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NUMERICAL ANALYSIS OF A NEW MIXED FORMULATION FOR EIGENVALUE CONVECTION-DIFFUSION PROBLEMS*

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Abstract. A mixed formulation is proposed and analyzed mathematically for coupled convection-diffusion in heterogeneous medias. Transfer in solid parts driven by pure diffusion is coupled with convection-diffusion transfer in fluid parts. This study is carried out for translation-invariant geometries (general infinite cylinders) and unidirectional flows. This formulation brings to the fore a new convection-diffusion operator, the properties of which are mathematically studied: its symmetry is first shown using a suitable scalar product. It is proved to be self-adjoint with compact resolvent on a simple Hilbert space. Its spectrum is characterized as being composed of a double set of eigenvalues: one converging towards $-\infty$ and the other towards $+\infty$, thus resulting in a nonsectorial operator. The decomposition of the convection-diffusion problem into a generalized eigenvalue problem permits the reduction of the original three-dimensional problem into a two-dimensional one. Despite the operator being nonsectorial, a complete solution on the infinite cylinder, associated to a step change of the wall temperature at the origin, is exhibited with the help of the operator's two sets of eigenvalues/eigenfunctions. On the computational point of view, a mixed variational formulation is naturally associated to the eigenvalue problem. Numerical illustrations are provided for axisymmetrical situations, the convergence of which is found to be consistent with the numerical discretization.

Key words. convection-diffusion, variational formulation, Hilbert space, mixed formulation

AMS subject classifications. 75R99, 46-99, 35A15, 65M60

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1. Introduction. Convection-diffusion problems are of importance in many fields of application in thermal, chemical, and biomedical engineering sciences. More specifically, heat or mass diffusion coupled with unidirectional convection is present in many types of equipment such as heat pipes, heat exchangers (shell, tube, or plate), chromatographs, reactors, and mass exchangers in microchannel artificial devices, and it occurs in real biological tissues. This framework covers both parallel and counter flow configurations.

A classical strategy for describing the temperature field T of tube-like configurations in the applied literature is generally to assume the separation of variables solution,

$$(1) \quad T(x, y, z) = \sum_{\lambda \in \Lambda} c_{\lambda} T_{\lambda}(x, y) e^{\lambda z},$$

where z is the longitudinal coordinate along which the flow is aligned and x, y are transverse coordinates. The usual subsequent steps [7] are then to search for the *eigenvalues/eigenfunctions* λ/T_{λ} and finally compute the amplitude coefficients c_{λ} .

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For a clear understanding of these points, returning to their origin is instructive. Graetz and Nusselt [9, 17] studied the following simplified version of the problem: a fluid flowing in a single duct at high Péclet number Pe (which is the ratio of convection to diffusion time scales), when longitudinal diffusion is negligible compared to radial diffusion. The duct is assumed to be either a circular cylinder or made of two parallel infinite plates. Such a symmetric configuration actually leads to simplified one-dimensional problems. The original Graetz problem correspond to the case of cylindrical duct. The radial coordinate being denoted r , it reads

$$\frac{1}{r} \partial_r (r \partial_r T) = Pe v(r) \partial_z T,$$

with a Poiseuille parabolic velocity profile $v(r)$. In this simplified framework, searching for a separation of variables solution, we find

$$(2) \quad T(r, z) = T_\lambda(r) e^{\lambda Pe z}, \quad \frac{1}{r} \frac{d}{dr} \left(r \frac{dT_\lambda}{dr} \right) = \lambda v T_\lambda,$$

which allows the definition of λ/T_λ as eigenvalues/eigenfunctions. Problem (2) is, moreover, symmetric negative and self-adjoint with compact resolvent, justifying decomposition (1), where Λ appears as a discrete subset of \mathbb{R}^- . Moreover, the coefficients c_λ can be easily computed using the simple scalar product over variable r thanks to the axisymmetry of the initial condition and the boundary conditions

$$c_\lambda = \int T_0(r) T_\lambda(r) r dr,$$

where T_0 is the inlet condition at $z = 0$.

These results have historically justified (1) as an interesting heuristic. However, as soon as the Graetz–Nusselt framework is modified, none of the previous steps can be performed in a simple way. Indeed, many studies have explored possible extensions to that framework. Among these extensions, the following two are of particular importance: the extended Graetz problem, where the longitudinal diffusion term is no longer neglected, and the conjugated Graetz problem, in which coupling with a solid wall where diffusion occurs is considered. The difficulties met by previous contributors when considering these two simple but nontrivial extensions are listed below.

Looking for a separation of variables solution $T(r, z) = T_\lambda(r) e^{\lambda z}$ no longer provides an eigenvalue problem. Precisely in the case of the conjugated Graetz problem, the new problem to be solved for T_λ reads

$$\begin{cases} \frac{1}{r} \partial_r (r \partial_r T_\lambda) = \lambda Pe v T_\lambda & \text{fluid part} \\ \frac{1}{r} \partial_r (r \partial_r T_\lambda) = -\lambda^2 T_\lambda & \text{solid part} \end{cases} + \text{coupling condition on the fluid/solid interface,}$$

where the quadratic term λ^2 is accounting for the axial diffusion along z . In such a form, one can see that this problem is not an eigenvalue problem on the whole fluid+solid domain.

Adding axial diffusion now permits information back-flow in the $z < 0$ direction, not only along the flow with $z > 0$. Therefore both positive and negative *eigenvalues* λ are physically expected: the previous symmetric-negative structure of the Graetz problem is no longer relevant here. However, until the work of Papatoukakis, Ramakrishna, and Lim [18], detailed below, no attention had been paid

to this important point. Early papers on the extended/conjugated Graetz problem [26, 1, 15, 5, 6, 13, 27, 28, 16] assumed a negative *spectrum* (that could, at least in principle, be complex) and a complete set of *eigenfunctions* by inserting a Graetz-problem-like series solution into the convection-diffusion equation.

Still in these early works, as pointed out by Michelsen and Villadsen [16], the difficulties of determining both the nonorthogonal *eigenfunctions* and the expansion coefficients c_λ appear critical. From a computational point of view the strategy used by Hsu and Tam [13, 27, 28] using the Gram-Schmidt reorthogonalization procedure has a high cost, especially when approaching the entrance region where a large number of *eigenvalues* is necessary for a correct representation of the solution.

The domain definition and inlet condition also raise new questions and difficulties. In early papers, the flow domain is set as the positive real axis, and the assumption of uniform fluid temperature at the inlet has been widely used. As pointed out in [18, 29], e.g., when axial diffusion is permitted, the uniform inlet condition is invalid since the temperature would be altered by upstream conduction before reaching the inlet location.

The most important progress in overcoming these difficulties has been made by Papoutsakis, Ramakrishna, and Lim in a series of innovative papers [19, 20, 18]. Paper [18] proposes a new formulation of the extended Graetz problem, adding a second unknown temperature flux, leading to a symmetric eigenvalue problem. This approach thus solves the problem regarding the spectrum location (real eigenvalues only) and provides an adequate formulation for the amplitude coefficient c_λ computation. This approach has been successfully used in a series of recent papers by Weigand et al. [30, 33, 32, 31] and Ho, Yeh, and Yang for various heat exchanger configurations; see, e.g., [12, 11]. Hence, to our knowledge, there is no complete theoretical foundation for decomposition (1). This lack of theoretical framework, despite the commonly used terminology, does not permit A and T_λ to be defined via an eigenvalue problem, all the more so a symmetrical one. On the one hand, this is a fundamental problem for the definition of A 's topology and location, though it is always assumed to be real and discrete. On the other hand, this is a practical issue for the numerical computation of T_λ and of the coefficients c_λ for which no direct orthogonal properties are available from a simple, scalar-product-based, definition.

In our opinion, three important issues are still pending concerning the framework of Papoutsakis, Ramakrishna, and Lim:

1. It only covers symmetrical configurations such as circular ducts or rectangular channels;
2. the extension to the conjugated Graetz problem proposed in [19, 20] remains heavy and complicated;
3. from a theoretical point of view, only a symmetry property has been proved. This is not sufficient to justify either the discrete structure of the considered spectrum or the finite order of the eigenfunctions. For this, self-adjointness results as well as compactness properties are necessary, which haven't been proved yet, weakening the legitimacy of the proposed decomposition (1).

The aim of this paper is to address these issues in a very general tube configuration (we assume no symmetry of the tube section) for any general unidirectional velocity profile (for example, allowing non-Newtonian velocity profiles).

At this point, it is important to stress that the mathematical justification of the previous approaches is not the main motivation of the present contribution. The framework proposed here is opening new perspectives for the computation of a large variety of configurations that have not been considered previously. A major conse-

quence of this work is a complete description of the original three-dimensional problem by solving a two-dimensional one only, whose numerical discretization is obviously much lighter. Moreover, this two-dimensional problem to be solved can naturally be embedded into a simple mixed variational formulation. This provides a wide class of standard discretization using mixed finite-element methods that can be implemented with basic finite-element libraries.

The physical and geometrical frameworks are described in section 2. Section 3 develops a theoretical investigation of equation (1) decomposition for the temperature solution. Subsection 3.1 introduces a reformulation of the problem which allows the search for a separation of variables solution and leads to an eigenvalue problem. In subsection 3.2 the functional properties of the eigenvalue problem operator are established. It is proved to be symmetric and, moreover, self-adjoint with a compact resolvent on a basic Hilbert space. At the end of this theoretical section, these results are used in subsection 3.3 to display a full decomposition of a temperature field for which far field conditions are substituted for an inappropriate inlet condition at $z = 0$. This decomposition appears efficient from a computational point of view since it exhibits only the eigenvalues/eigenvectors of the problem as well as easily computable coefficients using simple scalar products. In section 4, it is shown that the eigenvalue problem is naturally equivalent to a mixed variational problem, thus providing a simple computational framework to solve the eigenvalue problem in terms of mixed finite-element methods. The remaining part of this section is devoted to the analysis of the numerical convergence of the method. We restrict ourselves to symmetric configurations where analytical solutions are available allowing an a priori error estimate of the solution. In this last section we notably study the previously discussed extended Graetz and conjugated Graetz problems.

2. Physical statement.

2.1. Geometry, general assumptions, and notation. The domain considered here is an infinite cylinder $Z = \Omega \times \mathbb{R}$ having a cross-section $\Omega \subset \mathbb{R}^2$ (assumptions on Ω are stated below) as displayed in Figure 1. The coordinate system relative to Ω will be denoted by (x, y) and the axial coordinate by $z \in \mathbb{R}$.

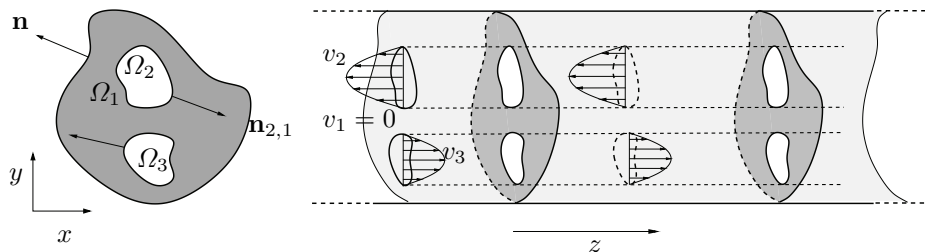


FIG. 1. Domain cross-section Ω (left) and whole domain $Z = \Omega \times \mathbb{R}$ (right).

The domain cross-section Ω is assumed bounded and its boundary $\partial\Omega$ is taken to be smooth (C^1 regularity). Its outward normal is denoted by \mathbf{n} . Ω is divided into a collection of open subdomains Ω_i ($1 \leq i \leq N$) with smooth boundaries, disjoint ($\Omega_i \cap \Omega_j = \emptyset$ if $i \neq j$) and such that $\overline{\Omega} = \cup_i \overline{\Omega}_i$. The interface between Ω_i and Ω_j (if nonempty) is denoted by $\Gamma_{ij} = \overline{\Omega}_i \cap \overline{\Omega}_j$, and its unit normal, outward from Ω_i towards Ω_j , will be denoted by \mathbf{n}_{ij} . These assumptions ensure that the seminorm $\int_{\Omega} |\nabla u|^2 dx$

is a norm on $H_0^1(\Omega)$ equivalent to the H_1 norm (Poincaré inequality) and also that $H_0^1(\Omega)$ and $H^1(\Omega_i)$ have compact embedding into $L^2(\Omega)$ and $L^2(\Omega_i)$, respectively (see, e.g., [8, 3]).

The flow in the fluid part is assumed to be established and laminar, so that the velocity $\mathbf{v} = v(x, y)\mathbf{e}_z$ is along the z direction and is a function of (x, y) only. The velocity profile v is only assumed bounded, i.e., $v \in L^\infty(\Omega)$, though it is physically continuous in all applications. Solid subdomains Ω_i are taken into account by setting $v|_{\Omega_i} = 0$. $v > 0$ (resp., $v < 0$) on Ω_i naturally means that Ω_i is a fluid subdomain where the flow is in the $z > 0$ (resp., $z < 0$) direction.

The conductivity k is isotropic but heterogeneous. Precisely, k is a bounded, positive, and piecewise constant function constant on every Ω_i :

$$(3) \quad 0 < \alpha \leq k(x) \leq \beta < +\infty \quad \text{a.e. in } \Omega, \quad k_i := k|_{\Omega_i} \in \mathbb{R}.$$

$T_i := T|_{\Omega_i}$ indicates the restriction of the function T to the subdomain Ω_i . Conventionally here, the differential operators div , ∇ are considered on \mathbb{R}^2 only, i.e., $\text{div} \mathbf{p} = \partial_x p_1 + \partial_y p_2$ and $\nabla f = (\partial_x f, \partial_y f)$, for a vector field \mathbf{p} and a scalar function f , respectively.

2.2. Energy equation. On the infinite cylinder $Z = \Omega \times \mathbb{R}$. The dimensionless energy equation is

$$(4) \quad \text{div}(k\nabla T) + k\partial_z^2 T = \text{Pe } v\partial_z T,$$

where Pe is the dimensionless Péclet number. On the cylinder boundary ∂Z , constant temperatures are imposed, with a step change at the entry $z = 0$,

$$(5) \quad \begin{cases} T|_{\partial Z} = 1 & \text{if } z < 0, \\ T|_{\partial Z} = 0 & \text{if } z > 0. \end{cases}$$

Relevant limit conditions as $z \rightarrow \pm\infty$ therefore are

$$(6) \quad T(\cdot, z) \xrightarrow{z \rightarrow -\infty} 1, \quad T(\cdot, z) \xrightarrow{z \rightarrow +\infty} 0.$$

Coupling conditions at the subdomain interfaces also are required; physically standing for the continuity of the temperature (concentration) and of the normal heat (mass) flux, they read

$$(7) \quad T_i = T_j \quad \text{and} \quad k_i \nabla T_i \cdot \mathbf{n}_{ij} = k_j \nabla T_j \cdot \mathbf{n}_{ij} \quad \text{on } \Gamma_{ij},$$

whenever the interface Γ_{ij} is nonempty, the dot product naturally standing for the scalar product in \mathbb{R}^2 .

3. Mathematical analysis.

3.1. Problem reformulation. Equation (4) is reformulated into a system of two first order differential equations

$$(8) \quad \partial_z T = \text{Pe } v k^{-1} T - k^{-1} \text{div}(\mathbf{p}),$$

$$(9) \quad \partial_z \mathbf{p} = k \nabla T,$$

where T still denotes the dimensionless temperature (or concentration), and the additional unknown \mathbf{p} denotes a vector valued function on Ω .

Albeit mathematically correct, this formulation calls for some physical justification. Formulation (8)–(9) is derived from the splitting of the three-dimensional divergence operator (4) into a two-dimensional contribution in the transverse plane and a longitudinal one along the z coordinate. The transverse contribution of the flux on the right-hand side of relation (9) is integrated along the longitudinal direction in vector \mathbf{p} . Thus this contribution acts as a source term along the one-dimensional longitudinal convection-diffusion formulation on the right-hand side of relation (8). This splitting which is allowed from the integration of the flux along the longitudinal direction in (9) is possible for longitudinally invariant problems hereby considered. It then permits the formal integration of the solution along the longitudinal direction and reduces the dimensionality of the problem from three to two.

Introducing the following unbounded operator $A : D(A) \subset \mathcal{H} \mapsto \mathcal{H}$ on a Hilbert space \mathcal{H} and with domain $D(A)$ (whose definitions follow), system (8) takes the form of an ODE on the infinite-dimensional space \mathcal{H} with unknown $\Phi(z) \in \mathcal{H}$:

$$(10) \quad \frac{d}{dz}\Phi(z) = A\Phi(z) \quad \Phi(z) = \begin{pmatrix} T(z) \\ \mathbf{p}(z) \end{pmatrix}, \quad A = \begin{pmatrix} \text{Pe } vk^{-1} & -k^{-1}\text{div}(\cdot) \\ k\nabla \cdot & 0 \end{pmatrix}.$$

The space \mathcal{H} is defined as the Hilbert space product $\mathcal{H} = L^2(\Omega) \times (L^2(\Omega))^2$, where $(L^2(\Omega))^2$ is the space of square integrable vector valued functions on Ω . \mathcal{H} is equipped with the following scalar product:

$$(11) \quad (\Psi_1, \Psi_2)_{\mathcal{H}} = \left(\begin{pmatrix} T_1 \\ \mathbf{p}_1 \end{pmatrix}, \begin{pmatrix} T_2 \\ \mathbf{p}_2 \end{pmatrix} \right)_{\mathcal{H}} = \int_{\Omega} T_1 T_2 k dx + \int_{\Omega} \mathbf{p}_1 \cdot \mathbf{p}_2 k^{-1} dx.$$

Note that this scalar product on \mathcal{H} is equivalent to the canonical one (taking $k = 1$) by using assumption (3). It has been modified to ensure the symmetry of the operator A .

Relative to a homogeneous Dirichlet boundary condition, the domain $D(A)$ is given as $D(A) := H_0^1(\Omega) \times H(\text{div}, \Omega)$, where $H(\text{div}, \Omega) = \{\mathbf{p} \in (L^2(\Omega))^2, \text{div}(\mathbf{p}) \in L^2(\Omega)\}$ in the distribution sense. We shall refer to [4] for the basic properties of the space. Such a definition of $D(A)$ ensures that $A : D(A) \subset \mathcal{H} \mapsto \mathcal{H}$ in (10) is well defined.

PROPOSITION 1. *The operator A is dense and symmetric:*

$$(12) \quad \forall \Psi_1, \Psi_2 \in D(A) : (A\Psi_1, \Psi_2)_{\mathcal{H}} = (\Psi_1, A\Psi_2)_{\mathcal{H}}.$$

Proof. The density of A directly follows from its definition. Denoting

$$\Psi_j = \begin{pmatrix} T_j \\ \mathbf{p}_j \end{pmatrix}, \quad j = 1, 2,$$

using the Green formula and the fact that $T_j \in H_0^1(\Omega)$ yields

$$\begin{aligned} (A\Psi_1, \Psi_2)_{\mathcal{H}} &= \int_{\Omega} \text{Pe } v T_1 T_2 dx - \int_{\Omega} \text{div}(\mathbf{p}_1) T_2 dx + \int_{\Omega} \nabla T_1 \cdot \mathbf{p}_2 dx \\ &= \int_{\Omega} \text{Pe } v T_2 T_1 dx + \int_{\Omega} \mathbf{p}_1 \cdot \nabla T_2 dx - \int_{\Omega} T_1 \text{div}(\mathbf{p}_2) dx \\ &= (\Psi_1, A\Psi_2)_{\mathcal{H}}. \quad \square \end{aligned}$$

3.2. Spectral analysis of A . In this section, the main theoretical result of our study is proved. We show that A is self-adjoint and that (0 excepted), its spectrum is made of eigenvalues of finite order only, the corresponding eigenfunctions forming a Hilbert (complete) base of $(\text{Ker } A)^\perp = \text{Ran } A$. We observe that denoting by $\Psi_n = (T_n, \mathbf{p}_n)$ the components of the n th eigenfunction ($A\Psi_n = \lambda_n\Psi_n$) and introducing $T(x, y, z) = e^{\lambda_n z}T_n(x, y)$, we have

$$\text{div}(k\nabla T_n) + \lambda_n^2 kT_n = \lambda_n \text{Pe } vT_n \quad \text{and} \quad \text{div}(k\nabla T) + k\partial_z^2 T = \text{Pe } v\partial_z T,$$

and T is a solution of the original energy equation (4). Incidentally, we also recover the so-called *eigenvalues/eigenfunctions* of the previously quoted literature [1, 2, 6, 5, 13, 27, 28, 15, 26]. This theorem therefore brings full legitimacy to the decompositions routinely found in the literature.

THEOREM 1. $A : D(A) \subset \mathcal{H} \mapsto \mathcal{H}$ is self-adjoint and has a compact resolvent.

We introduce the Kernel of A , $\text{Ker } A = \{(0, \mathbf{p}), \mathbf{p} \in H_0(\text{div}, \Omega)\}$, where $H_0(\text{div}, \Omega) = \{\mathbf{p} \in H(\text{div}, \Omega), \text{div } \mathbf{p} = 0\}$. Then there exists a Hilbert base $(\Psi_n)_{n \in \mathbb{N}}$ of $\text{Ran } A = (\text{Ker } A)^\perp$ composed of eigenfunctions: $\Psi_n \in D(A)$, $A\Psi_n = \lambda_n\Psi_n$, $\|\Psi_n\|_{\mathcal{H}} = 1$. The coordinates of Ψ_n are denoted $\Psi_n = (T_n, \mathbf{p}_n) = (T_n, k\nabla T_n/\lambda_n)$. We therefore have

$$D(A) = \left\{ \Psi \in \mathcal{H}, \sum_n |\lambda_n(\Psi, \Psi_n)_{\mathcal{H}}|^2 < +\infty \right\}, \quad A\Psi = \sum_n \lambda_n(\Psi, \Psi_n)_{\mathcal{H}}\Psi_n$$

for all $\Psi \in D(A)$.

Moreover this base can be split into two parts $(\Psi_i^+)_{i \in \mathbb{N}}$ and $(\Psi_i^-)_{i \in \mathbb{N}}$ such that

$$(13) \quad 0 > \lambda_1^+ \geq \dots \geq \lambda_j^+ \geq \dots \rightarrow -\infty, \quad 0 < \lambda_1^- \leq \dots \leq \lambda_j^- \leq \dots \rightarrow +\infty.$$

The corresponding eigenfunctions are denoted Ψ_n^\pm . Eigenvalues and eigenfunctions, according to this decomposition, are respectively called upstream (+) and downstream (-).

In the proof, we shall use the following regularity result (see [14, pp. 192–196]).

LEMMA 1. For any $f \in L^2(\Omega)$, there exists a unique $T \in H_0^1(\Omega)$ satisfying $\text{div}(k\nabla T) = f$ in the distribution sense. That solution also satisfies, on each subdomain Ω_i , $T_i \in H^2(\Omega_i)$, $\text{div}(k\nabla T) = f$ in $L^2(\Omega_i)$ (strong sense), and $\|T_i\|_{H^2(\Omega_i)} \leq C\|f\|_{L^2(\Omega)}$ (C independent on f). Moreover T satisfies on every interface $\Gamma_{i,j}$ the coupling conditions (7) in the trace sense.

Proof. A is dense and symmetric. Since $vk^{-1} \in L^\infty(\Omega)$, A is also a continuous perturbation of the symmetric operator $A_0 : D(A) \subset \mathcal{H} \mapsto \mathcal{H}$ defined as

$$A_0 = \begin{pmatrix} 0 & -k^{-1}\text{div}(\cdot) \\ k\nabla \cdot & 0 \end{pmatrix}.$$

Using the Kato–Relish theorem (see, e.g., [24, p. 163]), the self-adjointness of A_0 implies the self-adjointness of A . To prove the self-adjointness of A_0 , one shows that $A_0 + i$ has range \mathcal{H} (see, e.g., [23]).

Let us fix $(f, \mathbf{q}) \in \mathcal{H}$. We search for $T \in H_0^1(\Omega)$ such that

$$\forall \varphi \in H_0^1(\Omega) : \int_\Omega T\varphi k dx + \int_\Omega k\nabla T \cdot \nabla \varphi dx = \int_\Omega \nabla \varphi \cdot \mathbf{q} dx - \int_\Omega i\varphi f k dx.$$

The right-hand side clearly has a continuous linear form on $H_0^1(\Omega)$, whereas the left-hand side exhibits a symmetric, positive, continuous, and coercive bilinear product

on $H_0^1(\Omega)$. As a result, the Lax–Milgram theorem applies (see, e.g., [8]) ensuring the existence and uniqueness of such a T . Let us define $i\mathbf{p} = \mathbf{q} - k\nabla T \in (L^2(\Omega))^2$. From the above equality we obtain

$$\forall \varphi \in C_c^\infty(\Omega) : \int_{\Omega} i\mathbf{p} \cdot \nabla \varphi dx = \int_{\Omega} k(if + T)\varphi dx.$$

This equality shows that, in the distribution sense, $\text{div}(\mathbf{p}) \in L^2(\Omega)$ and we have $\mathbf{p} \in H(\text{div}, \Omega)$. Thus $\Psi = (T, \mathbf{p}) \in D(A)$ and one has $(A_0 + i)\Psi = (f, \mathbf{q})$, proving the self-adjointness of A_0 and A .

To prove that A has a compact resolvent, we introduce the pseudoinverse of A , $A^{-1} : \text{Ran } A \mapsto (\text{Ker } A)^\perp \cap D(A) = \text{Ran } A \cap D(A)$, and we prove that A^{-1} is compact.

For this let us consider a bounded sequence $(f_n, \mathbf{q}_n) \in \text{Ran } A$. There is a unique $(T_n, \mathbf{p}_n) \in \text{Ran } A \cap D(A)$ satisfying $A(T_n, \mathbf{p}_n) = (f_n, \mathbf{q}_n)$. (T_n) then satisfies $k\nabla T_n = \mathbf{q}_n$ and therefore forms a bounded sequence in $H_0^1(\Omega)$. The compact embedding $H_0^1(\Omega) \mapsto L^2(\Omega)$ thus implies that (T_n) is relatively compact in $L^2(\Omega)$.

We now introduce $\varphi_n \in H_0^1(\Omega)$, the unique variational solution to $\text{div}(k\nabla \varphi_n) = \text{Pe } vT_n - kf_n$. Let us prove that $\mathbf{p}_n = k\nabla \varphi_n$. Since $A(T_n, k\nabla \varphi_n) = (f_n, \mathbf{q}_n)$, we have to check that $(T_n, k\nabla \varphi_n) \in (\text{Ker } A)^\perp$ that follows from

$$\forall \mathbf{p} \in H_0(\text{div}, \Omega) : \left(\begin{array}{c} T_n \\ k\nabla \varphi_n \end{array}, \begin{array}{c} 0 \\ \mathbf{p} \end{array} \right)_{\mathcal{H}} = \int_{\Omega} \nabla \varphi_n \cdot \mathbf{p} dx = - \int_{\Omega} \varphi_n \text{div}(\mathbf{p}) dx = 0.$$

Lemma 1 then applies and ensures that $\varphi_n|_{\Omega_i} \in H^2(\Omega_i)$ and that, since $(\text{Pe } vT_n - kf_n)$ is bounded in $L^2(\Omega)$, $(\varphi_n|_{\Omega_i})$ is bounded in $H^2(\Omega_i)$. Therefore both components of $(\nabla \varphi_n|_{\Omega_i})$ are bounded in $H^1(\Omega_i)$, thus implying that both components of $(\mathbf{p}_n|_{\Omega_i})$ also are bounded in $H^1(\Omega_i)$. The compact embedding $H^1(\Omega_i) \subset L^2(\Omega_i)$ then ensures that (\mathbf{p}_n) is relatively compact in $L^2(\Omega)$.

Consequently, A^{-1} is compact and self-adjoint on the separable space $\text{Ran } A$. Therefore there exists a Hilbert base $(\Psi_n)_{n \in \mathbb{N}}$ for $\text{Ran } A$ made of eigenfunctions: $\Psi_n \in D(A)$, $A\Psi_n = \lambda_n\Psi_n$.

A^{-1} being compact, 0 is the only limit point for subsequences of $(1/\lambda_n)$, and thus $\{-\infty, +\infty\}$ are the only two possible limit points for subsequences of (λ_n) . It is easily seen that, whatever the value of $\alpha \in \mathbb{R}$, $A + \alpha$ is bounded neither below nor above. The spectrum is therefore also neither bounded below nor above. Thus $\{-\infty, +\infty\}$ are both limit points for the spectrum, implying decomposition (13). \square

3.3. Solution derivation. The results of the previous section are used here to derive the solution $\Phi(z) = (T(z), \mathbf{p}(z))$ to (8)–(10) such that T satisfies the boundary, limit, and interface conditions in (5)–(6) and (7). We point out that the boundary condition (5) implies that, for $z < 0$, one does not have $\Phi(z) \in D(A)$. For this to be taken into account, we shall consider the (maximal) extension \overline{A} to operator A as follows:

- $D(\overline{A}) = H^1(\Omega) \times H(\text{div}, \Omega)$,
- $\overline{A} : D(\overline{A}) \mapsto \mathcal{H}$ has the same algebraic expression as A in (10).

Unlike A , \overline{A} is not symmetric:

$$(14) \quad (\overline{A}\Psi_1, \Psi_2)_{\mathcal{H}} = (\Psi_1, \overline{A}\Psi_2)_{\mathcal{H}} + \int_{\partial\Omega} T_1\mathbf{p}_2 \cdot \mathbf{n} ds - \int_{\partial\Omega} T_2\mathbf{p}_1 \cdot \mathbf{n} ds$$

for all pairs of functions in $D(\overline{A})$, with the usual notation.

DEFINITION 1. We shall define a solution to (8)–(10) with conditions (5), (6), and (7) as a function $\Phi : z \in \mathbb{R} \mapsto \Phi(z) = (T(z), \mathbf{p}(z)) \in \mathcal{H}$ such that

- $\Phi \in \mathcal{C}(\mathbb{R}, \mathcal{H})$ (continuity on \mathbb{R}),
- $\Phi \in \mathcal{C}^1(\mathbb{R} - \{0\}, \mathcal{H})$ (continuous Fréchet differentiability on $\mathbb{R} - \{0\}$),
- for all $z \in \mathbb{R} - \{0\}$, $\Phi(z) \in D(\bar{A})$ and $\frac{d}{dz}\Phi(z) = \bar{A}\Phi(z)$,

and such that T satisfies the limit condition (6) as $z \rightarrow \pm\infty$ in \mathcal{H} 's norm and the boundary and interface conditions (5)–(7) for all $z \neq 0$ in the trace sense.

That formalism being stated, we have the following.

PROPOSITION 2. *There exists a unique solution Φ to (8)–(10) with conditions (5), (6), and (7). Defining the constants (α_n) ,*

$$(15) \quad \alpha_n := \frac{1}{\lambda_n^2} \int_{\partial\Omega} k\nabla T_n \cdot \mathbf{n} ds = \frac{1}{\lambda_n} \int_{\partial\Omega} \mathbf{p}_n \cdot \mathbf{n} ds,$$

this solution is given as follows:

$$(16) \quad \Phi(z) = \begin{cases} -\sum_n \alpha_n \Psi_n + \sum_n \alpha_n^- e^{\lambda_n^- z} \Psi_n^-, & z \leq 0, \\ -\sum_n \alpha_n^+ e^{\lambda_n^+ z} \Psi_n^+, & z \geq 0. \end{cases}$$

The expression can moreover be simplified, and the temperature field is given by

$$(17) \quad T(z) = \begin{cases} 1 + \sum_n \alpha_n^- e^{\lambda_n^- z} T_n^-, & z \leq 0, \\ -\sum_n \alpha_n^+ e^{\lambda_n^+ z} T_n^+, & z \geq 0. \end{cases}$$

Since A is not sectorial (is not the infinitesimal generator of an analytic semigroup; see, e.g., [10]), some precautions have to be taken in demonstrating the proposition. A detailed proof follows.

Proof. Using the Hilbert base (Ψ_n) of $(\text{Ker } A)^\perp$, the solution Φ is sought in the form $\Phi(z) = \sum_n (\Phi(z), \Psi_n)_{\mathcal{H}} \Psi_n$. All coefficients must therefore satisfy the ODE $\frac{d}{dz}(\Phi(z), \Psi_n)_{\mathcal{H}} = (A\Phi(z), \Psi_n)_{\mathcal{H}}$. Then using (14), the boundary condition (5) and the equality $k\nabla T_n = \lambda_n \mathbf{p}_n$, we find that

$$\frac{d}{dz}(\Phi, \Psi_n)(z) = (\Phi, A\Psi_n)(z) + \omega(z) \int_{\partial\Omega} \mathbf{p}_n \cdot \mathbf{n} ds = \lambda_n (\Phi, \Psi_n)(z) + \lambda_n \alpha_n \omega(z),$$

where $\omega(z) = 0$ when $z > 0$ and $\omega(z) = 1$ otherwise. Looking for a bounded and continuous solution to this ODE on \mathbb{R} gives us a unique solution, according to λ_n 's sign ($\lambda_n^+ < 0$ and $\lambda_n^- > 0$), that reads

$$(\Phi, \Psi_n^-)(z) = \begin{cases} \alpha_n^- (e^{\lambda_n^- z} - 1), & z < 0, \\ 0, & z > 0, \end{cases} \quad (\Phi, \Psi_n^+)(z) = \begin{cases} -\alpha_n^+, & z < 0, \\ -\alpha_n^+ e^{\lambda_n^+ z}, & z > 0. \end{cases}$$

This gives us decomposition (16) and the uniqueness of the solution. Let us now prove that Φ defined by (16) is a solution with the sense in Definition 1.

Consider the (unique) function $\varphi_\infty \in H_0^1(\Omega)$ such that $\text{div}(k\nabla\varphi_\infty) = \text{Pe } v$. We introduce

$$\Phi_\infty = \left| \begin{array}{l} 1 \\ k\nabla\varphi_\infty \end{array} \right. \in \mathcal{H},$$

a function that clearly satisfies $\Phi_\infty \in D(\bar{A})$, $\bar{A}\Phi_\infty = 0$, and $\Phi_\infty \in (\text{Ker } A)^\perp$. Let us prove that $\Phi_\infty = -\sum_n \alpha_n \Psi_n$ (thus explaining how to go from (16) to (17)). Since $\lambda_n \mathbf{p}_n = k \nabla T_n$,

$$(\Phi_\infty, \Psi_n)_\mathcal{H} = \int_\Omega T_n k dx + \frac{1}{\lambda_n} \int_\Omega k \nabla \varphi_\infty \cdot k \nabla T_n k^{-1} dx = \int_\Omega T_n k dx - \frac{1}{\lambda_n} \int_\Omega \text{Pe } v T_n dx,$$

and using the equality $\lambda_n k T_n = \text{Pe } v T_n - \frac{1}{\lambda_n} \text{div}(k \nabla T_n)$, we obtain

$$(\Phi_\infty, \Psi_n)_\mathcal{H} = -\frac{1}{\lambda_n^2} \int_\Omega k \nabla T_n \cdot \mathbf{n} ds = -\alpha_n.$$

Thus $-\sum_n \alpha_n \Psi_n = \Phi_\infty \in \mathcal{H}$, and it follows that $\Phi_\infty^\pm = -\sum_n \alpha_n^\pm \Psi_n \in \mathcal{H}$ and $\Phi_\infty = \Phi_\infty^- + \Phi_\infty^+$. We use the fact that $\Phi \in D(A)$ if and only if $\sum_n |\lambda_n (\Phi, \Psi_n)_\mathcal{H}|^2 < +\infty$.

Since $\lambda_n^+ \xrightarrow{n} -\infty$ (resp., $\lambda_n^- \xrightarrow{n} +\infty$), it is straightforward to check that the two functions,

$$f(z) = \sum_n \alpha_n^- \Psi_n^- e^{\lambda_n^- z}, \quad g(z) = \sum_n \alpha_n^+ \Psi_n^+ e^{\lambda_n^+ z},$$

satisfy the following:

- $f \in \mathcal{C}((-\infty, 0], \mathcal{H})$, $g \in \mathcal{C}([0, +\infty), \mathcal{H})$ (continuity);
- $f \in \mathcal{C}^1((-\infty, 0), \mathcal{H})$, $g \in \mathcal{C}^1((0, +\infty), \mathcal{H})$ (continuous Fréchet differentiability);
- for $z < 0$ (resp., $z > 0$), $f(z) \in D(A)$ (resp., $g(z) \in D(A)$), and $\frac{d}{dz} f(z) = Af(z)$ (resp., $\frac{d}{dz} g(z) = Ag(z)$).

The function Φ in (16) can be rewritten as $\Phi(z) = \Phi_\infty + f(z)$, $z \leq 0$, and $\Phi(z) = -g(z)$, $z \geq 0$ (whose functions actually match at $z = 0$ using $\Phi_\infty = \Phi_\infty^- + \Phi_\infty^+$). It is therefore continuous on \mathbb{R} , Fréchet differentiable on $\mathbb{R} - \{0\}$, $\Phi(z) \in D(\bar{A})$, and $\frac{d}{dz} \Phi(z) = \bar{A}\Phi(z)$ for $z \in \mathbb{R} - \{0\}$ since $\bar{A}\Phi_\infty = 0$. It is also clear that $T(z)$ satisfies the limit condition (6) and the boundary condition (5) for $z \neq 0$.

It remains to be proved that the function Φ in (16) also satisfies the interface conditions (7) for $z \neq 0$. For this, let us consider the previously introduced function f whose components will be denoted as $f(z) = (t(z), \mathbf{p}(z))$. Since $\lambda_n^- \xrightarrow{n} +\infty$, it is easy to check that, for $z < 0$, $Af(z) \in D(A)$. Therefore $k \nabla t(z) \in H(\text{div}, \Omega)$, which implies that $\text{div}(k \nabla t)(z) \in L^2(\Omega)$ for $z < 0$. Applying Lemma 1, it follows that $t(z)$ satisfies the interface conditions (7). The same result applies to $g(z)$ for $z > 0$ and, as a result, to $T(z)$ for $z \neq 0$. \square

4. Mixed variational formulation and approximation.

4.1. Mixed variational formulation. Let us consider the following variational problem: Find $(\lambda, T, \mathbf{p}) \in \mathbb{R} \times L^2(\Omega) \times H(\text{div}, \Omega)$ such that, for all $(u, \mathbf{q}) \in L^2(\Omega) \times H(\text{div}, \Omega)$,

$$(18) \quad \int_\Omega \text{Pe } v T u dx - \int_\Omega u \text{div}(\mathbf{p}) dx = \lambda \int_\Omega T u k dx,$$

$$(19) \quad - \int_\Omega T \text{div}(\mathbf{q}) dx = \lambda \int_\Omega \mathbf{p} \cdot \mathbf{q} k^{-1} dx.$$

It is clear that whenever Ψ_n is an eigenfunction as given in Theorem 1, then $(\lambda_n, T_n, \mathbf{p}_n)$ satisfies the variational problem above. Conversely if (λ, T, \mathbf{p}) satisfies (18)–(19) for

all $(u, \mathbf{q}) \in L^2(\Omega) \times H(\operatorname{div}, \Omega)$, then the second line implies that $T \in H_0^1(\Omega)$ (using the dense embedding of $H(\operatorname{div}, \Omega)$ into $H^{1/2}(\partial\Omega)'$; see [4]). Therefore $\Psi = (T, \mathbf{p}) \in D(A)$ and satisfies $A\Psi = \lambda\Psi$. Thus $\Psi = \Psi_n$ for some n , and solving (18)–(19) is equivalent to finding all the eigenvalues/eigenfunctions of operator A .

4.2. Axisymmetrical implementation. In order to test this variational formulation, we have derived a one-dimensional version of the problem which is interesting in the case of axisymmetrical configurations. The motivation is to test the convergence of the problem numerically on known solutions. The simplest case is convection-diffusion inside a single cylinder for which, in the limit of large Péclet numbers, we should recover the Graetz spectrum [9] for the operator A . In this subsection we consider the somewhat more general case of two concentric cylinders, for which $\Omega = \Omega_1 \cup \Omega_2$, with Ω_1 an inner disk filled with liquid and Ω_2 an outer solid corona. When the size of the second domain is set to zero, the single cylinder problem is found again as a particular case.

A liquid flows inside Ω_1 with a unidirectional, longitudinal, dimensionless velocity $v(r)\mathbf{e}_z$ which varies from a maximal value at the cylinder center $r = 0$ to zero at the boundary, with the second cylinder placed at $r = r_0$. We choose the dimensionless velocity to follow the usual Poiseuille flow profile $v(r) = 2\operatorname{Pe}(r_0^2 - r^2)$, although any continuous profile being zero at the boundary could be chosen. The velocity normalization is set so that normalized surface averaged velocity flux is the Péclet number

$$\frac{1}{\|\Omega_1\|} \int_{\Omega_1} v(r) d\Omega_1 = \operatorname{Pe},$$

where $\|\Omega_1\| = \pi r_0^2$ is the inner disk area associated with the first inner cylinder section. In corona Ω_2 the velocity is taken to be zero; no convection occurs in this second domain. Continuity of flux and temperature (7) are applied at the domain frontier $\partial\Omega_2 \cap \partial\Omega_1$ with uniform conductivity $k = 1$. The radial dimensionless distance is chosen so that $r = 1$ corresponds to the outer boundary of the second cylinder $\partial\Omega_2 - \partial\Omega_1 \cap \partial\Omega_2$, where a homogeneous Dirichlet boundary condition (5) is chosen.

Problem (18)–(19) is approximated on a regular one-dimensional mesh discretizing coordinate $r \in [0, 1]$ with index i on grid $r = i/n$ with $i \in \{1, n\}$. We adopt here the classical mixed finite-element approximation of order 0 of Raviart and Thomas, $P_0 \times RT_0$ (see, e.g., [4]), in the present axisymmetrical one-dimensional formulation. Base elements for the scalar T are therefore P_0 piecewise constant functions over the grid elements, whereas base elements for the *vector* \mathbf{p} are the P_1 continuous piecewise affine functions over the grid elements, thus re-establishing the flux continuity at the grid points.

The generalized linear eigenvalue problem resulting from this discretization choice is as follows:

$$(20) \quad A\Psi_n = \begin{pmatrix} \mathbf{a} & \mathbf{b} \\ \mathbf{b}^T & 0 \end{pmatrix} \Psi_n = \lambda_n \begin{pmatrix} \mathbf{c} & 0 \\ 0 & \mathbf{d} \end{pmatrix} \Psi_n,$$

where Ψ_n is a $2n$ component vector whose first n components are the discrete temperature field $T_n = (T_i)_{i \in \{1, n\}}$ approximating T_λ , and the following $n+1$ to $2n$ components describe p_n approximating the gradient field $\mathbf{p}_\lambda = \partial_r T_\lambda / \lambda$ which is one-dimensional in this axisymmetrical context. The $n \times n$ matrices \mathbf{a} , \mathbf{b} , \mathbf{c} , and \mathbf{d} can be computed

analytically and admit the following coefficients:

$$\begin{aligned}
 (21) \quad a_{ij} &= -\delta_{ij} \frac{\text{Pe}}{2r_0 n^4} (2i-1)(2i^2 - 2i - 2r_0^2 n^2 + 1), \\
 b_{ij} &= -\frac{1}{n} (\delta_{ij} i + \delta_{i-1j} (1-i)), \\
 c_{ij} &= \delta_{ij} \frac{2i-1}{2n^2}, \\
 d_{ij} &= -\frac{1}{12n^2} (\delta_{ij} 8i + \delta_{i-1j} (2i-1) + \delta_{i+1j} (2i+1)),
 \end{aligned}$$

where $(i, j) \in \{1, n\}^2$ and δ is the Kronecker symbol.

4.3. Numerical results and convergence. In the generalized eigenvalue problem (20), one notes that the matrix A is symmetric and that the right-hand side mass-matrix $\text{Diag}(\mathbf{c}, \mathbf{d})$ is symmetric positive definite. Therefore, problem (20) can be numerically solved using the variant of the Lanczos algorithm for generalized eigenvalue problems (see, e.g., [25]). The resulting first eigenvectors and eigenvalues were computed using the Fortran library ARPACK and sparse matrix storage. The results presented here correspond to the following two particular configurations:

- a single cylinder with a single radial domain Ω_1 for which $r_0 = 1$, and
- two concentric cylinders whose radius ratio is two, so that $r_0 = 1/2$.

We study the numerical convergence of the first eigenvalues and first eigenvectors when the Péclet number is varied from low to high values. We systematically compared the discrete numerical results with reference solutions obtained with another iterative method explained in the appendix.

4.3.1. Single cylinder: $r_0 = 1$. In the case of a single cylinder, for large values of the Péclet number, the upstream part of A 's spectrum (positive eigenvalues λ_n^- associated with the $z < 0$ region) is difficult to compute numerically because it diverges with Pe [21]. In contrast, the downstream part of the spectrum (negative eigenvalues λ_n^+ associated with the $z > 0$ region) converges to the Graetz spectrum and decays to zero as $1/\text{Pe}$ when the Péclet number increases.

Let us first discuss the eigenvalue convergence. Figure 2 illustrates the relative error $E = \sqrt{(\lambda_n - \lambda)^2} / \lambda$ associated with the first two downstream eigenvalues λ_1^+ and λ_2^+ and with the first upstream one λ_1^- . It can be seen in this figure that the convergence of the numerical estimation is consistent with the chosen classical mixed finite-element approximation space $P_0 \times RT_0$, for which a $\sim 1/n$ behavior is expected. Furthermore, the strong influence of the Péclet number on the convergence rate can also be observed. For small Péclet number, the spectrum is almost symmetrical, so that one expects the convergence for λ_1^+ and λ_1^- to be very close, as observed in Figure 2(a). In contrast, as the Péclet number increases, there is a distinct shift in the convergence curve. The closer the eigenvalue is to zero, the easier it is to compute. Since λ_1^- diverges with Pe, it is more difficult to approximate numerically and, then, the relative error associated with λ_1^- in Figure 2(b) is 30% larger than the one associated with λ_1^+ for Pe = 10. This difference further increases with the Péclet number. We also wish to illustrate the numerical convergence on the eigenfunction. Figure 3 illustrates the eigenvector computation for the temperature and gradient fields associated with λ_1^+ , λ_2^+ , and λ_1^- eigenvalues. In the case of small Péclet number, the asymptotic symmetry of the eigenvalue spectrum also implies a symmetry of the eigenvectors, which is clearly visible when comparing the 1+ and 1- fields in Figure 3. The associated leading order eigenfunction shows a single maximum at

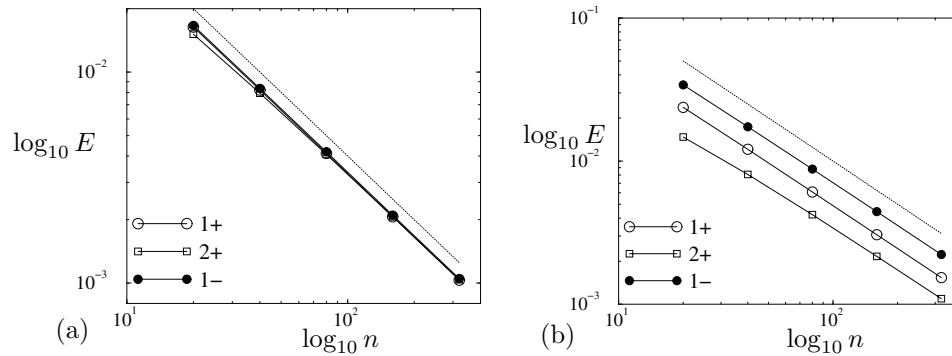


FIG. 2. (a) Relative numerical error for eigenvalues λ_1^+ , λ_2^+ , and λ_1^- for $Pe = 0.1$. The dotted lines corresponds to a -1 slope associated with a $\sim 1/n$ behavior. (b) Same convention as (a) for $Pe = 10$.

$r = 0$, the cylinder center, and obviously decreases to zero at $r = 1$ for the Dirichlet boundary condition to be fulfilled. When the associated eigenvalue order increases, the corresponding eigenfunction has as many oscillations as the eigenvalue order. For example, for λ_2^+ , two critical points can be seen, a minimum and a maximum, for the eigenfunction in Figure 3. The superposition between the discrete numerical computation and the “exact” solution is also illustrated in Figure 3. One can see that the comparison for the gradient depicted in Figure 3(b) is rough for $n = 20$, but no difference is visible between the two for $n = 320$ in Figure 3(d). The convergence to the exact solution is also illustrated in Figure 4 for $Pe = 10$. In this case the two eigenfunctions associated with λ_1^+ and λ_1^- differ markedly. The first one, associated with λ_1^+ , still reaches a maximum at the tube center $r = 0$, whereas the maximum position of the second one, associated with λ_1^- , is shifted close to the tube boundary at $r = 1$. Furthermore, this second eigenfunction decays to zero at the tube center. The reason for this distinct behavior is now the opposite role of convection for these two temperature profiles. For the downstream eigenfunction associated with λ_1^+ , longitudinal convection prevails over diffusion. Since this convection is maximum at the tube center, it dictates the shape of the corresponding temperature profile. For the upstream eigenfunction associated with λ_1^- , retrodiffusion is the only mechanism for this temperature to display a back-flow exponential decay. Hence, since the convection is maximal at the tube center, retrodiffusion is maximum at the tube boundary, where the velocity vanishes. A boundary layer develops near $r = 1$, the thickness of which decays to zero as the Péclet number diverges. This boundary layer is responsible for the numerical difficulties arising in the computation of the upstream part of the spectrum at large Péclet number. The slower convergence of the eigenvectors 1- is clearly visible in Figures 4(a) and (b) for a rough discretization of $n = 20$ points. Although in this case, the first two downstream eigenfunctions, 1+ and 2+, are well approximated by the corresponding eigenvectors, this is not the case for the upstream 1-. Nevertheless, for a sufficient discretization of $n = 320$ points, the convergence can be satisfactory as illustrated in Figures 4(c) and (d).

We finally wish to illustrate the convergence on the eigenvector by computing

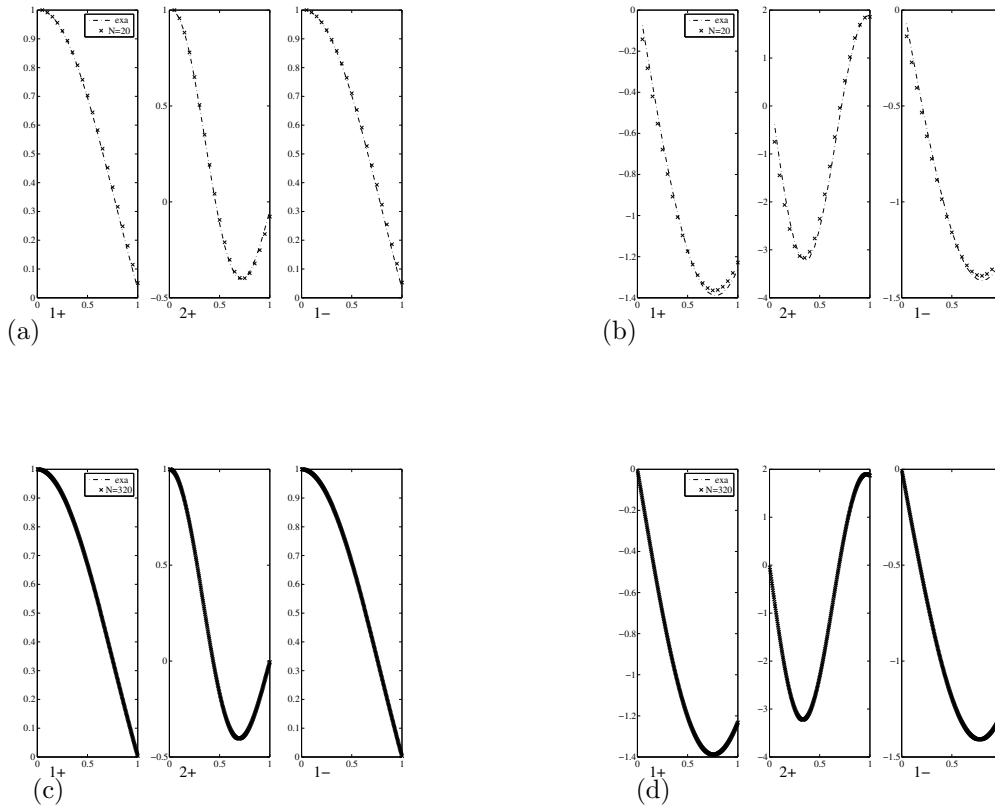
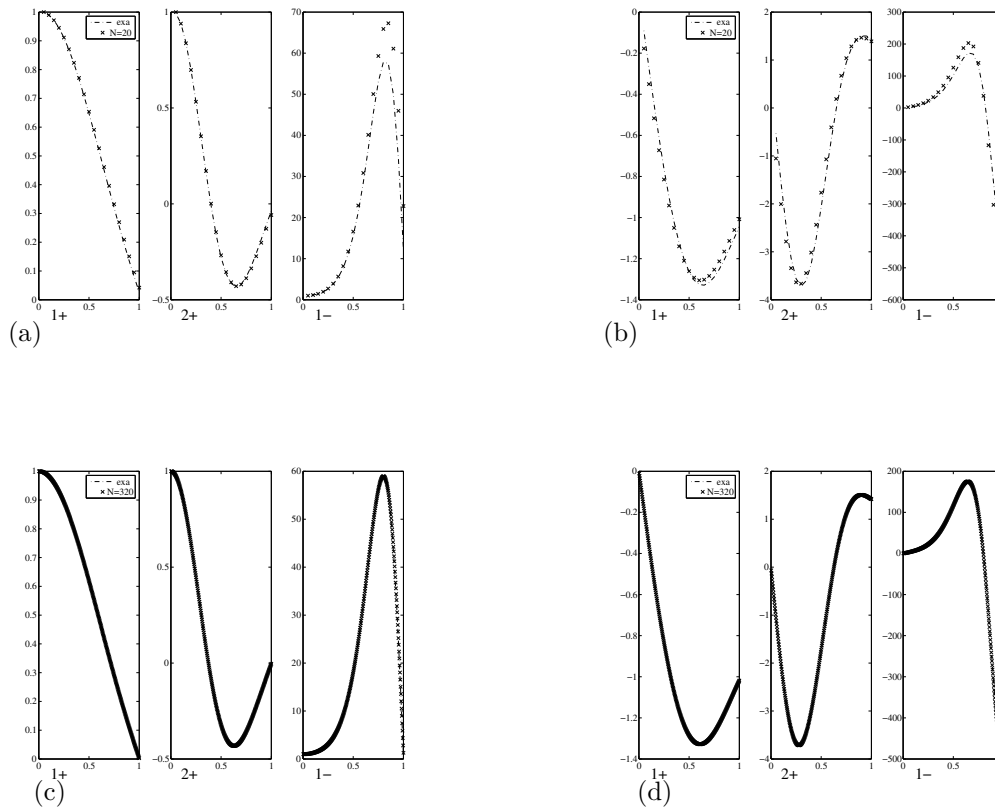


FIG. 3. (a) Temperature field $T(i/n)$ $i \in \{1, n\}$ for discretization $n = 20$ and $Pe = 0.1$ with the first two downstream eigenvectors 1+ and 2+ and the first upstream eigenvector 1-. Normalization $T(0) = 1$ has been imposed. (b) Temperature gradient $p = \partial_r T(i/n)/\lambda$ for discretization $n = 20$ and $Pe = 0.1$. (c) Same convention as (a) for discretization $n = 320$. (d) Same convention as (b) for discretization $n = 320$.

the relative error $E = \sqrt{(\Psi_n - \Psi, \Psi_n - \Psi)_{\mathcal{H}} / (\Psi, \Psi)_{\mathcal{H}}}$ built with the \mathcal{H} norm (11) for a discrete eigenvector Ψ_n to converge to the theoretical one Ψ . Figure 5 shows the convergence of the relative error for increasing point number n . As expected, $1/n$ behavior is observed for both $Pe = 0.1$ and $Pe = 10$, but the error is larger in the latter case.

4.3.2. Two concentric cylinders: $r_0 = 1/2$. In the case where two domains are present, it is interesting to test the numerical implementation of the flux and temperature continuity (7) between the two domains in this formulation. Figure 6 shows some eigenfunction profiles at the same Péclet number as those previously illustrated for the single cylinder case, $Pe = 0.1$ and $Pe = 10$. It can be observed in this figure that the temperature continuity at the domain border $r = r_0 = 1/2$ is excellent even for a modest discretization $n = 20$. The same observation can be made on the gradient field. The convergence to the exact solution which can be visually checked in Figure 6(c) is better than the one previously obtained with the same parameter in Figure 4(a). This is due to the fact that there is no boundary layer

FIG. 4. Same conventions as Figure 3 for $Pe = 10$.

in the latter case when two domains are present. The retrodiffusion of the upstream eigenvector $1-$ is possible in the second annular domain Ω_2 , so that it is not confined in a small region near the boundary. The resulting temperature gradients are much lower and do not diverge with the Péclet number. Hence, the maximum temperature observed for the $1-$ eigenvector of Figures 6(c) and (d) is indeed localized inside the second domain at a radial coordinate larger than $1/2$. Obviously, the temperature values associated with this maximum are much lower than in the case of the single cylinder, due to the smoothing effect associated with permitting retrodiffusion in the second domain Ω_2 .

The convergence rate, which can be computed either for the eigenvalues or the eigenvectors, follows the same scaling as already found for the single cylinder case. The convergence rate is only a little better (not shown).

5. Conclusion. This paper has presented a new approach for complex three-dimensional configurations of convection-diffusion in unidirectional flows. We justify a separation of variable solution approach by defining the eigenvalue/eigenfunction decomposition of an appropriate mixed operator. The theoretical analysis shows that the properties of this operator allow a nonsectorial decomposition of the solution in longitudinally exponentially decaying solutions. This approach permits a full three-dimensional problem to be numerically restricted to two dimensions. Furthermore, a

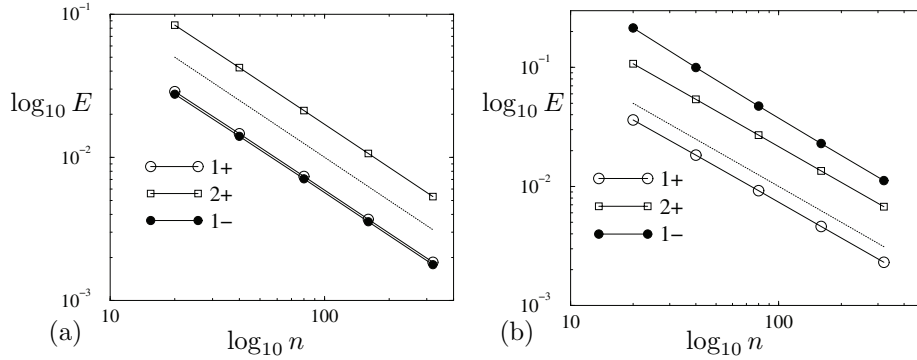


FIG. 5. (a) Relative error for eigenvectors associated with eigenvalues λ_1^+ , λ_2^+ , and λ_1^- for $Pe = 0.1$. The dotted lines corresponds to a -1 slope associated with a $\sim 1/n$ behavior. (b) Same convention as (a) for $Pe = 10$.

naturally efficient numerical discretization has been proposed using finite elements. The relevance and efficiency of such a discretization has been analyzed in simple configurations.

Appendix. Reference solutions in axisymmetrical problems. In this appendix, we give some details about the analytical method used in section 4 for the analysis of the numerical results. The method is based on a property of the eigenfunctions called λ -analycity: in the axisymmetrical framework, any eigenfunction T_λ can be expanded in the form

$$(22) \quad T_\lambda(r) = \sum_{n \in \mathbb{N}} t_n(r) \lambda^n .$$

In this description the closure functions $\{t_n\}_{n \in \mathbb{N}}$ are independent of the eigenvalue λ considered and also of the considered boundary condition at $r = 1$. They can be computed using a simple iterative process for the computation of the spectrum and eigenfunctions with a *Maple* code.

The convergence of the λ -analycity method has been established for general axisymmetrical configurations. The proof being the topic of a forthcoming paper, and for the sake of simplicity, we focus our attention here on the treatment of the Graetz problem. In this case, the proof for the convergence of the λ -analycity method is available in [22]. The eigenvalues T_λ are defined as follows, on the interval $[0, 1]$:

$$T_\lambda(0) = 1, \quad \Delta_c T_\lambda = v(r)\lambda T,$$

where Δ_c stands for the cylindrical part of the Laplace operator $\Delta_c \equiv 1/r \partial_r (r \partial_r)$. Eigenfunctions T_λ then read as in (22), where the $t_n(r)$ fulfill the recursive scheme

$$t_0(r) = 1 \quad \text{and} \quad \Delta_c t_n = v(r)t_{n-1}(r), \quad t_n(0) = 0 \quad \text{for} \quad n \geq 1.$$

We point out that this scheme actually has a unique solution thanks to the degeneracy of the ODE at $r = 0$.

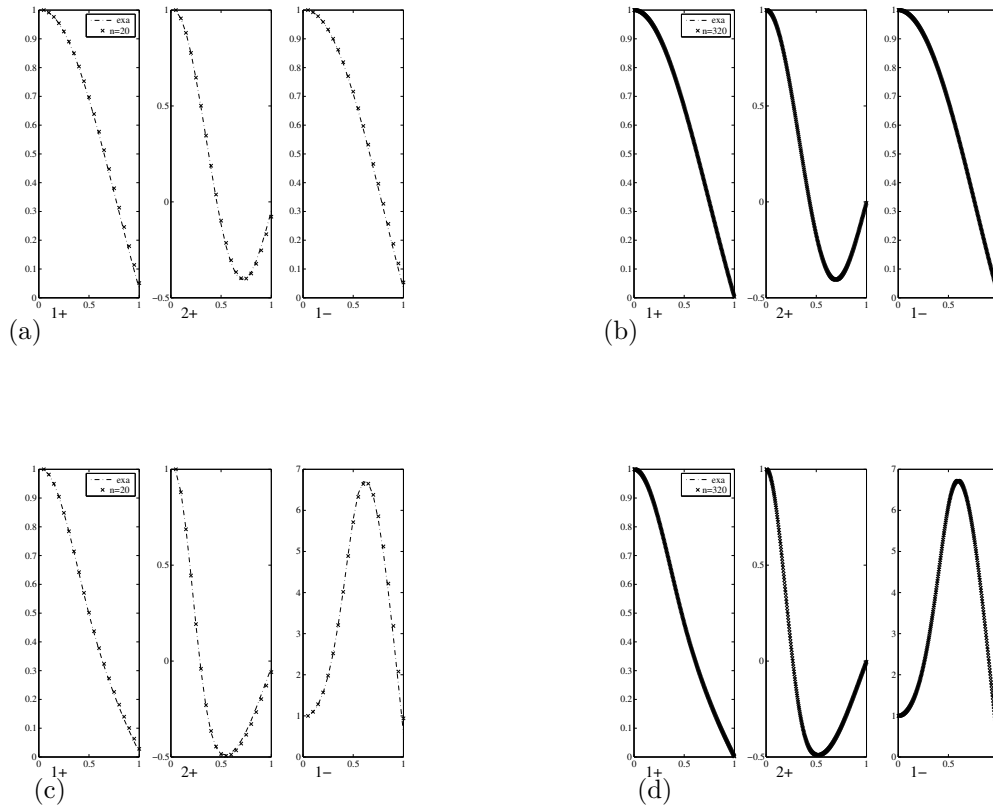


FIG. 6. (a) Temperature field $T(i/n) i \in \{1, n\}$ for discretization $n = 20$ and $Pe = 0.1$ for the first two positive eigenvectors $1+$ and $2+$ and the first negative eigenvector $1-$. Normalization $T(0) = 1$ has been imposed. (b) Same convection as (a) for discretization $n = 320$. (c) Same convention as (a) $Pe = 10$. (d) Same convention as (b) for discretization $n = 320$.

The spectrum, in the case of a Dirichlet boundary condition, is thus defined as

$$\Lambda = \left\{ \lambda, \sum_{n \in \mathbb{N}} t_n(1) \lambda^n = 0 \right\}.$$

It can be approximated using truncations, with an exponential rate of convergence.

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