

# Finite Domain Constraints in SICStus Prolog

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# Outline of the Talk

- The SICStus `library(clpfd)` Package
  - built-in primitives
  - implementation architecture
  - indexicals
  - global constraints
- Host Language Support
- Internal Representation
  - domain variables
  - propagation queues
- Stateful Constraints
  - unification and co-references
  - optimizations
- Debugging
- Conclusion

# CLP over Finite Domains

- Constraint store
  - $X \subseteq D, D \subseteq \mathbf{Z}$
- Terms
  - integers (can be  $<0$ )
  - variables ranging over finite domains
- Constraints
  - linear arithmetic constraints
  - combinatorial constraints
  - reified constraints:  $p(x_1, \dots, x_n) \Leftrightarrow b$
  - propositional combinations of reified constraints
  - user-defined constraints

# Built-in Constraints

element/3

case/[3,4]

all\_different/[1,2]

assignment/[2,3]

circuit/[1,2]

cumulative/[4,5]

serialized/[2,3]

disjoint1/[1,2]

disjoint2/[1,2]

cumulatives/[2,3]

global\_cardinality/2

count/4

scalar\_product/4

sum/3

knapsack/3

X in Domain, X in\_set Set

X #= Y, X #\= Y

X #< Y, X #=< Y

X #>= Y, X #> Y

#\ C

C #/\ D

C #\ / D

C #=> D

C #<=> D

C #<=> B

# Built-in Search

- `indomain(Var)`
- `labeling(Options,Vars)`
- `minimize(Goal,Var)`
- `maximize(Goal,Var)`

## Labeling options

- `leftmost | min | max | ff  
| ffc | variable(Sel)`
- `enum | step | bisect | up  
| down | value(Enum)`
- `discrepancy(D)`
- `all | minimize(Var) |  
maximize(Var)`

# Implementation Architecture

- A scheduler for **indexicals** and **global constraints**
- Support for **reified constraints**
- User-defined indexicals for fine-tuned propagation within a general framework
- Global constraints use specialized filtering algorithms
- Custom designed suspension mechanism
- Support for stateful constraints

# Indexicals

- Given a constraint  $C(X_1, \dots, X_n)$ , for each  $X_i$ , write a rule  $X_i \text{ in } R_i$  that computes the feasible values of  $X_i$  in terms of  $\{dom(X_j) \mid i \neq j\}$ .
  - [VSD92] P. Van Hentenryck, V. Saraswat, Y. Deville. Constraint processing in cc(FD), 1992. Draft.

- Example:  $X = Y + C$ , domain consistent version.

eqcd(X, Y, C) +:

X in dom(Y) + C,

Y in dom(X) - C.

- Example:  $X = Y + C$ , interval consistent version.

eqcd(X, Y, C) +:

X in min(Y) + C .. max(Y) + C,

Y in min(X) + C .. max(X) - C.

## Indexicals: Pros and Cons

- Feasibility demonstrated by D. Diaz: clp(FD), GNU Prolog
- Other implementations by G. Sidebottom, H. Lock, H. Vandecasteele, B. Carlson, ...
- A RISC approach to constraint solving
- Reactive functional rules executed by a specialized virtual machine
- A language for fine-tuned propagation in a general framework
- A language for **entailment detection** and hence **reification**
- Drawbacks:
  - low granularity
  - local effect
  - fixed arity



## Indexicals: Definitions

- $R_S$  denotes the range expression  $R$  evaluated in the constraint store  $S$
- $S'$  is an **extension of  $S$**  iff

$$\forall X : \text{dom}(X)_{S'} \subseteq \text{dom}(X)_S$$

- $R$  is **monotone in  $S$**  iff for every extension  $S'$  of  $S$ ,

$$R_{S'} \subseteq R_S$$

- $R$  is **anti-monotone in  $S$**  iff for every extension  $S'$  of  $S$ ,

$$R_S \subseteq R_{S'}$$

# Indexicals: Syntax of $X$ in $R$

## Range expressions

$R ::= T..T \mid R/\backslash R \mid R\backslash/R \mid \backslash R \mid R+T \mid R-T \mid R \bmod T \mid \{T, \dots, T\}$   
 $\mid \text{dom}(X)$

## Term expressions

$T ::= T+T \mid T-T \mid T*T \mid T/>T \mid T</T \mid T \bmod T \mid \min(X) \mid$   
 $\max(X) \mid \text{card}(X) \mid X \mid N$

$N ::= \text{integer} \mid \text{inf} \mid \text{sup}$

## Monotonicity

Indexicals for **constraint solving** must be **monotone**

Indexicals for **entailment detection** must be **anti-monotone**

# Indexicals for Reification

- Example:  $X = Y + C$ .

?- eqcd(X, Y, 5) <=> B.

eqcd(X, Y, C) +:       % positive constraint solving

  X in dom(Y)+C,

  Y in dom(X)-C.

eqcd(X, Y, C) -:       % negative constraint solving

  X in \{Y+C},

  Y in \{X-C}.

eqcd(X, Y, C) +?       % entailment detection

  X in {Y+C}.

eqcd(X, Y, C) -?       % disentanglement detection

  X in \dom(Y)+C.

# Indexicals: Implementation

- Compiled to (bytecode, symbol table).
- Indexical syntax intercepted by `user:term_expansion/2`

```
user:term_expansion((Head+:Body), Expansion) :-  
    functor(Head, N, A),  
    Expansion = [:- clpfd:'$fd_install'(N/A, 1, Info)],  
    compile(Head, Body, Info).
```

- Executed by a simple stack-based VM.
- `eqcd/3` gets defined as a **Prolog predicate**
  - the WAM escapes to a solver entrypoint

# The Global Constraints API

- `fd_global(+C,+S,+V)`
  - Posts a global constraint `C` with initial state `S`; `V` tells how to suspend on variables by means of a list of
    - `dom(X)`, `min(X)`, `max(X)`, `minmax(X)`, `val(X)`
- `clpfd:dispatch_global(+C,+S0,-S,-A)` **User defined.**
  - Entrypoint for the filtering algorithm of global constraint `C` with state `S0`, producing a new state `S` and solver requests `A` (entailed, disentailed, prune, ...).
- `fd_min(?X,-Min)`, `fd_max(?X,-Max)`, ...
  - Unifies `Min` (`Max`) with the current lower (upper) bound of `X`.
- FD set ADT
  - Comes with all the necessary operations.

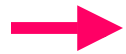
## $x \leq y \Leftrightarrow b$ as a Global Constraint

```
le_iff(X,Y,B) :-
    B in 0..1,
    fd_global(le(X,Y,B), [], [minmax(X),minmax(Y),val(B)]).

:- multifile clpfd:dispatch_global/4.
clpfd:dispatch_global(le(X,Y,B), [], [], Actions) :-
    (
        var(B)
    -> (
        fd_max(X,Xmax), fd_min(Y,Ymin), Xmax =< Ymin
    -> Actions = [exit,B=1]           % entailed, B=1
    -> (
        fd_max(Y,Ymax), fd_min(X,Xmin), Xmin > Ymax
    -> Actions = [exit,B=0]           % entailed, B=0
        ; Actions = []                % not entailed, no pruning
    )
    ; B:=0
    -> Actions = [exit,call(X#>Y)]   % rewrite to X#>Y
    ; Actions = [exit,call(X#=<Y)]   % rewrite to X#=<Y
    ).
```

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  - global constraints



## Host Language Support

- Internal Representation
  - domain variables
  - propagation queues
- Stateful Constraints
  - unification and co-references
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# Generic Support

- **Backtracking, trailing**
  - Provides *search*, automatic *memory reclamation*, *state restoration*, *do-on-backtracking*
- **Meta-calls, encapsulated computations**
  - Enables meta-constraints
    - *cardinality-path* [Beldiceanu&Carlsson, ICLP2001]
    - *Satisfiability Sum* [Régin et al., CP2001]
- **Term Expansion**: `user:term_expansion/2`
  - Recognizes and translates indexical “clauses”
- **Goal Expansion**: `user:goal_expansion/3`
  - Provides macro-expansion
  - Recognizes and translates arithmetic constraints
    - $X \# = Y$ ,  $X \# \geq Y$ , etc.
  - Recognizes and translates propositional constraints
    - $P \# \setminus Q$ ,  $P \# \setminus / Q$ , etc.



# Support Targeted for CLP

- **Attributed Variables** provide the link from unification to solvers, and allow solvers to store data on variables.
  - C. Holzbaur. *Specification of Constraint Based Inference Mechanism through Extended Unification*. PhD thesis, U. of Vienna, 1990.
  - Unification hooks
  - Top-level loop hooks

```
:- attribute fd_attribute(_, _).
```

```
?- get_atts(X, fd_attribute(DomMut, SuspMut)).
```

```
?- put_atts(X, fd_attribute(DomMut, SuspMut)).
```

```
verify_attributes(Var, Term, Goals) :- ...
```

## Support Targeted for CLP

- **Mutable Terms** provide backtrackable assignment (value-trailing).
  - N. Beldiceanu, A. Aggoun. *Time Stamps Techniques for the Trailed Data in CLP Systems*. Actes du Séminaire 1990 - Programmation en Logique, Tregastel, France.
  - Only for Prolog terms, not arbitrary memory locations
  - Coarse trailing [Choi, Henz and Ng, CP2001]

```
'$mutable'(Term, Timestamp)
```

```
create_mutable(+Term, +Mutable)
```

```
get_mutable(+Term, +Mutable)
```

```
update_mutable(+Term, +Mutable)
```

# Outline of the Talk

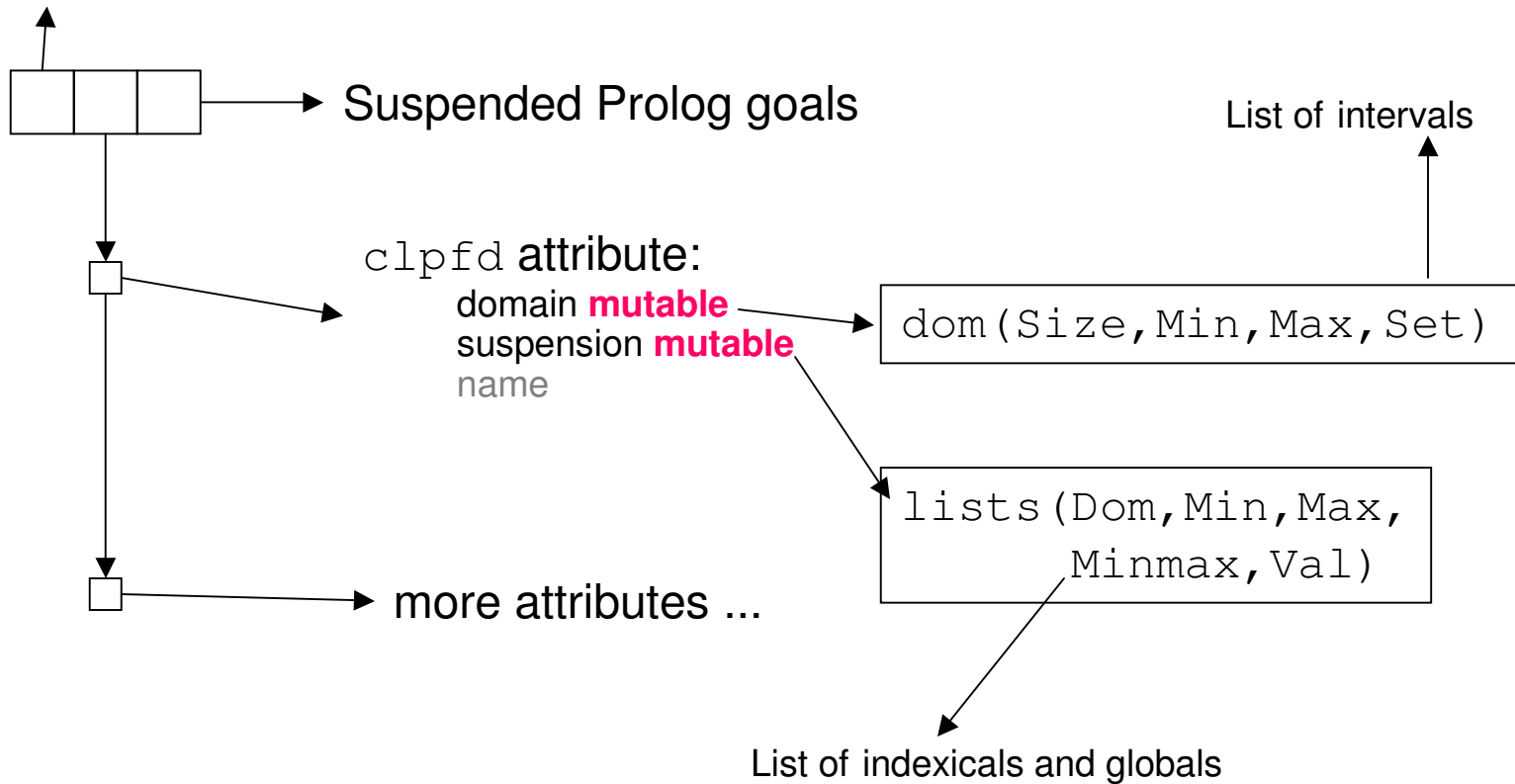
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# Domain representation

- Options:
  - interval+bit array [CHIP compiler, clp(FD), GNU Prolog, CHOCO, Mozart]
  - array of integers [CHIP compiler]
  - **list of intervals** [ECLiPSe, SICStus, CHOCO, Mozart, MROPE, Figaro]
  - interval trees [CHOCO]
  - interval only [interval solvers, CHIP compiler]
  - interval + list of holes [?]
- Pros (assuming  $M$  intervals)
  - operations  $O(M)$  in the worst case
  - implementation straightforward
  - Prolog representation straightforward
  - scalable
- Cons
  - performs poorly on *N Queens*

# Domain Variables

Value cell



# Propagation Queues

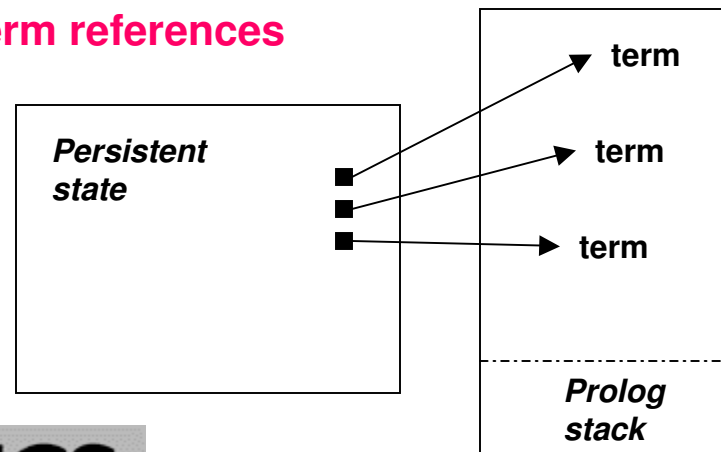
- Queues of **constraints**, not **variables**
  - The KISS principle
  - One indexical queue (greater priority)
  - One global constraint queue (lesser priority)
- Enqueued test in  $O(1)$  time
  - using a **mutable term**
- **No extra information** stored with queue elements
  - which variables were pruned
  - why they were pruned
  - their previous domains
- Historically, **difference lists** were being passed around
- Now using **dedicated buffers**
  - modest performance gains
  - needs garbage collector services

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# Stateful Constraints

- `clpfd:dispatch_global(+Ctr,+S0,-S,-A)` **User defined.**
  - Entrypoint for the filtering algorithm of global constraint Ctr with state S0, producing a new state S and solver requests A.
  - Does not say **which** domain variables were pruned.
  - Provides for state as a **Prolog term**. However, most built-in constraints are written in C  $\Rightarrow$  costly conversion to C data **each time** Ctr wakes up.
- Persistent state in C, requiring:
  - **deallocation guaranteed** on backtracking or determinate entailment
  - global **term references**



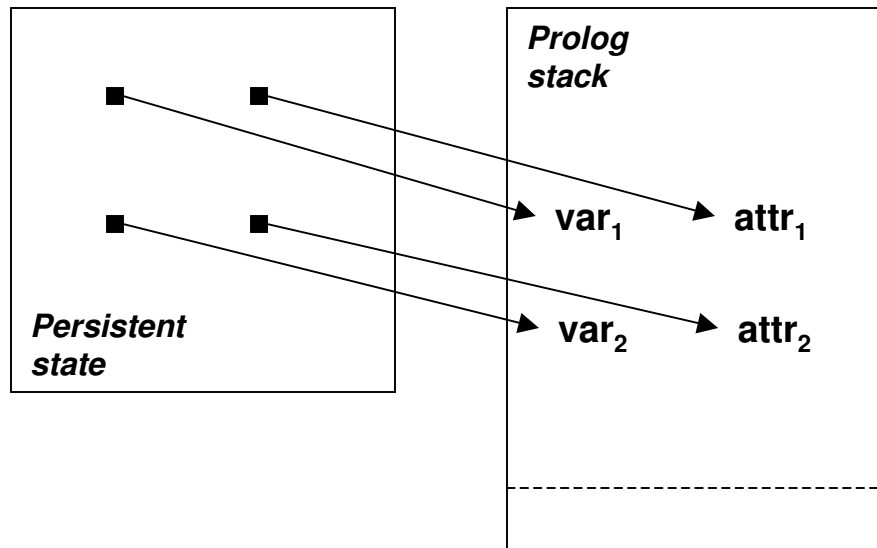


# Support for Stateful Constraints

- Global **term references**
  - explicitly allocated and deallocated
  - requires garbage collector support
  - dangling pointer hazard if used generally
- **Deallocation guaranteed**
  - on backtracking
  - on determinate entailment
  - both the memory block and the global term references

# Domain Variables in the Persistent State

- For each domain variable, we store
  - one term reference to the variable itself
  - one term reference to the attribute term
- Why?
  - Look up attribute term once only
  - Retain access to attribute even if the variable is ground



# Pruning in Global Constraints

```
clpfd:dispatch_global(+C,+S0,-S,-A)
```

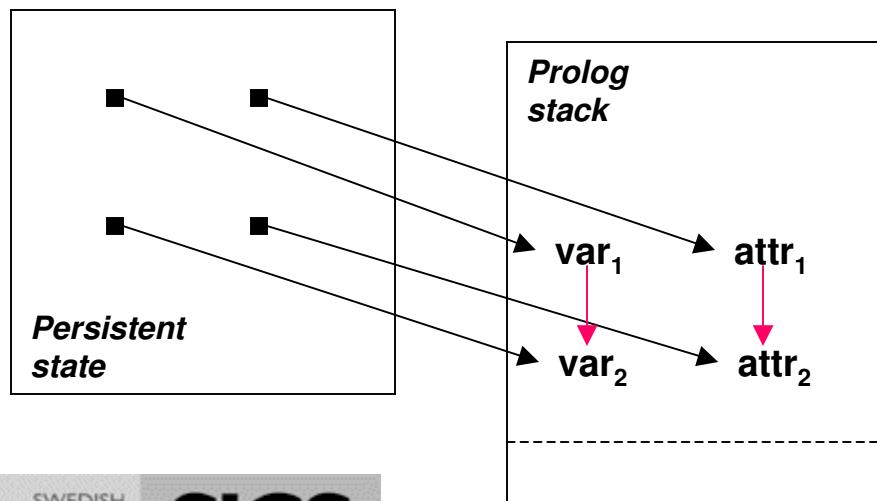
where  $A$  is a list of:

```
X in Domain, X in_set Set, X=Int, call(Goal), exit, fail
```

- Direct pruning *inside* filtering algorithm is not allowed.
- Three-phase pruning scheme:
  1. At entry, make local “copies” of the domain variables.
  2. The algorithm works with the local “copies”.
  3. At exit, results are posted by computing  $A$ .

# Handling Unification and Co-References

- Variable-variable unifications require:
  - forwarding one attribute to another
  - forming intersection of domains
  - forming union of suspensions
  - waking up relevant constraints
  - marking relevant constraints as having co-references
  - in C: dereferencing attributes as well as variables

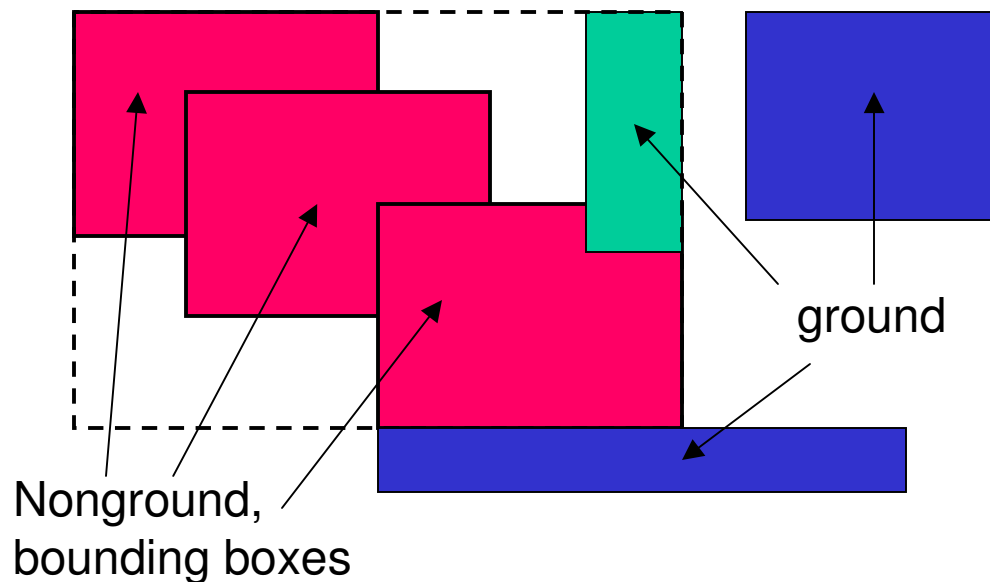


# Filtering Algorithms and Co-References

- Each filtering algorithms is assumed to reach a fixpoint if no domain variable occurs more than once.
  - The constraint normally does not wake itself up.
- If there are co-references, the solver will repeat the filtering algorithm until no more pruning.
  - The constraint wakes itself up.
  - domain variables occurring more than once initially
  - co-references introduced by unification

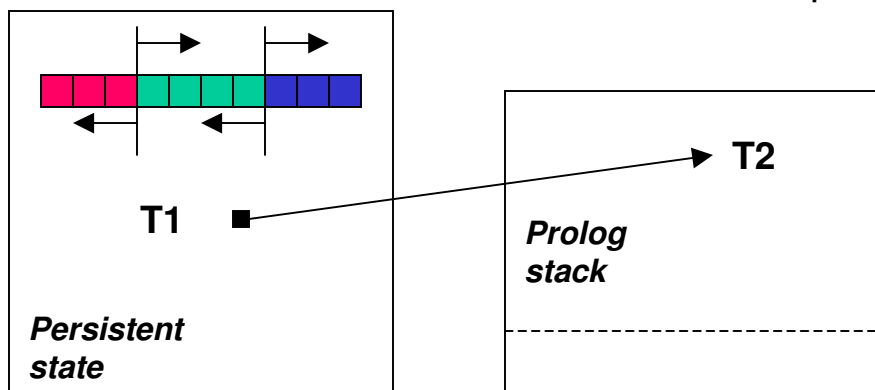
# Generic Optimization: Sources & Targets

- A **target** object is subject to pruning or check
- A **source** object can lead to some pruning or check
- **Inactive** objects can be ignored
- Speedup  $> 2.5$  observed for non-overlapping rectangles



# Generic Optimization: Incrementality

- If the current store is an extension of the previous one, then
  - ground/source/inactive objects stay so
- Otherwise,
  - recompute (part of) the persistent state
- If no choicepoints younger than the posting time of the constraint
  - ground/source/inactive objects stay so **forever**
- Detecting the incremental case:
  - timestamps:  $T_1$  in C,  $T_2$  in a **mutable term**,  $T_1 := T_2 := T_2+1$  at exit
  - the current store is an extension of the previous one if  $T_1=T_2$  at entry



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# A Finite Domain Constraint Tracer

- Provides:
  - tracing of selected constraints
  - naming of domain variables
  - Prolog debugger extensions (naming variables, displaying annotated goals)
- Default appearance (customizable):

```
scalar_product([0,1,2,3],[1,<list_2>,<list_3>,<list_4>],#=,4)
  list_2 = 1..3
  list_3 = 0..2 -> 0..1
  list_4 = 0..1
```

- Comes with SICStus Prolog 3.9

# Towards Better Debugging Tools

- Starting point: fine-grained execution trace
  - the DiSCiPI experience
- Drawbacks:
  - rough explanations (unary constraints)
  - flat sequence of low-level events
  - static information missing
    - the constraints themselves
    - the way constraints are woken
    - what kind of pruning constraints do
    - what kind of consistency the constraints achieve
    - what type of filtering algorithms they use
  - no means of considering subparts of global constraints to improve explanations
    - specific necessary conditions
    - specific methods used
    - implied constraints

# Prerequisites for Better Debuggers

- Static information about constraints
  - the way they are woken
  - what kind of pruning they do
  - what kind of consistency they achieve
  - details about the filtering algorithms they use
- Status information
  - status of constraints
    - e.g. suspended, entailed, failed
  - status of variables
    - e.g. infinite domain, finite domain, interval, ground
- Trace information
  - the events that occur during execution
  - **explanations** for these events
  - structured

# Towards Better Explanations

- Challenges:
  - record **multiple explanations** for each value removal compactly
  - give explanations in terms of **non-unary constraints**
  - give explanations in terms of **objects of the applications**

*“To fix this failure, you should modify the origin attribute of at least 3 tasks out of this set of 5 tasks.”*

- Uses:
  - non-chronological backtracking
  - focused explanations to the user
  - propose which constraints to relax to fix a failure
  - propose which constraints to relax or enforce in over-constrained problems

## Conclusion: what's crucial for a good CLP(FD) system

- Generic host language support
  - attributed variables, mutables, term and goal expansion
- A good foreign language interface
- Support for persistent foreign language state
  - do-on-backtracking, persistent term references
- Good debugging facilities
- Nicolas Beldiceanu
  
- The full story at:

<http://www.sics.se/sicstus>