

# Finite Domain Constraint Programming Systems

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KUNGL.  
TEKNISKA  
HÖGSKOLAN



## What Is This Tutorial About?



- Focus is on
  - *Services systems provide*
  - *Implementation of these systems*
- No detailed description of one system
  - *Common techniques, approaches, challenges*
  - *No intention to do complete survey*

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## Finite Domain Constraint Programming Systems



- Offer *reusable* software components for
  - constraint propagation
  - combining constraints (combinators)
  - search
    - branching (labeling)
    - exploration (for example: depth-first, LDS, ...)
  - user extensions
- Services provided
  - environment for integrating components
  - libraries of commonly used components

[Henz & Müller 00]

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## Systems Discussed



- Prolog-based systems
  - SICStus Prolog, Eclipse Prolog, GNU Prolog, CHIP,...
- Libraries
  - ILOG Solver (C++) and JSolver (Java), Choco (Claire), Figaro (C++), Facile (Ocaml), CHIP Library (C++)
- Specialized languages
  - Claire, Oz

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## Outline of Tutorial

- Constraint propagation
  - example [Christian]
  - model [Christian]
  - implementation [Mats]
  - optimizations [Mats]
- Search [Christian]
- Combinators [Christian]
- Trends & Challenges [Mats]
- References

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## Constraint Propagation

Example

## Example

$$x + y = 9$$

$$2x + 4y = 24$$

x	0	1	2	3	4	5	6	7	8	9
y	0	1	2	3	4	5	6	7	8	9

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## Constraint Propagation

Model

## Constraint Propagation

- Variables
  - feature variable domain (finite set of integers)
- Propagators
  - implement constraints
- Propagation loop
  - execute propagators until simultaneous fixpoint

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## Propagator

- Propagator  $p$  is procedure
  - implements constraint  $\text{con}(p)$   
its semantics (set of tuples)
  - computes on set of variables  $\text{var}(p)$
- Execution of propagator  $p$ 
  - narrows domains of variables in  $\text{var}(p)$
  - signals failure
  - signals entailment [discussed later]

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## Classes of Constraints

- Basic constraints
  - Constraints for which the solver is complete
    - $x \in D$ ,  $x = v$ ,  $x = y$  (variable aliasing)
- Primitive constraints (need propagators)
  - Non-decomposable constraints
    - $x < y$ ,  $x \neq y$ ,  $x + y = z$ ,  $x * y = z$ , ...
- Global constraints (need propagators)
  - Subsume a set of basic or primitive constraints, usually providing stronger consistency

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## Reification

- Control constraint by control variable  $b \in \{0,1\}$ 
$$c \Leftrightarrow b=1$$
  - also require propagator
- A.k.a.: metaconstraints

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## Propagators Are Intensional

- Propagators implement narrowing
  - also: filtering, propagation, domain reduction
- No extensional representation of  $\text{con}(p)$ 
  - impractical in most cases (space)
- Extensional representation of constraint
  - can be provided by special propagator
  - often: "element" constraint, "relation" constraint, ...

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## Implementing Propagators

- Implementation uses operations on variables
  - reading domain information
  - narrowing domains
- Variables are the only communication channels between propagators
- More detail later

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## Propagator Properties

- Propagator  $p$  is
  - correct: no solution of  $\text{con}(p)$  is removed
  - assignment complete: failure at latest for assignments
    - compatibility with search
- Propagator  $p$  is
  - contracting: variable domains are narrowed
  - monotonic: application to smaller domains will result in smaller domains than application to larger domains
  - may be idempotent: [discussed later]

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## Propagation Loop

- Largest simultaneous fixpoint of propagators
  - fixpoint: propagators cannot narrow any further
  - largest: no solutions lost
- Guaranteed
  - termination: domains finite  
propagators contracting
  - largest fixpoint: propagators monotonic

Detailed study with proofs: [Apt 00]

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## Fix and Runnable Propagators

- Propagator is either
  - fix: has reached fixpoint
  - runnable: not known to have reached fixpoint
- Propagation loop maintains propagator sets
  - all propagators  $Prop$
  - runnable propagators  $Run$
  - initially  $Run := Prop$

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## Sketch of Propagation Loop

```

while ( $Run \neq \emptyset$ ) {
  pick and remove  $p$  from  $Run$ ;
  execute  $p$ ;
   $ModVar := \{ x \mid x \text{ modified by } p \}$ ;
   $DepProp := \{ q \mid x \in \text{var}(q), x \in ModVar \}$ ;
   $Run := \text{join}(DepProp, Run)$ ;
}

```

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## Sketch of Propagation Loop

```
while ( $Run \neq \emptyset$ ) {  
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     $Run := \text{join}(DepProp, Run)$ ;  
}
```

Loop invariant:  $p \text{ is fix} \Leftrightarrow p \in (Prop-Run)$

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## Sketch of Propagation Loop

```
while ( $Run \neq \emptyset$ ) {  
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     $Run := \text{join}(DepProp, Run)$ ;  
}
```

Termination ( $Run=\emptyset$ ):  $p \text{ is fix} \Leftrightarrow p \in Prop$

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## Sketch of Propagation Loop

```
while ( $Run \neq \emptyset$ ) {  
    pick and remove  $p$  from  $Run$ ;  
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     $ModVar := \{ x \mid x \text{ modified by } p \}$ ;  
     $DepProp := \{ q \mid x \in \text{var}(q), x \in ModVar \}$ ;  
     $Run := \text{join}(DepProp, Run)$ ;  
}
```

Ignored: failure (signaled by  $p$ )

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## Consistency Level Computed

- Model is generic
- Consistency level defined by each individual propagator
  - accurate way of characterization [Maher 02]
- Supports many different consistency levels
  - propagator for domain-consistent alldifferent
  - propagator for bound-consistent alldifferent
  - propagator for value-consistent alldifferent

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## Major Design Decisions

- Implementing *Run* (that is, pick and join)
  - queue: first in – first out
  - stack: last in – first out
  - priority queue
- Implementing *ModVar* and *DepProp*
  - variable-centered representation

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## Implementing *ModVar* and *DepProp*

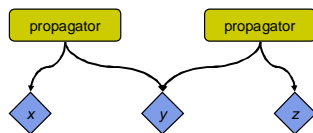
- Variable-centered approach
  - each variable  $x$  knows dependent propagators
  - typically organized as list (*suspension list*)
  - propagator  $p$  included in list of  $x \Leftrightarrow x \in \text{var}(p)$
- Upon propagator creation
  - propagator subscribes to its variables
  - becomes runnable

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## Propagators $\Rightarrow$ Variables



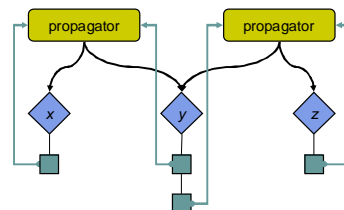
- **Propagators** know their **variables**
  - to perform domain modifications
  - passed as parameters to propagator creation

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## Variables $\Rightarrow$ Propagators



- **Variables** know dependent **propagators**
  - to perform efficient computation of dependent propagators
  - implemented by *suspension lists*

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## Modifying a Variable

- Traverse suspension list
  - add propagators to *Run*
- Optimization
  - mark runnable propagators
  - that is: propagators already in *Run*
- Multiple variable modification by propagator
  - explicitly maintain *ModVar* (as in model)
  - only after propagator execution: process *ModVar*
  - suspension list traversed only once per variable

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## Propagation Events

- Use knowledge on propagator to avoid its redundant execution
  - redundant: application to fixpoint
- Example: bound-consistent linear equality
  - need to execute, if bound of variable changes
  - no need to execute, if inner value of variable removed
- Suspension list:  $\langle \text{propagator}, \text{event} \rangle$ 
  - event describes relevant domain modifications
  - implementation: lists per event, single list of pairs
  - events: VALUE, BOUND, DOMAIN

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## Idempotent Propagators

- Idempotent propagator
  - always computes fixpoint
- Propagation loop perspective
  - no need to include in *Run*
  - more efficient: saves one invocation of propagator
- Propagator perspective
  - must compute fixpoint itself
  - more efficient: specific method for computing fixpoint
  - might be more challenging

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## Propagator Entailment

- Propagator will never contribute anything
  - fixpoint property preserved by narrowing
- Delete propagator, if entailment detected
  - remove from suspension-list, or
  - mark as dead, delegate removal to garbage collection
- Similar to consistency, different entailment levels
  - semantically relevant in concurrent constraint programming

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## Summary of Model

- Variables
  - domain
  - suspension list: (event, propagator)
- Propagators
  - intensional, correct, contracting, monotone, define consistency level, ...
  - know variables for narrowing
- Propagation loop
  - computes largest simultaneous fixpoint

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## Constraint Propagation

Implementation

## Propagation Queues

- Contents
  - Events, variables, or propagators
- Scheduling Policy
  - LIFO makes sense for "important" events
  - FIFO – fair scheduling, no starvation
  - Compare LIFO and FIFO for:
    - $x > y, y > x, x \geq 100t, y \leq t, \{x, y, t\} \in 1..1000$
- Structure
  - Flat or layered

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## Layered Propagator Queue

- CHOCO's 8 priority levels
  - VALUE event queue: LIFO
  - BOUND event queue: FIFO
  - DOMAIN event queue: FIFO
  - P's for extensionally defined constraints (AC-4)
  - $O(N)$  propagators
  - $O(< N^2)$  propagators
  - $O(N^2)$  propagators
  - $O(> N^2)$  propagators

[Laburthe 00]

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## Stateful Propagators

- Prerequisite for incremental algorithms
  - Can bring down complexity by an “order”
- Arguments checked initially only
- Prolog level state not enough
- State can be used for:
  - Gradually ignoring ground variables
  - Data structures for the filtering algorithm
  - Memory of variables’ min/max/domain
  - Local trailing for backtracking

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## What Does a Propagator Know?

- Course-grained information
  - Something has changed (SICStus, Mozart)
- Medium-grained information
  - Variables  $v_3, v_7, v_{11}$  have changed (CHIP)
- Fine-grained information (ILOG)
 

Variable	Old domain	New domain	Delta
$v_1$	1..5	2..4	{1,5}
- Stateful propagators can figure out what changed

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## What Does a Propagator Need?

- A good filtering algorithm
  - An algorithm library might come in handy
    - Shortest-path, bipartite matching, max flow, min-cost flow, profiles, strongly connected components, ...
- ADT: finite domain
- ADT: domain variable
- Host language services
- Solver kernel interface
  - True/false/suspend, replace\_by, I\_am\_not\_idempotent, ...
- State

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## ADT: Finite Domain

- Representation
  - List of intervals (ECLiPSe, SICStus)
  - Bounds + bit array (CHIP, GNU Prolog, Mozart)
  - Bounds + list of holes
  - Interval trees
  - Multiple, adaptive (CHOCO, Mozart, ...)
- Operations
  - Set operations
  - Constructors, iterators
  - Complexity depends on representation

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## ADT: Domain Variable

- Representation
  - Logic variable + attributes for domain and suspensions, or
  - Class instance
- Operations
  - Access min, max, domain
  - Adjust min, max, domain; remove values
  - Raise events
  - Attach/detach suspensions

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## Variable Aliasing ( $x = y$ )

- Only an issue in logic-based languages
- Normalization:
  - Merge suspension lists
  - Intersect domains
  - Raise events
  - IF  $\text{con}(p)$  mentions both  $x$  and  $y$  THEN
    - $p$  may no longer be idempotent
    - $p$  can make more inferences, e.g.:  
 $\text{xor}(x,y,z), x=y \Rightarrow z=0$

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## Host Language Services (Generic)

- Memory management
  - Allocation: objects, states
  - Garbage collections: term refs in states and queues
  - Copying
- Trailing
  - Coarse or fine
  - Semantic trailing for self-destruct on backtracking
- Resume/suspend mechanism
  - Full coroutines, multithreading etc. not needed

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## Host Language Services (Prolog-Based)

- Predicate/function type extensions
  - Constraints must be callable like predicates
  - WAM support for indexicals (coming slides)
- Attributed variables [Holzbaur 92] [Le Huitouze 90]
  - Domains
  - Suspensions
  - Unification hook
- Mutable terms
  - Coarse trailing

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## Implementation Choices

- In host language
  - Prolog (ECLiPSe, SICStus)
  - C++ (ILOG Solver, Figaro, CHIP Library)
  - Claire (CHOCO)
  - Java (ILOG JSolver)
- C/C++
  - For predefined constraints (ECLiPSe, SICStus)
  - For predefined + user-defined constraints (Mozart)
- Indexicals
  - For "pseudo primitives" (GNU Prolog, SICStus)

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## Indexicals

- Given  $C(X_1, \dots, X_n)$ , for each  $i$ , provide a rule  $X_i \text{ in } R_i$  which computes the feasible values of  $X_i$ 
  - Example:  $X = Y + C$ , arc-consistent version
 

```
eqcd(X, Y, C) +:
    X in dom(Y)+C,
    Y in dom(X)-C.
```
  - Example:  $X = Y + C$ , bound-consistent version
 

```
eqcd(X, Y, C) +:
    X in min(Y)+C..max(Y)+C,
    Y in min(X)-C..max(X)-C.
```

[Van Hentenryck & Deville & Saraswat 92]

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## Indexicals: Syntax of $X \text{ in } R$

### Range expressions

$R ::= T..T \mid R \setminus R \mid R \vee R \mid R \mid R+T \mid R-T \mid R \bmod T \mid \{T, \dots, T\} \mid \text{dom}(X)$

### Term expressions

$T ::= T+T \mid T-T \mid T/>T \mid T</T \mid T \bmod T \mid \min(X) \mid \max(X) \mid X \mid \text{integer} \mid \text{inf} \mid \text{sup}$

Monotone indexicals for propagation

Anti-monotone indexicals for entailment check

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## Indexicals for Reification

Example:  $X = Y + C$ , SICStus syntax

?- eqcd(X, Y, 5) #<=> B.

```
eqcd(X, Y, C) +:      % propagation
    X in dom(Y)+C, Y in dom(X)-C.
eqcd(X, Y, C) -:      % converse propagation
    X in \{Y+C\}, Y in \{X-C\}.
eqcd(X, Y, C) +?      % entailment check
    X in {Y+C}.
eqcd(X, Y, C) -?      % disentanglement check
    X in \dom(Y)+C.
```

[Carlsson & Ottosson & Carlson 97]

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## Indexicals: Implementation

- Compiled to (bytecode, symbol table)
- Syntax intercepted by *term expansion*
- Executed by a simple stack-based VM
- `eqcd/3` gets defined as a Prolog predicate
  - The WAM escapes to a solver entrypoint

[Carlsson & Ottosson & Carlson 97]

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## Indexicals: Pros and Cons

- Efficiency: witness GNU Prolog
- A RISC approach to constraint solving
- A VM for propagators
- A language for fine-tuned propagation in a general framework
- Can detect entailment as well as propagate
- Drawbacks
  - Pseudo-primitives only (no global constraints)
  - N propagators needed for 1 constraint

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## An Entity-Relationship Model (CHOCO, Figaro, ILOG)

- Objects
    - Problems
    - Variables
    - Domains
    - Constraints
  - Relationships
    - Links between constraints and variables  
(*constraint, variable, event*)
- [Puget 94][Puget & Leconte 95] [Laborthe 00]

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## Constraint Objects

- State in private data
- Virtual methods for (some of):
  - Posting
  - Propagation
  - Entailment/disentailment test
  - Reification
  - Profiler and visualizer services
  - Memory manager services

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## The ILOG Global Constraint API (Simplified)

```
class ClassName : public IlcConstraint {
public:
    ClassName(IloSolver solver, Args);
    ~ClassName(void);
    virtual void post(void);
    virtual void propagate(void);
    virtual IlcBool isViolated(void) const;
};
```

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## The Mozart Global Constraint API (Simplified)

```
class ClassName : public OZ_Propagator {
public:
    ClassName(OZ_Term Args);
    virtual OZ_Return propagate(void);
    virtual size_t sizeOf(void);
    virtual void gCollect(void);
    virtual void sClone(void);
    virtual OZ_Term getParameters(void) const;
};
```

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## A Global Constraint API for Prolog (SICStus)

- `fd_global(+C, +S, +V)`
  - Posts a global constraint *C* with initial state *S*, suspended according to *V*, which is a list of `dom(X)`, `min(X)`, `max(X)`, `minmax(X)`, `val(X)`
- `dispatch_global(+C, +S0, -S, -A)`
  - user defined
  - Entrypoint to the propagator of constraint *C* with state *S0*, producing a new state *S* and kernel requests *A* (*true/false/suspend*, events)
- ADTs for domains and domain variables
- Control is implicit

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## Constraint Propagation

Optimizations

## Rewriting

- Generic  $\rightarrow$  special  
 $3x + y - z = 0, x = 0$   
 $\rightarrow$   
 $y = z$  (variable aliasing)
- Gradual decomposition  
 $\text{alldiff}([T, U, V, X, Y, Z]), [T, U, V] \text{ in } 1..3, [X, Y, Z] \text{ in } 4..6$   
 $\rightarrow$   
 $\text{alldiff}([T, U, V]), \text{alldiff}([X, Y, Z])$

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## Avoiding Useless Work

- Idempotent  $p$  should be immune to events raised by  $p$ 
  - Kernel may or may not assume idempotence
- An entailed  $p$  should never be resumed
  - It can even be detached (undoably) from  $\text{var}(p)$
- IF time of latest event < time of latest resumption THEN don't resume  $p$ 
  - Event queues require timestamps
- Indexicals linked to the same constraint should (sometimes) be immune to each other's events

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## More Optimizations

- Different event types
  - VALUE > BOUND > DOMAIN
  - $p$  is suspended on a set of  $(v, \text{event})$
  - Demons vs. propagators
- Scheduling policies
  - Poorly understood
  - Complexity-based priority queues make sense
  - Always bear the worst case in mind

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## Search



## Branching and Exploration

- Branching: defines shape of search tree
  - labeling, branching, distribution, ...
  - often based on heuristics
- Exploration: explore nodes of search tree
  - often fixed to be depth-first
  - many aspects
    - optimization (branch-and-bound)
    - development tools (Oz Explorer)
    - parallelism (ILOG Solver, Oz)

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## Branching

- Requires synchronization on fixpoint
  - for implementing dynamic variable orderings
  - by construction: Prolog, ILOG Solver, ...
  - explicit synchronization in concurrent setup: Oz
- Programmed
  - from builtin-search: Prolog-based
  - special (language) constructs: ILOG Solver, Oz
- Typically, rich library available

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## Exploration

- All systems support
  - search for first solution
  - search for some/all solutions
  - search for best solution
- Most systems support
  - LDS and some variants

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## Exploration Strategy

- Often fixed to be depth-first
- Sometimes can be programmed
  - Oz: spaces ("nodes") as ADT for exploration
    - exploration programmed from operations
    - for example: copy node in search tree  
access solution
  - ILOG Solver: control exploration by limits and priorities
    - limit cut-off branches
    - priorities which node to explore next

[Schulte 97] [Perron 99]

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## Infrastructure for Exploration

- State restauration
  - backtrack to a *previous* state
- Approaches
  - trailing: recording and undoing changes
  - copying: put complete state aside
  - recomputation: recompute state on need
- By far dominating approach: trailing

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## Trailing

- Trailing stores undo and redo information
  - interleaved with constraint propagation
  - uses trail data structure
  - update: put (location, content)
  - undo: write location  $\leftarrow$  content
  - every choice point: put mark or record top of trail
- Requires
  - all updates trail-aware
  - for example: domain change, change of suspension list, ...

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## Time Stamping

- Problem: multiple change of same location
  - for example: multiple narrowing of domain
  - only original value needs restauration
  - intermediate values not needed
- Solution: local time stamp on modified entity
  - new choice point increase global time stamp
  - upon modification trail, if local stamp earlier
  - update local stamp

[Aggoun & Beldiceanu 90] [Aggoun & Beldiceanu 91]

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## Multiple Value Trail

- Modifying  $n$  successive locations
  - record start, number ( $n$ ) and  $n$  locations on trail
  - instead of  $2n$  individual entries

[Aggoun & Beldiceanu 90] [Aggoun & Beldiceanu 91]

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## Copying And Recomputation

- Copying
  - operations ignorant of state restoration
  - support for concurrency and parallelism
  - alone infeasible: excessive memory requirements
- Hybrid strategies: copying and recomputation
  - adaptive: create copy on demand to speed up future recomputation
  - batch: speed up recomputation by avoiding repeated fixpoint computation
  - competitive with trailing

[Schulte 99] [Choi & Henz & Ng 01] [Schulte 02]

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## Combinators

## Combinators

- Reification-based combination
  - reified constraints
  - propositional combination
- Propagation-preserving approaches
- Constructive disjunction

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## Reification

- Use control variable  $b \in \{0, 1\}$   
 $c \Leftrightarrow b=1$
- Propagate
  - $c$  entailed  $\Rightarrow$  propagate  $b=1$
  - $\neg c$  entailed  $\Rightarrow$  propagate  $b=0$
  - $b=1$  entailed  $\Rightarrow$  propagate  $c$
  - $b=0$  entailed  $\Rightarrow$  propagate  $\neg c$  (might be difficult)

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## Propositional Combination

- Constraints for combining reified constraints
  - constraints as connectives over 0/1 variables
- Combine  $(c_1 \wedge c_2) \vee c_3$ 
  - reify each  $c_i$  to 0/1 variable
  - use constraints on 0/1 variables
- Problem: not propagation-preserving
  - no propagation between  $c_1$  and  $c_2$
  - in  $c_1 \wedge c_2$ , both  $c_1$  and  $c_2$  propagate individually

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## Compositional Approaches

- Use language-based primitives for implementing combinators
  - encapsulated propagation
  - generalization of ccp-paradigm
  - pioneered by AKL [Haridi & Janson 90]
  - generalized to programming abstraction [Schulte 02]
- Advantages and disadvantages
  - expressive and propagation preserving
  - implementation complex and less efficient than reification
  - unclear how to provide in language-independent setting

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## Constructive Disjunction

- Idea: make assumptions and generalize
  - propagate locally in each branch of disjunction
  - lift out common information on domains from branches
- Well researched/published idea
  - cc(FD) [Van Hentenryck & Saraswat & Deville 95]
  - many other papers, for example [Codognet & Codognet 95] [Würtz & Müller 96]
  - not of strategic importance
  - technique useful to know about

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## Trends and Challenges

## Explanations

- Definition

*A (minimal) set of constraints and choices made during search justifying a propagation event*

- Uses

- Understanding dead ends
- Nogoods
- Conflict-directed backtrack search
- Debuggers and visualizers

- Challenges

- Sharp explanations for global constraints
  - Bridging semantic gap between application and CP model
- [Jussien & Barichard 00]

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## Meta-Programming

- Applications:

- Debuggers
- Visualizers
- Static analysers
- Search strategy synthesizers
- Test case generators
- Parser generators for propagators

- Requirement:

- Exact and formal description of all constructs

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## Challenges

- Communication between constraints

*Constraints communicate via domain variables only, so constraints are independent of each other*

- Good news: constraints can be posted regardless of already posted ones
- Bad news:
  - Loss of global view
  - Obvious propagation missing
  - Thrashing
  - Creates artificial global constraints

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## Challenges

- Exact and formal description of all constructs

- Syntax and options
- Declarative semantics
- Events
- Level of consistency
- Complexity

- No information should appear only in the manual

[Beldiceanu 00]

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## Challenges

- Hybridization
  - with local search
    - Let CP explore the neighborhood
  - with linear programming
    - Benders decomposition
- [Eremin & Wallace 01]
- Modelling languages and global constraints
- Optimization
  - Cost-based filtering algorithms
- Over-constrained problems
  - Replace  $C(X)$  by  $C(X, cost)$  where  $cost$  is the degree to which  $X$  violates  $C(X)$
- [Petit & Régim & Bessière 01]

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## Challenges

- Beyond finite domains
  - [Jaffar & Maher & Stuckey & Yap 94]
  - Richer set of basic constraints, e.g. TVPI
    - $X \bmod 11 \in \{1, 5\}, x \geq 2y+3, \dots$
- Classification and standardization
- Parametric constraints
  - One constraint family – one filtering algorithm
- [Beldiceanu 2000]

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