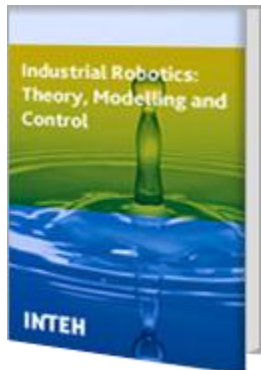


Industrial Robotics: Theory, Modelling and Control



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This book covers a wide range of topics relating to advanced industrial robotics, sensors and automation technologies. Although being highly technical and complex in nature, the papers presented in this book represent some of the latest cutting edge technologies and advancements in industrial robotics technology. This book covers topics such as networking, properties of manipulators, forward and inverse robot arm kinematics, motion path-planning, machine vision and many other practical topics too numerous to list here. The authors and editor of this book wish to inspire people, especially young ones, to get involved with robotic and mechatronic engineering technology and to develop new and exciting practical applications, perhaps using the ideas and concepts presented herein.

Table of Contents

1. [Robotic Body-Mind Integration: Next Grand Challenge in Robotics](#)
K. Kawamura, S. M. Gordon and P. Ratanaswasd
2. [Automatic Modeling for Modular Reconfigurable Robotic Systems: Theory and Practice](#)
I-Ming Chen, Guilin Yang and Song Huat Yeo

3. [Kinematic Design and Description of Industrial Robotic Chains](#)
Peter Mitrouchev
4. [Robot Kinematics: Forward and Inverse Kinematics](#)
Serdar Kucuk and Zafer Bingul
5. [Structure Based Classification and Kinematic Analysis of Six-Joint Industrial Robotic Manipulators](#)
Tuna Balkan, M. Kemal Ozgoren and M. A. Sahir Arikan
6. [Inverse Position Procedure for Manipulators with Rotary Joints](#)
Ibrahim A. Sultan
7. [Cable-based Robot Manipulators with Translational Degrees of Freedom](#)
Saeed Behzadipour and Amir Khajepour
8. [A Complete Family of Kinematically-Simple Joint Layouts: Layout Models, Associated Displacement Problem Solutions and Applications](#)
Scott Nokleby and Ron Podhorodeski
9. [On the Analysis and Kinematic Design of a Novel 2-DOF Translational Parallel Robot](#)
Jinsong Wang, Xin-Jun Liu and Chao Wu
10. [Industrial and Mobile Robot Collision-Free Motion Planning Using Fuzzy Logic Algorithms](#)
Tzafestas S. G. and Zavlangas P.
11. [Trajectory Planning and Control of Industrial Robot Manipulators](#)
S. R. Munasinghe and Masatoshi Nakamura
12. [Collision Free Path Planning for Multi-DoF Manipulators](#)
Samir Lahouar, Said Zegloul and Lotfi Romdhane
13. [Determination of Location and Path Planning Algorithms for Industrial Robots](#)
Yung Ting and Ho-Chin Jar
14. [Homogeneous Approach for Output Feedback Tracking Control of Robot Manipulators](#)
Luis T. Aguilar
15. [Design and Implementation of Fuzzy Control for Industrial Robot](#)
Muhammad Suzuri Hitam
16. [Modelling of Parameter and Bound Estimation Laws for Adaptive-Robust Control of Mechanical Manipulators Using Variable Function Approach](#)
Recep Burkan

17. [Soft Computing Based Mobile Manipulator Controller Design](#)
Abdessemed Foudil and Benmahammed Khier
18. [Control of Redundant Robotic Manipulators with State Constraints](#)
Mirosław Galicki
19. [Model-Based Control for Industrial Robots: Uniform Approaches for Serial and Parallel Structures](#)
Houssem Abdellatif and Bodo Heimann
20. [Parallel Manipulators with Lower Mobility](#)
Raffaele Di Gregorio
21. [Error Modeling and Accuracy of Parallel Industrial Robots](#)
Hongliang Cui and Zhenqi Zhu
22. [Networking Multiple Robots for Cooperative Manipulation](#)
M. Moallem
23. [Web-Based Remote Manipulation of Parallel Robot in Advanced Manufacturing Systems](#)
Dan Zhang, Lihui Wang and Ebrahim Esmailzadeh
24. [Human-Robot Interaction Control for Industrial Robot Arm through Software Platform for Agents and Knowledge Management](#)
Tao Zhang, Vuthichai Ampornaramveth and Haruki Ueno
25. [Spatial Vision-Based Control of High-Speed Robot Arms](#)
Friedrich Lange and Gerd Hirzinger
26. [Visual Control System for Robotic Welding](#)
De Xu, Min Tan and Yuan Li
27. [Visual Conveyor Tracking in High-Speed Robotics Tasks](#)
Theodor Borangiu
28. [Visual Feedback Control of a Robot in an Unknown Environment \(Learning Control Using Neural Networks\)](#)
Xiao Nan-Feng and Saeid Nahavandi
29. [Joystick Teaching System for Industrial Robots Using Fuzzy Compliance Control](#)
Fusaomi Nagata, Keigo Watanabe and Kazuo Kiguchi
30. [Forcefree Control for Flexible Motion of Industrial Articulated Robot Arms](#)
Satoru Goto
31. [Predictive Force Control of Robot Manipulators in Nonrigid Environments](#)
L.F. Baptista, J.M.C. Sousa and J.M.G. Sa da Costa

32. [Friction Compensation in Hybrid Force/Velocity Control for Contour Tracking Tasks](#)
Antonio Visioli, Giacomo Ziliani and Giovanni Legnani
33. [Industrial Robot Control System Parametric Design on the Base of Methods for Uncertain Systems Robustness](#)
Alla A. Nesenчук and Victor A. Nesenчук
34. [Stochastic Analysis of a System Containing One Robot and \(n-1\) Standby Safety Units with an Imperfect Switch](#)
B.S. Dhillon and S. Cheng