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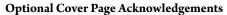
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Supporting Trajectory UDF Queries and Indexes on PostGIS



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Supporting Trajectory UDF Queries and Indexes on PostGIS

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Abstract: In this paper, we propose a system model for querying and indexing the GPS trajectory of moving objects on PostGIS/PostgreSQL. We developed moving object data types including MPoint(moving point), MDouble(moving double) for GPS trajectories. Also, various moving objects UDFs(user-defined functions) are implemented for moving objects queries. For efficient query processing, r-tree index is extended for trajectory, and pre-materialization techniques are proposed for fast UDF processing. Experimental results show that the pre-materialization techniques are about 1.2 times faster than nave query processing using r-tree index.

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Supporting Trajectory UDF Queries and Indexes on PostGIS

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Introduction

In this paper, we propose a system model for querying and indexing the GPS trajectory of moving objects on PostGIS/PostgreSQL.

We developed moving object data types including moving point, MDouble for GPS trajectories. Also, various moving objects UDFs are implemented for moving objects queries. For efficient query processing, r-tree index is extended for trajectory, and pre-materialization techniques are proposed for fast UDF processing.

Experimental results show that the pre-materialization techniques are about 1.2 times faster than naïve query processing using r-tree index.

Related Work

UDF(User Defined Function) approach have been used widely for developing advanced applications[1]. But, trajectory DBMS is not popular because of performance optimization [2].

Trajectories DBMSs

- DOMINO[3]
- HERMES[4]
- Trajectory Functions of PostGIS[5]

Trajectory UDF Queries by Examples Creation of Trajectory Table CREATE TABLE seed (test jid int, sed marries cher(20), test model cher(20), test driver cher(20)); SELECT addinglactorycolomin(public', 'texf', 'tref', 4326, 'MOVINGPOINT', 2, 150); Appending/Updating Trajectories ## Inserting Moving Objects insert into taxi values(1, '57MU2001', 'Optima', 'hongkd7'); insert into taxi values(2, '57NU2002', 'SonataYF, 'honokd7'); ## Appending and Updating GPS Trjaectories UPDATE tand SET traj = append(traj, 'MPOINT(100 100 5000, 150 150 5001)) WHERE text_id = 1; SET traj = remove(traj, 'PERIOD(5001, 5003)') WHERE taxi_id = 1; Retrieving Trajectories ## Spatial and Temporal Slicing SELECT along tool Transpoor 2011-02-20 17:13507, Transpoor 2011-02-20 ## Trajectory Predicates SELECT fact jid, if order traj, at geometry(NESQ17 6, 29 31)::box2d WHERE II, enter I test, GeomPromRest; POLYGON (15000, 18000, 30000 30000 15000 THROUGH, PERCON SORE, SORE YE ## Trajectory Functions SELECT taxi_jd, taxi_number, TJ_Traj(traj) tra(, TU_BOK(116.35, 39.93, 116.22, 40.14, PERIODS('2008-02-0213:30:44', '2008-02-0215:54:46'))); SELECT count(*) FROM tax WHERE TJ_Imide(traj, TJ_BOX(116.35, 39.93, 116.22, 40.14, PERIODS("2008-02-02 13:30:44", "2008-02-02 15:54:46"))); SELECT taxl_id, taxl_number FROM tax WHERETJ Cress(trai, tax) id. TJ BC00116.35,39.93, 116.22, 40.14. PERIODS("2008-02-02 13:30:44", "2008-02-02 15:54:46"))); SELECT wally, 🖦 (w., transferant 2011-02-20 17/12/07, transferant 2011-02-20 17/26/07) FROM tail

Trajectory Data Model on PostGIS

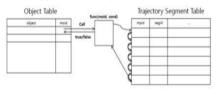
Trajectories are split into trajectory segment tables. And, metadata for trajectory objects are stored in a trajectory column table.



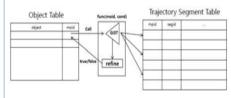
trajectory_column(Meta Table)				
Table_ catalog	Table_ schema		Trajectory_ column	Tpseg_size

Performance Optimization by Query Materialization

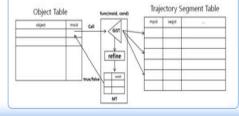
Naïve Approach: No Optimization



GiST Index Extension Approach for Trajectories

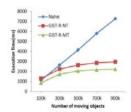


Query Materialization Approach

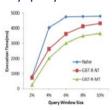


Performance Evaluation

• Time by number of trajectories



Time by guery window size



Conclusion and References

PostTrajectory: We developed a new system supporting trajectory queries on PostGIS using UDFs.

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PostTrajectory Project

nttp://github.com/awarematics/posttrajectory