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# Generating high-integrity systems with AADL and Ocarina

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## Outline

- **AADL crash course**
- The Ocarina project
- AADL to Ada: experiments in IST-ASSERT
- AADL to C: experiments in ANR Flex-eWare
- Some other features



## AADL components

- **AADL model** : hierarchy/tree of components
- **AADL component:**
  - **Component definition** : model of a software or hardware element, notion of type/interface, one or several implementations organized in package. A component implementation may have subcomponents.
  - **Component interactions** : features (part of the interface) + connections (access to data, to subprograms, ports, ...)
  - **Component properties**: valued attributes to model non-functional property (priority, WCET, memory consumption, ...)



## Component type/implementation

- AADLv2 distinguishes type and implementation

<category> foo

### features

- *list of features*
- *interface*

### properties

- *list of properties*
- *e.g. priority*

end foo;

<category> foo.i [**extends** <bar>]

### subcomponents

- ...

### calls

- *subprogram subcomponents*
- *called*

### connections

### properties

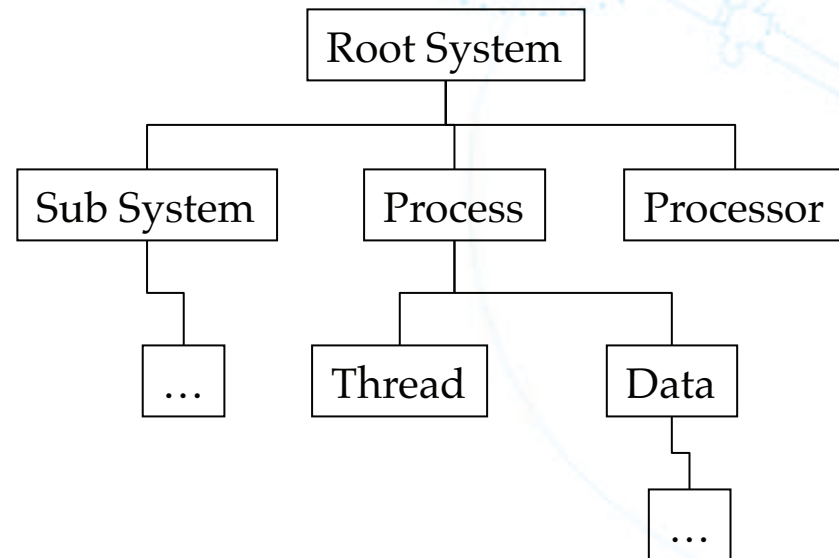
- *list of properties*
- *e.g. priority*

end foo.i;



## A full AADL system

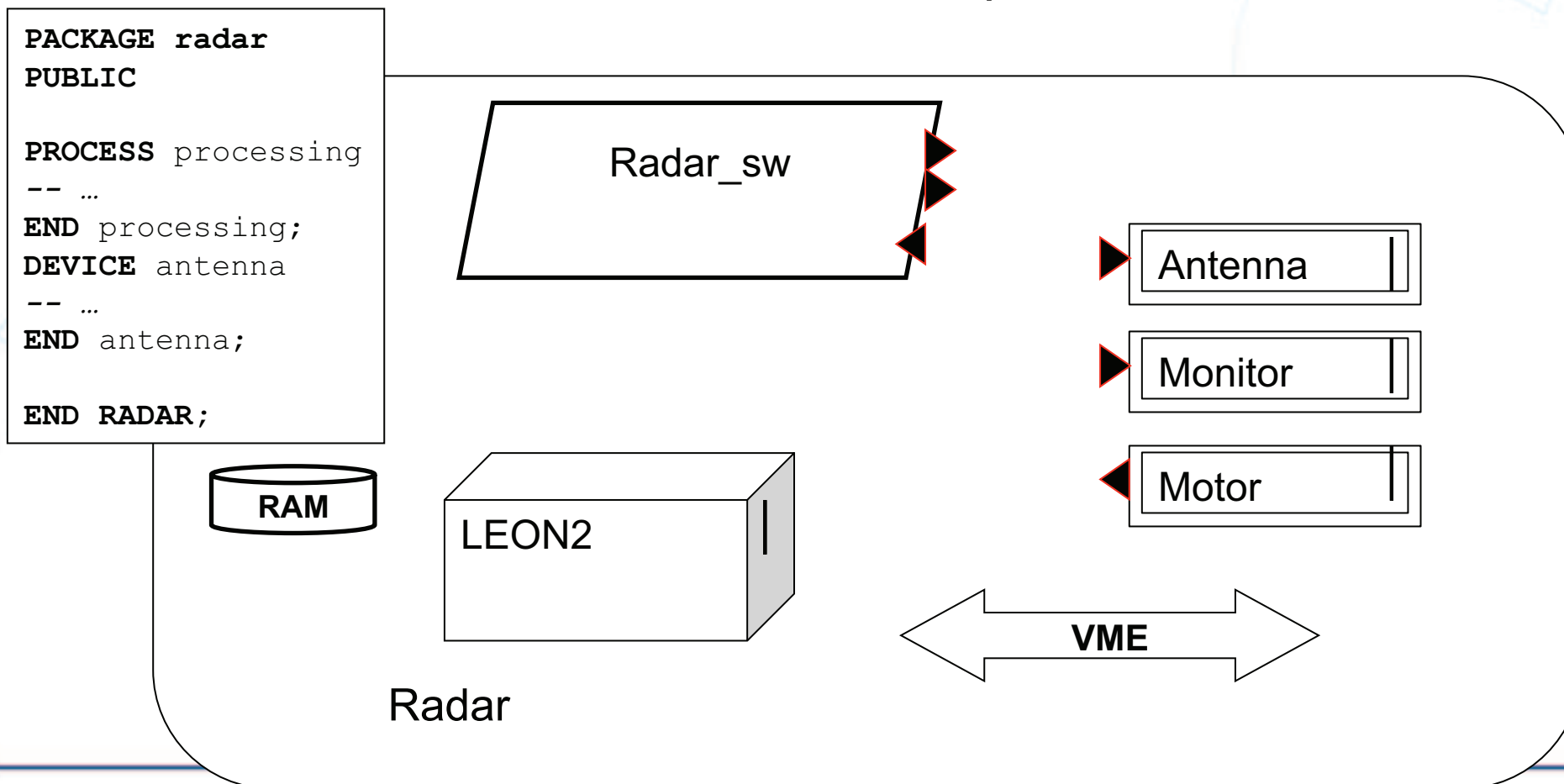
- Component types and implementations only define a library of entities
- System must be instantiated through a hierarchy of subcomponents, from top-most (system) to top-down (subprograms, ..)
- Level N use entities at level N-1 as subcomponents, connect them





# Radar case study

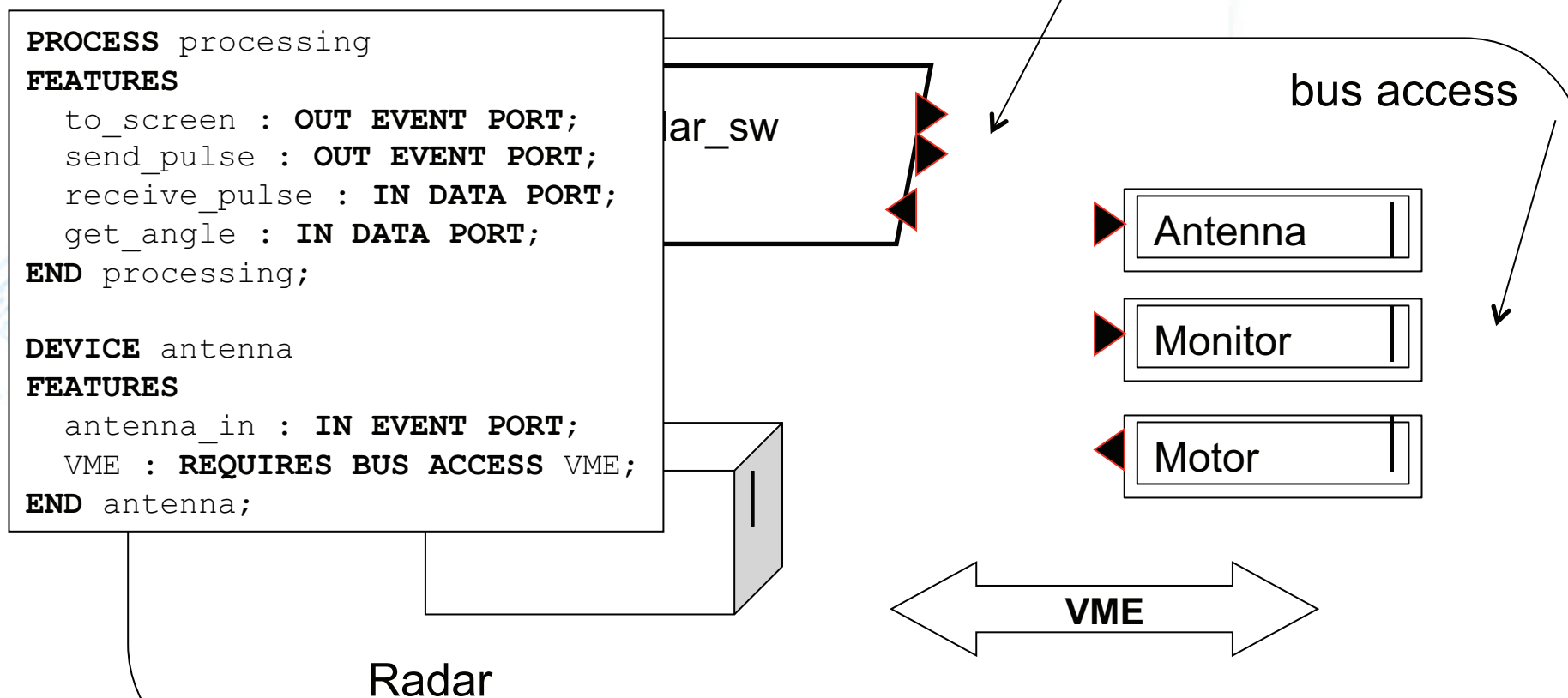
- Hardware/Software breakdown: components





# Radar case study

- Hardware/Software breakdown: features

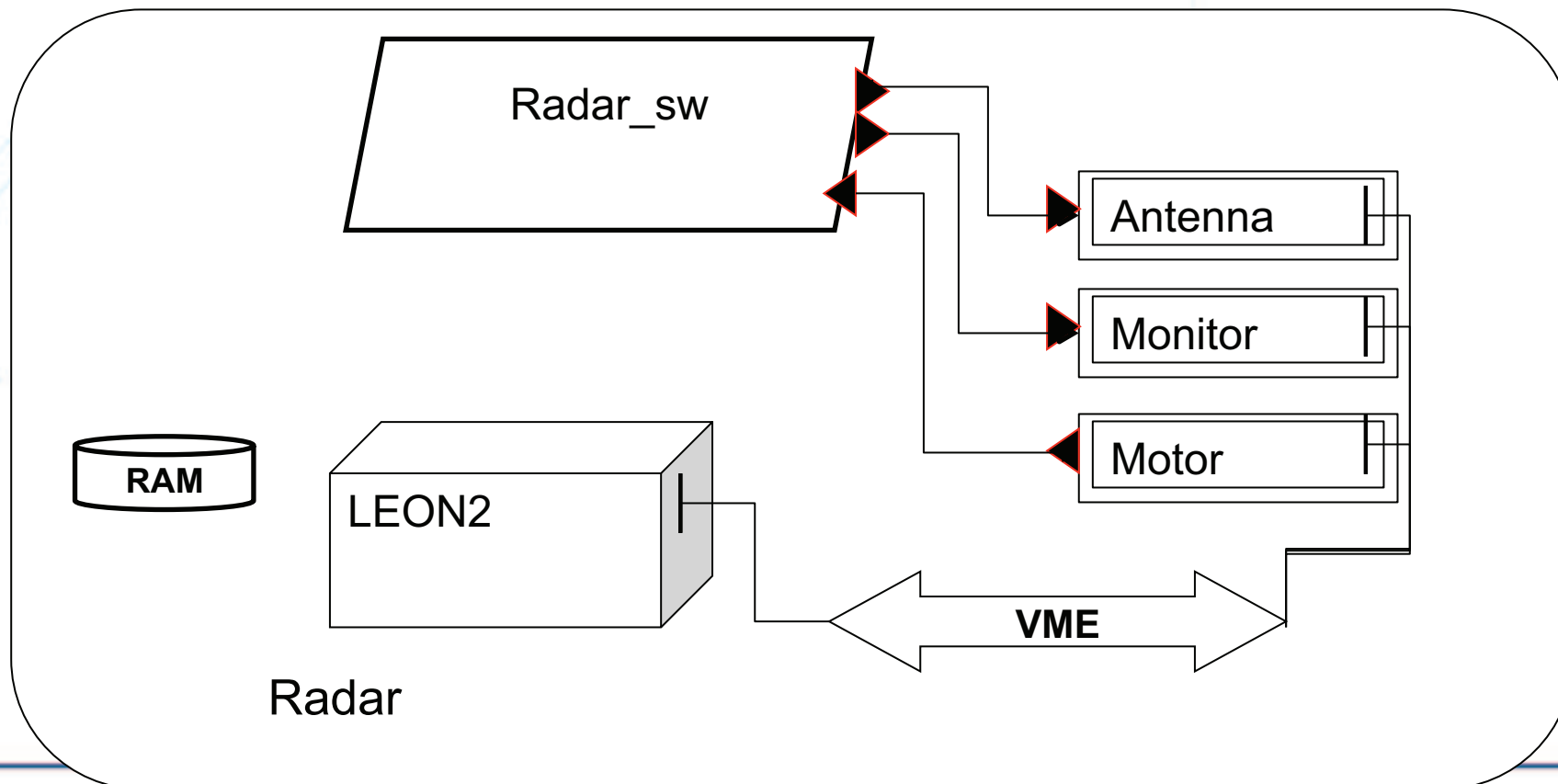






## Radar case study

- Hardware/Software breakdown: connections





## Radar case study

- Hardware/Software breakdown: connections

```
SYSTEM IMPLEMENTATION radar.simple
SUBCOMPONENTS
  aerial : DEVICE antenna;
  rotor  : DEVICE motor;
  monitor : DEVICE screen;
  main   : PROCESS processing.others;
  cpu    : PROCESSOR leon2;
  VME    : BUS VME;
  RAM    : MEMORY RAM;
CONNECTIONS
  Cnx : PORT aerial.antenna_out -> main.receive_pulse;
  PORT rotor.motor_out -> main.get_angle;
  PORT main.send_pulse -> aerial.antenna_in;
  PORT main.to_screen -> monitor.screen_in;
  BUS ACCESS VME -> aerial.VME;
  BUS ACCESS VME -> rotor.VME;
  BUS ACCESS VME -> monitor.VME;
  BUS ACCESS VME -> cpu.VME;
  BUS ACCESS VME -> RAM.VME;
```



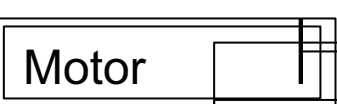
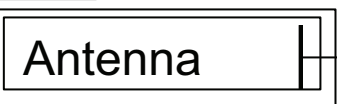
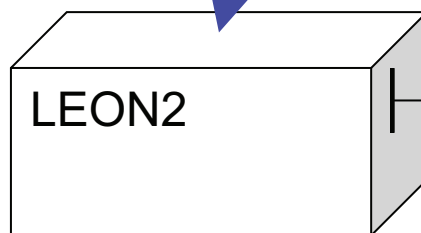
# Radar case study

- Hardware/Software breakdown: bindings

## PROPERTIES

```
Actual_Memory_Binding => reference (ram) applies to main;  
Actual_Processor_Binding => reference (cpu) applies to main;  
Actual_Connection_Binding => reference (VME) applies to cnx;  
END radar.simple;
```

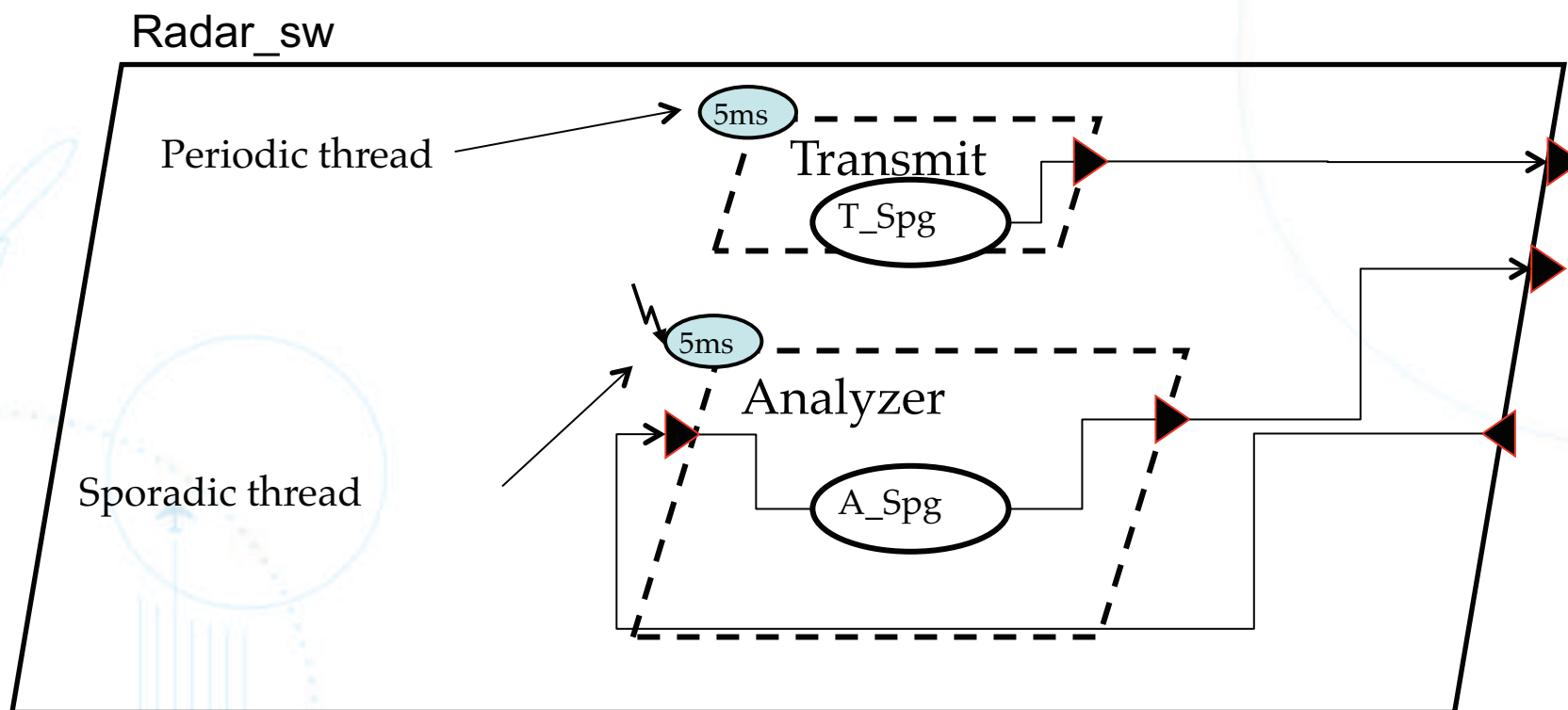
bindings



Radar

# Radar case study

- Software elements





## Modeling with AADL, what else ?

- AADL is an interesting framework to model and validate complex systems: clear syntax, semantics, low overhead
  - “only” 300 pages for the core document
  - Increasing number of supporting tools for validation
  - MARTE standard to provide guidelines to model AADL patterns
- Scheduling analysis, resource dimensioning, behavior analysis, mapping for formal methods, fault analysis, ...
  - Cheddar, Colored/Timed/Stochastic Petri Nets (CPN AMI, GreatSPN, TINA), FIACRE, BIP, Signal, Lustre, Alloy, TLA, UPPALL, Timed Automata, LOTOS
- AADL requirement document (ARD 5296)
  - Validate and **Generate** complex systems



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## Ocarina: an AADL code generator

<http://aadl.telecom-paristech.fr>

- Ocarina is a stand-alone tool for processing AADL models
  - Command-line tool, a-la gcc
  - Can be integrated with third-party tools
    - ✓ OSATE (SEI), TASTE (ESA), Cheddar (UBO), MyCCM-HI (Thales)
    - ✓ Also emacs and vim modes
  - Joint work: Telecom ParisTech (leader), contributors ENIS, ISAE
- Fully supports both AADLv1 and AADLv2
- **Code generation** facilities target AADL runtimes
  - Ada HI integrity profiles, with Ada native and bare board runtimes
  - C POSIX or RTEMS, for RTOS & Embedded
  - C/ARINC653 and partitioned kernel POK
  - User code can be Ada, C, C++, Esterel, Simulink , Lustre, SCADE



## Ocarina, other relevant features

- Model to model transformations
- WCET analysis of AADL runtime + user code: Bound-T
  - Take advantage on code generation patterns to “teach” how to measure WCET
- Constraint language to validate AADL model
  - Check static aspects of a system (see next presentation)
- Model checking models using Colored or Timed Petri Nets
  - Test for specific behavior scenarios
- Automatic evaluation of code coverage running scenarios
  - Based on the Couverture project
  - <http://libre.adacore.com/libre/tools/coverage/>





## Ocarina distributions

- <http://aadl.telecom-paristech.fr/>
- Ocarina 2.0 wavefront, daily snapshots
  - Binaries of Ocarina (release 1.2 and nightly builds)
    - ✓ For GNU/Linux, Windows, Solaris, Mac OS X, FreeBSD
  - Documentation and examples (30+ available)
  - Scientific papers on the use of AADL
  - Teaching materials for Master degree
- PolyORB-HI AADL runtimes
  - Two versions: Ada 2005 and C/RT-POSIX
- POK AADL runtime
  - For MILS and IMA-like systems, using time and space partitioning



## AADL and code generation

- AADL has a full execution semantics
  - Allow for full analysis
    - ✓ Scheduling, security, error, behavior
- **Issue:** what about the implementation ?
  - How to go to code
  - Preserve both the semantics and non functional properties ?
- **Solution:** enrich AADL with annexes documents
  - To describe application data
  - To detail how to bind code to AADL models



## AADL: modeling data types

- **Issue:** how to model data types: an integer, a struct?
- **Solution:** Data Modeling annex document
  - Property set and design patterns for modeling data type
  - Closer to source code

```
subprogram Receiver_Spg
```

```
features
```

```
    receiver_out : out parameter Target_Distance;
```

```
    receiver_in  : in parameter Target_Distance;
```

```
end Receiver_Spg;
```

```
data Target_Distance
```

```
properties
```

```
    Data_Model::Data_Representation => integer;
```

```
end Target_Distance;
```



## AADL and subprograms

- **Issue:** how to bind user code ?
- **Solution:** default AADLv2 properties / AADL runtime

```
subprogram Receiver_Spg
```

```
features
```

```
receiver_out : out parameter Target_Distance;
```

```
receiver_in : in parameter Target_Distance;
```

```
properties
```

```
Source_Language => Ada95; -- defined in AADL_Project
```

```
Source_Name => "radar.receiver";
```

```
end Receiver_Spg;
```



## AADL runtime

- **Issue:** how to interact with message queues ?
- **Solution:** use the AADL runtime (A.9) that define 10 services to interact with queues, ...

```
subprogram Send_Output
```

```
features
```

```
    OutputPorts: in parameter <implementation-dependent>;
```

```
    -- List of ports whose output is transferred
```

```
    SendException: out event data;
```

```
    -- exception if send fails to complete
```

```
end Send_Output;
```

- Unfortunately, it remains implementation-defined
  - Mostly to allow for different designs, and enhance performances



## AADL and programming languages

- **Issue:** how to map source code ?
- **Solution:** guidelines provided in the programming language annex document
  - Define mapping rules between AADL and the target language

```
subprogram Receiver_Spg
```

```
features
```

```
  receiver_out : out parameter Target_Distance;
```

```
  receiver_in  : in parameter Target_Distance;
```

```
end Receiver_Spg;
```

```
procedure Receiver
```

```
  (Receiver_Out : out Target_Distance;
```

```
   Receiver_In  : Target_Distance);
```

```
void receiver
```

```
  (target_distance *receiver_out,
```

```
   target_distance Receiver_in);
```

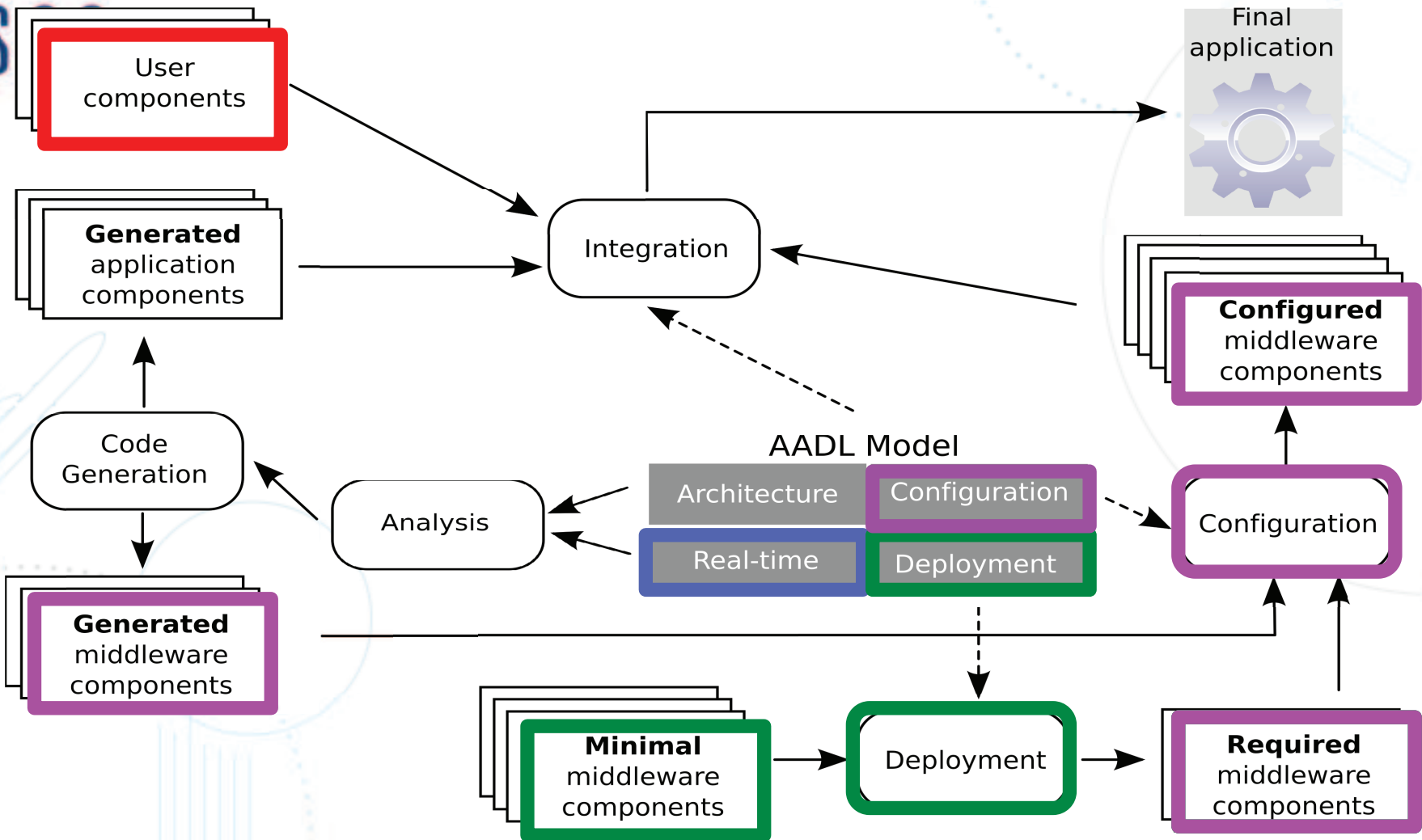




## AADL and code generation

- **Issue:** How much code should we write ? Tasks ?  
Queues ?
- **Answer:** the architecture says all
  - One can define a full framework and use it
    - ✓ Limited value, a-la CORBA
  - Generate as much as possible
- **Ocarina:** massive code generation
  - Take advantage of global knowledge to optimize code, and generate only what is required
  - Rely on a restricted runtime to support basic constructs

# Building process for HI-DRE systems







## Ocarina and code generated

- Strong emphasis on code quality
  - Generate code compatible with coding standards for HI systems
- Ada code: “easy”, checked by the compiler
  - Ravenscar profile for deterministic concurrency
  - HI restrictions: no dynamicity (OO, memory, ...)
  - Also, simplifies the runtime, approx. 2200 SLOC
- C code: more tricky
  - Stringent coding guidelines for now
  - Consistent with ECSS-E-40A (ESA) and Thales practice
  - Even with POSIX: 2400 SLOC



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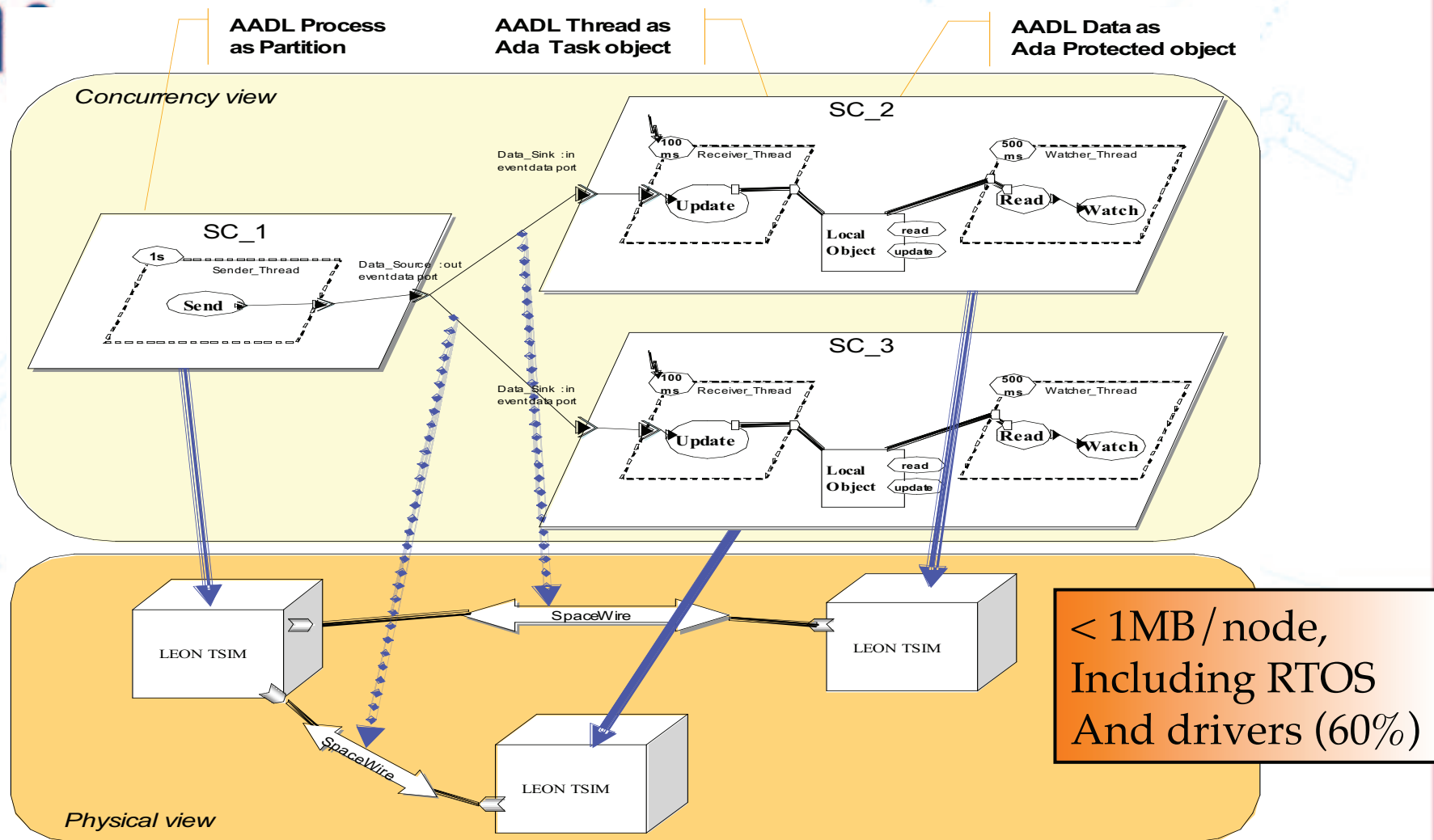


## Ocarina's AADL runtime #1: Ada

- PolyORB-HI/Ada
  - Target Ada Ravenscar and High-Integrity runtimes
  - Supports AADL semantics, v1 and v2
  - Based on the Ravenscar & HI Ada profiles
    - ✓ Meets stringent requirements for High-Integrity systems, e.g. ESA
    - ✓ Checked at compile-time by Ada compiler, GNAT
    - ✓ On-going work to support SPARK/Ada
  - Supports native, RTEMS, and LEON2, ERC32 bare-board targets
- Validated in the context of the IST-ASSERT and TASTE projects with ESA
  - Increasing user base



# The ASSERT MPC V2 demonstrator (2007)

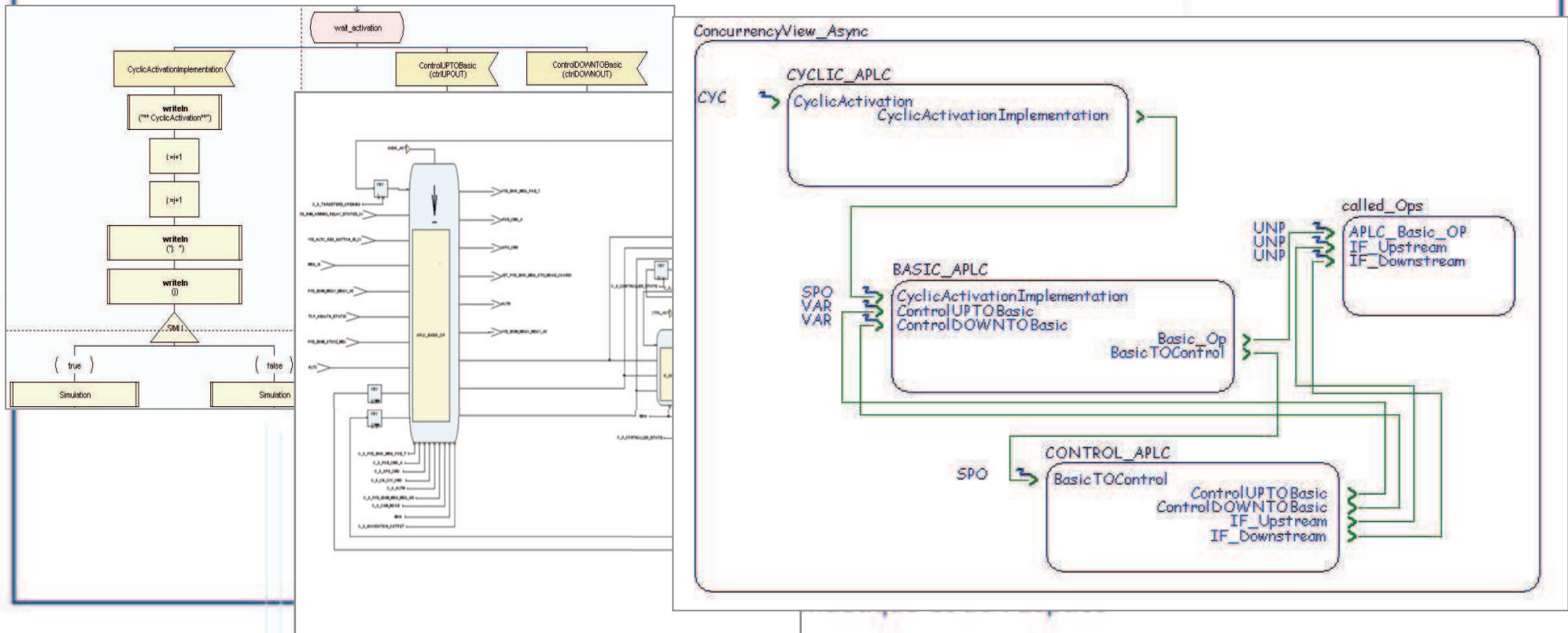




# The ASSERT ESA demonstrator (2008)

<http://www.assert-project.net/>

- Seamless integration of SDL, SCADE, Simulink, C, Ada, ASN.1, AADL
- Follow-up activities in TASTE: add VHDL, formal verifications



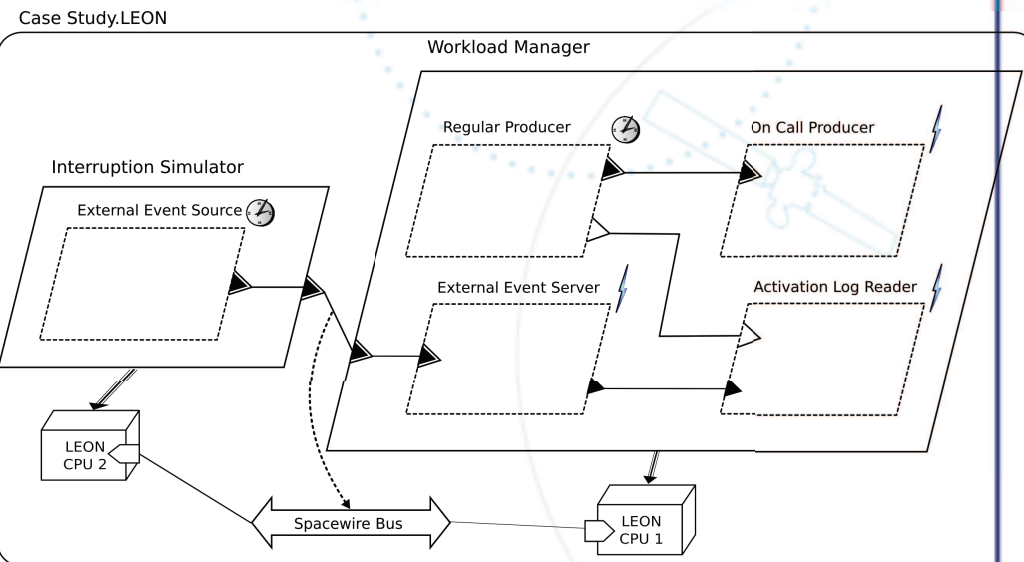
## AADL vs. manual coding (2008)

- Example from the “Guide for the use of the Ada Ravenscar Profile in high integrity systems »

- Typical example of RT system patterns
- AADL generated code vs. Ada hand-coded

- Same functional model

- Both are analyzable with RMA and RTA
- Shares same code quality enforced by Ada compiler



### ■ For LEON2 targets

- Penalty of 6% in memory size, equivalent WCET

### ■ Big improvement in analysis



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## Ocarina's AADL runtime #2: C/RT-POSIX

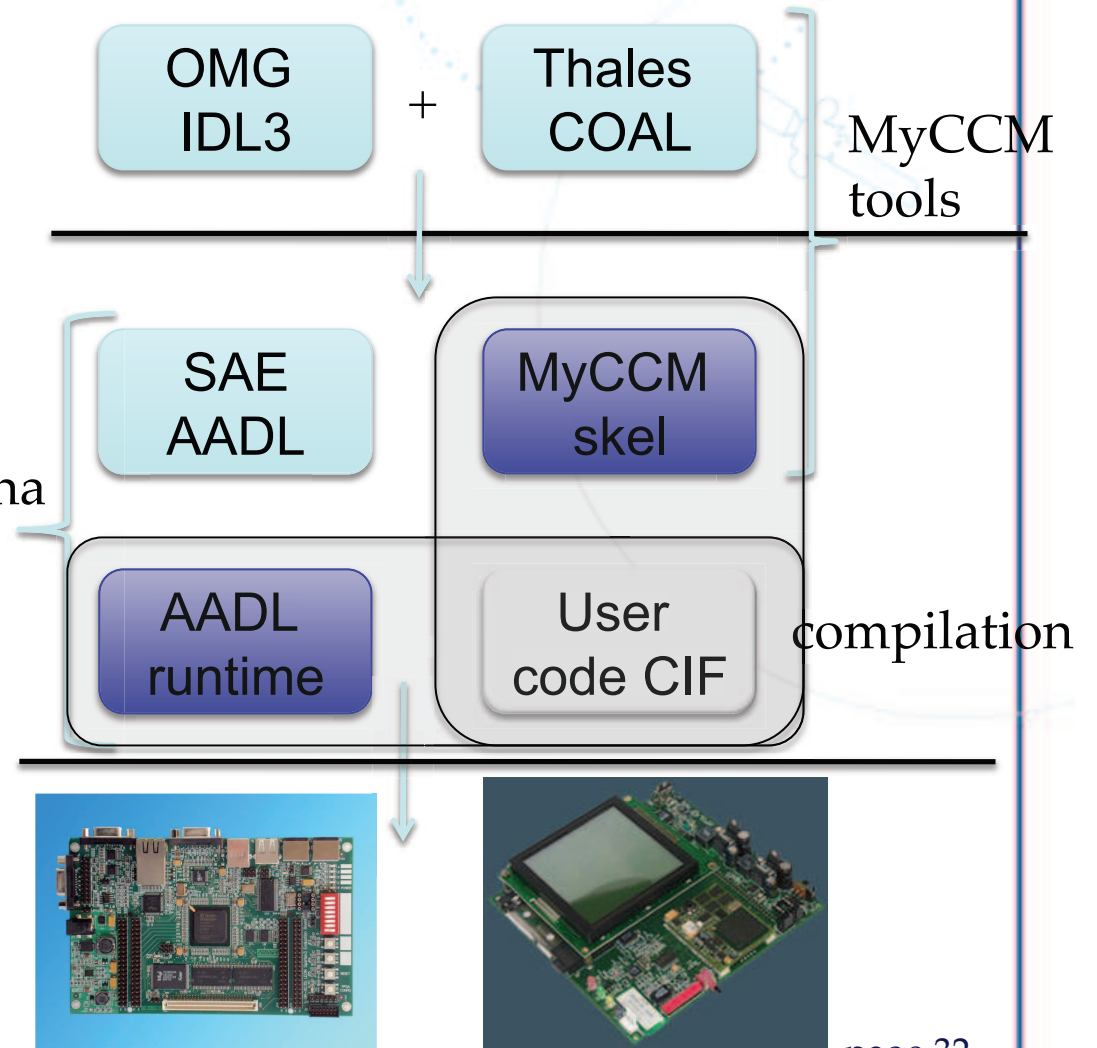
- PolyORB-HI/C
  - Targets C/RT-POSIX and C/RTEMS
    - ✓ Set of macros to support other RTOS
  - Tested on multiple operating systems
    - ✓ Native, GNU/Linux
    - ✓ Restricted libc: GNU/Linux on Nintendo DS and Nokia 770
    - ✓ POSIX RTOS: RTEMS
  - Tests demonstrated a limited subsystem of RT-POSIX & libc is enough to support AADL
  - Performance comparable to the Ada version
- Used in the ANR Flex-eWare project by Thales





# Flex-eWare project (2009) Merging CCM and AADL

- Using ASSERT philosophy: combining notations
- LwCCM is interesting for system designers
  - Comfortable with the OMG
- Map onto AADL for consolidation
- Generate code using Ocarina
- Uses AADLv2





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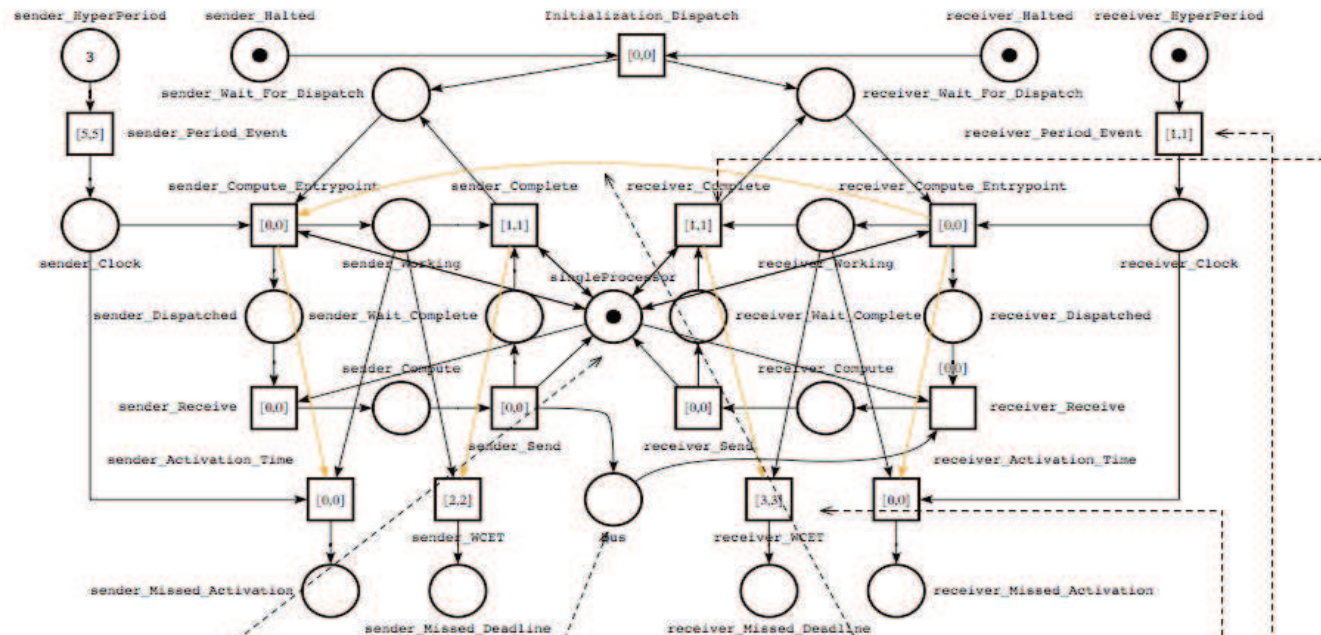


## Ocarina's AADL runtime #3: IMA-like

- POK (<http://pok.gunnm.org>)
  - A bare board AADL runtime: both an AADL runtime and a kernel
  - Finely tuned using AADL properties
  - Follow ARINC philosophy for time and space partitioning
- Separate services as more as possible
  - Restrict functionalities of each service
  - Fine-grain configuration
  - Ex: include static scheduler, not RMS
- Configures resources of each layer
- Main goal : use ONLY needed functionalities
  - Help the certification process (cf. DO178B)
  - Low memory footprint

# Petri nets and AADL

- Colored PN
  - CPN-AMI
- Time PN
  - TINA
- Adapt patterns to the property to be checked (observers, or reduced patterns)



```

system CaseStudy
end CaseStudy;

system implementation CaseStudy.impl
subcomponents
  SingleProcessor processor DefaultProcessor.impl;
  singleProcess ; process DefaultProcess.impl ;
properties
  Actual_Processor_Binding =>
    reference singleProcessor
    applies to singleProcess.send
  Actual_Processor_Binding =>
    reference singleProcessor
    applies to singleProcess.receiver;
end CaseStudy.impl

-- Description of a processor to execute the threads
end DefaultProcessor ;

processor DefaultProcessor
end DefaultProcessor ;

processor implementation DefaultProcessor.impl
properties
  Scheduling_Protocol => { RMS };
  Preemptive_Scheduler => False;
end DefaultProcessor.impl;

-- A process containing two threads
process DefaultProcess
end DefaultProcess ;

process implementation DefaultProcess.impl
subcomponents
  SenderThread.impl ;
  ReceiverThread.impl ;
  sender.outPort
  -> receiver.inPort ;
impl ;

thread implementation SenderThread.impl
properties
  Period => 5ms;
  Compute_Execution_Time => 1ms .. 1ms;
  Compute_Deadline => 2ms;
  Dispatch_Protocol => { Periodic };
  Priority => 2;
end SenderThread.impl ;

thread ReceiverThread
features
  inPort : in event port (Queue_Size => 1);
end ReceiverThread ;

```

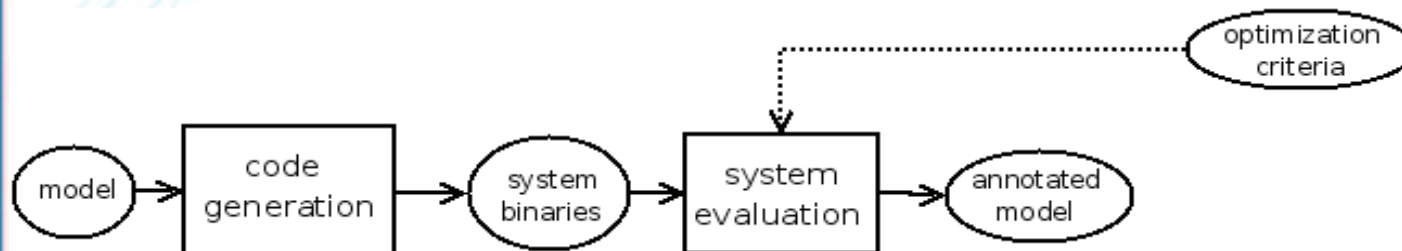
bus

Period  
 Compute\_Execution\_Time  
 Compute\_Deadline  
 Priority



## Optimizing AADL models

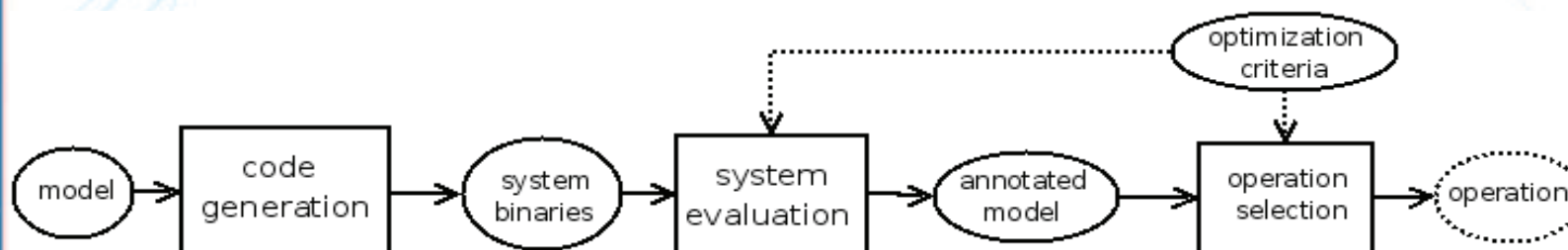
- Take advantage of full MBD chain to generate code and then evaluate system  
model-level evaluation: some user-defined metrics  
binary-level evaluation: WCET, binutils, ...





## Optimizing AADL models

- Drive Optimisation process using REAL as a DSL to express relevant criteria  
As many criteria as projects

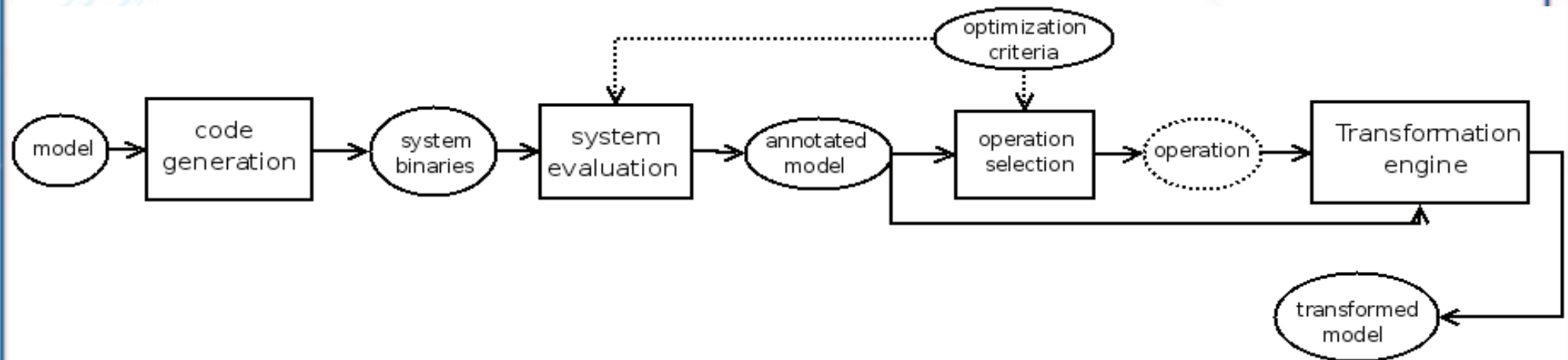


```
theorem minimum_distance_to_deadline
  foreach th in Thread_Set do
    var distance := if exists(th, "Transformations::Fusion_Occurred")
      then compute distance_to_deadline_optimized (th)
      else compute distance_to_deadline_regular (th);
    return (Mmin (distance));
  end minimum_distance_to_deadline;
```



# Optimizing AADL models

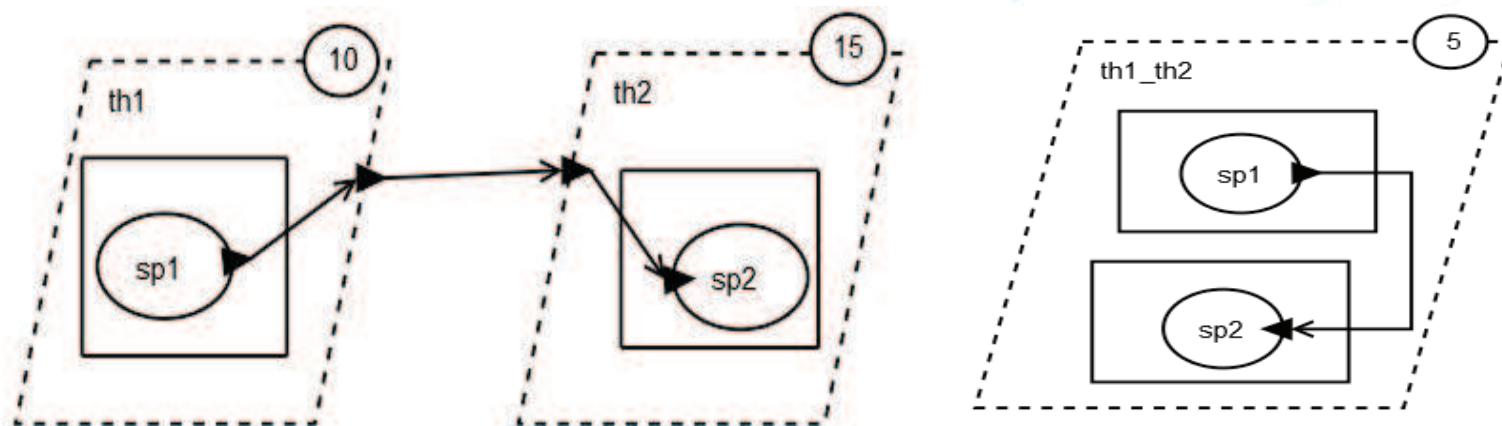
- Then perform the transformation



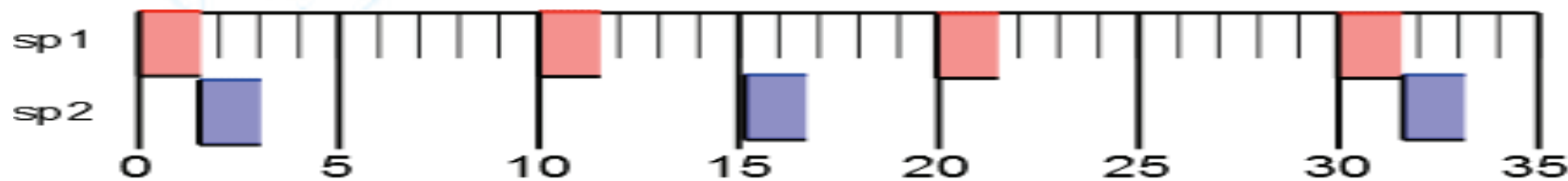




# Optimizing AADL models: ex Merge



- Two periodic threads of periods 10 and 15 ms
  - Connected through a data connection (asynchronous)
- Merge : a periodic thread of period 5 ms
  - The tasks are connected through local connection





## To conclude

- Ocarina provides tools to generate part of your system, and to relieve you from misconfiguration of the runtime
- Not presented
  - REAL: a constraint language to check properties on system
    - ✓ E.g. Bell-LaPadula, Biba, ARINC consistency, ...
  - Bound-T integration: compute WCET of AADL runtime
  - Behavioral annex
  - Automatic execution of model: integrate compilation and run on simulator or real hardware in one click, to ease rapid prototyping
  - Code coverage of the model's generated code
  - ...



## Credits

- Ocarina is the result of more than 5 years of research
  - Lead work: Laurent Pautet (ENST) + Jérôme Hugues
  - Members of AS-2C since 2005
- PhD students involved
  - Thomas Vergnaud: initial architecture of Ocarina + code generation to PolyORB
  - Bechir Zalila: code generation to and design of PolyORB-HI/Ada
  - Julien Delange: PolyORB-HI/C + POK + ARINC 653
  - Xavier Renault: mapping to Petri Nets
  - Olivier Gilles : optimization of AADL models
  - Gilles Lasnier: integration of the Behavioral annex