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# Spectral calibration of exponential Lévy Models [2]

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# SPECTRAL CALIBRATION OF EXPONENTIAL LEVY MODELS

DENIS BELOMESTNY AND MARKUS REISS

## 1. INTRODUCTION

The calibration of financial models has become rather important topic in recent years mainly because of the need to price increasingly complex options in a consistent way. The choice of the underlying model is crucial for the good performance of any calibration procedure. Recent empirical evidences suggest that more complex models taking into account such phenomenons as jumps in the stock prices, smiles in implied volatilities and so on should be considered. Among most popular such models are Levy ones which are on the one hand able to produce complex behavior of the stock time series including jumps, heavy tails and on other hand remain tractable with respect to option pricing. The work on calibration methods for financial models based on Lévy processes has mainly focused on certain parametrisations of the underlying Lévy process with the notable exception of Cont and Tankov (2004). Since the characteristic triplet of a Lévy process is a priori an infinite-dimensional object, the parametric approach is always exposed to the problem of misspecification, in particular when there is no inherent economic foundation of the parameters and they are only used to generate different shapes of possible jump distributions. In this work we propose and test a non-parametric calibration algorithm which is based on the inversion of the explicit pricing formula via Fourier transforms and a regularisation in the spectral domain. Using the Fast Fourier Transformation, the procedure is fast, easy to implement and yields good results in simulations in view of the severe ill-posedness of the underlying inverse problem.

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## 2. DESCRIPTION OF THE METHOD

Let the prices  $Y_1, \dots, Y_N$  of  $N$  call options at strikes  $K_1 < \dots < K_N$  be observable

**2.1. Data transformation.** We transform the observations  $(K_j, Y_j)$  to  $(x_j, O_j)$  by

$$\begin{aligned} O_j &:= Y_j/S - (1 - K_j e^{-rT}/S)^+, \\ x_j &:= \log(K_j/S) - rT, \end{aligned}$$

where  $T$  is the time to maturity,  $r$  is a short rate and  $S$  is the spot price.

**2.2. Estimation of  $\mathcal{O}$ .** Find function  $\tilde{O}$  among all functions  $O$  with two continuous derivatives that minimizes the penalized residual sum of squares

$$(1) \quad \text{RSS}(O, \varkappa) = \sum_{i=0}^{N+1} (O_i - O(x_i))^2 + \varkappa \int_{x_0}^{x_{N+1}} [O''(u)]^2 du,$$

where  $x_0 \ll x_1$  and  $x_{N+1} \gg x_N$  are two artificial points and  $O_{N+1} = O_0 = 0$ . The first term in (1) measures closeness to the data, while the second term penalizes curvature in the function, and  $\varkappa$  establishes a tradeoff between the two. The two special cases are  $\varkappa = 0$  when  $\tilde{O}$  interpolates the data and  $\varkappa = \infty$  when the simple least squares line is fitted. It can be shown that (1) has an explicit, finite dimensional, unique minimizer which is a natural cubic spline with knots at the unique values of  $x_i$ ,  $i = 1, \dots, N$ . The general cross validation can be used to choose  $\varkappa$  (see, for example, Green and Silverman (1994)). Note, that due to the non-smooth behavior of  $\mathcal{O}(x)$  at 0 (see Belomestny and Reiß (2004)) it is more reasonable to fit smoothing splines separately for  $x > 0$  and  $x \leq 0$  and combine them thereafter.

**2.3. Estimation of  $\mathcal{FO}$ .** Since the solution of (1) is a natural cubic spline, we can write

$$\tilde{O}(x) = \sum_{j=1}^N \theta_j \beta_j(x)$$

where  $\beta_j(x)$ ,  $j = 1, \dots, N$  are set of basis function for representing the family of natural cubic splines. Now we estimate  $\mathcal{FO}(v+i)$  by

$$\mathcal{F}\tilde{O}(v+i) = \sum_{j=1}^N \theta_j \mathcal{F}[e^{-x} \beta_j(x)](v).$$

Although  $\mathcal{F}[e^{-x}\beta_j(x)]$  can be computed in the closed form we prefer using FFT and compute  $\mathcal{F}\tilde{O}(v+i)$  on the grid.

**2.4. Estimation of  $\psi$ .** Calculate

$$(2) \quad \tilde{\psi}(v) := \frac{1}{T} \log\left(1 + v(v+i)\mathcal{F}\tilde{O}(v+i)\right), \quad v \in \mathbb{R},$$

where  $\log(\cdot)$  is taken in such a way that  $\tilde{\psi}(v)$  is continuous with  $\tilde{\psi}(-i) = 0$ .

**2.5. Estimation of  $\sigma$ ,  $\gamma$  and  $\lambda$ .** With an estimate  $\tilde{\psi}$  of  $\psi$  at hand, we obtain estimators for the parametric part  $(\sigma^2, \gamma, \lambda)$  by an averaging procedure taking into account the polynomial structure of  $\psi$ . Upon fixing the spectral cut-off value  $U$ , we set

$$(3) \quad \hat{\sigma}^2 := \int_{-U}^U \operatorname{Re}(\tilde{\psi}(u))w_\sigma^U(u) du,$$

$$(4) \quad \hat{\gamma} := \int_{-U}^U \operatorname{Im}(\tilde{\psi}(u))w_\gamma^U(u) du,$$

$$(5) \quad \hat{\lambda} := \int_{-U}^U \operatorname{Re}(\tilde{\psi}(u))w_\lambda^U(u) du,$$

where the weight functions  $w_\sigma^U$ ,  $w_\gamma^U$  and  $w_\lambda^U$  are given explicitly by

$$w_\sigma^U(u) = \frac{r+3}{1-2^{-2/(r+1)}}U^{-(r+3)}|u|^r(1 - 2 \cdot \mathbf{1}_{\{|u|>2^{-1/(r+1)}U\}}), \quad u \in [-U, U],$$

$$w_\gamma^U(u) := \frac{r+2}{2U^{r+2}}|u|^r \operatorname{sgn}(u), \quad u \in [-U, U],$$

$$w_\lambda^U(u) := \frac{r+1}{2(2^{2/(r+3)}-1)}U^{-(r+1)}|u|^r(1 - 2 \cdot \mathbf{1}_{\{|u|<2^{-1/(r+3)}U\}}), \quad u \in [-U, U],$$

and  $r > 0$  is a parameter reflecting our priori knowledge about the smoothness of  $\nu$ .

**2.6. Estimation of  $\nu$ .** Define

$$(6) \quad \hat{\nu}(u) := \mathcal{F}^{-1}\left[\left(\tilde{\psi}(\cdot) + \frac{\hat{\sigma}^2}{2}x^2 - i\hat{\gamma}x + \hat{\lambda}\right)\mathbf{K}(x)\right](u), \quad u \in \mathbb{R},$$

where  $\mathbf{K}(x)$  is a compactly supported kernel. In all simulations we take

$$\mathbf{K}(x) = (1 - (x/U_\nu)^2)^+, \quad x \in \mathbb{R}$$

for some  $U_\nu$  which may differ from  $U$ . The use of an additional cut-off parameter  $U_\nu$  can improve the quality of  $\hat{\nu}$  significantly.

**2.7. Correction of  $\nu$ .** Due to the estimation error and as a result of the cut-off procedure in (6) the estimate  $\hat{\nu}$  can take negative values and needs correcting. Our aim is therefore to find  $\hat{\nu}^+$  such that

$$\|\hat{\nu}^+ - \hat{\nu}\|_{L^2(\mathbb{R})}^2 \rightarrow \min, \quad \inf_{x \in \mathbb{R}} \hat{\nu}^+(x) \geq 0$$

subject to

$$\int_{\mathbb{R}} \hat{\nu}^+(x) dx = \int_{\mathbb{R}} \hat{\nu}(x) dx.$$

It can be easily shown that the solution of the above problem is given by

$$\hat{\nu}^+(x; \xi) := \max\{0, \hat{\nu}(x) - \xi\}, \quad x \in \mathbb{R}$$

where  $\xi$  is chosen to satisfy the equation

$$\int_{\mathbb{R}} \hat{\nu}^+(u; \xi) du = \int_{\mathbb{R}} \hat{\nu}(u) du.$$

**2.8. Choice of parameters.** In our simulations the following heuristic criteria for choosing the spectral cut-off parameter  $U^*$  is employed

$$(7) \quad U^* = \operatorname{argmin}_U \left| \frac{d}{dU} \hat{\sigma}_U \right|.$$

So,  $U^*$  corresponds to the flattest region of the curve  $U \rightarrow \hat{\sigma}_U$  or in other words the region where  $\hat{\sigma}_U$  stabilizes. Other possible approaches to choose  $U$  include stagewise aggregation discussed in Belomesnty and Reiß (2005) and risk hull minimization developed by Cavalier and Golubev (2005). As to  $U_\nu^*$ , it can be found as a point where  $\hat{\nu}_U$  stabilizes

$$(8) \quad U_\nu^* = \operatorname{argmin}_{U_\nu} \left\| \frac{d}{dU_\nu} \hat{\nu}_{U_\nu} \right\|_{L_2}.$$

In the case of real data examples when the Levy model serves as an approximation only the following criteria can be useful. One defines  $U^*$  as a solution of the following minimization problem

$$(9) \quad \inf_U \left[ \sum_{i=1}^N |C(K_i; \mathcal{T}_U) - Y_i|^2 + \alpha \int_{\mathbb{R}} |\hat{\nu}_U''(x)|^2 dx \right], \quad \alpha > 0$$

where  $C(K; \mathcal{T}_U)$  is the price at strike  $K$  computed using the Levy model with the triplet  $\mathcal{T}_U = (\hat{\sigma}_U, \hat{\gamma}_U, \hat{\nu}_U)$ .

### 3. SIMULATED AND REAL DATA EXAMPLES

In this section we present simulated as well as real data examples demonstrating the performance of the calibration algorithm proposed. In our simulations different data designs, sample sizes and noise levels are used in order to investigate the behavior of the procedure in circumstances mimicking real ones. The data design  $\{x_i\}$  is chosen to be normally distributed with zero mean and variance  $1/3$  and hence is similar to the one observed on the market where much more contracts are settled at the money than in- or out of money. Upon simulating the design,  $\{O(x_i)\}$  are computed from the underlying model and then contaminated by the noise with zero mean and variances of the order  $\{[\delta O(x_i)]^2\}$ .

In section 3.1 the *Merton* jump diffusion model is considered where jumps are normally distributed with mean  $\eta$  and variance  $v^2$

$$\nu(x) = \frac{\lambda}{v\sqrt{2\pi}} \exp\left(-\frac{(x-\eta)^2}{2v^2}\right), \quad x \in \mathbb{R}.$$

The parameter  $\gamma$  in the Lévy triple  $(\sigma^2, \gamma, \nu)$  is uniquely determined by the martingale condition

$$\gamma = -(\sigma^2/2 + \lambda(\exp(v^2/2 + \eta) - 1)).$$

Our choice of parameters

$$\underline{\sigma = 0.1, \quad \lambda = 5, \quad \eta = -0.1, \quad v = 0.2}$$

implies  $\underline{\gamma = 0.371}$ . Note, that under such a choice the mean jump size is negative and the model reflects the important feature observed on the market.

More interesting example of *Kou model* is considered in section 3.2 where Lévy density  $\nu$  is given by

$$\nu(x) = \lambda\left(p\lambda_+e^{-\lambda_+x}\mathbf{1}_{[0,\infty)}(x) + (1-p)\lambda_-e^{\lambda_-x}\mathbf{1}_{(-\infty,0)}(x)\right), \quad x \in \mathbb{R}.$$

and  $\lambda_+, \lambda_- \geq 0, p \in [0, 1]$  are parameters. Again the parameter  $\gamma$  is given explicitly by

$$\gamma = -(\sigma^2/2 + \lambda(p/(\lambda_+ - 1) - (1-p)/(\lambda_- + 1)))$$

and under the choice

$$\underline{\sigma = 0.1, \quad \lambda = 5, \quad \lambda_- = 4, \quad \lambda_+ = 8, \quad p = 1/3}$$

one has  $\underline{\gamma = 0.424}$ . The Kou model allows us to model different tails behavior for positive and negative jumps and hence makes the modelling more realistic.

Finally, in section 3.3 two real data examples are presented. Both data

sets consist of DAX options (put and call) for different maturities and strikes. Lévy models are calibrated separately for each maturity.

### 3.1. Merton Model.

Sample Size:  $N = 100$

Noise Level:  $\delta = 0.05$

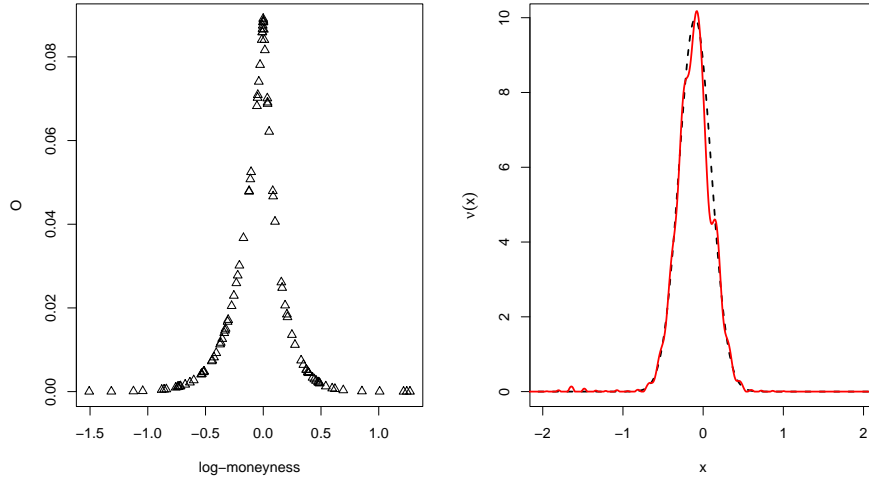


FIGURE 1. Left: Sample  $(O_j)$ . Right: True  $\nu$  (dashed) and estimated  $\hat{\nu}$  (solid) Lévy densities.

$\hat{\sigma}$	$\hat{\gamma}$	$\hat{\lambda}$
0.10402	0.38998	4.90736

TABLE 1. Parameters estimates for the sample shown in Fig. 1 obtained using  $U$  and  $U_\nu$  given by (7) and (8).

$[\mathbb{E}(\hat{\sigma} - \sigma)^2]^{1/2}$	$[\mathbb{E}(\hat{\gamma} - \gamma)^2]^{1/2}$	$[\mathbb{E}(\hat{\lambda} - \lambda)^2]^{1/2}$	$[\mathbb{E} \ \hat{\nu} - \nu\ _{L^2}^2]^{1/2}$
0.000350	0.003237	0.038097	0.487033

TABLE 2. MSE estimated using 500 Monte Carlo simulations under optimal (oracle) choices of  $U$  and  $U_\nu$ .



Sample Size:  $N = 100$

Noise Level:  $\delta = 0.1$

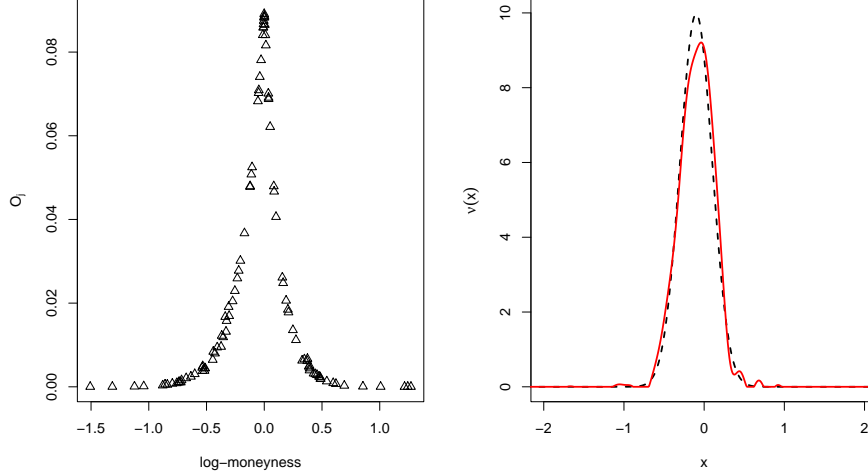


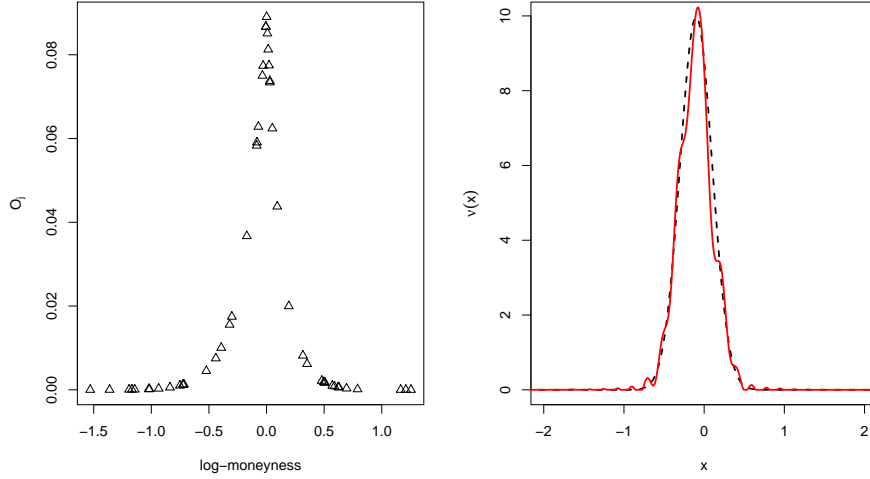
FIGURE 2. Left: Sample  $(O_j)$ . Right: True  $\nu$  (dashed) and estimated  $\hat{\nu}$  (solid) Lévy densities.

$\hat{\sigma}$	$\hat{\gamma}$	$\hat{\lambda}$
0.10208	0.35187	5.06226

TABLE 3. Parameters estimates for the sample shown in Fig. 2 obtained using  $U$  and  $U_\nu$  given by (7) and (8).

$[\mathbb{E}(\hat{\sigma} - \sigma)^2]^{1/2}$	$[\mathbb{E}(\hat{\gamma} - \gamma)^2]^{1/2}$	$[\mathbb{E}(\hat{\lambda} - \lambda)^2]^{1/2}$	$[\mathbb{E} \ \hat{\nu} - \nu\ _{L^2}^2]^{1/2}$
0.000721	0.008502	0.047850	0.632208

TABLE 4. MSE estimated using 500 Monte Carlo simulations under optimal (oracle) choices of  $U$  and  $U_\nu$ .

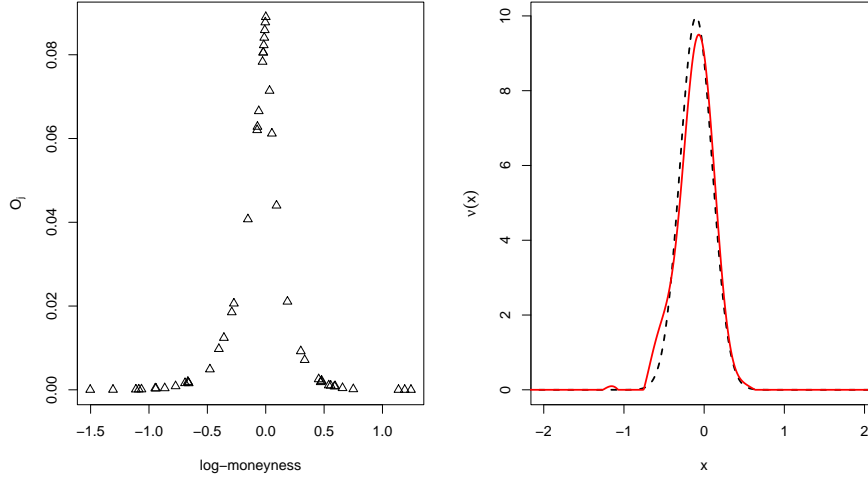
Sample Size:  $N = 50$ Noise Level:  $\delta = 0.05$ FIGURE 3. Left: Sample  $(O_j)$ . Right: True  $\nu$  (dashed) and estimated  $\hat{\nu}$  (solid) Lévy densities.

$\hat{\sigma}$	$\hat{\gamma}$	$\hat{\lambda}$
0.11637	0.38541	4.73875

TABLE 5. Parameters estimates for the sample shown in Fig. 3 obtained using  $U$  and  $U_\nu$  given by (7) and (8).

$[\mathbb{E}(\hat{\sigma} - \sigma)^2]^{1/2}$	$[\mathbb{E}(\hat{\gamma} - \gamma)^2]^{1/2}$	$[\mathbb{E}(\hat{\lambda} - \lambda)^2]^{1/2}$	$[\mathbb{E} \ \hat{\nu} - \nu\ _{L^2}^2]^{1/2}$
0.000882	0.013349	0.043730	0.662298

TABLE 6. MSE estimated using 500 Monte Carlo simulations under optimal (oracle) choices of  $U$  and  $U_\nu$ .

Sample Size:  $N = 50$ Noise Level:  $\delta = 0.1$ FIGURE 4. Left: Sample  $(O_j)$ . Right: True  $\nu$  (dashed) and estimated  $\hat{\nu}$  (solid) Lévy densities.

$\hat{\sigma}$	$\hat{\gamma}$	$\hat{\lambda}$
0.12870	0.36274	4.96426

TABLE 7. Parameters estimates for the sample shown in Fig. 4 obtained using  $U$  and  $U_\nu$  given by (7) and (8).

$[\mathbb{E}(\hat{\sigma} - \sigma)^2]^{1/2}$	$[\mathbb{E}(\hat{\gamma} - \gamma)^2]^{1/2}$	$[\mathbb{E}(\hat{\lambda} - \lambda)^2]^{1/2}$	$[\mathbb{E} \ \hat{\nu} - \nu\ _{L^2}^2]^{1/2}$
0.001852	0.030394	0.060641	0.859707

TABLE 8. MSE estimated using 500 Monte Carlo simulations under optimal (oracle) choices of  $U$  and  $U_\nu$ .

### 3.2. Kou Model.

Sample Size:  $N = 100$

Noise Level:  $\delta = 0.05$

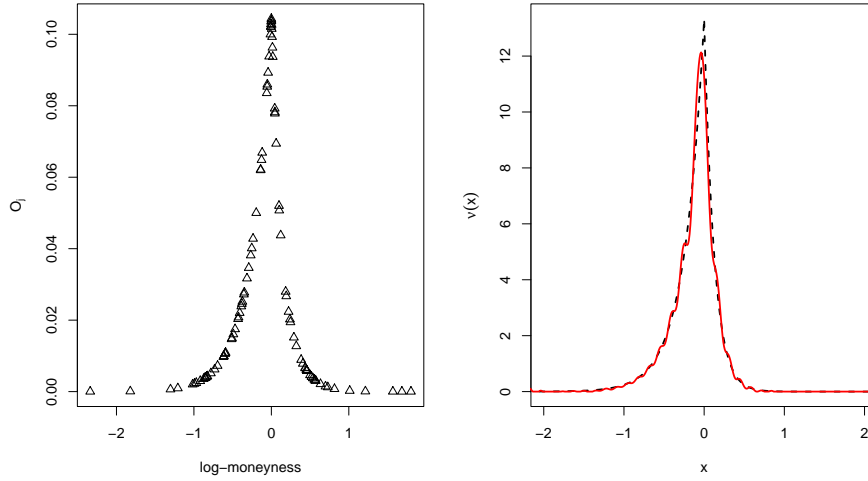


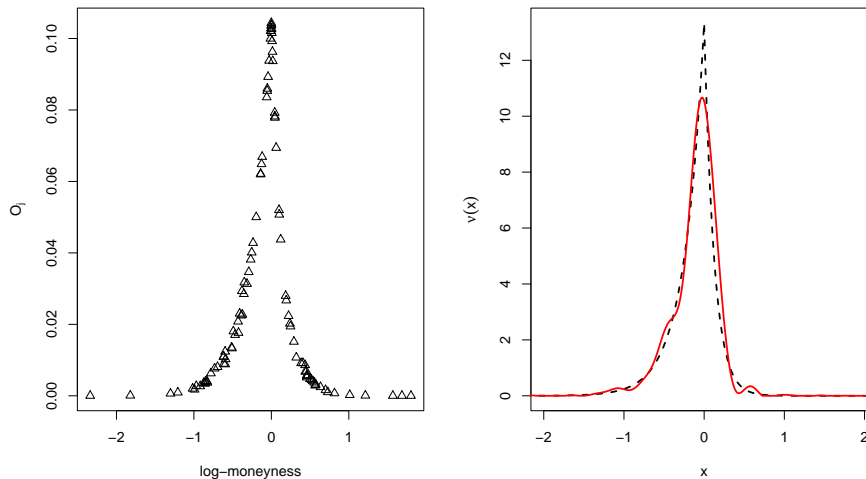
FIGURE 5. Left: Sample  $(O_j)$ . Right: True  $\nu$  (dashed) and estimated  $\hat{\nu}$  (solid) Lévy densities.

$\hat{\sigma}$	$\hat{\gamma}$	$\hat{\lambda}$
0.10071	0.43404	5.04483

TABLE 9. Parameters estimates for the sample shown in Fig. 5 obtained using  $U$  and  $U_\nu$  given by (7) and (8).

$[\mathbb{E}(\hat{\sigma} - \sigma)^2]^{1/2}$	$[\mathbb{E}(\hat{\gamma} - \gamma)^2]^{1/2}$	$[\mathbb{E}(\hat{\lambda} - \lambda)^2]^{1/2}$	$[\mathbb{E} \ \hat{\nu} - \nu\ _{L^2}^2]^{1/2}$
0.001006	0.005631	0.044007	0.662266

TABLE 10. MSE estimated using 500 Monte Carlo simulations under optimal (oracle) choices of  $U$  and  $U_\nu$ .

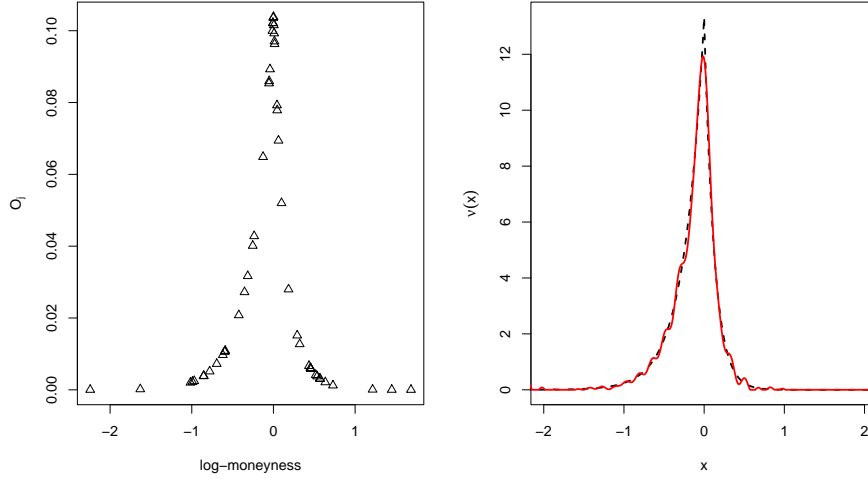
Sample Size:  $N = 100$ Noise Level:  $\delta = 0.1$ FIGURE 6. Left: Sample  $(O_j)$ . Right: True  $\nu$  (dashed) and estimated  $\hat{\nu}$  (solid) Lévy densities.

$\hat{\sigma}$	$\hat{\gamma}$	$\hat{\lambda}$
0.09696	0.38269	5.19702

TABLE 11. Parameters estimates for the sample shown in Fig. 6 obtained using  $U$  and  $U_\nu$  given by (7) and (8).

$[\mathbb{E}(\hat{\sigma} - \sigma)^2]^{1/2}$	$[\mathbb{E}(\hat{\gamma} - \gamma)^2]^{1/2}$	$[\mathbb{E}(\hat{\lambda} - \lambda)^2]^{1/2}$	$[\mathbb{E} \ \hat{\nu} - \nu\ _{L^2}^2]^{1/2}$
0.001786	0.012310	0.054588	0.944580

TABLE 12. MSE estimated using 500 Monte Carlo simulations under optimal (oracle) choices of  $U$  and  $U_\nu$ .

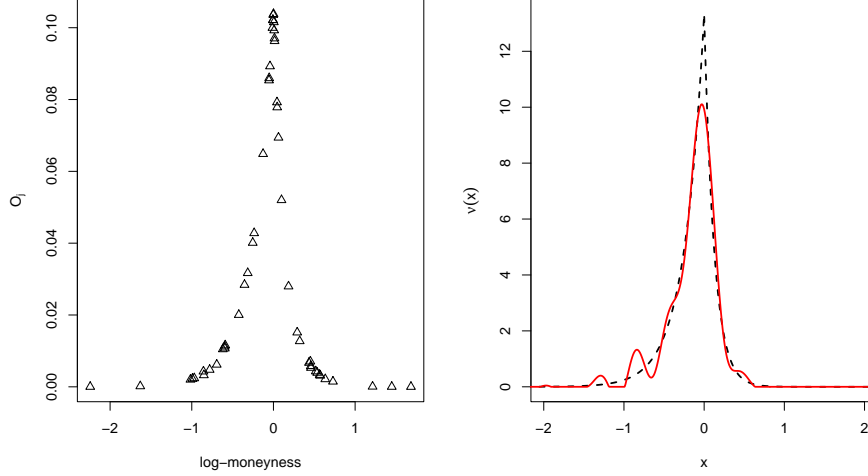
Sample Size:  $N = 50$ Noise Level:  $\delta = 0.05$ FIGURE 7. Left: Sample  $(O_j)$ . Right: True  $\nu$  (dashed) and estimated  $\hat{\nu}$  (solid) Lévy densities.

$\hat{\sigma}$	$\hat{\gamma}$	$\hat{\lambda}$
0.10889	0.41842	4.99187

TABLE 13. Parameters estimates for the sample shown in Fig. 7 obtained using  $U$  and  $U_\nu$  given by (7) and (8).

$[\mathbb{E}(\hat{\sigma} - \sigma)^2]^{1/2}$	$[\mathbb{E}(\hat{\gamma} - \gamma)^2]^{1/2}$	$[\mathbb{E}(\hat{\lambda} - \lambda)^2]^{1/2}$	$[\mathbb{E} \ \hat{\nu} - \nu\ _{L^2}^2]^{1/2}$
0.002444	0.018898	0.064104	0.998157

TABLE 14. MSE estimated using 500 Monte Carlo simulations under optimal (oracle) choices of  $U$  and  $U_\nu$ .

Sample Size:  $N = 50$ Noise Level:  $\delta = 0.1$ FIGURE 8. Left: Sample  $(O_j)$ . Right: True  $\nu$  (dashed) and estimated  $\hat{\nu}$  (solid) Lévy densities.

$\hat{\sigma}$	$\hat{\gamma}$	$\hat{\lambda}$
0.13086	0.42390	4.98324

TABLE 15. Parameters estimates for the sample shown in Fig. 8 obtained using  $U$  and  $U_\nu$  given by (7) and (8).

$[\mathbb{E}(\hat{\sigma} - \sigma)^2]^{1/2}$	$[\mathbb{E}(\hat{\gamma} - \gamma)^2]^{1/2}$	$[\mathbb{E}(\hat{\lambda} - \lambda)^2]^{1/2}$	$[\mathbb{E} \ \hat{\nu} - \nu\ _{L^2}^2]^{1/2}$
0.004917	0.037315	0.108304	1.40540

TABLE 16. MSE estimated using 500 Monte Carlo simulations under optimal (oracle) choices of  $U$  and  $U_\nu$ 


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### 3.3. Real Data Examples.

DAX options, 22 March 1999

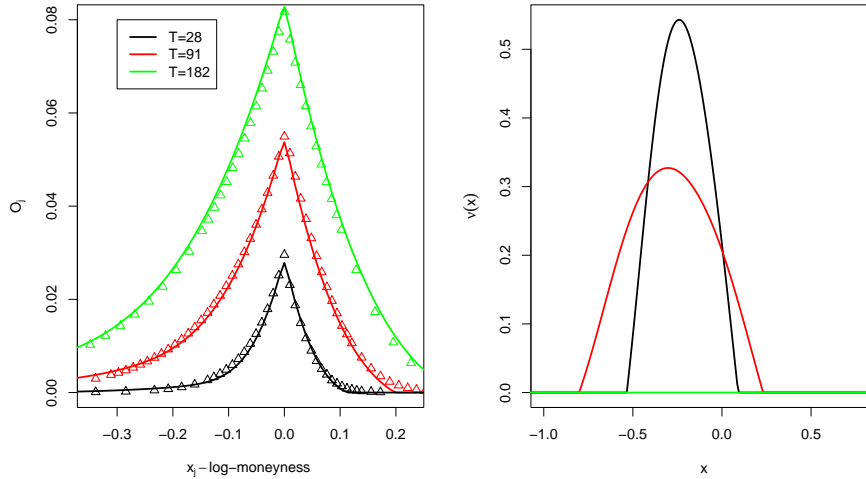


FIGURE 9. Left: Observed (triangles) and fitted (solid line) put ( $x_j < 0$ ) and call ( $x_j \geq 0$ ) prices for different maturities. Right: Estimated Lévy densities.

$T$	$N$	$\hat{\sigma}$	$\hat{\gamma}$	$\hat{\lambda}$
<b>28</b>	37	0.0673	0.0379	0.2105
<b>91</b>	56	0.0699	0.0360	0.2118
<b>182</b>	38	0.0819	0.0417	0.0019

TABLE 17. Parameters of Lévy triple estimated from DAX data shown in Fig. 9 with  $U$  chosen via the criteria (9) with  $\alpha = 1e - 8$

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All options data used here are publicly available in MDBase at <http://www.quantlet.org/mdbase>



## DAX options, 21 Juni 1999

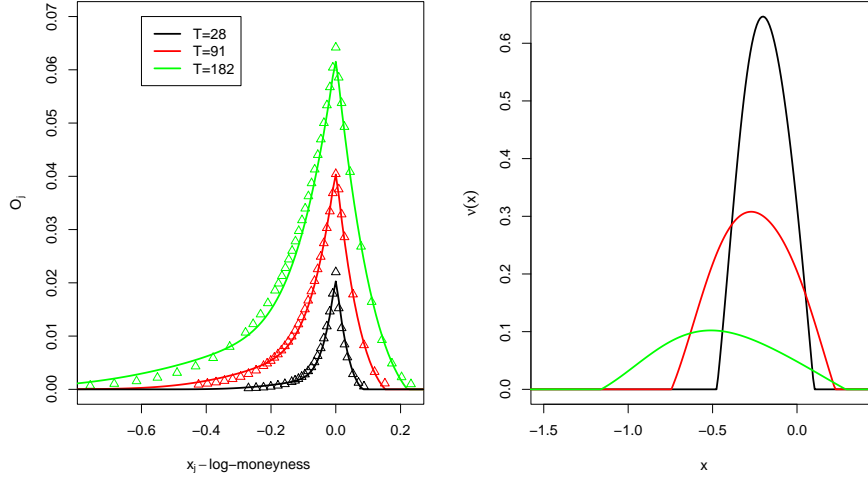


FIGURE 10. Left: Observed (triangles) and fitted (solid line) put ( $x_j < 0$ ) and call ( $x_j \geq 0$ ) prices for different maturities. Right: Estimated Lévy densities.

$T$	$N$	$\hat{\sigma}$	$\hat{\gamma}$	$\hat{\lambda}$
<b>28</b>	28	0.0353	0.0416	0.2317
<b>91</b>	38	0.0381	0.0347	0.1876
<b>182</b>	42	0.0446	0.0214	0.0887

TABLE 18. Parameters of Lévy triple estimated from DAX data shown in Fig. 10 with  $U$  chosen via the criteria (9) with  $\alpha = 1e - 8$

## 4. CONCLUSIONS

- The performance of the procedure depends strongly on the noise level and the number of observations the first being dominating.
- The smoother is the Lévy density the better is the performance of the procedure the difference being more pronounced for smaller noise levels.
- The main features of Lévy measures (different tails behavior, negative mean jump size) are preserved during the reconstruction.
- In the real data examples the algorithm produces stable estimates for  $\sigma$ ,  $\lambda$  decreasing with maturity, jump distributions with negative mean jump sizes, and by rather small complexity of Lévy measures fits the data in a reasonable way.

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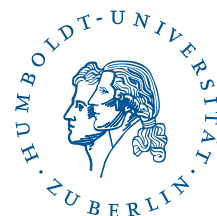
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