

EXTRACTION OF LINES AND REGIONS
FROM GREY TONE LINE DRAWING IMAGES*

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Tech Report #CS830008

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June 26, 1983

Abstract. An algorithm is described for extracting lines from grey level digitizations of industrial drawings. The algorithm is robust, non iterative, and sequential, and includes procedures for differentiating shaded areas from lines. Examples are given for complex regions of a typical mechanical drawing.

Key words: adaptive thresholding, grey tone intensity surface, line drawing, line extraction, line tracker, region extraction, region growing.

*This work was supported by Control Data Corporation Grant 82V101.

1. INTRODUCTION

There are many applications such as mapping, drafting, image compression, and computer vision that require robust algorithms for extracting lines and boundaries from images. While a very substantial effort has been made to solve that problem under the adverse image conditions typical in computer vision applications, most popular techniques have many computational disadvantages when image conditions are good. When there is no need to be concerned with serious line fragmentation due to noise, it is possible to deal more directly with the problems of line drawing semantics, including curvature, endpoints, junctions, intersections, variable width, smoothness, straightness, and problems of approximation and encoding.

The particular application that motivated the work reported here is the problem of converting industrial line drawings from hard copy into highly compressed graphical representations involving a small number of primitives such as lines, curves, and regions. This problem vanishes when electronic drafting systems are used to generate the original drawings. However, the reality is that many technical drawings are still created and communicated on paper, and relatively little use is being made of electronically stored representations. As a consequence, revision and updating is difficult to do, and field documentation of large, high-technology systems such as aircraft, space vehicles, buildings, and computers all too frequently consists of containers, files, or even entire rooms

full of hard copy reproductions.

The algorithms described in this paper make use of grey level digitizations rather than binary digitizations to maximize the amount of image information available to the interpretation procedures and to minimize the intelligence required of the sensors themselves. The resolution is high, and the images are assumed to be large - at least 1024 by 1024 picture elements. No attempt is made to repair poorly executed drawings. Because of the large data volume and in order to facilitate processing on inexpensive microcomputers, the use of iterative algorithms, including grey level and binary thinning, is precluded, and every possible attempt is made to make processing sequential by scan line. It is also assumed that the line drawings to be processed may contain small, solid, shaded (not textured) regions or regions of parallel adjacent lines too fine to resolve individually. Before presenting specific algorithms, a review of some of the existing approaches for extracting lines from high-contrast digitizations is given.

Currently there are a number of systems for the extracting and encoding of line structured data. These systems frequently contain dedicated hardware such as fast optical scanners that do fast local raster scanning of image data. Black et. al.(1) discuss a general purpose follower for line structured data which is table driven using a PEPR flying spot scanner. Fulford et. al.(2) describe the FASTRAK system, which is an interactive line following digitizer, scanning a reduction of a

map with a laser beam. The system depends upon human interaction and intervention. SysCan, a system described by Leberl et. al. (3), features KartoScan, a raster scanner using white light and a CCD array sensor. It is an operational automated system which converts maps and drawings into digital format, and the digital data is edited, stored, retrieved and generally manipulated.

Holdermann et. al. (4), Peleg et. al. (5), Ting et. al. (6), Wang et. al. (7) and Weszka (8) describe general preprocessing techniques such as thresholding and other forms of filtering applied to binary and gray tone images.

Complete systems for the extraction of line structured data from binary and gray scale images are described in the literature. A coding method for the vector representation of engineering drawings is discussed by Ramachandran (9). This algorithm does not distinguish between lines and regions, and moreover, the final form of extracted information, which is an approximation, is not suitable for parametric representation (by splines, for example). Compression ratios of about 35:1 were achieved, which are not very satisfactory for line drawings. Woetzel (10) describes an automatic method for the scanning of cartographic maps and extracting the linework. The method only works on binary images and uses a fast thinning algorithm which may distort the line structure (this is not very critical for maps). Furthermore regions cannot be extracted. Dudani (11) describes a contour following algorithm

that can be adapted as a line following algorithm. However, the algorithm does not handle thick lines.

The paper by Freeman (12) is a good tutorial on line drawings and also explains the concept of chain codes. Graham (13) and Huang (14) discuss methods for digital transmission. Maxwell (15) attempts to evolve natural descriptors for line drawings for efficient human-computer communication in the domain of computer graphics. Watson et. al. (16) describe a method for the topographic labelling of gray scale image characteristics such as peaks, ridges, valleys, etc., which can be applied to line drawings.

This paper describes a system which extracts the linework and solid regions from large gray tone images of line drawings using non iterative fast algorithms with minimal storage requirements.

2. ALGORITHMS

A large digitized image produced by a collimated white light scanner was initially blurred by a Gaussian filter and then resampled at every other pixel (2:1 sampling) to produce the input image that was used to develop the algorithms. This image (see Figure 1a) was of size 1024 by 1024, and consisted of thin and thick lines and a few regions with a uniform gray tone value except at the borders. The gray tone intensity surface of a line was ridge-like from the Gaussian filtering. The gray tones in the image ranged from 0 to 255 in value, and average

line intensities varied in different parts of the image. Line separation was as low as one pixel in some portions of the image, and the valleys that separated these close lines had gray tone values in between those of the lines and the zero background.

DOUBLE ADAPTIVE THRESHOLDING

Because of the small differences in height between valleys and ridges and variation in average intensities over the image, simple thresholding using a single cutoff value fails to resolve all the lines and suggests the use of local adaptive thresholding. A good local characteristic is the average of pixel values in a neighborhood centered around the pixel being tested. Thresholding can be described as determining which are the object pixels (typically represented by ones in the output image) and which are the background pixels (represented by zeros in the output image). A strategy whereby the threshold cutoff was computed by multiplying some constant times the average gray tone over a square n by n window centered at the current pixel produced very good results. Decreasing the window size has the effect of increasing the resolution, making the thresholding more sensitive to local features. Since low background pixel values have the effect of depressing the computed average, thereby diluting large peaks, only those pixels in the neighborhood which are greater than a certain low threshold are used in the computation of the average. This lower threshold is chosen to be slightly higher than the

background pixel values. Thus there are two thresholds, the upper threshold which is computed by multiplying the window average by a cutoff factor, and the lower threshold--hence the name double adaptive thresholding. By choosing a value slightly greater than one for the cutoff factor, only the ridgeline pixels of the convex ridges have values more than the computed cutoff and therefore appear in the output as object pixels. Region pixels do not pass the thresholding condition because of the flat nature of the regions. Here we make a small modification of the algorithm. Pixels which do not pass the thresholding condition but which are greater than a certain region threshold (chosen to be consistent with region pixel values) are marked as region pixels in the output.

Thresholding that normally produces a binary image does not produce lines exactly one pixel thick, making line tracking rather difficult. One course of action would be to thin the binary image produced by the thresholding. A large variety of thinning algorithms are described in the literature, each has its own flavor from the point of view of the accuracy and aesthetic appeal of the skeletons they produce from the original binary image. Often the result is unappealing, as for example when curved lines are reduced to thin jagged lines. The problem is not with the thinning, but with the fact that once we create a binary image from thresholding, the information contained in gray tones of the original image is lost and no distinction can be made between weak and strong object pixels which are all ones. Hence, in the double adaptive thresholding

algorithm, all pixels which are above their computed cutoff values (i.e., the object pixels) are represented in the output by their original gray tone values. Region pixels are represented by the negative of their original gray tone values. The reason for retaining the gray tone values for region pixels will be apparent later when we describe region pruning.

The double adaptive thresholding algorithm (DAT) works well for lines when their gray tone intensity surfaces have a convex ridge shape, which can be artificially produced by Gaussian filtering, local averaging, or other known blurring techniques. The DAT algorithm is given below.

```

n := 3 (* window size *)
factor := 1.063
region_threshold := 200
low_threshold := 6
avg := average of all pixel values
      > low_threshold in an n by n
      neighborhood of the current
      pixel
cur_pixel := current input pixel
            value
out_pixel := current output pixel
            value

IF cur_pixel <= ( avg * factor )
THEN IF cur_pixel > region_threshold
      THEN out_pixel := ( -cur_pixel )

```

```

ELSE out_pixel := 0
ELSE out_pixel := cur_pixel.

```

REGION DETERMINATION

The DAT, though it handles regions well, has the effect of marking some stray pixels as region pixels. In addition, there may also be holes at the boundaries of the regions. In the next two steps, called 'growing' and 'shrinking', stray region pixels are eliminated and small holes in the regions are filled. Both these steps are based on the connectivity of region pixels. In the 'growing' operation each non-zero non-region pixel is marked as a region pixel if more than $k=2$ of its eight neighbors are region pixels. This has the effect of filling up small holes and growing the regions. Stray region pixels are not affected because of their low region connectivity. In the 'shrinking' operation, which is complementary to and follows the 'growing' operation, a region pixel is changed to a non-region pixel if less than $k=4$ of its eight neighbors are region pixels. Stray region pixels are converted to non-region (i.e., line) pixels in this operation. The two steps described above which constitute region determination are shown below.

```

n := 3          (* window size *)
cur_pixel := current input pixel value
out_pixel := current output pixel value
num_neg := number of negative neighbors
           in an n by n neighborhood of

```

the current pixel not counting
the current pixel.

```
const1 := 3
```

```
const2 := 4
```

Grow:

```
IF num_neg >= const1 AND cur_pixel > 0  
THEN out_pixel := ( -cur_pixel ) (* region *)  
else out_pixel := ( cur_pixel ).
```

Shrink: (* with output of Grow as input *)

```
IF cur_pixel < 0 AND num_neg >= const2  
THEN out_pixel := cur_pixel (* region *)  
ELSE out_pixel := abs ( cur_pixel )
```

REGION EXTRACTION

The region determination step is followed by region extraction and line extraction. The regions can be represented by following and encoding their contours. Dudani (11) describes a method for region extraction using boundary following. Alternatively, simple run length coding or one of its more complex variations could be used. Such schemes work well because of good correlation of pixel runs between adjacent scan lines in the regions.

LINE EXTRACTION

Using a simple thinning algorithm to reduce the line width to one pixel followed by a simple line tracker is

unsatisfactory for the reasons given above. A more complicated line tracker which tracks the ridges of the gray tone intensity surfaces of the lines is described below in two steps.

1) Finding the starting pixel for a new line.

The image is scanned from left to right and top to bottom. Thus, line by line each pixel is examined to check whether it is a candidate for starting a line. The following conditions must be satisfied by an unmarked pixel (called the candidate pixel) in order to be a starting point of a line:

- a) Its value is more than a certain threshold to indicate which pixel values are background and which are not.
- b) Its value is more than a factor (a good value is 0.7) times the average of its non-zero marked or unmarked eight neighbors. (When a pixel is tracked it is marked.)
- c) Its value is more than a factor (0.9) times the average of its marked eight neighbors. This condition ensures that the pixel is strong compared to nearby tracked vectors.
- d) Let pixel P1 be the unmarked, untested eight neighbor of the candidate pixel with maximum gray tone value. This selection implies a probable direction for a new line. Directions of the eight neighbors with respect to the candidate pixel are labeled as follows:

Let d be the direction of P_1 with respect to the candidate pixel. P_1 must also satisfy conditions a) through c).

- e) Let P_{11} , P_{12} , P_{13} be the neighbors in the directions $d-1$, d , $d+1$ (modulo 8) respectively from P_1 . At least one of these pixels P_{1j} must not be marked, must not have a marked eight neighbor in the directions $s-1$ and $s+1$ from P_1 (s is the direction of P_{1j} from P_1), and must satisfy conditions a) through c). Otherwise consider P_1 tested, and attempt to satisfy d) and e) with a different P_1 , until all possibilities have been tested.

If conditions a) through e) are satisfied by the candidate pixel, then it is marked along with P_1 and the line tracker is invoked to continue tracking from pixel P_1 .

2) Tracking a line .

Let P_1 represent the previously marked pixel, P_2 the current marked pixel, and P_3 the next pixel sought by the line tracker. Let d_1 be the direction to P_1 from the pixel marked prior to P_1 , d_2 the direction from P_1 to P_2 , and d_3 the direction from P_2 to P_3 . From among the unmarked neighbors of P_2 in the directions d_2-2 (mod 8), d_2-1 (mod 8), d_2 , d_2+1 (mod 8), d_2+2 (mod 8), P_3 is chosen as the pixel (if it exists) with maximum gray tone value. P_3 is marked if it satisfies the conditions:

- a) P3's gray tone value is greater than a certain threshold which is slightly more than typical background values.
- b) P3 has no marked eight neighbors in the directions $d3-1 \pmod{8}$ and $d3+1 \pmod{8}$ from P2.
- c) $\min \{ \text{abs}(d3-d1), 8-\text{abs}(d3-d1) \} \leq 2$.

If P3 does not exist or does not satisfy conditions a) through c), then the current vector is terminated and a starting pixel for the next line is sought. If no such pixel is found, the line tracker is terminated.

The algorithm for the line tracker is shown below.

```

STEP 1. Determination of the starting point.

cur_pix := current pixel
VALUE ( cur_pix ) := value of current pixel
cur_val := VALUE ( cur_pix )
n := 3 (* window size *)
avg_marked := average of all the marked pixel
              values in an n by n neighborhood
              of the current pixel
avg_nonzero := average of all the non-zero
              pixel values in an n by n
              neighborhood of the current pixel
cutoff1 := 0.9 * avg_marked
cutoff2 := 0.7 * avg_nonzero
CUTOFF ( cur_pix ) := MAX ( 50, cutoff1, cutoff2 )

IF cur_pix is not marked AND

```

```
cur_val > CUTOFF ( cur_pix )
THEN WHILE ( some unmarked neighbor of cur_pix
            not tested ) DO

    BEGIN

        temp_pix := unmarked, untested neighbor of
                    cur_pix with maximum value

        temp_val := VALUE ( temp_pix )

        IF temp_val > CUTOFF ( temp_pix )
        THEN
            BEGIN

                cur_dir := direction from cur_pix to
                        temp_pix

                pix1 := pixel in dir. cur_dir-1 from temp_pix
                pix2 := pixel in dir. cur_dir from temp_pix
                pix3 := pixel in dir. cur_dir+1 from temp_pix

                IF VALUE ( pix1 ) > CUTOFF ( pix1 ) AND pix1
                    not marked AND pix1 has no adjacent
                    marked neighbors (* adjacent means
                    in the direction from temp_pix +1
                    or -1 *)
                OR VALUE ( pix2 ) > CUTOFF ( pix2 ) AND pix2
                    not marked AND pix2 has no adjacent
                    marked neighbors
                OR VALUE ( pix3 ) > CUTOFF ( pix3 ) AND pix3
                    not marked AND pix3 has no adjacent
                    marked neighbors
            THEN mark cur_pix, temp_pix, and call tracker
```

```
END
ELSE designate temp_pix as tested
END (* WHILE *)

STEP 2. Tracking the vector.

cur_dir := current direction
prev_dir := previous direction
threshold := 50
next_pix := unmarked neighbor in direction d from
             cur_pix, abs ( d-cur_dir (mod 8) ) <= 2,
             with maximum value.

IF next_pix exists
THEN
BEGIN
    next_dir := direction from cur_pix to next_pix
    next_val := VALUE ( next_pix )
END
ELSE next_val := 0
IF next_val > threshold AND
    abs ( next_dir-prev_dir (mod 8) ) <= 2 AND
    neighbors of next_pix in directions
    next_dir-1, next_dir+1 from cur_pix are not
    marked
THEN
BEGIN
    mark next_pix
    cur_pix := next_pix
```



```
    prev_dir := cur_dir
    cur_dir := next_dir
    continue tracking the current vector
END
ELSE
BEGIN
    terminate tracking the current vector
    determine the starting point of next vector
END.
```

The line tracker, in addition to marking the pixels in the image, also outputs the new chain code or absolute coordinates of the pixels. The output format depends on the user's requirements. Skiansky et. al. (17) discuss a method for fast polygonal approximation of the pixels as the pixels are being tracked. With their scheme a straight line would be represented by its two end points.

3. RESULTS

Fig. 1a shows one of the images used for testing the algorithms. Fig. 1b shows a close up view of the spool of wire in the same image. This is the most crucial part of the image since the line separation here is very low, and the lines merge at the edge of the coil to form textured regions. The image shown in Fig. 1a is large, nearly 2048 by 2048 pixels. The lines are sparse in most of the image except in the spool of wire. The 1024 by 1024 test image (to which the algorithms

were applied) was obtained by blurring the original image using a Gaussian filter of standard deviation 1.3, and then resampling the filtered image at every other pixel. Compression ratios higher than 2:1 cause Moire patterns in the spool of wire, attributed to the classical problem of aliasing.

The test image corresponded very closely with what would have been produced by some industrial imaging hardware already in place. The larger image was taken as the starting point simply for the purposes of comparison and testing.

Fig. 2a displays the gray tone values of a portion of the spool of wire, where the upper portion resembles a "bobbin". Note the presence of a considerable amount of noise, some of which was present in the original image, and the rest was added by the filtering. A well known iterative sharpening algorithm EHNUM (19) (an iterative algorithm which replaces each pixel's gray tone value by the nearest of the max or min of its eight neighbors' gray tone values) was applied to this noisy image. The result is illustrated in Fig. 2b. Although the image in Fig. 2b does have a cleaner, sharper appearance, the lines are now rather jagged because the gray tone values of many insignificant pixels have now been raised. There is a more serious defect, namely, although there are only two vertical lines at the top in the input image Fig. 2a, the sharpening algorithm EHNUM has found three.

Fig. 3 shows the result of applying the topographic labeling algorithm (16) to the image in Fig. 2a. The algorithm fits a

two-dimensional cubic polynomial to the gray tone values in a square 5 by 5 window (this window size can be changed) centered around each pixel. This polynomial represents a surface which best fits, in a discrete least squares sense, the pixel data in the window. The topography of the surface at the position of the central pixel is now determined using partial derivatives of the polynomial. By tuning threshold parameters in the algorithm a good representation of the ridges was obtained.

Fig. 4a shows a dense part of the coil. The lines are not well resolved and there is a lot of noise between the lines. The topographic labeling algorithm was applied to this image with the same parameter values that were used to obtain the image in Fig. 3 (see Fig. 4b). The detection of the gray tone surface ridges, which clearly exist in Fig. 4a, is obviously extremely poor in Fig. 4b. This illustrates the sensitive nature of the algorithm to the threshold parameter values, making it unsuitable for the present application.

The DAT was used with very good results on the image in Fig. 4a. Fig. 5 shows this result, in which the lines have been accentuated very well. The negative pixels represent the regions on which the GROW and SHRINK algorithms were applied to finally get the regions shown in Fig. 6. These extracted regions were quite consistent with the perceived regions in the original unprocessed image.

The line tracker was now applied to the image in Fig. 5 after the regions (shown in Fig. 6) had been removed. Pixels which the line tracker marked are shown with negative values in Fig. 7. For further illustration, the same tracked image is shown in Fig. 8, but with asterisks used to indicate the pixels marked by the tracker. Observe that the tracked lines very faithfully represent the lines in the original unprocessed image.

4. CONCLUSION.

The difficulties associated with real digitized line drawing images, as opposed to artificially generated images, are significant. Many papers on line drawings have used binary images as their starting point, but the present work shows that producing a good binary image from a real digitized gray tone image is highly nontrivial. Any practical production algorithm must clearly begin with noisy gray tone images. Standard thinning, sharpening, and medial axis transformations were tried, and (despite occasional exemplary performances) none were found to be uniformly good.

For certain industrial applications it may not be practical or economic to connect the imaging equipment to mainframe computers with high speed transmission lines. Thus the low level processing (extraction of the lines and regions) must be done with limited local compute power and storage. The DAT algorithm presented here meets these requirements by being reasonably cheap and non iterative, although several sequential

passes through the image are required. Numerous experiments on different types of line drawings also strongly suggest that a good algorithm must be adaptive, and the adaptive nature of the DAT is crucial to its success.

The overall problem being addressed here for real digitized gray tone images of line drawings consists of (1) recognition and extraction of lines and solid regions (textured regions are not considered), (2) the compression and transmission of the line and region data, and (3) the high level representation (e.g., as graphics primitives) of the line drawing (lines, curves, regions). This paper represents a solution to (1) requiring only limited local compute power and storage. The next goals are an economic solution to (2) using slow transmission speeds (300 baud), and a powerfull and sophisticated high level encoding of the line drawing as graphical primitives in, e.g., CDC's TUTOR system.

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LIST OF FIGURE CAPTIONS

- Figure 1a. Original image.
- Figure 1b. Close up of coil section of original image.
- Figure 2a. Bobbin, after filtering and sampling, before DAT.
- Figure 2b. Result of sharpening operator EHNUM on bobbin.
- Figure 3. Topographic labelling of bobbin, where 1=flat, 2=convex hillside, 3=concave hillside, 4=saddle hillside, 5=slope, 6=ridge, 7=peak, 8=ravine, 9=pit, 10=saddle, 11=inflection point.
- Figure 4a. Coil, after filtering and sampling, before DAT.
- Figure 4b. Topographic labelling of coil, where 1=flat, 2=convex hillside, 3=concave hillside, 4=saddle hillside, 5=slope, 6=ridge, 7=peak, 8=ravine, 9=pit, 10=saddle, 11=inflection point.
- Figure 5. Result of double adaptive threshold (DAT) algorithm on coil.
- Figure 6. Regions extracted from coil.
- Figure 7. Output of line tracker on coil (shown with regions removed).
- Figure 8. Same as Figure 7 but with tracked lines marked by asterisks.

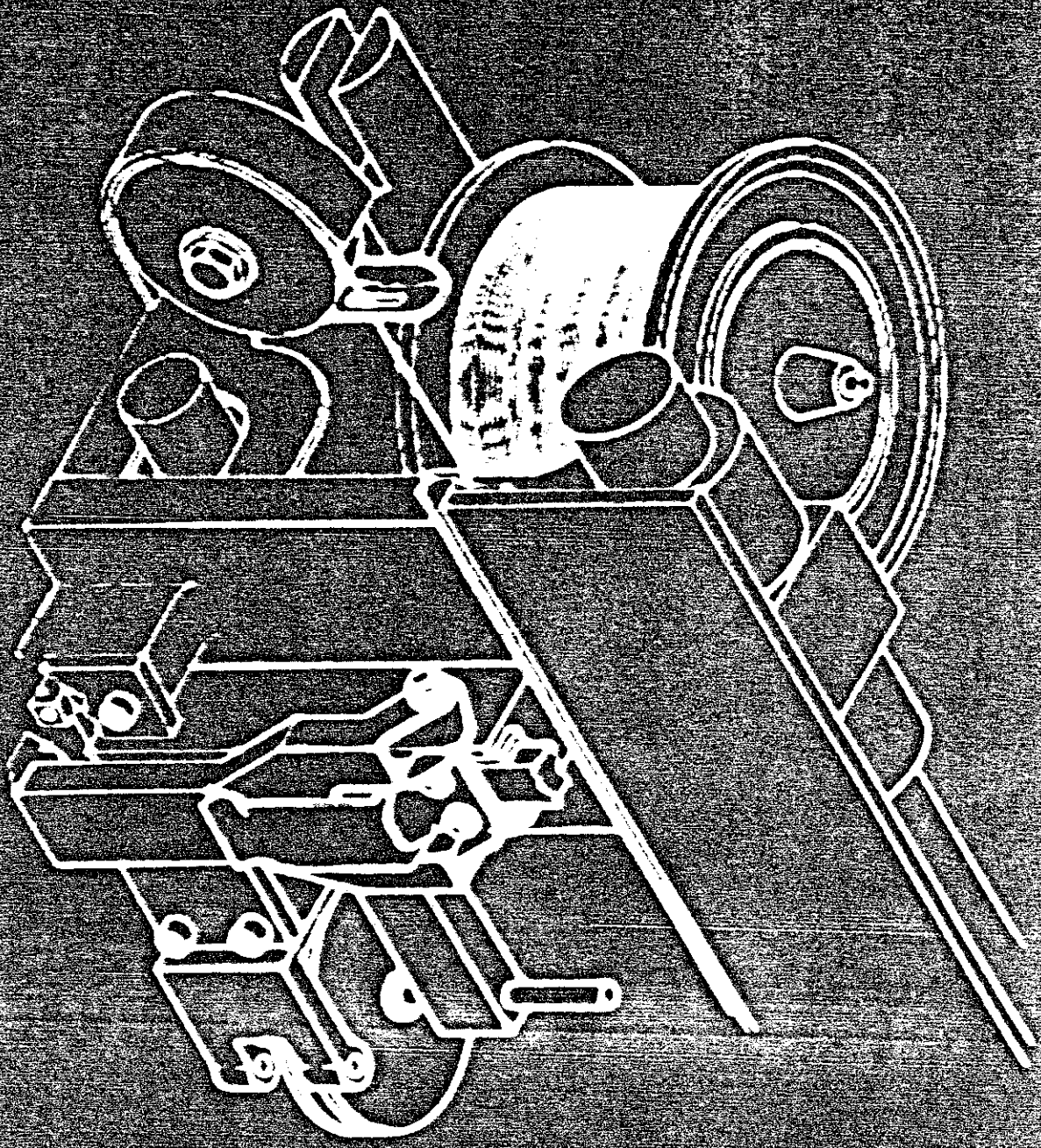
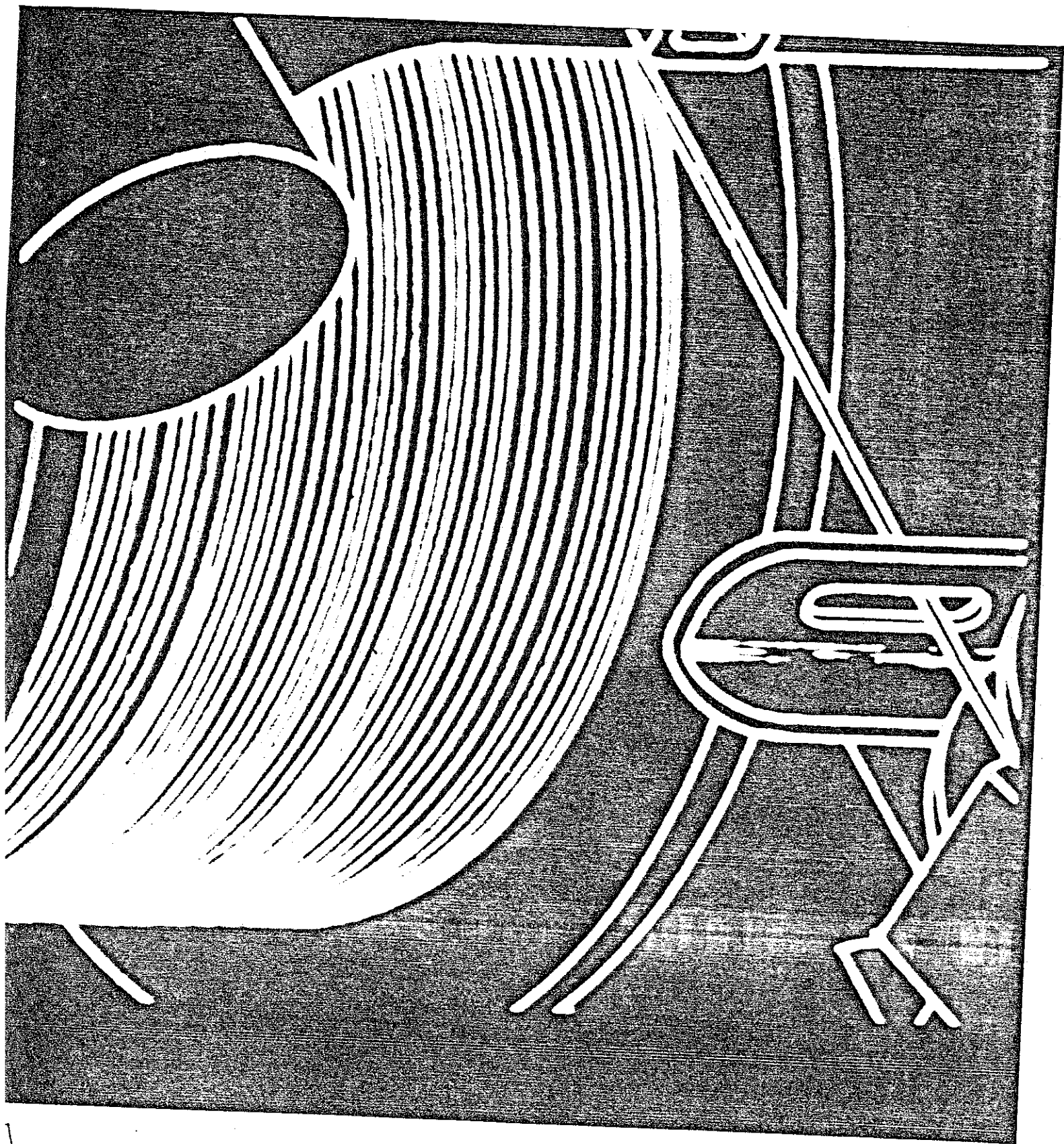


Fig. 10



0	0	0	0	0	5	93	78	12	20	49	6	0	0	0	0	0	0	0
0	0	0	0	0	4	86	77	6	24	72	10	0	0	0	0	0	0	0
0	0	0	0	0	4	81	71	5	26	82	12	0	0	0	0	0	0	0
0	0	0	0	0	4	75	51	16	36	107	19	0	0	0	0	0	0	0
0	0	0	0	0	4	74	58	11	36	129	26	0	0	0	0	0	0	0
0	0	0	0	0	4	78	67	34	35	89	16	0	0	0	0	0	0	0
0	0	0	0	0	4	80	67	78	41	53	6	0	0	0	0	0	0	0
0	0	0	0	0	5	89	84	92	51	62	8	0	0	0	0	0	0	0
0	0	0	0	0	5	91	101	118	59	85	14	0	0	0	0	0	0	0
0	0	0	0	0	4	84	88	125	61	92	16	0	0	0	0	0	0	0
0	0	0	0	0	4	71	64	130	66	95	14	0	0	0	0	0	0	0
0	0	0	0	0	3	57	53	127	62	78	10	0	0	0	0	0	0	0
0	0	0	0	0	3	46	47	136	64	85	10	0	0	0	0	0	0	0
0	0	0	0	0	4	74	71	147	69	104	16	0	0	0	0	0	0	0
0	0	0	0	0	5	87	91	151	70	107	17	0	0	0	0	0	0	0
0	0	0	0	0	5	95	106	155	72	109	16	0	0	0	0	0	0	0
0	0	0	0	0	5	88	103	153	74	129	23	0	0	0	0	0	0	2
0	0	0	0	0	5	90	106	159	76	143	28	0	0	0	0	0	1	31
0	0	0	0	0	5	95	112	162	75	135	25	0	0	0	0	0	22	138
0	0	0	0	0	5	94	107	164	75	129	23	0	0	0	12	101	218	
5	0	0	0	0	5	93	100	163	77	139	26	0	1	15	97	209	187	
84	14	2	0	0	5	99	109	166	78	143	27	1	21	105	214	201	74	
202	122	60	17	3	7	106	115	168	85	144	30	33	132	221	199	79	9	
120	181	200	145	74	46	145	131	179	117	174	98	165	227	186	73	9	10	
9	41	125	195	208	192	221	189	219	204	237	227	224	147	48	8	24	105	
1	1	13	44	107	176	223	238	245	242	235	193	102	25	9	44	142	222	
32	6	1	1	7	30	74	113	125	116	94	41	12	31	100	191	225	164	
171	100	42	14	3	1	3	5	6	6	10	26	72	168	222	201	114	32	
166	205	196	141	77	32	21	24	33	49	109	171	214	204	130	56	10	1	
25	76	158	208	211	183	165	172	194	210	233	216	152	66	12	2	0	0	
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0	0	0	0	0	255	253	0	0	0	0	0	0	238	233	245	243	251	248
0	0	0	0	0	0	0	0	0	0	0	0	0	0	240	253	255	255	255
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	248	255	255	255
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	216	252	255	255
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	233	206	238	254
0	0	0	0	0	0	0	0	0	0	253	233	0	223	238	224	249	255	0

Fig. 6

-192-204	0	0	145-215	0	0-154-204	0	0-187	0	0-214	185	0		
0	0-214	0	0	0-209	0	0	158-194	0	0-195	0	0-222	0	
-223	0	0-214	176	0	0-207	156	0	152-191	0	0-190	0	0-221	
0-220	0	0-217	181	0	0-206	152	0	158-164	0-192	0	0	198	
0	0-226	209	0-216	182	0	0-201	0	0	175-196	0-235	0	0	
205-213	212	0	0	0-224	185	0	0-205	0	0	195-242-243	232	0	
0	199-233	0	0	0	207-210	162	0	0-211	0	0	215	240-249	208
0	0	182-228	0	0	0	0-209	0	0	0-209	0	0	230-254	244
177	0	0	163-231	0	0	0	0-227	188	0	0-212	0	0	242-254
-182-192	0	0	0-232	0	0	0	0-240	0	0	0-215	0	0	249
0	152-210	0	0	0-227	0	0	0	0-228	190	0	187-202	0	215
0	0	140-212	149	0	0-230	0	0	0	0-224	0	0-208	0	0
184	0	0	0-199	162	0	0-224	0	0	0	0-227	0	0-224	0
-197-200	0	0	0-200	186	0	0-225	0	0	0	0	0	0	0
0	172-202	0	0	0-203	194	0	0-230	0	0	0	0	0	0
0	0	144-212	143	0	0-195	192	0	0-229	0	0	0	0	0
-208	0	0	0-208	166	0	0-196	178	0	0-235	0	0	0	0
0-221	156	0	0-211	177	0	0-185	143	0	0-238	0	0	0	0
0	0-219	175	0	0-199	179	0	0-162	149	0	0	0	0	0
-223	0	0-214	196	0	0-201	189	0	0-175	0	0-188	0	0	0
0-222	208	0-220	201	0	0-198	178	0	0-149	0	0-204	0	0	0
206	0-221	0	0-219	205	0	0-192	177	0	0-131	0	0-225	0	0
202-221	0	0	0	0-218-203	0	0-196	153	0	0-146	0	0-243	0	0
0	193-227	0	0	0	0	0-214	0	0-200	172	0	0-188	0	0
0	0	0-230	0	0	0	0	0-202	0	0-207	0	0	176-206	0
-232	180	0	0-231	0	0	0	0	0-204	0	0-214	163	0-193-196	0
0-232	200	0	0-227	0	0	0	0	0-213	0	0-219	0	0-213	0
0	0-223-212	0	0-214	0	0	0	0	0-204	0	0-213	0	0	0
154	0	0	199-223	0	0-220	0	0	0	0	0	179-194	0	0
-203	182	0	0	197-231	0	0-212	0	0	0	0	0	0-203-188	0
0-191-199	0	0	186-229	0	0-213	0	0	0	0	0	0	0-224	0
0	0	176-211	0	0	0-225	0	0-214	0	0	0	0	0	0
-203	0	0	0-216	0	0	167-222	0	0-225	0	0	0	0	0
186-220	0	0	0-217	0	0	0-222	0	0-236	0	0	0	0	0
0	155-224	163	0	0-213	0	0	184-226	0	0	0	0	0	0
0	0	139-214	183	0	0-212	0	0	192-226	0	0	0	0	0
-202	0	0	0-206	191	0	0-213	177	0	199-222	0	0	0	0
184-214	0	0	0-204	200	0	0-203	183	0-214	208	0	0	0	0
0	0-219	151	0	0-202-206	0	0-210	0	0-222	0	0	0	0	0
177	0	0-217	165	0	0	200-206	0	0-215	0	0-230	0	0	0
-201	192	0	0-216	192	0	0	201-202	0	0-221	0	0-238	0	0
0-209-211	0	0-220	165	0	0-213	188	0	0-226	0-231	0	0	0	0
193	0	0-207	0	0-197	188	0	0-194	199	0	0-227	0	0	0
-234	209	0	0-223	0	0-210	208	0	0-203	207	0	0	0	0
0-210-219	0	0-226	0	0-214	209	0	0-207	204	0	0	0	0	0
0	0	191-229	0	0-221	204	0-214	204	0	0-219	0	0	0	0
-224	0	0	0-230	0	0-217	202	0-205	199	0	0-226	0	0	0
0-222	202	0	0-227	0	0-219	0	0-208	202	0	0-231	0	0	0
0	0-210-208	0	0-231	207	0-218	0	0-210	194	0	0-233	0	0	0
-221	0	0	200-214	0	0-229	211	0-222	0	0-222	0	0	212-231	0
0-234	0	0	186-217	0	0-232	221	0-229	0	0-226	0	0	232	0
0	0-245	0	0	0-216	0	0-233	218	0-233	0	0-227	0	0	0
0	0	0	0	0	0-224	0	0-233	0	0	0	207-213	0	0
0-236-254	0	0	0	0	0-227	0	0	0	0	0	0	0	0
0	0	227-253	0	0	0	0-223	0	0	0	0	0	0	0
0	0	0	211-251	0	0	223	0	0-231	0	0	0	0	0
154	0	0	0	198-249-255-253	230	0	0-229	0	0	0	0	0	0
-207	183	0	0	177	244-255-254	230	0	0-223	0	0	0	0	0
0-201-201	0	0	0	0	242-255	253	220	0-214	0	0	0	0	0
0	0	176-209	0	0	0	156	242-255	0	0	0	0	0	0

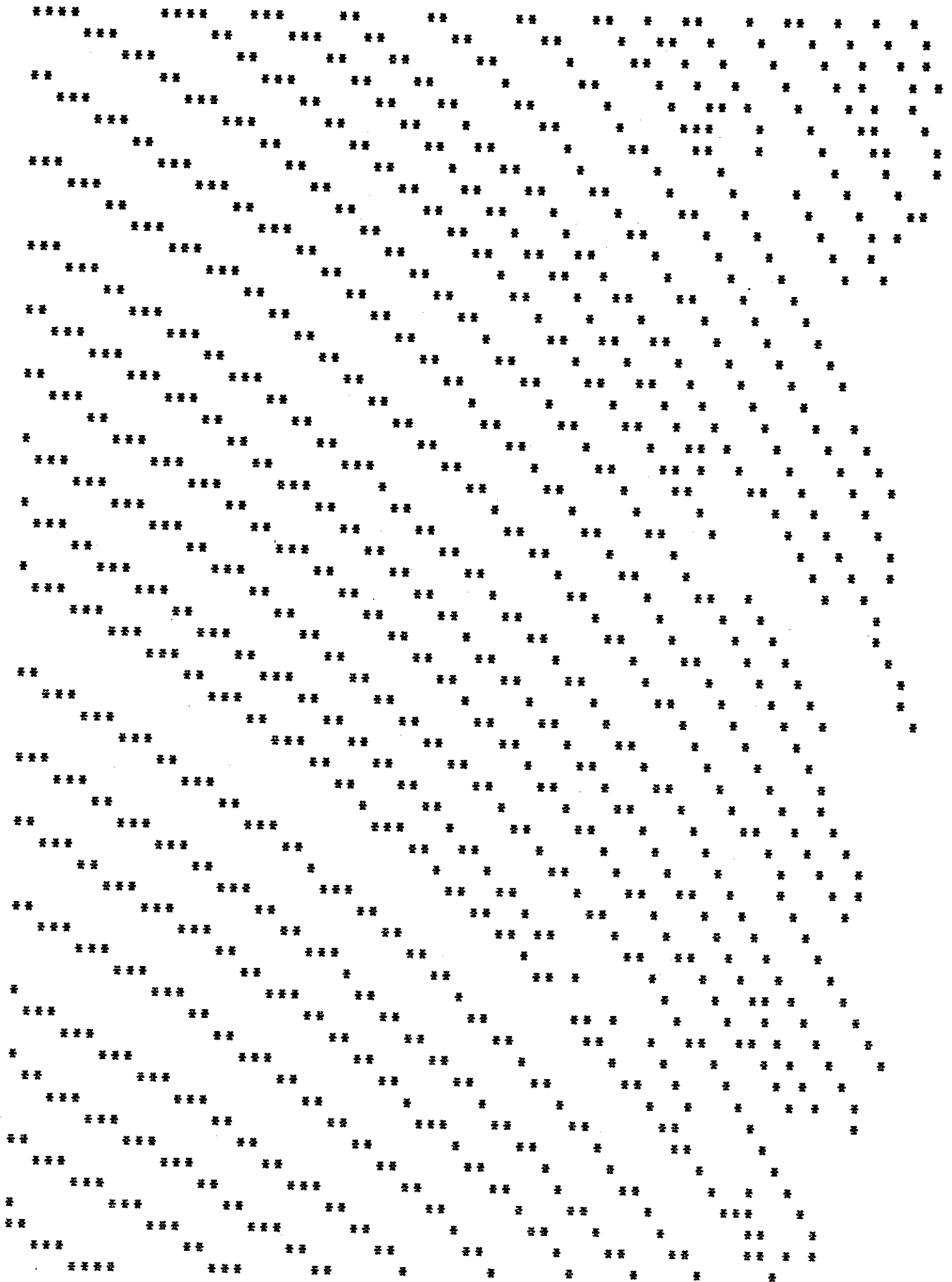


Fig. 8