

2011 IEEE/RSJ International Conference on Intelligent Robots and Systems  
September 25-30, 2011, Hilton San Francisco Union Square, San Francisco, CA, USA

## Commitment Statement

By uploading this manuscript I certify that

(1) the manuscript is submitted with the full knowledge and consent of all co-authors (if any), and that I will undertake to keep my co-authors informed of all correspondence about the manuscript.

(2) contents of this manuscript are original and it is not being considered simultaneously for consideration towards publication in another conference or journal.

I also understand that

(1) by submitting my manuscript through the RAS conference paper management system, I am permitting the RAS society access to my contact information and research interests. I agree that this data may only be used by the RAS designated users to contact me regarding future events sponsored by the society and to assist its editorial board to identify qualified reviewers for peer review of submissions to its conferences.

(2) if my manuscript is accepted by the conference, I or one of my co-authors or colleagues will attend the conference to present the paper and will comply with the conference registration policy.

(3) failure to comply with above may lead to the Robotics and Automation Society preventing me and my co-authors from submitting manuscripts to future events.

*Joern Vogel*, March 27, 2011

Submission number 1054  
*EMG-Based Teleoperation and Manipulation with the DLR LWR-III*  
by Joern Vogel and Claudio Castellini and Patrick van der Smagt