# Satellite Intercomparison and Validation using the Radiometric Calibration Test Site (RadCaTS) at Railroad Valley, Nevada

Jeffrey Czapla-Myers, Nikolaus Anderson, and Stuart Biggar College of Optical Sciences, University of Arizona

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the university of arizona College of Optical Sciences



# Outline

- Introduction to RadCaTS
- Instrumentation and methodology
- Current projects
- Sample of current results
- Future work





#### **Traditional Methods**

- Remote Sensing Group (RSG) has traditionally used the reflectance-based approach
  - Requires on-site personnel at time of interest
  - All equipment must be transported to site for in situ measurements
  - Travel to test site (7-10 hours)
  - Sites: Railroad Valley, NV, Ivanpah Playa, CA, Alkali Lake, NV, Red Lake, AZ











# RadCaTS

- Recent efforts focused on the Radiometric Calibration Test Site (RadCaTS)
- Similar to reflectance-based approach
  - Atmospheric measurements (automated solar radiometers)
  - Surface reflectance measurements (ASD and Spectralon panel)
- Yet different...
  - Absolutely-calibrated ground-viewing radiometers (GVRs)
  - Cimel CE-318T solar lunar photometer
  - On-site calibration of radiometers
  - Data logging
  - Infrastructure
  - Automated processing





### Introduction to RadCaTS

- Railroad Valley, Nevada, chosen for RadCaTS
  - High surface reflectance (BRF > 0.3 reduces path radiance effects)
  - Spatially uniform (minimizes misregistration)
  - Spectrally flat (reduces uncertainty in cross calibration)
  - Near-lambertian surface (reduces directional effects)
  - High altitude (reduces uncertainty due to aerosols)
  - Large size (reduces adjacency effects)
  - Arid region (less clouds, and less rain)









# Evolution of Surface Reflectance Instrumentation: Ground-Viewing Radiometers (GVRs)

#### GLOBE Sun photometer







#### Instrumentation

- Laboratory calibration of GVRs before deployment
  - Radiometric (absolute and stability)
  - Spectral (in and out of band)
  - Field of view









#### Instrumentation

- Cimel CE-318T solar lunar photometer
- Meteorological station
- Satellite uplink base station









### **Other Instrumentation**

- GVR 23 at south end of site for GOES work
- **Development of Calibration Test Site SI-Traceable Transfer** lacksquareRadiometer (CaTSSITTR-A and -G)
- Spectrometer Arduino Mega (SpAM) student project
- GVR 23 for GOES-16 CaTSSITTR-G

SpAM







# **Other Instrumentation**

Commercial sUAS for spatial uniformity analysis







# **RadCaTS Layout**







### Methodology

- GVRs make point measurements every 2 min throughout day
- Cimel makes measurements based on AERONET protocol
- Data uploaded daily to Univ. of Arizona
- Multispectral BRF data converted to hyperspectral using library of data collected from 2000–2016 (~85 data sets)







# **Current Projects Using RadCaTS Data**

- Landsat 7 ETM+ and Landsat 8 OLI
- Terra and Aqua MODIS
- Suomi NPP VIIRS (radcats.gsfc.nasa.gov)
- Sentinel-2A and -2B MSI
- RapidEye
- GOES-16 ABI
- CEOS WGCV Radiometric Calibration Network (RadCalNet) (www.radcalnet.org)



# **RadCaTS Involvement in CEOS WGCV RadCalNet**

- Currently one of four global sites
- RadCalNet is currently in beta testing mode
- Going live late 2017
- RadCaTS data uploaded daily to NASA GSFC for further processing
- Output:
  - TOA reflectance
  - 400–2500 nm (10-nm intervals)
  - 09:00–15:00 local time, every 30 min
  - Nadir view





# **Typical Overpass Conditions**

	Overpass time(s) UTC	View Angle(s)
Landsat 8	18:21	Nadir
Terra	18:32, 18:38, 18:44	12°, Nadir, 11°
Sentinel-2A	18:34, 18:44	11°, 6°
Aqua	20:48, 20:53	7°, 4°
SNPP	20:33, 20:39, 20:46	11°, Nadir, 10°



# Results

# • Sample of results: MODIS (2012–2017)





### Results

• Sample of results: SNPP VIIRS (2012–2016)





# Results

 Sample of results: Landsat 8 OLI and Sentinel-2A MSI (launch– 2017)





### **Future Work**

- Continue to process specific overpasses
  - Current missions: Terra, Aqua, Landsat, SNPP, Sentinel-2, GOES-16
  - Future missions: Landsat-9, GOES-17, JPSS-1
- Continue to process daily RadCalNet data and upload to NASA
- Routine maintenance and calibration of equipment
- Install web camera to monitor conditions
- Develop additional GVR for GOES-17 work
- Develop GVR head translation mechanism for additional spatial sampling (student project)
- Deploy SpAM (student project)



Thanks!

• Questions?

