V_{C})$$

$$\tau_{S} \frac{dS_{i}}{dt} &= \alpha_{S}(1 - S_{i})C_{i}^{4} - S_{i}$$

$$\tau_{R} \frac{dR_{i}}{dt} &= \alpha_{R}S_{i}(1 - R_{i}) - R_{i}$$

$$\frac{dA_{i}}{dt} &= -\mu A_{i} + \beta_{A}T_{A}(V_{i}),$$

Leak time scale: $\tau_L = \frac{C}{g_L}$. Ach time scale: $\tau_A = \frac{1}{\mu}$. Conductances rescaling: $\tilde{g}_X = \frac{g_X}{g_I}$.

$$\begin{cases} \tau_{L} \frac{dV_{i}}{dt} &= -(V_{i} - V_{L}) - \tilde{g}_{C} M_{\infty}(V_{i})(V_{i} - V_{C}) - \tilde{g}_{K} N_{i}(V_{i} - V_{K}) \\ - \tilde{G}_{sAHP}(R_{i})(V_{i} - V_{K}) - \tilde{G}_{A}(\{A_{k}\}_{k \in \mathcal{B}_{i}})(V_{i} - V_{A}); \end{cases}$$

$$\tau_{N} \frac{dN_{i}}{dt} &= \Lambda(V_{i})(N_{\infty}(V_{i}) - N_{i});$$

$$\tau_{C} \frac{dC_{i}}{dt} &= -\frac{\alpha_{C}}{H_{X}}C_{i} + C_{0} - \delta_{C}g_{C}M_{\infty}(V_{i})(V_{i} - V_{C});$$

$$\tau_{S} \frac{dS_{i}}{dt} &= \alpha_{S}(1 - S_{i})C_{i}^{4} - S_{i};$$

$$\tau_{R} \frac{dR_{i}}{dt} &= \alpha_{R}S_{i}(1 - R_{i}) - R_{i};$$

$$\tau_{A} \frac{dA_{i}}{dt} &= -A_{i} + \frac{\beta_{A}}{\mu}T_{A}(V_{i});$$

Multi-scale dynamics

Fast V, N. $\tau_L = 11$ ms, $\tau_N = 5$ ms.

Medium C, A. $\tau_C = 2$ s, $\tau_A = 1.86$ s.

Slow *S*, *R*. $\tau_R = \tau_S = 44$ s.

Inspired from Lansdell et al, Plos. Comp. Bio, 2014

Main hypotheses:

1) We neglect the fast Potassium current. V_i has only two stable states: low and high. In the high state SAC does not burst.

Main hypotheses:

- 2) To switch from low to high state, neuron *i* needs an external excitatory current. This can be:
 - The Ach current coming from neighbours;
 - A "shot noise" current of the form:

$$g_N B_i (V_i - V_C)$$

where $B \in \{0,1\}$ is a Bernoulli variable with probability $Prob\left[B_i(s)=1, s\in[t,t+dt\right]=pdt$, with $p\sim\frac{1}{\tau_B}$.



Main hypotheses:

3) sAHP has a simplified form (does not depend on Calcium). We only keep the variables S, R where S depends directly on V:

$$\tau_{S}\frac{dS_{i}}{dt}=-S_{i}+\gamma G(V_{i})$$

with:

$$G(V_i) = \frac{1}{1 + e^{-\kappa(V - V_0)}}.$$

Main hypotheses:

4) Acetylcholine synapses are assumed not to be yet functional (Ford-Feller, 2011). The main source of Ach coupling is Ach *diffusion*.

$$\tau_A \frac{dA_i}{dt} = -A_i + \frac{\beta_A}{\mu} T_A(V_i) + D\Delta A_i;$$

where Δ is the Laplacian on a square lattice. Boundary conditions are ignored.

The Ach current depends only on the local Ach: $I_A = -g_A U(A)(V - V_A)$.



Main hypotheses:

- Two state voltage.
- Shot noise.
- Simplified form for sAHP.
- Ach diffusion.

From now we consider that variables depend continuously on space $\Rightarrow \frac{d}{dt} \rightarrow \frac{\partial}{\partial t}$

$$\begin{cases} \tau_{L} \frac{\partial V}{\partial t} &= -(V - V_{L}) - \tilde{g}_{C} M_{\infty}(V)(V - V_{C}) + \tilde{g}_{N} B(V - V_{C}) \\ - \tilde{G}_{SAHP}(R)(V - V_{K}) - \tilde{g}_{A} U(A)(V - V_{A}); \end{cases}$$

$$\begin{cases} \tau_{S} \frac{\partial S}{\partial t} &= -S + \gamma G(V); \\ \tau_{R} \frac{\partial R}{\partial t} &= \alpha_{R} S(1 - R) - R; \\ \tau_{A} \frac{\partial A}{\partial t} &= -A + \frac{\beta_{A}}{\mu} T_{A}(V) + D \Delta A(V); \end{cases}$$

$$t_m = \frac{t}{\tau_A} \Rightarrow dt = \tau_A dt_m$$

 $\epsilon_V = \frac{\tau_I}{\tau_A} \sim 5 \times 10^{-3}; \quad \epsilon_S = \epsilon_R = \frac{\tau_A}{\tau_S} \sim 4.5 \times 10^{-2}$

$$\begin{cases} \epsilon_{V} \frac{\partial V}{\partial t_{m}} &= -(V - V_{L}) - \tilde{g}_{C} M_{\infty}(V)(V - V_{C}) - g_{N} B(V - V_{C}) \\ - \tilde{G}_{sAHP}(R)(V - V_{K}) - \tilde{g}_{A} U(A)(V - V_{A}); \end{cases}$$

$$\frac{\partial S}{\partial t_{m}} &= \epsilon_{S} \left[-S + \gamma G(V) \right];$$

$$\frac{\partial R}{\partial t_{m}} &= \epsilon_{R} \left[\alpha_{R} S(1 - R) - R \right];$$

$$\frac{\partial A}{\partial t_{m}} &= -A + \frac{\beta_{A}}{\mu} T_{A}(V) + D \Delta A;$$

$$\begin{cases} 0 &= -(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) + g_N B(V - V_C) \\ &- \tilde{G}_{SAHP}(R)(V - V_K) - \tilde{g}_A U(A)(V - V_A); \end{cases}$$

$$\begin{cases} \frac{\partial S}{\partial t_m} &= 0; \\ \frac{\partial R}{\partial t_m} &= 0; \\ \frac{\partial A}{\partial t_m} &= -A + \frac{\beta_A}{\mu} T_A(V) + D\Delta A; \end{cases}$$

Medium-scale approximation

At this time scale:

- R, S are constant;
- V follows the variations of R, A;

$$V = \frac{V_L + \tilde{g}_C M_{\infty}(V) V_C + \tilde{g}_N B V_C + \tilde{G}_{sAHP}(R) V_K + \tilde{g}_A U(A) V_A}{1 + \tilde{g}_C M_{\infty}(V) + \tilde{g}_N B + \tilde{G}_{sAHP}(R) + \tilde{g}_A U(A)}$$

From the implicit functions theorem: V = f(R, A, B).



We consider here a propagation in 1 dimension.

$$\frac{\partial A}{\partial t_m} = -A + \frac{\beta_A}{\mu} T_A(V) + D\Delta A \Rightarrow$$

$$\frac{\partial A}{\partial t_m} = -A + \frac{\beta_A}{\mu} T_A(V) + D \frac{\partial^2 A}{\partial x^2}$$

Spatially homogeneous state

Low voltage state. If all neurons are in the low voltage state, V_- , $\Delta A=0 \Rightarrow A$ reaches a stationary homogeneous state on the medium time scale.

$$A_{-}=rac{eta_{A}}{\mu}T_{A}(f(R,A_{-},0)),$$

where 0 means that B = 0 everywhere (no shot noise current).

In this state, the S production $G(V_{-}) \sim 0$ so there is no sAHP on the slow time scale.

Spatially homogeneous state

High voltage state. If all neurons are in the high voltage state, V_+ , $\Delta A = 0 \Rightarrow A$ reaches a stationary homogeneous state on the medium time scale.

$$A_{+}=\frac{\beta_{A}}{\mu}T_{A}(f(R,A_{+},B)).$$

Here, the state can be reached either due to shot noise or to Ach current.

In this state, the S production $G(V_+) >> 0$ so there is an sAHP on the slow time scale.

Local perturbation of the low state. At some point x_0 we induce a shot noise current at time 0 ($B(x_0, 0) = 1$).

- This raises the voltage to its upper value V_+ .
- This increases the Ach production at x_0 .
- Ach diffuses to neighbours and induces an excitatory current.
- If g_A conductance is large enough this current raises the neighbours voltage to V_+ .
- This can lead to a propagating wave.

Under which conditions?



Moving frame:

$$\xi = x - ct_m$$
 where c is a constant $\Rightarrow d\xi = dx - cdt_m$.

For a function $A(x, t_m) \equiv A(\xi)$ we have:

$$dA = \frac{\partial A}{\partial \xi} d\xi = \frac{\partial A}{\partial \xi} (dx - cdt_m) \Rightarrow$$

$$\frac{\partial A}{\partial x} = \frac{\partial A}{\partial \xi}; \quad ; \frac{\partial^2 A}{\partial x^2} = \frac{\partial^2 A}{\partial \xi^2}; \quad \frac{\partial A}{\partial t_m} = -c \frac{\partial A}{\partial \xi}$$

$$-c\frac{\partial A}{\partial \xi} = -A + \frac{\beta_A}{\mu} T_A(f(R, A, B)) + D\frac{\partial^2 A}{\partial \xi^2}$$



Potential well: $\frac{\partial \mathcal{V}}{\partial A} = A - \frac{\beta_A}{\mu} T_A(f(R, A, B))$

$$\mathcal{V}(A) = rac{A^2}{2} - rac{eta_A}{\mu} \int T_A(f(R,a,B)) da + K$$

Rest states: $\frac{\partial V}{\partial A} = 0$.

Newton equation

$$D\frac{\partial^2 A}{\partial \xi^2} = -c\frac{\partial A}{\partial \xi} - \frac{\partial \mathcal{V}}{\partial A}.$$

We note $\frac{\partial A}{\partial \xi} \equiv \dot{A}$; $\frac{\partial A^2}{\partial \xi^2} \equiv \ddot{A}$

$$D\ddot{A} = -c\dot{A} - \frac{\partial V}{\partial A}.$$
 (5)

$$D\ddot{A} = -c\dot{A} - \frac{\partial \mathcal{V}}{\partial A}.$$

Formally, this is the equation of motion of a particle, with mass D, in a potential well V, with a friction coefficient c.

 $\mathcal V$ has 3 extrema, given by $\frac{\partial \mathcal V}{\partial A} = A - \frac{\beta_A}{\mu} T_A(f(R,A,B)) = 0 \Rightarrow$:

$$A = \frac{\beta_A}{\mu} T_A(f(R, A, B))$$

These are the fixed points of the medium scale local dynamics ($\Delta A = 0$).

Maxima of $\mathcal V$ correspond to stable fixed points.



Heteroclinic connection

Figure: Bifurcation diagram in the space I = V.

Effect of sAHP

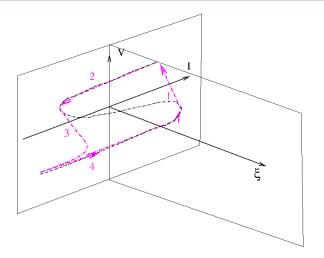


Figure: Trajectory in the space I - V.

Effect of sAHP

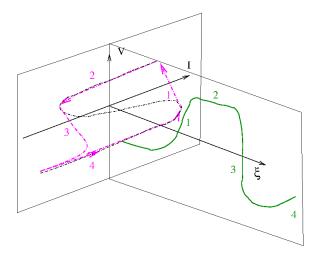


Figure: Pulse propagation.

Effect of sAHP

Time and space scales

- Ach raising and propagation, controlled by g_{Ach} and D
 (Diffusion);
- sAHP controlled by g_{sAHP} (Local);
- Time of excitation controlled by characteristic times and conductances:
- Time of propagation controlled by c depending on the other parameters.
- ⇒ Characteristic wave length depending on parameters.



Coupling SACs with Acetylcholine Dynamical systems analysis A simplified setting to mathematically study retinal waves Gene

Generalisations

- Two state voltage.
- Shot noise.
- Simplified form for sAHP.
- Ach diffusion.

- **1** Two state voltage. \Rightarrow Fast bursting in the high voltage state.
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Relaxing hypotheses

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Relaxing hypotheses

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- 3 Simplified form for sAHP. Role of Ca?
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Relaxing hypotheses

- **1** Two state voltage. \Rightarrow Fast bursting in the high voltage state.
- **2** Shot noise. \Rightarrow Spontaneous bursting.
- **Simplified form for sAHP.**Role of *Ca*?
- **4** Ach diffusion. \Rightarrow Ach nicotinic coupling.

Ach nicotinic coupling

$$C_m \frac{dV_i}{dt} = -g_L(V_i - V_L) - g_C M_\infty(V_i)(V_i - V_C) - g_K N_i(V_i - V_K)$$
$$-G_{sAHP}(R_i)(V_i - V_K) - g_A(V_i - V_A) \sum_{k \in R_i} U(A_k)$$

Coupling two bursting cells

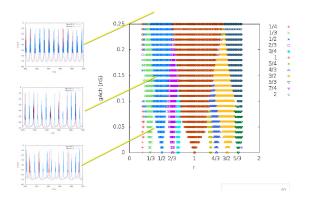


Figure: Synchronisation of two bursting cells.

Coupling *N* bursting cells

- There is a competition between 2 mechanisms:
 - Interburst variability which tends to desynchronise
 - Acetylcholine which tends to synchronise

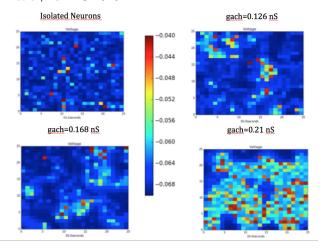
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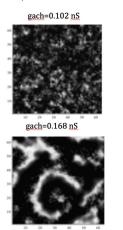
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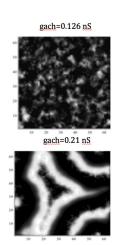
- There is a competition between 2 mechanisms:
 - Interburst variability which tends to desynchronise
 - Acetylcholine which tends to synchronise
- There is an intermediate regime of coupling, where variability is maximum
- Therefore there is a wide repertoire of patterns
 - Weak coupling leads to small localised activity
 - Moderate coupling leads to propagating patterns
 - Strong coupling leads to complete synchrony of neurons





Spatio temporal patterns





Nearest neighbours interactions

- Neurons are located on a lattice with step a.
- A depends smoothly on coordinates.

$$\sum_{k\in\mathcal{B}_i}U(A_k)\sim 4U(A(x_i,y_i))+a^2\Delta U(A)$$

Non linear diffusion!

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- More ??
 - \Rightarrow invite Dora as a speaker to the next LACONEU conference